

MA 6.101

Probability and Statistics

Tejas Bodas

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Generate samples using uniform distribution

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- ▶ Suppose you have access to samples from a uniform random variable U over support $[0, 1]$.

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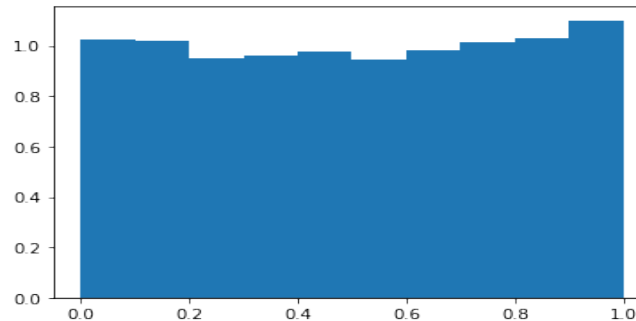
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import numpy as np
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uni_samples = np.random.uniform(0, 1, 5000)
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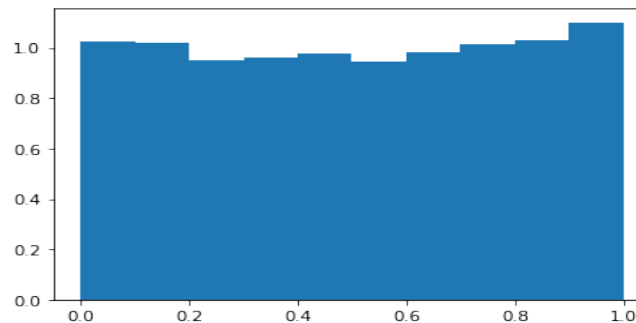


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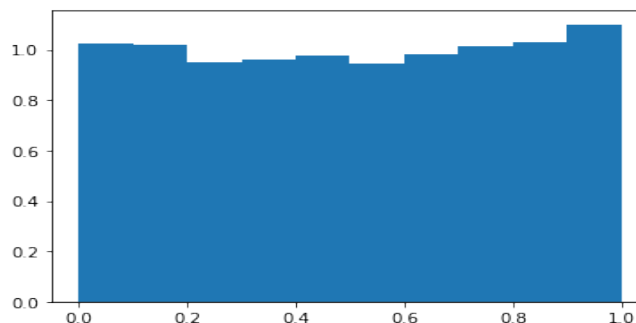
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- ▶ *uni_samples* is a vector of 5000 realizations of uniform random variable U .
- ▶ You can also see it as a realization of $U_1, U_2, \dots, U_{5000}$ i.i.d uniform variables.

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t=0
dice_samples=np.zeros(5000)
for u in uni_samples:
    if u < 1/6:
        dice_sample = 1
    if 1/6 < u < 2/6:
        dice_sample = 2
    if 2/6 < u < 3/6:
        dice_sample = 3
    if 3/6 < u < 4/6:
        dice_sample = 4
    if 4/6 < u < 5/6:
        dice_sample = 5
    if 5/6 < u < 6/6:
        dice_sample = 6
    dice_samples[t] = dice_sample
    t = t+1
plt.hist(dice_samples, bins = 6, density = True)
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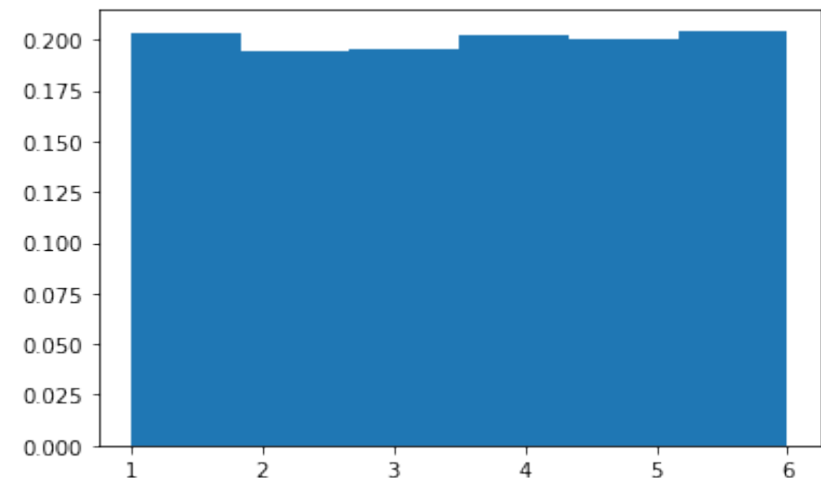
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▶ [0.02, 0.8, 0.6, 0.03]

▶ [1, 5, 4, 1]



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- ▶ Consider a discrete random variable X with support set $\{x_0, x_1, \dots\}$ and pmf $p_X(x_j) = p_j$ for $j = 0, 1, \dots$ such that $\sum_j p_j = 1$.

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- ▶ We shall now formally see the [inverse transform method](#) to do this.

The inverse transform method

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$$X = \begin{cases} x_0 & \text{if } u < p_0 \\ x_1 & \text{if } p_0 \leq u < p_0 + p_1 \\ x_2 & \text{if } p_0 + p_1 \leq u < p_0 + p_1 + p_2 \\ \vdots & \\ x_j & \text{if } \sum_{i=0}^{j-1} p_i \leq u < \sum_{i=0}^j p_i \\ \vdots & \end{cases}$$

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- ▶ Why is this method correct?

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- ▶ We are thus finding the inverse of $F_X(U)$!

How to generate samples of a continuous random variable

(Using samples of a continuous uniform variable over $[0, 1]$)

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- ▶ **Answer:** Draw $u \sim U$ and obtain $F^{-1}(u)$. This is a sample from X .
- ▶ Do you observe anything “special” about this lemma?

Application in data analysis

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- ▶ This property is used to test whether a set of observations can be modelled as arising from a specified distribution $G(\cdot)$ or not.

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- ▶ This property is known as “probability integral transform or universality of uniform”.
- ▶ This property is used to test whether a set of observations can be modelled as arising from a specified distribution $G(\cdot)$ or not.
 - ▶ Given set of data samples s_1, s_2, \dots, s_n , plot $G(s_i)$ for different samples.
 - ▶ If these points are spread uniformly over the interval $[0, 1]$ then it indicates that the samples are indeed from $G(\cdot)$.

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- ▶ Some popular techniques in simulation are:
 - ▶ The inverse transform method
 - ▶ Accept-Reject method (rejection sampling)
 - ▶ Importance sampling
 - ▶ Markov Chain Monte Carlo (MCMC) methods

Stochastic Simulation

- ▶ This was a brief introduction to this area of stochastic simulation.
- ▶ Refer the book Simulation by Sheldon Ross!
- ▶ Some popular techniques in simulation are:
 - ▶ The inverse transform method
 - ▶ Accept-Reject method (rejection sampling)
 - ▶ Importance sampling
 - ▶ Markov Chain Monte Carlo (MCMC) methods
 - ▶ Hasting-Metropolis algorithm
 - ▶ Gibbs sampling
 - ▶ Slice sampling

Convergence of Random Variables

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If $N(\epsilon, x) = N(\epsilon)$ (i.e., independent of x) for every $x \in \mathbb{R}$, then such convergence of $F_n(\cdot)$ to $F(\cdot)$ is called as uniform convergence.