# ISHITA GUPTA

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#### **EDUCATION**

## Carnegie Mellon University

Pittsburgh, PA

Master of Science in Robotic Systems Development (MRSD) CGPA: 3.92

August 2024 - May 2026

- Coursework: Generative AI (10-623), Robot Mobility, Manipulation, Estimation & Controls, Deep Learning (PhD), Systems Engineering, Robot Autonomy
- TA for Introduction to Deep Learning (11-785)

## The LNM Institute of Information Technology (LNMIIT)

Jaipur, Rajasthan

Bachelor of Technology (B.Tech) in Computer Science and Engineering

August 2018 - July 2022

Coursework: Probability & Statistics, Artificial Intelligence, NLP, GANs, Advanced Algorithms

#### **EXPERIENCE**

**Addverb** | Advanced Robotics & Industrial Automation | Website Software Engineer – 2.5 years

Noida, India

January 2022 - July 2024

- VSLAM: Developed a complete Visual SLAM system for a quadruped robot, implementing **pose graph optimization**, bundle adjustment for **Local Mapping**, and Visibility Graph Visualizers using modern C++ and OpenCV. Designed the visual odometry pipeline with **feature extraction** using X-Feat descriptors, **Perspective-n-Point (PnP)** algorithms, and motion-only bundle adjustment, and optimized the back-end with a Levenberg-Marquardt-based graph optimizer.
- Simulator Engineering: Built a simulator engine using OpenGL and the NVIDIA PhysX, integrated with a Haptic device to deliver real-time force feedback, enhancing fidelity of robotic motion simulations.
- Multi-Robot GUI & Rehabilitation Games: Led the creation of a GUI application for 3 robotic systems Robotic Arm (Cobot), Exoskeleton, and Haptic device, using ImGui (C++). Developed rehabilitation games (Unity3D) for Exoskeleton robots for physical therapy solutions.
- Warehouse Management System: Devised new APIs to enhance warehouse efficiency in WES and WMS using Java (SpringBoot), Kafka, MongoDB, Design Patterns, and Multithreading (threads, synchronization).

Google | Nest Devices Cloud

Bengaluru, India

Software Engineering Intern – 3 months

May 2021 - August 2021

• Automated a backend cloud pipeline, reducing a **4-month** task by 4-5 Google Software Engineers to a single Bash script. Curated an end-to-end onboarding infrastructure that generates and modifies **1,000+** lines of code across **150** files in multiple languages, driven by user configurations. Leveraged Python, JSON, Go, Bash, and Unit Testing.

# **PROJECTS**

- Humanoid Loco-Manipulation for Tote Logistics | Link August 2024 Present Developing an autonomous humanoid robot system integrating hybrid whole-body control, motion planning, and sensor fusion (RGBD & LiDAR) for precise tote manipulation and obstacle avoidance in dynamic warehouse environments.
- Training Language Models to Self-Correct via Reinforcement Learning | Link August 2024 December 2024 Led benchmarking of self-correction in LLMs, evaluating performance across Llama 3.2 1B, Llama 3.1 8B, and Mathstral 7B on MATH dataset. Achieved accuracy rates of up to 41.8%, identifying high Cor->Inc rates (46.9%) and low Inc->Cor improvement (3.78%). Engineered a multi-turn reinforcement learning framework (SCoRe) for fine-tuning.
- Automatic Speech Recognition using LSTM RNNs

  October 2024
  Created a phoneme recognition model with dynamic decoding (greedy and beam search), achieving a validation Levenshtein distance of 5 and validation loss of 0.31 for competitive phoneme sequence accuracy.
- Face classification and verification Using CNNs

  September 2024

  Implemented and trained CNN models (ResNet34, SEResNet etc.) for face classification and verification using techniques like Transforms and CutMix achieving an 11% Equal Error Rate and 90.6% Validation accuracy.

## **SKILLS**

- Programming: C++, Python, Java, Go. | Frameworks: Pytorch, Scikit-learn, Angular, ROS2, Protobuf, Django.
- IDE's: VSCode, Pycharm, Cider. | Others: Linux, Gazebo, Mujoco, Github, Wandb, OpenCV, Matlab, Rviz, Unity 3D, NVIDIA PhysX, Kaggle.