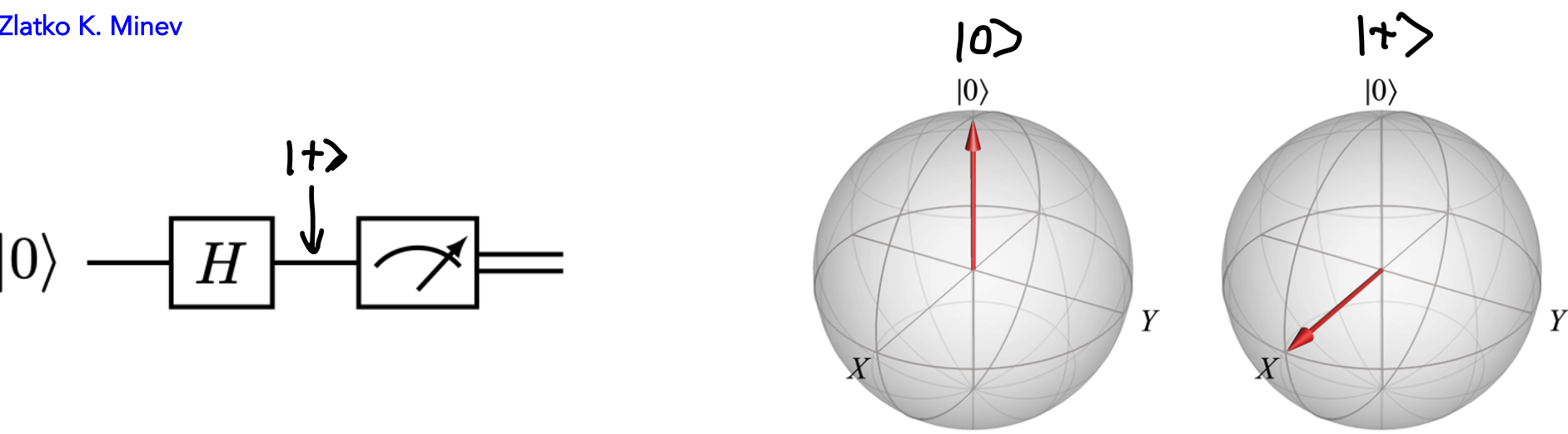


# Introduction to quantum noise

## Measurement theory & projection noise

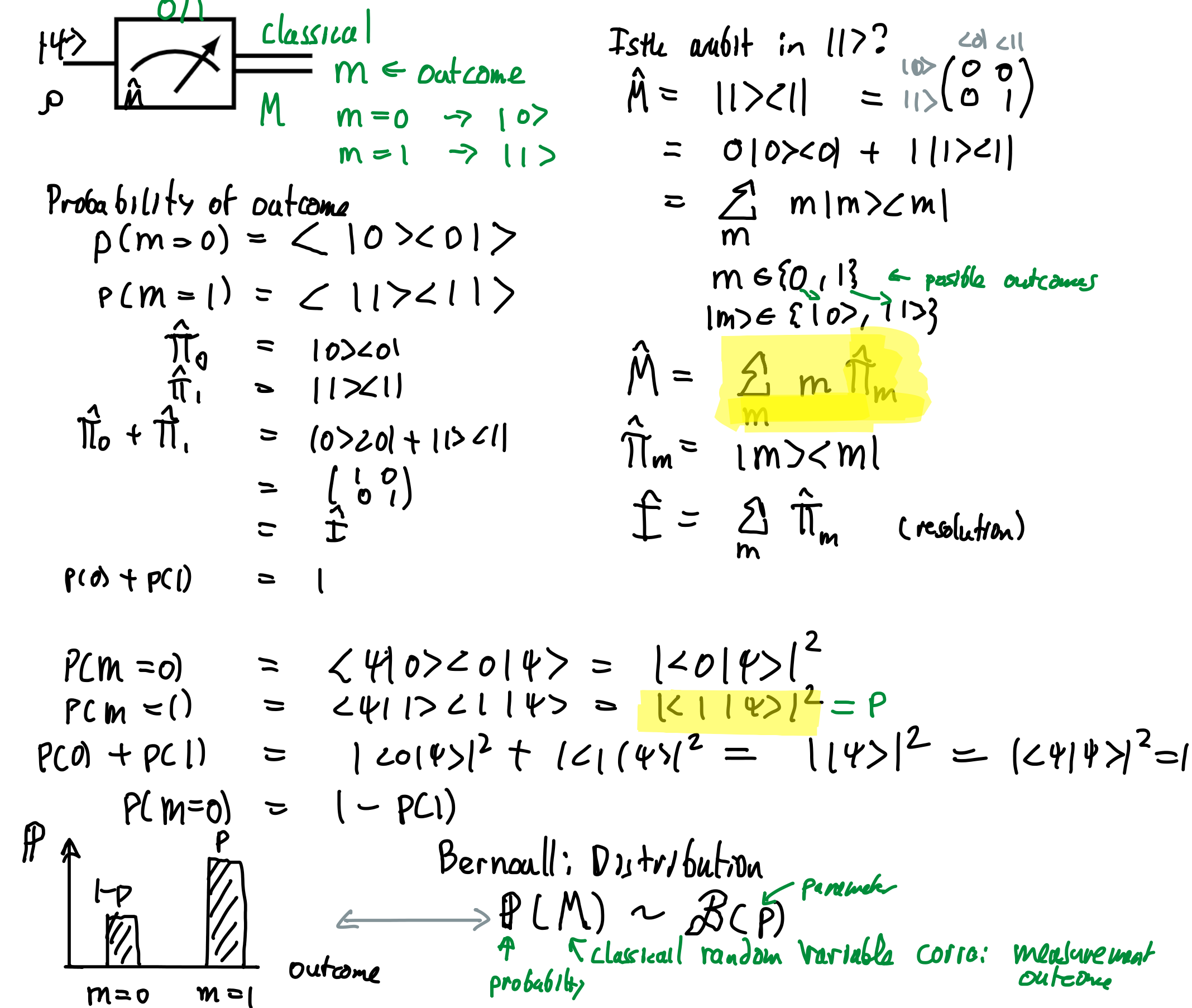
Qiskit Global Summer School on Quantum Machine Learning  
Zlatko K. Mineev



Measurement: theory 101

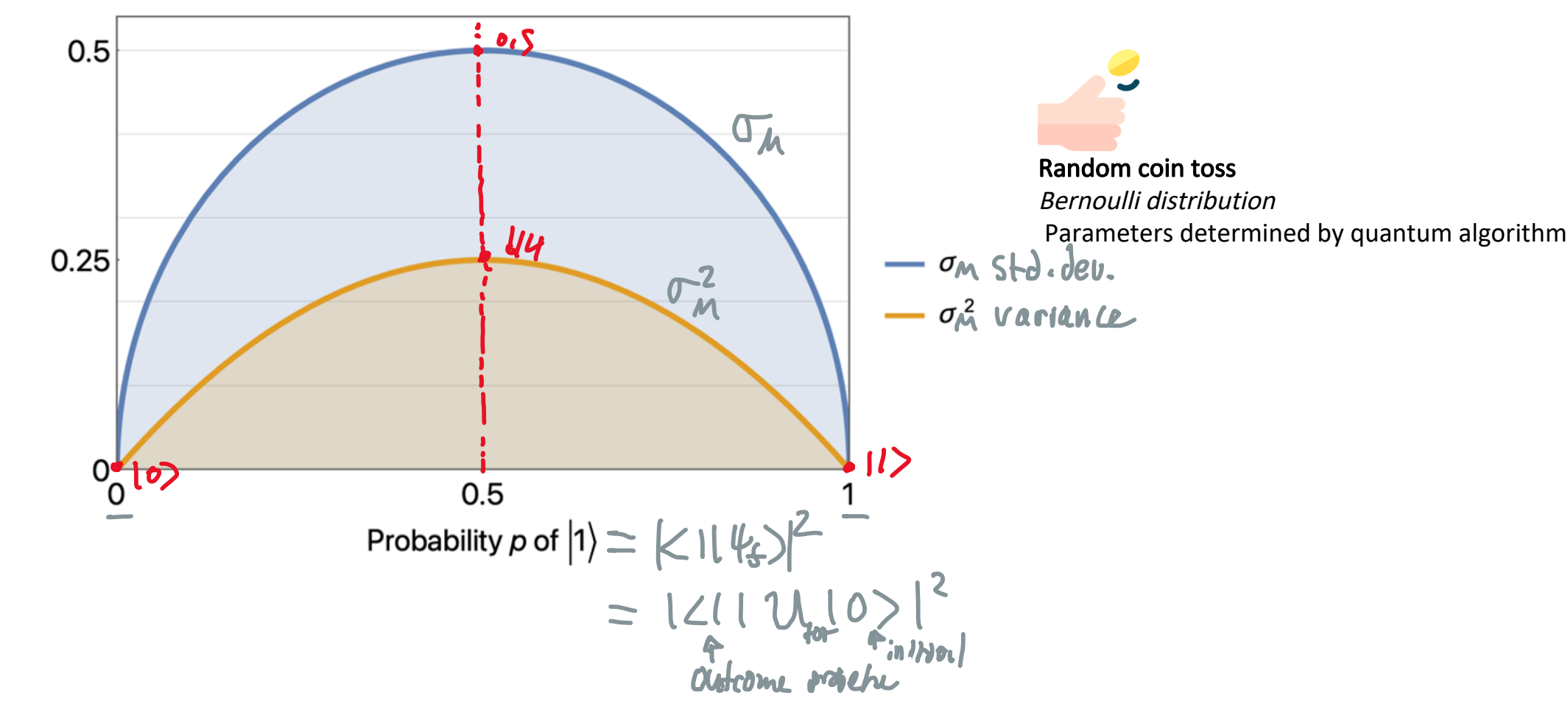
*The standard (von Neumann) measurement of a quantum system.*  
von Neumann measurement is efficient, strong, and projective

Measurement operator (observable)  $\hat{M}$



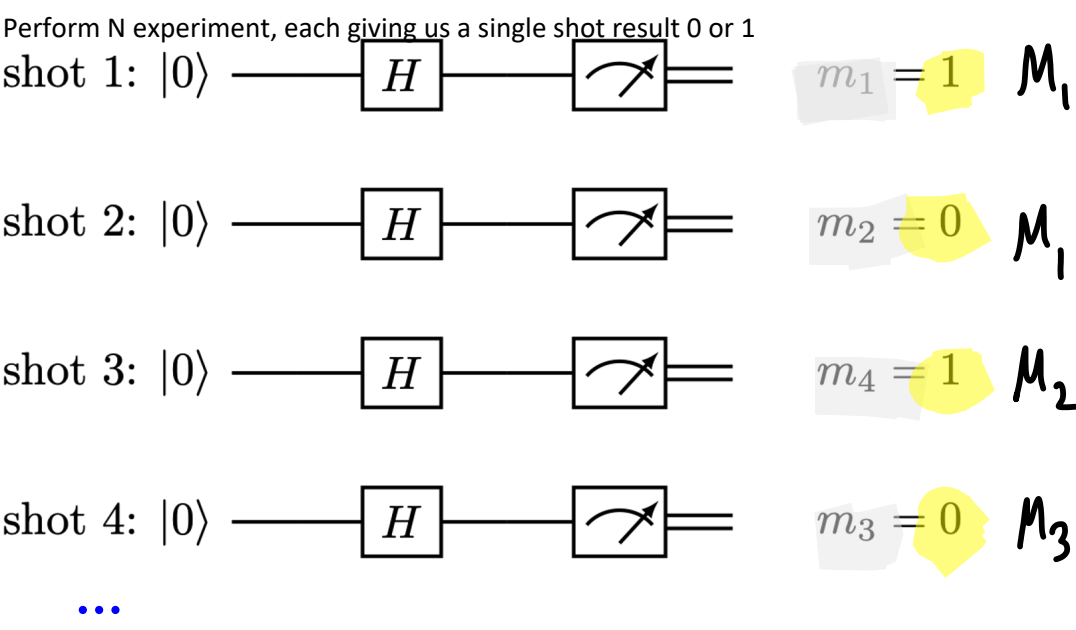
# Statistics

$$\begin{aligned} \mathbb{E}[M] &= \sum_m m P(m) = 0 P(m=0) + 1 P(m=1) \\ &= P \\ &= \langle \hat{M} \rangle \\ &\quad \text{Quantum} \\ \mathbb{V}[M] &= \mathbb{E}[M^2] - \mathbb{E}[M]^2 \approx \langle \hat{M}^2 \rangle - \langle \hat{M} \rangle^2 \\ \mathbb{E}[M^2] &= \sum_m m^2 P(m) \\ &= \sum_m m^2 \langle 1m | \langle m | \rangle \\ &= \langle \sum_m m^2 |m \rangle \langle m| \rangle \\ &= \langle \hat{M}^2 \rangle \\ &= \cancel{\sigma^2 + p} + 1^2 p \\ &= p \\ \mathbb{V}[M] &= p - p^2 \\ &= p(1-p) \quad \begin{matrix} = 0 & \text{if } p=0 \\ = 1 & \text{if } p=1 \end{matrix} \\ &= \sigma_M^2 \end{aligned}$$



## Projection noise and sampling error

Let's turn to the example of finite number of shots we execute for our experiment



For 3 samples, there are  $2^3$  possible outcome sequences.

