

# Aashi Goel

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## OBJECTIVE

I am seeking a Fall 2024 co-op position related to engineering and full-time opportunities starting after May 2025.

## EDUCATION & AFFILIATIONS

**Worcester Polytechnic Institute (WPI)**, Worcester, MA

AUG. 2021 - PRESENT

B.S. in **Robotics Engineering**, Minor in **Computer Science** | GPA: 3.69/4.0 | Dean's List | Graduation: **May 2025**

Campus Involvement: Alpha Gamma Delta, Society of Asian Scientists & Engineers, Society of Women Engineers

*External Organizations: Rewriting the Code, Aspiring Professionals in STEM*

## SKILLS

C/C++, Java, MATLAB, Python, Solidworks (CSWA certified), HTML, CSS, Git/GitHub, SQL, AutoCAD, ArcGIS Pro

## WORK EXPERIENCE

**Gas Asset Management & Engineering Intern — National Grid**, Waltham, MA

JUN. 2024 - PRESENT

- Design AutoCAD drawings of gas lines and create a Bill of Materials (BOM) for construction
- Create paving layers in ArcGIS Pro using Python and databases knowledge

**Energy Efficiency Procurement Intern — National Grid**, Waltham, MA

JUN. 2023 - AUG. 2023

- Played a strategic role in supplier selection by contributing to the execution of a Request for Proposal (RFP)
- Managed and executed contract changes for company's energy efficiency initiatives to ensure seamless transitions
- Collaborated closely with stakeholders to identify and implement appropriate strategic sourcing methods

**Customer Experience Intern — National Grid**, Waltham, MA

MAY 2022 - AUG. 2022

- Initiated and executed research projects to propose solutions aimed at elevating customer satisfaction scores
- Leveraged industry trends and conducted data-driven market research to inform and drive recommendations to improve customer engagement in company programs (currently being used to develop new company mobile app)

## RESEARCH

**AVA Robotics Tour Guide Project**, Perception & Autonomous Robotics Group (PeAR), WPI

MAY. 2024 - PRESENT

- Design a vision-based system that allows the robot to use an elevator and navigate multiple floors of a building
- Utilize a pathfinding algorithm for the robot to move to/from an arbitrary point & localize the robot using SLAM

## PROJECTS

**LIDAR Mapping & Path Planning Robotics Project**, WPI

OCT. 2023 - DEC. 2023

- Mapped and navigated through an unknown maze using ROS nodes and services within a Linux-based environment
- Developed occupancy grid, padding, mapping, frontier finding, and path planning algorithms in Python
- Utilized the LiDAR-equipped TurtleBot3 platform to implement simultaneous localization and mapping (SLAM)

**Pick-&-Place Sorting Balls Robotics Project**, WPI

AUG. 2023 - OCT. 2023

- Programmed a 4-DOF robotic arm in MATLAB to pick and sort objects based on color on a checkerboard base
- Implemented kinematics and trajectory planning to move robot's end effector to its desired positions
- Created computer vision system to determine color of objects and localize them to checkerboard coordinates

**Escape Room Maze Robotics Project**, WPI

MAR. 2023 - MAY 2023

- Implemented embedded programming in C++ to enable 3 robots to autonomously navigate a complex maze
- Applied speed control algorithms to achieve precise movement control and MQTT broker for robot communication
- Incorporated PID controllers and sensor fusion for accurate navigation and utilized ESP32 microcontroller

**Panel Replacement Robotics Project**, WPI

AUG. 2022 - OCT. 2022

- Programmed state machines in C++ to create autonomous algorithms that control 2 robots via infrared remote
- Created detailed Solidworks assemblies & 3-D printed and laser-cut fourbars and grippers for mechanical design

## LEADERSHIP

**Vice President of Academic Excellence**, Alpha Gamma Delta - Zeta Zeta Chapter, WPI

DEC. 2023 - PRESENT

- Organize events and provide other academic resources to help improve the chapter's performance and GPA

**Undergraduate Mentor**, Women's Research And Mentorship Program, WPI

SEP. 2023 - DEC. 2023

- Mentored two high school students in building an autonomous robot using teamwork and communication skills