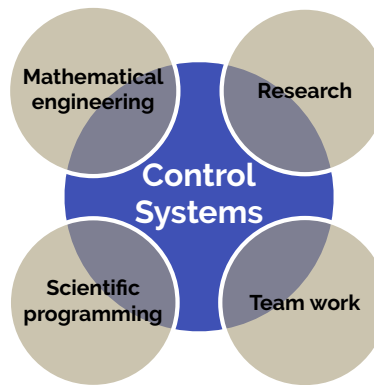
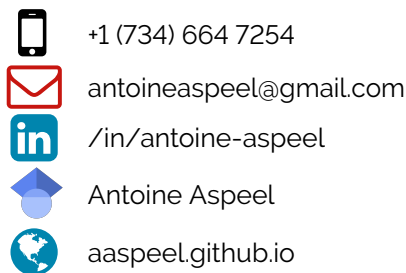


ANTOINE ASPEEL | CV



Professional Summary

I am a Ph.D. in Mathematical Engineering with a focus on control theory and optimization. In the last years, I have published papers focusing on safety control, reachability analysis, networked control systems, and resource-aware control. During my PhD and my postdoc, I worked on multiple team projects as well as on my own personal research. I also had the opportunity to be a teaching assistant and to mentor several master and Ph.D. students. I am excited about the opportunity to bring my expertise to a new team and continue my research in an open-minded setting.

Skills

Areas of Expertise	Software / programming	Languages
<div>Safety control</div> <div>Koopman theory</div> <div>Predictive control</div> <div>Reachability analysis</div> <div>Reinforcement learning</div> <div>Optimization</div>	<div>Python ●●●●●</div> <div>Matlab ●●●●●</div> <div>Julia ●●●●●</div>	<div>French ●●●●●</div> <div>English ●●●●●</div> <div>Italian ●●●●●</div>

Education

2022 - 2024	Postdoc in Control and Optimization	University of Michigan, Ann Arbor, United States of America
	With Prof. Necmiye Ozay . Focus on safety control, reachability analysis, Koopman theory, and inverse reinforcement learning.	
2022	Postdoc in Control and Optimization	Université Catholique de Louvain, Louvain-la-Neuve, Belgium
	With Prof. Raphaël M Jungers and Prof. Benoit Macq . Focus on networked control systems, and resource-aware control.	
2017 - 2022	Ph.D. in Mathematical Engineering	Université Catholique de Louvain, Louvain-la-Neuve, Belgium
	Thesis title: "Optimal Sampling for State Estimation of Stochastic Dynamical Systems". Supervisors: Prof. Raphaël M Jungers , and Prof. Benoit Macq . From May to June 2019, I was a visiting PhD student at McGill University, Montreal, Canada. I was working with Prof. Vincent François-Lavet on applications of deep reinforcement learning to sensor scheduling.	

2015 - 2017

Master of Mathematical Engineering

Université Catholique de Louvain,
Louvain-la-Neuve, Belgium

- » Advanced courses in dynamical systems, control, optimization and graph theory.
- » Thesis title: "Community detection in large-scale time-varying networks: a modularity based approach". Supervisor: **Prof. Jean-Charles Delvenne**.
- » International exchange in 2016 at the École Polytechnique Fédérale de Lausanne (EPFL), Switzerland.

2012 - 2015

Bachelor of Mathematical and Mechanical Engineering

Université Catholique de Louvain,
Louvain-la-Neuve, Belgium

- » I have completed the credits for the double bachelor's degree in applied mathematics and mechanical engineering.

»» Publications

I have published scientific articles in control journals and conferences (check my Google Scholar profile [here](#)).

Articles published or accepted for publication in scientific journals

- » **Antoine Aspeel**, Jakob Nylof, Jing Shuang (Lisa) Li, and Necmiye Ozay. A Low Rank Approach to Minimize Sensor-to-Actuator Communication in Finite Horizon Output Feedback. *IEEE Control Systems Letters*, 2023. (With ACC24 option), (accepted for publication).
- » Haldun Balim, **Antoine Aspeel**, Zexiang Liu, and Necmiye Ozay. Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems. *IEEE Control Systems Letters*, 2023. (With CDC23 option).
- » **Antoine Aspeel**, Amaury Gouverneur, Raphaël M Jungers, and Benoit Macq. Optimal intermittent particle filter. *IEEE Transactions on Signal Processing*, 2022.
- » Michaël Fanuel, **Antoine Aspeel**, Jean-Charles Delvenne, and Johan AK Suykens. Positive semi-definite embedding for dimensionality reduction and out-of-sample extensions. In *SIAM Journal on Mathematics of Data Science*, 2022.
- » Damien Dasnoy, **Antoine Aspeel**, Kevin Souris, and Benoit Macq. Locally tuned deformation fields combination for 2D cine-MRI-based driving of 3D motion models. In *Physica Medica*, 2022.
- » **Antoine Aspeel**, Axel Legay, Raphaël M Jungers, and Benoit Macq. Optimal measurement budget allocation for Kalman prediction over a finite time horizon by genetic algorithms. *EURASIP Journal on Advances in Signal Processing*, 2021.

Works in proceedings of conferences

- » **Antoine Aspeel**, Kwesi Rutledge, Raphaël M Jungers, Benoit Macq, and Necmiye Ozay. Optimal control for linear networked control systems with information transmission constraints. In *The 60th IEEE International Conference on Decision and Control*, 2021.
- » **Antoine Aspeel**, Amaury Gouverneur, Raphaël M Jungers, and Benoit Macq. Optimal measurement budget allocation for particle filtering. In *27th IEEE International Conference on Image Processing*, 2020.
- » **Antoine Aspeel**, Damien Dasnoy, Raphaël M Jungers, and Benoit Macq. Optimal intermittent measurements for tumor tracking in X-ray guided radiotherapy. In *Medical Imaging 2019: Image-Guided Procedures, Robotic Interventions, and Modeling*, volume 10951, page 109510C. International Society for Optics and Photonics, 2019.

»» Presentations in Events

- » Our work *Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems* will be presented at the *62th Conference on Decision and Control (CDC)*, Singapore, 2023.
- » I presented the work *Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems* at the *CLEVR-AI, MURI Symposium*, Boston, 2023.

- » I presented the content of my Ph.D. thesis to the group of Prof. Necmiye Ozay, at the *University of Michigan*, Ann Arbor, 2022.
- » I presented the work *Optimal Control for Linear Networked Control Systems with Information Transmission Constraints* in the *60th Conference on Decision and Control (CDC)*, Texas, 2021.
- » I presented the work *Optimal measurement budget allocation for particle filtering* in the *IEEE International Conference on Image Processing (ICIP)*, Abu Dhabi, 2020.
- » I presented the work *Optimal intermittent measurements for tumor tracking in x-ray guided radiotherapy* in the *International Conference Medical Imaging 2019: Image-Guided Procedures, Robotic Interventions, and Modeling (SPIE)*, San Diego, 2019.
- » I presented the work *Genetic Algorithms for optimal intermittent measurements for tumor tracking* in the *International Conference on the Use of Computers in Radiation Therapy (ICCR)*, Montreal, 2019.

»»» Service to scientific community

I was the chair of the *Control over Communications* session at the Conference on Decision and Control (CDC) 2021. I am also a reviewer for the following journals and conferences (check my web of science profile [here](#)):

- » Automatica, Elsevier Journal.
- » TAC — IEEE Transactions on Automatic Control.
- » L-CSS — IEEE Control Systems Letters.
- » EURASIP Journal on Advances in Signal Processing.
- » CDC — Conference on Decision and Control.
- » L4DC — Conference on Learning for Dynamics and Control.
- » AAAI — Association for the Advancement of Artificial Intelligence.

»»» Teaching Activities

Since 2014, I have been developing my teaching skills by creating and correcting assignments and teaching in the following courses:

- » Introduction to Algebra, undergraduate level.
- » Algebra, undergraduate level.
- » Introduction to Calculus, undergraduate level.
- » Calculus, undergraduate level.
- » Discrete mathematics and probabilities, undergraduate level.
- » Economics, undergraduate level.
- » Sustainable development, master level.

»»» Mentoring and proposal writing

- » Mentored 5 Ph.D. students working on control theory and reinforcement learning.
- » Mentored 3 visiting master students: **Jakob Nylof** (co-author in *IEEE Control System Letters*, 2023), **Haldun Balim** (co-author in *IEEE Control System Letters*, 2023), and **Amaury Gouverneur** (co-author in *IEEE Transactions on Signal Processing*, 2022 and *IEEE International Conference on Image Processing*, 2020).

- » Supervised and was a member of the jury for 6 master's theses.
- » Co-authored a research proposal on reinforcement learning that received 1.1 M€ from the Walloon region of Belgium.

»» Other Activities

- » Between 2014 and 2016, I was a founding member, treasurer and then elected president of a non-profit organization. I was responsible for the management of reusable glasses for student activities (turnover ~ 30,000€/year).
- » I have been an organizer of youth movements.
- » I run regularly, enjoy playing chess and piano, reading and learning new things.