Antoine Aspeel CV

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Antoine Aspeel aaspeel.github.io

>>> Professional Summary

I am a Ph.D. in Mathematical Engineering with a focus on control theory and optimization. In the last years, I have published papers focusing on safety control, reachability analysis, networked control systems, and resource-aware control. During my PhD and my postdoc, I worked on multiple team projects as well as on my own personal research. I also had the opportunity to be a teaching assistant and to mentor several master and Ph.D. students. I am excited about the opportunity to bring my expertise to a new team and continue my research in an open-minded setting.

>>> Skills

Areas of Expertise Software / programming Languages French Matlab Matlab Dython Dython Dython Matlab Dython Dython Dython Matlab Dython Dython

>>> Education

Laucation		
2022 - 2024	Postdoc in Control and Optimization	University of Michigan, Ann Arbor, United States of America
	➤ With Prof. Necmiye Ozay . Focus on safety control, reacha and inverse reinforcement learning.	bility analysis, Koopman theory,
2022	Postdoc in Control and Optimization	Université Catholique de Louvain, Louvain-la-Neuve, Belgium
	With Prof. Raphaël M Jungers and Prof. Benoit Macq systems, and resource-aware control.	. Focus on networked control
2017 - 2022	Ph.D. in Mathematical Engineering	Université Catholique de Louvain, Louvain-la-Neuve, Belgium

- ▶ Thesis title: "Optimal Sampling for State Estimation of Stochastic Dynamical Systems". Supervisors: Prof. Raphaël M Jungers, and Prof. Benoit Macq.
- From May to June 2019, I was a visiting PhD student at McGill University, Montreal, Canada. I was working with **Prof. Vincent François-Lavet** on applications of deep reinforcement learning to sensor scheduling.

Master of Mathematical Engineering

Université Catholique de Louvain, Louvain-la-Neuve, Belgium

- Advanced courses in dynamical systems, control, optimization and graph theory.
- Thesis title: "Community detection in large-scale time-varying networks: a modularity based approach". Supervisor: **Prof. Jean-Charles Delvenne**.
- International exchange in 2016 at the École Polytechnique Fédérale de Lausanne (EPFL), Switzerland.

2012 - 2015

Bachelor of Mathematical and Mechanical Engineering

Université Catholique de Louvain, Louvain-la-Neuve, Belgium

▶ I have completed the credits for the double bachelor's degree in applied mathematics and mechanical engineering.

>>> Publications

I have published scientific articles in control journals and conferences (check my Google Scholar profile here).

Articles published or accepted for publication in scientific journals

- **Antoine Aspeel**, Jakob Nylof, Jing Shuang (Lisa) Li, and Necmiye Ozay. A Low Rank Approach to Minimize Sensor-to-Actuator Communication in Finite Horizon Output Feedback. *IEEE Control Systems Letters*, 2023. (With ACC24 option), (accepted for publication).
- ▶ Haldun Balim, **Antoine Aspeel**, Zexiang Liu, and Necmiye Ozay. Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems. *IEEE Control Systems Letters*, 2023. (With CDC23 option).
- ▶ **Antoine Aspeel**, Amaury Gouverneur, Raphaël M Jungers, and Benoit Macq. Optimal intermittent particle filter. *IEEE Transactions on Signal Processing*, 2022.
- ▶ Michaël Fanuel, **Antoine Aspeel**, Jean-Charles Delvenne, and Johan AK Suykens. Positive semi-definite embedding for dimensionality reduction and out-of-sample extensions. In *SIAM Journal on Mathematics of Data Science*, 2022.
- Damien Dasnoy, **Antoine Aspeel**, Kevin Souris, and Benoit Macq. Locally tuned deformation fields combination for 2D cine-MRI-based driving of 3D motion models. In *Physica Medica*, 2022.
- **Antoine Aspeel**, Axel Legay, Raphaël M Jungers, and Benoit Macq. Optimal measurement budget allocation for Kalman prediction over a finite time horizon by genetic algorithms. *EURASIP Journal on Advances in Signal Processing*, 2021.

Works in proceedings of conferences

- ▶ Antoine Aspeel, Kwesi Rutledge, Raphaël M Jungers, Benoit Macq, and Necmiye Ozay. Optimal control for linear networked control systems with information transmission constraints. In *The 60th IEEE International Conference on Decision and Control*, 2021.
- ▶ **Antoine Aspeel**, Amaury Gouverneur, Raphaël M Jungers, and Benoit Macq. Optimal measurement budget allocation for particle filtering. In *27th IEEE International Conference on Image Processing*, 2020.
- ▶ Antoine Aspeel, Damien Dasnoy, Raphaël M Jungers, and Benoit Macq. Optimal intermittent measurements for tumor tracking in X-ray guided radiotherapy. In *Medical Imaging 2019: Image-Guided Procedures, Robotic Interventions, and Modeling*, volume 10951, page 109510C. International Society for Optics and Photonics, 2019.

>>> Presentations in Events

- ▶ Our work Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems will be presented at the 62th Conference on Decision and Control (CDC), Singapore, 2023.
- ▶ I presented the work Koopman-inspired Implicit Backward Reachable Sets for Unknown Nonlinear Systems at the CLEVR-AI, MURI Symposium, Boston, 2023.

- ▶ I presented the content of my Ph.D. thesis to the group of Prof. Necmiye Ozay, at the *University of Michigan*, Ann Arbor, 2022.
- ▶ I presented the work Optimal Control for Linear Networked Control Systems with Information Transmission Constraints in the 60th Conference on Decision and Control (CDC), Texas, 2021.
- ▶ I presented the work Optimal measurement budget allocation for particle filtering in the IEEE International Conference on Image Processing (ICIP), Abu Dhabi, 2020.
- ▶ I presented the work Optimal intermittent measurements for tumor tracking in x-ray guided radiotherapy in the International Conference Medical Imaging 2019: Image-Guided Procedures, Robotic Interventions, and Modeling (SPIE), San Diego, 2019.
- ▶ I presented the work Genetic Algorithms for optimal intermittent measurements for tumor tracking in the International Conference on the Use of Computers in Radiation Therapy (ICCR), Montreal, 2019.

>>> Service to scientific community

I was the chair of the *Control over Communications* session at the Conference on Decision and Control (CDC) 2021. I am also a reviewer for the following journals and conferences (check my web of science profile <u>here</u>):

- ▶ Automatica, Elsevier Journal.
- ▶ TAC IEEE Transactions on Automatic Control.
- ▶ L-CSS IEEE Constrol Systems Letters.
- ▶ EURASIP Journal on Advances in Signal Processing.
- ▶ CDC Conference on Decision and Control.
- ▶ L4DC Conference on Learning for Dynamics ans Control.
- ▶ AAAI Association for the Advancement of Artificial Intelligence.

>>> Teaching Activities

Since 2014, I have been developing my teaching skills by creating and correcting assignments and teaching in the following courses:

- ▶ Introduction to Algebra, undergraduate level.
- ▶ Algebra, undergraduate level.
- Introduction to Calculus, undergraduate level.
- Calculus, undergraduate level.
- Discrete mathematics and probabilities, undergraduate level.
- ▶ Economics, undergraduate level.
- Sustainable development, master level.

>>> Mentoring and proposal writing

- Mentored 5 Ph.D. students working on control theory and reinforcement learning.
- Mentored 3 visiting master students: **Jakob Nylof** (co-author in *IEEE Control System Letters, 2023*), **Haldun Balim** (co-author in *IEEE Control System Letters, 2023*), and **Amaury Gouverneur** (co-author in *IEEE Transactions on Signal Processing, 2022* and *IEEE International Conference on Image Processing, 2020*).

- ▶ Supervised and was a member of the jury for 6 master's theses.
- **)** Co-authored a research proposal on reinforcement learning that received 1.1 M€ from the Walloon region of Belgium.

>>> Other Activities

- ▶ Between 2014 and 2016, I was a founding member, treasurer and then elected president of a non-profit organization. I was responsible for the management of reusable glasses for student activities (turnover $\sim 30,000$ €/year).
- ▶ I have been an organizer of youth movements.
- I run regularly, enjoy playing chess and piano, reading and learning new things.