SUDOKU SOLVING USING DIGIT CLASSIFICATION, IMAGE PROCESSING AND MATHEMATICS

NAME – AASHISH SAH ROLL NO. – 123CS0960 BRANCH – COMPUTER SCIENCE & ENGINEERING

Theory

Sudoku

A number placement puzzle has 9×9 grids with 0-9 occurring once horizontally, vertically and in each box.

Sudoku was a Japanese invented game for fun and later on it became popular for its brain testing puzzles.

This is a newspaper cutting from 1895 of a French newspaper.



Libraries

OpenCV:

OpenCV is a library of programming functions mainly aimed at real-time computer vision plus its open-source, fun to work with and my personal favorite. I have used version 4.1.0 for this project.

Keras:

Easy to use and widely supported, Keras makes deeplearning about as simple as deeplearning can be.

Scikit-Learn:

It is a free software machine learning library for the Python programming language.

Digit Recognition

Data Augmentation:

Data augmentation is a technique to artificially create new training data from existing training data. This is done by applying domain-specific techniques to examples from the training data that create new and different training examples.

Image Processing

Grey scaling the images

It takes average of the 3 RGB values of every pixel.

Gaussian Blur:

An image blurring technique in which the image is convolved with a Gaussian kernel. I'll be using it to smoothen the input image by reducing noise.

Thresholding:

In grayscaled images, each pixel has a value between 0–255, to convert such an image to a binary image we apply thresholding. To do this, we choose a threshold value between 0–255 and check each pixel's value in the grayscale image. If the value is less than the threshold, it is given a value of 0 else 1.

Contour detection:

Contours can be explained simply as a curve joining all the continuous points (along the boundary), having the same color or intensity.

Cropping and wrapping the contour

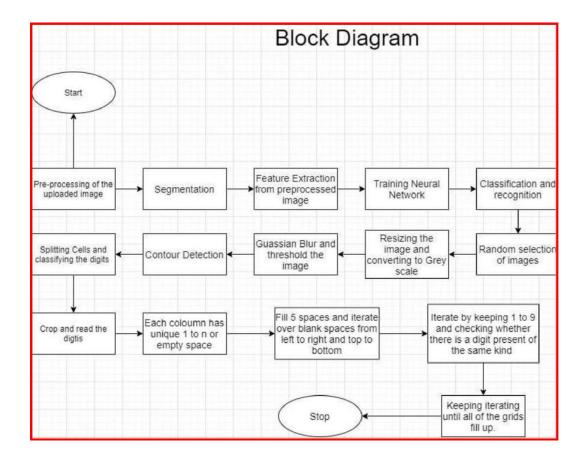
We can extract the actual image through the wrapping and contour and also read the digits to extract the puzzle.

Suduko Solving

Back tracking:

Backtracking is an algorithmic technique for solving problems recursively by trying to build a solution incrementally, one piece at a time, removing those solutions that fail to satisfy the constraints of the problem at any point.

And hence, we print the final result.



Sudoku Solving using Digit classification, image processing and mathematics

Part 1: Digit Classification Model

Importing Libraries

```
In [1]:
import numpy as np
import pandas as pd
import seaborn as sns
import matplotlib.pyplot as plt
import os, random
import cv2
from glob import glob
import sklearn
from sklearn.model selection import train test split
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from keras.preprocessing.image import ImageDataGenerator, load img
from keras.utils.np utils import to categorical
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Activation, Dropout, Dense, Flatten, BatchNormalizat
ion, Conv2D, MaxPooling2D
from tensorflow.keras.optimizers import RMSprop
from tensorflow.keras import backend as K
from tensorflow.keras.preprocessing import image
from sklearn.metrics import accuracy score, classification report
from pathlib import Path
from PIL import Image
Loading the data
In [2]:
data = os.listdir(r"../input/digits/Digits")
data X = []
datay = []
data classes = len(data)
for i in range (0, data classes):
    data list = os.listdir(r"../input/digits/Digits" +"/"+str(i))
    for j in data list:
        pic = cv2.imread(r"../input/digits/Digits" +"/"+str(i)+"/"+j)
        pic = cv2.resize(pic, (32, 32))
        data X.append(pic)
        data_y.append(i)
```

```
if len(data_X) == len(data_y) :
    print("Total Dataponits = ",len(data_X))

# Labels and images
data_X = np.array(data_X)
data_y = np.array(data_y)
```

Total Dataponits = 10160

Data Spliting

```
In [3]:

train_X, test_X, train_y, test_y = train_test_split(data_X, data_y, test_size=0.05)
train_X, valid_X, train_y, valid_y = train_test_split(train_X, train_y, test_size=0.2)
print("Training Set Shape = ",train_X.shape)
print("Validation Set Shape = ",valid_X.shape)
print("Test Set Shape = ",test_X.shape)

Training Set Shape = (7721, 32, 32, 3)
Validation Set Shape = (1931, 32, 32, 3)
Test Set Shape = (508, 32, 32, 3)
```

Preprocessing the images

```
In [4]:
def Prep(img):
    img = cv2.cvtColor(img,cv2.COLOR BGR2GRAY) #making image grayscale
    img = cv2.equalizeHist(img) #Histogram equalization to enhance contrast
    img = img/255 #normalizing
    return img
train X = np.array(list(map(Prep, train X)))
test X = np.array(list(map(Prep, test X)))
valid X= np.array(list(map(Prep, valid X)))
#Reshaping the images
train_X = train_X.reshape(train_X.shape[0], train_X.shape[1], train_X.shape[2],1)
test X = test X.reshape(test X.shape[0], test X.shape[1], test X.shape[2],1)
valid_X = valid_X.reshape(valid_X.shape[0], valid_X.shape[1], valid_X.shape[2],1)
#Augmentation
datagen = ImageDataGenerator(width_shift_range=0.1, height_shift_range=0.1, zoom range=0.
2, shear range=0.1, rotation range=10)
datagen.fit(train X)
```

```
train_y = to_categorical(train_y, data_classes)
test_y = to_categorical(test_y, data_classes)
valid y = to categorical(valid y, data_classes)
```

Building the model

In [5]:

```
In [6]:
model = Sequential()
model.add((Conv2D(60,(5,5),input_shape=(32, 32, 1) ,padding = 'Same' ,activation='relu')
))
model.add((Conv2D(60, (5,5),padding="same",activation='relu')))
model.add(MaxPooling2D(pool_size=(2,2)))
#model.add(Dropout(0.25))
```

```
model.add((Conv2D(30, (3,3),padding="same", activation='relu')))
model.add((Conv2D(30, (3,3), padding="same", activation='relu')))
model.add(MaxPooling2D(pool_size=(2,2), strides=(2,2)))
model.add(Dropout(0.5))
model.add(Flatten())
model.add(Dense(500, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
model.summary()
```

Model: "sequential"

| Layer (type) | Output Shape | Param # |
|------------------------------|--------------------|---------|
| conv2d (Conv2D) | (None, 32, 32, 60) | 1560 |
| conv2d_1 (Conv2D) | (None, 32, 32, 60) | 90060 |
| max_pooling2d (MaxPooling2D) | (None, 16, 16, 60) | 0 |
| conv2d_2 (Conv2D) | (None, 16, 16, 30) | 16230 |
| conv2d_3 (Conv2D) | (None, 16, 16, 30) | 8130 |
| max_pooling2d_1 (MaxPooling2 | (None, 8, 8, 30) | 0 |
| dropout (Dropout) | (None, 8, 8, 30) | 0 |
| flatten (Flatten) | (None, 1920) | 0 |
| dense (Dense) | (None, 500) | 960500 |
| dropout_1 (Dropout) | (None, 500) | 0 |
| dense_1 (Dense) | (None, 10) | 5010 |
| | | |

Total params: 1,081,490 Trainable params: 1,081,490 Non-trainable params: 0

Model Compilation and Model training

```
In [7]:
optimizer = RMSprop(lr=0.001, rho=0.9, epsilon = 1e-08, decay=0.0)
model.compile(optimizer=optimizer,loss='categorical crossentropy',metrics=['accuracy'])
#Fit the model
history = model.fit(datagen.flow(train X, train y, batch size=32),
                              epochs = 30, validation data = (valid X, valid y),
                              verbose = 2, steps per epoch= 200)
Epoch 1/30
200/200 - 72s - loss: 1.0519 - accuracy: 0.6371 - val loss: 0.1685 - val accuracy: 0.9467
Epoch 2/30
200/200 - 70s - loss: 0.3084 - accuracy: 0.9043 - val loss: 0.0778 - val accuracy: 0.9751
Epoch 3/30
200/200 - 70s - loss: 0.2047 - accuracy: 0.9338 - val_loss: 0.0367 - val_accuracy: 0.9881
Epoch 4/30
200/200 - 70s - loss: 0.1714 - accuracy: 0.9470 - val loss: 0.0363 - val accuracy: 0.9896
Epoch 5/30
200/200 - 70s - loss: 0.1385 - accuracy: 0.9581 - val loss: 0.0272 - val accuracy: 0.9922
Epoch 6/30
200/200 - 70s - loss: 0.1256 - accuracy: 0.9627 - val loss: 0.0450 - val accuracy: 0.9896
Epoch 7/30
```

```
200/200 - 71s - loss: 0.1127 - accuracy: 0.9668 - val_loss: 0.0256 - val_accuracy: 0.9907
Epoch 8/30
200/200 - 72s - loss: 0.1162 - accuracy: 0.9650 - val loss: 0.0545 - val accuracy: 0.9850
Epoch 9/30
200/200 - 70s - loss: 0.0982 - accuracy: 0.9718 - val loss: 0.0291 - val accuracy: 0.9907
Epoch 10/30
200/200 - 70s - loss: 0.0886 - accuracy: 0.9731 - val loss: 0.0329 - val accuracy: 0.9943
Epoch 11/30
200/200 - 69s - loss: 0.0960 - accuracy: 0.9735 - val loss: 0.0240 - val accuracy: 0.9959
Epoch 12/30
200/200 - 70s - loss: 0.0906 - accuracy: 0.9737 - val loss: 0.0168 - val accuracy: 0.9953
Epoch 13/30
200/200 - 72s - loss: 0.0735 - accuracy: 0.9780 - val loss: 0.0229 - val accuracy: 0.9933
Epoch 14/30
200/200 - 70s - loss: 0.0920 - accuracy: 0.9721 - val loss: 0.0266 - val accuracy: 0.9927
Epoch 15/30
200/200 - 70s - loss: 0.0927 - accuracy: 0.9750 - val loss: 0.0157 - val accuracy: 0.9959
Epoch 16/30
200/200 - 70s - loss: 0.0894 - accuracy: 0.9741 - val_loss: 0.0228 - val accuracy: 0.9948
Epoch 17/30
200/200 - 70s - loss: 0.0783 - accuracy: 0.9775 - val loss: 0.0375 - val accuracy: 0.9922
Epoch 18/30
200/200 - 70s - loss: 0.0799 - accuracy: 0.9788 - val loss: 0.0235 - val accuracy: 0.9938
Epoch 19/30
200/200 - 71s - loss: 0.0856 - accuracy: 0.9754 - val loss: 0.0345 - val accuracy: 0.9902
Epoch 20/30
200/200 - 71s - loss: 0.0793 - accuracy: 0.9765 - val loss: 0.0194 - val accuracy: 0.9948
Epoch 21/30
200/200 - 70s - loss: 0.0836 - accuracy: 0.9798 - val loss: 0.0288 - val accuracy: 0.9927
Epoch 22/30
200/200 - 70s - loss: 0.0730 - accuracy: 0.9798 - val_loss: 0.0162 - val_accuracy: 0.9953
Epoch 23/30
200/200 - 71s - loss: 0.0804 - accuracy: 0.9789 - val loss: 0.0646 - val accuracy: 0.9860
Epoch 24/30
200/200 - 70s - loss: 0.0767 - accuracy: 0.9791 - val loss: 0.0540 - val accuracy: 0.9876
Epoch 25/30
200/200 - 70s - loss: 0.0866 - accuracy: 0.9771 - val loss: 0.0124 - val accuracy: 0.9959
Epoch 26/30
200/200 - 70s - loss: 0.0819 - accuracy: 0.9788 - val loss: 0.0297 - val accuracy: 0.9938
Epoch 27/30
200/200 - 70s - loss: 0.0826 - accuracy: 0.9780 - val loss: 0.0208 - val accuracy: 0.9969
Epoch 28/30
200/200 - 70s - loss: 0.0730 - accuracy: 0.9812 - val loss: 0.0191 - val accuracy: 0.9959
Epoch 29/30
200/200 - 70s - loss: 0.0910 - accuracy: 0.9751 - val loss: 0.0327 - val accuracy: 0.9917
Epoch 30/30
200/200 - 70s - loss: 0.0697 - accuracy: 0.9818 - val loss: 0.0216 - val accuracy: 0.9933
```

Evaluating the model

```
In [8]:
```

```
score = model.evaluate(test_X, test_y, verbose=0)
print('Test Score = ',score[0])
print('Test Accuracy =', score[1])
```

```
Test Score = 0.0032084500417113304
Test Accuracy = 0.998031497001648
```

Part 2: Reading the Sudoku

Random Selection of an Image

```
In [79]:
```

```
folder=r"../input/sudoku-box-detection/aug"
```

```
a=random.choice(os.listdir(folder))
print(a)
sudoku_a = cv2.imread(folder+'/'+a)
plt.figure()
plt.imshow(sudoku_a)
plt.show()
```

```
_197_2443114.jpeg
```

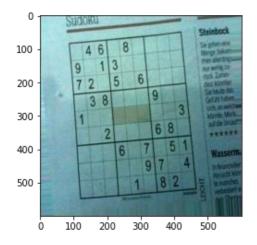


Image preprocessing

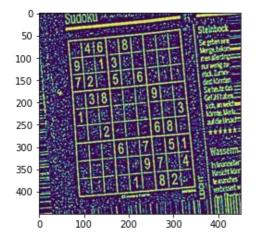
```
In [80]:
```

```
sudoku_a = cv2.resize(sudoku_a, (450,450))

# function to greyscale, blur and change the receptive threshold of image
def preprocess(image):
    gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
    blur = cv2.GaussianBlur(gray, (3,3),6)
    #blur = cv2.bilateralFilter(gray,9,75,75)
    threshold_img = cv2.adaptiveThreshold(blur,255,1,1,11,2)
    return threshold_img

threshold = preprocess(sudoku_a)

plt.figure()
plt.imshow(threshold)
plt.show()
```



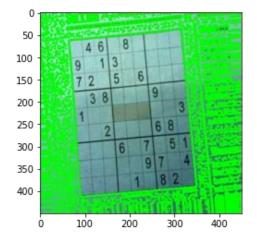
Contour Detection

```
In [81]:
```

Finding the outline of the sudoku puzzle in the image

```
contour_1 = sudoku_a.copy()
contour_2 = sudoku_a.copy()
contour, hierarchy = cv2.findContours(threshold,cv2.RETR_EXTERNAL,cv2.CHAIN_APPROX_SIMPLE
)
cv2.drawContours(contour_1, contour,-1,(0,255,0),3)

plt.figure()
plt.imshow(contour_1)
plt.show()
```

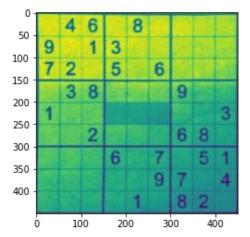


In [82]:

```
def main outline (contour):
   biggest = np.array([])
   max area = 0
    for i in contour:
        area = cv2.contourArea(i)
        if area >50:
            peri = cv2.arcLength(i, True)
            approx = cv2.approxPolyDP(i , 0.02* peri, True)
            if area > max area and len(approx) ==4:
                biggest = approx
                max area = area
    return biggest ,max_area
def reframe(points):
   points = points.reshape((4, 2))
   points new = np.zeros((4,1,2),dtype = np.int32)
    add = points.sum(1)
   points_new[0] = points[np.argmin(add)]
   points new[3] = points[np.argmax(add)]
   diff = np.diff(points, axis =1)
   points new[1] = points[np.argmin(diff)]
   points new[2] = points[np.argmax(diff)]
   return points new
def splitcells(img):
    rows = np.vsplit(img,9)
   boxes = []
    for r in rows:
        cols = np.hsplit(r, 9)
        for box in cols:
            boxes.append(box)
    return boxes
black_img = np.zeros((450,450,3), np.uint8)
biggest, maxArea = main_outline(contour)
if biggest.size != 0:
   biggest = reframe(biggest)
    cv2.drawContours(contour 2, biggest, -1, (0, 255, 0), 10)
   pts1 = np.float32(biggest)
   pts2 = np.float32([[0,0],[450,0],[0,450],[450,450]])
   matrix = cv2.getPerspectiveTransform(pts1,pts2)
    imagewrap = cv2.warpPerspective(sudoku a, matrix, (450, 450))
```

```
imagewrap =cv2.cvtColor(imagewrap, cv2.COLOR_BGR2GRAY)

plt.figure()
plt.imshow(imagewrap)
plt.show()
```

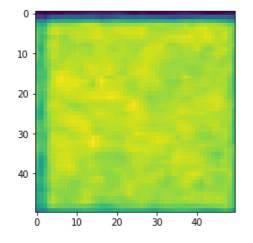


Splitting cells and classifying the digits

```
In [83]:
```

```
sudoku_cell = splitcells(imagewrap)

plt.figure()
plt.imshow(sudoku_cell[58])
plt.show()
```



In [84]:

```
def CropCell(cells):
    Cells_croped = []
    for image in cells:

        img = np.array(image)
        img = img[4:46, 6:46]
        img = Image.fromarray(img)
        Cells_croped.append(img)

    return Cells_croped

sudoku_cell_croped= CropCell(sudoku_cell)
plt.figure()
plt.imshow(sudoku_cell_croped[58])
plt.show()
```

```
0
5
10
```

```
15 -
20 -
25 -
30 -
35 -
40 -
0 10 20 30
```

```
In [85]:
```

```
def read_cells(cell, model):
    result = []
    for image in cell:
        # preprocess the image as it was in the model
        img = np.asarray(image)
        img = img[4:img.shape[0] - 4, 4:img.shape[1] - 4]
        img = cv2.resize(img, (32, 32))
        img = img / 255
        img = img.reshape(1, 32, 32, 1)
        # getting predictions and setting the values if probabilities are above 65%
        predictions = model.predict(img)
        classIndex = model.predict classes(img)
        probabilityValue = np.amax(predictions)
        if probabilityValue > 0.65:
            result.append(classIndex[0])
        else:
           result.append(0)
    return result
grid = read cells(sudoku cell croped, model)
grid = np.asarray(grid)
```

Part 3: Solving the Sudoku

```
In [86]:
```

```
grid = np.reshape(grid, (9,9))
grid
```

Out[86]:

In [87]:

```
plt.figure()
plt.imshow(imagewrap)
plt.show()
```



```
250

300

350

400

2 6 7 5 1

9 7 4

1 8 2
```

In [88]:

```
#This function finds the next box to solve
def next box(quiz):
    for row in range(9):
        for col in range(9):
            if quiz[row][col] == 0:
                return (row, col)
    return False
#Function to fill in the possible values by evaluating rows collumns and smaller cells
def possible (quiz,row, col, n):
    #global quiz
    for i in range (0,9):
        if quiz[row][i] == n and row != i:
            return False
    for i in range (0,9):
        if quiz[i][col] == n and col != i:
            return False
    row0 = (row) //3
    col0 = (col)//3
    for i in range(row0*3, row0*3 + 3):
        for j in range (col0*3, col0*3 + 3):
            if quiz[i][j] == n and (i,j) != (row, col):
                return False
    return True
#Recursion function to loop over untill a valid answer is found.
def solve (quiz):
   val = next box(quiz)
   if val is False:
       return True
    else:
        row, col = val
        for n in range (1,10): #n is the possible solution
            if possible(quiz,row, col, n):
                quiz[row][col]=n
                if solve (quiz):
                    return True
                else:
                    quiz[row][col]=0
        return
def Solved(quiz):
    for row in range(9):
        if row % 3 == 0 and row != 0:
            print("....")
        for col in range(9):
            if col % 3 == 0 and col != 0:
                print("|", end=" ")
            if col == 8:
                print(quiz[row][col])
            else:
                print(str(quiz[row][col]) + " ", end="")
```

```
solve(grid)
Out[89]:
True
In [90]:
if solve(grid):
   Solved(grid)
else:
print("Solution don't exist. Model misread digits.")
1 4 6 | 1 2 3 | 5 7 9
9 8 5 | 4 7 8 | 1 6 2
7 2 3 | 5 9 6 | 4 3 8
1 3 8 | 2 6 5 | 9 4 7
6 5 7 | 9 8 4 | 2 1 3
4 9 2 | 7 3 1 | 6 8 5
2 8 4 | 6 5 7 | 3 9 1
3 6 1 | 2 8 9 | 7 5 4
5 7 9 | 3 4 1 | 8 2 6
```