

HW 11

# Problem 1

a. Signal 1:

2	1	2	1
-2		-2	
2	2	-2	
-2	-2	-2	
-2	-2	-2	
-2	2	2	
2	-2	-2	
-2	2	2	
2	2	2	

Using Python  $\Rightarrow$

40
-8
8
-8
8
8
-40
8
-8
8
-8

b. Signal 2:

1
2
3
4
5
6
7
6
5
4

Using Python  $\Rightarrow$

217
208
193
176
161
156
161
176
193
208

b. Cross-Correlate

2	7	1
-2		2
2	3	
-2	4	
-2	5	
-2	6	
2	7	
-2	6	
2	5	
2	4	

Using Python  $\Rightarrow$

-6
6
10
22
18
6
-6
-10
-22
-18

## Problem 2

- a. The values are fairly small until the massive spike to  $\sim 1000$ . Therefore, the autocorrelation at the 0 offset is large.
- b. The values are very small and only have a range from -80 - 80.
- c. The shape of the graph is very similar to that of the cross-correlation between satellite 10 and 13. This means that the random signal does not match satellite 13. We can identify the satellites by doing cross-correlation and observe which one is highest.
- d. The graph is still similar to part (b) and (c). This means that the gaussian noise creates "static" or noise that jumbles up the values.
- e. The satellites are 4, 17, 13 and 19.
- f. The satellite is Gold code satellite 3.  
The sequence is [1, -1, -1, -1, 1]
- g. I expect the values of the cross-correlation to be significantly higher with the proper satellite than the other ones.

The satellites are 5 and 20. The relative delay is 506 samples

### Problem 3

- a. The largest inner products is where  $\vec{s}_1 \cdot \vec{o}$  is always, seemingly less than 0.1.
- b. Yes, we can find the delay b/c the peaks occur at different times.  
This works b/c we are able to see at which time the signal  $\vec{y}$  is most similar to  $\vec{s}_1^{(i)}$ .
- c. The  $K_{\vec{s}_1, \vec{n}} > 1$  is very small and is never higher than 0.1. This closely relates to the signal b/c they are around the same values.
- d. Yes we can find the delay. This works b/c there is only one peak and all the other values.
- e. The cross-correlation still works for  $\vec{y} = \vec{s}_1^{(i)} + \vec{n}$  b/c there is still a distinct peak.  
However, the cross-correlation does not  $\vec{y} = \vec{s}_1^{(i)} + 10\vec{n}$  b/c there is too much noise for there to be a distinct label.
- f. Yes, we can find the delays b/c there are two different distinct points where peaks occur.
- g. Yes, we can find signal 1 b/c there is a distinct point where a peak occurs.  
However, we cannot find signal 2 b/c there is too much noise.
- h. Yes, this does work. This works b/c the signal  $s_1$  has a larger peak and thus the cross-correlation becomes more distinct. Thus when you subtract  $s_1$ ,  $s_2$  becomes clearer.

### Problem 3 cont.

- i Yes we can use inner-products to find the amplitudes b/c the signal is normalized so we get an amplitude that is not multiplied by some factor.  
They are very close b/c they are off by very small margins.
- j The amplitudes are still very close b/c the amplitudes are off by only a small margin.

# Problem 4.

a.  $A = \begin{bmatrix} 2 \\ 4 \\ 6 \\ 8 \end{bmatrix}$        $b = \begin{bmatrix} 3 \\ 6 \\ 7 \\ 8 \end{bmatrix}$

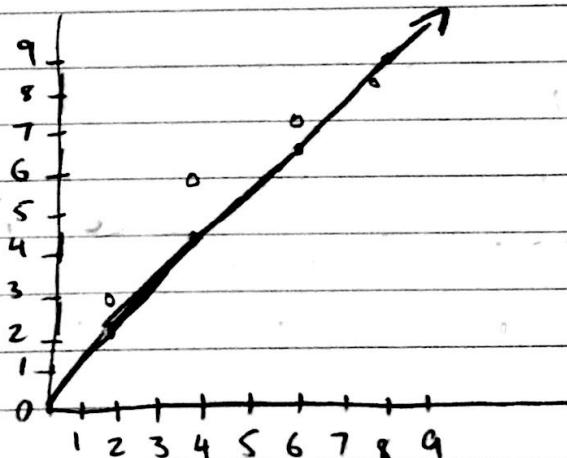
$$A^T A = [2 \ 4 \ 6 \ 8] \begin{bmatrix} 2 \\ 4 \\ 6 \\ 8 \end{bmatrix} = 4 + 16 + 36 + 64 = 120$$

$$A^T b = [2 \ 4 \ 6 \ 8] \begin{bmatrix} 3 \\ 6 \\ 7 \\ 8 \end{bmatrix} = 6 + 24 + 42 + 64 = 30 + 106 = 136$$

$$x = \frac{136}{120} = \frac{68}{60} = \frac{34}{30} = \boxed{\frac{17}{15}} \quad \frac{17}{15} \begin{bmatrix} 2 \\ 4 \\ 6 \\ 8 \end{bmatrix} = \begin{bmatrix} \frac{34}{15} \\ \frac{68}{15} \\ \frac{102}{15} \\ \frac{136}{15} \end{bmatrix}$$

$$\left( \begin{bmatrix} 3 \\ 6 \\ 7 \\ 8 \end{bmatrix} - \begin{bmatrix} \frac{34}{15} \\ \frac{68}{15} \\ \frac{102}{15} \\ \frac{136}{15} \end{bmatrix} \right)^T$$

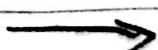
$$\text{Error: } \boxed{3.867} \quad \frac{58}{15}$$



b.  $A = \begin{bmatrix} 2 & 1 \\ 4 & 1 \\ 6 & 1 \\ 8 & 1 \end{bmatrix}$        $A^T A = \begin{bmatrix} 2 & 4 & 6 & 8 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 4 & 1 \\ 6 & 1 \\ 8 & 1 \end{bmatrix} = \begin{bmatrix} 120 & 20 \\ 20 & 4 \end{bmatrix}$

$$A^T A^{-1} = \frac{1}{20} \begin{bmatrix} 1 & -5 \\ -5 & 30 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 2 & 4 & 6 & 8 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 6 \\ 7 \\ 8 \end{bmatrix} = \begin{bmatrix} 136 \\ 24 \end{bmatrix} \quad (A^T A)^{-1} A^T b = \frac{1}{20} \begin{bmatrix} 1 & -5 \\ -5 & 30 \end{bmatrix} \begin{bmatrix} 136 \\ 24 \end{bmatrix} = \begin{bmatrix} 4/5 \\ 2 \end{bmatrix}$$

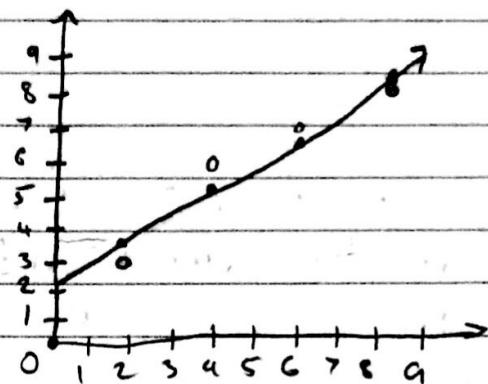


b. cont.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4/5 \\ 2 \end{bmatrix} \quad A\hat{x} = \hat{b} = \begin{bmatrix} 2 & 1 \\ 4 & 1 \\ 6 & 1 \\ 8 & 1 \end{bmatrix} \begin{bmatrix} 4/5 \\ 2 \end{bmatrix} = \begin{bmatrix} 18/5 \\ 26/5 \\ 34/5 \\ 42/5 \end{bmatrix}$$

$$\text{Error} = \left\| \begin{bmatrix} 3 \\ 6 \\ 7 \\ 8 \end{bmatrix} - \begin{bmatrix} 18/5 \\ 26/5 \\ 34/5 \\ 42/5 \end{bmatrix} \right\|^2$$

$$= \boxed{1.2}$$



This plot fits the data much better  
b/c the error is lower

c. Suppose  $\hat{b} = A\hat{x} = A(A^T A)^{-1} A^T b$

Consider  $\vec{x}_2 = \vec{A}\vec{x}$

$$\vec{x}_2^T (\vec{b} - \hat{b}) = \cancel{\vec{x}^T A^T} \underbrace{(\vec{b} - A(A^T A)^{-1} A^T b)}_{= 0} = \vec{x}^T (A^T b - A^T A(A^T A)^{-1} A^T b)$$

$$= \vec{x}^T (A^T b - A^T b) = \vec{x}^T (0), \quad \text{B/C } A^T (\vec{b} - \hat{b}) = 0, \text{ we can show}$$

that the error vector is  $\perp$  to the columns of  $A$ .

# Problem 5

a.  $\begin{matrix} & 3 \\ \begin{bmatrix} 1 & 1 & 1 \\ x^2 + xy & x & y \\ 1 & 1 & 1 \end{bmatrix} & A^T A \quad \underline{3 \times n \quad n \times 3} \end{matrix}$

$$A = \begin{bmatrix} 0.5661 & 0.3 & -0.69 \\ 1.0069 & 0.5 & 0.87 \\ 1.5496 & 0.9 & -0.86 \\ 1.7744 & 1 & 0.88 \\ 2.1124 & 1.2 & -0.82 \\ 2.6593 & 1.5 & 0.64 \\ 3.24 & 1.8 & 0 \end{bmatrix} \quad \vec{x} = \begin{bmatrix} a \\ d \\ e \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \vec{e} = \vec{b} - \vec{a}$$

$$= \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \\ c_7 \end{bmatrix}$$

b.  $A = \begin{bmatrix} x^2 & xy & y^2 & x & y \end{bmatrix} = \begin{bmatrix} 0.09 & -0.207 & 0.4761 & 0.3 & -0.69 \\ 0.25 & 0.435 & 0.7569 & 0.5 & 0.87 \\ 0.81 & -0.774 & 0.7396 & 0.9 & -0.86 \\ 1 & 0.88 & 0.7744 & 1 & 0.88 \\ 1.44 & -0.984 & 0.6724 & 1.2 & -0.82 \\ 2.25 & 0.96 & 0.4096 & 1.5 & 0.64 \\ 3.24 & 0 & 0 & 1.8 & 0 \end{bmatrix}$

$$\vec{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \vec{x} = \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix}$$

$$\vec{e} = \vec{c}_1 - \vec{b} = \vec{b} - A\vec{x}$$

$e_1$   
 $e_2$   
 $e_3$   
 $e_4$   
 $e_5$   
 $e_6$   
 $e_7$

c. 
$$\frac{\|c\|^4}{N} = 0.1375$$

d. 
$$\frac{\|ell\|^4}{N} = 0.01285$$

The error is significantly lower than the error for the circle.  
This concludes that the ellipse technique is better.

## Problem - 6

Question.

Given  $x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  and  $y = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$ , find the best-fit curve in the form  $y = x_1 x + x_2$ .

Solution:

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 14 & 6 \\ 6 & 3 \end{bmatrix} \quad A^T b = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 19 \\ 8 \end{bmatrix}$$

$$A^T A^{-1} = \frac{1}{6} \begin{bmatrix} 3 & -6 \\ -6 & 14 \end{bmatrix} \quad (A^T A)^{-1} A^T b = \frac{1}{6} \begin{bmatrix} 3 & -6 \\ -6 & 14 \end{bmatrix} \begin{bmatrix} 19 \\ 8 \end{bmatrix} = \begin{bmatrix} 3/2 \\ -1/3 \end{bmatrix}$$

Solution

$$y = \frac{3}{2}x - \frac{1}{3}$$

7.

**I worked by myself with no study group. I went to office hours both Friday and Monday in order to get my work done.**

# prob11

November 20, 2017

## 1 EE16A Homework 11

### 1.1 Question 1: Mechanical Correlation

```
In [1]: # Any IPython code here
%pylab inline
import numpy as np
import matplotlib.pyplot as plt
import scipy.io
import sys

a = np.array([2, -2, 2, -2, -2, -2, 2, -2, 2, 2])
b = np.array([2, -2, 2, -2, -2, -2, 2, -2, 2, 2])

c = []

for x in range(a.shape[0]):
    value = np.dot(np.transpose(a), b)
    c.append(value)
    b = np.roll(b, 1)

print(c)

d = np.array([1, 2, 3, 4, 5, 6, 7, 6, 5, 4])
e = np.array([1, 2, 3, 4, 5, 6, 7, 6, 5, 4])

f = []

for x in range(d.shape[0]):
    value = np.dot(np.transpose(d), e)
    f.append(value)
    e = np.roll(e, 1)

print(f)
```

Populating the interactive namespace from numpy and matplotlib  
[40, -8, 8, -8, 8, -40, 8, -8, 8, -8]

```
[217, 208, 193, 176, 161, 156, 161, 176, 193, 208]
```

```
In [2]: signal1 = np.array([2, -2, 2, -2, -2, -2, 2, -2, 2, 2])
    signal2 = np.array([1, 2, 3, 4, 5, 6, 7, 6, 5, 4])
    cross_corr = []
    for x in range(signal1.shape[0]):
        value = np.dot(np.transpose(signal1), signal2)
        cross_corr.append(value)
        signal2 = np.roll(signal2, 1)

print(cross_corr)
```

```
[-6, 6, 10, 22, 18, 6, -6, -10, -22, -18]
```

## 1.2 Question 2: GPS Receivers

```
In [3]: %pylab inline
import numpy as np
import matplotlib.pyplot as plt
import scipy.io
import sys
```

Populating the interactive namespace from numpy and matplotlib

```
/Users/aatifjiwani/anaconda3/lib/python3.6/site-packages/IPython/core/magics/pylab.py:161: UserWarning: `~%matplotlib` prevents importing * from pylab and numpy
"\\n`%matplotlib` prevents importing * from pylab and numpy"
```

```
In [4]: ## RUN THIS FUNCTION BEFORE YOU START THIS PROBLEM
## This function will generate the gold code associated with the satellite ID using linear feedback shift register
## The satellite_ID can be any integer between 1 and 24
def Gold_code_satellite(satellite_ID):
    codelength = 1023
    registerlength = 10

    # Defining the MLS for G1 generator
    register1 = -1*np.ones(registerlength)
    MLS1 = np.zeros(codelength)
    for i in range(codelength):
        MLS1[i] = register1[9]
        modulo = register1[2]*register1[9]
        register1 = np.roll(register1,1)
        register1[0] = modulo

    # Defining the MLS for G2 generator
```

```

register2 = -1*np.ones(registerlength)
MLS2 = np.zeros(codelength)
for j in range(codelength):
    MLS2[j] = register2[9]
modulo = register2[1]*register2[2]*register2[5]*register2[7]*register2[8]*register2[9]
register2 = np.roll(register2,1)
register2[0] = modulo

delay = np.array([5,6,7,8,17,18,139,140,141,251,252,254,255,256,257,258,469,470,471])
G1_out = MLS1;
shamt = delay[satellite_ID - 1]
G2_out = np.roll(MLS2,shamt)

CA_code = G1_out * G2_out

return CA_code

```

### 1.2.1 Part (a)

```

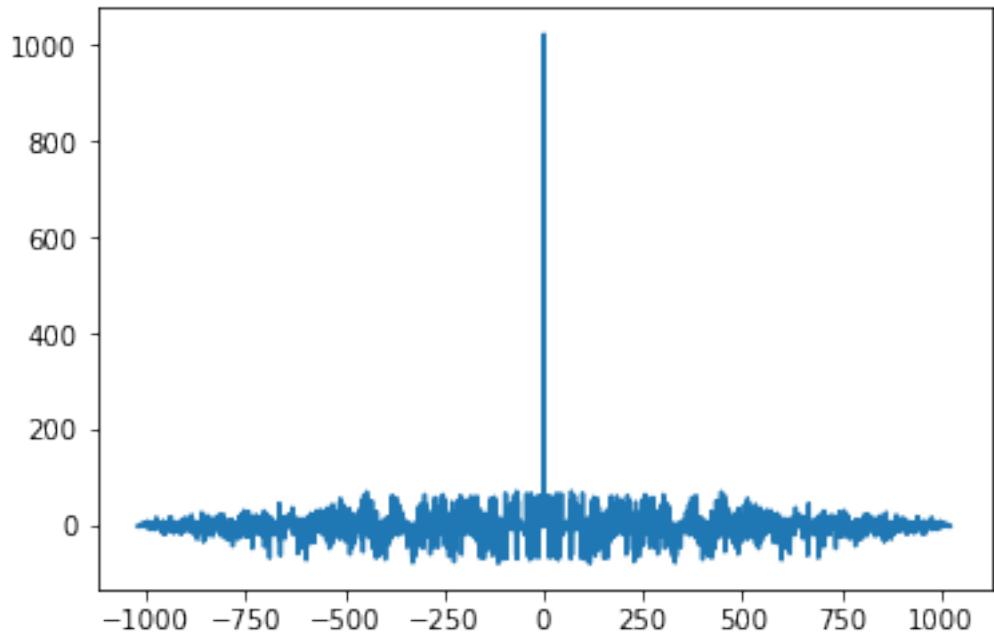
In [5]: def array_correlation(array1, array2):
    """ This function should return two arrays or a matrix with one row corresponding
    the offset and other to the correlation value
    """
    ## YOUR CODE HERE
    ## Use np.correlate with "FULL". Check out the documentation page.
    correlate = np.correlate(array1, array2, "FULL")
    offset = [(k - len(correlate)/2 + 1) for k in range(len(correlate))]
    return correlate, offset

# Plot the auto-correlation of satellite 10 with itself. Your signal should be centered
# at offset = 0.
# Use plt.plot or plt.stem to plot.
array1 = Gold_code_satellite(10)
array2 = Gold_code_satellite(10)
x, y = array_correlation(array1, array2)
plt.plot(y, x)

# YOUR CODE HERE

```

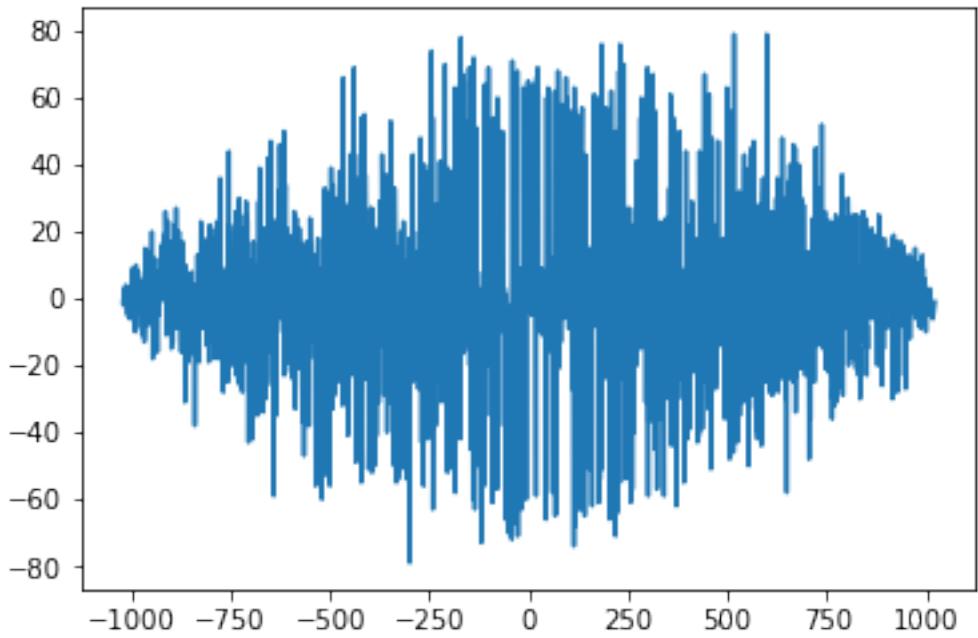
Out[5]: [`<matplotlib.lines.Line2D at 0x118326160>`]



### 1.2.2 Part (b)

```
In [6]: # YOUR CODE HERE
array1 = Gold_code_satellite(10)
array2 = Gold_code_satellite(13)
x, y = array_correlation(array1, array2)
plt.plot(y, x)
```

```
Out[6]: []
```

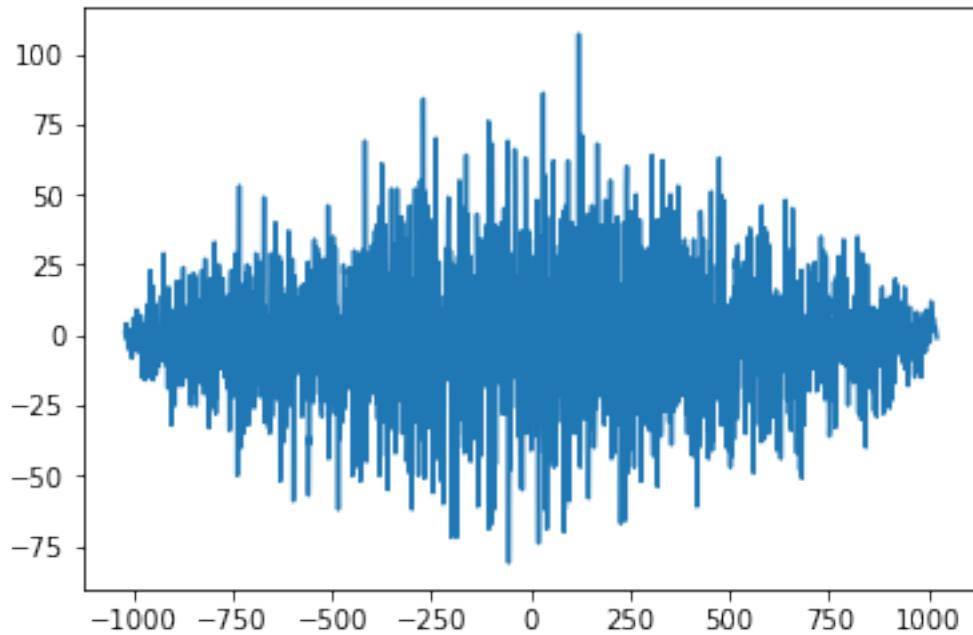


### 1.2.3 Part (c)

```
In [7]: ## THIS IS A HELPER FUNCTION FOR PART C
def integernoise_generator(length_of_noise):
    noise_array = np.random.randint(2, size = length_of_noise)
    noise_array = 2 * noise_array - np.ones(size(noise_array))
    return noise_array

# YOUR CODE HERE
randomarray = integernoise_generator(1023)
array1 = Gold_code_satellite(10)
x, y = array_correlation(array1, randomarray)
plt.plot(y, x)
```

```
Out[7]: [<matplotlib.lines.Line2D at 0x1186f7cc0>]
```

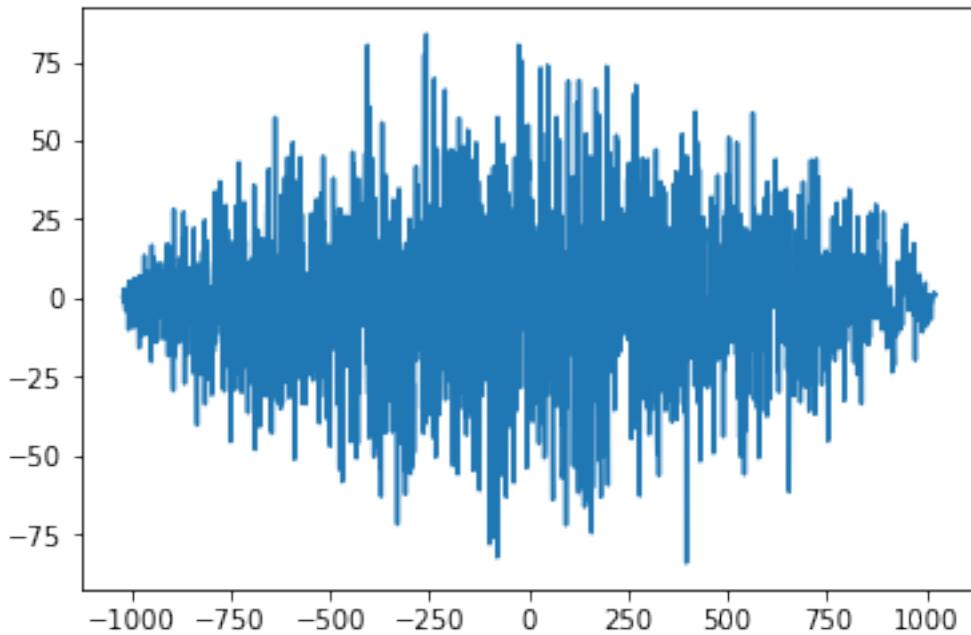


#### 1.2.4 Part (d)

```
In [8]: ## THIS IS A HELPER FUNCTION FOR PART D
def gaussiannoise_generator(length_of_noise):
    noise_array = np.random.normal(0, 1, length_of_noise)
    return noise_array

# YOUR CODE HERE
randomarray = gaussiannoise_generator(1023)
array1 = Gold_code_satellite(10)
x, y = array_correlation(array1, randomarray)
plt.plot(y, x)
```

```
Out[8]: [
```



### 1.2.5 Part (e)

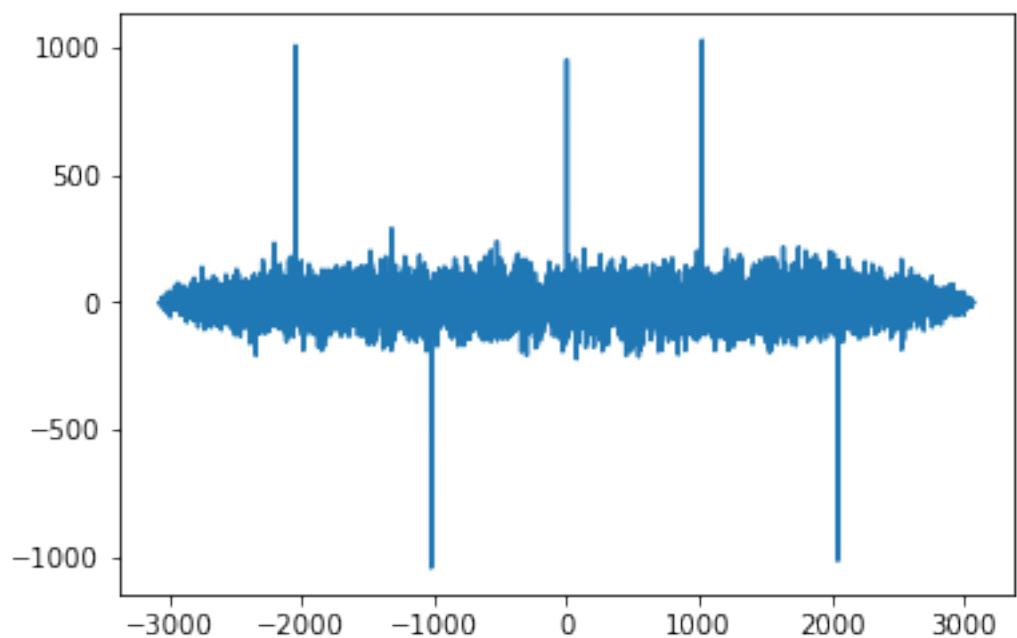
```
In [9]: ## USE 'np.load' FUNCTION TO LOAD THE DATA
## USE DATA1.NPY AS THE SIGNAL ARRAY

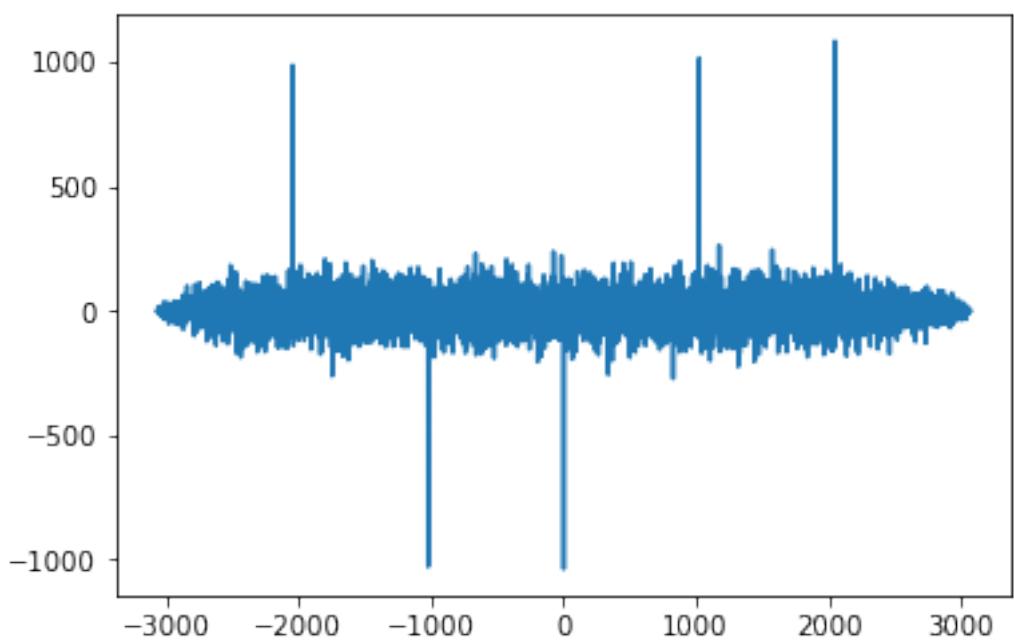
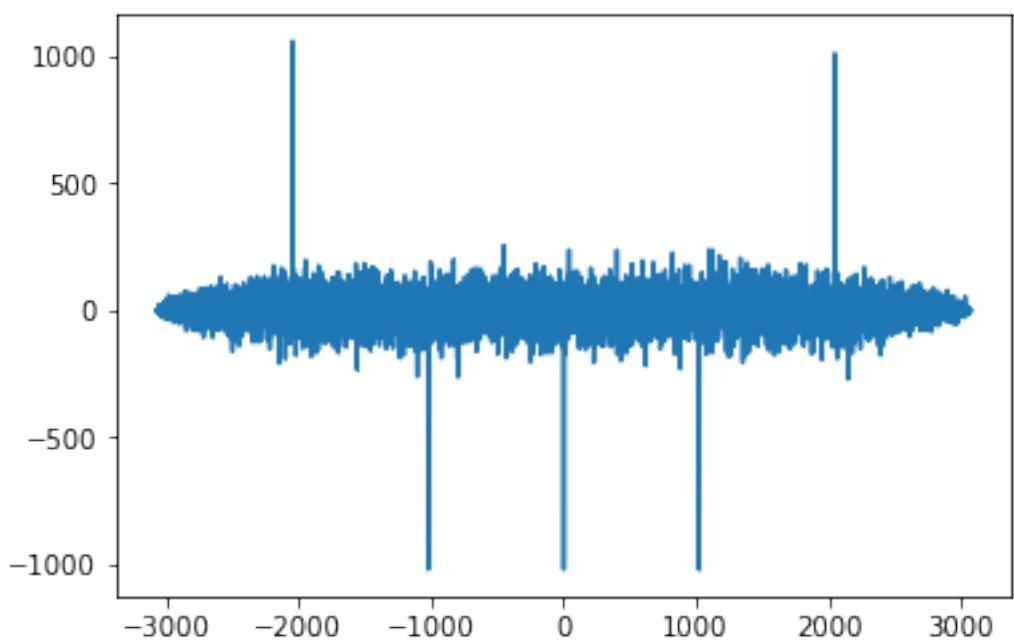
# YOUR CODE HERE
data = np.load("data1.npy")
for x in range(1, 25):
    gold_satellite = Gold_code_satellite(x)
    x, y = array_correlation(data, gold_satellite)
    print(max(x))

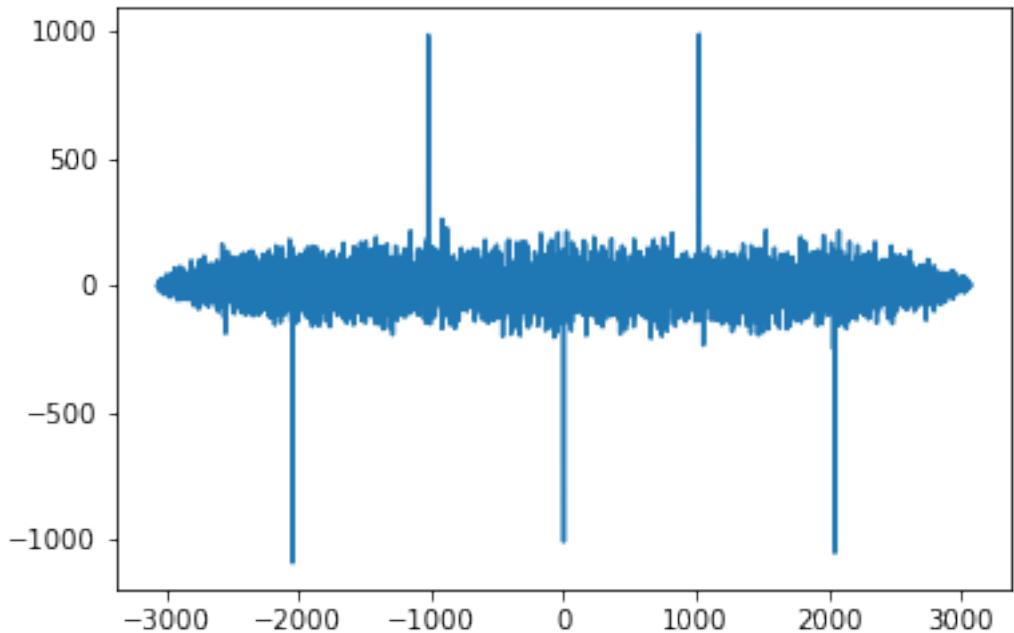
# 4 7 13 19
arr = [4, 7, 13, 19]
for x in arr:
    gold_satellite = Gold_code_satellite(x)
    x, y = array_correlation(data, gold_satellite)
    plt.plot(y, x)
    plt.figure()

306.066515658
245.099653007
299.365433408
1029.71556601
292.718281052
279.928206052
```

1057.68837212  
278.575821539  
216.606272817  
287.189517393  
253.64845426  
247.331691242  
1084.14887121  
265.069084198  
243.774824523  
268.518923482  
282.272830391  
242.824606907  
987.991784761  
246.872065605  
243.393295861  
280.289230731  
246.266997465  
268.470755486







```
<matplotlib.figure.Figure at 0x118cc1d68>
```

### 1.2.6 Part (f)

```
In [10]: ## USE DATA2.NPY AS THE SIGNAL ARRAY
```

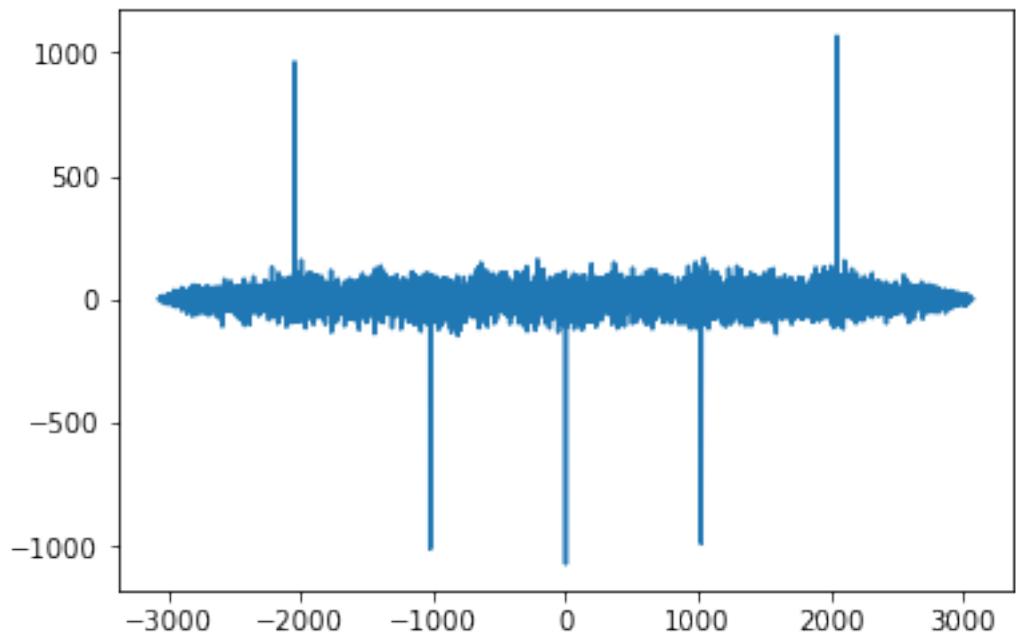
```
# YOUR CODE HERE
data = np.load("data2.npy")
for x in range(1, 25):
    gold_satellite = Gold_code_satellite(x)
    x, y = array_correlation(data, gold_satellite)
    print(max(x))

#3
gold_satellite = Gold_code_satellite(3)
x, y = array_correlation(data, gold_satellite)
plt.plot(y, x)
plt.figure()
```

```
157.940844998
177.330855364
1065.46213414
164.914018878
151.638961506
188.315106572
```

```
160.721501081
165.141125454
166.902354093
167.810004862
154.59619961
162.591649795
154.740096351
179.257269302
168.611703473
169.144643862
150.688491882
155.144874353
167.769166479
160.924503569
165.64737499
153.485615358
205.436619607
173.461766874
```

```
Out[10]: <matplotlib.figure.Figure at 0x10df2e358>
```



```
<matplotlib.figure.Figure at 0x10df2e358>
```

### 1.2.7 Part (g)

In [11]: *## USE DATA3.NPY AS THE SIGNAL ARRAY*

```
# YOUR CODE HERE
data = np.load("data3.npy")
for x in range(1, 25):
    gold_satellite = Gold_code_satellite(x)
    x, y = array_correlation(data, gold_satellite)
    print(max(x))

#5 20

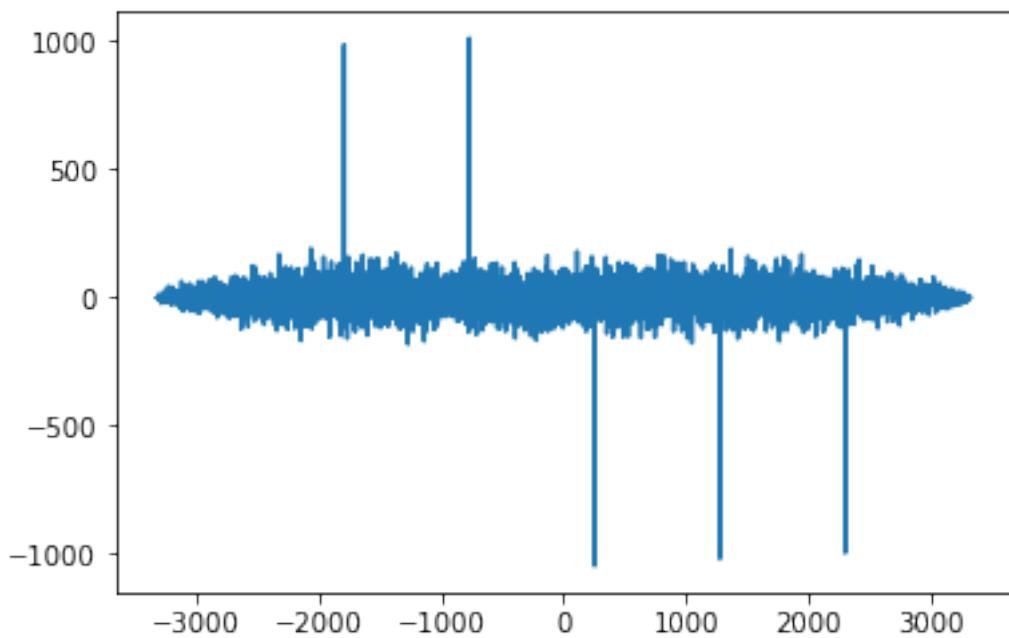
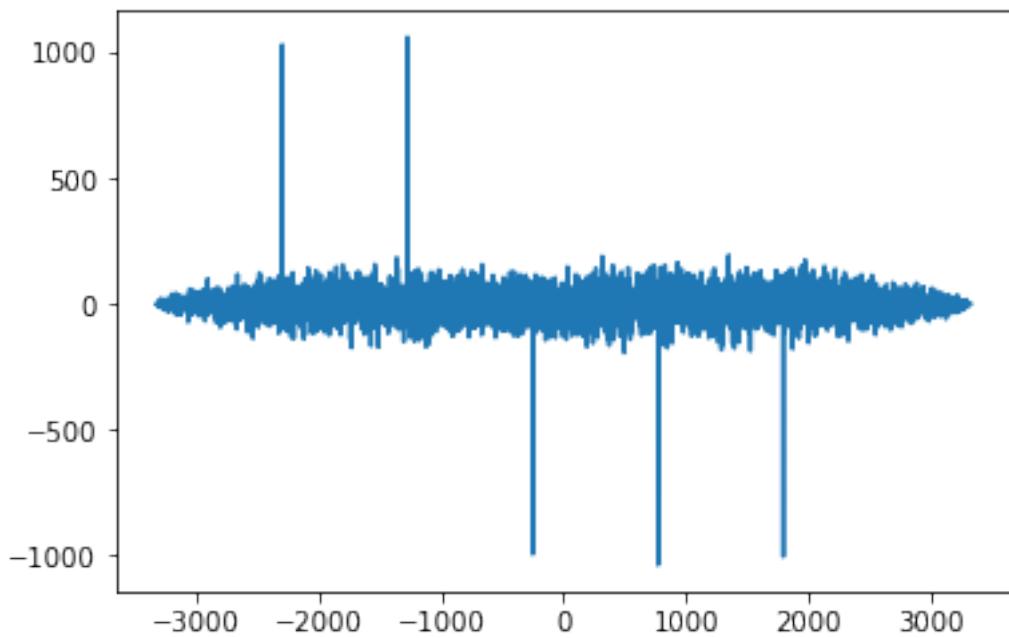
gold_satellite = Gold_code_satellite(5)
x_4, y_4 = array_correlation(data, gold_satellite)
plt.plot(y_4, x_4)
plt.figure()
print(np.argmax(x_4))

gold_satellite = Gold_code_satellite(20)
x_20, y_20 = array_correlation(data, gold_satellite)
plt.plot(y_20, x_20)
plt.figure()

print(np.argmax(x_20))

203.412060513
183.041201823
197.684194839
192.900391581
1062.8879826
196.667473199
196.837348295
194.558853532
184.680362336
212.502300883
196.245526004
205.581948421
190.460621463
202.327612241
201.688660911
202.418580195
205.51628162
203.954304576
224.216875585
1011.07973291
194.44925157
256.761024881
183.660513653
```

205.584553721  
2045  
2551



```
<matplotlib.figure.Figure at 0x1192d3860>
```

### 1.3 Question 3: Finding Signals in Noise

```
In [12]: %matplotlib inline
import numpy as np
import scipy as sp
import scipy.linalg as la
import pylab as plt
import numpy.random
```

```
In [13]: N = 1000
```

```
def rand_vector(n): # returns a random {+1, -1} vector of length n
    return np.random.randint(2, size=n)*2 - 1.0

def rand_normed_vector(n): # returns a random normalized vector of length n
    x = rand_vector(n)
    return x / la.norm(x)

def cross_corr(f, g):
    # returns the cross-correlation (a vector of all the inner products of 'g' with
    C = la.circulant(f)
    corr = C.T.dot(g)
    return corr
```

#### 1.3.1 Part (a)

```
In [14]: # Generate a random normalized vector for s1
# Running this cell again will generate a new random vector
s1 = rand_normed_vector(N)

# Compute all the inner products of s1 with shifted versions of s1
# (i.e., the cross-correlation of s1 with s1)
corr = cross_corr(s1, s1)

# The inner product <s1, s1^(1)> is:
print(corr[1])

# np.roll circularly shifts the signal,
# so the above inner product could be computed as:
print(np.dot(s1, np.roll(s1,1)))

# Plot the autocorrelation:
plt.title("Autocorrelation s1")
plt.plot(corr)
```

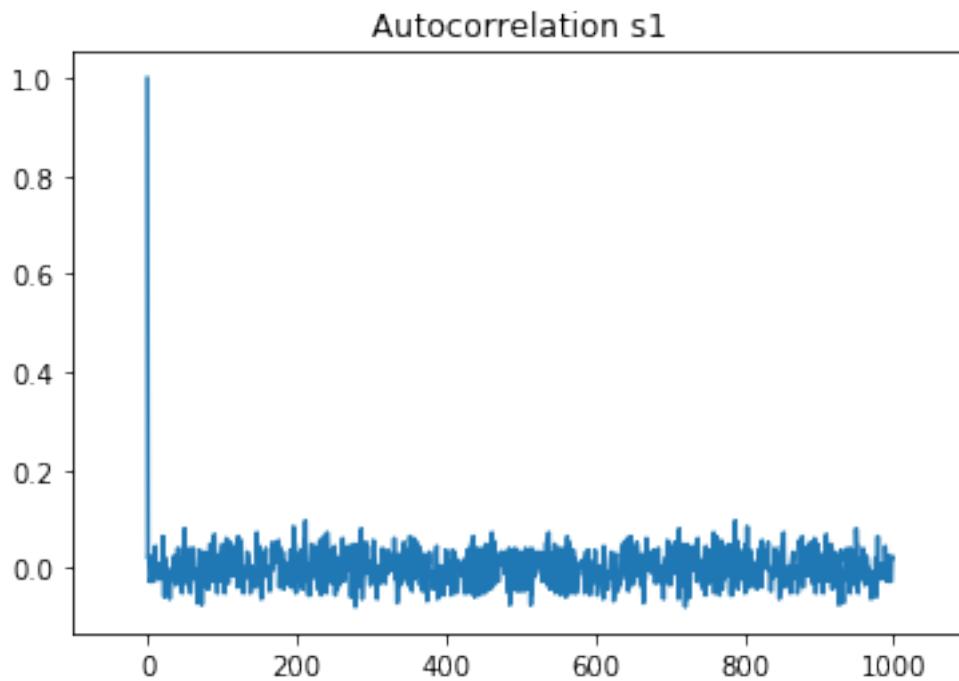
```

x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])

plt.show()

0.02
0.02

```



### 1.3.2 Part (b)

```

In [15]: y = np.roll(s1, 10) # Received y = s1 shifted by 10

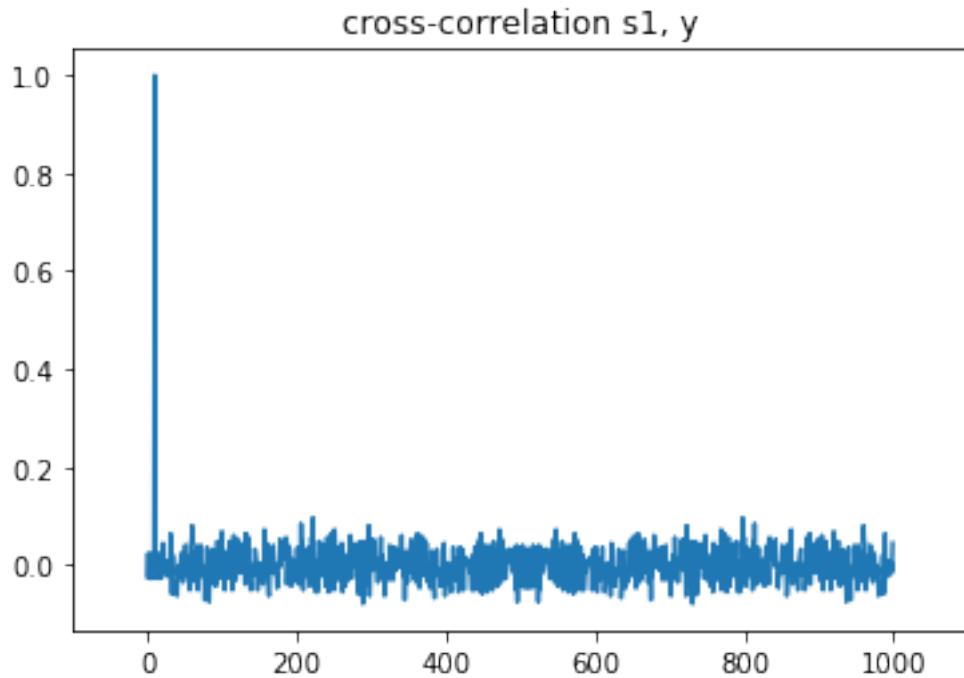
# Compute the cross-correlation (all the inner products of y with shifted versions of
corr = cross_corr(s1, y)

# Plot
plt.title("cross-correlation s1, y")
plt.plot(corr)

x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])
plt.show()

# Find the index of maximum correlation (inner product)
print(np.argmax(corr))

```



10

### 1.3.3 Part (c)

```
In [16]: # Generate a random normalized vector for s1
          # and a random normalized vector for n
          # Running this cell again will generate new random vectors
          s1 = rand_normed_vector(N)
          n = rand_normed_vector(N)

          print(np.abs(np.dot(s1, n)))
```

0.034

### 1.3.4 Part (d)

This is the code from part (b) but with the received signal  $\vec{y}$ , which is corrupted by noise.

```
In [17]: s1 = rand_normed_vector(N)
          n = rand_normed_vector(N)
          y = np.roll(s1, 10) + 0.1*n

          corr = cross_corr(s1, y)
```

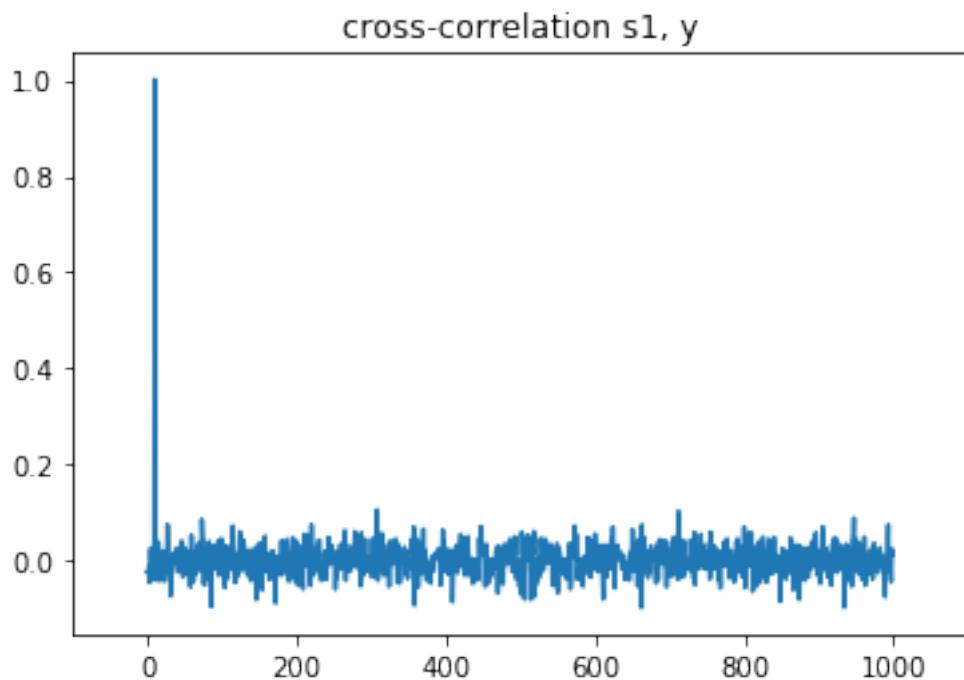
```

plt.title("cross-correlation s1, y")
plt.plot(corr)

x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])
plt.show()

# Find the index of maximum correlation (inner product)
np.argmax(corr)

```



Out [17]: 10

### 1.3.5 Part (e)

Copy the code provided for part (d), but modify it appropriately, so that the noise is higher. You should generate two cross-correlation plots, one for each noise level in the question. (You can just copy the code from part (d) twice.)

```

In [18]: s1 = rand_normed_vector(N)
          n = rand_normed_vector(N)
          y = np.roll(s1, 10) + n

          corr = cross_corr(s1, y)

```

```

plt.title("cross-correlation s1, y")
plt.plot(corr)

x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])
plt.show()

# Find the index of maximum correlation (inner product)
np.argmax(corr)

s1 = rand_normed_vector(N)
n = rand_normed_vector(N)
y = np.roll(s1, 10) + 10*n

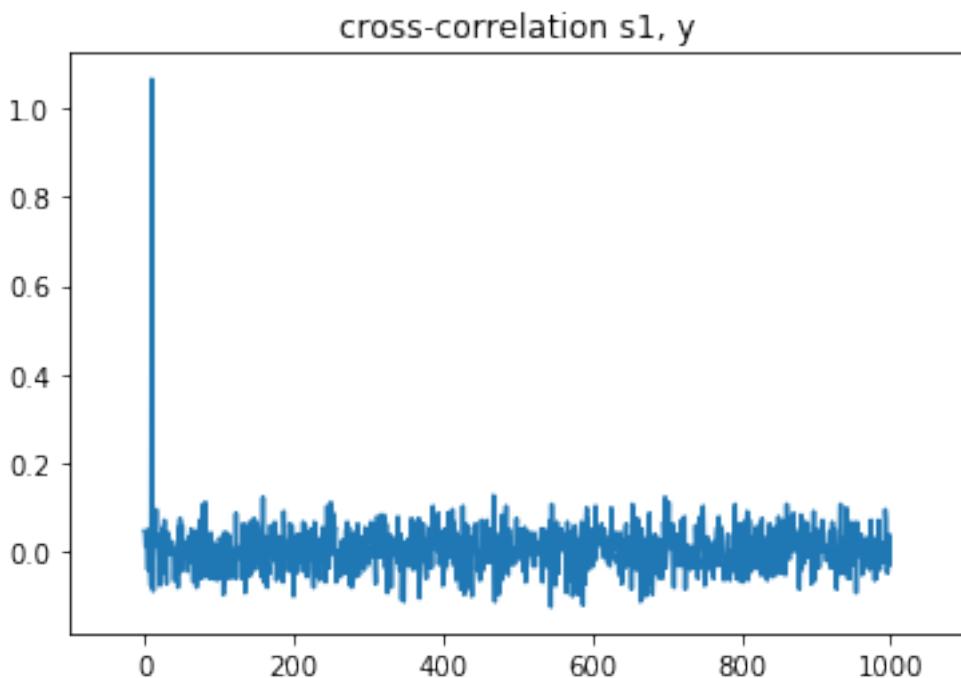
corr = cross_corr(s1, y)

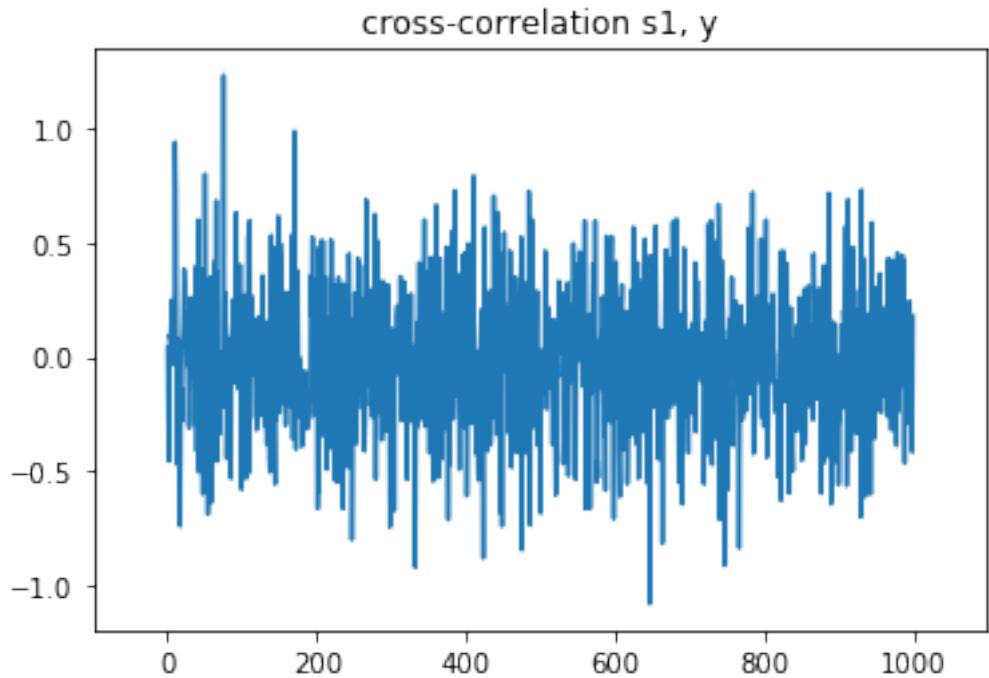
plt.title("cross-correlation s1, y")
plt.plot(corr)

x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])
plt.show()

# Find the index of maximum correlation (inner product)
np.argmax(corr)

```





Out [18]: 75

### 1.3.6 Part (f)

```
In [19]: s1 = rand_normed_vector(N)
          s2 = rand_normed_vector(N)

          y = np.roll(s1, 10) + np.roll(s2, 100)

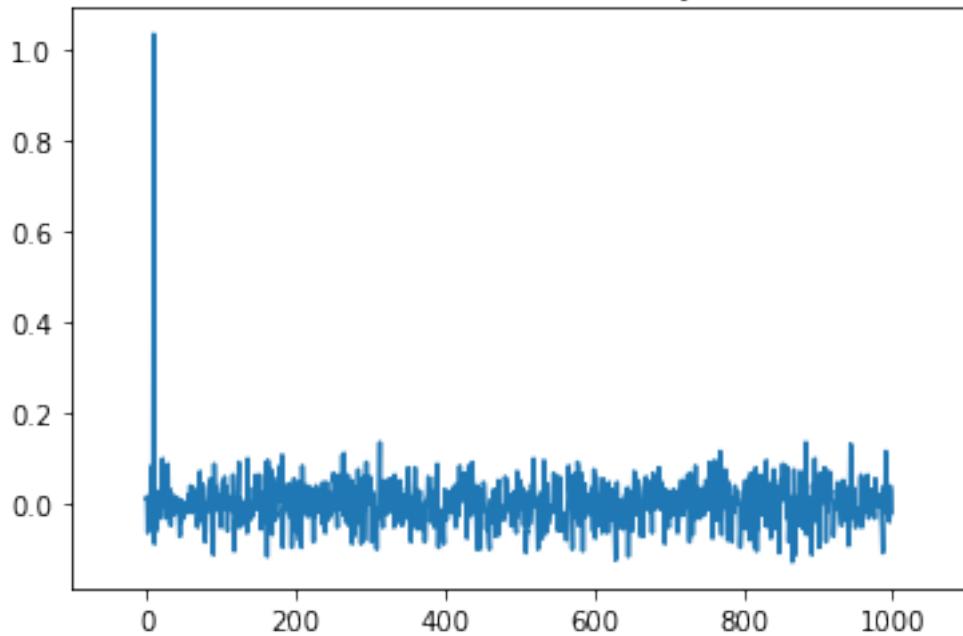
          # Compute cross-correlations:
          corr_s1_y = cross_corr(s1, y)
          corr_s2_y = cross_corr(s2, y)

          # Plot cross-correlations:
          plt.title("cross-correlation s1, y")
          plt.plot(cross_corr(s1, y))
          x1,x2,y1,y2 = plt.axis()
          plt.axis([x1-50,x2+50,y1,y2])
          plt.show()

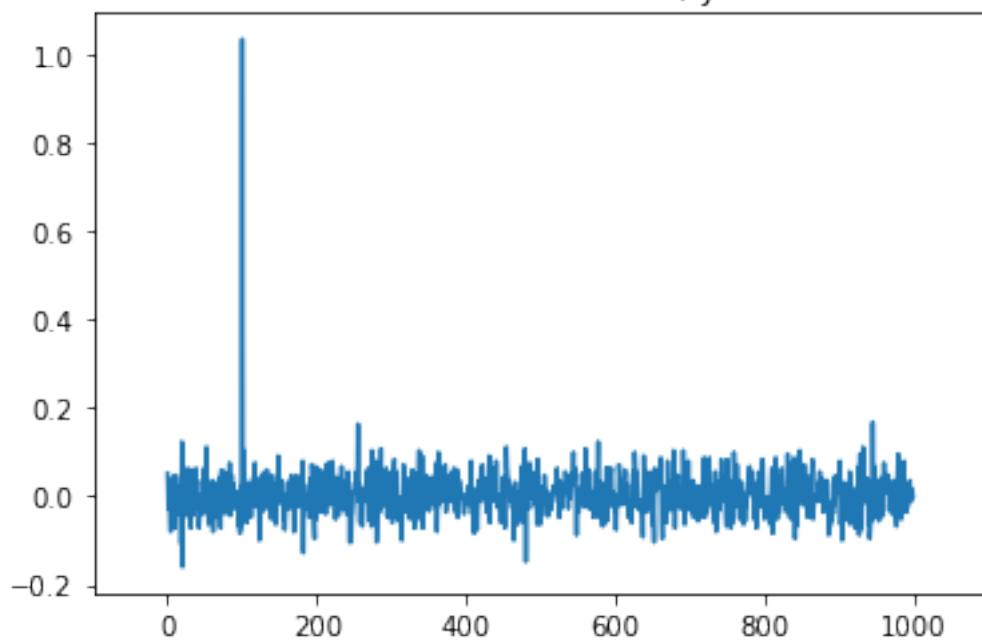
          plt.title("cross-correlation s2, y")
          plt.plot(cross_corr(s2, y))
          x1,x2,y1,y2 = plt.axis()
          plt.axis([x1-50,x2+50,y1,y2])
          plt.show()
```

```
j = np.argmax(corr_s1_y) # find the first signal delay (max index of correlation)
k = np.argmax(corr_s2_y) # find the second signal delay
print(j, k)
```

cross-correlation s1, y



cross-correlation s2, y



10 100

### 1.3.7 Part (g)

This is the same code as in part (f) but with a slight modification to how the received signal  $y$  is generated. Run the below cell a few times to test for different choices of random signals.

```
In [20]: s1 = rand_normed_vector(N)
          s2 = rand_normed_vector(N)

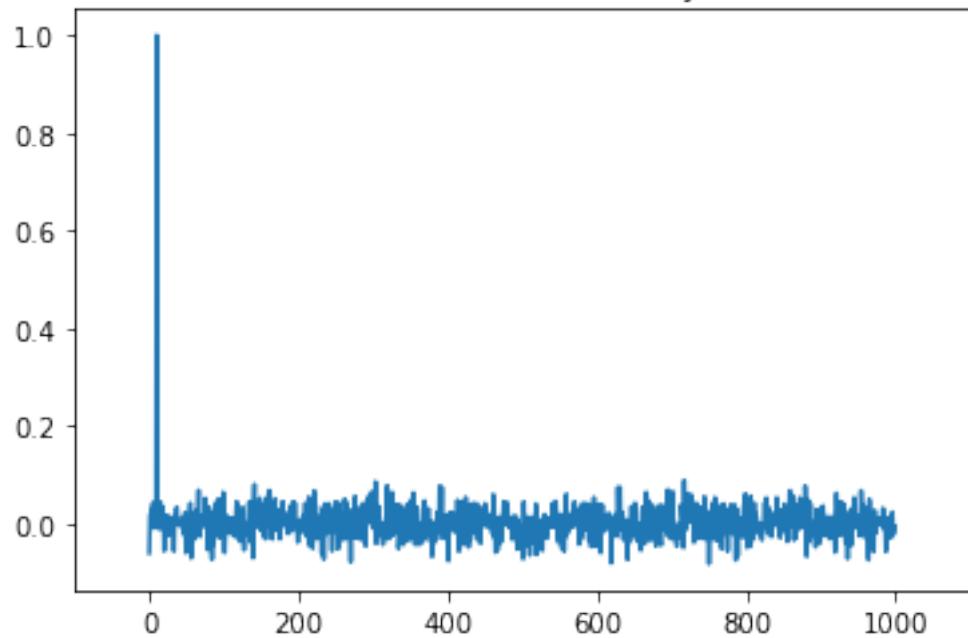
          y = np.roll(s1, 10) + 0.1*np.roll(s2, 100)

          # Compute cross-correlations:
          corr_s1_y = cross_corr(s1, y)
          corr_s2_y = cross_corr(s2, y)

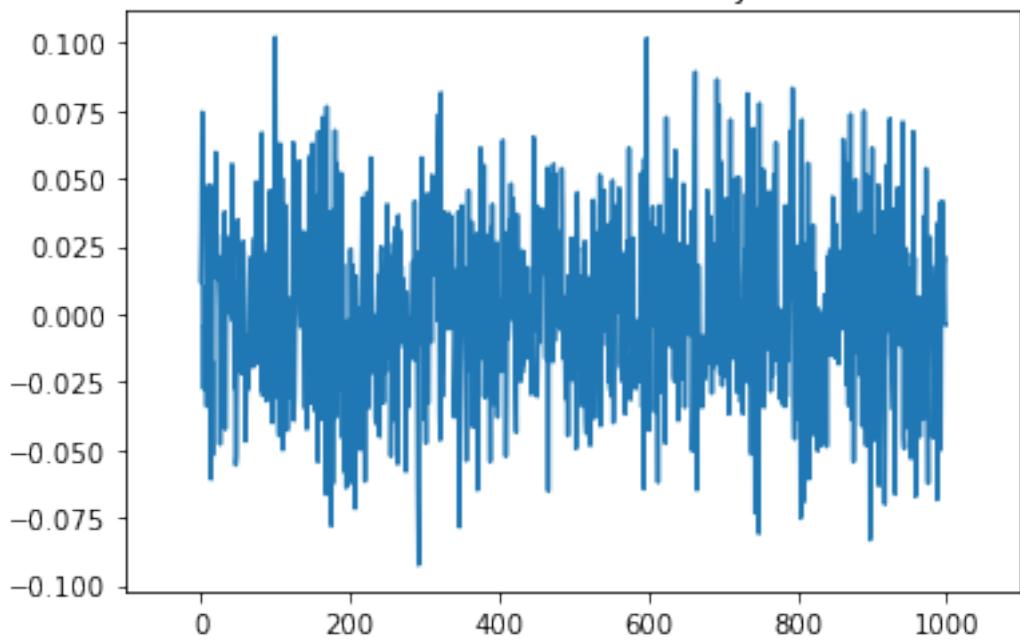
          # Plot cross-correlations:
          plt.title("cross-correlation s1, y")
          plt.plot(cross_corr(s1, y))
          x1,x2,y1,y2 = plt.axis()
          plt.axis([x1-50,x2+50,y1,y2])
          plt.show()

          plt.title("cross-correlation s2, y")
          plt.plot(cross_corr(s2, y))
          x1,x2,y1,y2 = plt.axis()
          plt.axis([x1-50,x2+50,y1,y2])
          plt.show()
```

cross-correlation s1, y



cross-correlation s2, y



### 1.3.8 Part (h)

```
In [21]: corr_s1_y = cross_corr(s1, y)
j = np.argmax(corr_s1_y) # find the first signal delay
print(j)

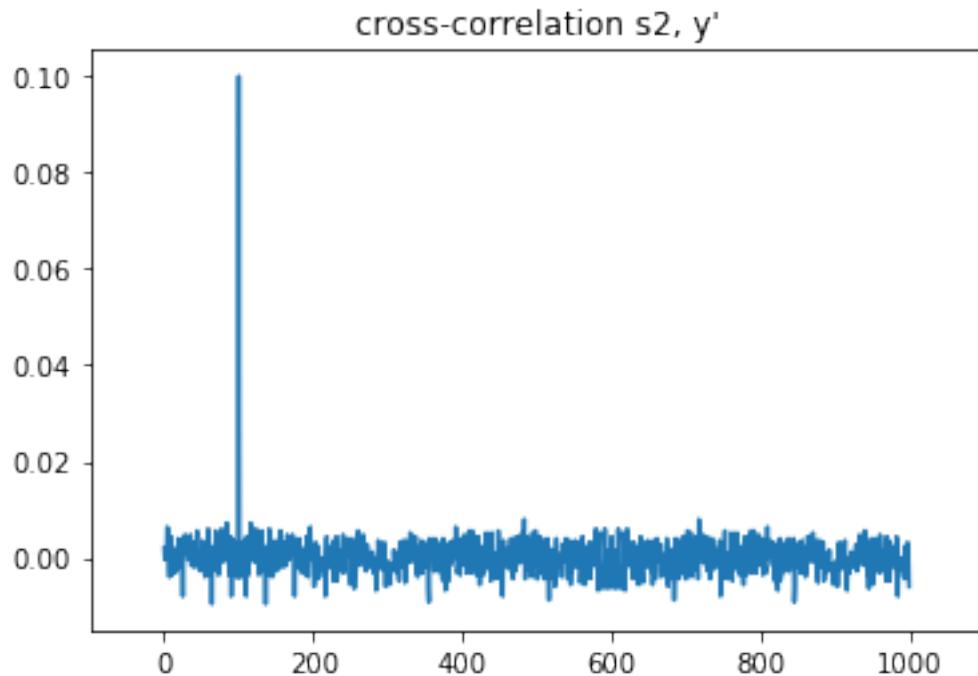
# Subtract out the contribution of the first signal
y_prime = y - np.roll(s1, j)

# Correlate the residual against the second signal
corr_s2_y = cross_corr(s2, y_prime)

# Plot
plt.title("cross-correlation s2, y'")
plt.plot(corr_s2_y)
x1,x2,y1,y2 = plt.axis()
plt.axis([x1-50,x2+50,y1,y2])
plt.show()

k = np.argmax(corr_s2_y) # find the second signal delay by looking at the index of max
print(k)
```

10



100

### 1.3.9 Part (i)

```
In [22]: s1 = rand_normed_vector(N)
          s2 = rand_normed_vector(N)

          y = 0.7*np.roll(s1, 10) + 0.5*np.roll(s2, 100)

          corr_s1_y = cross_corr(s1, y)
          j = np.argmax(corr_s1_y) # find the first signal delay

          corr_s2_y = cross_corr(s2, y)
          k = np.argmax(corr_s2_y) # find the second signal delay

          print(j, k)

          # Once we have found the shifts, estimate the coefficients as inner products:
          a1 = np.dot(y, np.roll(s1, j))
          a2 = np.dot(y, np.roll(s2, k))

          print(a1, a2)

10 100
0.698 0.4972
```

### 1.3.10 Part (j)

This is the same code as in part (i) but with noise added to the received signal  $\vec{y}$ .

```
In [23]: s1 = rand_normed_vector(N)
          s2 = rand_normed_vector(N)
          n = rand_normed_vector(N)

          y = 0.7*np.roll(s1, 10) + 0.5*np.roll(s2, 100) + 0.1*n

          corr_s1_y = cross_corr(s1, y)
          j = np.argmax(corr_s1_y) # find the first signal delay

          corr_s2_y = cross_corr(s2, y)
          k = np.argmax(corr_s2_y) # find the second signal delay

          print(j, k)

          # Once we have found the shifts, estimate the coefficients as inner products:
          a1 = np.dot(y, np.roll(s1, j))
          a2 = np.dot(y, np.roll(s2, k))

          print(a1, a2)
```

```
10 100  
0.704 0.5096
```

## 1.4 Question 5: Image Analysis

```
In [24]: def plot_circle(a, d, e):  
    """  
        You can use this function to plot circles with parameters a,d,e.  
        The parameters are described in the homework pdf.  
  
        You can comment out the line that starts with `plt.title`  
        because this makes assumptions regarding the title of your plot.  
    """  
    is_circle = d**2 + e**2 - 4*a > 0  
    assert is_circle, "Not a circle"  
  
    XLIM_LO = -1  
    XLIM_HI = 3  
    YLIM_LO = -2  
    YLIM_HI = 2  
    X_COUNT = 400  
    Y_COUNT = 400  
  
    x = np.linspace(XLIM_LO, XLIM_HI, X_COUNT)  
    y = np.linspace(YLIM_LO, YLIM_HI, Y_COUNT)  
    x, y = np.meshgrid(x, y)  
    f = lambda x,y: a*(x**2 + y**2) + d*x + e*y  
  
    c1 = plt.contour(x, y, f(x,y), [1], colors='r')  
    plt.axis('scaled')  
    plt.xlabel('x')  
    plt.ylabel('y')  
    plt.title(r'${:.2f} (x^2 + y^2) {:.2f} x {:.2f} y$'.format(a,d,e))
```

```
In [25]: def plot_ellipse(a, b, c, d, e):  
    """  
        You can use this function to plot ellipses with parameters a-e.  
        The parameters are described in the homework pdf.  
  
        You can comment out the line that starts with `plt.title`  
        because this makes assumptions regarding the title of your plot.  
    """  
    is_ellipse = b**2 - 4*a*c < 0  
    assert is_ellipse, "Not an ellipse"  
  
    XLIM_LO = -1  
    XLIM_HI = 3
```

```

YLIM_LO = -2
YLIM_HI = 2
X_COUNT = 400
Y_COUNT = 400

x = np.linspace(XLIM_LO, XLIM_HI, X_COUNT)
y = np.linspace(YLIM_LO, YLIM_HI, Y_COUNT)
x, y = np.meshgrid(x, y)
f = lambda x,y: a*x**2 + b*x*y + c*y**2 + d*x + e*y

c1 = plt.contour(x, y, f(x,y), [1], colors='r')
plt.axis('scaled')
plt.xlabel('x')
plt.ylabel('y')
plt.title(r'$\{:.2f\}x^2 \{:+.2f\}xy \{:+.2f\}y^2 \{:+.2f\}x \{:+.2f\}y$'.format(a,b,c,d,e))

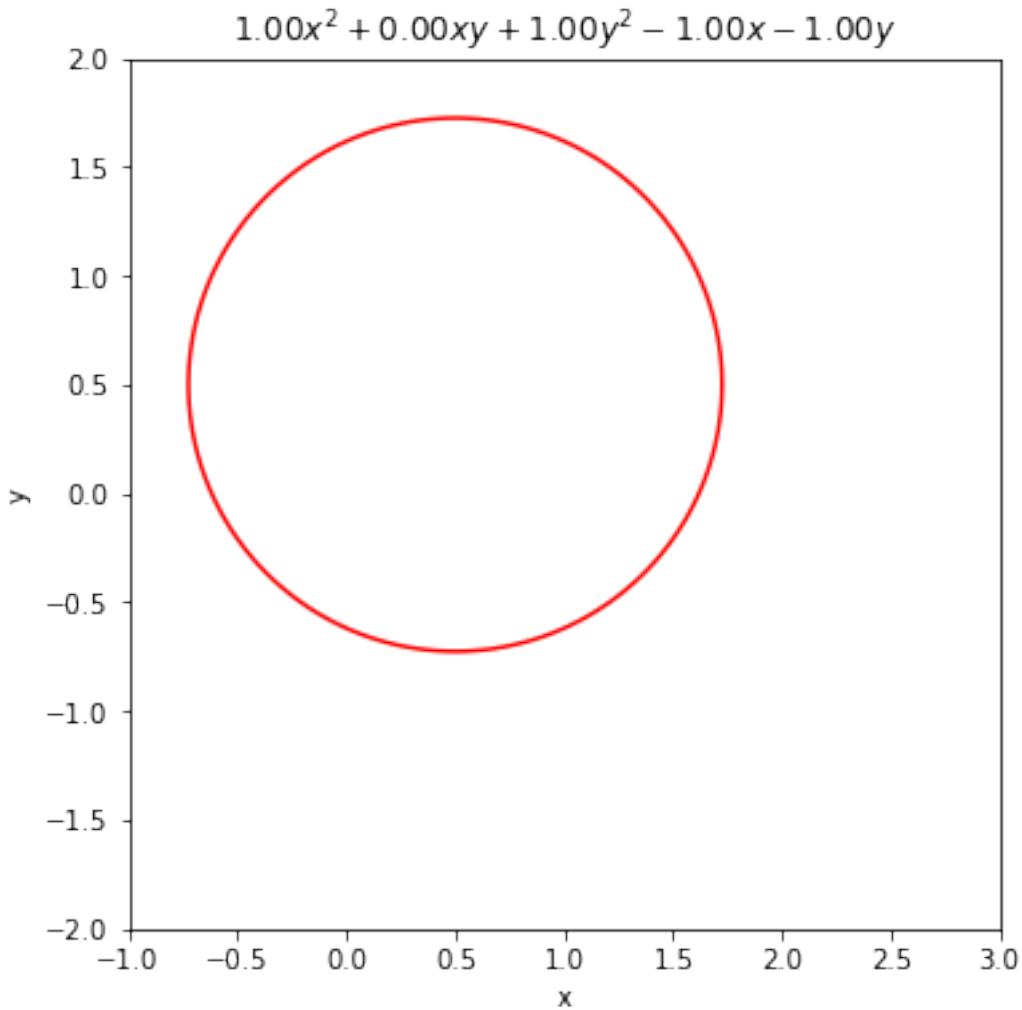
```

In [26]: # Here is an example of plot\_ellipse.  
# This plots  $(x-1)^2 + (y-1)^2 = 1$ ,  
# which is a circle centered at (1,1).

```

plt.figure(figsize=(6,6))
plot_ellipse(1, 0, 1, -1, -1)

```



You may find `plt.scatter` useful for plotting the points.

#### 1.4.1 Part (c)

In [27]: # YOUR CODE HERE

```
a = np.array([[0.5661, 0.3, -0.69],
              [1.0069, 0.5, 0.87],
              [1.5496, 0.9, -0.86],
              [1.7744, 1, 0.88],
              [2.1124, 1.2, -0.82],
              [2.6593, 1.5, 0.64],
              [3.24, 1.8, 0]])
```

```
b = np.array([1, 1, 1, 1, 1, 1, 1])
aTa = np.dot(np.transpose(a), a)
aTb = np.dot(np.transpose(a), b)
x = np.dot(np.linalg.inv(aTa), aTb)
```

```

print(x)

plot_circle(4.86902644, -7.88536506, -0.226141826)

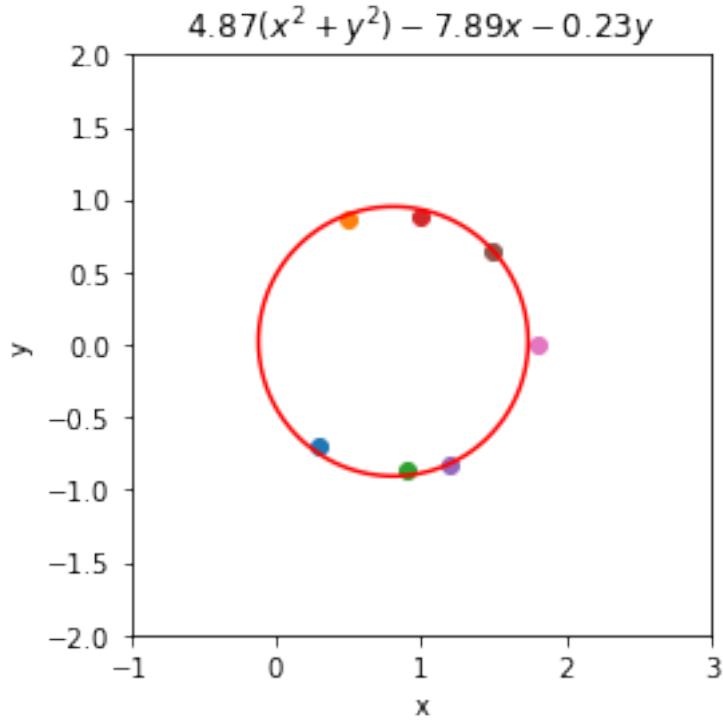
b_hat = np.dot(a, x)
b_minus_b_hat = np.subtract(b, b_hat)
print(np.linalg.norm(b_minus_b_hat) / 7)

plt.scatter(0.3, -0.69)
plt.scatter(0.5, 0.87)
plt.scatter(0.9, -0.86)
plt.scatter(1, 0.88)
plt.scatter(1.2, -0.82)
plt.scatter(1.5, 0.64)
plt.scatter(1.8, 0)

[ 4.86902644 -7.88536506 -0.22614826]
0.13749580546

```

Out[27]: <matplotlib.collections.PathCollection at 0x118d07c18>



## 1.4.2 Part (d)

In [28]: # YOUR CODE HERE

```
a = np.array([
    [0.09, -0.207, 0.4761, 0.3, -0.69],
    [0.25, 0.435, 0.7569, 0.5, 0.87],
    [0.81, -0.774, 0.7396, 0.9, -0.86],
    [1, 0.88, 0.7744, 1, 0.88],
    [1.44, -0.984, 0.6724, 1.2, -0.82],
    [2.25, 0.96, 0.4096, 1.5, 0.64],
    [3.24, 0, 0, 1.8, 0]

])

b = np.array([1, 1, 1, 1, 1, 1])
aTa = np.dot(np.transpose(a), a)
aTb = np.dot(np.transpose(a), b)
x = np.dot(np.linalg.inv(aTa), aTb)
print(x)

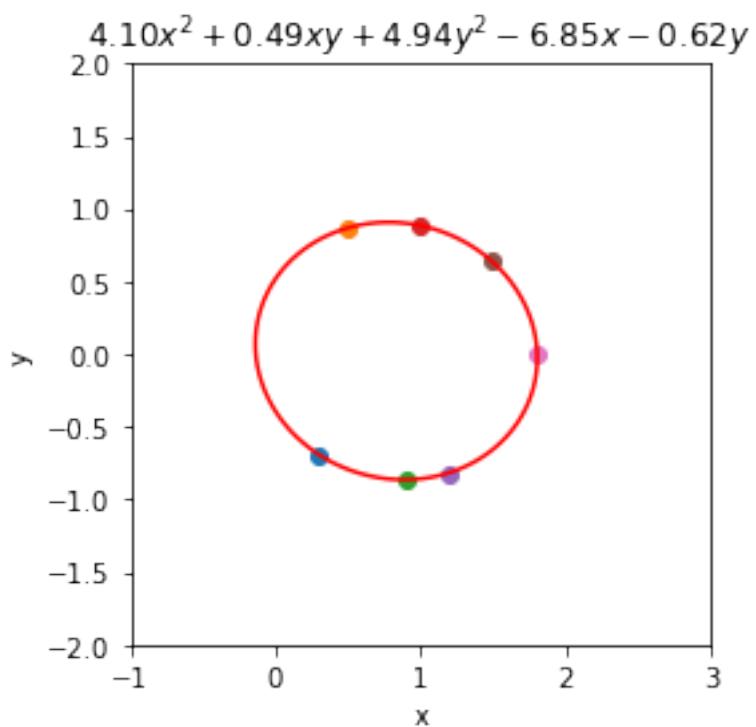
plot_ellipse(4.10382951, 0.48711384, 4.93938449, -6.85032284, -0.62259529)

b_hat = np.dot(a, x)
b_minus_b_hat = np.subtract(b, b_hat)
print(np.linalg.norm(b_minus_b_hat) / 7)

plt.scatter(0.3, -0.69)
plt.scatter(0.5, 0.87)
plt.scatter(0.9, -0.86)
plt.scatter(1, 0.88)
plt.scatter(1.2, -0.82)
plt.scatter(1.5, 0.64)
plt.scatter(1.8, 0)

[ 4.10382951  0.48711384  4.93938449 -6.85032284 -0.62259259]
0.0128538290872
```

Out [28]: <matplotlib.collections.PathCollection at 0x11895b668>



In [ ]: