HW1 problem 1 wasses and a) 2k = -0.8 k+2k-1 Homogeneous solution is of the form Zn=A1 Zn-1 = A11 18-1 Ax = -0.8 Ax =-1 1x +0.8 1x-1=0 multiply by 1'-k 1+0.8=0 - charecteristic equation 6) nn = 1.1x-1-0.3k-2 NR = AXR NXR-1 = AXR-1 XR-2 = AXR-2 Ax = 1.1 Ax k-1-0.3 AAX x-2 1 -1.1 K1 R-1 +0.3 x k-2 = 0 multiply by λ^{2-h} $\lambda^{2}-1.1x+0.3=0$ — Chareckeristic cquation c) Jk = 1.3816 Jk-1 - 0.5625 Jk-2 $JR = A \lambda^{k} \quad J_{k-1} = A \lambda^{k-1} \quad J_{R-2} = A \lambda^{k-2}$ $A \lambda^{k} = 1.3816 A^{k-1} - 0.85625A\lambda^{k-2}$ $\lambda^{k} - 1.3816 \lambda^{k-1} - 6.5625 \lambda^{k-1} = 0$ multiply by λ^{2-k} 12-1.3816λ -0.5625 = 0 -> charectoristic

equation.

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d) Wk = 2.8380 Wk-1-2.2323 Wk-2+0.576Wk-3 Wk = Axk Wk-1 = Axk-1 Wk-2=Axk-2 Wk-3=Axk-3

Ax= 2.380 AXA-1 2.2323 AXR-2+ 0.576 AXR-3

 $\lambda^{k} - 2.380\lambda^{k-1} + 2.2323\lambda^{k-2} = 0.576\lambda^{k-3} = 0$ multiply both sides by λ^{3-k}

 $\lambda^{3}-2.380 \lambda^{2}+2.2323 \lambda-0.576=0$ -charecteristic equation.

a) - rook - -0.8 -> stable
b) rook - 0.6000 lo.5000 -> stable
c) rook - 1.7105 l -0.3289 -> proof greater
than 1 hence unstable
d) rook - 0.3999 l 0.9901+0.6784

Zk = 0=8 A1(x) k ZR = A. (-0.8)K 8 -10 = A. (-0.8) A1 = 10 Zh=-10(0.8)k A1 = 0.6 X2 = 0.5 X k = A, (0.6) k + Az (0.5) k $\chi_0 = 3$ $\chi_1 = 1.3$ $3 = A_1(0.6)^{\frac{1}{4}} + A_2(0.5)^{\circ}$ 3 = A1 + A2 1.3 = A, (0.6) + Az (0.5) 1.3 = A (0.6) + A2 (0.5) $\begin{bmatrix} 0.6 & 0.5 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1.3 \end{bmatrix}$

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 $A_{1} = -2 \qquad A_{2} = +5$ $\lambda_{k} = -2(0.6)^{k} + (+5)(6.5)^{k}$ $\lambda^{2} - 1.3816\lambda - 0.5625 = 0$ $\lambda_{1} = 1.7105 \qquad \lambda_{2} = -0.3289$

 $y_k = A_1(\lambda_1)^k + A_2(\lambda_2)^k$ $y_k = A_1(1.7105)^k + A_2(-0.3289)^k$ $y_0 = 8$ $y_1 = 6.4026$

 $y_{0} = A_{1}(1.7105)^{\frac{1}{2}} + A_{2}(-0.3289)^{\frac{1}{2}} = 8$ $A_{1} + A_{2} = 8$ $y_{1} = 6.4026 = A_{1}(1.7105)^{\frac{1}{2}} + A_{2}(-0.3289)^{\frac{1}{2}}$

 $\begin{bmatrix} 1 & 1 & 1 \\ 1.7105 & -0.38289 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 8 & 1 \\ 6.4026 \end{bmatrix}$

A. = 4-4296 Az = 3.5704

Jk= 4.4296(1.17105)k+3.5704(-0.3289)k

6 λ3-2-380λ2+2·3323λ-0.576 1,=0.3999 12,3 = 0.9901 ± 0.67841 magnitude of 12,3 = 1.2002 Phase = ±0.6008 Wn = A1(0.3999) + A2(1.2002)e + A3 (1.2002)e.6008k WR= A1(0.3399) + (1.2002) 2 (A2(05(0.6008) K) + Â3 sin (0.6008 R) W0 = 8 W1=6.157 W2 = 3.089 Wo = A (0.3999) + (1.2002) (A2 cos(0) + A 3 sin(0) ado 8 = A1 + A2 $\omega_1 = A_1 (0.3999) + (1.2002) (\hat{A}_2 \cos(0.6008)07$ = 6.152 + $\hat{A}_3 \sin(0.6008(1))$ $\omega_2 = A_1 (0.3999^2) + (1.2002)^2 (A_2 \cos(1.2016) +$ Assin (1.2016)

$$\begin{bmatrix}
1 & 1 & 0 & A_1 \\
0.399 & 0.679 & 0.678 & A_2 & = 6.152 \\
0.159 & 0.519 & 1.343 & A_3 & A_3 & 3.089
\end{bmatrix}$$

$$A_1 = 3.0087$$
 $A_2 = 4.9913$
 $A_3 = 0.0150$

+ Asa 0.0150 Sin (0.6008k)

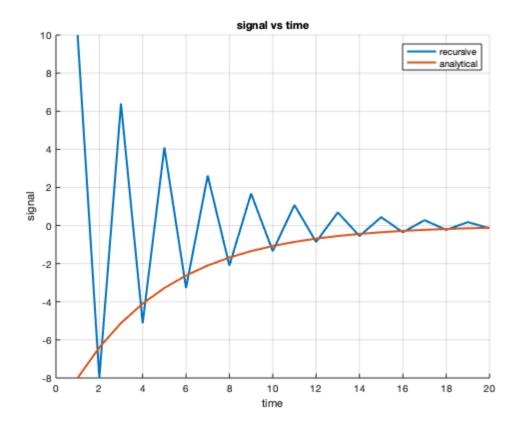
)2934A) (5305.1) + (8882

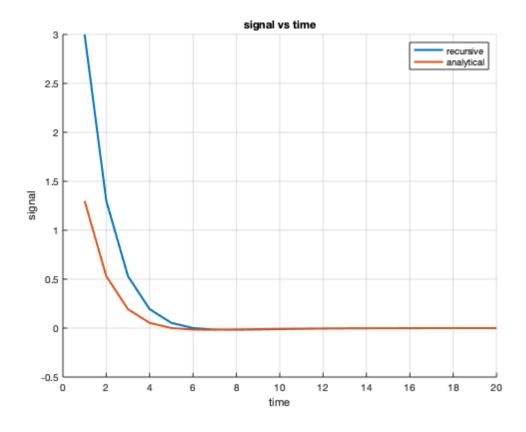
14 - 1 5 20 - A Wassell 4 (P.S.

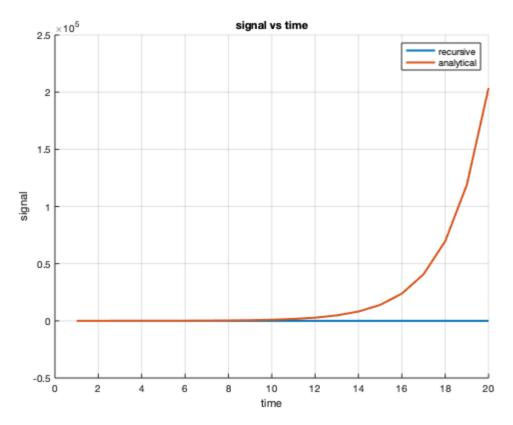
18003.00 118 (4)

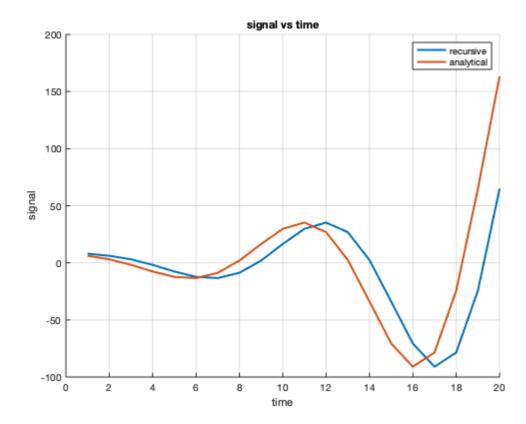
```
z char = [1,0.8];
x_{char} = [1,-1.1,0.3];
y char = [1,-1.3816,-0.5625];
w_{char} = [1,-2.380,2.2323,-0.576];
z roots = roots(z char)
x roots = roots(x char)
y_roots = roots(y_char)
w_roots = roots(w_char)
z k(1) = 10;
x k(1) = 3;
x_k(2) = 1.3;
y k(1) = 8;
y_k(2) = 6.4026;
w k(1) = 8;
w k(2) = 6.152;
w k(3) = 3.089;
for z = 2:20;
    z_k(z) = -0.8*z_k(z-1);
end
for x = 3:20;
    x_k(x) = 1.1*x_k(x-1)-0.3*x_k(x-2);
end
for y = 3:20;
    y_k(y) = 1.3816*y_k(y-1)-0.5625*y_k(y-2);
end
for w = 4:20;
    w_k(w) = 2.380*w_k(w-1)-2.2323*w_k(w-2)+0.576*w_k(w-3);
end
k = linspace(1,20,20);
z = -10*(0.8).^k;
x = -2*(0.6).^k + 5*(0.5).^k;
y = 4.4296*(1.7105).^k + 3.5704*(-0.3289).^k;
for n = 1:20;
w(n) = (3.0087)*(0.399)^k(n) + (1.2002)^k(n) * (4.9913*cos(0.6008*k(n))+0.0150*sin(0.6008*k(n)));
end
mag w = abs(w roots);
phase = angle(w_roots);
figure
hold on
plot(k,z k,'linew',2)
plot(k,z,'linew',2)
xlabel('time')
ylabel('signal')
title('signal vs time')
legend('recursive', 'analytical')
grid on
hold off
figure
hold on
plot(k,x_k,'linew',2)
plot(k,x,'linew',2)
xlabel('time')
ylabel('signal')
```

```
title('signal vs time')
legend('recursive', 'analytical')
grid on
hold off
figure
hold on
plot(k,y k,'linew',2)
plot(k,y,'linew',2)
xlabel('time')
ylabel('signal')
title('signal vs time')
legend('recursive', 'analytical')
grid on
hold off
figure
hold on
plot(k,w k,'Linew',2)
plot(k,w,'linew',2)
xlabel('time')
ylabel('signal')
title('signal vs time')
legend('recursive', 'analytical')
grid on
hold off
```









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