

Error codes	
a)adapter_success	=0;
b)adapter_AF	=1;
c)adapter_BERR	=2;
d)adapter_ARLO	=3;
e)adapter_OVR	=4;
f)adapter_timeout	=5;
g)adapter_other_error	=6;
e)adapter_busy	=7;

Data markers
a)data_from_host =18;
b)data_to_host =19;

Commands
a) write_to_i2c_dev =24;
b) read_from_i2c_dev =25;
c) reset_interface_i2c =26;
d) setup_interface_i2c =27;
e) read_last_stub_rx_i2c =28;
f) write_tx_stub_buffer_i2c = 29;
g) write_to_spi_dev =30
h) read_from_spi_dev=31
i) full_duplex_spi_dev =32
j) setup_spi_dev =33

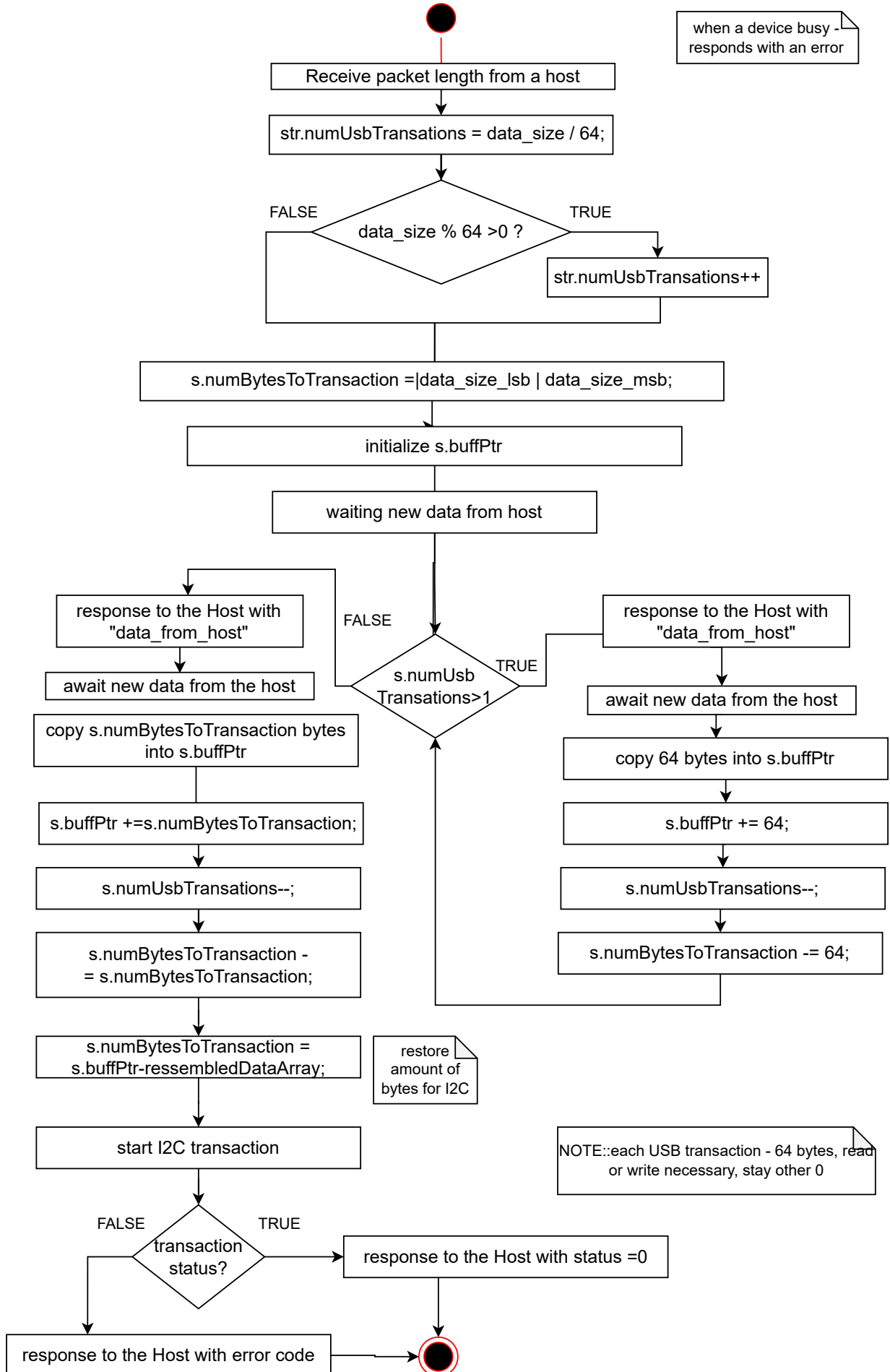
## USB Device : the state machine

the structure must be aligned to 4 to improve CPU (Cortex-M3) and peripheral performance

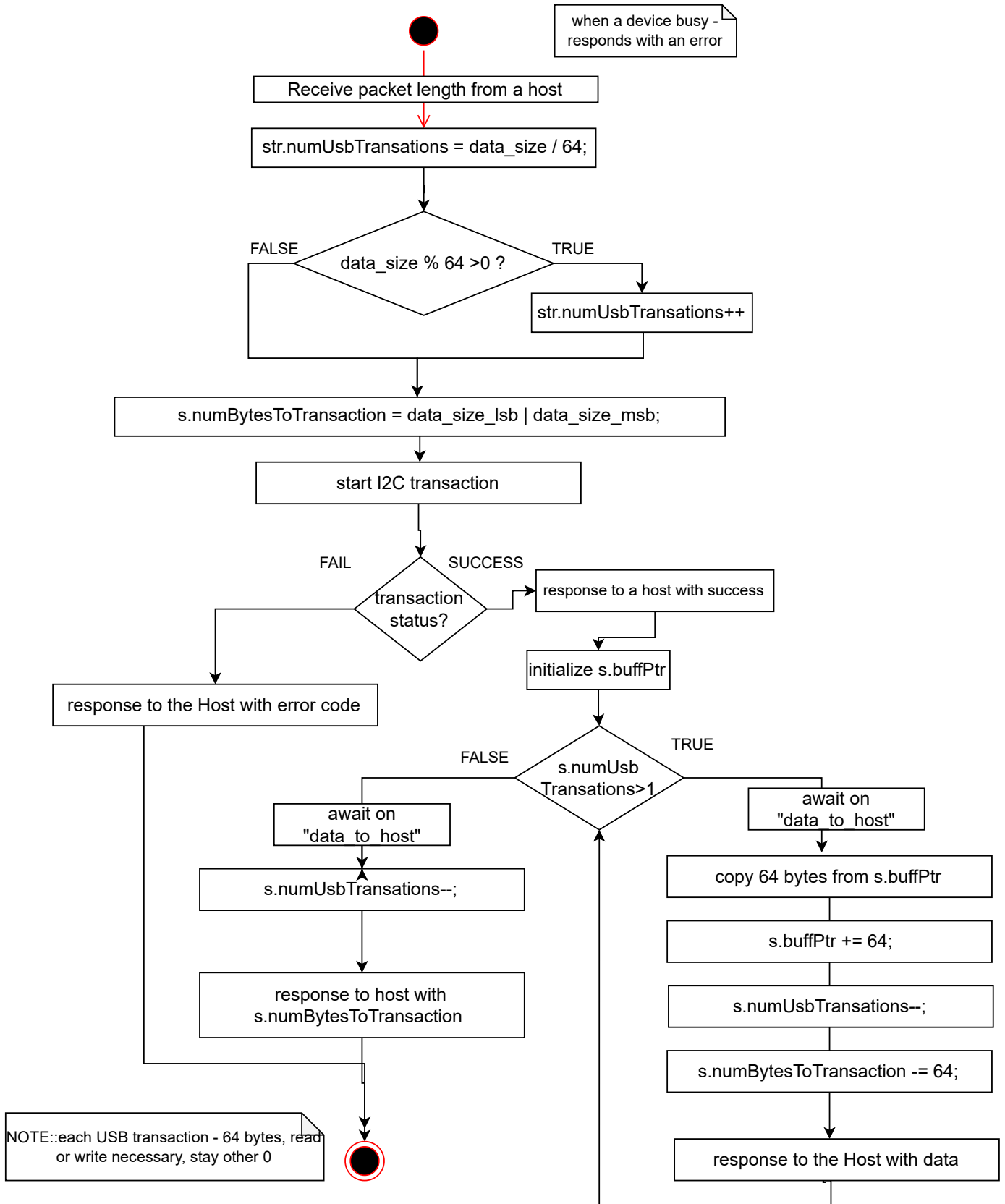
```

STRUCT {
  uchar typeOfAction;
  uchar slaveAddr;
  uchar* buffPtr; //changes during exec.
  uin16_t numUsbTransations;
  uint16_t numBytesToTransaction;
  uchar* reassembledDataArray; //not changed
}statesHandle;
  
```

## CASE1: write\_to\_i2c\_dev (device side)



## CASE2: read\_from\_i2c\_dev (device side)

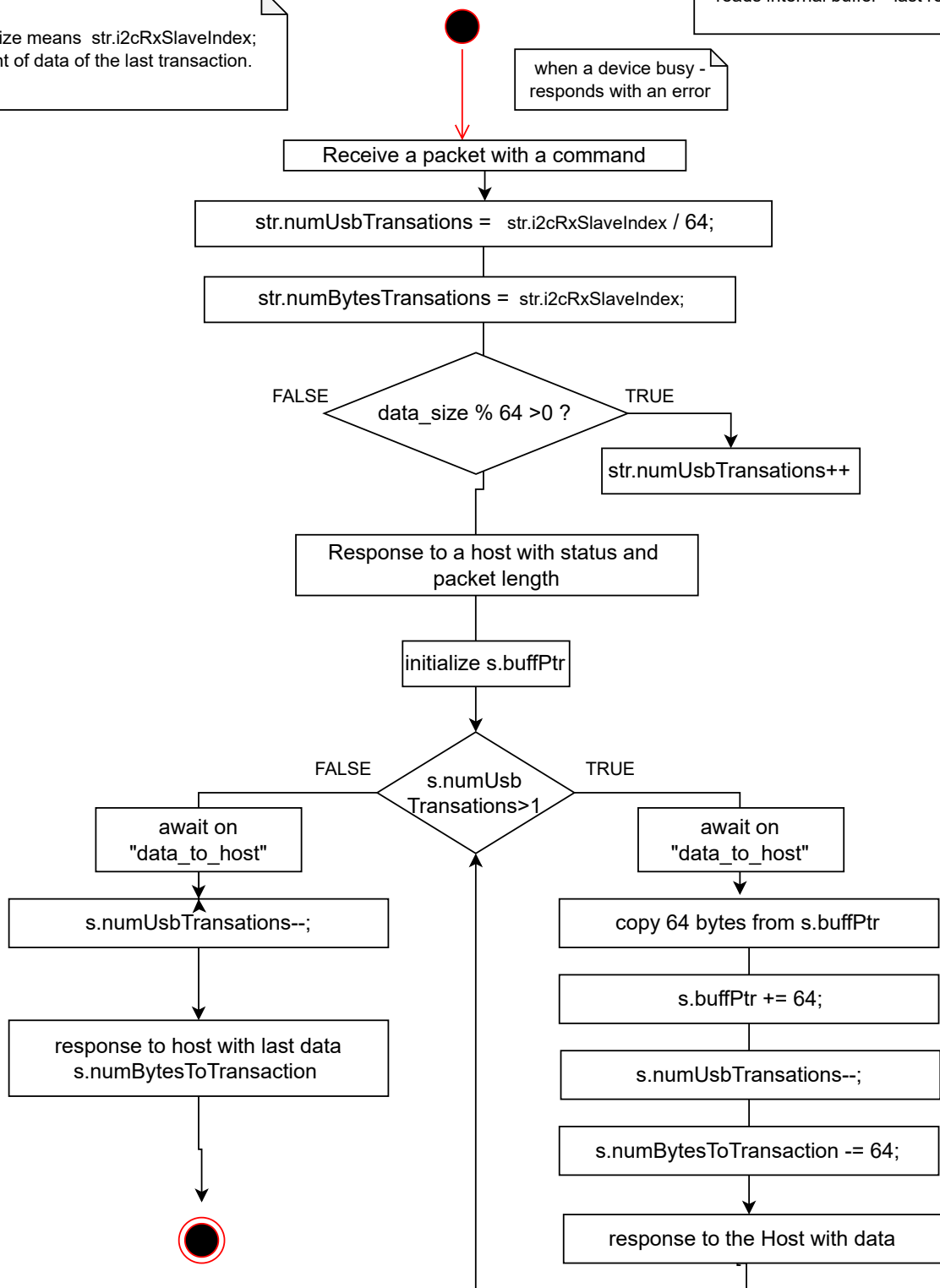


### CASE3: read\_last\_internal\_received\_data (device side)

data\_size means str.i2cRxSlaveIndex;  
amount of data of the last transaction.

NOTE::there is I2C1 (slave) , that acts as  
slave device with own address. This command  
reads internal buffer - last received data.

when a device busy -  
responds with an error

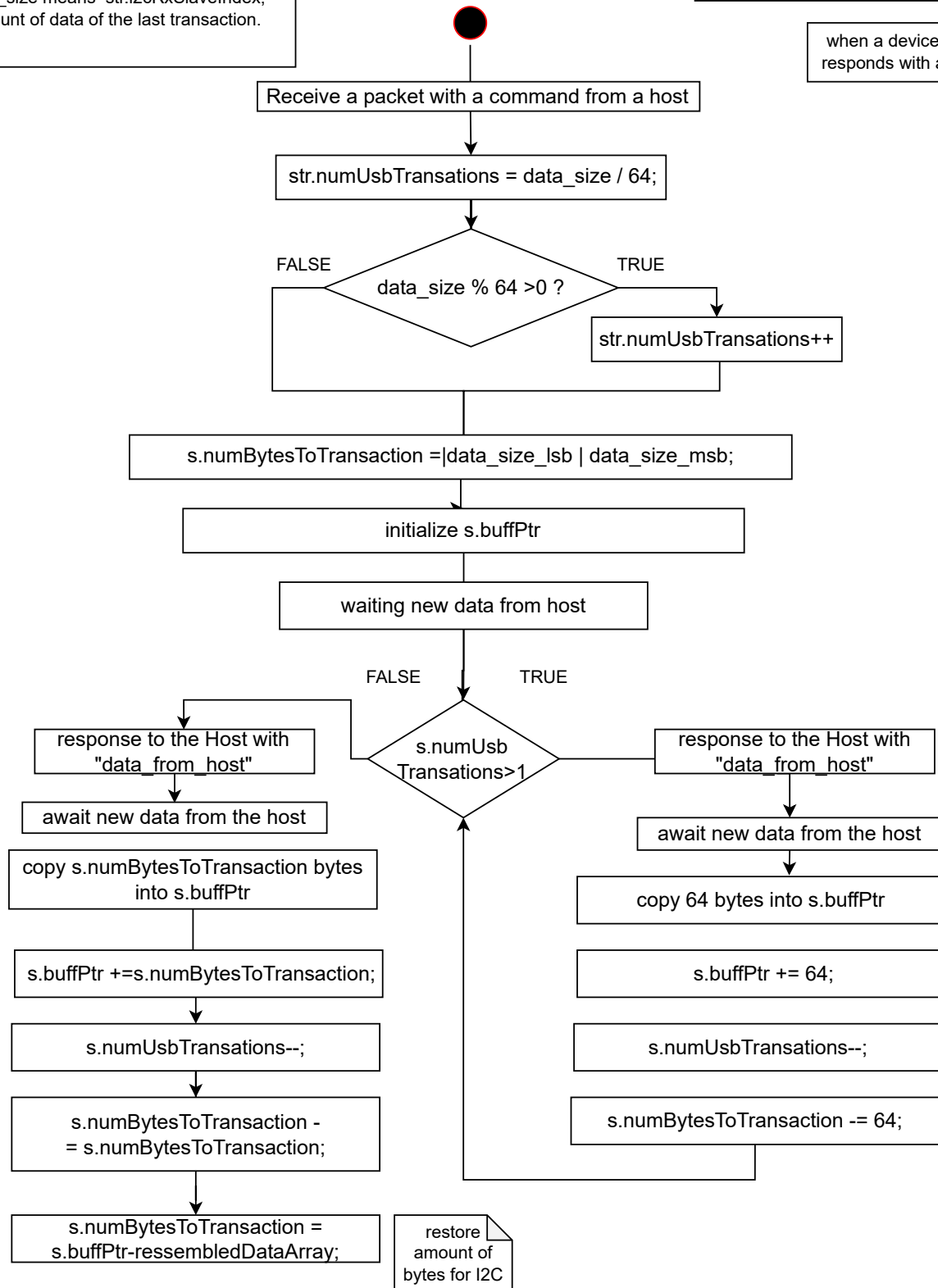


## CASE4: Write slave Tx internal buffer(device side)

data\_size means str.i2cRxSlaveIndex;  
amount of data of the last transaction.

NOTE::there is I2C1 (slave) , that acts as slave device with own addres.This command reads internal buffer - last received data.

when a device busy - responds with an error



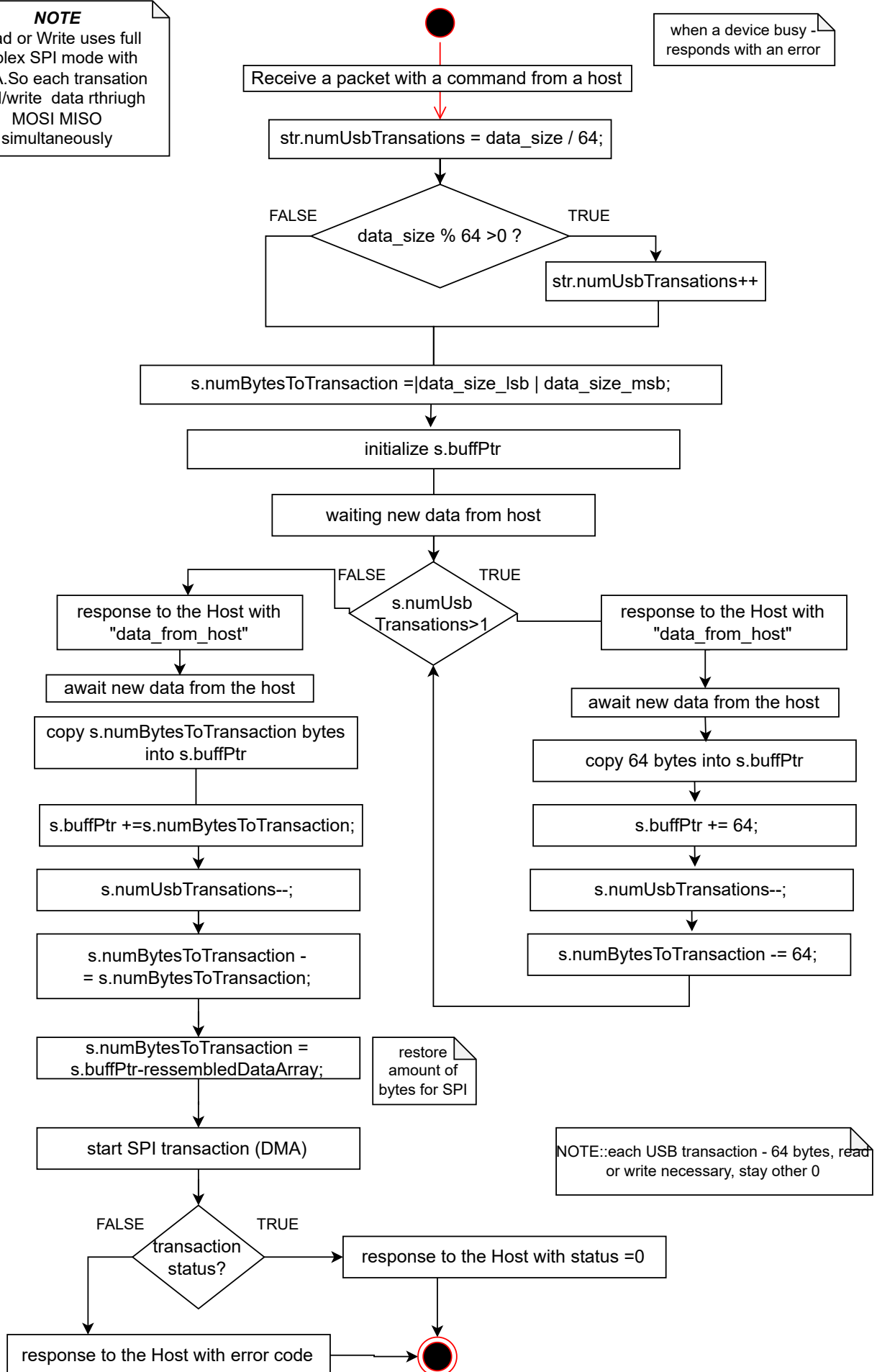


## CASE5: write\_to\_spi\_dev (device side)

### NOTE

Read or Write uses full duplex SPI mode with DMA. So each transaction read/write data through MOSI MISO simultaneously

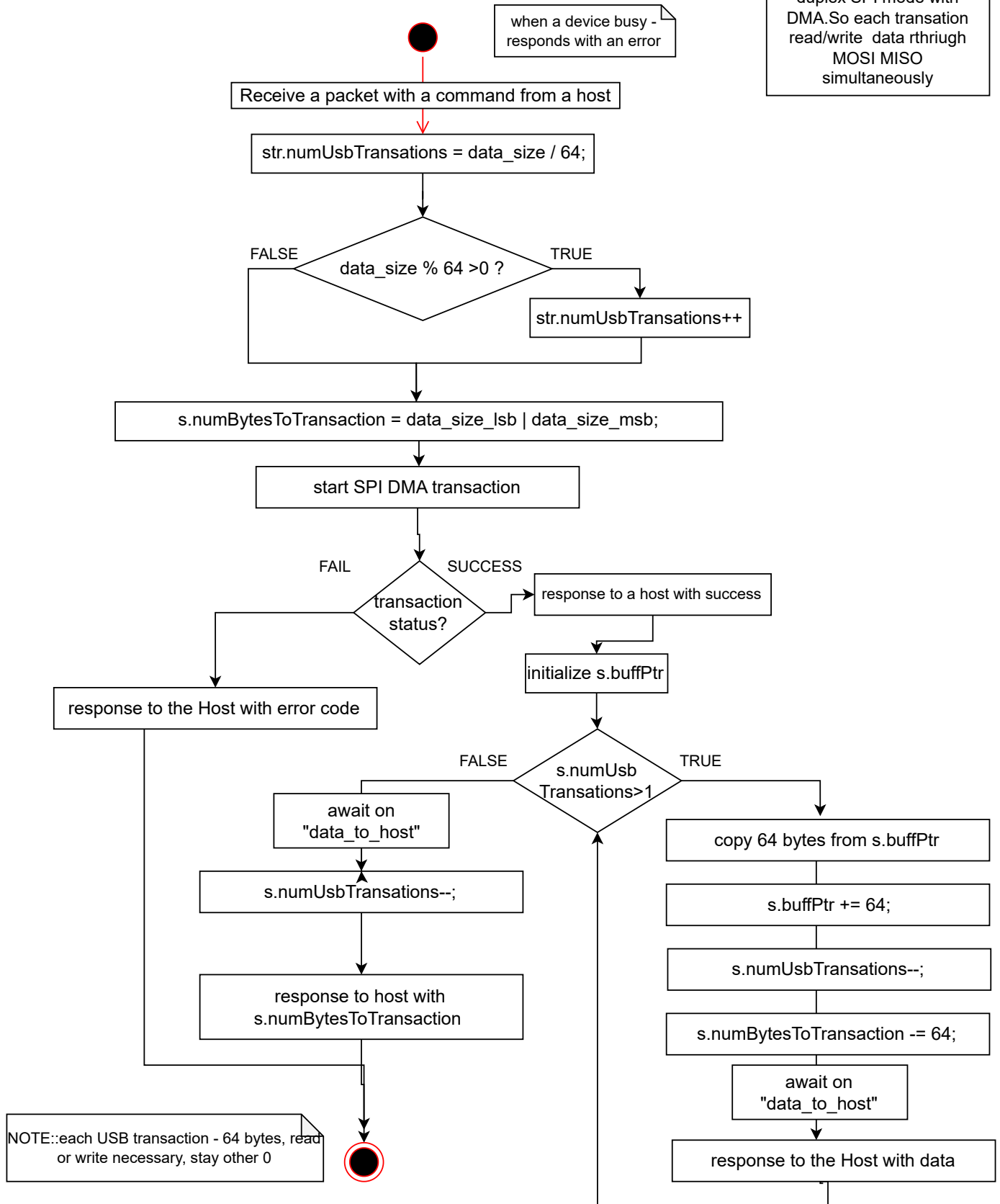
when a device busy - responds with an error



## CASE6: read\_from\_spi\_dev(device side)

### NOTE

Read or Write uses full duplex SPI mode with DMA. So each transaction read/write data through MOSI MISO simultaneously

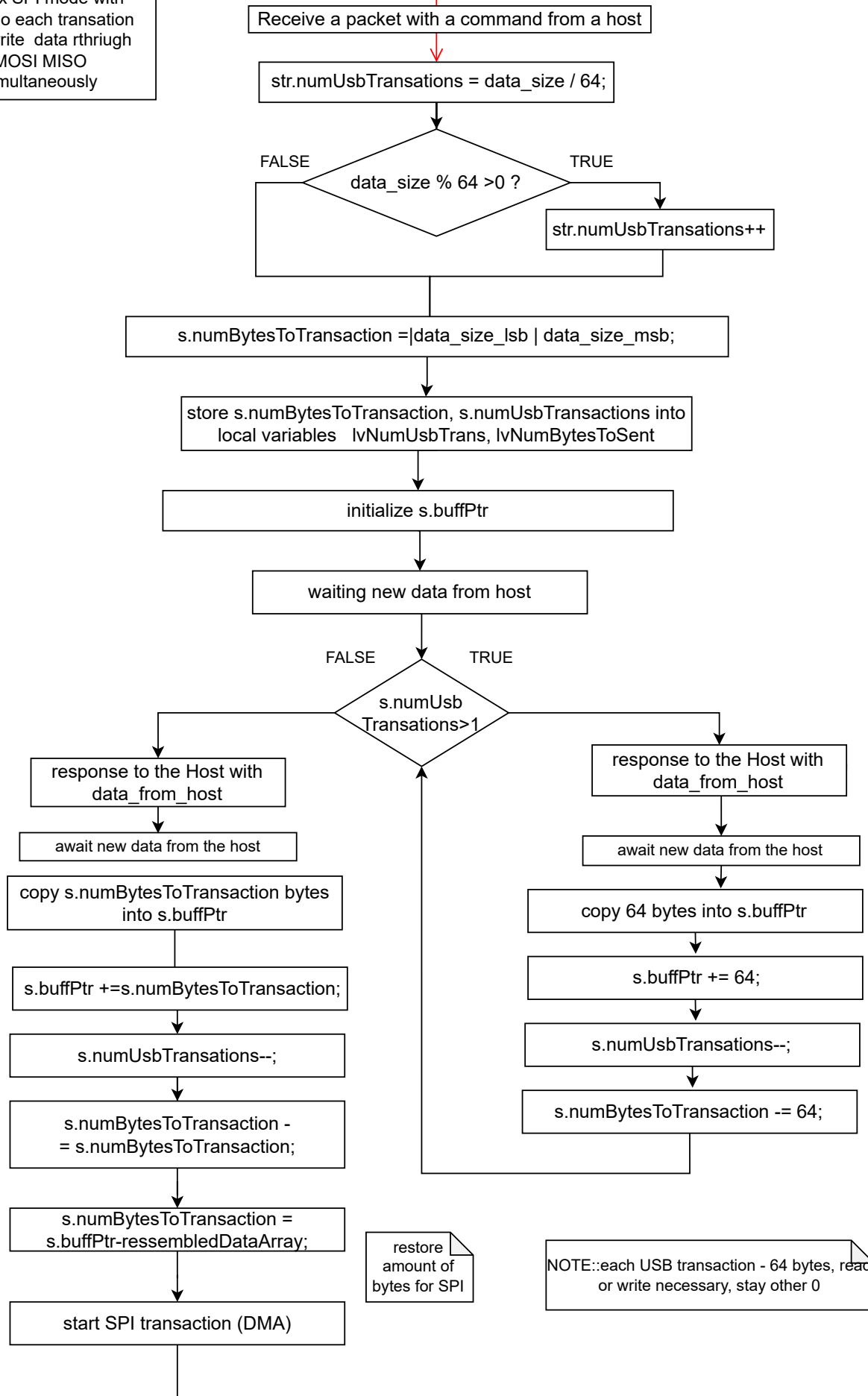


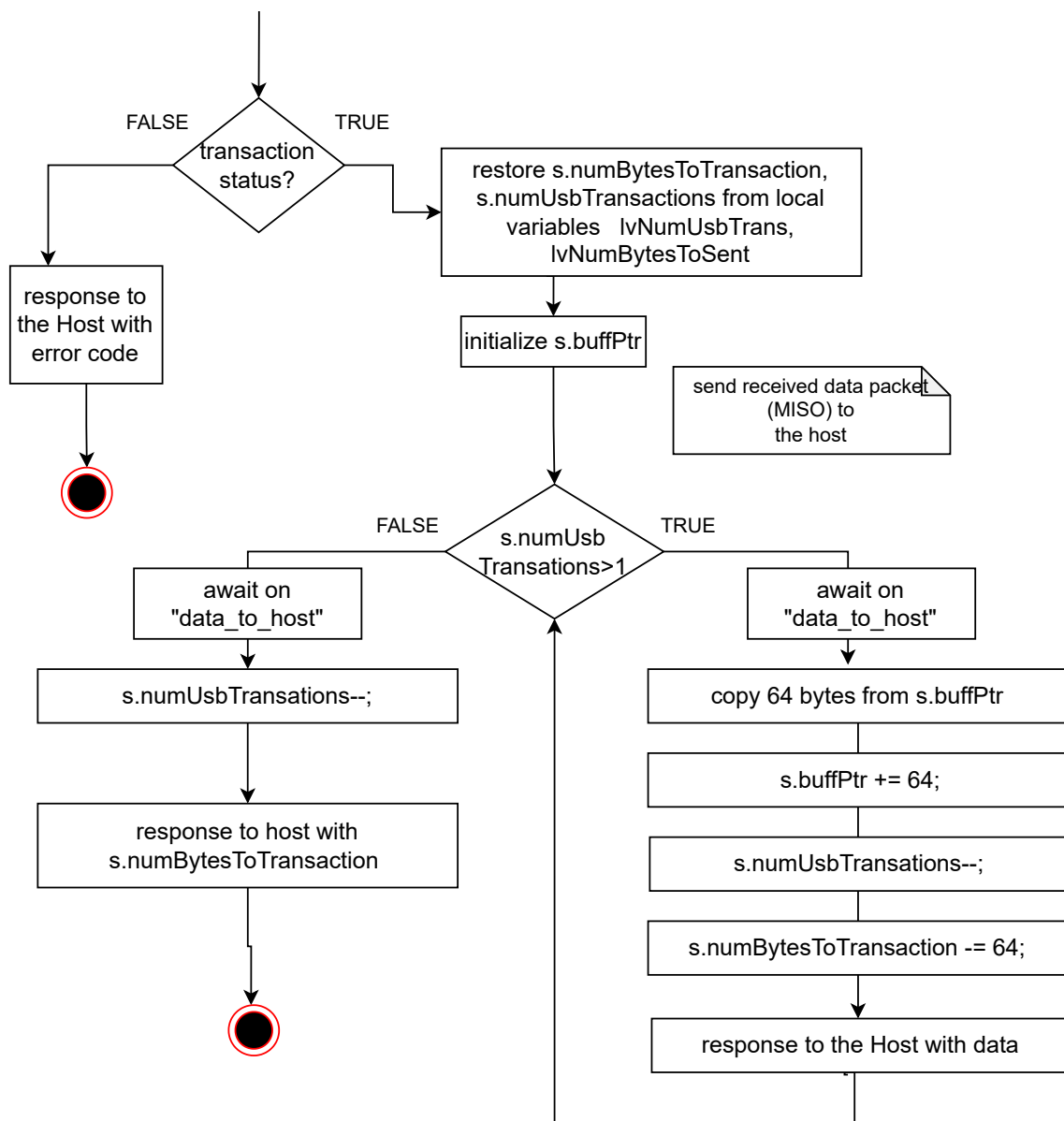
## CASE7: full\_duplex\_spi\_dev (device side)

### NOTE

Read or Write uses full duplex SPI mode with DMA. So each transaction read/write data through MOSI MISO simultaneously

when a device busy - responds with an error





USB Device : the state maschine

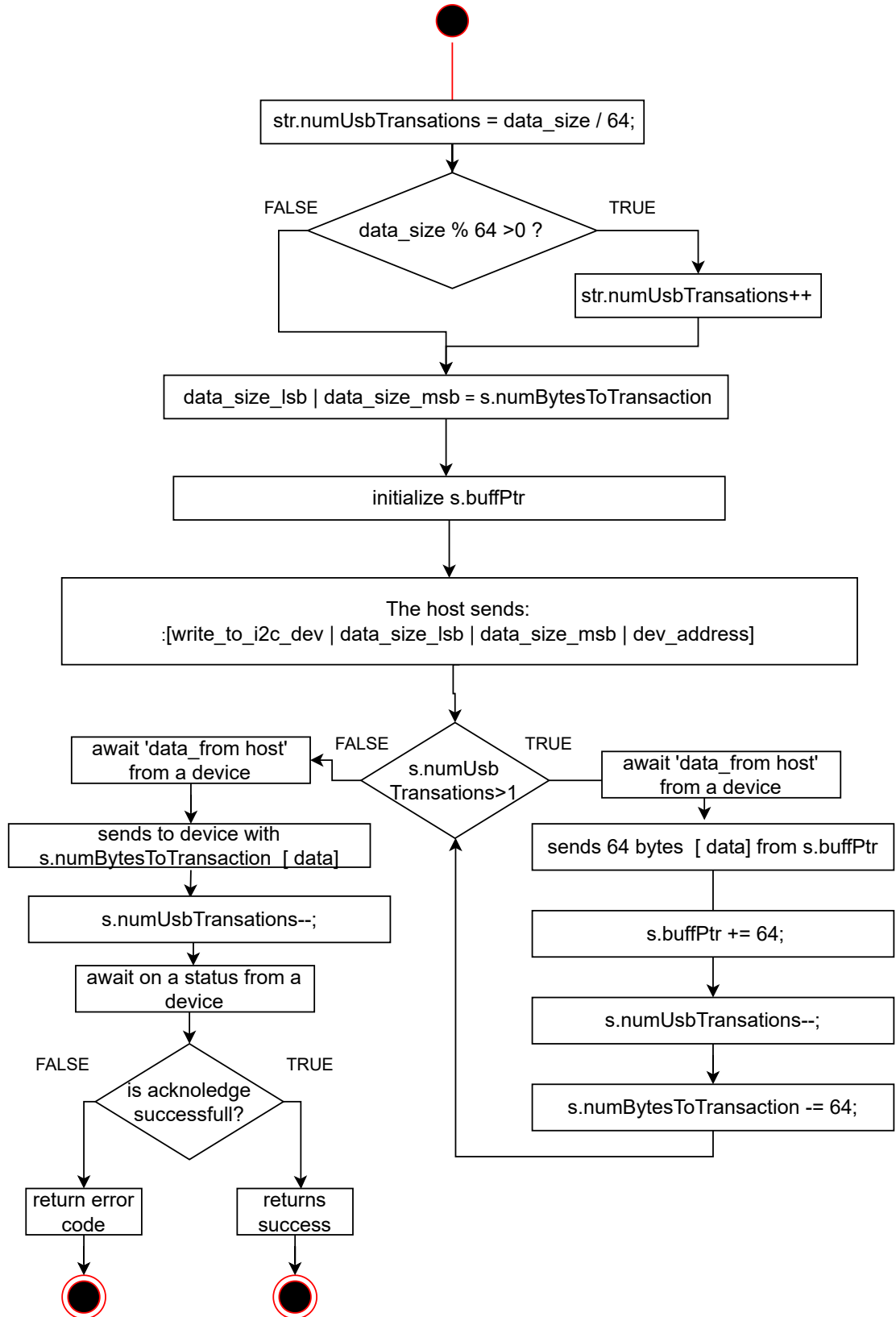
<pre>STRUCT { uchar typeOfAction; uchar slaveAddr; uchar* buffPtr; //changes during exec. uint16_t numUsbTransations; uint16_t numBytesToTransaction; uchar* reassembledDataArray; //not changed }statesHandle;</pre>	
---	--

Error codes	
a)Success	=0;
b)Acknowledge failure AF	=1;
c)Bus Error BERR	=2;
d)Arbitration lost (ARLO)	=3;
e)Overrun/underrun (OVR)	=4;
f)Timeout	=5;
g)Other error	=6;
e)Busy	=7;

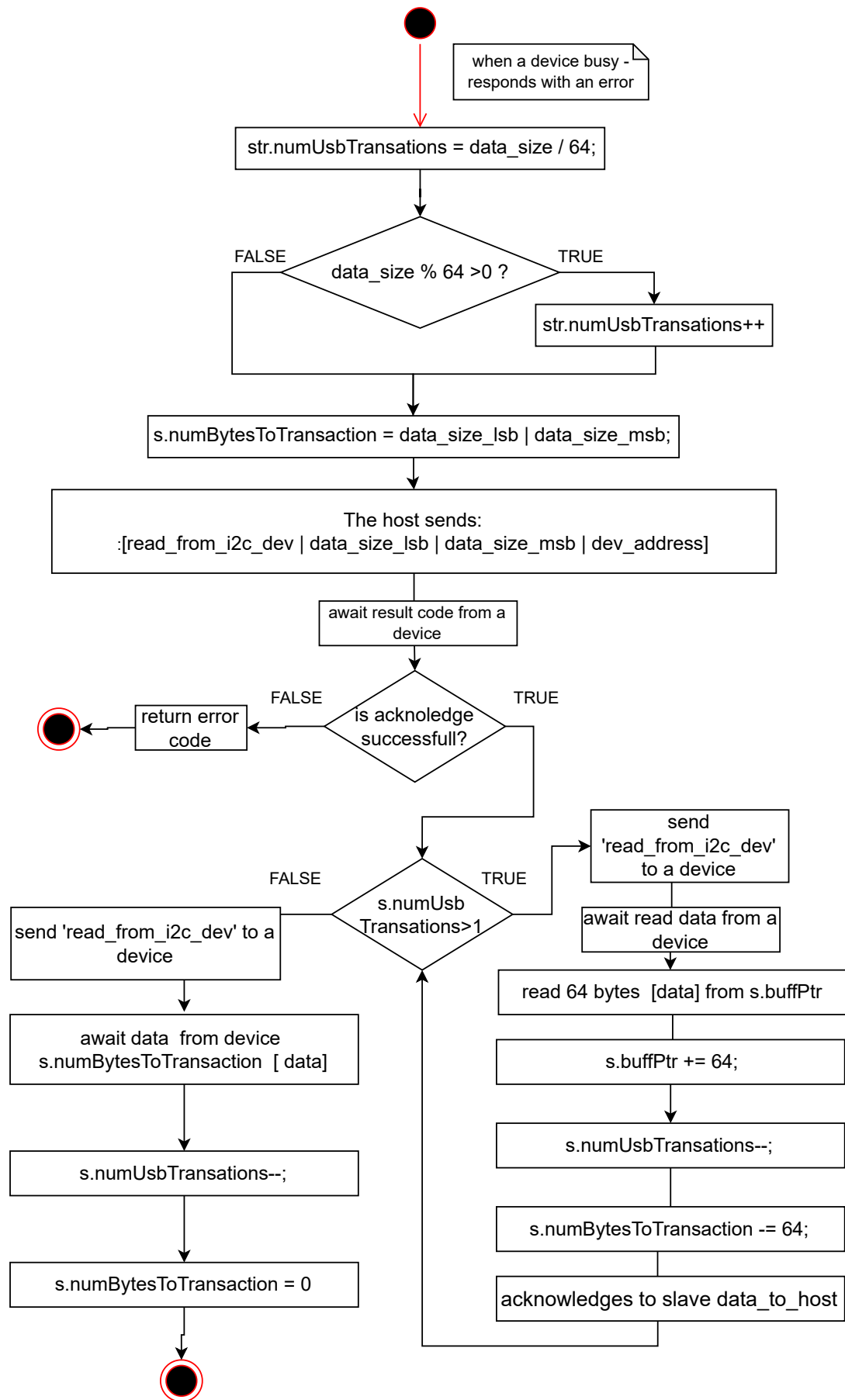
Data markers
a)data_from_host =18; b)data_to_host =19;

Commands
a) write_to_i2c_dev =24; b) read_from_i2c_dev =25; c) reset_interface_i2c =26; d) setup_interface_i2c =27; e) read_last_stub_rx_i2c =28; f) write_tx_stub_buffer_i2c = 29; g) write_to_spi_dev =30 h) read_from_spi_dev=31 i) full_duplex_spi_dev =32 j) setup_spi_dev =33

CASE1: write\_to\_i2c\_dev (HOST side)

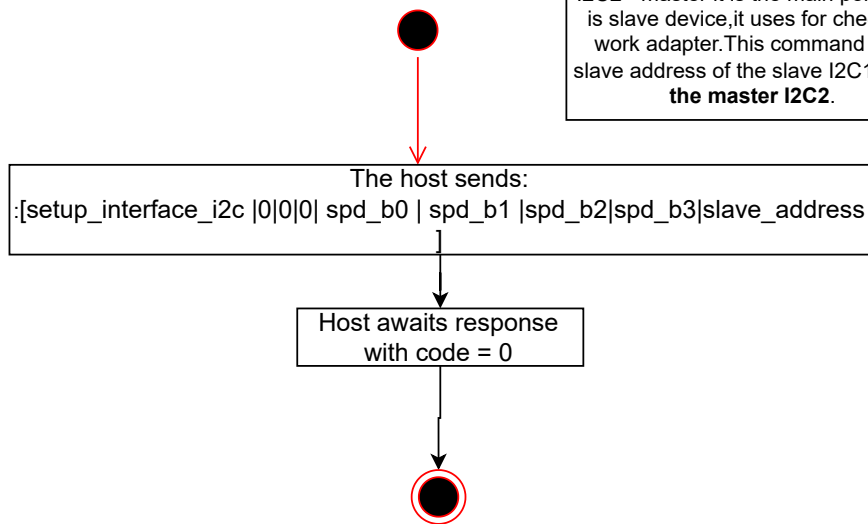


# CASE2: read\_from\_i2c\_dev (HOST side)



### Set frequency and I2C1 slave address

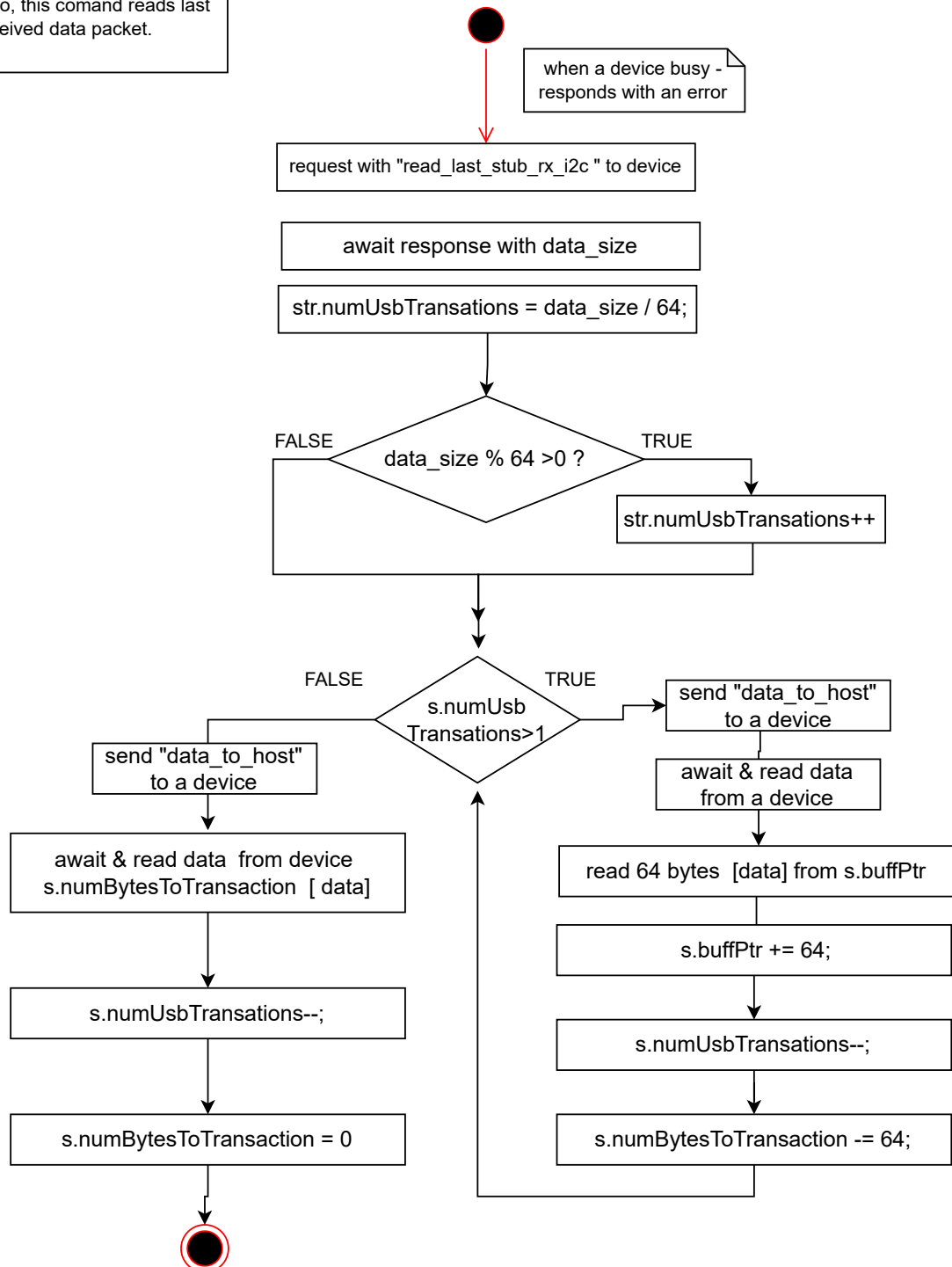
I2C2 - master it is the main port. I2C1 is slave device, it uses for checking work adapter. This command sets slave address of the slave I2C1, **NOT the master I2C2.**





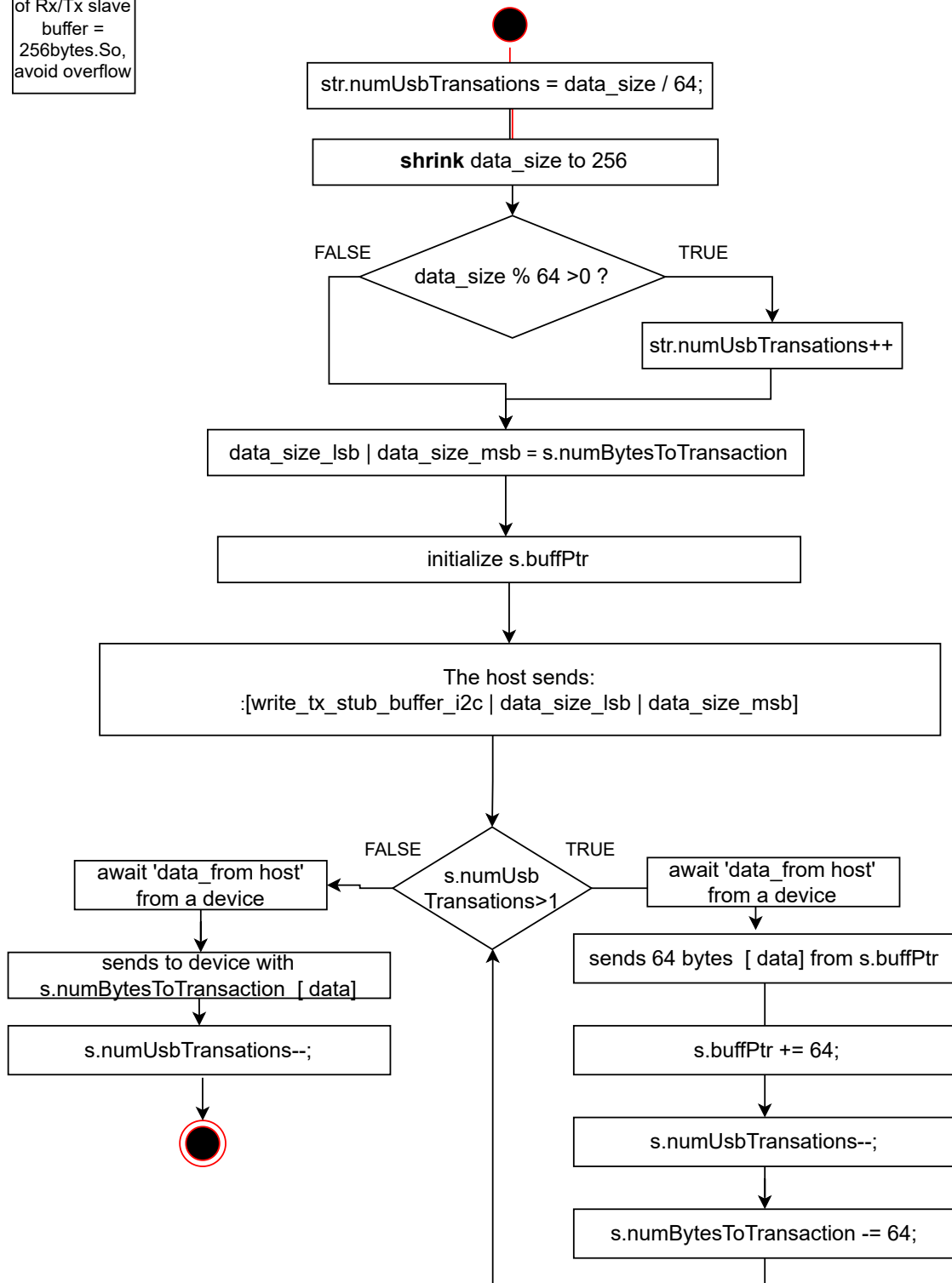
### CASE3: read\_last\_received\_internal\_data (HOST side)

I2C1 acts as slave device with it's own address. So, this comand reads last received data packet.

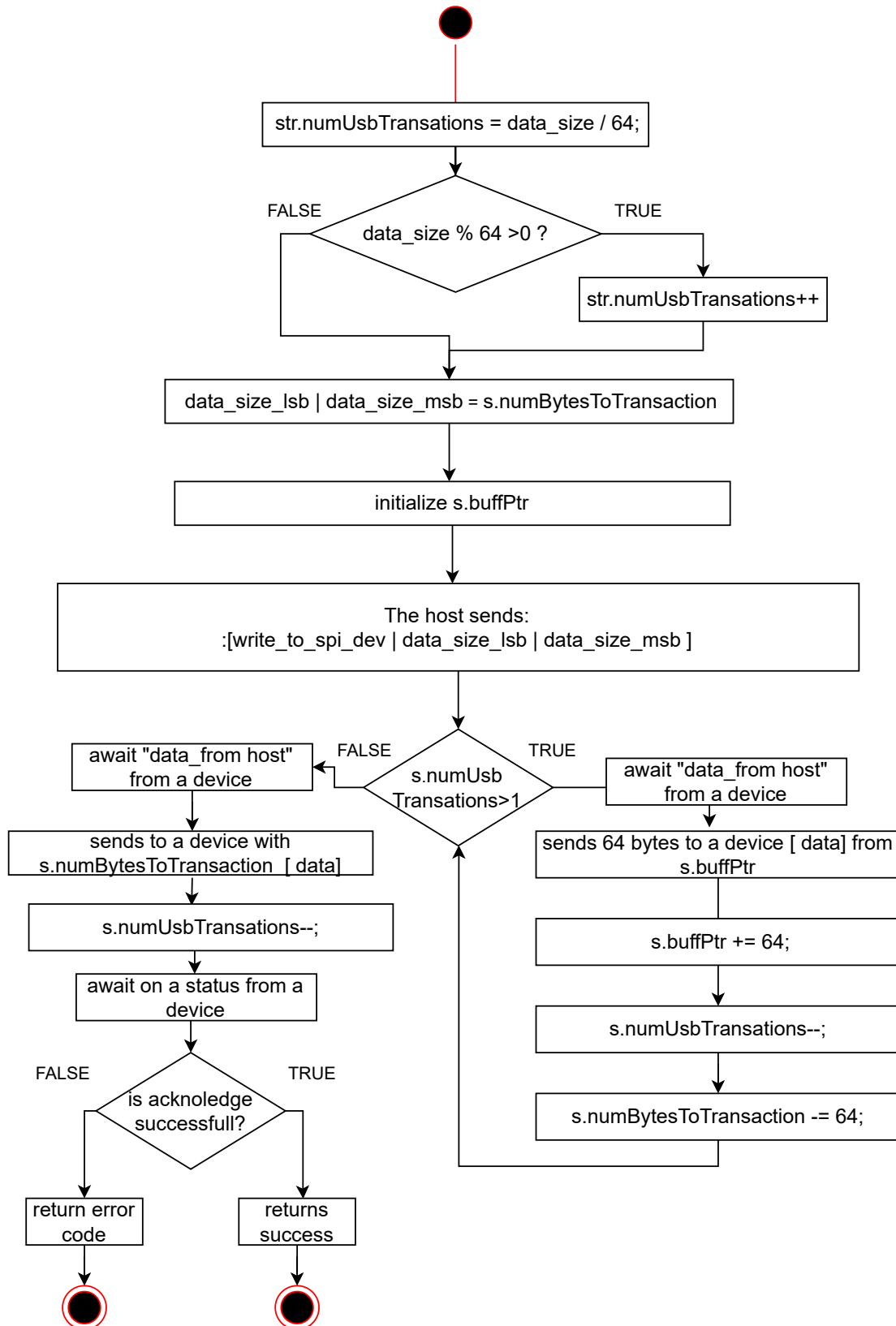


NOTE:  
maximum size  
of Rx/Tx slave  
buffer =  
256bytes. So,  
avoid overflow

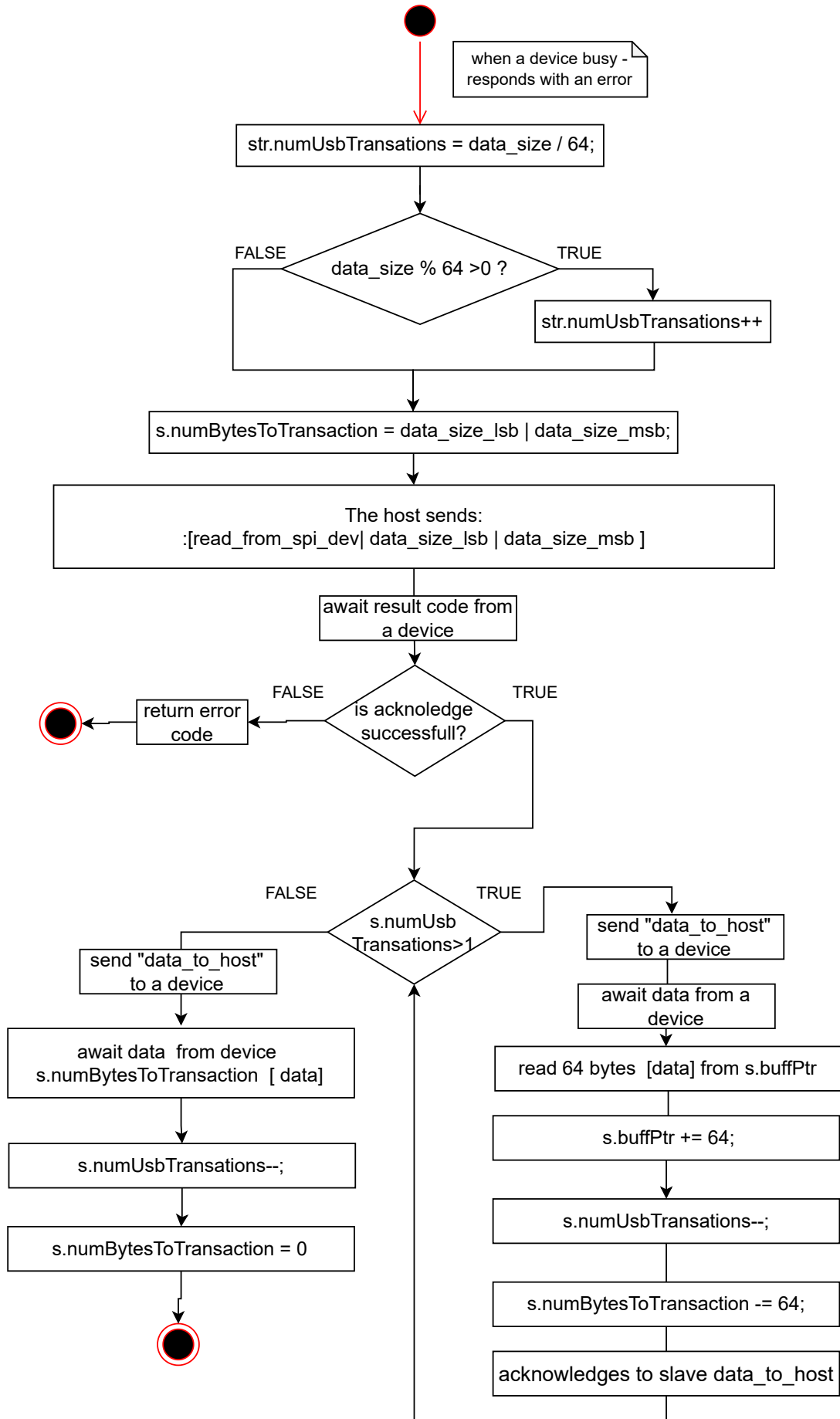
# CASE4: write internal slave Tx bufer (I2C1) (HOST side)



CASE5: write\_to\_spi\_dev (HOST side)



## CASE6: read\_from\_spi\_dev(HOST side)



# CASE7: full\_duplex\_spi\_dev (HOST side)

