P.4. Noise-Removal and Classification

Machine Learning Tasks

- Many algorithms are sensitive to outliers or noise:
 - An object with extreme values may substantially distort the distribution of the data.
- A good dataset is often better than a good algorithm.

Project Objectives

- Develop efficient noise-removal algorithms,
 - using e.g., the *k*-NN and the Clustering-PCA.
- **Merge** the noise-removal algorithms to **classification**.
- **Test and tune** the resulting algorithms for public-domain datasets.

For each of selected datasets, you will design the best model for noise-removal and classification.

Confidence Region

A **confidence score** indicates the **likelihood** that a machine learning model assigns the respective intent correctly.

<u>Definition</u>] **P.6.** A **confidence region** is the region where a new point belongs to a specified class, given a confidence score/value.

Review: k-NN and PCA

k-Nearest Neighbors (k-NN)

Algorithm 5.37, p. 137. (*k***-NN algorithm**). The algorithm itself is fairly straightforward and can be summarized by the following steps:

- 1. Choose the number k and a distance metric.
- 2. For the new sample, find the *k*-nearest neighbors.
- 3. Assign the class label by majority vote.

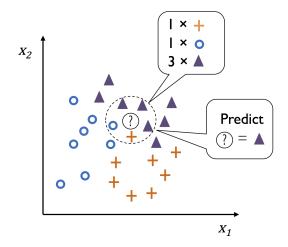


Figure 5.16: Illustration for how a new data point (?) is assigned the triangle class label, based on majority voting, when k = 5.

Example P.7. Along with the k-NN algorithm:

- Select k.
- Set a confidence value $\xi < k$.

Then the **confidence region** for a class can be defined as the region where the k-NN of a point includes at least ξ points from the same class.

For example, k=5 and $\xi=4$.

Remark P.8. Rather than counting (a constant weighting), an **IDW** may be incorporated; the goal is to keep **grouped data points**.

PCA

Recall: (PCA), p. 197. Consider a data matrix $X \in \mathbb{R}^{N \times d}$:

- \circ each of the N rows represents a different data point,
- o each of the *d* columns gives a particular kind of feature, and
- o each column has zero empirical mean (e.g., after standardization).
- The goal of the standard PCA is to find an **orthogonal** weight matrix $W_k \in \mathbb{R}^{d \times k}$ such that $Z_k = X W_k, \quad k < d,$ (P.4.1)

where $Z_k \in \mathbb{R}^{N \times k}$ is call the **truncated score matrix** and $Z_d = Z$. Columns of Z represent the **principal components** of X.

• (Claim 7.3, p. 160). The transformation matrix W_k turns out to be the collection of normalized eigenvectors of X^TX :

$$W_k = [\mathbf{w}_1 | \mathbf{w}_2 | \cdots | \mathbf{w}_k], \quad (X^T X) \mathbf{w}_j = \lambda_j \mathbf{w}_j, \quad \mathbf{w}_i^T \mathbf{w}_j = \delta_{ij}, \tag{P.4.2}$$

where $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_k \geq 0$.

• (Remark 7.4, p. 160). The matrix $Z_k \in \mathbb{R}^{N \times k}$ is scaled eigenvectors of XX^T :

$$Z_k = [\sqrt{\lambda_1} \mathbf{u}_1 | \sqrt{\lambda_2} \mathbf{u}_2 | \cdots | \sqrt{\lambda_k} \mathbf{u}_k], \quad (XX^T) \mathbf{u}_j = \lambda_j \mathbf{u}_j, \quad \mathbf{u}_i^T \mathbf{u}_j = \delta_{ij}.$$
(P.4.3)

• A **data** (**row**) **vector** x (**new or old**) is transformed to a *k*-dimensional row vector of principal components

$$\mathbf{z} = \mathbf{x} W_k \in \mathbb{R}^{1 \times k}. \tag{P.4.4}$$

• (Remark 7.5, p. 161). Let $X = U \Sigma V^T$ be the **SVD** of X, where

$$\Sigma = \mathbf{diag}(\sigma_1, \sigma_2, \cdots, \sigma_d), \quad \sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_d \ge 0.$$

Then,

$$V \cong W; \quad \sigma_j^2 = \lambda_j, \quad j = 1, 2, \cdots, d,$$

$$Z_k = [\sigma_1 \mathbf{u}_1 | \sigma_2 \mathbf{u}_2 | \cdots | \sigma_k \mathbf{u}_k].$$
(P.4.5)

Geometric Interpretation of PCA

Example P.9. Consider the following synthetic dataset.

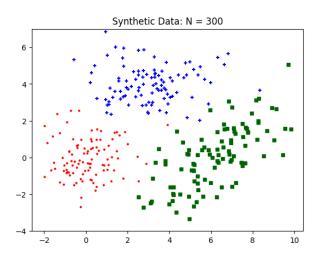


Figure P.5: A synthetic dataset of three classes.

• For each class, one may perform PCA along with the SVD.

```
for c in range(nclass):
    Xc = X[y==c]; CC = np.mean(Xc,axis=0)
    U, s, VT = svd(Xc-CC,full_matrices=False)
```

• Let $\mu^{(c)} = \text{CC[c]}$, $V^{(c)} = [\mathbf{v}_1^{(c)}, \cdots, \mathbf{v}_d^{(c)}]$, and $\sigma_j^{(c)} = s[j]$, the jth singular value for Class c. Define an **anisotropic distance** as

$$\gamma^{(c)}(\mathbf{x}) = \sum_{j=1}^{d} \left(\frac{(\mathbf{x} - \boldsymbol{\mu}^{(c)}) \cdot \mathbf{v}_{j}^{(c)}}{\sigma_{j}^{(c)}} \right)^{2}.$$
 (P.4.6)

- It is implemented in the function aniso_dist2, in util_PCA.py.
- For r > 0, $\gamma^{(c)}(\mathbf{x}) = r^2$ assigns an **ellipse**. \square

Definition P.10. The minimum-volume enclosing ellipsoid (MVEE) is the ellipsoid of smallest volume that fully contains all the objects.

Remark P.11. Let
$$r_{\text{max}}^{(c)}$$
 be

$$r_{\text{max}}^{(c)^{2}} = \max_{\mathbf{x} \in X^{(c)}} \gamma^{(c)}(\mathbf{x}).$$
 (P.4.7)

Then $\gamma^{(c)}(\mathbf{x}) = r_{\text{max}}^{(c)}$ approximates the MVEE relatively well. **See Figure P.6 (a).**

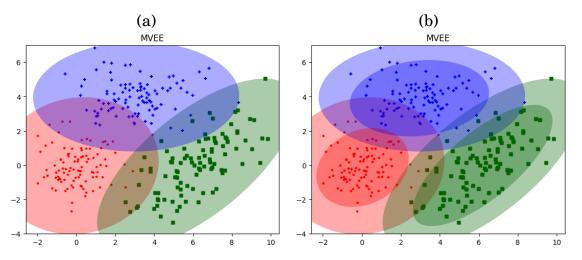


Figure P.6: Approximate MVEEs for: (a) the dataset and (b) the confidence regions.

Example P.12. Along with PCA:

- Either set a threshold $\theta > 0$
- or a portion 0 .

The confidence region for a class can be defined as the region where

- (a) either the points x satisfy $\gamma^{(c)}(\mathbf{x}) \leq \theta$ (as a result of a **histogram analysis**)
- (b) or only the *p*-portion of the near-center points are picked from the dataset ordered by the anisotropic distances.

Figure P.6(b) shows the confidence regions, for p=0.9.

Note: You must **first find confidence regions** for the training dataset, which can be viewed as **denoising**. You may **then begin the training step with the denoised dataset**.

What to do

- 1. Download PCA-KNN-Denoising.PY.tar:
 - https://skim.math.msstate.edu/LectureNotes/data/PCA-KNN-Denoising.PY.tar
- 2. Compose a **denoising-and-classification** code, using appropriate functions from the downloaded package.
 - You must implement both denoising algorithms: the *k*-NN-based and the PCA-based.
- 3. Use similar datasets, utilized for **Project 1. mCLESS**, Section P.3:
 - Select a **synthetic dataset**, using Line 7 or 8 in GLOBAL_VARIABLES.py.
 - **Real datasets**. Use public datasets such as iris and wine.

To get the public datasets, you may use:

```
from sklearn import datasets
data_read1 = datasets.load_iris()
data_read2 = datasets.load_wine()
```

- 4. Compare performances of the classifiers with and without denoising
 - LogisticRegression(max_iter = 1000)
 - KNeighborsClassifier(5)
 - SVC(gamma=2, C=1)
 - RandomForestClassifier(max_depth=5, n_estimators=50, max_features=1)
- 5. (Optional for Undergraduate Students)

Add modules for clustering-and-PCA denoising.

- For example, the MVEE does not make sense for a half-moon dataset.
- Add another dataset, such as

```
from sklearn.datasets import make_moons
X, y = make_moons(noise=0.2, n_samples=400, random_state=12)
```

- Preform k-Means cluster analysis for each class, with k=4.
- For each cluster in each class, perform the PCA-based denoising.
- Carry out Steps 2-4.
- 6. Report your experiments with the code and results.

Note: You did already the portion: "without denoising". Undergraduate students may consider that a class is a cluster. For graduate students, Step 5 will be worth 40% your score.