

Lec 1b

Lots of Algorithms Independently Discovered!

- Ford-Fulkerson
 - Integer capacities: maximum flow f in $O(m \cdot v(f))$
 - Real capacities: ∞ . It may never halt!
 - Useful for **thinking about** cuts & flows; not a great algorithm.
- Dinic/Dinitz (USSR → Israel)
 - Maximum flow in $O(mn^2)$ time. $n = |V|, m = |E|$.
- Edmonds-Karp (Canada-USA)
 - Maximum flow in $O(m^2n)$ time.

Recall that:

Formal Definition of Flow

- $f : V \times V \rightarrow \mathbb{Z}^+$ is a legal flow if it satisfies:
 - **CAPACITY CONSTRAINT:** $f(u, v) \leq c(u, v)$ $c(u, v) = 0$ if $(u, v) \notin E$
 - **SKEW SYMMETRY:** $f(u, v) = -f(v, u)$
 - **FLOW CONSERVATION:** for all $u \in V - \{s, t\}$
$$\sum_{(u,x) \in E} f(u, x) = 0. \quad (\text{flow out of } u = 0)$$
- $v(f)$ = total flow leaving s = total flow entering t

Residual Networks

- A flow f in G defines a **residual network** G_f
 - $c_f(u, v)$ represents the amount of additional flow that could be sent through (u, v) without violating the capacity constraint
 - $c_f(u, v) = c(u, v) - f(u, v)$
 - Only edges w/ **positive** capacity appear in G_f
- If f is a legal flow in G and f' is a legal flow in G_f then $f + f'$ is a legal flow in G .

Max-Flow — Min-Cut Theorem

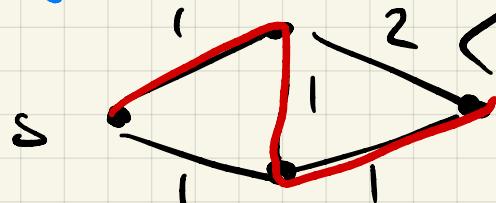
- The following are equivalent:
 - (1) f is a maximum flow in G
 - (2) There is no path from s to t in G_f
 - (3) $v(f) = c(A, B)$ for some $s-t$ cut (A, B)

Blocking Flows

Def) An edge $e \in E(G)$ is **saturated** by f if $f(e) = c(e)$

Def) A flow f in G is called a "**blocking flow**" if every path from s to t has a saturated edge

Note: blocking $\not\Rightarrow$ maximal



This is blocking with flow 1
as maximal is 2.

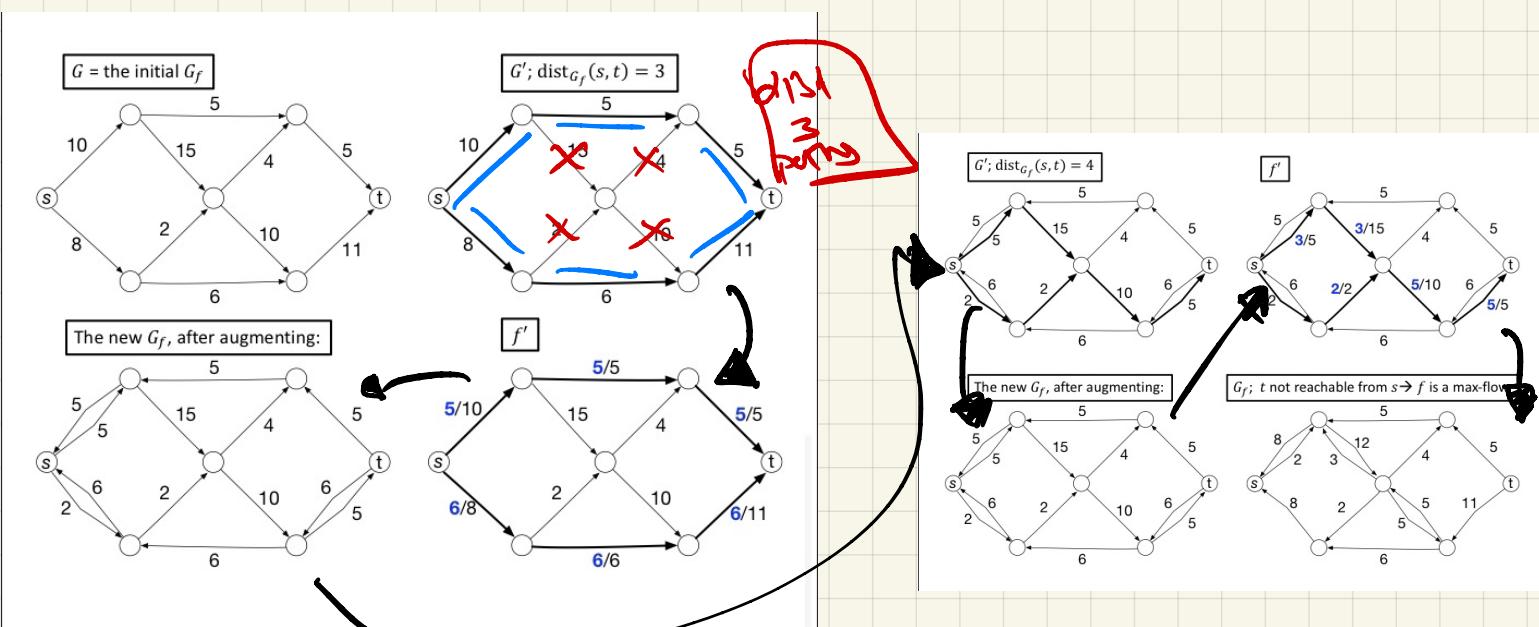
Dinitz's Max-Flow Algorithm

- $f := 0$
- While(f is not a maximum flow) {
 - Let G_f be the residual network for G w.r.t. f .
 - Let $G' = (V, E')$, where $E' \subseteq E(G_f)$ are those edges in **shortest paths from s to t in G_f** .
 - $f' :=$ any blocking flow in G'
 - $f := f + f'$
}

→ by max flow min cut
→ path from $s \rightarrow t$ in G_f

? flow in G'
as flow in G_f
 $\Rightarrow f + f'$ flow in G

Return f .



Issues

- 1) How to find a blocking flow
- 2) How many iterations

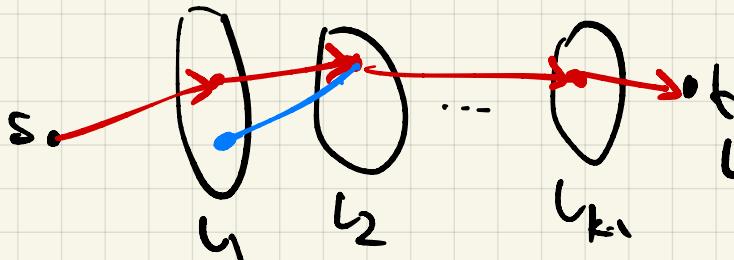
The key lemma

- Lemma: In every iteration of the while loop of Dinitz's algorithm, $\text{dist}_{G_f}(s, t)$ increases by at least 1.
- Corollary: The algorithm computes at most $n - 1$ blocking flows.

Unit weight edge graph

dist in $n-1$ edges
reduces

Think of G' as below



$$L_i = \{v \mid \text{dist}(s, v) = i\}$$

all good paths

(no edge with capacity > 2)
skips forward 2 layers

f' is a blocking flow in G'

$f'' = f + f'$ $\text{dist}(s, t)$ in $G_{f''}$ (s, t) $> k$

Let $P = (s = u_0, u_1, \dots, t)$ be a path in $G_{f''}$

→ no flow in either direction

cut ① $\forall i \ u_i \in L_j \Rightarrow u_{i+1} \in L_0 \cup \dots \cup L_{j+1}$ → if $u_{i+1} \in L_{j+2}$ or further

② $\exists i \text{ so } u_i \in L_j \text{ & } u_{i+1} \notin L_{j+1}$

$C_f(u_i, u_{i+1}) = 0$

but can't! ← only way it shows up if no flow!

→ can't have existed in G'

② By contra: if we advance exactly one layer
 $\Leftrightarrow (s_0 = u_0, \underbrace{u_1, \dots, u_k}_{l_0}, \underbrace{m_1 = t_0, \dots, m_k = t_k}_{l_k})$ in G_f' \Rightarrow same layer as earlier
 \Leftrightarrow haven't saturated in G_f !
 $\Leftrightarrow f'$ wasn't blocking

③ $\Rightarrow \text{dist}_{G_f'}(s, t) > \text{dist}_{G_f}(s, t)$!

Computing Blocking Flows

- Problem on HW5:
 - (1) A blocking flow can be computed in $O(mn)$ time.
 - (2) If, $\forall e \in E, c(e) = 1$, a blocking flow can be computed in $O(m)$ time.
- Theorem.** Dinitz's max flow algorithm takes $O(mn^2)$ time.
- Pf.** There are $< n$ blocking flows, each takes $O(mn)$ time.

Dinitz trivial $O(n^2)$

DFS $O(n)$

\hookrightarrow saturate edge on path
 \Leftrightarrow since it saturates an edge
 \Leftrightarrow at most n iter

Dynamic Trees, min cut tree

Edmonds-Karp MaxFlow

- $f := 0$
 - While(f is not a maximum flow) {
 - Let G_f be the residual network for G w.r.t. f .
 - Let P be a **shortest path** from s to t in G_f .
 - $f' :=$ maximum flow along P .
 - $f := f + f'$
- Return f .

Unit-Capacity Networks

- Theorem.** [Karzanov, Even-Tarjan] If $G = (V, E, c)$ is a flow network with
 - $c(s, u)$ and $c(u, t)$ arbitrary.
 - $c(u, v) = 1$ for all other edges $(u, v) \in E$.
- then Dinitz's alg. takes $O(\min\{m^{3/2}, mn^{2/3}\})$ time.

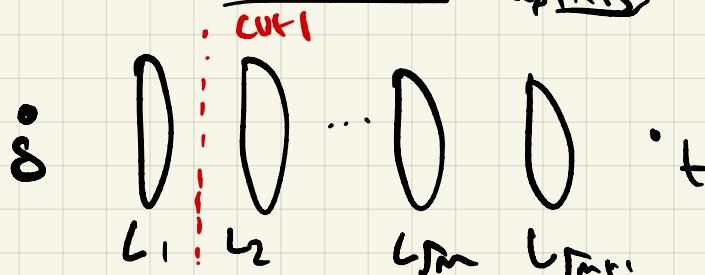
Holds even if G is a multigraph

Only holds if G is simple (multiple copies of same edge disallowed)

Maximum Matching

- Theorem.** [Karzanov, Hopcroft-Karp] A maximum matching in a **bipartite** graph $G = (A \cup B, E)$ can be computed in $O(m\sqrt{n})$ time.
- The algorithm:
 - Convert G to a flow network. (Direct edges from A to B , add s, t , put capacity $c(e) = 1$ on all edges.)
 - Run Dinitz's algorithm. Running time is $O(m \cdot (\#BF))$ where $(\#BF)$ is the number of blocking flows.

\hookrightarrow well in unit cap graph \hookrightarrow **blocking flow is linear**. \hookrightarrow **flow** \hookrightarrow $\#BF = O(\sqrt{m})$ \hookrightarrow $O(m)$ \hookrightarrow **iterations**



$$\begin{aligned} v(P_f^*) - v(P_f) &\leq c((\text{cut}_1), \dots, \text{cut}(\sqrt{m})) \\ \Rightarrow \min_{1 \leq i \leq \sqrt{m}} c(\text{cut}(i)) &\leq \sqrt{m} \end{aligned}$$

\hookrightarrow by **Pidgeonhole**

any blocking flow get at least 1.

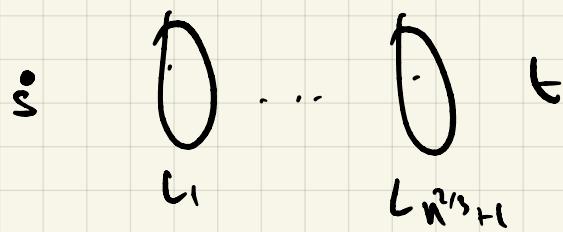
At most another $\frac{1}{m}$ iter

$\hookrightarrow O(m^{1/2}) / \text{iter}$

Claim $\#B\text{-f} \in O(n^{2/3})$ Suppose simple graph

Similar argument

$$n^{2/3} + 1 \text{ BF.}$$



$$\text{cut}_i = (\dots l_i) (\dots l_{n^{2/3}})$$

$$c(\text{wt}_i) \leq |l_i| \cdot |l_{i+1}|$$

worse $\leq \left(\frac{|l_i| + |l_{i+1}|}{2} \right)^2$ geometric mean

\bigcup_i O comp
l_i (l_i is bipartite)

$$\sum_i \left(\frac{|l_i| + |l_{i+1}|}{2} \right)^2 \leq n$$

$$\therefore v(f) - v(f^*) = \min_i c(\text{cut}_i) \leq (n^{1/3})^2$$



$$\Rightarrow \text{need } n^{2/3} + n^{2/3} \text{ iter} \Rightarrow \underline{O(n^{2/3})}$$

$$\frac{n}{n^{2/3}} = n^{1/3}$$

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$\leq \sqrt{n}$ bf

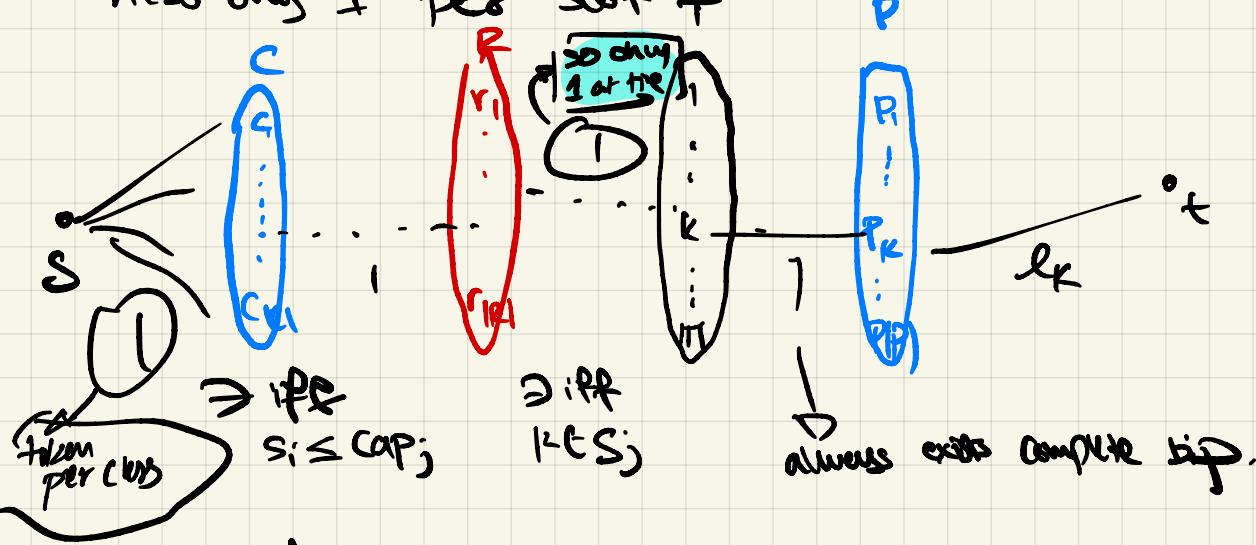


Application

Scheduling Finaly

- C classes. Class C_i has s_i students
- R rooms. room r_j has capacity cap_j
- T time slots. Room r_j available in slots $S_j = \{1, \dots, T\}$
- P proctors that can proctor P_k ones at most R_k exams.

Also only 1 per slot T



Another example: precedence constn..