



# REPORT - ASSIGNMENT 1

MONSOON SEMESTER 2022

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## Introduction

In Computer Graphics, many concepts are widely used in various fields. Two of these concepts are “Bezier Curves” and “Shape Modeling,” on which the assignment was given. A summary of the work completed as part of the given assignment in CSE333/533 in the area of Computer Graphics is presented in this report.

### QUESTION 1

In this question , our objective is to create a cylinder using its parametric equation.

Parametric equation of a cylinder is

$$X = a \cos(t)$$

$$Y = a \sin(t)$$

$$Z = h$$

```
//Shape data
size_t nVertices = 5*2*4*2*3; // No. of vertices of the shape
GLfloat *shape_vertices = new GLfloat[nVertices*3];
float pi = M_PI;
float arr[9][3];
for(int u = 0 ; u <= 8 ; u++){
    float x = 5*cos(u*pi/(float)4.0f);
    float y = 5*sin(u*pi/(float)4.0f);
    float z = 0.0f;
    arr[u][0] = x;
    arr[u][1] = y;
    arr[u][2] = z;
}
```

Here, we create an array to store the set of points of x,y,z. Radius is constant at 5.

```
for(int j = 1; j<6 ; j++){
    for (size_t l = 0; l < 8; l++) {
        int k = ((j-1)*8*2*3*3)+(l*18);
        shape_vertices[k+9] = shape_vertices[k+0] = arr[l][0];
        shape_vertices[k+10] = shape_vertices[k+1] = arr[l][1];
        shape_vertices[k+11] = shape_vertices[k+2] = j*5;

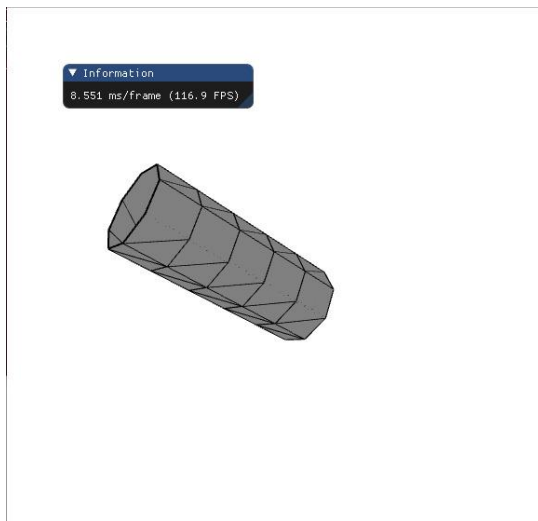
        shape_vertices[k+3] = arr[l][0];
        shape_vertices[k+4] = arr[l][1];
        shape_vertices[k+5] = (j-1)*5;

        shape_vertices[k+12] = arr[l+1][0];
        shape_vertices[k+13] = arr[l+1][1];
        shape_vertices[k+14] = j*5;

        shape_vertices[k+15] = shape_vertices[k+6] = arr[l+1][0];
        shape_vertices[k+16] = shape_vertices[k+7] = arr[l+1][1];
        shape_vertices[k+17] = shape_vertices[k+8] = (j-1)*5;
    }
}
```

Here, we are storing all the coordinates of the vertices of the shape.

**Output of the code is shown below**



The code is also attached in the zip file submitted on the classroom.

## QUESTION 2

To design an interpolating piecewise cubic Bezier curve, we must understand the concept of linear interpolation.

We know that, by linear interpolation, we can express any point  $x$  on a straight line such that  $t$  divides the line in the ratio  $t : 1-t$ , where  $t$  is the parameter.

For the cubic Bezier curve, the approach is pretty exact. Moreover, it will be based on the principle of repeated linear interpolation.

Here, we have degree 3 of the polynomial, and we know that degree = no. of pts - 1 or no. of pts = degree + 1.

Therefore, we will have 4 control points to draw the Bezier curve.

We also know that to find the number of linear interpolations needed to draw a curve of  $n$  degree and  $n+1$  control points, we can find by using the formula.

$$N = n(n+1)/2$$

Here,  $n = 3$

Therefore, no. of linear interpolations required = 6.

## Pseudo Code

```
Display_Bezier( $P_0, P_1, P_2, P_3$ ) {
    if( $P_0, P_1, P_2, P_3$  are flat or collinear){
        draw straight line  $P_0P_3$ ;
```

```

else{

subdivide P0,P1,P2,P3 into L0,L1,L2,L3 and R0,R1,R2,R3

Display_Bezier(L0,L1,L2,L3);

Display_Bezier(R0,R1,R2,R3);

End

End

```

This algorithm is also known as Recursive Subdivision display algorithm. (Also, given in the [Lec 02 resources](#)).

### Derivation of the cubic curve

We have 4 control pts:  $P_0, P_1, P_2, P_3$  and let  $t \in \mathbb{R}$   
Four points are taken from the set of  $n$  points in a plane

$$P_0^1(t) = (1-t)P_0 + tP_1$$

$$P_1^1(t) = (1-t)P_1 + tP_2$$

$$P_2^1(t) = (1-t)P_2 + tP_3$$

$$P_0^2(t) = (1-t)P_0^1(t) + tP_1^1(t)$$

$$P_1^2(t) = (1-t)P_1^1(t) + tP_2^1(t)$$

$$P_0^3(t) = (1-t)P_0^2(t) + tP_1^2(t)$$

By putting first 3 eq<sup>s</sup> in next two

$$P_0^2(t) = (1-t)^2 P_0 + 2(1-t)t P_1 + t^2 P_2$$

$$P_1^2(t) = (1-t)^2 P_1 + 2(1-t)t P_2 + t^2 P_3$$

By putting these eq<sup>s</sup> in last eq<sup>n</sup>.

$$P_0^3(t) = (1-t)^3 P_0 + 3(1-t)^2 t P_1 + 3(1-t)t^2 P_2 + t^3 P_3$$

Superscript here denote the curve degree.

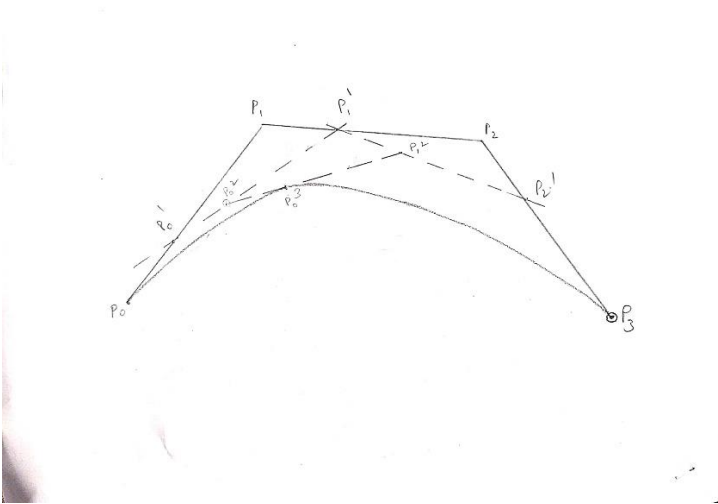
In lecture slide 2, using ~~de~~ de Casteljau algorithm

$$P_i^K(t) = (1-t)P_i^{K-1}(t) + tP_{i+1}^{K-1}(t)$$

$$P_i^0(t) = P_i$$

From the equation derived, the equation is a cubic expression in  $t$ . Hence the curve obtained is a cubic Bezier curve.

### Geometric Representation of the curve at $t=3$



### Continuity

For continuity, the Bezier curves should obey the following two properties :-

- $d(P)/dt_{(At\ 0)} = d(Q)/dt_{(At\ 1)}$
- When the tangent drawn from the intersection point from both the curve, they should point in the same direction.

Now, consider 2 sets of four points such that there is a common point in both the curves.

The tangent from that common point always satisfies the direction for both the curves.

Hence, the curve will always be in  $C_1$  continuity.

### SOURCES

<https://ctan.math.illinois.edu/macros/latex/contrib/lapdf/bezinfo.pdf>

<https://www.kth.se/social/files/55492cacf276542be2fc547a/BezierCurvesAndSurfaces.pdf>

[https://www.cs.utexas.edu/users/fussell/courses/cs384g-fall2011/lectures/lecture16-Interpolating\\_curves.pdf](https://www.cs.utexas.edu/users/fussell/courses/cs384g-fall2011/lectures/lecture16-Interpolating_curves.pdf)