Stereo matching estimates the disparity between a rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing, autonomous driving, and other rectified image pair, which is of great importance to depth sensing and the properties of the properties o	related ta