Contents

1 Combinatorial optimization

1.1 Dinic's

```
struct Dinic {
  struct Edge {
    int u, v;
    long long cap, flow;
    Edge() {}
    Edge(int u, int v, long long cap): u(u), v(v), cap(
        cap), flow(0) {}
  };
  int N;
  vector<Edge> E;
  vector<vector<int>> g;
  vector<int> d, pt;

  Dinic(int N): N(N), E(0), g(N), d(N), pt(N) {}

  void AddEdge(int u, int v, long long cap) {
    if (u != v) {
      E.emplace_back(Edge(u, v, cap));
      g[u].emplace_back(E.size() - 1);
      E.emplace_back(Edge(v, u, 0));
      g[v].emplace_back(E.size() - 1);
    }
  }

  bool BFS(int S, int T) {
    queue<int> q({S});
    fill(d.begin(), d.end(), N + 1);
    d[S] = 0;
    while(!q.empty()) {
      int u = q.front(); q.pop();
      if (u == T) break;
      for (int k: g[u]) {
        Edge &e = E[k];
        if (e.flow < e.cap && d[e.v] > d[e.u] + 1) {
          d[e.v] = d[e.u] + 1;
          q.emplace(e.v);
        }
      }
    }
    return d[T] != N + 1;
  }

  long long DFS(int u, int T, long long flow = -1) {
    if (u == T || flow == 0) return flow;
    for (int &i = pt[u]; i < g[u].size(); ++i) {
      Edge &e = E[g[u][i]];
      Edge &oe = E[g[u][i]^1];
      if (d[e.v] == d[e.u] + 1) {
        long long amt = e.cap - e.flow;
        if (flow != -1 && amt > flow) amt = flow;
        if (long long pushed = DFS(e.v, T, amt)) {
          e.flow += pushed;
          oe.flow -= pushed;
          return pushed;
        }
      }
    }
```

```
    return 0;
  }

  long long MaxFlow(int S, int T) {
    long long total = 0;
    while (BFS(S, T)) {
      fill(pt.begin(), pt.end(), 0);
      while (long long flow = DFS(S, T))
        total += flow;
    }
    return total;
  }
};
```

1.2 Min-cost max-flow

```
// Implementation of min cost max flow algorithm using adjacency
// matrix (Edmonds and Karp 1972).  This implementation keeps track of
// forward and reverse edges separately (so you can set cap[i][j] !=
// cap[j][i]).  For a regular max flow, set all edge costs to 0.
//
// Running time, O(|V|^2) cost per augmentation
//     max flow:           O(|V|^3) augmentations
//     min cost max flow:  O(|V|^4 * MAX_EDGE_COST) augmentations
//
// INPUT:
//     - graph, constructed using AddEdge()
//     - source
//     - sink
//
// OUTPUT:
//     - (maximum flow value, minimum cost value)
//     - To obtain the actual flow, look at positive values only.

#include <cmath>
#include <vector>
#include <iostream>

using namespace std;

typedef vector<int> VI;
typedef vector<VI> VVI;
typedef long long L;
typedef vector<L> VL;
typedef vector<VL> VVL;
typedef pair<int, int> PII;
typedef vector<PII> VPII;

const L INF = numeric_limits<L>::max() / 4;

struct MinCostMaxFlow {
  int N;
  VVL cap, flow, cost;
  VI found;
  VL dist, pi, width;
  VPII dad;

  MinCostMaxFlow(int N) :
    N(N), cap(N, VL(N)), flow(N, VL(N)), cost(N, VL(N)),
    found(N), dist(N), pi(N), width(N), dad(N) {}

  void AddEdge(int from, int to, L cap, L cost) {
    this->cap[from][to] = cap;
    this->cost[from][to] = cost;
  }

  void Relax(int s, int k, L cap, L cost, int dir) {
    L val = dist[s] + pi[s] - pi[k] + cost;
    if (cap && val < dist[k]) {
      dist[k] = val;
      dad[k] = make_pair(s, dir);
      width[k] = min(cap, width[s]);
    }
  }

  L Dijkstra(int s, int t) {
    fill(found.begin(), found.end(), false);
    fill(dist.begin(), dist.end(), INF);
    fill(width.begin(), width.end(), 0);
    dist[s] = 0;
    width[s] = INF;

    while (s != -1) {
      int best = -1;
      found[s] = true;
      for (int k = 0; k < N; k++) {
        if (found[k]) continue;
        Relax(s, k, cap[s][k] - flow[s][k], cost[s][k], 1);
        Relax(s, k, flow[k][s], -cost[k][s], -1);
        if (best == -1 || dist[k] < dist[best]) best = k;
      }
      s = best;
    }

    for (int k = 0; k < N; k++)
      pi[k] = min(pi[k] + dist[k], INF);
    return width[t];
  }

  pair<L, L> GetMaxFlow(int s, int t) {
    L totflow = 0, totcost = 0;
    while (L amt = Dijkstra(s, t)) {
      totflow += amt;
      for (int x = t; x != s; x = dad[x].first) {
        if (dad[x].second == 1) {
          flow[dad[x].first][x] += amt;
          totcost += amt * cost[dad[x].first][x];
        } else {
          flow[x][dad[x].first] -= amt;
          totcost -= amt * cost[x][dad[x].first];
        }
      }
    }
    return make_pair(totflow, totcost);
  }
};

// BEGIN CUT
// The following code solves UVA problem #10594: Data
```

```
  Flow
int main() {
  int N, M;

  while (scanf("%d%d", &N, &M) == 2) {
    VVL v(M, VL(3));
    for (int i = 0; i < M; i++)
      scanf("%Ld%Ld%Ld", &v[i][0], &v[i][1], &v[i][2]);
    L D, K;
    scanf("%Ld%Ld", &D, &K);

    MinCostMaxFlow mcmf(N+1);
    for (int i = 0; i < M; i++) {
      mcmf.AddEdge(int(v[i][0]), int(v[i][1]), K, v[i
          ][2]);
      mcmf.AddEdge(int(v[i][1]), int(v[i][0]), K, v[i
          ][2]);
    }
    mcmf.AddEdge(0, 1, D, 0);

    pair<L, L> res = mcmf.GetMaxFlow(0, N);

    if (res.first == D) {
      printf("%Ld\n", res.second);
    } else {
      printf("Impossible.\n");
    }
  }

  return 0;
}
// END CUT
```

1.3 Edmonds Max Matching

```
/*
Input:
V->number of vertices
E->number of edges
pair of vertices as edges (vertices are 1..V)

Output:
output of edmonds() is the maximum matching
match[i] is matched pair of i (-1 if there isn't a
    matched pair)
 */
#include <bits/stdc++.h>
using namespace std;
const int M=505;
struct struct_edge{int v;struct_edge* n;};
typedef struct_edge* edge;
struct_edge pool[M*M*2];
edge top=pool,adj[M];
int V,E,match[M],qh,qt,q[M],father[M],base[M];
bool inq[M],inb[M],ed[M][M];
void add_edge(int u,int v)
{
  top->v=v,top->n=adj[u],adj[u]=top++;
  top->v=u,top->n=adj[v],adj[v]=top++;
}
int LCA(int root,int u,int v)
{
  static bool inp[M];
  memset(inp,0,sizeof(inp));
  while(1)
    {
      inp[u=base[u]]=true;
      if (u==root) break;
      u=father[match[u]];
    }
  while(1)
    {
      if (inp[v=base[v]]) return v;
      else v=father[match[v]];
    }
}
void mark_blossom(int lca,int u)
{
  while (base[u]!=lca)
    {
      int v=match[u];
      inb[base[u]]=inb[base[v]]=true;
      u=father[v];
      if (base[u]!=lca) father[u]=v;
    }
}
void blossom_contraction(int s,int u,int v)
{
  int lca=LCA(s,u,v);
  memset(inb,0,sizeof(inb));
  mark_blossom(lca,u);
  mark_blossom(lca,v);
  if (base[u]!=lca)
    father[u]=v;
  if (base[v]!=lca)
    father[v]=u;
  for (int u=0;u<V;u++)
    if (inb[base[u]])
      {
  base[u]=lca;
  if (!inq[u])
    inq[q[++qt]=u]=true;
      }
}
int find_augmenting_path(int s)
{
  memset(inq,0,sizeof(inq));
  memset(father,-1,sizeof(father));
  for (int i=0;i<V;i++) base[i]=i;
  inq[q[qh=qt=0]=s]=true;
  while (qh<=qt)
    {
      int u=q[qh++];
      for (edge e=adj[u];e;e=e->n)
        {
    int v=e->v;
    if (base[u]!=base[v]&&match[u]!=v)
      if ((v==s)||(match[v]!=-1 && father[match[v]]!=-1)
        )
        blossom_contraction(s,u,v);
      else if (father[v]==-1)
        {
```

```
      father[v]=u;
      if (match[v]==-1)
        return v;
      else if (!inq[match[v]])
        inq[q[++qt]=match[v]]=true;
          }
          }
      }
    return -1;
  }
  int augment_path(int s,int t)
  {
    int u=t,v,w;
    while (u!=-1)
      {
        v=father[u];
        w=match[v];
        match[v]=u;
        match[u]=v;
        u=w;
      }
    return t!=-1;
  }
  int edmonds()
  {
    int matchc=0;
    memset(match,-1,sizeof(match));
    for (int u=0;u<V;u++)
      if (match[u]==-1)
        matchc+=augment_path(u,find_augmenting_path(u));
    return matchc;
  }
  int main()
  {
    int u,v;
    cin>>V>>E;
    while(E--)
      {
        cin>>u>>v;
        if (!ed[u-1][v-1])
    {
      add_edge(u-1,v-1);
      ed[u-1][v-1]=ed[v-1][u-1]=true;
    }
      }
    cout<<edmonds()<<endl;
    for (int i=0;i<V;i++)
      if (i<match[i])
        cout<<i+1<<" "<<match[i]+1<<endl;
  }
```

1.4 Global min-cut

```
// Adjacency matrix implementation of Stoer-Wagner min
   cut algorithm.
//
// Running time:
//     O(|V|^3)
//
// INPUT:
//     - graph, constructed using AddEdge()
//
// OUTPUT:
//     - (min cut value, nodes in half of min cut)

#include <cmath>
#include <vector>
#include <iostream>

using namespace std;

typedef vector<int> VI;
typedef vector<VI> VVI;

const int INF = 1000000000;

pair<int, VI> GetMinCut(VVI &weights) {
  int N = weights.size();
  VI used(N), cut, best_cut;
  int best_weight = -1;

  for (int phase = N-1; phase >= 0; phase--) {
    VI w = weights[0];
    VI added = used;
    int prev, last = 0;
    for (int i = 0; i < phase; i++) {
      prev = last;
      last = -1;
      for (int j = 1; j < N; j++)
        if (!added[j] && (last == -1 || w[j] > w[last]))
          last = j;
      if (i == phase-1) {
        for (int j = 0; j < N; j++) weights[prev][j] +=
            weights[last][j];
        for (int j = 0; j < N; j++) weights[j][prev] =
            weights[prev][j];
        used[last] = true;
        cut.push_back(last);
        if (best_weight == -1 || w[last] < best_weight)
          {
          best_cut = cut;
          best_weight = w[last];
        }
      } else {
        for (int j = 0; j < N; j++)
          w[j] += weights[last][j];
        added[last] = true;
      }
    }
  }
  return make_pair(best_weight, best_cut);
}

// BEGIN CUT
// The following code solves UVA problem #10989: Bomb,
   Divide and Conquer
int main() {
  int N;
  cin >> N;
  for (int i = 0; i < N; i++) {
    int n, m;
    cin >> n >> m;
    VVI weights(n, VI(n));
```

```
    for (int j = 0; j < m; j++) {
      int a, b, c;
      cin >> a >> b >> c;
      weights[a-1][b-1] = weights[b-1][a-1] = c;
    }
    pair<int, VI> res = GetMinCut(weights);
    cout << "Case #" << i+1 << ": " << res.first << endl
        ;
  }
}
// END CUT
```

2 Geometry

2.1 Convex hull

```
typedef pair<long long, long long> PT;
long double dist(PT a, PT b){
  return sqrt(pow(a.first-b.first,2)+pow(a.second-b.
      second,2));
}

long long cross(PT o, PT a, PT b){
  PT OA = {a.first-o.first,a.second-o.second};
  PT OB = {b.first-o.first,b.second-o.second};
  return OA.first*OB.second - OA.second*OB.first;
}
vector<PT> convexhull(){
  vector<PT> hull;
  sort(a,a+n,[](PT i, PT j){
    if(i.second!=j.second)
      return i.second < j.second;
    return i.first < j.first;
  });
  for(int i=0;i<n;++i){
    while(hull.size()>1 && cross(hull[hull.size()-2],
        hull.back(),a[i])<=0)
      hull.pop_back();
    hull.push_back(a[i]);
  }
  for(int i=n-1, siz = hull.size();i--;){
    while(hull.size()>siz && cross(hull[hull.size()-2],
        hull.back(),a[i])<=0)
      hull.pop_back();
    hull.push_back(a[i]);
  }
  return hull;
}
```

2.2 Miscellaneous geometry

```
double INF = 1e100,EPS = 1e-12;

struct PT {
  double x, y;
  PT() {}
  PT(double x, double y) : x(x), y(y) {}
  PT(const PT &p) : x(p.x), y(p.y)    {}
  PT operator + (const PT &p)  const { return PT(x+p.x,
      y+p.y); }
  PT operator - (const PT &p)  const { return PT(x-p.x,
      y-p.y); }
  PT operator * (double c)     const { return PT(x*c,
      y*c  ); }
  PT operator / (double c)     const { return PT(x/c,
      y/c  ); }
};

double dot(PT p, PT q)     { return p.x*q.x+p.y*q.y; }
double dist2(PT p, PT q)   { return dot(p-q,p-q); }
double cross(PT p, PT q)   { return p.x*q.y-p.y*q.x; }
ostream &operator<<(ostream &os, const PT &p) {
  os << "(" << p.x << "," << p.y << ")";
}

// rotate a point CCW or CW around the origin
PT RotateCCW90(PT p)   { return PT(-p.y,p.x); }
PT RotateCW90(PT p)    { return PT(p.y,-p.x); }
PT RotateCCW(PT p, double t) {
  return PT(p.x*cos(t)-p.y*sin(t), p.x*sin(t)+p.y*cos(t)
      );
}

// project point c onto line through a and b
// assuming a != b
PT ProjectPointLine(PT a, PT b, PT c) {
  return a + (b-a)*dot(c-a, b-a)/dot(b-a, b-a);
}

// project point c onto line segment through a and b
PT ProjectPointSegment(PT a, PT b, PT c) {
  double r = dot(b-a,b-a);
  if (fabs(r) < EPS) return a;
  r = dot(c-a, b-a)/r;
  if (r < 0) return a;
  if (r > 1) return b;
  return a + (b-a)*r;
}

// compute distance from c to segment between a and b
double DistancePointSegment(PT a, PT b, PT c) {
  return sqrt(dist2(c, ProjectPointSegment(a, b, c)));
}

// compute distance between point (x,y,z) and plane ax+
    by+cz=d
double DistancePointPlane(double x, double y, double z,
                          double a, double b, double c,
                              double d)
{
  return fabs(a*x+b*y+c*z-d)/sqrt(a*a+b*b+c*c);
}

// determine if lines from a to b and c to d are
    parallel or collinear
bool LinesParallel(PT a, PT b, PT c, PT d) {
  return fabs(cross(b-a, c-d)) < EPS;
}

bool LinesCollinear(PT a, PT b, PT c, PT d) {
  return LinesParallel(a, b, c, d)
      && fabs(cross(a-b, a-c)) < EPS
      && fabs(cross(c-d, c-a)) < EPS;
```

```
}

// determine if line segment from a to b intersects with
// line segment from c to d
bool SegmentsIntersect(PT a, PT b, PT c, PT d) {
  if (LinesCollinear(a, b, c, d)) {
    if (dist2(a, c) < EPS || dist2(a, d) < EPS ||
      dist2(b, c) < EPS || dist2(b, d) < EPS) return
          true;
    if (dot(c-a, c-b) > 0 && dot(d-a, d-b) > 0 && dot(c-
        b, d-b) > 0)
      return false;
    return true;
  }
  if (cross(d-a, b-a) * cross(c-a, b-a) > 0) return
      false;
  if (cross(a-c, d-c) * cross(b-c, d-c) > 0) return
      false;
  return true;
}

// compute intersection of line passing through a and b
// with line passing through c and d, assuming that
    unique
// intersection exists; for segment intersection, check
    if
// segments intersect first
PT ComputeLineIntersection(PT a, PT b, PT c, PT d) {
  b=b-a; d=c-d; c=c-a;
  assert(dot(b, b) > EPS && dot(d, d) > EPS);
  return a + b*cross(c, d)/cross(b, d);
}

// compute center of circle given three points
PT ComputeCircleCenter(PT a, PT b, PT c) {
  b=(a+b)/2;
  c=(a+c)/2;
  return ComputeLineIntersection(b, b+RotateCW90(a-b), c
      , c+RotateCW90(a-c));
}

// determine if point is in a possibly non-convex
    polygon (by William
// Randolph Franklin); returns 1 for strictly interior
    points, 0 for
// strictly exterior points, and 0 or 1 for the
    remaining points.
// Note that it is possible to convert this into an *
    exact* test using
// integer arithmetic by taking care of the division
    appropriately
// (making sure to deal with signs properly) and then by
     writing exact
// tests for checking point on polygon boundary
bool PointInPolygon(const vector<PT> &p, PT q) {
  bool c = 0;
  for (int i = 0; i < p.size(); i++){
    int j = (i+1)%p.size();
    if ((p[i].y <= q.y && q.y < p[j].y ||
      p[j].y <= q.y && q.y < p[i].y) &&
      q.x < p[i].x + (p[j].x - p[i].x) * (q.y - p[i].y)
          / (p[j].y - p[i].y))
      c = !c;
  }
  return c;
}

// determine if point is on the boundary of a polygon
bool PointOnPolygon(const vector<PT> &p, PT q) {
  for (int i = 0; i < p.size(); i++)
    if (dist2(ProjectPointSegment(p[i], p[(i+1)%p.size()
        ], q), q) < EPS)
      return true;
    return false;
}

// compute intersection of line through points a and b
    with
// circle centered at c with radius r > 0
vector<PT> CircleLineIntersection(PT a, PT b, PT c,
    double r) {
  vector<PT> ret;
  b = b-a;
  a = a-c;
  double A = dot(b, b);
  double B = dot(a, b);
  double C = dot(a, a) - r*r;
  double D = B*B - A*C;
  if (D < -EPS) return ret;
  ret.push_back(c+a+b*(-B+sqrt(D+EPS))/A);
  if (D > EPS)
    ret.push_back(c+a+b*(-B-sqrt(D))/A);
  return ret;
}

// compute intersection of circle centered at a with
    radius r
// with circle centered at b with radius R
vector<PT> CircleCircleIntersection(PT a, PT b, double r
    , double R) {
  vector<PT> ret;
  double d = sqrt(dist2(a, b));
  if (d > r+R || d+min(r, R) < max(r, R)) return ret;
  double x = (d*d-R*R+r*r)/(2*d);
  double y = sqrt(r*r-x*x);
  PT v = (b-a)/d;
  ret.push_back(a+v*x + RotateCCW90(v)*y);
  if (y > 0)
    ret.push_back(a+v*x - RotateCCW90(v)*y);
  return ret;
}

// This code computes the area or centroid of a (
    possibly nonconvex)
// polygon, assuming that the coordinates are listed in
    a clockwise or
// counterclockwise fashion.  Note that the centroid is
    often known as
// the "center of gravity" or "center of mass".
double ComputeSignedArea(const vector<PT> &p) {
  double area = 0;
  for(int i = 0; i < p.size(); i++) {
    int j = (i+1) % p.size();
    area += p[i].x*p[j].y - p[j].x*p[i].y;
  }
  return area / 2.0;
}
```

```
double ComputeArea(const vector<PT> &p) {
  return fabs(ComputeSignedArea(p));
}

PT ComputeCentroid(const vector<PT> &p) {
  PT c(0,0);
  double scale = 6.0 * ComputeSignedArea(p);
  for (int i = 0; i < p.size(); i++){
    int j = (i+1) % p.size();
    c = c + (p[i]+p[j])*(p[i].x*p[j].y - p[j].x*p[i].y);
  }
  return c / scale;
}

// tests whether or not a given polygon (in CW or CCW
   order) is simple
bool IsSimple(const vector<PT> &p) {
  for (int i = 0; i < p.size(); i++) {
    for (int k = i+1; k < p.size(); k++) {
      int j = (i+1) % p.size();
      int l = (k+1) % p.size();
      if (i == l || j == k) continue;
      if (SegmentsIntersect(p[i], p[j], p[k], p[l]))
        return false;
    }
  }
  return true;
}
```

2.3 3D geometry

```
public class Geom3D {
  // distance from point (x, y, z) to plane aX + bY + cZ
      + d = 0
  public static double ptPlaneDist(double x, double y,
      double z,
       double a, double b, double c, double d) {
    return Math.abs(a*x + b*y + c*z + d) / Math.sqrt(a*a
        + b*b + c*c);
  }

  // distance between parallel planes aX + bY + cZ + d1
      = 0 and
  // aX + bY + cZ + d2 = 0
  public static double planePlaneDist(double a, double b
      , double c,
       double d1, double d2) {
    return Math.abs(d1 - d2) / Math.sqrt(a*a + b*b + c*c
       );
  }

  // distance from point (px, py, pz) to line (x1, y1,
      z1)-(x2, y2, z2)
  // (or ray, or segment; in the case of the ray, the
      endpoint is the
  // first point)
  public static final int LINE = 0;
  public static final int SEGMENT = 1;
  public static final int RAY = 2;
  public static double ptLineDistSq(double x1, double y1
      , double z1,
       double x2, double y2, double z2, double px, double
          py, double pz,
       int type) {
    double pd2 = (x1-x2)*(x1-x2) + (y1-y2)*(y1-y2) + (z1
        -z2)*(z1-z2);

    double x, y, z;
    if (pd2 == 0) {
      x = x1;
      y = y1;
      z = z1;
    } else {
      double u = ((px-x1)*(x2-x1) + (py-y1)*(y2-y1) + (
          pz-z1)*(z2-z1)) / pd2;
      x = x1 + u * (x2 - x1);
      y = y1 + u * (y2 - y1);
      z = z1 + u * (z2 - z1);
      if (type != LINE && u < 0) {
        x = x1;
        y = y1;
        z = z1;
      }
      if (type == SEGMENT && u > 1.0) {
        x = x2;
        y = y2;
        z = z2;
      }
    }

    return (x-px)*(x-px) + (y-py)*(y-py) + (z-pz)*(z-pz)
        ;
  }

  public static double ptLineDist(double x1, double y1,
      double z1,
       double x2, double y2, double z2, double px, double
          py, double pz,
       int type) {
    return Math.sqrt(ptLineDistSq(x1, y1, z1, x2, y2, z2
        , px, py, pz, type));
  }
}
```

2.4 Slow Delaunay triangulation

```
// Slow but simple Delaunay triangulation. Does not
   handle
// degenerate cases (from O'Rourke, Computational
   Geometry in C)
//
// Running time: O(n^4)
//
// INPUT:    x[] = x-coordinates
//           y[] = y-coordinates
//
// OUTPUT:   triples = a vector containing m triples of
   indices
//                     corresponding to triangle
   vertices

#include<vector>
using namespace std;
```

```
typedef double T;

struct triple {
    int i, j, k;
    triple() {}
    triple(int i, int j, int k) : i(i), j(j), k(k) {}
};

vector<triple> delaunayTriangulation(vector<T>& x,
   vector<T>& y) {
        int n = x.size();
        vector<T> z(n);
        vector<triple> ret;

        for (int i = 0; i < n; i++)
            z[i] = x[i] * x[i] + y[i] * y[i];

        for (int i = 0; i < n-2; i++) {
            for (int j = i+1; j < n; j++) {
                for (int k = i+1; k < n; k++) {
                    if (j == k) continue;
                    double xn = (y[j]-y[i])*(z[k]-z[i])
                       - (y[k]-y[i])*(z[j]-z[i]);
                    double yn = (x[k]-x[i])*(z[j]-z[i])
                       - (x[j]-x[i])*(z[k]-z[i]);
                    double zn = (x[j]-x[i])*(y[k]-y[i])
                       - (x[k]-x[i])*(y[j]-y[i]);
                    bool flag = zn < 0;
                    for (int m = 0; flag && m < n; m++)
                        flag = flag && ((x[m]-x[i])*xn +
                                        (y[m]-y[i])*yn +
                                        (z[m]-z[i])*zn
                                           <= 0);
                    if (flag) ret.push_back(triple(i, j,
                        k));
                }
            }
        }
        return ret;
}

int main()
{
    T xs[]={0, 0, 1, 0.9};
    T ys[]={0, 1, 0, 0.9};
    vector<T> x(&xs[0], &xs[4]), y(&ys[0], &ys[4]);
    vector<triple> tri = delaunayTriangulation(x, y);

    //expected: 0 1 3
    //          0 3 2

    int i;
    for(i = 0; i < tri.size(); i++)
        printf("%d %d %d\n", tri[i].i, tri[i].j, tri[i].
           k);
    return 0;
}
```

3 Numerical algorithms

3.1 Number theory (modular, Chinese remainder, linear Diophantine)

```
// All algorithms described here work on nonnegative
   integers.

// return a % b (positive value)
int mod(int a, int b) {
        return ((a%b) + b) % b;
}

// computes lcm(a,b)
int lcm(int a, int b) {
        return a / __gcd(a, b)*b;
}

// (a^b) mod m via successive squaring
int powermod(int a, int b, int m){
        return b?powermod(a*a%m,b/2,m)*(b%2?a:1)%m:1;
}

// returns g = gcd(a, b); finds x, y such that d = ax +
   by
int extended_euclid(int a, int b, int &x, int &y) {
        int xx = y = 0;
        int yy = x = 1;
        while (b) {
                int q = a / b;
                int t = b; b = a%b; a = t;
                t = xx; xx = x - q*xx; x = t;
                t = yy; yy = y - q*yy; y = t;
        }
        return a;
}

// finds all solutions to ax = b (mod n)
VI modular_linear_equation_solver(int a, int b, int n) {
        int x, y;
        VI ret;
        int g = extended_euclid(a, n, x, y);
        if (!(b%g)) {
                x = mod(x*(b / g), n);
                for (int i = 0; i < g; i++)
                        ret.push_back(mod(x + i*(n / g),
                           n));
        }
        return ret;
}

// computes b such that ab = 1 (mod n), returns -1 on
   failure
int mod_inverse(int a, int n) {
        int x, y;
        int g = extended_euclid(a, n, x, y);
        if (g > 1) return -1;
        return mod(x, n);
}

// Chinese remainder theorem (special case): find z such
```

```
      that
// z % m1 = r1, z % m2 = r2.  Here, z is unique modulo M
      = lcm(m1, m2).
// Return (z, M).  On failure, M = -1.
PII chinese_remainder_theorem(int m1, int r1, int m2,
    int r2) {
        int s, t;
        int g = extended_euclid(m1, m2, s, t);
        if (r1%g != r2%g) return make_pair(0, -1);
        return make_pair(mod(s*r2*m1 + t*r1*m2, m1*m2) /
            g, m1*m2 / g);
}

// Chinese remainder theorem: find z such that
// z % m[i] = r[i] for all i.  Note that the solution is
// unique modulo M = lcm_i (m[i]).  Return (z, M). On
// failure, M = -1. Note that we do not require the a[i
    ]'s
// to be relatively prime.
PII chinese_remainder_theorem(const VI &m, const VI &r)
    {
        PII ret = make_pair(r[0], m[0]);
        for (int i = 1; i < m.size(); i++) {
                ret = chinese_remainder_theorem(ret.
                    second, ret.first, m[i], r[i]);
                if (ret.second == -1) break;
        }
        return ret;
}

// computes x and y such that ax + by = c
// returns whether the solution exists
bool linear_diophantine(int a, int b, int c, int &x, int
     &y) {
        if (!a && !b) {
                if (c) return false;
                x = 0; y = 0;
                return true;
        }
        if (!a) {
                if (c % b) return false;
                x = 0; y = c / b;
                return true;
        }
        if (!b) {
                if (c % a) return false;
                x = c / a; y = 0;
                return true;
        }
        int g = __gcd(a, b);
        if (c % g) return false;
        x = c / g * mod_inverse(a / g, b / g);
        y = (c - a*x) / b;
        return true;
}
```

3.2 Systems of linear equations, matrix inverse, determinant

```
// Gauss-Jordan elimination with full pivoting.
//
// Uses:
//    (1) solving systems of linear equations (AX=B)
//    (2) inverting matrices (AX=I)
//    (3) computing determinants of square matrices
//
// Running time: O(n^3)
//
// INPUT:    a[][] = an nxn matrix
//           b[][] = an nxm matrix
//
// OUTPUT:   X      = an nxm matrix (stored in b[][])
//           A^{-1} = an nxn matrix (stored in a[][])
//           returns determinant of a[][]

#include <iostream>
#include <vector>
#include <cmath>

using namespace std;

const double EPS = 1e-10;

typedef vector<int> VI;
typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

T GaussJordan(VVT &a, VVT &b) {
  const int n = a.size();
  const int m = b[0].size();
  VI irow(n), icol(n), ipiv(n);
  T det = 1;

  for (int i = 0; i < n; i++) {
    int pj = -1, pk = -1;
    for (int j = 0; j < n; j++) if (!ipiv[j])
      for (int k = 0; k < n; k++) if (!ipiv[k])
        if (pj == -1 || fabs(a[j][k]) > fabs(a[pj][pk]))
            { pj = j; pk = k; }
    if (fabs(a[pj][pk]) < EPS) { cerr << "Matrix is
        singular." << endl; exit(0); }
    ipiv[pk]++;
    swap(a[pj], a[pk]);
    swap(b[pj], b[pk]);
    if (pj != pk) det *= -1;
    irow[i] = pj;
    icol[i] = pk;

    T c = 1.0 / a[pk][pk];
    det *= a[pk][pk];
    a[pk][pk] = 1.0;
    for (int p = 0; p < n; p++) a[pk][p] *= c;
    for (int p = 0; p < m; p++) b[pk][p] *= c;
    for (int p = 0; p < n; p++) if (p != pk) {
      c = a[p][pk];
      a[p][pk] = 0;
      for (int q = 0; q < n; q++) a[p][q] -= a[pk][q] *
          c;
      for (int q = 0; q < m; q++) b[p][q] -= b[pk][q] *
          c;
    }
  }

  for (int p = n-1; p >= 0; p--) if (irow[p] != icol[p])
      {
```

```
      for (int k = 0; k < n; k++) swap(a[k][irow[p]], a[k
          ][icol[p]]);
    }

  return det;
}

int main() {
  const int n = 4;
  const int m = 2;
  double A[n][n] = {
      {1,2,3,4},{1,0,1,0},{5,3,2,4},{6,1,4,6} };
  double B[n][m] = { {1,2},{4,3},{5,6},{8,7} };
  VVT a(n), b(n);
  for (int i = 0; i < n; i++) {
    a[i] = VT(A[i], A[i] + n);
    b[i] = VT(B[i], B[i] + m);
  }

  double det = GaussJordan(a, b);

  // expected: 60
  cout << "Determinant: " << det << endl;

  // expected: -0.233333 0.166667 0.133333 0.0666667
  //            0.166667 0.166667 0.333333 -0.333333
  //            0.233333 0.833333 -0.133333 -0.0666667
  //            0.05 -0.75 -0.1 0.2
  cout << "Inverse: " << endl;
  for (int i = 0; i < n; i++) {
    for (int j = 0; j < n; j++)
      cout << a[i][j] << ' ';
    cout << endl;
  }

  // expected: 1.63333 1.3
  //           -0.166667 0.5
  //            2.36667 1.7
  //           -1.85 -1.35
  cout << "Solution: " << endl;
  for (int i = 0; i < n; i++) {
    for (int j = 0; j < m; j++)
      cout << b[i][j] << ' ';
    cout << endl;
  }
}
```

3.3 Reduced row echelon form, matrix rank

```
// Reduced row echelon form via Gauss-Jordan elimination
// with partial pivoting.  This can be used for
    computing
// the rank of a matrix.
//
// Running time: O(n^3)
//
// INPUT:    a[][] = an nxm matrix
//
// OUTPUT:   rref[][] = an nxm matrix (stored in a[][])
//           returns rank of a[][]

#include <iostream>
#include <vector>
#include <cmath>

using namespace std;

const double EPSILON = 1e-10;

typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

int rref(VVT &a) {
  int n = a.size();
  int m = a[0].size();
  int r = 0;
  for (int c = 0; c < m && r < n; c++) {
    int j = r;
    for (int i = r + 1; i < n; i++)
      if (fabs(a[i][c]) > fabs(a[j][c])) j = i;
    if (fabs(a[j][c]) < EPSILON) continue;
    swap(a[j], a[r]);

    T s = 1.0 / a[r][c];
    for (int j = 0; j < m; j++) a[r][j] *= s;
    for (int i = 0; i < n; i++) if (i != r) {
      T t = a[i][c];
      for (int j = 0; j < m; j++) a[i][j] -= t * a[r][j
          ];
    }
    r++;
  }
  return r;
}

int main() {
  const int n = 5, m = 4;
  double A[n][m] = {
    {16,  2,  3, 13},
    { 5, 11, 10,  8},
    { 9,  7,  6, 12},
    { 4, 14, 15,  1},
    {13, 21, 21, 13}};
  VVT a(n);
  for (int i = 0; i < n; i++)
    a[i] = VT(A[i], A[i] + m);

  int rank = rref(a);

  // expected: 3
  cout << "Rank: " << rank << endl;

  // expected: 1 0 0 1
  //           0 1 0 3
  //           0 0 1 -3
  //           0 0 0 3.10862e-15
  //           0 0 0 2.22045e-15
  cout << "rref: " << endl;
  for (int i = 0; i < 5; i++) {
    for (int j = 0; j < 4; j++)
      cout << a[i][j] << ' ';
    cout << endl;
  }
}
```

3.4 Simplex algorithm

```cpp
// Two-phase simplex algorithm for solving linear programs of the form
//
//     maximize     c^T x
//     subject to   Ax <= b
//                  x >= 0
//
// INPUT: A -- an m x n matrix
//        b -- an m-dimensional vector
//        c -- an n-dimensional vector
//        x -- a vector where the optimal solution will be stored
//
// OUTPUT: value of the optimal solution (infinity if unbounded
//         above, nan if infeasible)
//
// To use this code, create an LPSolver object with A, b, and c as
// arguments.  Then, call Solve(x).

#include <iostream>
#include <iomanip>
#include <vector>
#include <cmath>
#include <limits>

using namespace std;

typedef long double DOUBLE;
typedef vector<DOUBLE> VD;
typedef vector<VD> VVD;
typedef vector<int> VI;

const DOUBLE EPS = 1e-9;

struct LPSolver {
  int m, n;
  VI B, N;
  VVD D;

  LPSolver(const VVD &A, const VD &b, const VD &c) :
    m(b.size()), n(c.size()), N(n + 1), B(m), D(m + 2, VD(n + 2)) {
    for (int i = 0; i < m; i++) for (int j = 0; j < n; j++) D[i][j] = A[i][j];
    for (int i = 0; i < m; i++) { B[i] = n + i; D[i][n] = -1; D[i][n + 1] = b[i]; }
    for (int j = 0; j < n; j++) { N[j] = j; D[m][j] = -c[j]; }
    N[n] = -1; D[m + 1][n] = 1;
  }

  void Pivot(int r, int s) {
    double inv = 1.0 / D[r][s];
    for (int i = 0; i < m + 2; i++) if (i != r)
      for (int j = 0; j < n + 2; j++) if (j != s)
        D[i][j] -= D[r][j] * D[i][s] * inv;
    for (int j = 0; j < n + 2; j++) if (j != s) D[r][j] *= inv;
    for (int i = 0; i < m + 2; i++) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
  }

  bool Simplex(int phase) {
    int x = phase == 1 ? m + 1 : m;
    while (true) {
      int s = -1;
      for (int j = 0; j <= n; j++) {
        if (phase == 2 && N[j] == -1) continue;
        if (s == -1 || D[x][j] < D[x][s] || D[x][j] == D[x][s] && N[j] < N[s]) s = j;
      }
      if (D[x][s] > -EPS) return true;
      int r = -1;
      for (int i = 0; i < m; i++) {
        if (D[i][s] < EPS) continue;
        if (r == -1 || D[i][n + 1] / D[i][s] < D[r][n + 1] / D[r][s] ||
          (D[i][n + 1] / D[i][s]) == (D[r][n + 1] / D[r][s]) && B[i] < B[r]) r = i;
      }
      if (r == -1) return false;
      Pivot(r, s);
    }
  }

  DOUBLE Solve(VD &x) {
    int r = 0;
    for (int i = 1; i < m; i++) if (D[i][n + 1] < D[r][n + 1]) r = i;
    if (D[r][n + 1] < -EPS) {
      Pivot(r, n);
      if (!Simplex(1) || D[m + 1][n + 1] < -EPS) return -numeric_limits<DOUBLE>::infinity();
      for (int i = 0; i < m; i++) if (B[i] == -1) {
        int s = -1;
        for (int j = 0; j <= n; j++)
          if (s == -1 || D[i][j] < D[i][s] || D[i][j] == D[i][s] && N[j] < N[s]) s = j;
        Pivot(i, s);
      }
    }
    if (!Simplex(2)) return numeric_limits<DOUBLE>::infinity();
    x = VD(n);
    for (int i = 0; i < m; i++) if (B[i] < n) x[B[i]] = D[i][n + 1];
    return D[m][n + 1];
  }
};

int main() {

  const int m = 4;
  const int n = 3;
  DOUBLE _A[m][n] = {
    { 6, -1, 0 },
    { -1, -5, 0 },
    { 1, 5, 1 },
    { -1, -5, -1 }
```

```
    };
    DOUBLE _b[m] = { 10, -4, 5, -5 };
    DOUBLE _c[n] = { 1, -1, 0 };

    VVD A(m);
    VD b(_b, _b + m);
    VD c(_c, _c + n);
    for (int i = 0; i < m; i++) A[i] = VD(_A[i], _A[i] + n);

    LPSolver solver(A, b, c);
    VD x;
    DOUBLE value = solver.Solve(x);

    cerr << "VALUE: " << value << endl; // VALUE: 1.29032
    cerr << "SOLUTION:"; // SOLUTION: 1.74194 0.451613 1
    for (size_t i = 0; i < x.size(); i++) cerr << " " << x[i];
    cerr << endl;
    return 0;
}
```

3.5 Fast Fourier transform

```
auto FFT = [](vector<long double>a,vector<long double>b){
  auto DFT = [](vector<complex<long double>>&a, bool inv){
    int L=31-__builtin_clz(a.size()), n=1<<L;
    vector<complex<long double>> A(n);
    for(int k=0,r,i;k<n;A[r]=a[k++])
      for(i=r=0;i<L;(r<<=1)|=(k>>i++)&1);
    complex<long double> w,wm,t;
    for(int m=2,j,k;m<=n;m<<=1)
      for(w={0,2*acos(-1)/m},wm=exp(inv?-w:w),k=0;k<n;k+=m)
        for(j=0,w=1;j<m/2;++j,w*=wm)
          t=w*A[k+j+m/2],A[k+j+m/2]=A[k+j]-t,A[k+j]+=t;
    return A;
  };
  int n=4<<31-__builtin_clz(max(a.size(),b.size()));
  vector<complex<long double>> A(n), B(n), CC(n);
  for(int i=0;i<n;++i)
    A[i]=i<a.size()?a[i]:0,B[i]=i<b.size()?b[i]:0;
  vector<complex<long double>> AA=DFT(A,0), BB=DFT(B,0);
  for(int i=0;i<n;++i) CC[i]=AA[i]*BB[i];
  vector<long double> c;
  for(auto i:DFT(CC,1)) if(c.size()<a.size()+b.size()-1)
    c.push_back(i.real()/n+1e-5);
  return c;
};
```

3.6 BigInt library

```
struct bigint {
    const int base = 1000000000, base_digits = 9;
    vector<int> a;
    int sign;
    bigint() : sign(1) {}
    bigint(long long v) {
        *this = v;
    }
    bigint(const string &s) {
        read(s);
    }
    void operator=(const bigint &v) {
        sign = v.sign;
        a = v.a;
    }
    void operator=(long long v) {
        sign = 1;
        if (v < 0) sign = -1, v = -v;
        for (; v > 0; v = v / base)
            a.push_back(v % base);
    }
    bigint operator+(const bigint &v) const {
        if (sign == v.sign) {
            bigint res = v;

            for (int i = 0, carry = 0; i < (int) max(a.size(), v.a.size()) || carry; ++i) {
                if (i == (int) res.a.size())
                    res.a.push_back(0);
                res.a[i] += carry + (i < (int) a.size() ? a[i] : 0);
                carry = res.a[i] >= base;
                if (carry)
                    res.a[i] -= base;
            }
            return res;
        }
        return *this - (-v);
    }
    bigint operator-(const bigint &v) const {
        if (sign == v.sign) {
            if (abs() >= v.abs()) {
                bigint res = *this;
                for (int i = 0, carry = 0; i < (int) v.a.size() || carry; ++i) {
                    res.a[i] -= carry + (i < (int) v.a.size() ? v.a[i] : 0);
                    carry = res.a[i] < 0;
                    if (carry)
                        res.a[i] += base;
                }
                res.trim();
                return res;
            }
            return -(v - *this);
        }
        return *this + (-v);
    }
    void operator*=(int v) {
        if (v < 0)
            sign = -sign, v = -v;
        for (int i = 0, carry = 0; i < (int) a.size() || carry; ++i) {
            if (i == (int) a.size())
                a.push_back(0);
            long long cur = a[i] * (long long) v + carry;
```

```
            carry = (int) (cur / base);
            a[i] = (int) (cur % base);
            //asm("divl %%ecx" : "=a"(carry), "=d"(a[i])
                 : "A"(cur), "c"(base));
        }
        trim();
    }
    bigint operator*(int v) const {
        bigint res = *this;
        res *= v;
        return res;
    }
    friend pair<bigint, bigint> divmod(const bigint &a1,
         const bigint &b1) {
        int norm = a1.base / (b1.a.back() + 1);
        bigint a = a1.abs() * norm;
        bigint b = b1.abs() * norm;
        bigint q, r;
        q.a.resize(a.a.size());
        for (int i = a.a.size() - 1; i >= 0; i--) {
            r *= a1.base;
            r += a.a[i];
            int s1 = r.a.size() <= b.a.size() ? 0 : r.a[
                b.a.size()];
            int s2 = r.a.size() <= b.a.size() - 1 ? 0 :
                r.a[b.a.size() - 1];
            int d = ((long long) a1.base * s1 + s2) / b.
                a.back();
            r -= b * d;
            while (r < 0)
                r += b, --d;
            q.a[i] = d;
        }
        q.sign = a1.sign * b1.sign;
        r.sign = a1.sign;
        q.trim();
        r.trim();
        return make_pair(q, r / norm);
    }
    bigint operator/(const bigint &v) const {
        return divmod(*this, v).first;
    }
    bigint operator%(const bigint &v) const {
        return divmod(*this, v).second;
    }
    void operator/=(int v) {
        if (v < 0) sign = -sign, v = -v;
        for (int i = (int) a.size() - 1, rem = 0; i >=
            0; --i) {
            long long cur = a[i] + rem * (long long)
                base;
            a[i] = (int) (cur / v);
            rem = (int) (cur % v);
        }
        trim();
    }
    bigint operator/(int v) const {
        bigint res = *this;
        res /= v;
        return res;
    }
    int operator%(int v) const {
        if (v < 0)
            v = -v;
        int m = 0;
        for (int i = a.size() - 1; i >= 0; --i)
            m = (a[i] + m * (long long) base) % v;
        return m * sign;
    }
    void operator+=(const bigint &v) {
        *this = *this + v;
    }
    void operator-=(const bigint &v) {
        *this = *this - v;
    }
    void operator*=(const bigint &v) {
        *this = *this * v;
    }
    void operator/=(const bigint &v) {
        *this = *this / v;
    }
    bool operator<(const bigint &v) const {
        if (sign != v.sign)
            return sign < v.sign;
        if (a.size() != v.a.size())
            return a.size() * sign < v.a.size() * v.sign
                ;
        for (int i = a.size() - 1; i >= 0; i--)
            if (a[i] != v.a[i])
                return a[i] * sign < v.a[i] * sign;
        return false;
    }
    bool operator>(const bigint &v) const {
        return v < *this;
    }
    bool operator<=(const bigint &v) const {
        return !(v < *this);
    }
    bool operator>=(const bigint &v) const {
        return !(*this < v);
    }
    bool operator==(const bigint &v) const {
        return !(*this < v) && !(v < *this);
    }
    bool operator!=(const bigint &v) const {
        return *this < v || v < *this;
    }
    void trim() {
        while (!a.empty() && !a.back())
            a.pop_back();
        if (a.empty())
            sign = 1;
    }
    bool isZero() const {
        return a.empty() || (a.size() == 1 && !a[0]);
    }
    bigint operator-() const {
        bigint res = *this;
        res.sign = -sign;
        return res;
    }
    bigint abs() const {
```

```
    bigint res = *this;
    res.sign *= res.sign;
    return res;
}
long long longValue() const {
    long long res = 0;
    for (int i = a.size() - 1; i >= 0; i--)
        res = res * base + a[i];
    return res * sign;
}
friend bigint gcd(const bigint &a, const bigint &b)
   {
    return b.isZero() ? a : gcd(b, a % b);
}
friend bigint lcm(const bigint &a, const bigint &b)
   {
    return a / gcd(a, b) * b;
}
void read(const string &s) {
    sign = 1;
    a.clear();
    int pos = 0;
    while (pos < (int) s.size() && (s[pos] == '-' ||
          s[pos] == '+')) {
        if (s[pos] == '-') sign = -sign;
        ++pos;
    }
    for (int i = s.size() - 1; i >= pos; i -=
        base_digits) {
        int x = 0;
        for (int j = max(pos, i - base_digits + 1);
             j <= i; j++)
             x = x * 10 + s[j] - '0';
        a.push_back(x);
    }
    trim();
}
friend istream& operator>>(istream &stream, bigint &
   v) {
    string s;
    stream >> s;
    v.read(s);
    return stream;
}
friend ostream& operator<<(ostream &stream, const
   bigint &v) {
    if (v.sign == -1) stream << '-';
    stream << (v.a.empty() ? 0 : v.a.back());
    for (int i = (int) v.a.size() - 2; i >= 0; --i)
        stream << setw(v.base_digits) << setfill('0'
            ) << v.a[i];
    return stream;
}
static vector<int> convert_base(const vector<int> &a
   , int old_digits, int new_digits) {
    vector<long long> p(max(old_digits, new_digits)
        + 1);
    p[0] = 1;
    for (int i = 1; i < (int) p.size(); i++)
        p[i] = p[i - 1] * 10;
    vector<int> res;
    long long cur = 0;
    int cur_digits = 0;
    for (int i = 0; i < (int) a.size(); i++) {
        cur += a[i] * p[cur_digits];
        cur_digits += old_digits;
        while (cur_digits >= new_digits) {
            res.push_back(int(cur % p[new_digits]));
            cur /= p[new_digits];
            cur_digits -= new_digits;
        }
    }
    res.push_back((int) cur);
    while (!res.empty() && !res.back())
        res.pop_back();
    return res;
}
typedef vector<long long> vll;
static vll karatsubaMultiply(const vll &a, const vll
     &b) {
    int n = a.size();
    vll res(n + n);
    if (n <= 32) {
        for (int i = 0; i < n; i++)
            for (int j = 0; j < n; j++)
                res[i + j] += a[i] * b[j];
        return res;
    }
    int k = n >> 1;
    vll a1(a.begin(), a.begin() + k);
    vll a2(a.begin() + k, a.end());
    vll b1(b.begin(), b.begin() + k);
    vll b2(b.begin() + k, b.end());
    vll a1b1 = karatsubaMultiply(a1, b1);
    vll a2b2 = karatsubaMultiply(a2, b2);
    for (int i = 0; i < k; i++)
        a2[i] += a1[i];
    for (int i = 0; i < k; i++)
        b2[i] += b1[i];
    vll r = karatsubaMultiply(a2, b2);
    for (int i = 0; i < (int) a1b1.size(); i++)
        r[i] -= a1b1[i];
    for (int i = 0; i < (int) a2b2.size(); i++)
        r[i] -= a2b2[i];
    for (int i = 0; i < (int) r.size(); i++)
        res[i + k] += r[i];
    for (int i = 0; i < (int) a1b1.size(); i++)
        res[i] += a1b1[i];
    for (int i = 0; i < (int) a2b2.size(); i++)
        res[i + n] += a2b2[i];
    return res;
}
bigint operator*(const bigint &v) const {
    vector<int> a6 = convert_base(this->a,
        base_digits, 6);
    vector<int> b6 = convert_base(v.a, base_digits,
        6);
    vll a(a6.begin(), a6.end());
    vll b(b6.begin(), b6.end());
    while (a.size() < b.size())
        a.push_back(0);
    while (b.size() < a.size())
```

```
            b.push_back(0);
        while (a.size() & (a.size() - 1))
            a.push_back(0), b.push_back(0);
        vll c = karatsubaMultiply(a, b);
        bigint res;
        res.sign = sign * v.sign;
        for (int i = 0, carry = 0; i < (int) c.size(); i
            ++) {
            long long cur = c[i] + carry;
            res.a.push_back((int) (cur % 1000000));
            carry = (int) (cur / 1000000);
        }
        res.a = convert_base(res.a, 6, base_digits);
        res.trim();
        return res;
    }
};
```

4 Graph algorithms

4.1 Bellman-Ford shortest paths with negative edge weights

```
// Single source shortest paths with negative edge
    weights.
// Returns false if a negative weight cycle is detected.
// Running time: O(|V|^3)
//   INPUT:   start, w[i][j] = cost of edge from i to j
//   OUTPUT:  dist[i] = min weight path from start to i
//            dad[i] = prevector<int>ous node on the
    best path from the
//                     start node
vector<int> dad;
vector<double> dist;
bool BellmanFord(int start, vector<vector<double>> &w){
  int n = w.size();
  dad = vector<int>(n, -1);
  dist = vector<double>(n, 1000000000);
  dist[start] = 0;
  for (int k = 0; k < n; k++)
    for (int i = 0; i < n; i++)
      for (int j = 0; j < n; j++)
        if (dist[j] > dist[i] + w[i][j]){
          if (k == n-1) return false;
          else dist[j] = dist[i] + w[i][j], dad[j] = i;
        }
  return true;
}
int main(){}
```

4.2 Eulerian path

```
struct Edge;
typedef list<Edge>::iterator iter;

struct Edge
{
        int next_vertex;
        iter reverse_edge;

        Edge(int next_vertex)
                :next_vertex(next_vertex)
                { }
};
const int max_vertices = ;
int num_vertices;
list<Edge> adj[max_vertices];           // adjacency
    list

vector<int> path;

void find_path(int v)
{
        while(adj[v].size() > 0)
        {
                int vn = adj[v].front().next_vertex;
                adj[vn].erase(adj[v].front().
                    reverse_edge);
                adj[v].pop_front();
                find_path(vn);
        }
        path.push_back(v);
}

void add_edge(int a, int b)
{
        adj[a].push_front(Edge(b));
        iter ita = adj[a].begin();
        adj[b].push_front(Edge(a));
        iter itb = adj[b].begin();
        ita->reverse_edge = itb;
        itb->reverse_edge = ita;
}
```

4.3 Minimum spanning trees

```
// This function runs Prim's algorithm for constructing
    minimum
// weight spanning trees.
//
// Running time: O(|V|^2)
//
//   INPUT:   w[i][j] = cost of edge from i to j
//
//            NOTE: Make sure that w[i][j] is
    nonnegative and
//            symmetric.  Missing edges should be given
    -1
//            weight.
//
//   OUTPUT:  edges = list of pair<int,int> in minimum
    spanning tree
//            return total weight of tree

#include <iostream>
#include <queue>
#include <cmath>
#include <vector>
```

```
using namespace std;

typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

typedef vector<int> VI;
typedef vector<VI> VVI;
typedef pair<int,int> PII;
typedef vector<PII> VPII;

T Prim (const VVT &w, VPII &edges){
  int n = w.size();
  VI found (n);
  VI prev (n, -1);
  VT dist (n, 1000000000);
  int here = 0;
  dist[here] = 0;

  while (here != -1){
    found[here] = true;
    int best = -1;
    for (int k = 0; k < n; k++) if (!found[k]){
      if (w[here][k] != -1 && dist[k] > w[here][k]){
        dist[k] = w[here][k];
        prev[k] = here;
      }
      if (best == -1 || dist[k] < dist[best]) best = k;
    }
    here = best;
  }

  T tot_weight = 0;
  for (int i = 0; i < n; i++) if (prev[i] != -1){
    edges.push_back (make_pair (prev[i], i));
    tot_weight += w[prev[i]][i];
  }
  return tot_weight;
}

int main(){
  int ww[5][5] = {
    {0, 400, 400, 300, 600},
    {400, 0, 3, -1, 7},
    {400, 3, 0, 2, 0},
    {300, -1, 2, 0, 5},
    {600, 7, 0, 5, 0}
  };
  VVT w(5, VT(5));
  for (int i = 0; i < 5; i++)
    for (int j = 0; j < 5; j++)
      w[i][j] = ww[i][j];

  // expected: 305
  //           2 1
  //           3 2
  //           0 3
  //           2 4

  VPII edges;
  cout << Prim (w, edges) << endl;
  for (int i = 0; i < edges.size(); i++)
    cout << edges[i].first << " " << edges[i].second <<
        endl;
}
```

4.4 Centroid decomposition

```
set<int> v[100005];
map<int,int> mp[100005];
int n,up[100005][17],lvl[100005],par[100005],CNT,siz
    [100005],tin[100005],tout[100005];
void dfspre(int u, int dad=1, int depth = 0){
    static int clk = 0;
    tin[u]=clk++;
    up[u][0] = dad;
    lvl[u] = depth;
    for(int i=1;i<17;++i)
        up[u][i] = up[up[u][i-1]][i-1];
    for(int i:v[u]) if(i!=dad)
        dfspre(i,u,depth+1);
    tout[u]=clk++;
}
int dfs(int u, int dad){
    siz[u] = 1;
    for(int i:v[u]) if(i!=dad)
        siz[u] += dfs(i,u);
    return siz[u];
}
int centroid(int u, int dad){
    for(int i:v[u]) if(i!=dad && siz[i]>CNT)
        return centroid(i,u);
    return u;
}
void decompose(int u, int dad){
    CNT = dfs(u,dad)/2;
    int centre = centroid(u,dad);
    par[centre] = dad;
    for(int i:v[centre]) if(i!=dad){
        v[i].erase(centre);
        decompose(i,centre);
    }
    v[centre].clear();
}
int lca(int u, int v){
    if(lvl[u]>lvl[v]) swap(u,v);
    if(tin[u]<=tin[v] && tout[v]<=tout[u]) return u;
    for(int i=17;i--;)
        if(!(tin[up[u][i]]<=tin[v] && tout[v]<=tout[up[u
            ][i]]))
            u = up[u][i];
    return up[u][0];
}
void update(int u){
    for(int node = u;u;u = par[u])
        ++mp[u][lvl[node]+lvl[u] - 2*lvl[lca(u,node)]];
}
int get(int u){
    int ans = INT_MAX;
    for(int node = u; u; u = par[u])
        ans = min(ans,lvl[u]+lvl[node]-2*lvl[lca(u,node)
            ]+(*mp[u].begin()).first);
    return ans;
}
```

4.5 Heavy-Light decomposition

```cpp
#include <bits/stdc++.h>
using namespace std;
int a[100005],sz[100005],lvl[100005];
int seg_id[100005],pos_id[100005],parent[100005];
int CNT;
int e_to_v[100005];
vector<pair<int,int>> edges(100005);
vector<pair<int,int>> v[100005];
vector<int> chain[100005];
template <typename T>
class SegmentTree{
  vector<T> segtree,lazy;
  public:
  SegmentTree(int size){
    segtree.resize(4*size,0);
    lazy.resize(4*size,0);
  }
  void update(int u, int a, int b, int i, int j, T x){
    if(lazy[u]){
      segtree[u]+=(b-a+1)*lazy[u];
      if(a!=b)
        lazy[u*2]+=lazy[u],lazy[2*u+1]+=lazy[u];
      lazy[u]=0;
    }
    if(j<a || i>b || a>b) return;
    if(j>=b && i<=a){
      segtree[u]=x;
      if(a!=b) lazy[u*2]+=x,lazy[2*u+1]+=x;
      return;
    }
    update(u*2,a,(a+b)/2,i,j,x); update(u*2+1,(a+b)/2+1,
       b,i,j,x);
    segtree[u]=max(segtree[u*2],segtree[u*2+1]);
  }
  void update(int i, T x){
    update(1, 0, segtree.size()/4-1, i, i, x);
  }
  void update(int i, int j, T x){
    update(1, 0, segtree.size()/4-1, i, j, x);
  }
  T query(int u, int a, int b, int i, int j){
    if(j<a || i>b || a>b) return 0;
    if(lazy[u]){
      segtree[u]+=(b-a+1)*lazy[u];
      if(a!=b)
        lazy[u*2]+=lazy[u],lazy[2*u+1]+=lazy[u];
      lazy[u]=0;
    }
    if(j>=b && i<=a) return segtree[u];
    return max(query(u*2,a,(a+b)/2,i,j),query(u*2+1,1+(a
       +b)/2,b,i,j));
  }
  T query(int i, int j){
    return query(1,0,segtree.size()/4-1,i,j);
  }
};
int dfs(int u, int dad=1, int depth=1){
  lvl[u] = depth;
  sz[u] = 1;
  for(auto i:v[u]) if(i.first!=dad)
    sz[u] += dfs(i.first,u,depth+1);
  return sz[u];
}
void hld(int u, int dad = 1, int chain_no = 0, int
    chain_parent = 0){
  seg_id[u] = chain_no;
  pos_id[u] = chain[chain_no].size();
  parent[u] = chain_parent;
  chain[chain_no].push_back(u);
  int max_sz = 0, heavy_child = -1;
  for(auto i:v[u]) if(i.first!=dad){
    a[i.first] = i.second;
    if(max_sz < sz[i.first])
      max_sz = sz[i.first], heavy_child = i.first;
  }
  if(heavy_child!=-1)
    hld(heavy_child, u, chain_no, chain_parent);
  for(auto i:v[u]) if(i.first!=dad && i.first!=
      heavy_child)
    hld(i.first,u,++CNT, u);
}
int main(){
  ios_base::sync_with_stdio(0);
  cin.tie(0); cout.tie(0);
  int T, n, x, y;
  for(cin>>T;T-- && cin>>n;){
    CNT = 0;
    for(int i=0;i<100005;chain[i].clear(), v[i].clear(),
        i++);

    for(int i=1,c;i<n;++i){
      cin>>x>>y>>c;
      edges[i] = {x,y};
      v[x].push_back({y,c});
      v[y].push_back({x,c});
    }

    dfs(1);

    for(int i=1;i<n;++i){
      int u = edges[i].first, v = edges[i].second;
      e_to_v[i] = (lvl[u]<lvl[v]?v:u);
    }

    hld(1);

    vector<SegmentTree<int>> ST;
    for(int i=0;i<=CNT;++i){
      ST.push_back(SegmentTree<int>(chain[i].size()));
      for(auto u:chain[i])
        ST[i].update(pos_id[u],a[u]);
    }

    for(string type;cin>>type && type!="DONE";){
      cin>>x>>y;
      if(type=="QUERY"){
        int res = 0;
        while(x!=y){
          if(seg_id[x]>seg_id[y]) swap(x,y);
          else if(seg_id[x] == seg_id[y]){
```

```
            if(pos_id[x]>pos_id[y]) swap(x,y);
            res = max(res,ST[seg_id[y]].query(pos_id[x
                ]+1,pos_id[y]));
            break;
          }
          res = max(res, ST[seg_id[y]].query(0,pos_id[y
              ]));
          y = parent[y];
        }
        cout<<res<<'\n';
      }
      else if(type == "CHANGE"){
        int u = e_to_v[x];
        ST[seg_id[u]].update(pos_id[u],y);
      }
    }
  }
}
```

5 Data structures

5.1 Suffix array

```
// Suffix array construction in O(L log^2 L) time.
    Routine for
// computing the length of the longest common prefix of
    any two
// suffixes in O(log L) time.
//
// INPUT:   string s
//
// OUTPUT:  array suffix[] such that suffix[i] = index (
    from 0 to L-1)
//          of substring s[i...L-1] in the list of
    sorted suffixes.
//          That is, if we take the inverse of the
    permutation suffix[],
//          we get the actual suffix array.

#include <vector>
#include <iostream>
#include <string>

using namespace std;

struct SuffixArray {
  const int L;
  string s;
  vector<vector<int> > P;
  vector<pair<pair<int,int>,int> > M;

  SuffixArray(const string &s) : L(s.length()), s(s), P
      (1, vector<int>(L, 0)), M(L) {
    for (int i = 0; i < L; i++) P[0][i] = int(s[i]);
    for (int skip = 1, level = 1; skip < L; skip *= 2,
        level++) {
      P.push_back(vector<int>(L, 0));
      for (int i = 0; i < L; i++)
        M[i] = make_pair(make_pair(P[level-1][i], i +
            skip < L ? P[level-1][i + skip] : -1000), i);
      sort(M.begin(), M.end());
      for (int i = 0; i < L; i++)
        P[level][M[i].second] = (i > 0 && M[i].first ==
            M[i-1].first) ? P[level][M[i-1].second] : i;
    }
  }

  vector<int> GetSuffixArray() { return P.back(); }

  // returns the length of the longest common prefix of
      s[i...L-1] and s[j...L-1]
  int LongestCommonPrefix(int i, int j) {
    int len = 0;
    if (i == j) return L - i;
    for (int k = P.size() - 1; k >= 0 && i < L && j < L;
        k--) {
      if (P[k][i] == P[k][j]) {
        i += 1 << k;
        j += 1 << k;
        len += 1 << k;
      }
    }
    return len;
  }
};

// BEGIN CUT
// The following code solves UVA problem 11512: GATTACA.
#define TESTING
#ifdef TESTING
int main() {
  int T;
  cin >> T;
  for (int caseno = 0; caseno < T; caseno++) {
    string s;
    cin >> s;
    SuffixArray array(s);
    vector<int> v = array.GetSuffixArray();
    int bestlen = -1, bestpos = -1, bestcount = 0;
    for (int i = 0; i < s.length(); i++) {
      int len = 0, count = 0;
      for (int j = i+1; j < s.length(); j++) {
        int l = array.LongestCommonPrefix(i, j);
        if (l >= len) {
          if (l > len) count = 2; else count++;
          len = l;
        }
      }
      if (len > bestlen || len == bestlen && s.substr(
          bestpos, bestlen) > s.substr(i, len)) {
        bestlen = len;
        bestcount = count;
        bestpos = i;
      }
    }
    if (bestlen == 0) {
      cout << "No repetitions found!" << endl;
    } else {
      cout << s.substr(bestpos, bestlen) << " " <<
          bestcount << endl;
    }
  }
}
```

```
#else
// END CUT
int main() {
  SuffixArray suffix("bobocel");
  vector<int> v = suffix.GetSuffixArray();
  // Expected output: 0 5 1 6 2 3 4
  //                  2
  for (int i = 0; i < v.size(); i++) cout << v[i] << " ";
  cout << endl;
  cout << suffix.LongestCommonPrefix(0, 2) << endl;
}
// BEGIN CUT
#endif
// END CUT
```

5.2 KD-tree

```
// A straightforward, but probably sub-optimal KD-tree implmentation
// that's probably good enough for most things (current it's a
// 2D-tree)
//
//  - constructs from n points in O(n lg^2 n) time
//  - handles nearest-neighbor query in O(lg n) if points are well
//    distributed
//  - worst case for nearest-neighbor may be linear in pathological
//    case
//
// Sonny Chan, Stanford University, April 2009

#include <iostream>
#include <vector>
#include <limits>
#include <cstdlib>
using namespace std;

// number type for coordinates, and its maximum value
typedef long long ntype;
const ntype sentry = numeric_limits<ntype>::max();

// point structure for 2D-tree, can be extended to 3D
struct point {
    ntype x, y;
    point(ntype xx = 0, ntype yy = 0) : x(xx), y(yy) {}
};

bool operator==(const point &a, const point &b){
    return a.x == b.x && a.y == b.y;
}

// sorts points on x-coordinate
bool on_x(const point &a, const point &b){
    return a.x < b.x;
}

// sorts points on y-coordinate
bool on_y(const point &a, const point &b){
    return a.y < b.y;
}

// squared distance between points
ntype pdist2(const point &a, const point &b){
    ntype dx = a.x-b.x, dy = a.y-b.y;
    return dx*dx + dy*dy;
}

// bounding box for a set of points
struct bbox{
    ntype x0, x1, y0, y1;

    bbox() : x0(sentry), x1(-sentry), y0(sentry), y1(-sentry) {}

    // computes bounding box from a bunch of points
    void compute(const vector<point> &v) {
        for (int i = 0; i < v.size(); ++i) {
            x0 = min(x0, v[i].x);   x1 = max(x1, v[i].x);
            y0 = min(y0, v[i].y);   y1 = max(y1, v[i].y);
        }
    }

    // squared distance between a point and this bbox, 0 if inside
    ntype distance(const point &p) {
        if (p.x < x0) {
            if (p.y < y0)       return pdist2(point(x0, y0), p);
            else if (p.y > y1)  return pdist2(point(x0, y1), p);
            else                return pdist2(point(x0, p.y), p);
        }
        else if (p.x > x1) {
            if (p.y < y0)       return pdist2(point(x1, y0), p);
            else if (p.y > y1)  return pdist2(point(x1, y1), p);
            else                return pdist2(point(x1, p.y), p);
        }
        else {
            if (p.y < y0)       return pdist2(point(p.x, y0), p);
            else if (p.y > y1)  return pdist2(point(p.x, y1), p);
            else                return 0;
        }
    }
};

// stores a single node of the kd-tree, either internal or leaf
struct kdnode {
    bool leaf;      // true if this is a leaf node (has one point)
    point pt;       // the single point of this is a leaf
    bbox bound;     // bounding box for set of points in children

    kdnode *first, *second; // two children of this kd-
```

```
        node
    kdnode() : leaf(false), first(0), second(0) {}
    ~kdnode() { if (first) delete first; if (second)
        delete second; }

    // intersect a point with this node (returns squared
        distance)
    ntype intersect(const point &p) {
        return bound.distance(p);
    }

    // recursively builds a kd-tree from a given cloud
        of points
    void construct(vector<point> &vp){
        // compute bounding box for points at this node
        bound.compute(vp);

        // if we're down to one point, then we're a leaf
            node
        if (vp.size() == 1) {
            leaf = true;
            pt = vp[0];
        }
        else {
            // split on x if the bbox is wider than high
                (not best heuristic...)
            if (bound.x1-bound.x0 >= bound.y1-bound.y0)
                sort(vp.begin(), vp.end(), on_x);
            // otherwise split on y-coordinate
            else
                sort(vp.begin(), vp.end(), on_y);

            // divide by taking half the array for each
                child
            // (not best performance if many duplicates
                in the middle)
            int half = vp.size()/2;
            vector<point> vl(vp.begin(), vp.begin()+half
                );
            vector<point> vr(vp.begin()+half, vp.end());
            first = new kdnode();   first->construct(vl)
                ;
            second = new kdnode();  second->construct(vr
                );
        }
    }
};

// simple kd-tree class to hold the tree and handle
    queries
struct kdtree{
    kdnode *root;

    // constructs a kd-tree from a points (copied here,
        as it sorts them)
    kdtree(const vector<point> &vp) {
        vector<point> v(vp.begin(), vp.end());
        root = new kdnode();
        root->construct(v);
    }
    ~kdtree() { delete root; }

    // recursive search method returns squared distance
        to nearest point
    ntype search(kdnode *node, const point &p)
    {
        if (node->leaf) {
            // commented special case tells a point not
                to find itself
//            if (p == node->pt) return sentry;
//            else
                return pdist2(p, node->pt);
        }

        ntype bfirst = node->first->intersect(p);
        ntype bsecond = node->second->intersect(p);

        // choose the side with the closest bounding box
            to search first
        // (note that the other side is also searched if
            needed)
        if (bfirst < bsecond) {
            ntype best = search(node->first, p);
            if (bsecond < best)
                best = min(best, search(node->second, p)
                    );
            return best;
        }
        else {
            ntype best = search(node->second, p);
            if (bfirst < best)
                best = min(best, search(node->first, p))
                    ;
            return best;
        }
    }

    // squared distance to the nearest
    ntype nearest(const point &p) {
        return search(root, p);
    }
};

// some basic test code here

int main(){
    // generate some random points for a kd-tree
    vector<point> vp;
    for (int i = 0; i < 100000; ++i) {
        vp.push_back(point(rand()%100000, rand()%100000)
            );
    }
    kdtree tree(vp);

    // query some points
    for (int i = 0; i < 10; ++i) {
        point q(rand()%100000, rand()%100000);
        cout << "Closest squared distance to (" << q.x
            << ", " << q.y << ")"
              << " is " << tree.nearest(q) << endl;
    }
}
```

5.3 Splay tree

```
#include <cstdio>
#include <algorithm>
```

```cpp
using namespace std;

const int N_MAX = 130010;
const int oo = 0x3f3f3f3f;
struct Node
{
  Node *ch[2], *pre;
  int val, size;
  bool isTurned;
} nodePool[N_MAX], *null, *root;

Node *allocNode(int val)
{
  static int freePos = 0;
  Node *x = &nodePool[freePos ++];
  x->val = val, x->isTurned = false;
  x->ch[0] = x->ch[1] = x->pre = null;
  x->size = 1;
  return x;
}

inline void update(Node *x)
{
  x->size = x->ch[0]->size + x->ch[1]->size + 1;
}

inline void makeTurned(Node *x)
{
  if(x == null)
    return;
  swap(x->ch[0], x->ch[1]);
  x->isTurned ^= 1;
}

inline void pushDown(Node *x)
{
  if(x->isTurned)
  {
    makeTurned(x->ch[0]);
    makeTurned(x->ch[1]);
    x->isTurned ^= 1;
  }
}

inline void rotate(Node *x, int c)
{
  Node *y = x->pre;
  x->pre = y->pre;
  if(y->pre != null)
    y->pre->ch[y == y->pre->ch[1]] = x;
  y->ch[!c] = x->ch[c];
  if(x->ch[c] != null)
    x->ch[c]->pre = y;
  x->ch[c] = y, y->pre = x;
  update(y);
  if(y == root)
    root = x;
}

void splay(Node *x, Node *p)
{
  while(x->pre != p)
  {
    if(x->pre->pre == p)
      rotate(x, x == x->pre->ch[0]);
    else
    {
      Node *y = x->pre, *z = y->pre;
      if(y == z->ch[0])
      {
        if(x == y->ch[0])
          rotate(y, 1), rotate(x, 1);
        else
          rotate(x, 0), rotate(x, 1);
      }
      else
      {
        if(x == y->ch[1])
          rotate(y, 0), rotate(x, 0);
        else
          rotate(x, 1), rotate(x, 0);
      }
    }
  }
  update(x);
}

void select(int k, Node *fa)
{
  Node *now = root;
  while(1)
  {
    pushDown(now);
    int tmp = now->ch[0]->size + 1;
    if(tmp == k)
      break;
    else if(tmp < k)
      now = now->ch[1], k -= tmp;
    else
      now = now->ch[0];
  }
  splay(now, fa);
}

Node *makeTree(Node *p, int l, int r)
{
  if(l > r)
    return null;
  int mid = (l + r) / 2;
  Node *x = allocNode(mid);
  x->pre = p;
  x->ch[0] = makeTree(x, l, mid - 1);
  x->ch[1] = makeTree(x, mid + 1, r);
  update(x);
  return x;
}

int main()
{
  int n, m;
  null = allocNode(0);
  null->size = 0;
  root = allocNode(0);
  root->ch[1] = allocNode(oo);
  root->ch[1]->pre = root;
  update(root);

  scanf("%d%d", &n, &m);
```

```
    root->ch[1]->ch[0] = makeTree(root->ch[1], 1, n);
    splay(root->ch[1]->ch[0], null);

    while(m --)
    {
      int a, b;
      scanf("%d%d", &a, &b);
      a ++, b ++;
      select(a - 1, null);
      select(b + 1, root);
      makeTurned(root->ch[1]->ch[0]);
    }

    for(int i = 1; i <= n; i ++)
    {
      select(i + 1, null);
      printf("%d ", root->val);
    }
}
```

6 Miscellaneous

6.1 Miller-Rabin Primality Test

```
//   Error rate: 2^(-TRIAL)
//   Almost constant time. srand is needed

int64_t ModMul(int64_t a, int64_t b, int64_t m){
        int64_t ret=0, c=a;
        for(;b;b>>=1, c=(c+c)%m)
                if(b&1) ret=(ret+c)%m;
        return ret;
}
int64_t ModExp(int64_t a, int64_t n, int64_t m){
        return n?ModMul(ModExp(ModMul(a,a,m),n/2,m),(n
            %2?a:1),m):1;
}
bool Witness(int64_t a, int64_t n){
        int64_t u=n-1;
        int t=0;
        while(!(u&1)){u>>=1; t++;}
        int64_t x0=ModExp(a, u, n), x1;
        for(int i=1;i<=t;i++) {
                x1=ModMul(x0, x0, n);
                if(x1==1&&x0!=1&&x0!=n-1) return true;
                x0=x1;
        }
        if(x0!=1) return true;
        return false;
}

bool IsPrimeFast(int64_t n, int TRIAL=15){
  if(n<=2) return (n==2);
  static random_device rd;
  static mt19937_64 g(rd());
  while(TRIAL--)
    if(Witness(g()/2%(n-2)+1, n))
        return false;
  return true;
}
```

6.2 Pollard-Rho factorization

```
typedef long long unsigned int llui;
typedef long long int lli;
typedef long double float64;

llui mul_mod(llui a, llui b, llui m){
   llui y = (llui)((float64)a*(float64)b/m+(float64)1/2)
       ;
   y = y * m;
   llui x = a * b;
   llui r = x - y;
   if ( (lli)r < 0 ){
      r = r + m; y = y - 1;
   }
   return r;
}

llui C,a,b;
llui gcd(){
   llui c;
   if(a>b){
      c = a; a = b; b = c;
   }
   while(1){
      if(a == 1LL) return 1LL;
      if(a == 0 || a == b) return b;
      c = a; a = b%a;
      b = c;
   }
}

llui f(llui a, llui b){
   llui tmp;
   tmp = mul_mod(a,a,b);
   tmp+=C; tmp%=b;
   return tmp;
}

llui pollard(llui n){
   if(!(n&1)) return 2;
   C=0;
   llui iteracoes = 0;
   while(iteracoes <= 1000){
      llui x,y,d;
      x = y = 2; d = 1;
      while(d == 1){
         x = f(x,n);
         y = f(f(y,n),n);
         llui m = (x>y)?(x-y):(y-x);
         a = m; b = n; d = gcd();
      }
      if(d != n)
         return d;
      iteracoes++; C = rand();
   }
   return 1;
}

llui pot(llui a, llui b, llui c){
   if(b == 0) return 1;
   if(b == 1) return a%c;
   llui resp = pot(a,b>>1,c);
```

```
    resp = mul_mod(resp,resp,c);
    if(b&1)
        resp = mul_mod(resp,a,c);
    return resp;
}
// Rabin-Miller primality testing algorithm
bool isPrime(llui n){
    llui d = n-1;
    llui s = 0;
    if(n <=3 || n == 5) return true;
    if(!(n&1)) return false;
    while(!(d&1)){ s++; d>>=1; }
    for(llui i = 0;i<32;i++){
        llui a = rand();
        a <<=32;
        a+=rand();
        a%=(n-3); a+=2;
        llui x = pot(a,d,n);
        if(x == 1 || x == n-1) continue;
        for(llui j = 1;j<= s-1;j++){
            x = mul_mod(x,x,n);
            if(x == 1) return false;
            if(x == n-1)break;
        }
        if(x != n-1) return false;
    }
    return true;
}
map<llui,int> factors;
// Precondition: factors is an empty map, n is a
    positive integer
// Postcondition: factors[p] is the exponent of p in
    prime factorization of n
void fact(llui n){
    if(!isPrime(n)){
        llui fac = pollard(n);
        fact(n/fac); fact(fac);
    }else{
        map<llui,int>::iterator it;
        it = factors.find(n);
        if(it != factors.end()){
            (*it).second++;
        }else{
            factors[n] = 1;
        }
    }
}
```

6.3 Manachers algorithm

```
// Maximal palindrome lengths centered around each
// position in a string (including positions between
    characters) and returns
// them in left-to-right order of centres. Linear time.
// Ex: "opposes" -> [0, 1, 0, 1, 4, 1, 0, 1, 0, 1, 0, 3,
    0, 1, 0]
vector<int> fastLongestPalindromes(string str) {
    int i=0,j,d,s,e,lLen,palLen=0;
    vector<int> res;
    while (i < str.length()) {
        if (i > palLen && str[i-palLen-1] == str[i]) {
            palLen += 2; i++; continue;
        }
        res.push_back(palLen);
        s = res.size()-2;
        e = s-palLen;
        bool b = true;
        for (j=s; j>e; j--) {
            d = j-e-1;
            if (res[j] == d) { palLen = d; b = false;
                break; }
            res.push_back(min(d, res[j]));
        }
        if (b) { palLen = 1; i++; }
    }
    res.push_back(palLen);
    lLen = res.size();
    s = lLen-2;
    e = s-(2*str.length()+1-lLen);
    for (i=s; i>e; i--) { d = i-e-1; res.push_back(min(d
        , res[i])); }
    return res;
}
```

6.4 Convex Hull Trick

```
struct Line {
        long long m, b;
        mutable function<const Line*()> succ;
        bool operator<(const Line& rhs) const{
                if (rhs.b != -(1ll<<62)) return m > rhs.
                    m; // < for max
                const Line* s = succ();
                if (!s) return 0;
                return b-s->b > (s->m -m)*rhs.m; // <
                    for max
        }
};
struct HullDynamic : public multiset<Line> {
        bool bad(iterator y) {
                auto z = next(y);
                if(y==begin()){
                        if(z==end())return 0;
                        return y->m == z->m && y->b >= z
                            ->b; // <= for max
                }
                auto x = prev(y);
                if (z == end()) return y->m == x->m && y
                    ->b >= x->b;  // <= for max
                return (x->b - y->b)*1.0*(z->m - y->m)
                    >= (y->b - z->b)*1.0*(y->m - x->m);
        }
        void insert_line(long long m, long long b) {
                auto y = insert({ m, b });
                y->succ = [=] { return next(y) == end()
                    ? 0 : &*next(y); };
                if (bad(y)) { erase(y); return; }
                while (next(y) != end() && bad(next(y)))
                     erase(next(y));
```

```
            while (y != begin() && bad(prev(y)))
                erase(prev(y));
        }
        long long eval(long long x) {
            auto l = *lower_bound((Line){x,-(1ll
                <<62)});
            return l.m * x + l.b;
        }
};
```

6.5 Dynamic Programming(DnC)

```
long long dp[21][100005];
void cost(int x, int y);
void computeDP(int idx,int jleft,int jright,int kleft,
    int kright){
        if(jleft>jright) return;
        int jmid=(jleft+jright)/2;
        int bestk=jmid;
        for(int k=kleft;k<=min(kright,jmid);++k){
                cost(k,jmid);
                if(dp[idx-1][k-1]+tot<dp[idx][jmid])
                        dp[idx][jmid]=dp[idx-1][k-1]+tot
                            ,bestk=k;
        }
        computeDP(idx,jleft,jmid-1,kleft,bestk);
        computeDP(idx,jmid+1,jright,bestk,kright);
}
int main(){
        for(int i=0;i<=k;++i)
                for(int j=0;j<=n;dp[i][j++]=1e17);
        dp[0][0]=0;
        for(int i=1;i<=k;++i)
                computeDP(i,1,n,1,n);
        cout<<dp[k][n];
}
```

6.6 Longest increasing subsequence

```
// Given a list of numbers of length n, this routine
    extracts a
// longest increasing subsequence.
//
// Running time: O(n log n)
//
//   INPUT: a vector of integers
//   OUTPUT: a vector containing the longest increasing
    subsequence

typedef vector<int> VI;
typedef pair<int,int> PII;
typedef vector<PII> VPII;

#define STRICTLY_INCREASNG

VI LongestIncreasingSubsequence(VI v) {
  VPII best;
  VI dad(v.size(), -1);

  for (int i = 0; i < v.size(); i++) {
#ifdef STRICTLY_INCREASNG
    PII item = make_pair(v[i], 0);
    VPII::iterator it = lower_bound(best.begin(), best.
        end(), item);
    item.second = i;
#else
    PII item = make_pair(v[i], i);
    VPII::iterator it = upper_bound(best.begin(), best.
        end(), item);
#endif
    if (it == best.end()) {
      dad[i] = (best.size() == 0 ? -1 : best.back().
          second);
      best.push_back(item);
    } else {
      dad[i] = it == best.begin() ? -1 : prev(it)->
          second;
      *it = item;
    }
  }

  VI ret;
  for (int i = best.back().second; i >= 0; i = dad[i])
    ret.push_back(v[i]);
  reverse(ret.begin(), ret.end());
  return ret;
}
```

6.7 Dates

```
// Months are expressed as integers from 1 to 12, Days
    are expressed
// as integers from 1 to 31, and Years are expressed as
    4-digit
// integers.
string dayOfWeek[] = {"Mon", "Tue", "Wed", "Thu", "Fri",
     "Sat", "Sun"};

// converts Gregorian date to integer (Julian day number
    )
int dateToInt (int m, int d, int y){
  return
    1461 * (y + 4800 + (m - 14) / 12) / 4 +
    367 * (m - 2 - (m - 14) / 12 * 12) / 12 -
    3 * ((y + 4900 + (m - 14) / 12) / 100) / 4 +
    d - 32075;
}

// converts integer (Julian day number) to Gregorian
    date: month/day/year
void intToDate (int jd, int &m, int &d, int &y){
  int x, n, i, j;
  x = jd + 68569;
  n = 4 * x / 146097;
  x -= (146097 * n + 3) / 4;
  i = (4000 * (x + 1)) / 1461001;
  x -= 1461 * i / 4 - 31;
  j = 80 * x / 2447;
  d = x - 2447 * j / 80;
  x = j / 11;
  m = j + 2 - 12 * x;
  y = 100 * (n - 49) + i + x;
```

```
}

// converts integer (Julian day number) to day of week
string intToDay (int jd){
  return dayOfWeek[jd % 7];
}
```

6.8 Knuth-Morris-Pratt

```
typedef vector<int> VI;

void buildPi(string& p, VI& pi){
  pi = VI(p.length());
  int k = -2;
  for(int i = 0; i < p.length(); i++) {
    while(k >= -1 && p[k+1] != p[i])
      k = (k == -1) ? -2 : pi[k];
    pi[i] = ++k;
  }
}

int KMP(string& t, string& p){
  VI pi;
  buildPi(p, pi);
  int k = -1;
  for(int i = 0; i < t.length(); i++) {
    while(k >= -1 && p[k+1] != t[i])
      k = (k == -1) ? -2 : pi[k];
    k++;
    if(k == p.length() - 1) {
      // p matches t[i-m+1, ..., i]
      cout << "matched at index " << i-k << ": ";
      cout << t.substr(i-k, p.length()) << endl;
      k = (k == -1) ? -2 : pi[k];
    }
  }
  return 0;
}

int main(){
  string a = "AABAACAADAABAABA", b = "AABA";
  KMP(a, b); // expected matches at: 0, 9, 12
}
```

6.9 2-SAT

```
struct TwoSat {
  int n;
  vector<vector<int> > adj, radj, scc;
  vector<int> sid, vis, val;
  stack<int> stk;
  int scnt;
  // n: number of variables, including negations
  TwoSat(int n): n(n), adj(n), radj(n), sid(n), vis(n),
      val(n, -1) {}
  // adds an implication
  void impl(int x, int y) { adj[x].push_back(y); radj[y
      ].push_back(x); }
  // adds a disjunction
  void vee(int x, int y) { impl(x^1, y); impl(y^1, x); }
  // forces variables to be equal
  void eq(int x, int y) { impl(x, y); impl(y, x); impl(x
      ^1, y^1); impl(y^1, x^1); }
  // forces variable to be true
  void tru(int x) { impl(x^1, x); }

  void dfs1(int x) {
    if (vis[x]++) return;
    for (int i = 0; i < adj[x].size(); i++)
      dfs1(adj[x][i]);
    stk.push(x);
  }
  void dfs2(int x) {
    if (!vis[x]) return; vis[x] = 0;
    sid[x] = scnt; scc.back().push_back(x);
    for (int i = 0; i < radj[x].size(); i++)
      dfs2(radj[x][i]);
  }

  // returns true if satisfiable, false otherwise
  // on completion, val[x] is the assigned value of
      variable x
  // note, val[x] = 0 implies val[x^1] = 1
  bool two_sat() {
    scnt = 0;
    for (int i = 0; i < n; dfs1(i++));
    while (!stk.empty()) {
      int v = stk.top(); stk.pop();
      if (vis[v]) {
        scc.push_back(vector<int>());
        dfs2(v);
        scnt++;
      }
    }
    for (int i = 0; i < n; i += 2)
      if (sid[i] == sid[i+1]) return false;
    vector<int> must(scnt);
    for (int i = 0; i < scnt; i++)
      for (int j = 0; j < scc[i].size(); j++){
        val[scc[i][j]] = must[i];
        must[sid[scc[i][j]^1]] = !must[i];
      }
    return true;
  }
};
```