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Assignment-2

(a) Ans: To prove: $-\sum_{w \in \text{Vocab}} y_w \log(\hat{y}_w) = -\log(\hat{y}_0)$

$y \rightarrow$ one-hot vector with 1 at true outside word
-0 and 0 at other word's places.

$$\therefore y = [0 \dots 1 \dots 0] \quad \hat{y} = [\dots \hat{y}_0 \dots]$$

\downarrow 0-word's position \downarrow Prediction for 0-word

$$\therefore -\sum_{w \in \text{Vocab}} y_w \log(\hat{y}_w) = -\left(0 \log(\hat{y}_0) + 0 \log(\hat{y}_1) + \dots + 1 \log(\hat{y}_0) + \dots\right)$$

$$= -\log(\hat{y}_0)$$

hence proved

(b)

Ans:

$$J_{\text{naive-softmax}}(v_0, v) = -\log P(0=0 | c=c)$$

$$= -\log \left(\frac{\exp(u_0^T v_c)}{\sum_{w \in \text{Vocab}} \exp(u_w^T v_c)} \right)$$

To find: $\frac{\partial J}{\partial v_c}$

Ans: We know that $-\log \left(\frac{\exp(u_0^T v_c)}{\sum_{w \in \text{Vocab}} \exp(u_w^T v_c)} \right)$

$$= -u_0^T v_c + \log \left(\sum_{w \in \text{Vocab}} \exp(u_w^T v_c) \right)$$

② We know that, $P(O=0|C=c) = \frac{\exp(u_0^T v_c)}{\sum_{w \in V} \exp(u_w^T v_c)}$

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$$\frac{\partial J}{\partial v_c} = -u_0 + \frac{\sum_w \exp(u_w^T v_c) \cdot u_w}{\sum_w \exp(u_w^T v_c)}$$

$$= -u_0 + \sum_{w \in V} \underbrace{\hat{y}_w}_{(x)} \cdot \underbrace{u_w}_{d \times 1} \quad [v \rightarrow d \times 1]$$

$$= -u_0 + \hat{y} \cdot v$$

$$\boxed{= -y \cdot v + \hat{y} \cdot v} \quad \underline{\text{Ans}} \quad \left(y = 0 \dots 0 \dots 1 \right. \\ \left. \begin{array}{c} \downarrow \\ \text{for true} \\ \text{label } 0 \end{array} \right)$$

$\therefore y \cdot v = u_0$

(c) Case I: $w = 0$,

$$\therefore J = -u_0^T v_c + \log\left(\sum_{w \in V} \exp(u_w^T v_c)\right)$$

$$\therefore \frac{\partial J}{\partial u_0} = -v_c + \frac{1}{\sum_{w \in V} \exp(u_w^T v_c)} \cdot v_c \cdot \exp(u_0^T v_c)$$

$$= -v_c + \hat{y}_0 \cdot v_c$$

$$= v_c (\hat{y}_0 - y)$$

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Case II: $w \neq 0$, let $w = k$

$$\therefore \frac{\partial J}{\partial u_k} = 0 + \frac{1}{\sum_{w \in V} \exp(u_w^T v_c)} \cdot \exp(u_k^T v_c) \cdot v_c$$

$$= \boxed{\hat{y}_k \cdot v_c} \quad \underline{\underline{\text{Ans}}}$$

\Rightarrow

$$(d) \quad \sigma(\alpha) = k = \frac{1}{1+e^{-\alpha}} = (1+e^{-\alpha})^{-1}$$

$$\therefore \frac{dk}{d\alpha} = -(1+e^{-\alpha})^{-2} \times (0 + e^{-\alpha} \times (-1))$$

$$= \frac{dk}{d\alpha} = \frac{e^{-\alpha}}{(1+e^{-\alpha})^2} = k^2 \cdot e^{-\alpha}$$

$$k = \frac{1}{1+e^{-\alpha}} \Rightarrow e^{-\alpha} = \left(\frac{1-k}{k} \right)$$

$$\therefore \frac{dk}{d\alpha} = k^2 \cdot \left(\frac{1-k}{k} \right)$$

$$\therefore \frac{d(\sigma(\alpha))}{d\alpha} = \sigma(\alpha) (1 - \sigma(\alpha)) \quad \underline{\underline{\text{Ans}}}$$

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$$(2) \quad J = -\log(\sigma(u_0^T v_c)) - \sum_{k=1}^K \log(\sigma(-u_k^T v_c))$$

$$\therefore \text{For any } \alpha, \frac{\partial J}{\partial \alpha} = -\frac{1}{\sigma(u_0^T v_c)} \cdot \cancel{\sigma(u_0^T v_c)} \cdot (1 - \sigma(u_0^T v_c)) \cdot \frac{\partial (u_0^T v_c)}{\partial \alpha} \\ + \sum_{k=1}^K \frac{1}{\sigma(-u_k^T v_c)} \cdot \cancel{\sigma(-u_k^T v_c)} \cdot (1 - \sigma(-u_k^T v_c)) \cdot \frac{\partial (-u_k^T v_c)}{\partial \alpha}$$

$$= \frac{\partial J}{\partial \alpha} = -\frac{(1 - \sigma(u_0^T v_c))}{\sigma(u_0^T v_c)} (u_0^T v_c) + \sum_{k=1}^K \frac{(1 - \sigma(-u_k^T v_c))}{\sigma(-u_k^T v_c)} (u_k^T v_c)$$

$$\therefore \quad \textcircled{1} \quad \frac{\partial J}{\partial v_c} = -(1 - \sigma(u_0^T v_c)) \cdot u_0 + \sum_{k=1}^K (1 - \sigma(-u_k^T v_c)) \cdot u_k$$

$$\textcircled{2} \quad \frac{\partial J}{\partial u_0} = -(1 - \sigma(u_0^T v_c)) \cdot v_c$$

$$\textcircled{3} \quad \frac{\partial J}{\partial u_k} = (1 - \sigma(-u_k^T v_c)) \cdot v_c$$

Ans

This loss is more efficient because we got rid of the Normalization term which made the naive-softmax computationally expensive.

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(f) Given:
$$T_{sg} = \sum_{\substack{-m \leq j \leq m \\ j \neq 0}} T(V_c, w_{+j}, U)$$

Q. (i)
$$\frac{\partial T_{sg}}{\partial U} = \sum_{\substack{-m \leq j \leq m \\ j \neq 0}} \frac{\partial T}{\partial U}$$

(ii)
$$\frac{\partial T_{sg}}{\partial V_c} = \sum \frac{\partial T}{\partial V_c}$$

(iii)
$$\frac{\partial T_{sg}}{\partial w} = 0$$