

Assignment 1.3

- (a) After n operations, the maximum size of DLL can be $O(n)$. Now, the worst case time complexities of these functions can be :-
- 1) Insert :- $O(1)$. Since only 4 operations are done.
 - 2) getfirst :- $O(n)$. Since we iterate back till the head sentinel node from current node.
 - 3) getNext :- $O(1)$. Just returns next or null if next is tail sentinel.
 - 4) Delete :- $O(n)$. calls the getfirst function which itself has $O(n)$ complexity.
After this iterates in DLL, if last element is the one needed then complexity with n operations. Hence complexity is $O(n)$.
 - 5) Find :- $O(n)$. getfirst of $O(n)$ is called. Also whole DLL is being searched & thus n operations in worst case. So $O(n)$ complexity.
 - 6) Sanity :- $O(n)$. Because for loop detection Floyd's Algorithm will take $n/2$ iterations atleast if there is no loop. Also the process of checking $\text{curr.next} == \text{prev}$ will also take $O(n)$ time.
- So insert & getNext take $O(1)$ time and the rest take $O(n)$ time, if n is the size of DLL.

(b)* Allocated block worst size can be $O(n)$, for example in all the n operations, I just kept doing Allocate 1.

* Free block can have a worst size of $O(n)$ also. Let's say that we did Allocate $O(1)$ for $\frac{n}{2}$ operations. Now for the remaining $\frac{n}{2}$ we can keep ~~calling~~ freeing these allocated blocks.

1) Allocate → we first search for a block (node) of appropriate size in the whole free block LL. For that we use Find function. It takes $O(n)$ time to run. Thus $O(n)$ complexity.

2) Free → Again, using Find we search in the Allocated block for a particular key. Thus since Find takes $O(n)$ time, free function will also take $O(n)$ time.

A3.2 After n operations the maximum size of ~~allobk~~ & freebk can be $O(n)$. Hence in our further analysis we will consider size is $O(n)$.

complexity of BST functions. if n is the total no. of nodes & h is the height.

(a) Insert $\rightarrow O(h)$, At each step we go either left or to right (or even null if we are inserting a duplicate). Hence complexity $= O(h)$. $h = O(n)$. So the worst case becomes $O(n)$.

(b) Delete $\rightarrow O(h)$. Because we search for key. Now getNext() returns successor, so it is also $O(h)$.

(c) Find \rightarrow we have only right or left until found. Hence maximum nodes we check are $O(h)$. Thus time complexity is $O(h)$.

~~(d) getfirst() \rightarrow~~

(d) getRoot() \rightarrow travels till the Root & hence $O(h)$.

(e) getfirst() \rightarrow travels only left & hence $O(h)$ complexity.

(f) getNext() \rightarrow finds the successor & hence either travels up or travels left. Thus complexity is $O(h)$.

(g) compareNode or compareDict is a $O(1)$ complexity function.

(h) Sanity \rightarrow Sanity is a $O(n)$ function.

In all these for a BST h can be worst case $O(n)$. Hence they are $O(n)$ functions.

Now in FreeBk and AllorBk

(i) AllorBk $\rightarrow O(h)$ since we are using the find, insert & delete functions a constant no. of times. Each of which takes $O(h)$ time. Hence the TC is $O(h)$ or $O(n)$ of AllorBk when we use BSTree to implement the dictionary.

(ii) FreeBk $\rightarrow O(h)$. Again we are just using the insert, find and delete functions. Each of them works in $O(h)$. Hence the time complexity is $O(h)$. In worst case the TC is $O(n)$.

(iii) Index Debragment \rightarrow first, we copy the whole freeBk into an address indexed. This requires inorder traversal & also at each step insert is being done. Insert is $O(h)$. So this requires $O(n \cdot h)$ time. After it we do an inorder traversal & in that we do the insert, delete operations during each iteration of traversal. Hence the each step of traversal requires $O(h)$ time & the travel takes $O(n)$ time. So total time is $O(nh)$. Hence, time complexity will be $O(nh)$ & in the worst case it becomes $O(n^2)$.

A3.3

~~The~~ AVL tree is an extension of BST Tree. In this maintain the height property which ensures that $h = O(\log n)$ for AVL Tree.

Now substituting this in the time complexities we analysed in BST Tree.

(i) Insert \rightarrow Putting the node takes $O(\log n)$ time (just like in BST). Now we call the updateheight function which starts a while that runs maximum $O(\log n)$ time, since travels only to root through parents. In b/w it can call Rebalance function. Now Rebalance does a lot of operations but they are independent of n . Hence TC of Rebalance is $O(1)$. So TC of updateheight is $O(\log n)$. Thus the time complexity of Insert remains $O(\log n)$ even after maintaining the height property. (ie max diff in height of left & right child is max 1). TC of Insert = $O(\log n)$

(ii) Delete \rightarrow ~~the BST~~, first we find the node to be deleted like BST & it takes $O(\log n)$ time. In the end we call the updateheight which takes $O(\log n)$ time. Hence TC of Delete is $O(\log n)$.

(iii) Find $\rightarrow O(\log n)$

(iv) getRoot() $\rightarrow O(\log n)$

(v) getFirst() $\rightarrow O(\log n)$

(vi) getNext() $\rightarrow O(\log n)$

(vii) Sanity() $\rightarrow O(n)$

(viii) compareDict & compareNode $\rightarrow O(1)$

Thus the TC of :-

(a) AllocBlk $\rightarrow O(\log n)$. In BST it was $O(h)$
and $h = O(\log n)$. Thus TC is $O(\log n)$

(b) FreeBlk $\rightarrow O(\log n)$. In BST it was $O(h)$
and $h = O(\log n)$. Thus TC is $O(\log n)$.

(c) Defragment $\rightarrow O(n \log n)$. ~~Because~~
In BST we saw it was $O(n \cdot h)$ &
here $h = O(\log n)$. Thus TC of
Defragment is $O(n \log n)$.