

1 !pip install ultralytics roboflow

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Requirement already satisfied: six in /usr/local/lib/python3.12/dist-packages (from roboflow) (1.17.0)
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Downloading roboflow-1.2.9-py3-none-any.whl (88 kB)
  88.7/88.7 kB 9.0 MB/s eta 0:00:00
Downloading idna-3.7-py3-none-any.whl (66 kB)
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Downloading opencv_python_headless-4.10.0.84-cp37-abi3-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (49.9 MB)
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Installing collected packages: pillow-avif-plugin, filetype, pi-heif, opencv-python-headless, idna, ultralytics-thop, roboflow, ultralytics
  Attempting uninstall: opencv-python-headless
    Found existing installation: opencv-python-headless 4.12.0.88
    Uninstalling opencv-python-headless-4.12.0.88:
      Successfully uninstalled opencv-python-headless-4.12.0.88
  Attempting uninstall: idna
    Found existing installation: idna 3.10
    Uninstalling idna-3.10:
```

Successfully uninstalled idna-3.10

Successfully installed filetype-1.2.0 idna-3.7 opencv-python-headless-4.10.0.84 pi-heif-1.1.0 pillow-avif-plugin-1.5.2 roboflow-1.2.9 ultralytics-8.3.203 ultralytics-thop-2.0.17

1 !pip install ultralytics kaggle

Requirement already satisfied: ultralytics in /usr/local/lib/python3.12/dist-packages (8.3.203)  
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```
1 from google.colab import files
2 files.upload()
3 !mkdir -p ~/.kaggle
4 !cp kaggle.json ~/.kaggle/
5 !chmod 600 ~/.kaggle/kaggle.json
```

Choose Files

 kaggle.json

**kaggle.json**(application/json) - 65 bytes, last modified: n/a - 100% done  
Saving kaggle.json to kaggle.json

```
1 !kaggle datasets download -d andrewmvd/pothole-detection
2
3 !unzip pothole-detection.zip -d pothole-detection
```

```
inflating: pothole-detection/images/potholes641.png
inflating: pothole-detection/images/potholes642.png
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inflating: pothole-detection/images/potholes80.png
inflating: pothole-detection/images/potholes81.png
inflating: pothole-detection/images/potholes82.png
```

```
inflating: pothole-detection/images/potholes83.png
inflating: pothole-detection/images/potholes84.png
inflating: pothole-detection/images/potholes85.png
inflating: pothole-detection/images/potholes86.png
inflating: pothole-detection/images/potholes87.png
inflating: pothole-detection/images/potholes88.png
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inflating: pothole-detection/images/potholes93.png
inflating: pothole-detection/images/potholes94.png
inflating: pothole-detection/images/potholes95.png
inflating: pothole-detection/images/potholes96.png
```

```
1 import os
2 import xml.etree.ElementTree as ET
3
4 images_path = "pothole-detection/images"
5 annotations_path = "pothole-detection/annotations"
6 yolo_labels_path = "pothole-detection/labels"
7
8 os.makedirs(yolo_labels_path, exist_ok=True)
9
10 def convert(size, box):
11     dw = 1. / size[0]
12     dh = 1. / size[1]
13     x = (box[0] + box[1]) / 2.0 - 1
14     y = (box[2] + box[3]) / 2.0 - 1
15     w = box[1] - box[0]
16     h = box[3] - box[2]
17     x = x * dw
18     w = w * dw
19     y = y * dh
20     h = h * dh
21     return (x, y, w, h)
22
23 for xml_file in os.listdir(annotations_path):
24     if not xml_file.endswith('.xml'):
25         continue
26
27     tree = ET.parse(os.path.join(annotations_path, xml_file))
28     root = tree.getroot()
29
30     img_file = root.find('filename').text
31     size = root.find('size')
32     w = int(size.find('width').text)
33     h = int(size.find('height').text)
34
35     yolo_file = os.path.join(yolo_labels_path, xml_file.replace('.xml', '.txt'))
36     with open(yolo_file, 'w') as f:
37         for obj in root.iter('object'):
38             cls = 0
39             xmlbox = obj.find('bndbox')
40             b = (
41                 int(xmlbox.find('xmin').text),
42                 int(xmlbox.find('xmax').text),
43                 int(xmlbox.find('ymin').text),
44                 int(xmlbox.find('ymax').text)
45             )
46             bb = convert((w, h), b)
47             f.write(f"{cls} {' '.join([str(a) for a in bb])}\n")
```

```
1 !ls pothole-detection/labels | head
```

```
potholes0.txt
potholes100.txt
potholes101.txt
potholes102.txt
potholes103.txt
potholes104.txt
potholes105.txt
potholes106.txt
potholes107.txt
potholes108.txt
```

```
1 import os
2 import shutil
3 import random
4
5 src_images = "/content/pothole-detection/images"
6 src_labels = "/content/pothole-detection/labels"
7 dest = "/content/pothole_yolo"
8 train_ratio = 0.8
9
10 for split in ["train", "val"]:
11     os.makedirs(f"{dest}/images/{split}", exist_ok=True)
12     os.makedirs(f"{dest}/labels/{split}", exist_ok=True)
13
14 images = [f for f in os.listdir(src_images) if f.endswith(".png")]
15 random.shuffle(images)
16 split_idx = int(len(images)*train_ratio)
17
18 train_imgs = images[:split_idx]
19 val_imgs = images[split_idx:]
20
21 for img_list, split in [(train_imgs, "train"), (val_imgs, "val")]:
22     for img in img_list:
23         shutil.copy(os.path.join(src_images, img), f"{dest}/images/{split}/")
24         label_file = img.replace(".png", ".txt")
25         shutil.copy(os.path.join(src_labels, label_file), f"{dest}/labels/{split}/")
```

```
1 %%writefile /content/pothole_yolo/pothole.yaml
2 train: /content/pothole_yolo/images/train
3 val: /content/pothole_yolo/images/val
4
5 nc: 1
6 names: ['pothole']
```

```
Writing /content/pothole_yolo/pothole.yaml
```

```
1 from google.colab import files
2 uploaded = files.upload()
```

Choose Files  yolo11n.pt

yolo11n.pt(n/a) - 5613764 bytes, last modified: n/a - 100% done  
Saving yolo11n.pt to yolo11n.pt

```
1 !mv yolo11n.pt yolov11n.pt
```

```
1 !ls -lh yolov11n.pt
```

```
-rw-r--r-- 1 root root 5.4M Sep 25 14:46 yolov11n.pt
```

```
1 from ultralytics import YOLO
2
3 model = YOLO("yolov11n.pt")
4
5 model.train(
6     data="/content/pothole_yolo/pothole.yaml",
7     epochs=50,
8     imgsz=640
9 )
```

0.68145,	0.68099,	0.68053,	0.68011,	0.67994,	0.67836,	0.67724,	0.67678,	0.67632,	0.67586,	0.66935,	0.66935,	0.66935,	0.66935,
0.66935,	0.66935,	0.66935,	0.66632,	0.66592,	0.66553,	0.66514,	0.66474,	0.66435,	0.6639,	0.66935,	0.66935,	0.66935,	0.66935,
0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.65398,	0.65352,	0.64785,	0.64785,
0.63444,	0.64516,	0.64516,	0.64468,	0.64399,	0.6433,	0.64262,	0.64193,	0.64124,	0.64055,	0.63986,	0.63897,	0.63805,	0.63713,
0.63444,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,
0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63379,	0.63287,	0.63195,	0.63104,	0.63012,	0.62097,	0.62097,	0.62097,	0.62097,
0.62097,	0.6292,	0.62847,	0.62778,	0.62709,	0.6264,	0.62634,	0.62634,	0.62634,	0.62227,	0.62097,	0.62097,	0.62097,	0.62097,
0.60829,	0.61828,	0.61828,	0.61702,	0.61564,	0.61511,	0.61461,	0.61411,	0.6136,	0.6131,	0.6129,	0.6129,	0.61201,	0.61063,
0.5992,	0.60734,	0.60708,	0.60681,	0.60655,	0.60629,	0.60603,	0.60576,	0.6055,	0.60524,	0.60215,	0.60215,	0.6015,	0.59946,
0.58525,	0.60498,	0.60462,	0.60416,	0.6037,	0.60324,	0.60278,	0.60232,	0.60215,	0.60215,	0.58768,	0.5863,	0.5858,	0.58553,
0.56582,	0.59828,	0.59737,	0.59677,	0.59677,	0.59677,	0.59593,	0.59501,	0.59409,	0.5934,	0.5667,	0.56648,	0.56626,	0.56604,
0.5457,	0.59271,	0.59203,	0.59136,	0.59094,	0.59051,	0.59009,	0.58966,	0.58924,	0.58882,	0.56692,	0.56692,	0.56692,	0.56692,
0.52798,	0.58498,	0.5847,	0.58442,	0.58415,	0.58387,	0.5836,	0.58053,	0.57789,	0.57678,	0.56714,	0.56714,	0.56714,	0.56714,
0.50806,	0.57568,	0.57355,	0.57079,	0.56989,	0.56989,	0.56989,	0.56989,	0.56714,	0.56692,	0.56692,	0.56692,	0.56692,	0.56692,
0.47514,	0.5656,	0.56538,	0.56516,	0.56494,	0.56472,	0.56427,	0.56167,	0.56029,	0.55645,	0.5457,	0.5457,	0.5457,	0.5457,
0.43402,	0.55645,	0.55645,	0.55512,	0.55305,	0.55076,	0.54966,	0.54856,	0.54722,	0.54584,	0.53656,	0.53601,	0.53546,	0.53189,
0.39127,	0.5457,	0.54558,	0.54374,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.53779,	0.53711,	0.53711,	0.53711,
	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54231,	0.54047,	0.53779,	0.53711,	0.53656,	0.53601,	0.53546,	0.53189,
	0.52353,	0.52243,	0.52133,	0.52022,	0.51912,	0.51749,	0.51599,	0.51543,	0.51488,	0.50806,	0.50806,	0.50806,	0.50806,
	0.51433,	0.51378,	0.51344,	0.51344,	0.51344,	0.51344,	0.51237,	0.51127,	0.50806,	0.50806,	0.50806,	0.50806,	0.50806,
	0.50806,	0.50806,	0.50806,	0.50806,	0.50806,	0.50664,	0.50247,	0.50179,	0.50041,	0.48118,	0.4779,	0.47698,	0.47606,
	0.49686,	0.49576,	0.49466,	0.49061,	0.48878,	0.48786,	0.48695,	0.48496,	0.48276,	0.48118,	0.4779,	0.47698,	0.47606,
	0.47422,	0.4733,	0.47224,	0.47114,	0.46845,	0.46774,	0.46774,	0.46774,	0.46774,	0.44237,	0.43953,	0.43672,	0.43548,
	0.46237,	0.46237,	0.46237,	0.46135,	0.45648,	0.4514,	0.44956,	0.44773,	0.44571,	0.44237,	0.43953,	0.43672,	0.43548,
	0.43094,	0.42894,	0.42756,	0.42403,	0.42324,	0.42245,	0.42204,	0.42204,	0.42022,	0.4007,	0.39833,	0.39634,	0.39317,
	0.41935,	0.41776,	0.415,	0.40956,	0.4077,	0.40632,	0.40306,	0.40227,	0.40148,	0.4007,	0.39833,	0.39634,	0.39317,
	0.38989,	0.3895,	0.3892,	0.38889,	0.38858,	0.38828,	0.38797,	0.38767,	0.38736,	0.37487,	0.37377,	0.37118,	0.3697,
	0.38697,	0.38605,	0.38513,	0.38401,	0.38218,	0.37903,	0.37903,	0.37903,	0.37597,	0.37487,	0.37377,	0.37118,	0.3697,



```
0.36832, 0.36292, 0.36153, 0.35997, 0.35599, 0.35164, 0.34779, 0.34369, 0.34094, 0.33836,
0.30425, 0.33652, 0.33469, 0.33261, 0.32905, 0.32649, 0.3248, 0.32343, 0.31883, 0.31138, 0.31027, 0.30917, 0.30646, 0.30535,
0.23365, 0.28067, 0.27515, 0.27192, 0.26682, 0.26372, 0.26096, 0.25566, 0.25364, 0.2518, 0.24988, 0.24584, 0.24184, 0.24046,
0.12608, 0.17487, 0.17098, 0.16709, 0.16412, 0.16311, 0.16219, 0.15848, 0.15297, 0.14772, 0.14588, 0.1408, 0.1367, 0.12857,
0.042644, 0.086304, 0.083407, 0.080652, 0.077836, 0.071109, 0.068866, 0.061723, 0.060621, 0.059519, 0.057332, 0.050138, 0.04876, 0.044359,
0.0068341, 0.021443, 0.018797, 0.018373, 0.01795, 0.017526, 0.017102, 0.016678, 0.016254, 0.012241, 0.0079943, 0.0077042, 0.0074142, 0.0071241,
0.006544, 0.006254, 0.0059639, 0.0056739, 0.0053839, 0.0047053, 0.0040164, 0.0033276, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
fitness: np.float64(0.5207394435845443)
keys: ['metrics/precision(B)', 'metrics/recall(B)', 'metrics/mAP50(B)', 'metrics/mAP50-95(B)']
maps: array([ 0.52074])
names: {0: 'pothole'}
nt_per_class: array([372])
nt_per_image: array([133])
results_dict: {'metrics/precision(B)': 0.811987240839706, 'metrics/recall(B)': 0.7150537634408602, 'metrics/mAP50(B)': 0.8021540086501076, 'metrics/mAP50-95(B)': 0.5207394435845443,
'fitness': 0.5207394435845443}
save_dir: PosixPath('/content/runs/detect/train')
speed: {'preprocess': 0.3198847744381356. 'inference': 4.521828210528797. 'loss': 0.0003998345875474922. 'postprocess': 6.12033751879341}
```

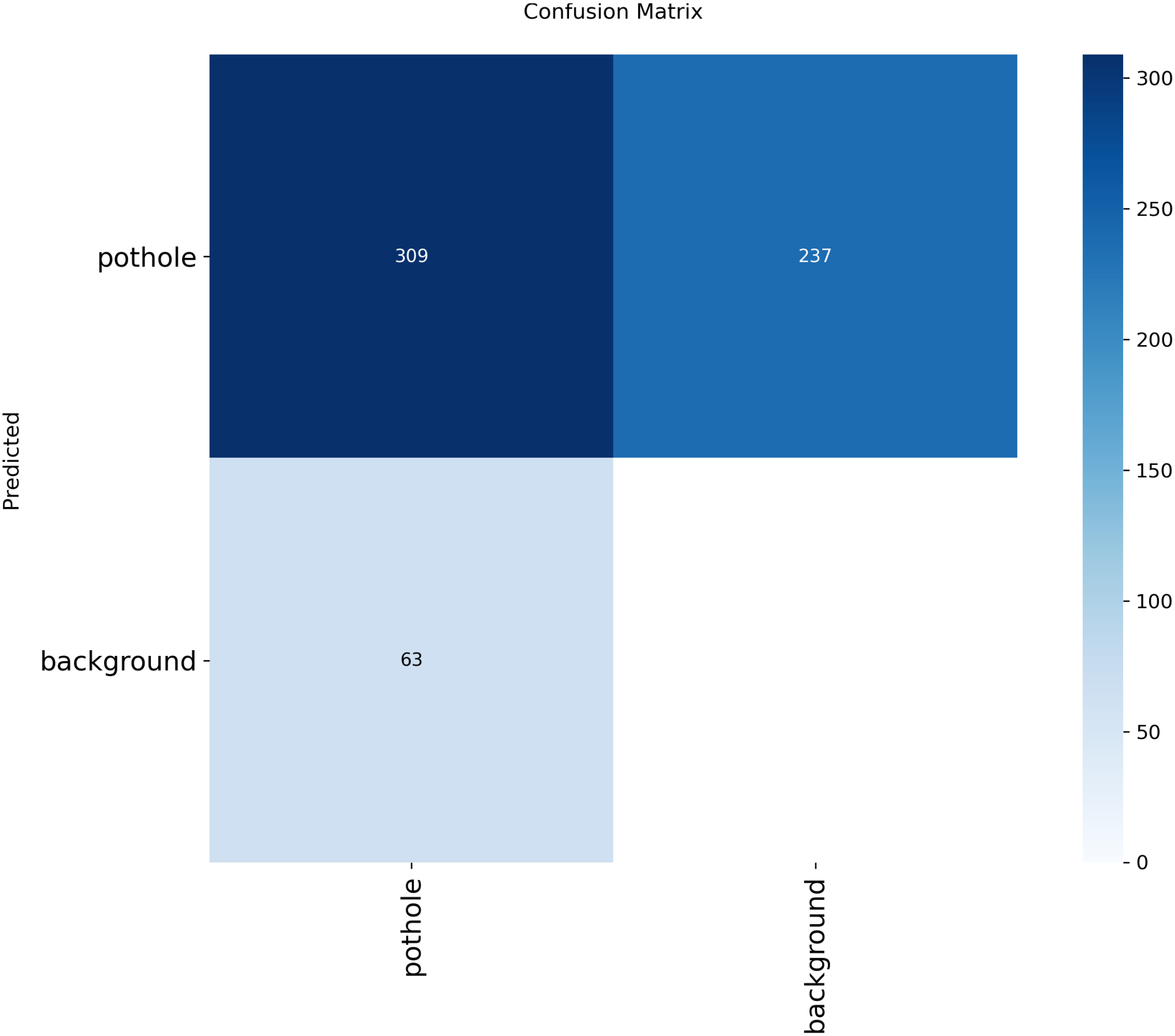
```
1 !pip install albumentations --quiet
2
3 from ultralytics import YOLO
4
5 model = YOLO("yolov11n.pt")
6
7 model.train(
8     data="/content/pothole_yolo/pothole.yaml",
9     epochs=70,
10    imgsiz=640,
11    batch=16,
12    augment=True,
13    lr0=0.001,
14    patience=10,
15 )
```

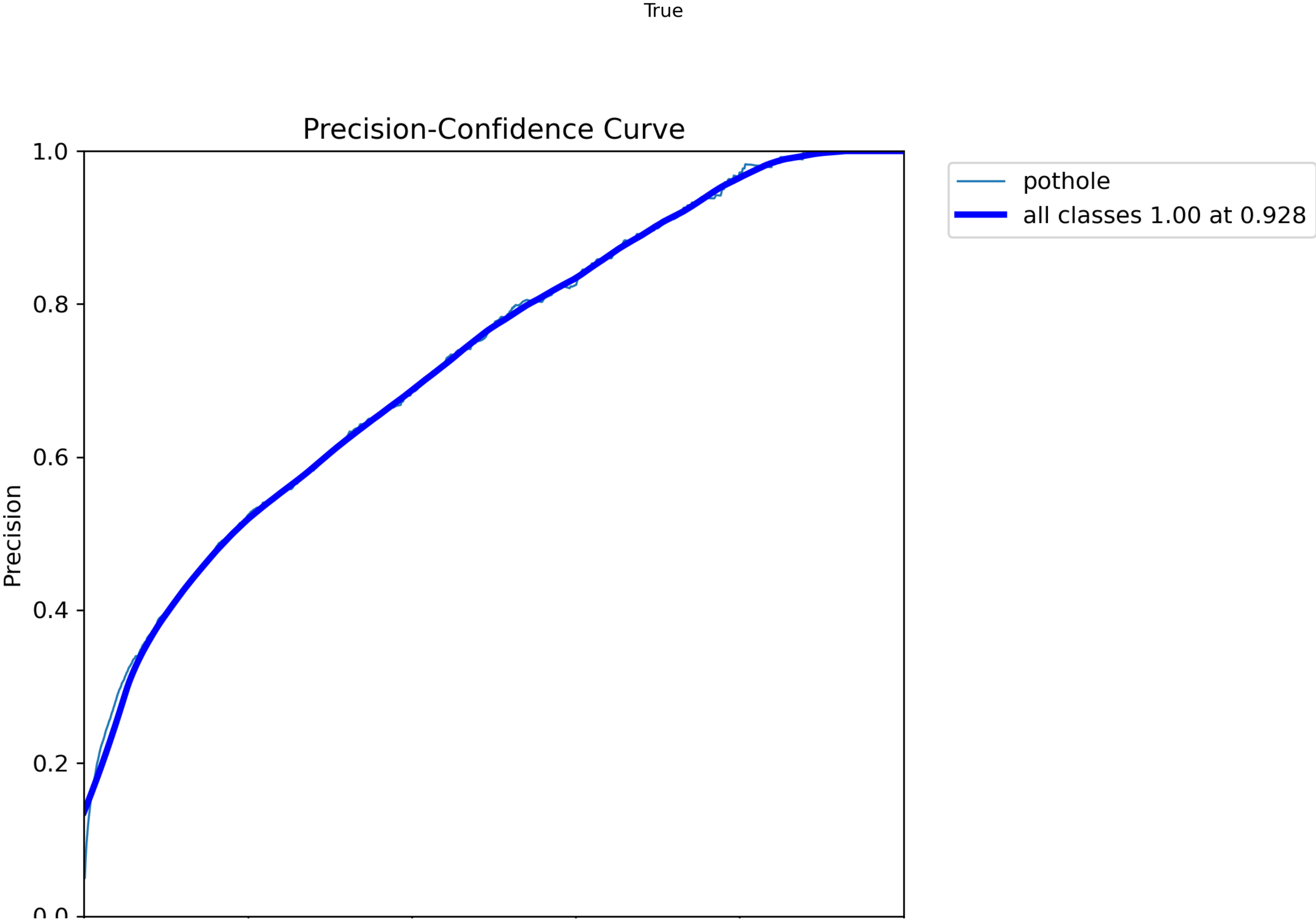
```
0.72312, 0.73145, 0.73118, 0.73118, 0.72771, 0.72633, 0.72581, 0.72581, 0.72544, 0.72489, 0.72434, 0.72378, 0.72323, 0.72312,
0.72043, 0.72312, 0.72312, 0.72189, 0.72051, 0.72043, 0.72043, 0.72043, 0.72043, 0.72043, 0.72043, 0.72043, 0.72043, 0.72043,
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0.69842, 0.6975, 0.69658, 0.69599, 0.6956, 0.6952, 0.69481, 0.69442, 0.69402, 0.69363, 0.68548, 0.68548, 0.68548, 0.68548,
0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548, 0.68548,
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0.67051, 0.66959, 0.6673, 0.66561, 0.66423, 0.66398, 0.66282, 0.66144, 0.66129, 0.66129, 0.66129, 0.66129, 0.66129, 0.66071, 0.65796, 0.65591,
0.65591, 0.65591, 0.65591, 0.65591, 0.65591, 0.65591, 0.65591, 0.65591, 0.65591, 0.655, 0.65066, 0.64969, 0.64859, 0.64768,
0.65409, 0.65323, 0.65323, 0.65323, 0.65323, 0.65323, 0.65287, 0.65232, 0.65177, 0.65121, 0.65066, 0.64969, 0.64859, 0.64768,
```

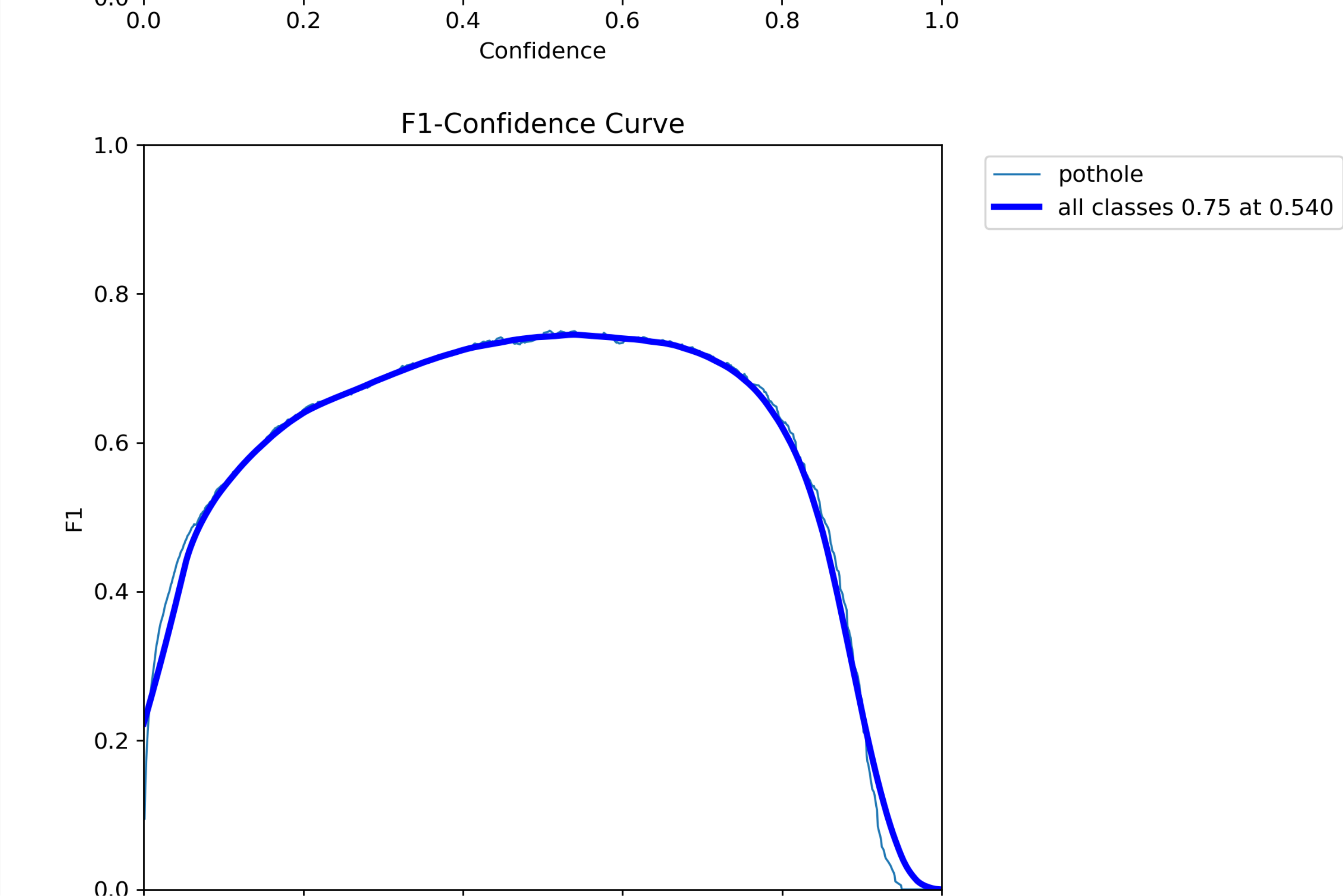
```

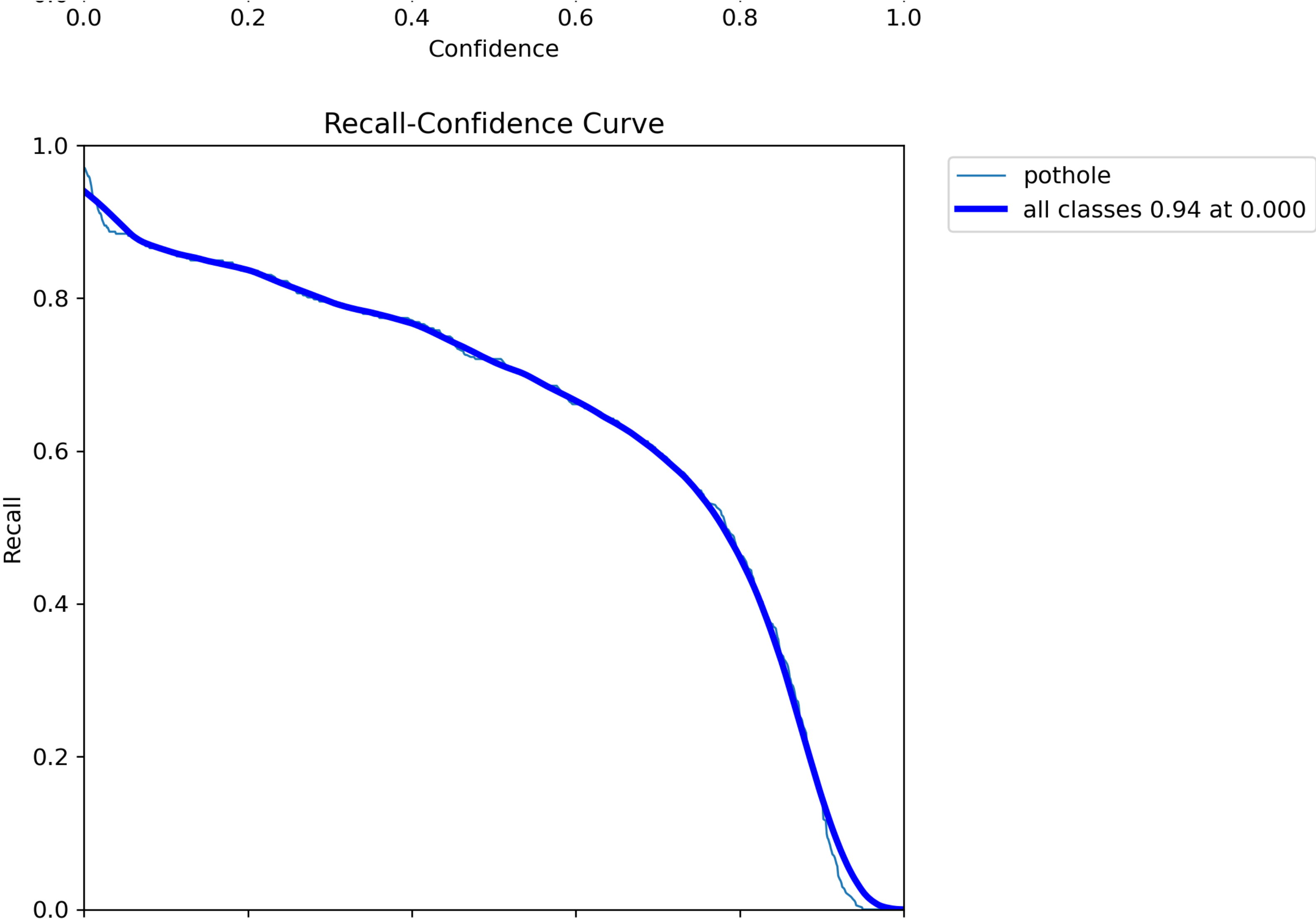
1 from IPython.display import Image, display
2 import glob
3
4 run_folder = "/content/runs/detect/train2/"
5
6 all_pngs = glob.glob(run_folder + "*.png")
7
8 if all_pngs:
9     for img_file in all_pngs:
10         display(Image(filename=img_file))
11 else:
12     print("No plot images found in the folder. Only model weights may be saved.")

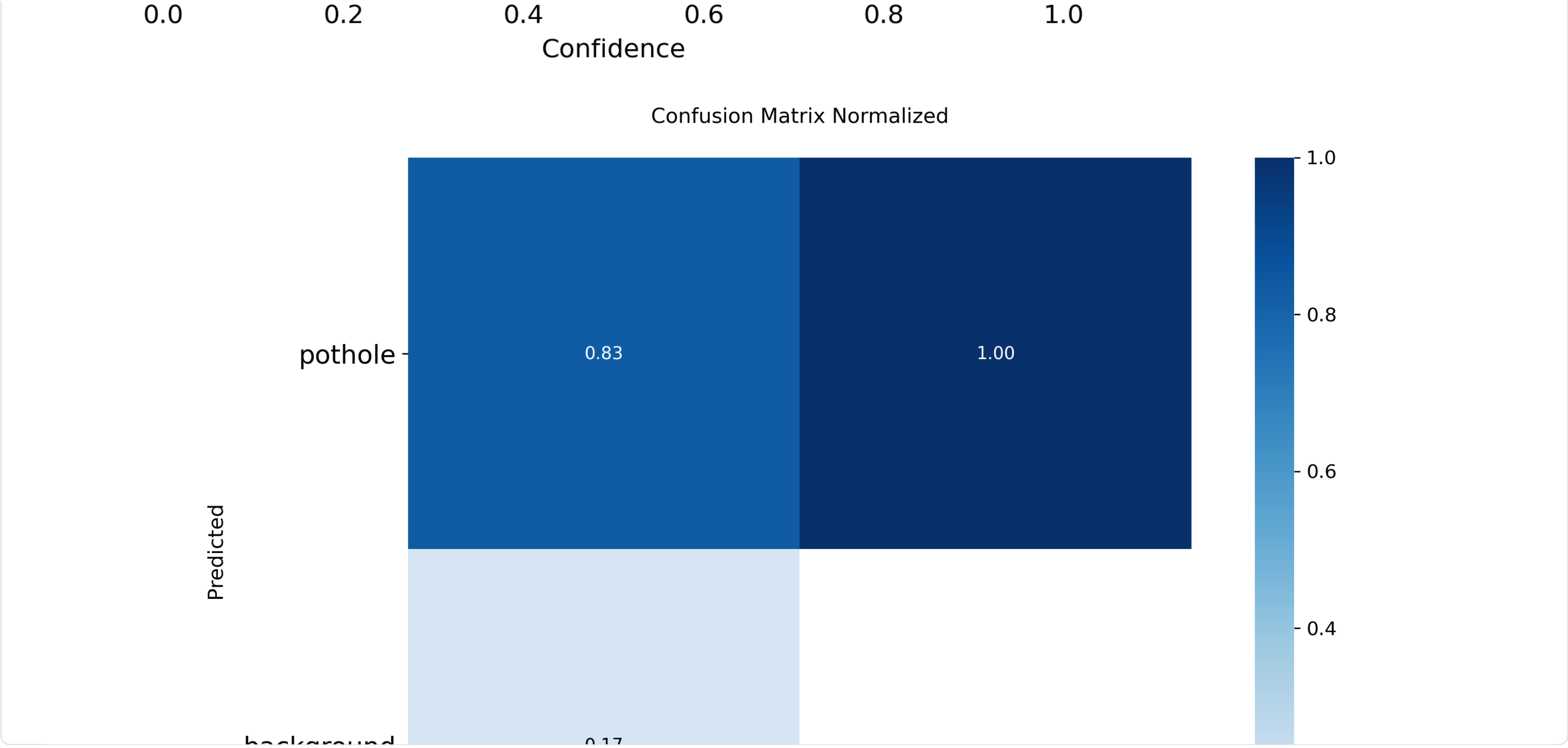
```











```
1 from google.colab import files
2 import os
3
4 uploaded = files.upload()
5 test_image = list(uploaded.keys())[0]
6
7 results = model.predict(test_image, imgsz=640)
8 res = results[0]
9
10 res.show()
11
12 os.makedirs("/content/test_results", exist_ok=True)
13
14 ...
```



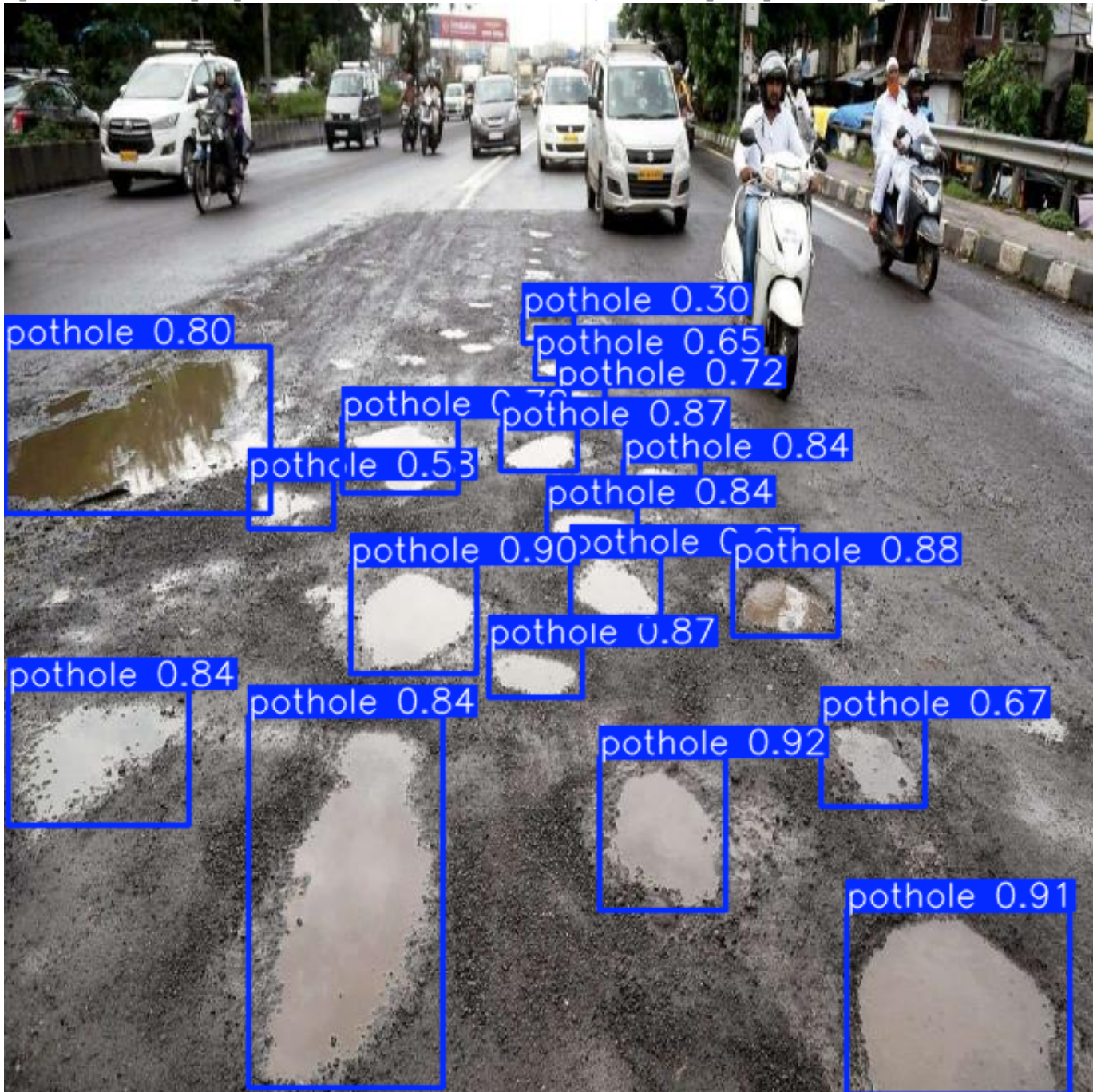
```
14 res.save("/content/test_results/result.png")
```

Choose Files  108\_jpg.rf....06795d.jpg

108\_jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg(image/jpeg) - 105332 bytes, last modified: n/a - 100% done

Saving 108\_jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg to 108\_jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg

image 1/1 /content/108\_jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg: 640x640 18 potholes, 10.5ms  
Speed: 2.2ms preprocess, 10.5ms inference, 1.3ms postprocess per image at shape (1, 3, 640, 640)



'/content/test\_results/result.png'

```
1 from google.colab import files
2 import os
3
4 uploaded = files.upload()
5
6 os.makedirs("/content/test_results_batch2", exist_ok=True)
7
8 for img_name in uploaded.keys():
9     results = model.predict(img_name, imsz=640)
10    res = results[0]
11    res.show()
```



```
12 save_path = f"/content/test_results_batch2/{img_name}"
13 res.save(save_path)
```


Choose Files  119\_jpg.rf....0860c4f.jpg  
119\_jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg(image/jpeg) - 140007 bytes, last modified: n/a - 100% done  
Saving 119\_jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg to 119\_jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg

image 1/1 /content/119\_jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg: 640x640 7 potholes, 12.6ms  
Speed: 1.9ms preprocess, 12.6ms inference, 1.5ms postprocess per image at shape (1, 3, 640, 640)

