

```
1 !pip install ultralytics roboflow
```

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Requirement already satisfied: six in /usr/local/lib/python3.12/dist-packages (from roboflow) (1.17.0)
Requirement already satisfied: urllib3>=1.26.6 in /usr/local/lib/python3.12/dist-packages (from roboflow) (2.5.0)
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  Downloading filetype-1.2.0-py2.py3-none-any.whl.metadata (6.5 kB)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.12/dist-packages (from matplotlib>=3.3.0->ultralytics) (1.3.3)
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Downloading roboflow-1.2.9-py3-none-any.whl (88 kB)
  88.7/88.7 KB 9.0 MB/s eta 0:00:00
Downloading idna-3.7-py3-none-any.whl (66 kB)
  66.8/66.8 KB 5.0 MB/s eta 0:00:00
Downloading opencv_python_headless-4.10.0.84-cp37abi3-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (49.9 MB)
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Downloading pi_heif-1.1.0-cp312-cp312-manylinux_2_27_x86_64.manylinux_2_28_x86_64.whl (1.4 MB)
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Downloading pillow_avif_plugin-1.5.2-cp312-cp312-manylinux_2_28_x86_64.whl (4.2 MB)
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Downloading filetype-1.2.0-py2.py3-none-any.whl (19 kB)
Installing collected packages: pillow-avif-plugin, filetype, pi-heif, opencv-python-headless, idna, ultralytics-thop, roboflow, ultralytics
  Attempting uninstall: opencv-python-headless
    Found existing installation: opencv-python-headless 4.12.0.88
  Uninstalling opencv-python-headless-4.12.0.88:
    Successfully uninstalled opencv-python-headless-4.12.0.88
  Attempting uninstall: idna
    Found existing installation: idna 3.10
  Uninstalling idna-3.10:
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```
Successfully uninstalled idna-3.10
Successfully installed filetype-1.2.0 idna-3.7 opencv-python-headless-4.10.0.84 pi-heif-1.1.0 pillow-avif-plugin-1.5.2 roboflow-1.2.9 ultralytics-8.3.203 ultralytics-thop-2.0.17
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```
1 !pip install ultralytics kaggle
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Requirement already satisfied: ultralytics in /usr/local/lib/python3.12/dist-packages (8.3.203)
Requirement already satisfied: kaggle in /usr/local/lib/python3.12/dist-packages (1.7.4.5)
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Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.12/dist-packages (from jinja2->torch>=1.8.0->ultralytics) (3.0.2)
```

```
1 from google.colab import files  
2 files.upload()  
3 !mkdir -p ~/.kaggle  
4 !cp kaggle.json ~/.kaggle/  
5 !chmod 600 ~/.kaggle/kaggle.json
```

Choose Files  kaggle.json

kaggle.json(application/json) - 65 bytes, last modified: n/a - 100% done
Saving kaggle.json to kaggle.json

```
1 !kaggle datasets download -d andrewmvd/pothole-detection  
2  
3 !unzip pothole-detection.zip -d pothole-detection
```

```
inflating: pothole-detection/images/potholes641.png  
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inflating: pothole-detection/images/potholes664.png  
inflating: pothole-detection/images/potholes67.png  
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inflating: pothole-detection/images/potholes81.png  
inflating: pothole-detection/images/potholes82.png
```

```
inflating: pothole-detection/images/potholes83.png
inflating: pothole-detection/images/potholes84.png
inflating: pothole-detection/images/potholes85.png
inflating: pothole-detection/images/potholes86.png
inflating: pothole-detection/images/potholes87.png
inflating: pothole-detection/images/potholes88.png
inflating: pothole-detection/images/potholes89.png
inflating: pothole-detection/images/potholes9.png
inflating: pothole-detection/images/potholes90.png
inflating: pothole-detection/images/potholes91.png
inflating: pothole-detection/images/potholes92.png
inflating: pothole-detection/images/potholes93.png
inflating: pothole-detection/images/potholes94.png
inflating: pothole-detection/images/potholes95.png
inflating: pothole-detection/images/potholes96.png
```

```
1 import os
2 import xml.etree.ElementTree as ET
3
4 images_path = "pothole-detection/images"
5 annotations_path = "pothole-detection/annotations"
6 yolo_labels_path = "pothole-detection/labels"
7
8 os.makedirs(yolo_labels_path, exist_ok=True)
9
10 def convert(size, box):
11     dw = 1. / size[0]
12     dh = 1. / size[1]
13     x = (box[0] + box[1]) / 2.0 - 1
14     y = (box[2] + box[3]) / 2.0 - 1
15     w = box[1] - box[0]
16     h = box[3] - box[2]
17     x = x * dw
18     w = w * dw
19     y = y * dh
20     h = h * dh
21     return (x, y, w, h)
22
23 for xml_file in os.listdir(annotations_path):
24     if not xml_file.endswith('.xml'):
25         continue
26
27     tree = ET.parse(os.path.join(annotations_path, xml_file))
28     root = tree.getroot()
29
30     img_file = root.find('filename').text
31     size = root.find('size')
32     w = int(size.find('width').text)
33     h = int(size.find('height').text)
34
35     yolo_file = os.path.join(yolo_labels_path, xml_file.replace('.xml', '.txt'))
36     with open(yolo_file, 'w') as f:
37         for obj in root.iter('object'):
38             cls = 0
39             xmlbox = obj.find('bndbox')
40             b = (
41                 int(xmlbox.find('xmin').text),
42                 int(xmlbox.find('xmax').text),
43                 int(xmlbox.find('ymin').text),
44                 int(xmlbox.find('ymax').text)
45             )
46             bb = convert((w, h), b)
47             f.write(f"{cls} {' '.join([str(a) for a in bb])}\n")
```

```
1 !ls pothole-detection/labels | head
```

```
potholes0.txt  
potholes100.txt  
potholes101.txt  
potholes102.txt  
potholes103.txt  
potholes104.txt  
potholes105.txt  
potholes106.txt  
potholes107.txt  
potholes108.txt
```

```
1 import os  
2 import shutil  
3 import random  
4  
5 src_images = "/content/pothole-detection/images"  
6 src_labels = "/content/pothole-detection/labels"  
7 dest = "/content/pothole_yolo"  
8 train_ratio = 0.8  
9  
10 for split in ["train", "val"]:  
11     os.makedirs(f"{dest}/images/{split}", exist_ok=True)  
12     os.makedirs(f"{dest}/labels/{split}", exist_ok=True)  
13  
14 images = [f for f in os.listdir(src_images) if f.endswith(".png")]  
15 random.shuffle(images)  
16 split_idx = int(len(images)*train_ratio)  
17  
18 train_imgs = images[:split_idx]  
19 val_imgs = images[split_idx:]  
20  
21 for img_list, split in [(train_imgs, "train"), (val_imgs, "val")]:  
22     for img in img_list:  
23         shutil.copy(os.path.join(src_images, img), f"{dest}/images/{split}/")  
24         label_file = img.replace(".png", ".txt")  
25         shutil.copy(os.path.join(src_labels, label_file), f"{dest}/labels/{split}/")
```

```
1 %%writefile /content/pothole_yolo/pothole.yaml  
2 train: /content/pothole_yolo/images/train  
3 val: /content/pothole_yolo/images/val  
4  
5 nc: 1  
6 names: ['pothole']
```

```
Writing /content/pothole_yolo/pothole.yaml
```

```
1 from google.colab import files
2 uploaded = files.upload()
```

Choose Files yolo11n.pt
yolo11n.pt(n/a) - 5613764 bytes, last modified: n/a - 100% done
 Saving yolo11n.pt to yolo11n.pt

```
1 !mv yolo11n.pt yolov11n.pt
```

```
1 !ls -lh yolov11n.pt
```

```
-rw-r--r-- 1 root root 5.4M Sep 25 14:46 yolov11n.pt
```

```
1 from ultralytics import YOLO
2
3 model = YOLO("yolov11n.pt")
4
5 model.train(
6     data="/content/pothole_yolo/pothole.yaml",
7     epochs=50,
8     imgsz=640
9 )
```

	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,	0.0001,
0.68145,	0.68099,	0.68053,	0.68011,	0.67994,	0.67836,	0.67724,	0.67678,	0.67632,	0.67586,	0.67535,	0.67485,	0.67435,	0.67385,	0.67335,
	0.6754,	0.67494,	0.67398,	0.6726,	0.67149,	0.67058,	0.66966,	0.66935,	0.66935,	0.66935,	0.66935,	0.66935,	0.66935,	0.66935,
0.66935,	0.66935,	0.66935,	0.66935,	0.66632,	0.66592,	0.66553,	0.66514,	0.66474,	0.66435,	0.6639,	0.6635,	0.6631,	0.6627,	0.6623,
	0.66252,	0.66099,	0.65842,	0.65704,	0.65591,	0.65582,	0.65536,	0.6549,	0.6544,	0.65398,	0.65352,	0.6531,	0.6527,	0.6523,
0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,	0.64516,
	0.64516,	0.64516,	0.64468,	0.64399,	0.6433,	0.64262,	0.64193,	0.64124,	0.64055,	0.63986,	0.63897,	0.63805,	0.63713,	0.63621,
0.63444,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63441,
	0.63441,	0.63441,	0.63441,	0.63441,	0.63379,	0.63287,	0.63195,	0.63104,	0.63012,	0.63012,	0.63012,	0.63012,	0.63012,	0.63012,
0.63441,	0.63441,	0.63441,	0.63441,	0.63441,	0.63379,	0.63287,	0.63195,	0.63104,	0.63012,	0.63012,	0.63012,	0.63012,	0.63012,	0.63012,
	0.6292,	0.62847,	0.62778,	0.62709,	0.6264,	0.62634,	0.62634,	0.62634,	0.62227,	0.62097,	0.62097,	0.62097,	0.62097,	0.62097,
0.62097,	0.62097,	0.62097,	0.62097,	0.62097,	0.62097,	0.61885,	0.61828,	0.61828,	0.61828,	0.61828,	0.61828,	0.61828,	0.61828,	0.61828,
	0.61828,	0.61828,	0.61702,	0.61564,	0.61511,	0.61461,	0.61411,	0.6136,	0.6131,	0.6129,	0.6129,	0.6129,	0.6129,	0.6129,
0.60829,	0.60734,	0.60708,	0.60681,	0.60655,	0.60629,	0.60603,	0.60576,	0.6055,	0.60524,	0.60524,	0.60524,	0.60524,	0.60524,	0.60524,
	0.60498,	0.60462,	0.60416,	0.6037,	0.60324,	0.60278,	0.60232,	0.60215,	0.60215,	0.60215,	0.60215,	0.60215,	0.60215,	0.60215,
0.5992,	0.59828,	0.59737,	0.59677,	0.59677,	0.59577,	0.59593,	0.59501,	0.59409,	0.5934,	0.5928,	0.5922,	0.5916,	0.5910,	0.5904,
	0.59271,	0.59203,	0.59136,	0.59094,	0.59051,	0.59009,	0.58966,	0.58924,	0.58882,	0.58768,	0.5863,	0.5858,	0.5853,	0.5847,
0.58525,	0.58498,	0.5847,	0.58442,	0.58415,	0.58387,	0.5836,	0.58053,	0.57789,	0.57678,	0.57667,	0.57648,	0.57626,	0.57604,	0.57582,
	0.57568,	0.57355,	0.57079,	0.56989,	0.56989,	0.56989,	0.56989,	0.56989,	0.56714,	0.56692,	0.5667,	0.56648,	0.56626,	0.56604,
0.56582,	0.5656,	0.56538,	0.56516,	0.56494,	0.56472,	0.56427,	0.56167,	0.56029,	0.55645,	0.55645,	0.55645,	0.55645,	0.55645,	0.55645,
	0.55645,	0.55645,	0.55512,	0.55305,	0.55076,	0.54966,	0.54856,	0.54722,	0.54584,	0.5457,	0.5457,	0.5457,	0.5457,	0.5457,
0.5457,	0.5457,	0.54558,	0.54374,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,
	0.54301,	0.54301,	0.54301,	0.54301,	0.54301,	0.54231,	0.54047,	0.53779,	0.53711,	0.53656,	0.53601,	0.53546,	0.53189,	0.53032,
0.52798,	0.52353,	0.52243,	0.52133,	0.52022,	0.51912,	0.51749,	0.51599,	0.51543,	0.51488,	0.51488,	0.51488,	0.51488,	0.51488,	0.51488,
	0.51433,	0.51378,	0.51344,	0.51344,	0.51344,	0.51344,	0.51344,	0.51237,	0.51127,	0.50806,	0.50806,	0.50806,	0.50806,	0.50806,
0.50806,	0.50806,	0.50806,	0.50806,	0.50806,	0.50806,	0.50664,	0.50247,	0.50179,	0.5011,	0.50041,	0.50041,	0.50041,	0.50041,	0.50041,
	0.49686,	0.49576,	0.49466,	0.49061,	0.48878,	0.48786,	0.48695,	0.48496,	0.48276,	0.48118,	0.4779,	0.47698,	0.47606,	0.47514,
0.47514,	0.47422,	0.4733,	0.47224,	0.47114,	0.46845,	0.46774,	0.46774,	0.46774,	0.46379,	0.46379,	0.46379,	0.46379,	0.46379,	0.46379,
	0.46237,	0.46237,	0.46237,	0.46135,	0.45648,	0.4514,	0.44956,	0.44773,	0.44571,	0.44237,	0.43953,	0.43672,	0.43548,	0.43402,
0.43402,	0.43094,	0.42894,	0.42756,	0.42403,	0.42324,	0.42245,	0.42204,	0.42022,	0.41935,	0.41935,	0.41935,	0.41935,	0.41935,	0.41935,
	0.41935,	0.41776,	0.415,	0.40956,	0.4077,	0.40632,	0.40306,	0.40227,	0.40148,	0.4007,	0.39833,	0.39634,	0.39317,	0.39127,
0.39127,	0.38989,	0.3895,	0.3892,	0.38889,	0.38858,	0.38828,	0.38797,	0.38767,	0.38736,	0.38736,	0.38736,	0.38736,	0.38736,	0.38736,
	0.38697,	0.38605,	0.38513,	0.38401,	0.38218,	0.37903,	0.37903,	0.37903,	0.37597,	0.37487,	0.37377,	0.37118,	0.3697,	0.3697,

```

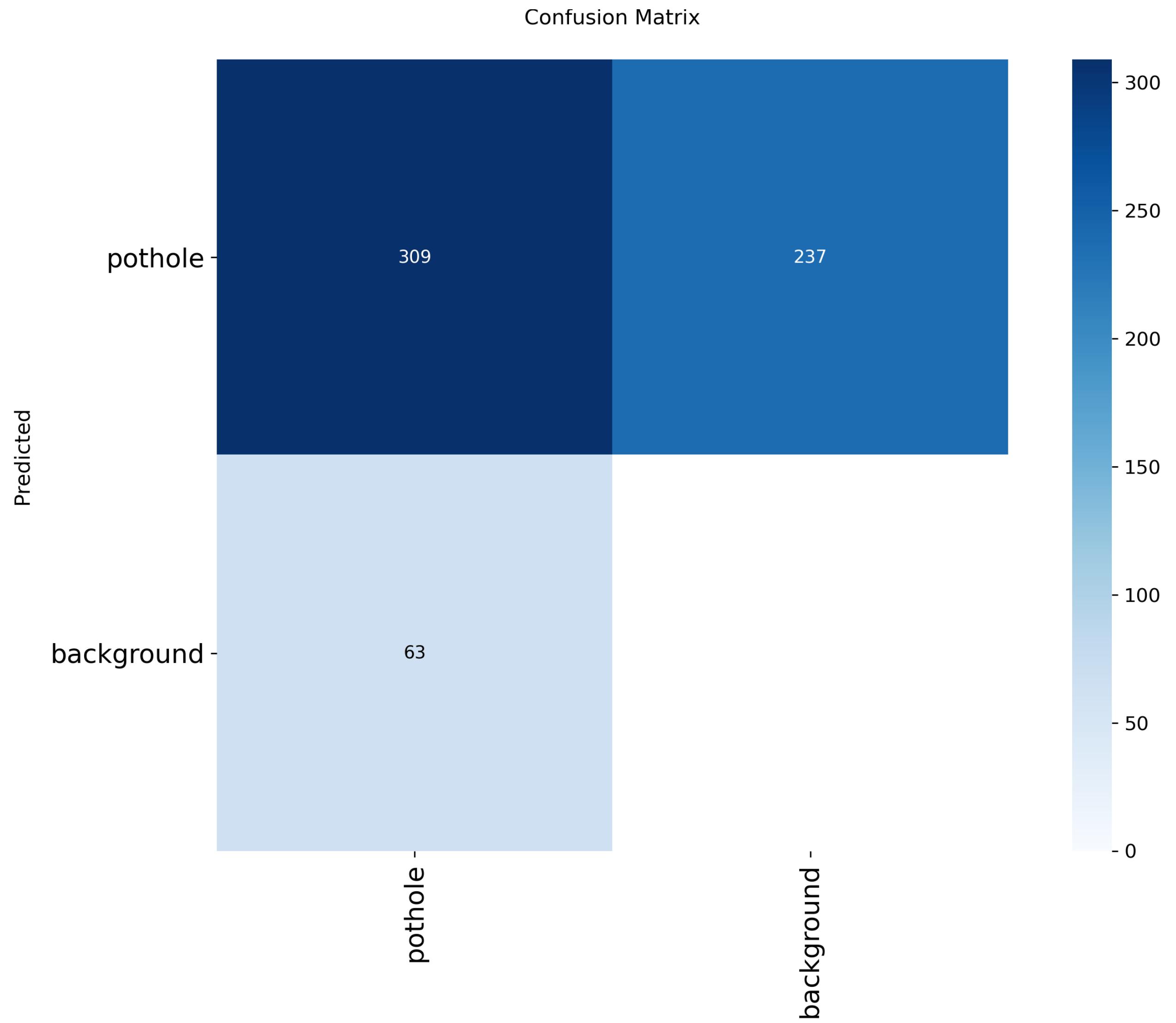
0.36832,    0.36292,    0.36153,    0.35997,    0.35599,    0.35164,    0.34779,    0.34369,    0.34094,    0.33836,
            0.33652,    0.33469,    0.33261,    0.32905,    0.32649,    0.3248,    0.32343,    0.31883,    0.31138,    0.31027,    0.30917,    0.30646,    0.30535,
0.30425,    0.30069,    0.29557,    0.29419,    0.29262,    0.2894,    0.28717,    0.28648,    0.28579,    0.2851,    0.31027,    0.30917,    0.30646,    0.30535,
            0.28067,    0.27515,    0.27192,    0.26682,    0.26372,    0.26096,    0.25566,    0.25364,    0.2518,    0.24988,    0.24584,    0.24184,    0.24046,
0.23365,    0.23182,    0.22757,    0.21668,    0.2058,    0.1976,    0.19306,    0.19122,    0.17707,    0.17597,    0.24584,    0.24184,    0.24046,
            0.17487,    0.17098,    0.16709,    0.16412,    0.16311,    0.16219,    0.15848,    0.15297,    0.14772,    0.14588,    0.1408,    0.1367,    0.12857,
0.12608,    0.1247,    0.12233,    0.10948,    0.1073,    0.10651,    0.10572,    0.10494,    0.10243,    0.09295,    0.09295,
            0.086304,   0.083407,   0.080652,   0.077836,   0.071109,   0.068866,   0.061723,   0.060621,   0.059519,   0.057332,   0.050138,   0.04876,   0.044359,
0.042644,    0.041266,   0.039889,   0.038511,   0.03563,    0.032533,   0.031431,   0.030513,   0.029594,   0.025093,
            0.021443,   0.018797,   0.018373,   0.01795,    0.017526,   0.017102,   0.016678,   0.016254,   0.012241,   0.0079943,   0.0077042,   0.0074142,   0.0071241,
0.0068341,   0.006544,   0.006254,   0.0059639,  0.0056739,  0.0053839,  0.0047053,  0.0040164,  0.0033276,  0,
            0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,
0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,
            0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,
0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,
            0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,          0,
fitness: np.float64(0.5207394435845443)
keys: ['metrics/precision(B)', 'metrics/recall(B)', 'metrics/mAP50(B)', 'metrics/mAP50-95(B)']
maps: array([ 0.52074])
names: {0: 'pothole'}
nt_per_class: array([372])
nt_per_image: array([133])
results_dict: {'metrics/precision(B)': 0.811987240839706, 'metrics/recall(B)': 0.7150537634408602, 'metrics/mAP50(B)': 0.8021540086501076, 'metrics/mAP50-95(B)': 0.5207394435845443,
'fitness': 0.5207394435845443}
save_dir: PosixPath('/content/runs/detect/train')
speed: {'preprocess': 0.3198847744381356, 'inference': 4.521828210528797, 'loss': 0.0003998345875474922, 'postprocess': 6.12033751879341}

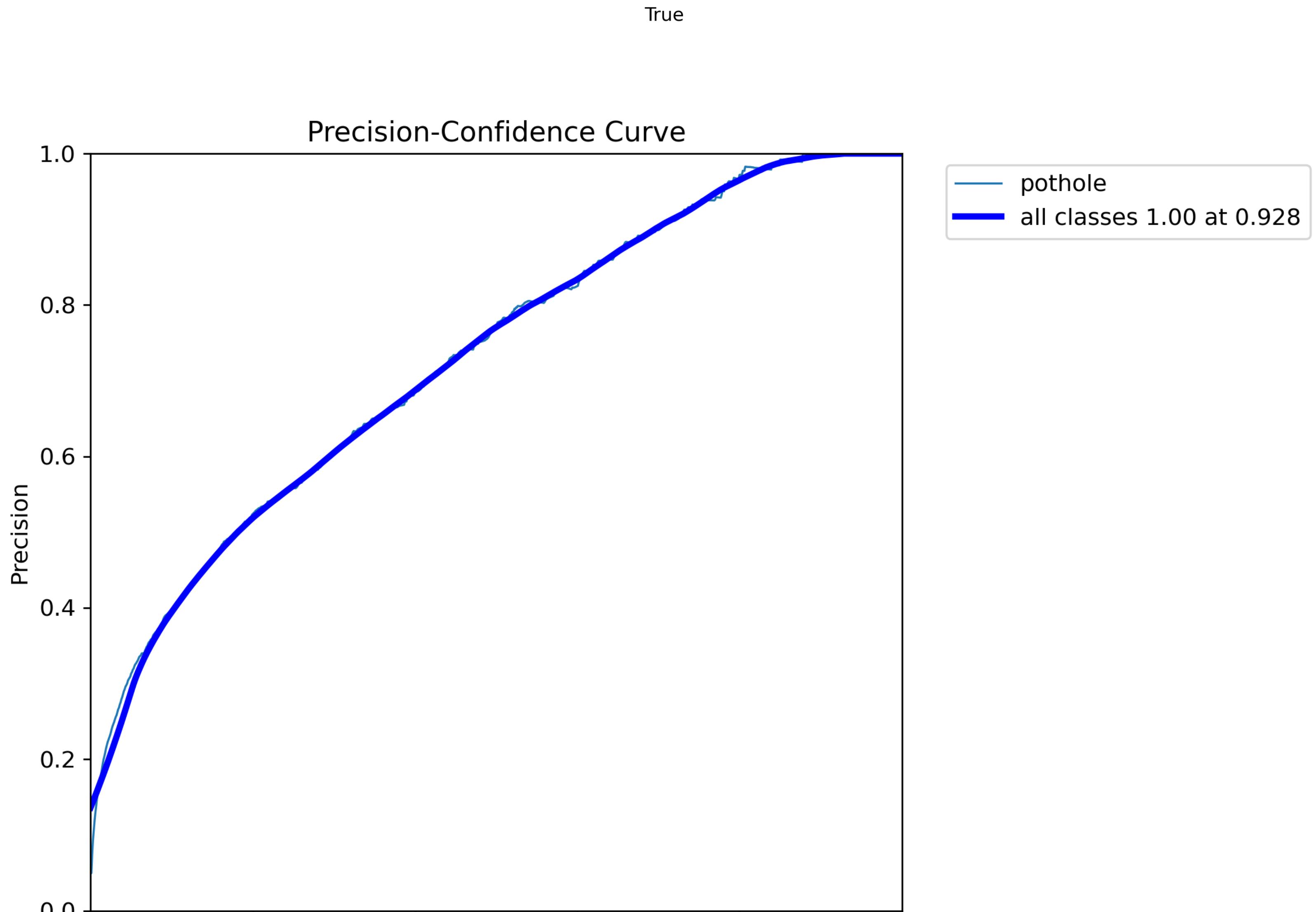
```

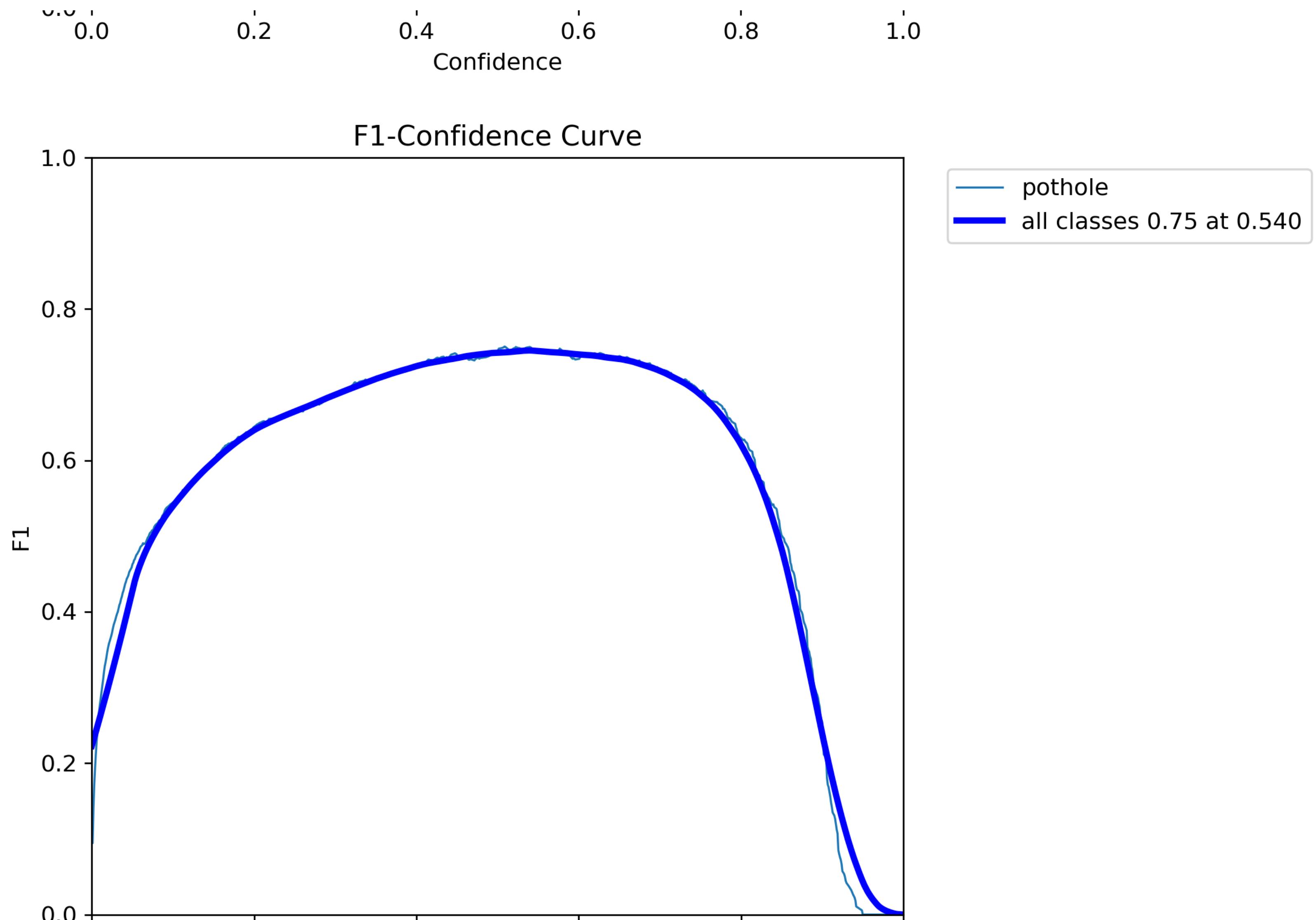
```
1 !pip install albumentations --quiet
2
3 from ultralytics import YOLO
4
5 model = YOLO("yolov11n.pt")
6
7 model.train(
8     data="/content/pothole_yolo/pothole.yaml",
9     epochs=70,
10    imgsz=640,
11    batch=16,
12    augment=True,
13    lr0=0.001,
14    patience=10,
15 )
```

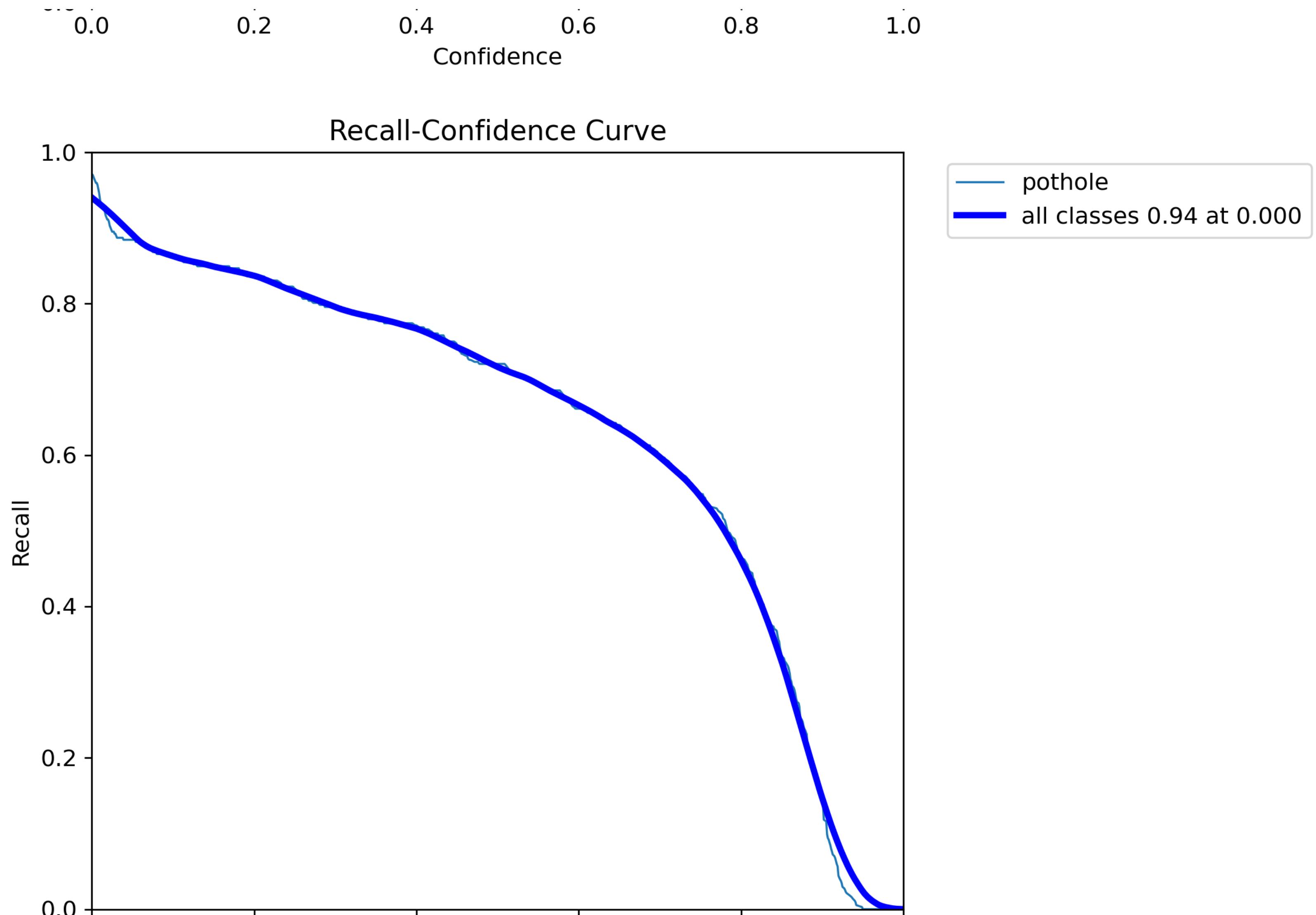
$0.72312,$	$0.73145,$	$0.73118,$	$0.73118,$	$0.72771,$	$0.72633,$	$0.72581,$	$0.72581,$	$0.72544,$	$0.72489,$	$0.72434,$	$0.72378,$	$0.72323,$	$0.72312,$	
	$0.72312,$	$0.72312,$	$0.72189,$	$0.72051,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	
$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	$0.72043,$	
	$0.72043,$	$0.72043,$	$0.72043,$	$0.71944,$	$0.71806,$	$0.71668,$	$0.71531,$	$0.71393,$	$0.71255,$	$0.70998,$	$0.70968,$	$0.70968,$	$0.70968,$	
$0.70968,$	$0.70968,$	$0.70968,$	$0.70951,$	$0.70699,$	$0.70669,$	$0.7043,$	$0.70419,$	$0.7035,$	$0.70281,$					
	$0.70212,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70161,$	$0.70092,$	
$0.69842,$	$0.6975,$	$0.69658,$	$0.69599,$	$0.6956,$	$0.6952,$	$0.69481,$	$0.69442,$	$0.69402,$	$0.69363,$					$0.69954,$
	$0.69311,$	$0.69256,$	$0.69201,$	$0.69146,$	$0.69091,$	$0.68985,$	$0.68875,$	$0.68817,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	
$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	$0.68548,$	
	$0.68548,$	$0.68548,$	$0.68422,$	$0.68284,$	$0.68147,$	$0.68009,$	$0.67899,$	$0.67789,$	$0.67473,$	$0.67418,$	$0.67326,$	$0.67234,$	$0.67143,$	
$0.67051,$	$0.66959,$	$0.6673,$	$0.66561,$	$0.66423,$	$0.66398,$	$0.66282,$	$0.66144,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66071,$	
	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66129,$	$0.66071,$	$0.65796,$	$0.65591,$
$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.65591,$	$0.64859,$	$0.64768,$
	$0.65409,$	$0.65323,$	$0.65323,$	$0.65323,$	$0.65323,$	$0.65287,$	$0.65232,$	$0.65177,$	$0.65121,$	$0.65066,$	$0.64969,$	$0.64859,$	$0.64768,$	

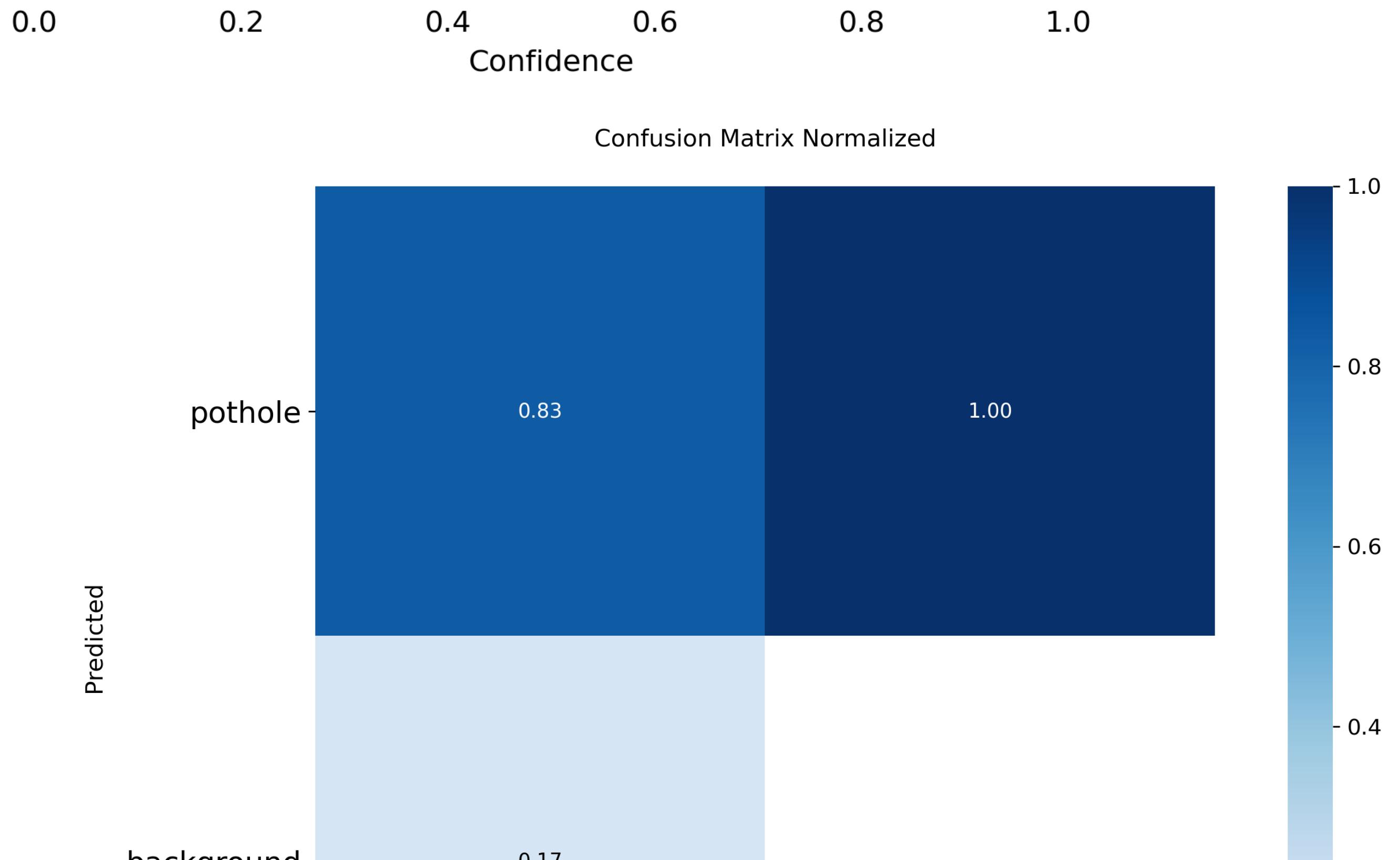
```
1 from IPython.display import Image, display
2 import glob
3
4 run_folder = "content/runs/detect/train2"
5
6 all_pngs = glob.glob(run_folder + "*.png")
7
8 if all_pngs:
9     for img_file in all_pngs:
10         display(Image(filename=img_file))
11 else:
12     print("No plot images found in the folder. Only model weights may be saved.")
```











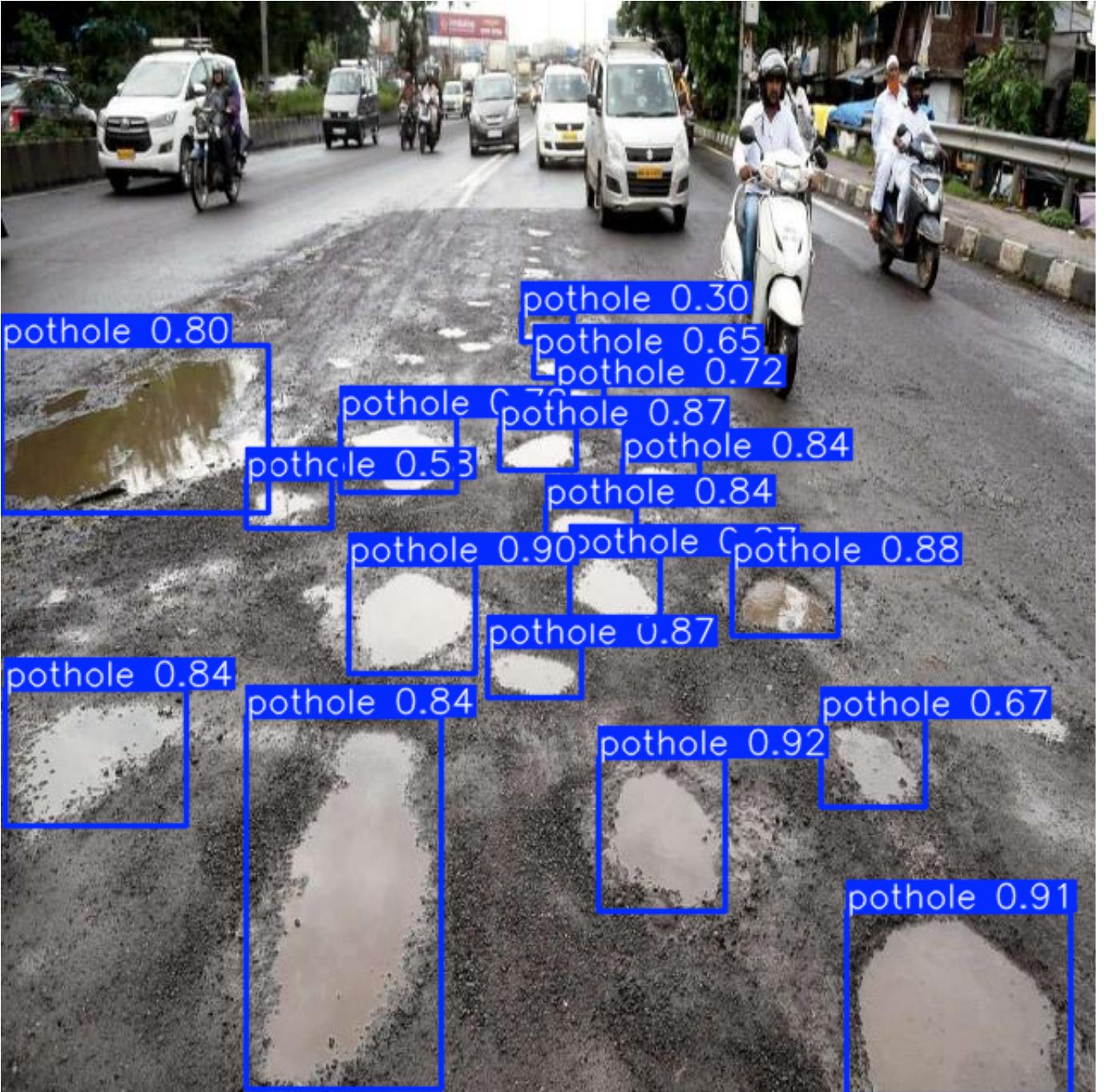
```
1 from google.colab import files
2 import os
3
4 uploaded = files.upload()
5 test_image = list(uploaded.keys())[0]
6
7 results = model.predict(test_image, imgsz=640)
8 res = results[0]
9
10 res.show()
11
12 os.makedirs("/content/test_results", exist_ok=True)
13
```

```
14 res.save("/content/test_results/result.png")
```

Choose Files 108.jpg.rf....06795d.jpg

108.jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg(image/jpeg) - 105332 bytes, last modified: n/a - 100% done
Saving 108.jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg to 108.jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg

image 1/1 /content/108.jpg.rf.4e9b9dca9d6ea7afc84dbc9e4706795d.jpg: 640x640 18 potholes, 10.5ms
Speed: 2.2ms preprocess, 10.5ms inference, 1.3ms postprocess per image at shape (1, 3, 640, 640)



'/content/test_results/result.png'

```
1 from google.colab import files
2 import os
3
4 uploaded = files.upload()
5
6 os.makedirs("/content/test_results_batch2", exist_ok=True)
7
8 for img_name in uploaded.keys():
9     results = model.predict(img_name, imgsz=640)
10    res = results[0]
11    res.show()
```

```
12 save_path = f"/content/test_results_batch2/{img_name}"  
13 res.save(save_path)
```

Choose Files 119.jpg.rf....0860c4f.jpg

119.jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg (image/jpeg) - 140007 bytes, last modified: n/a - 100% done
Saving 119.jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg to 119.jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg

image 1/1 /content/119.jpg.rf.aec2a22e68edc38dff8422d160860c4f.jpg: 640x640 7 potholes, 12.6ms
Speed: 1.9ms preprocess, 12.6ms inference, 1.5ms postprocess per image at shape (1, 3, 640, 640)

