

# Aayush Mishra

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## About

Robotics and Embedded Software Engineer with 2 years of experience integrating **Mechanical, Electrical-Electronics, and Computer Science** principles to build innovative solutions and projects.

## Education

**MIT Manipal, Manipal**

*July 2023 – Present*

*B.Tech in Mechatronics (Robotics and Automation)*

- CGPA: 7.14/10.00
- **Coursework:** Data Structures, Control Systems, Digital and Analog Design, Micro-controllers.

## Experience

**UG Researcher**

*Udupi*

*MIT Manipal*

*Sept 2024 – Present*

- Engineered a system to identify/classify flying objects (UAVs/drones) into Type 1/2/3 threat levels using micro-Doppler radar data.
- Integrated **FMCW and SAR modules for signal acquisition and imaging**. Processed radar signals and **generated micro-Doppler spectrograms using MATLAB (Signal Processing, Phased Array Toolbox)**.
- Designed and **trained CNN and Transformer-based models in Python (PyTorch, TensorFlow)** with large, augmented datasets.

## Skills and Competencies

**Programming:** Embedded C, Python, MATLAB, C++

**Design and Modeling:**

- 1) PCB Design (KiCAD, Fritzing, Proteus)
- 2) CAD Modeling (Fusion 360, Solidworks)

**Technologies:** Git/GitHub, VS Code, MATLAB Live Scripts, Keil uVision, Arduino IDE, Jupyter Notebook.

**Courses:** Micro-Controllers, Linear Control Systems, Probability, Signal Processing and Analysis, Mechanical Design and Element Analysis.

**Web Development:** HTML/CSS, JavaScript, TypeScript, ReactJS, TailwindCSS, NextJS, API/SDK Integration.

## Projects

**Digital Tachometer using MSP432P401R**

[GitHub Link](#) 

- Built a Digital Tachometer for measuring rotational speed, and **programmed it using MSP432P401R micro-controller in Embedded C**.
- Tools Used: Embedded C, Keil uVision

**PCB Design for Phase Shift Oscillator**

[EasyEDA Profile](#) 

- Engineered a PCB for a **Sine Wave Phase Shift Oscillator** using **Operational Amplifiers**.
- Achieved **stable frequency generation by precise component selection and circuit optimization**. Focused on minimizing noise, improving signal integrity, and maintaining compact board layout.
- Tools Used: KiCAD

**Automatic Motion Detection System using PLC**

[GitHub Link](#) 

- Engineered a Sensor-Based Automated Motion Detection system using **Bosch Rexroth PLC, Arduino**

**Mega 2560, Ultrasonic Sensors, Buck and Boost Converters, with Breadboard and PCB Design in Fritzing and Simulation in Proteus.**

- Tools Used: C++, Proteus, Fritzing.

#### **PI and PID Controller Designs for Control Systems**

[GitHub Link](#) 

- Designed and tuned PI and PID Controllers for a Linear Dynamic System **using Root Locus and Bode Analysis to optimize stability and performance** with the help of Control System Toolbox Add-On.
- Tools Used: MATLAB