

EOAlgo< EOT >

paradiseo::smp::Scheduler  
< Dummy, boost::numeric  
::interval\_lib::policies >

paradiseo::smp::MWModel  
< EOAlgo, EOT, Policy >

scheduler

```
graph LR; MWModel[paradiseo::smp::MWModel< EOAlgo, EOT, Policy >] --> EOAlgo[EOAlgo< EOT >]; MWModel -.- scheduler --> Scheduler[paradiseo::smp::Scheduler< Dummy, boost::numeric::interval_lib::policies >];
```

The diagram illustrates the relationships between three C++ classes. A grey box on the right represents `paradiseo::smp::MWModel` with template arguments `< EOAlgo, EOT, Policy >`. A white box at the top left represents `EOAlgo` with template argument `< EOT >`. A white box at the bottom left represents `paradiseo::smp::Scheduler` with template arguments `< Dummy, boost::numeric::interval_lib::policies >`. A solid blue arrow points from the `MWModel` box to the `EOAlgo` box. A dashed purple arrow, labeled "scheduler", points from the `MWModel` box to the `Scheduler` box.