

SPPU FOP B.E COMPUTER(2022)

DEEP LEARNING LAB V

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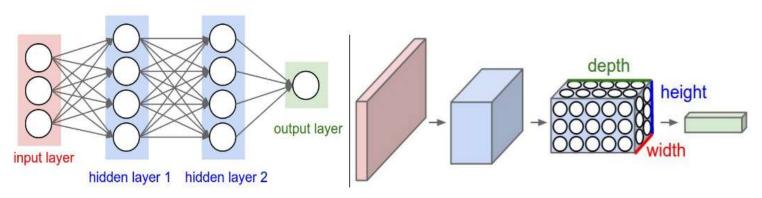


Lab Experiment

Topics:

- 1) Linear regression by using Deep Neural network: Implement Boston housing price prediction problem by Linear regression using Deep Neural network. Use Boston House price prediction dataset.
- 2) Classification using Deep neural network
- 3) Convolutional neural network (CNN)
- 4) Recurrent neural network (RNN)

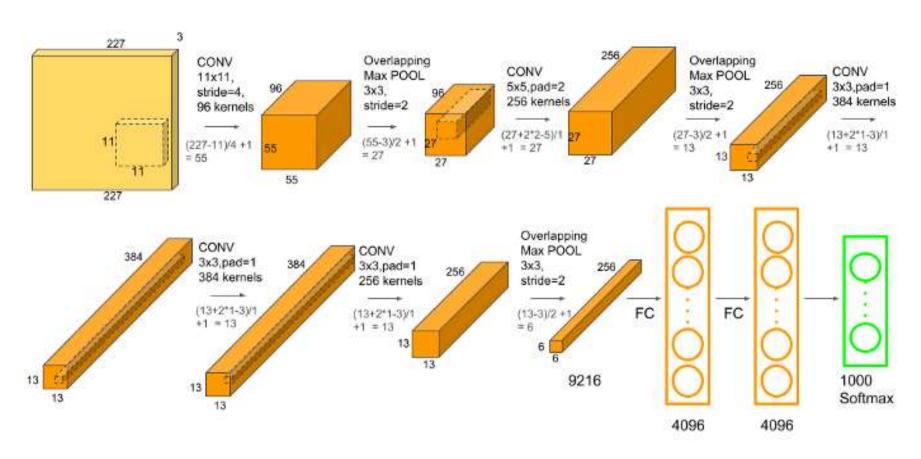
Dense neural network and Convolutional neural network



Left: A regular 3-layer Neural Network. Right: A ConvNet arranges its neurons in three dimensions (width, height, depth), as visualized in one of the layers. Every layer of a ConvNet transforms the 3D input volume to a 3D output volume of neuron activations. In this example, the red input layer holds the image, so its width and height would be the dimensions of the image, and the depth would be 3 (Red, Green, Blue channels).



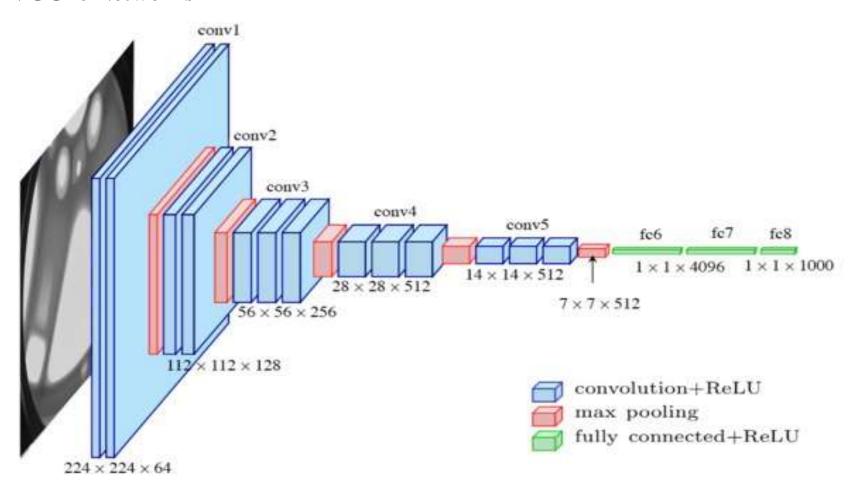
AlexNet Architecture



+

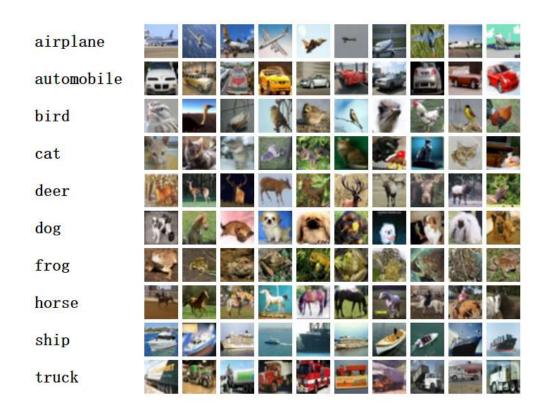


VGG16 Networks



CIFAR10 dataset and state of the art

The CIFAR-10 dataset consists of 60000 32x32 color images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images.



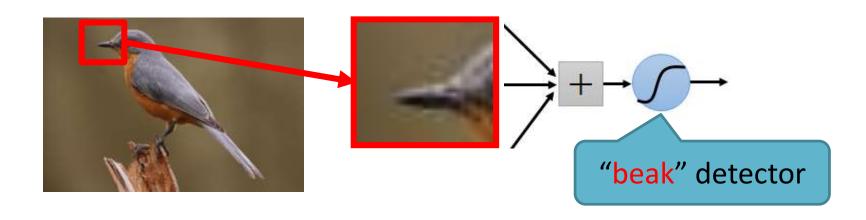
Accuracy

Model	Acc.
VGG16	92.64%
ResNet18	93.02%
ResNet50	93.62%
ResNet101	93.75%
ResNeXt29(32x4d)	94.73%
ResNeXt29(2x64d)	94.82%
DenseNet121	95.04%
PreActResNet18	95.11%
DPN92	95.16%

Consider learning an image:

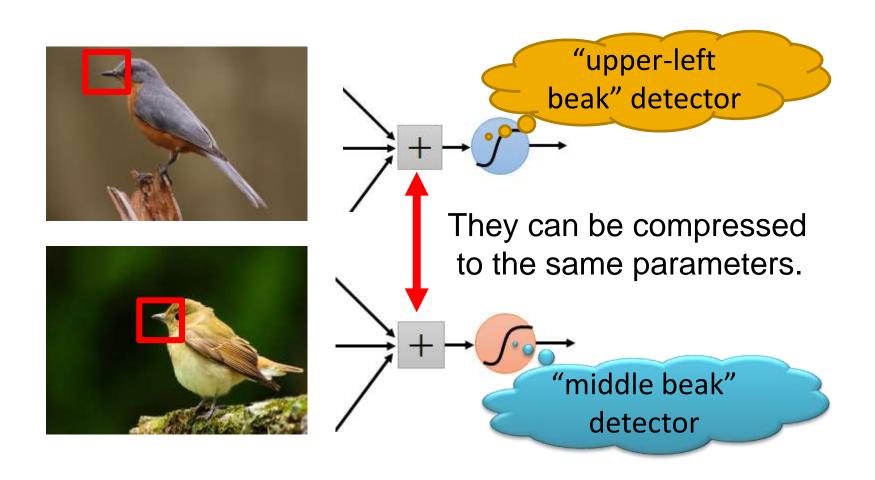
Some patterns are much smaller than the whole image

Can represent a small region with fewer parameters



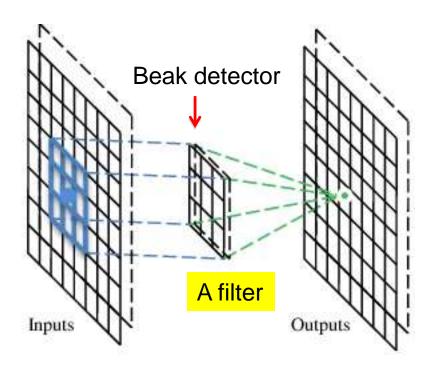
Same pattern appears in different places: They can be compressed!

What about training a lot of such "small" detectors and each detector must "move around".



A convolutional layer

A CNN is a neural network with some convolutional layers (and some other layers). A convolutional layer has a number of filters that does convolutional operation.



Convolution parameters to be learned.

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

: :

Each filter detects a small pattern (3 x 3).

Filter 1

stride=1

1	0	0	0	0	1	Dot
0	1	0	0	1	0	product 3 -1
0	0	1	1	0	0	
1	0	0	0	1	0	
0	1	0	0	1	0	
0	0	1	0	1	0	

6 x 6 image

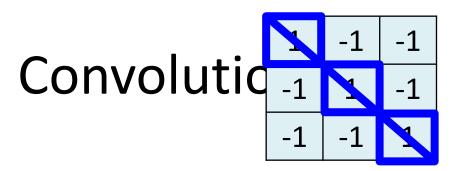
Filter 1

If stride=2

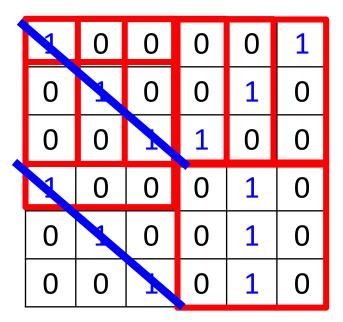
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

3 -3

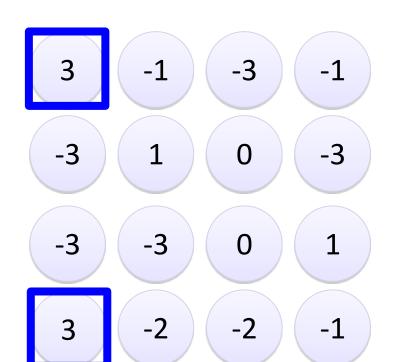
6 x 6 image



stride=1



6 x 6 image



Filter 1

Convolutio

	-1	1	-1
)	-1	1	-1
	-1	1	-1

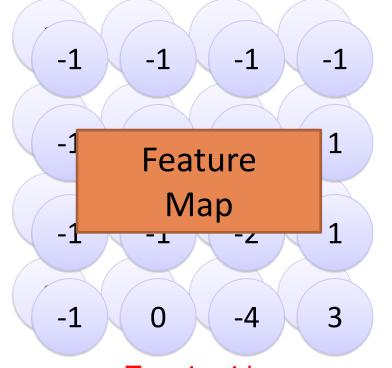
Filter 2

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

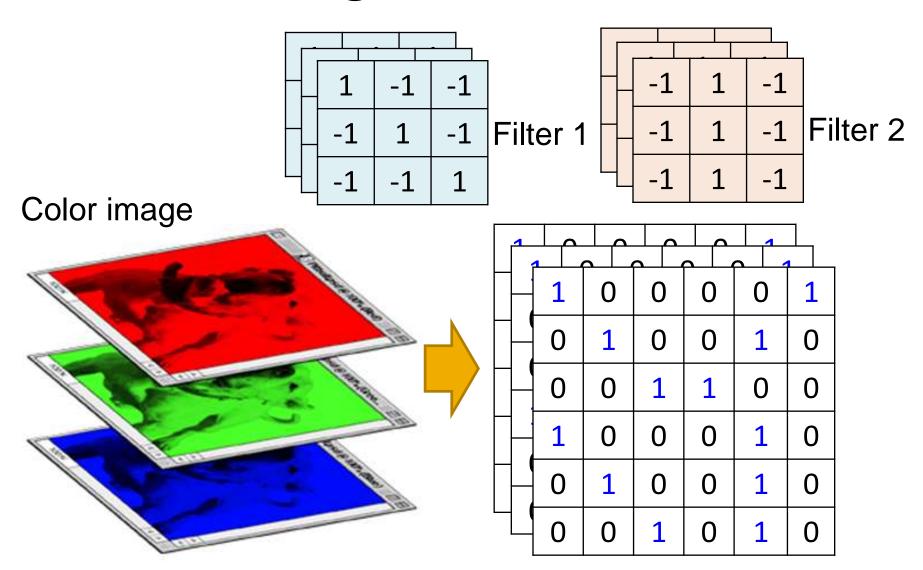
6 x 6 image

Repeat this for each filter

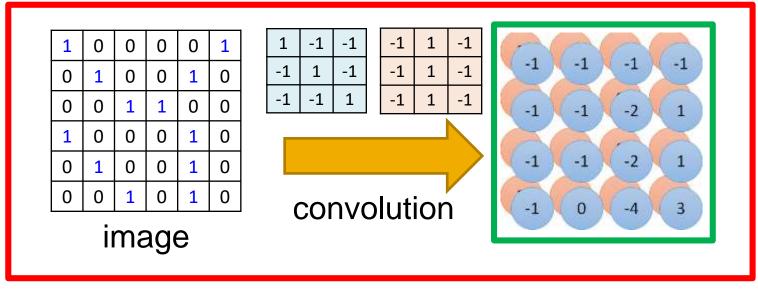


Two 4 x 4 images
Forming 2 x 4 x 4 matrix

Color image: RGB 3 channels

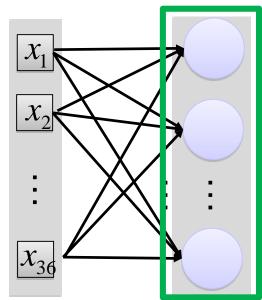


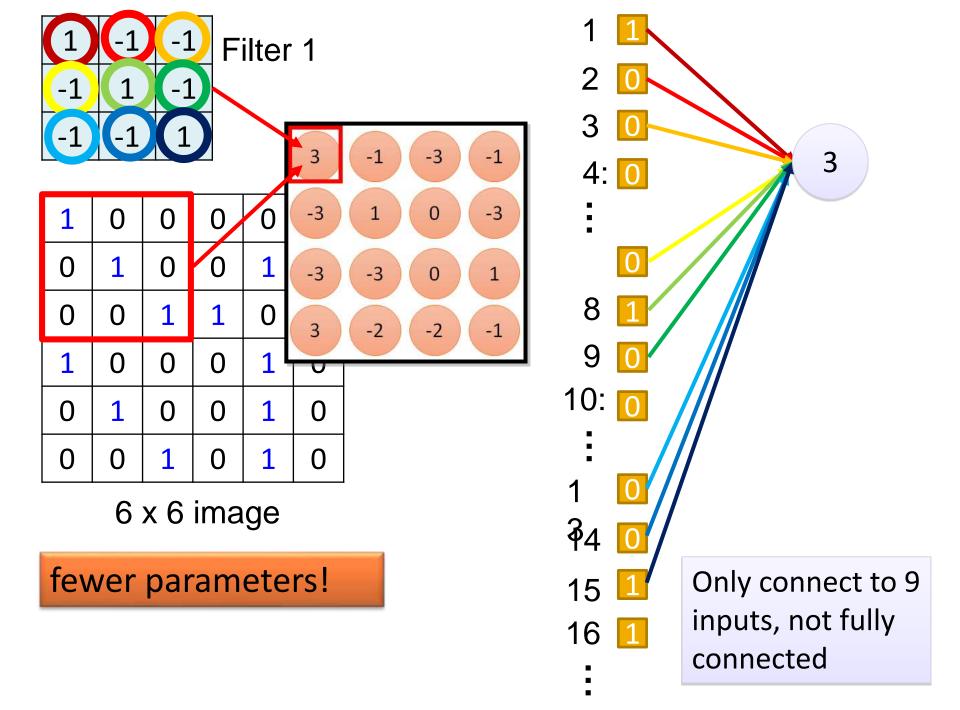
Convolution v.s. Fully Connected

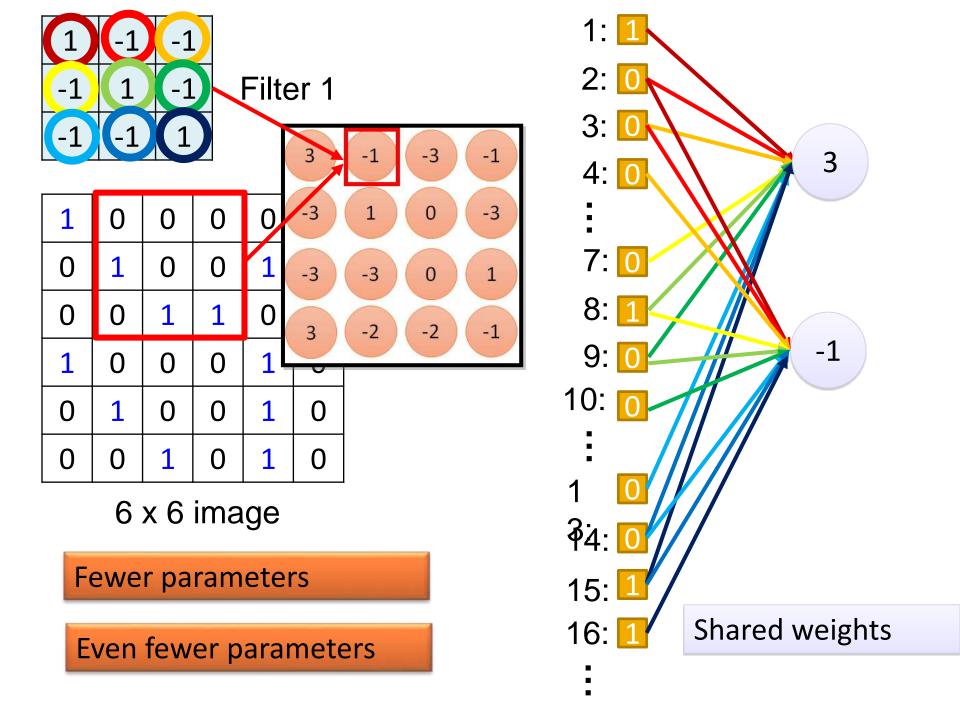


Fullyconnected

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0:
0	0	1	0	1	0



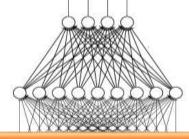




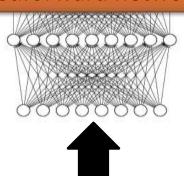
The whole



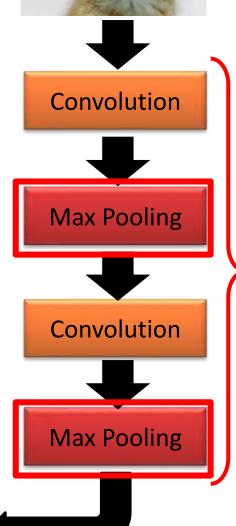




Fully Connected Feedforward network



Flattened



Can repeat many times

Max Pooling

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

3 -1 -1 1	-3 -1 0 -3
-3 -3	0 1
3 -2	-2 -1

Why Pooling

Subsampling pixels will not change the object bird

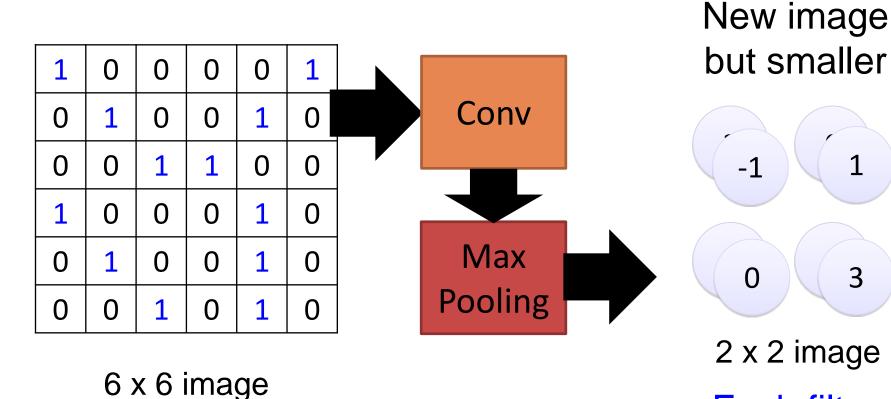


We can subsample the pixels to make image fewer parameters to characterize the image

A CNN compresses a fully connected network in two ways:

- Reducing number of connections
- Shared weights on the edges
- Max pooling further reduces the complexity

Max Pooling



Each filter

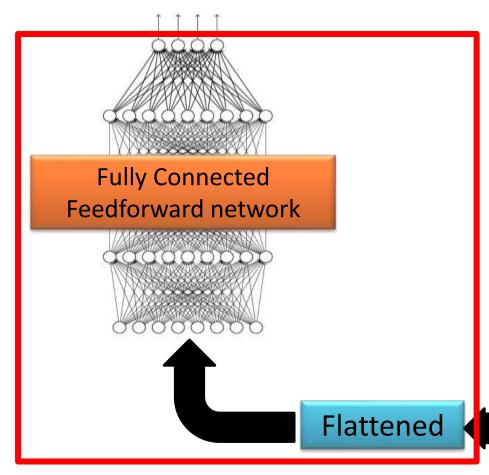
is a channel

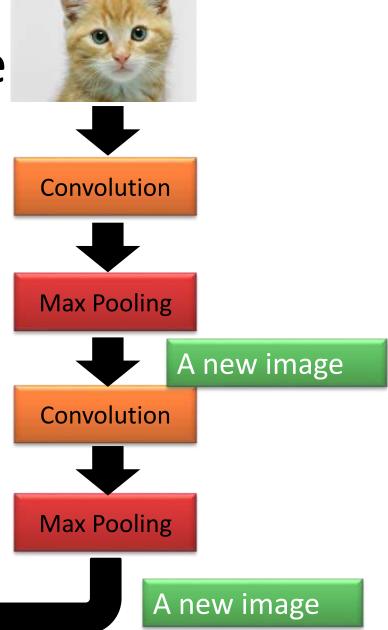
The whole -1 Convolution 0 3 **Max Pooling** Can A new image repeat Convolution many Smaller than the original times image **Max Pooling** The number of channels

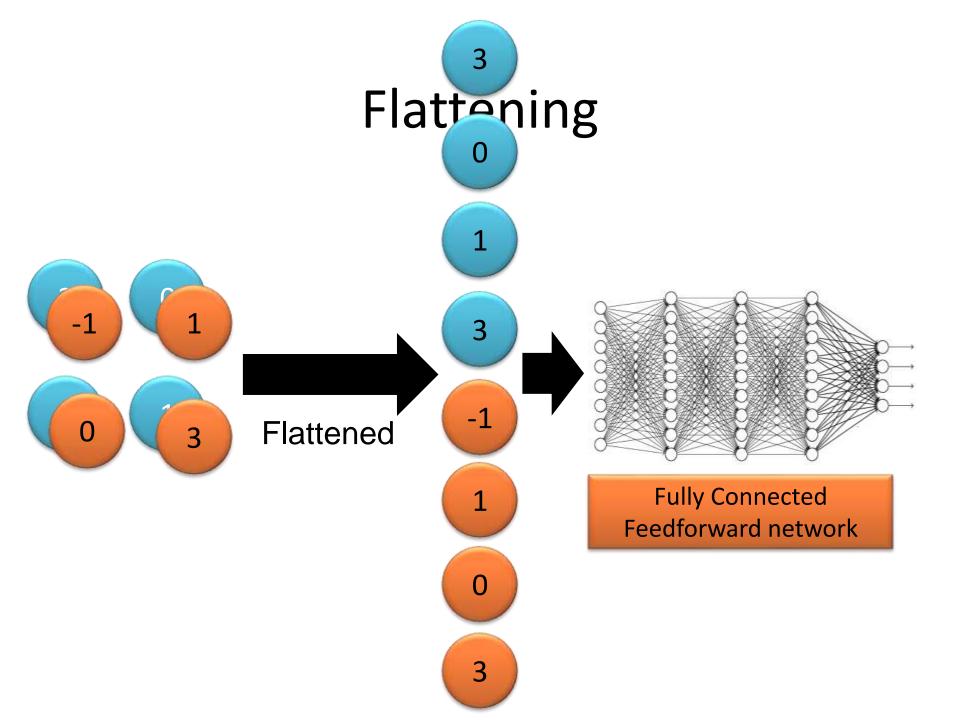
is the number of filters





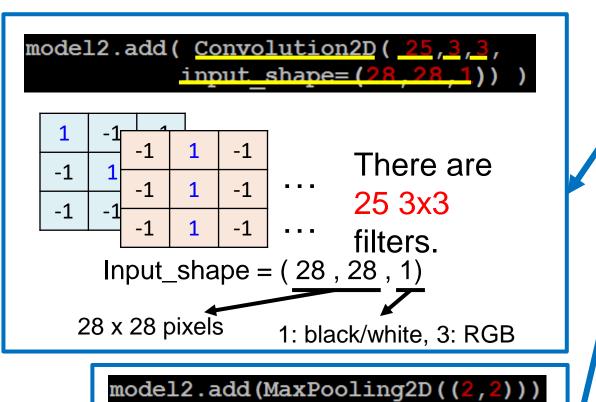


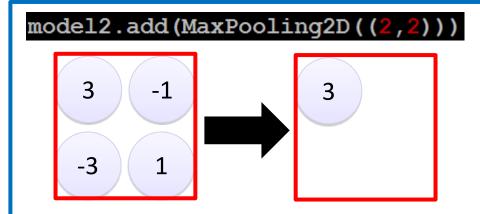


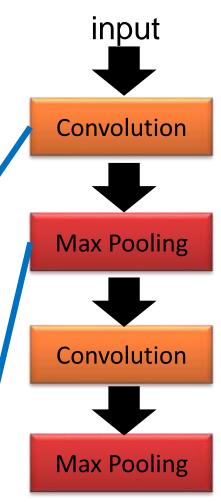


CNN in Keras

Only modified the *network structure* and *input* format (vector -> 3-D tensor)

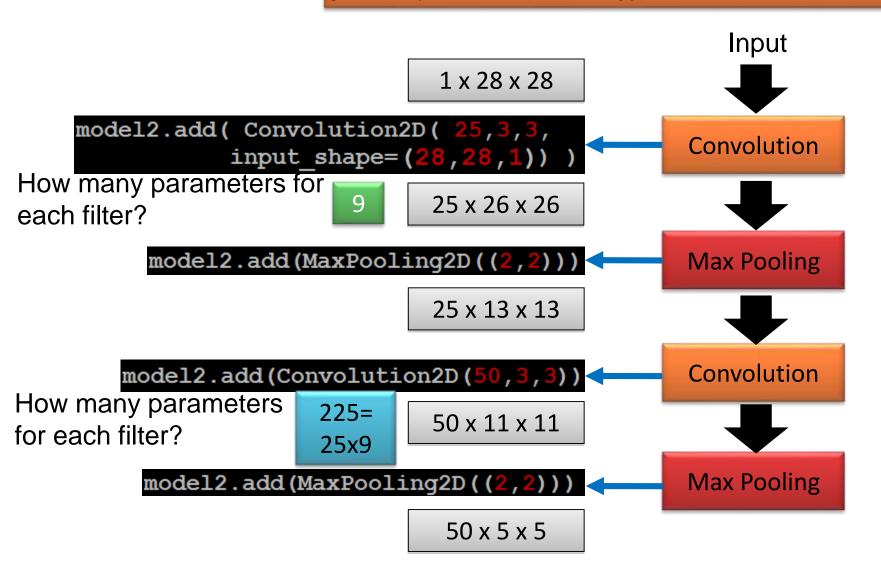






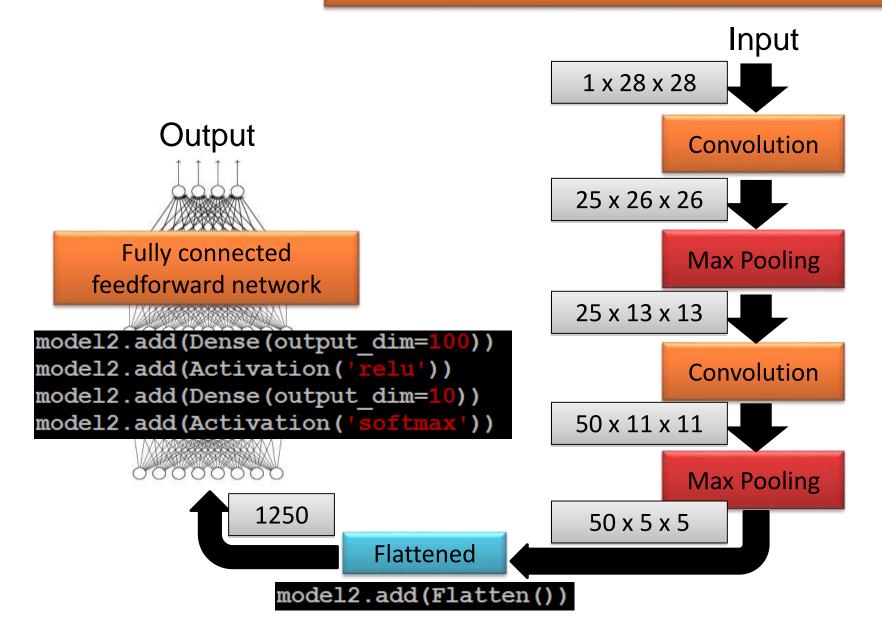
CNN in Keras

Only modified the *network structure* and *input* format (vector -> 3-D array)



CNN in Keras

Only modified the *network structure* and *input* format (vector -> 3-D array)



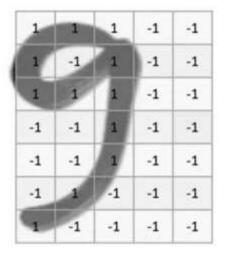


-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	9	-1	-1	-1

-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	1	-1	-1	-1



Location Shifted





	1	1	1	-1	-1
l	1	-1	1	-1	-1
1	1	1	1	-1	-1
	-1	-1	1	-1	-1
	-1	-1	1	-1	-1
	-1	1	-1	-1	-1
	1	-1	-1	-1	-1
- 1					



-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	1	-1	-1	-1



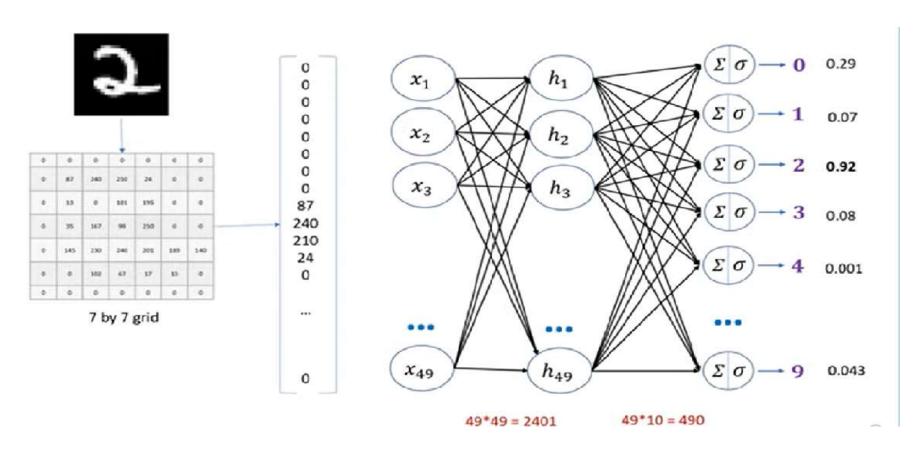






Image size = 1920 x 1080 X 3

First layer neurons = 1920 x 1080 X 3 ~ 6 million

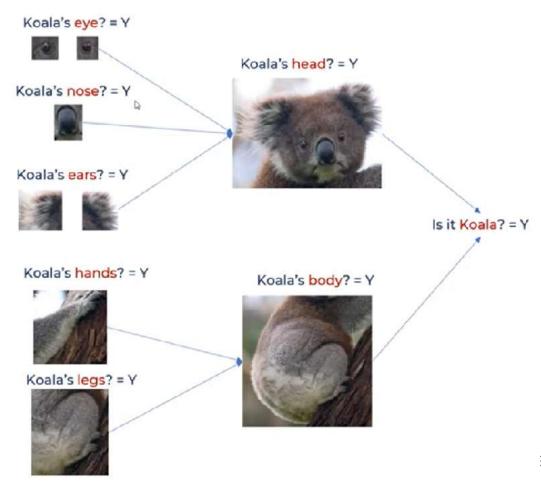
Ð

Hidden layer neurons = Let's say you keep it ~ 4 million

Weights between input and hidden layer = 6 mil * 4 mil = 24 million

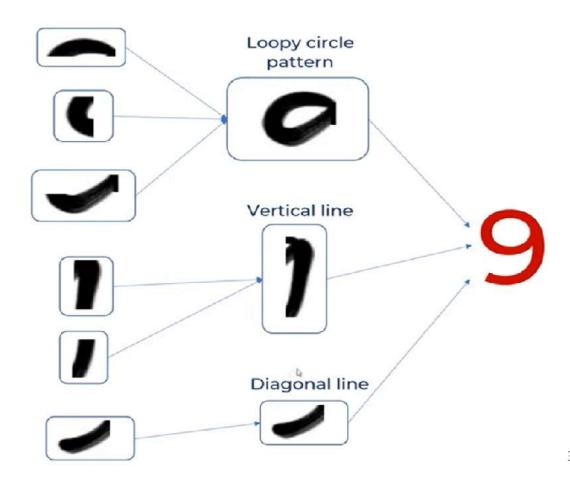








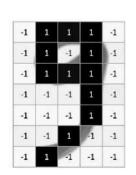


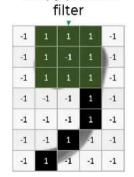


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Loopy pattern





Vertical line filter

Diagonal line filter



$$-1+1+1-1-1-1-1+1+1 = -1 \rightarrow -1/9 = -0.11$$

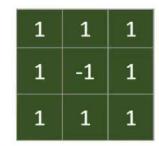
-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	1	-1	-1	-1



-0.11	



-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	1	-1	-1	-1



*

-0.11	1	

13



-1	1	1	1	-1
-1	1	-1	1	-1
-1	1	1	1	-1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
-1	-1	1	-1	-1
-1	1	-1	-1	-1

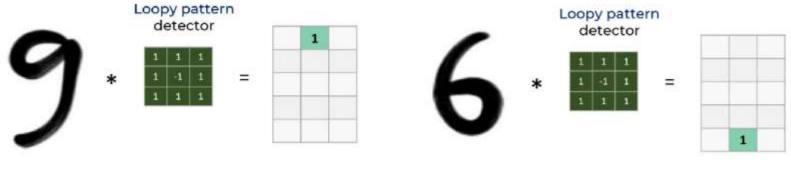


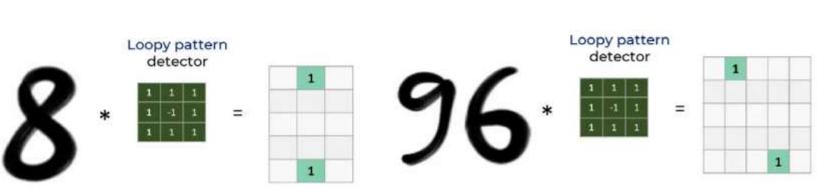
1	1	1
1	-1	1
1	1	1

-0.11	1	-0.11
-0.55	0.11	-0.33
-0.33	0.33	-0.33
-0.22	-0.11	-0.22
-0.33	-0.33	-0.33

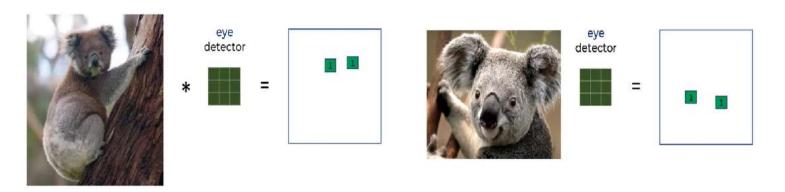
Feature Map

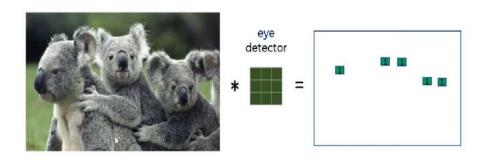




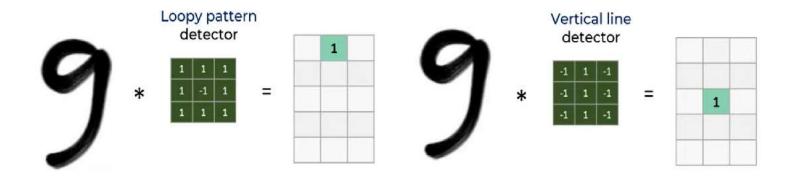


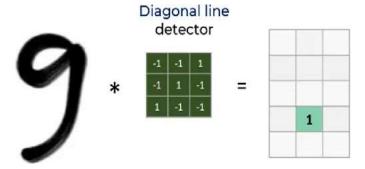




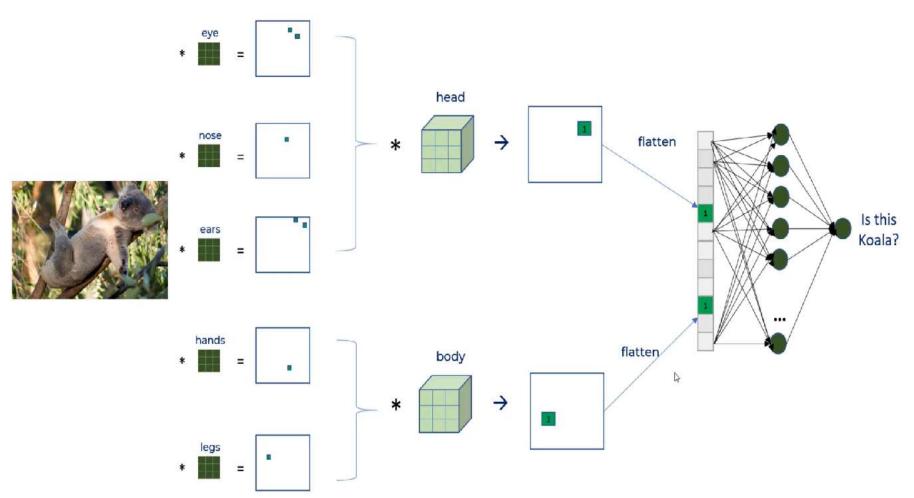




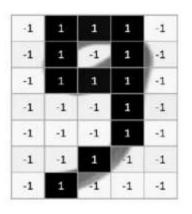






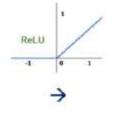






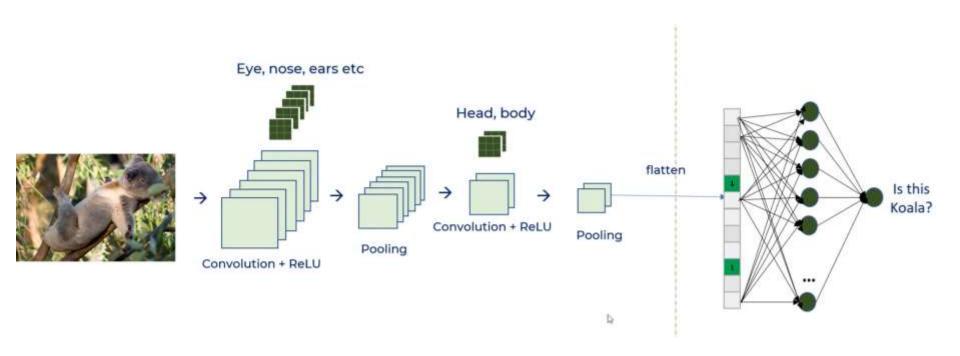




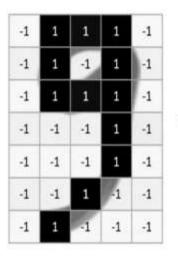


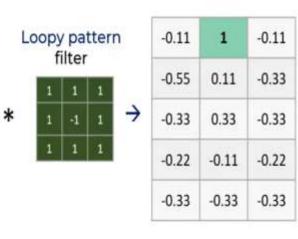
0	1	0
0	0.11	0
0	0.33	0
0	0	0
0	0	0

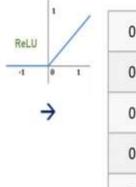




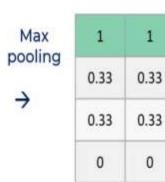






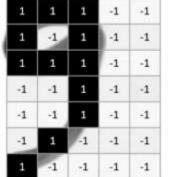


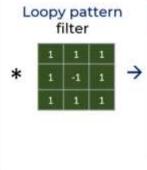
0	1	0
0	0.11	0
0	0.33	0
0	0	0
0	0	0

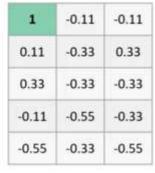


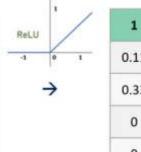


Shifted 9 at different position

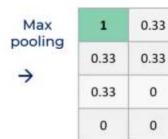








1	0	0
0.11	0	0.33
0.33	0	0
0	0	0
0	0	0



0

0



THANK YOU