Task 1

```
; 1DT301, Computer Technology I
; Date: 2017-09-12
; Author:
; Student name 1: Ruth Dirnfeld
; Student name 2: Alexandra Bjäremo
; Lab number: 2
; Title: Subroutines
; Hardware: STK600, CPU ATmega2560
; Function: Switching between the Ring and the Johnson counters when pressing SWO
; Input ports: On-board switches connected to PORTA.
; Output ports: On-board LEDs connected to PORTB.
; Subroutines: Delay of approximately 0,5 sec in between each count.
; Included files: m2560def.inc
; Other information: Clock set at 1MHz
; Changes in program: File updates: 2017-09-16, 2017-09-18, 2017-09-19
.include "m2560def.inc"
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND); R20 = high part of RAMEND address
out SPH,r20; SPH = high part of RAMEND address
ldi R20, low(RAMEND); R20 = low part of RAMEND address
out SPL,R20; SPL = low part of RAMEND address
ldi r20, 0xFF
out DDRB, r20
                        ; All one's to DDRB, outputs
                        ; starting with LED0
ldi r16, 0xFE
ldi r17, 0x00
                        ; temp register to help with sloop
ldi r23, 0x00
out DDRA, r23
```

```
main:
   ring:
       ldi r23, 0x00
       cpi r16, 0xFF
                             ; checking if all LEDs are off
       breq equal
       out PORTB, r16
                             ; write in PORTB, turning on LEDs
       com r16
                             ; inverting the bits of r16
       Isl r16
                             ; pushing a 0 to the left
       com r16
                             ; inverting the bits of r16 again
       rcall delay
       rjmp ring
                                                                     Start
    equal:
       ldi r16, 0xFE
    rjmp main
                                                                    Switch
                                                                               NO
                                                                   pressed?
; Generated by delay loop calculator
; at http://www.bretmulvey.com/avrdelay.html
; Delay 500 000 cycles
                                                                  Toggle flag
; 500ms at 1 MHz
delay:
    ldi r18, 3
                                                                  Flag = 0?
    ldi r19, 138
    ldi r21,86
                                                                       YES
L1: dec r21
    brne L1
                                                                   Call Ring
                                                                                        Call Johnson
    dec r19
    brne L1
    dec r18
    brne L1
    in r23, PINA
                             ; read PINA
                             ; check if button is pressed
    cpi r23, 0xFE
    breq pressed
    rjmp PC+1
ret
;;;;;;;;;;TASK6
johnsonLeft:
```

; keep track of counters, if 0 then ring, else johnson

ldi r22, 0x00

ldi r23, 0x00

cpi r16, 0x00 ; check if all LEDs are on

breq johnsonRight

out PORTB, r16; write to PORTB

Isl r16 ; pushing 0 to the left to turn on next light aswell

rcall delay

rjmp johnsonLeft

johnsonRight:

ldi r23, 0x00

out PORTB, r16; write to PORTB

cpi r16, 0xFF ; check if all LEDs are off

breg johnsonLeft

mov r17, r16; move r16's bits to r17

com r17 ; invert r17's bits

lsr r17 ; pushing 0 to the right com r17 ; invert r17's bits again mov r16, r17 ; move r17's bits to r16

rcall delay

rjmp johnsonRight

pressed:

com r22 ; invert r22 to change counter

cpi r22,0x00 ; check if counter is set to Ring counter

breq jumpToRing

rjmp jumpToJohnsonLeft

jumpToRing:

ldi r16, 0xFF

out PORTB, r16 ; turn off all LEDs

rjmp ring

jumpToJohnsonLeft:

ldi r16, 0xFF

out PORTB, r16 ; turn off all LEDs

rjmp johnsonLeft

/*Description:

*/

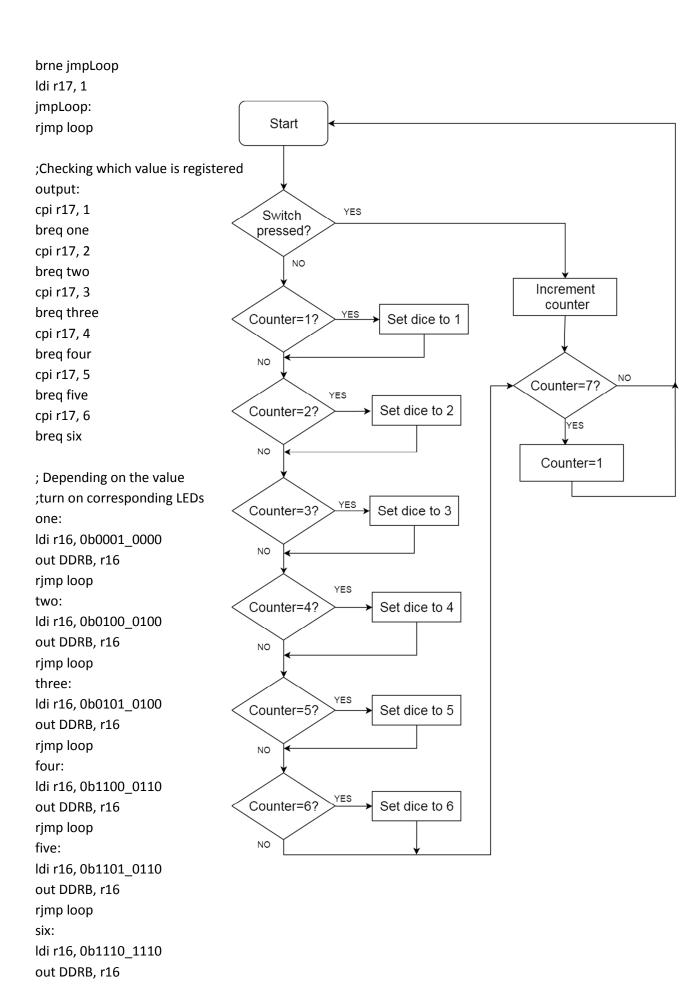
^{*}Starting the main program with the Ring counter, while in the delay phase the switch is checked. If

^{*}the switch has been pressed, then the program the flag is toggled (from 0 to 1 or 1 to 0) so that the

^{*}next counter will start. However, it will turn off all the LEDs before starting the counter.

Task 2

```
; 1DT301, Computer Technology I
; Date: 2017-09-16
; Author:
; Student name 1 Ruth Dirnfeld
; Student name 2 Alexandra Bjäremo
; Lab number: 2
; Title: Subroutines
; Hardware: STK600, CPU ATmega2560
; Function: Rolling the electronical dice by randomly generating the number
; with the switch
; Input ports: On-board switches connected to PORTA.
; Output ports: On-board LEDs connected to PORTB.
; Subroutines: Loops to help with the rolling of the dice and outputting.
; Included files: m2560def.inc
; Other information: Clock set at 1MHz
; Changes in program: None
.include "m2560def.inc"
ldi r16, 0xFF
out DDRB, r16
                         ; All one's to DDRB, output
ldi r16, 0x00
out DDRA, r16
                          ; All zero's to DDRA, input
ldi r17,1
                          ; r17 to help with output
loop:
in r18, PINA
                          ; read PINA
cpi r18, 0xFF
                          ; check if button is pressed
breq output
inc r17
                          ; increment r17
cpi r17, 7
                          ; check if value is 7
```



```
rjmp loop
/*Description:

*Checking if the switch is pressed, then incrementing the counter until it reaches 7 then resetting it

*to 1 and turning on the corresponding LEDs. This will generate a visual effect that resembles two

*dice.

*/
```

Task 3

```
;>>>>>>>>>>>>>>>>>
; 1DT301, Computer Technology I
; Date: 2017-09-17
; Author:
; Student name 1 Ruth Dirnfeld
; Student name 2 Alexandra Bjäremo
; Lab number: 2
; Title: Subroutines
; Hardware: STK600, CPU ATmega2560
; Function: A program that is able to count the number of changes on a switch.
; Input ports: On-board switches connected to PORTA.
; Output ports: On-board LEDs connected to PORTB.
; Subroutines: None.
; Included files: m2560def.inc
; Other information: Using a loop to make the counter work infinitely.
                 Clock set at 1MHz.
; Changes in program: File created - 2017-09-18.
.include "m2560def.inc"
.def counter = r17
ldi counter, 0x00
rjmp main
```

Start switch: inc counter ; pushed loop: in r16, PINA ; read PINA Read switch cpi r16, 0xFF ; release all switches brne loop inc counter ; released SW₀ NO out DDRB, counter pressed? YES main: in r16, PINA ; read PINA cpi r16, 0xFE ; switch 0 is pushed Increment breq switch counter rjmp main Turn on LEDs /*Description: *Reading the switch 0 to see if it is pressed. If it is

Reading the S

*/

Task 4

```
;>>>>>>>>>>>>
; 1DT301, Computer Technology I
; Date: 2017-09-18
; Author:
; Student name 1 Ruth Dirnfeld
; Student name 2 Alexandra Bjäremo
;
; Lab number: 2
; Title: Subroutines.
;
; Hardware: STK600, CPU ATmega2560
;
; Function: Adaptation of Ring counter, in which the delay is changeable depending
; on the decided input
;
; Input ports: None.
;
```

^{*}pressed the counter increases by one and is then ported to the LEDs. Otherwise it waits.

```
; Output ports: On-board LEDs connected to PORTB.
; Subroutines: Delay that is changeable.
; Included files: m2560def.inc
; Other information: Clock set at 1MHz.
; Changes in program: None.
.include "m2560def.inc"
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND); R20 = high part of RAMEND address
out SPH,r20; SPH = high part of RAMEND address
ldi R20, low(RAMEND); R20 = low part of RAMEND address
out SPL,R20; SPL = low part of RAMEND address
ldi r20, 0xFF
out DDRB, r20
                          ; All one's to DDRB, outputs
ldi r16, 0xFE
                           ; starting with LED0
floop:
cpi r16, 0xFF
                          ; checking if all LEDs are off
breq equal
out PORTB, r16
                          ; write in PORTB, turning on LEDs
com r16
                           ; inverting the bits of r16
Isl r16
                           ; pushing a 0 to the left
                           ; inverting the bits of r16 again
com r16
ldi r24, low(600)
                          ; Loading integer to register pair r25:r24
ldi r25, high(600)
rcall wait_milliseconds
                          ; Call the wait_milliseconds subroutine
rjmp floop
equal:
ldi r16, 0xFE
rjmp floop
```

; Depending on the integer value set in the registers the ; delay will either increase or decrease Start wait_milliseconds: L: ldi r20, low(600) ; loading part of the integer ; loading part of the integer ldi r21, high(600) Load value into registers L1: dec r20 ; decrement r20 nop Decrement brne L1 registers dec r21 ; decrement r21 nop brne L1 NO Registers' values sbiw r25:r24, 1 ; substract immediate from word 0x00? brne L YES ret Stop

DELAY FLOWCHART

/*Description:

*/

^{*}The program starts a Ring counter that will be turning on one LED at a time, while turning off the

^{*}previous one. The speed with which this will be done depends on the value set in the delay. In the

^{*}delay the value is split into two registers and then the registers are being decremented until their

^{*}values are 0x00 at which point the program returns to the ring counter loop.