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; 1DT301, Computer Technology I
; Date: 2016-09-11
; Author:
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; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
; Hardware: STK600, CPU ATmega2560
; Function: Describe the function of the program, so that you can understand it,
; even if you're viewing this in a year from now!
; Input ports: Describe the function of used ports, for example on-board switches
; connected to PORTA.
; Output ports: Describe the function of used ports, for example on-board LEDs
; connected to PORTB.
; Subroutines: If applicable.
; Included files: m2560def.inc
; Other information:
; Changes in program: (Description and date)
Task1
                                                                Start
.include "m2560def.inc"
                         ;include file for Atmega 2560
ldi r16, 0b00000100
out DDRB, r16
                         ; One one to DDRB, input
                                                               LED#2
                                                                          no
                                                               lights up
*Description:
*Using the only corresponding LED as input through
                                                                    yes
*Register 16
*Minimum instructions used in this case: 2
*/
                                                                End
```

Task2

.include "m2560def.inc"

ldi r16, 0xFF

out DDRB, r16; All one's to DDRB, outputs

ldi r16, 0b00000000

out DDRA, r16 ; All zero's to DDRA, inputs

loop:

in r16, PINA ; read PINA out PORTB, r16 ; write in PORTB

rJmp loop

/*Description:

*Using DDRB as output and DDRA as input, so that when pressing one of the switches the

*corresponding LED will be lighted up

*/

Task3

.include "m2560def.inc"

ldi r16, 0b00000001 ; One one to DDRB, output

out DDRB, r16

ldi r16, 0b11011111 ; One zero to DDRA, input

out DDRA, r16

loop:

ldi r16, 0b11111111

out PORTB, r16 ; turn off all LEDs in r16, PINA ; read PINA

cpi r16, 0 ; check if switch is pressed

brne loop ; restart loop

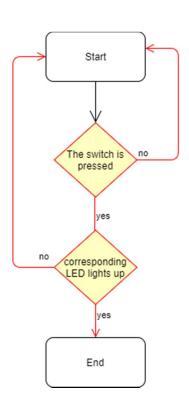
ldi r16, 0b11111110

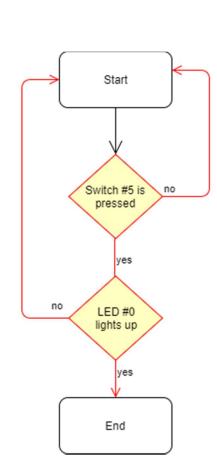
out PORTB,r16; turn on LED0

rJmp loop

/*Description:

* Using only the first LED (LED0) as output and switch 5(SW5) as input.





* Checking if the correct switch is pressed and if it is, light up LED0, otherwise does nothing.
*/

Task 5

brne L1

```
.include "m2560def.inc"
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND); R20 = high part of RAMEND address
out SPH,r20; SPH = high part of RAMEND address
ldi R20, low(RAMEND); R20 = low part of RAMEND address
out SPL,R20; SPL = low part of RAMEND address
ldi r20, 0xFF
out DDRB, r20
                         ; All one's to DDRB, outputs
ldi r16, 0xFE
                         ; starting with LED0
floop:
                                                                           START
cpi r16, 0xFF
                        ; checking if all LEDs are off
breq equal
out PORTB, r16
                        ; write in PORTB, turning on LEDs
com r16
                         ; inverting the bits of r16
Isl r16
                         ; pushing a 0 to the left
                                                                       TURN ON FIRST
com r16
                         ; inverting the bits of r16 again
                                                                           LED
rjmp delay
rjmp floop
equal:
ldi r16, 0xFE
                                                                        TURN ON NEXT
                                                                            LED
rjmp floop
; Generated by delay loop calculator
; at http://www.bretmulvey.com/avrdelay.html
                                                                                         YES
                                                                NO
; Delay 500 000 cycles
                                                                         IS THE LAST
                                                                          LED ON
; 500ms at 1 MHz
delay:
   ldi r18, 3
   ldi r19, 138
   ldi r21, 86
L1: dec r21
```

dec r19 brne L1 dec r18 brne L1 rjmp PC+1

rjmp floop

/*Description:

- * Using DDRB as output, we light up LED0. Checking if all LEDs are off we start writing in PORTB and
- * turn the LEDs on by pushing a 0 with the Logical Shift Left to the left side.

*/

Task 6

.include "m2560def.inc"

; Initialize SP, Stack Pointer

ldi r20, HIGH(RAMEND); R20 = high part of RAMEND address

out SPH,r20; SPH = high part of RAMEND address

ldi R20, low(RAMEND); R20 = low part of RAMEND address

out SPL,R20; SPL = low part of RAMEND address

ldi r20, 0xFF

out DDRB, r20; All one's to DDRB, outputs

ldi r16, 0xFE ; turn on LED0

ldi r17, 0x00; temp register to help with sloop

floop:

cpi r16, 0x00 ; check if all LEDs are on

breq sloop

out PORTB, r16 ; write to PORTB

Isl r16 ; pushing 0 to the left

rcall delay rjmp floop

sloop:

out PORTB, r16 ; write to PORTB

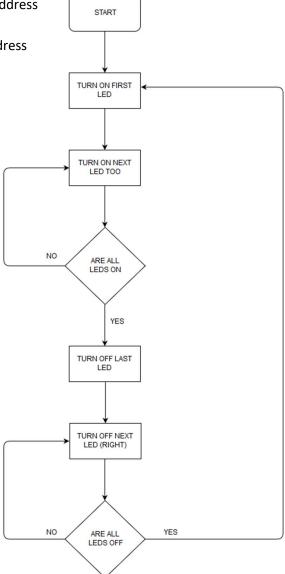
cpi r16, 0xFF ; check if all LEDs are off

breq floop

mov r17, r16; move r16's bits to r17

com r17 ; invert r17's bits

lsr r17; pushing 0 to the right



```
com r17
                ; invert r17's bits again
mov r16, r17
                ; move r17's bits to r16
rcall delay
rjmp sloop
; Generated by delay loop calculator
; at http://www.bretmulvey.com/avrdelay.html
; Delay 500 000 cycles
; 500ms at 1 MHz
delay:
   ldi r18, 3
   ldi r19, 138
   ldi r21,86
L1: dec r21
   brne L1
   dec r19
   brne L1
   dec r18
   brne L1
   rjmp PC+1
ret
```

/*Description:

- * Using DDRB as output, we light up LED0. Checking if all LEDs are off we start writing in PORTB and
- * turn the LEDs on by pushing a 0 with the Logical Shift Left to the left side. Writing to PORTB we
- * check if all LEDs are off and move the register 16 bits to register 17 and invert it's bits and push 0's
- * to the right. Inverting the r17's bits again and moving r17's bits to r16. At the end returning to
- * subroutine.

*/