

# Embedded System

## Lecture Note 3. Introductory Example /DSC (Digital Still Camera)

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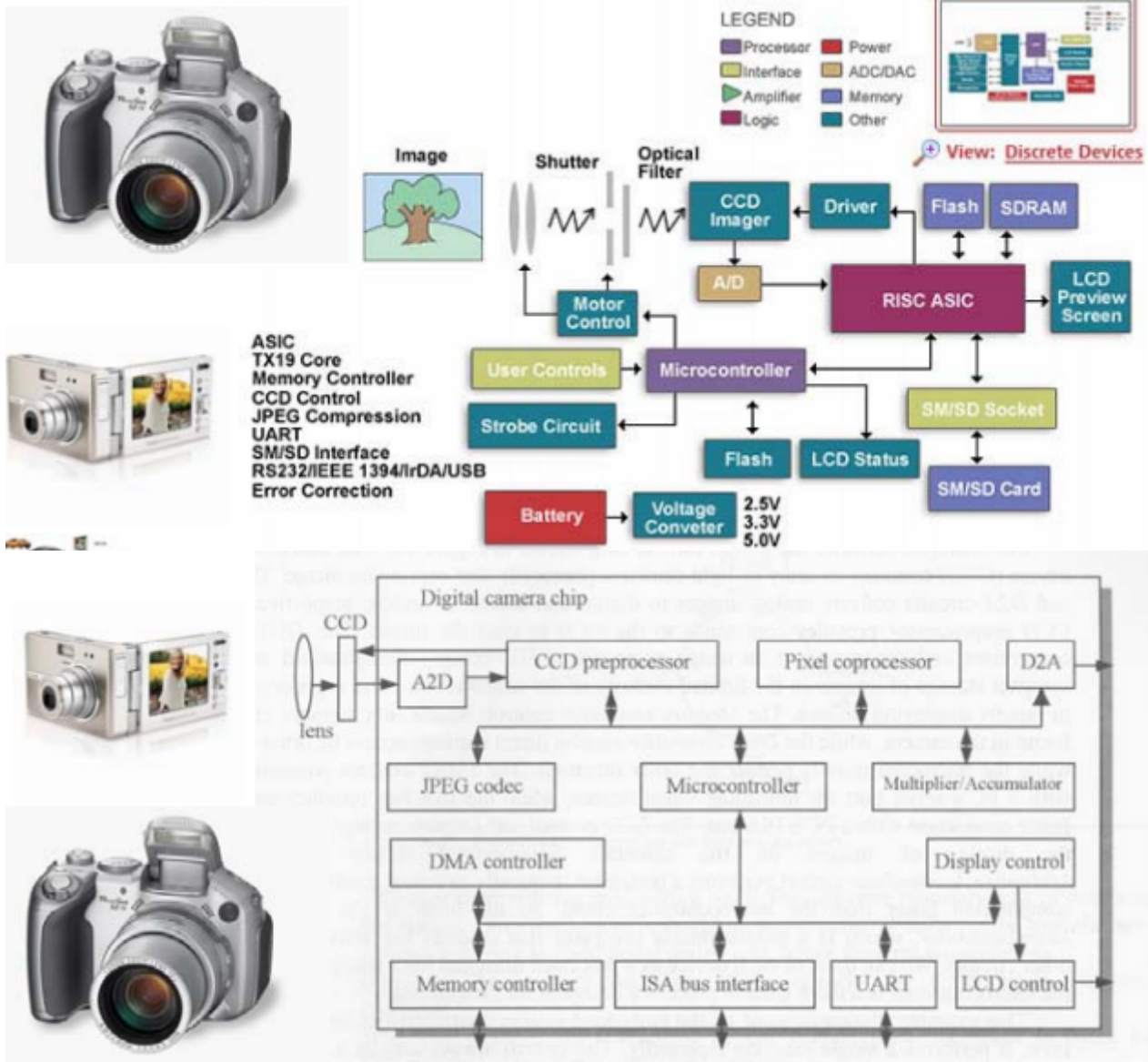
tags: Embedded

—  Chenging  Fri, Apr 30, 2021

- Embedded System Lecture Note 3. Introductory Example /DSC (Digital Still Camera).
  - Introduction to Digital Camera
  - A. Background Information
    - a. Digital Still Camera (DSC).
    - b. Main operations (simplified).
    - c. Auxiliary operations (simplified).
    - d. Structure of digital camera
  - B. Introduction of Main operations
    - 1. Capture of Image – CCD (Charged Coupled Device).
    - 2. Image Processing - Compression
    - 3. Image Processing – DCT
    - 4. Image Processing – more on DCT
    - 5. Image Processing – DCT Formula
    - 6. Image Processing – Implementation of DCT
    - 7. Image Processing – Quantization
    - 8. Image Processing – Hoffman Encoding.
  - C. The List of Requirements
  - D. The List of Specifications
  - E. The Design
- Different Implementation
  - Implementation 1 – Microcontroller (micro C) alone:
  - Implementation 2 – micro C + H/W Function Unit:
  - Implementation 3 – micro C + H/W Function Unit:
  - Implementation 4 –  $\mu$ C + H/W Function Units:
  - Comparison and Discussion

## Introduction to Digital Camera

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## A. Background Information

### a. Digital Still Camera (DSC)

1. typical consumer embedded system product
2. Captures and stores pictures in digital format

### b. Main operations (simplified)

1. Converts image obtained from CCD device to digital form
  - (1) Autofocus (A/F)
  - (2) Auto-Exposure (A/E)
  - (3) Zero-bias adjustment
2. Image processing

- (1) White balancing
- (2) Color reproduction

### 3. Compression (store the image in JPG format)

- (1) FDCT (Forward Discrete Cosine Transformation)
- (2) Quantization
- (3) Huffman encoding

### 4. Image archiving (storing)

#### c. Auxiliary operations (simplified)

1. Pre-viewing images
2. Storing images
3. Transferring images

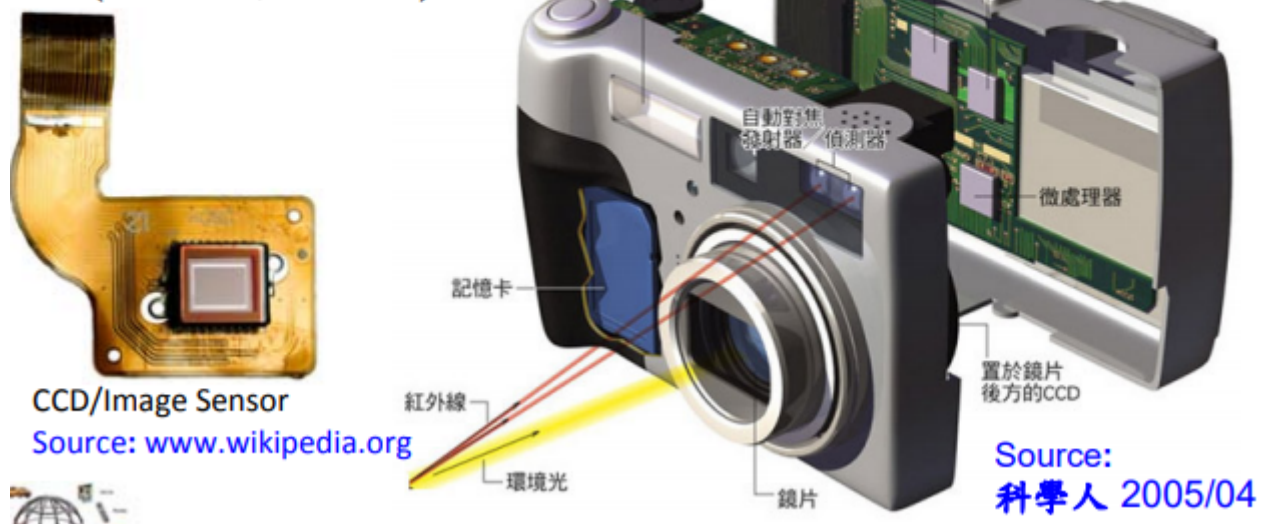
#### d. Structure of digital camera

## Background Information:

(4/20)

### Structure of digital camera

(Ref: 科學人雜誌)

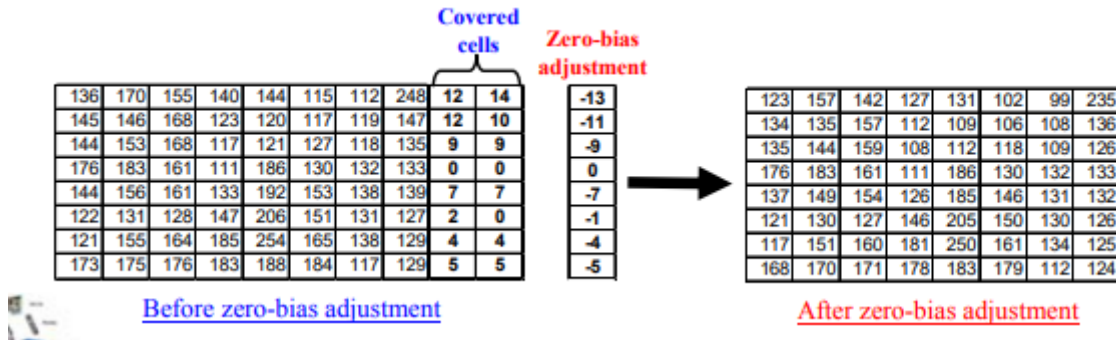


## B. Introduction of Main operations

### 1. Capture of Image – CCD (Charged Coupled Device)

- Special sensor that captures an image
- Light-sensitive silicon solid-state device composed of many cells (usually arranged in a two-dimension array)

- Primary stages in image generation:
  - Step 1. charge generation
  - Step 2. collection and storage of the liberated charge
  - Step 3. charge transfer
  - Step 4. charge measurement
- Zero-Bias Adjustment



- Image Processing – Compression
- JPEG (Joint Photographic Experts Group)
- A standard format for digital images in a compressed form
- Image data divided into blocks of 8 x 8 pixels
- 3 steps performed on each block
  - Step 1. DCT (Discrete Cosine Transform: FDCT/IDCT)
  - Step 2. Quantization
  - Step 3. Huffman encoding (Variable length encoding)

## 2. Image Processing - Compression

- Save space for storage and time for transmission
- Lossless or lossy (non-lossless)
- JPEG (Joint Photographic Experts Group)
  - A standard format for digital images in a compressed form
  - Image data divided into blocks of 8 x 8 pixels
  - 3 steps performed on each block
    - DCT (Discrete Cosine Transform: FDCT/IDCT)
    - Quantization
    - Huffman encoding (Variable length encoding)

## 3. Image Processing – DCT

- Discrete Cosine Transform
- Transforms original 8 x 8 block into the domain of cosine-frequency
  - Upper-left corner values represent more of the essence
  - Lower-right corner values represent finer details

- Can reduce precision and retain reasonable image quality
- DCT (Discrete Cosine Transformation)
  - FDCT (Forward DCT): Encoding
  - IDCT (Inverse DCT): Decoding [not needed here]
- Computation intensive

#### 4. Image Processing – more on DCT

- Popular applications:
  - ❖ Solving P. D. E.
  - ❖ Signal and image processing for lossy data compression
    - ☑ image compression: JPEG
    - ☑ video compression: MJPEG, MPEG, DV
- 8 standard DCT variants and 4 are commonly used
- Most common: DCT-II (FDCT) and DCT-III (IDCT)
- JPEG: Computation, quantization, entropy encoding
  - ❖ Two dimensional DCT-II of  $N \times N$  blocks ( $N$ : typically 8)
  - ❖ DCT-II:  $X_k = \sum_{n=0}^{N-1} x_n \cos \left[ \frac{\pi}{N} \left( n + \frac{1}{2} \right) k \right] \quad k = 0, \dots, N - 1.$
  - ❖ Multidimensional DCT (similar as in this example)

#### 5. Image Processing – DCT Formula

- FDCT (Forward DCT)

- ❖ Auxiliary function:

$$C(h) = \text{if } (h == 0) \text{ then } (1/\sqrt{2}) \text{ else } 1.0$$

- ❖ Main function:

$$F(u, v) = \frac{1}{4} \times C(u) \times C(v) \times$$

pixel value at  
(x, y)

$$\sum_{x=0..7} \sum_{y=0..7} D_{xy} \times \cos(\pi(2x+1)u/16) \times \cos(\pi(2y+1)v/16)$$

#### 6. Image Processing – Implementation of DCT

```

1  static double IMG_A[8][8], IMG_B[8][8];
2  void FDCT(void){
3      int u, v, x, y;
4      double r, sum;
5      for (u = 0; u < 8; u++){
6          for (v = 0; v < 8; v++){
7              cu = u ? 1.0 : (1.0/sqrt(2.0));
8              cv = v ? 1.0 : (1.0/sqrt(2.0));
9              for (x = 0; x < 8; x++){
10                 for (y = 0; y < 8; y++){
11                     r = r + IMG_A[x][y] * cos(3.1416*(2*y+1)*v/16.0);
12                 }
13                 sum = sum + r*cos(3.1416*(2*x+1)*u/16.0);
14             }
15         }
16         IMG_B[u][v] = 0.25*cu*cv*sum;
17     }
18 }

```

### ✧ Implementing FDCT:

- ❑ Using table look-up
- ❑ Using fixed-point arithmetic
  - Floating-point values are multiplied by 32,768 and rounded to nearest integer
  - 32,768 chosen in order to store each value in 2 bytes of memory
- ❑ Loop unrolling

```

static short ONE_OVER_SQRT_TWO = 23170;
static double COS(int xy, int uv) {
    return COS_TABLE[xy][uv] / 32768.0;
}
static double C(int h) {
    return h ? 1.0 : ONE_OVER_SQRT_TWO / 32768.0;
}

```

```

static const short COS_TABLE[8][8] = {
    { 32768, 32138, 30273, 27245, 23170, 18204, 12539, 6392 },
    { 32768, 27245, 12539, -6392, -23170, -32138, -30273, -18204 },
    { 32768, 18204, -12539, -32138, -23170, 6392, 30273, 27245 },
    { 32768, 6392, -30273, -18204, 23170, 27245, -12539, -32138 },
    { 32768, -6392, -30273, 18204, 23170, -27245, -12539, 32138 },
    { 32768, -18204, -12539, 32138, -23170, -6392, 30273, -27245 },
    { 32768, -27245, 12539, 6392, -23170, 32138, -30273, 18204 },
    { 32768, -32138, 30273, -27245, 23170, -18204, 12539, -6392 }
};

```

```

static int FDCT(int u, int v, short img[8][8]) {
    double s[8], r = 0; int x;
    for(x=0; x<8; x++) {
        s[x] = img[x][0] * COS(0, v) + img[x][1] * COS(1, v) +
            img[x][2] * COS(2, v) + img[x][3] * COS(3, v) +
            img[x][4] * COS(4, v) + img[x][5] * COS(5, v) +
            img[x][6] * COS(6, v) + img[x][7] * COS(7, v);
    }
    for(x=0; x<8; x++) r += s[x] * COS(x, u);
    return (short) (r * .25 * C(u) * C(v));
}

```

- Translating a real value to a fixed-point representation
  - Multiply real value by  $2^{\#}$  (# of bits used for fractional part)
  - Round to nearest integer
- Example : 3.14 as 8-bit integer with 4 bits for fraction
  - $2^4 = 16$
  - $3.14 * 16 = 50.24 = 50 = 00110010$
  - $16(2^4)$  possible values for fraction, each represents  $1/16$
  - The last 4 bits (0010) = 2  $\Rightarrow 2 * 0.0625(1/16) = 0.125$



- $3 (0011) + 0.125 = 3.125$  與  $3.14$  算相近  
more bits for fraction would increase accuracy

注意乘法會較加法不精準

### Addition

\* Adding integer representations

#### Example:

$$3.14 + 2.71 = 5.85$$

$$3.14 \rightarrow 50 = 00110010$$

$$2.71 \rightarrow 43 = 00101011$$

$$50 + 43 = 93 = 01011101$$

$$5(0101) + 13(1101) \times 0.0625 \\ = 5.8125 \approx 5.85$$

### Multiplication

1. Multiply integer representations

2. Shift result right by # of bits in fractional part

#### Example:

$$3.14 \times 2.71 = 8.5094$$

$$50 \times 43 = 2150 = 100001100110$$

$$>> 4 = 10000110$$

$$8(1000) + 6(0110) \times 0.0625 \\ = 8.375 \approx 8.5094$$

## Image Processing – FDCT

- COS\_TABLE gives 8-bit fixed-point representation of cosine values
- 6 bits used for fractional portion
- Result of multiplications shifted right 6 bits

```
static unsigned char C(int h) {
    return h ? 64 : ONE_OVER_SQRT_TWO;
}
static int F(int u, int v, short img[8][8]) {
    long s[8], r = 0;
    unsigned char x, j;
    for(x=0; x<8; x++) {
        s[x] = 0;
        for(j=0; j<8; j++)
            s[x] += (img[x][j] * COS_TABLE[j][v]) >> 6;
    }
    for(x=0; x<8; x++) r += (s[x] * COS_TABLE[x][u]) >> 6;
    return (short)(((((r * ((16 * C(u)) >> 6) * C(v)) >> 6) >> 6) >> 6));
}
```

```
static const char code COS_TABLE[8][8] = {
    { 64, 62, 59, 53, 45, 35, 24, 12 },
    { 64, 53, 24, -12, -45, -62, -59, -35 },
    { 64, 35, -24, -62, -45, 12, 59, 53 },
    { 64, 12, -59, -35, 45, 53, -24, -62 },
    { 64, -12, -59, 35, 45, -53, -24, 62 },
    { 64, -35, -24, 62, -45, -12, 59, -53 },
    { 64, -53, 24, 12, -45, 62, -59, 35 },
    { 64, -62, 59, -53, 45, -35, 24, -12 }};
```

```
static const char ONE_OVER_SQRT_TWO = 5;
static short xdata inBuffer [8][8],
            outBuffer[8][8], idx;
void CodecInitialize(void) { idx = 0; }
```

```
void CodecPushPixel(short p) {
    if( idx == 64 ) idx = 0;
    inBuffer[idx / 8][idx % 8] = p << 6; idx++;
}
```

```
void CodecDoFdct(void) {
    unsigned short x, y;
    for(x=0; x<8; x++)
        for(y=0; y<8; y++)
            outBuffer[x][y] = F(x, y, inBuffer);
    idx = 0;
}
```

## 7. Image Processing – Quantization

- Achieve high compression ratio by reducing image quality
- Reduce bit precision of encoded data:
  - Fewer bits needed for encoding
  - One way is to divide all values by a factor of 2 (right shift)

- Reverse the process for dequantization

1150	39	-43	-10	26	-83	11	41
-81	-3	115	-73	-6	-2	22	-5
14	-11	1	-42	26	-3	17	-38
2	-61	-13	-12	36	-23	-18	5
44	13	37	-4	10	-21	7	-8
36	-11	-9	-4	20	-28	-21	14
-19	-7	21	-6	3	3	12	-21
-5	-13	-11	-17	-4	-1	7	-4

After being decoded using DCT

Divide each cell's  
value by 8

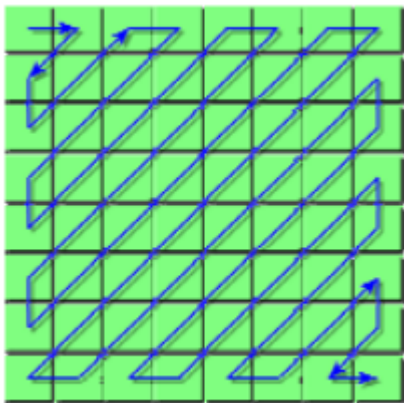


144	5	-5	-1	3	-10	1	5
-10	0	14	-9	-1	0	3	-1
2	-1	0	-5	3	0	2	-5
0	-8	-2	-2	5	-3	-2	1
6	2	5	-1	1	-3	1	-1
5	-1	-1	-1	3	-4	-3	2
-2	-1	3	-1	0	0	2	-3
-1	-2	-1	-2	-1	0	1	-1

After quantization

## 8. Image Processing – Huffman Encoding

- Variable length encoding
  - More frequently occurring pixels assigned short binary code
  - Longer binary codes left for less frequently occurring pixels
- Serialize 8 x 8 block of pixels and values are converted into single list using zigzag pattern
- Each pixel in the serial list is converted to Huffman encoded value
- Huffman encoding is reversible (No code is a prefix of another code)



- Build Huffman tree from bottom up

- ❖ leaf for pixel
- ❖ internal node of min sum

- Traverse tree from root to obtain leaf's pixel value

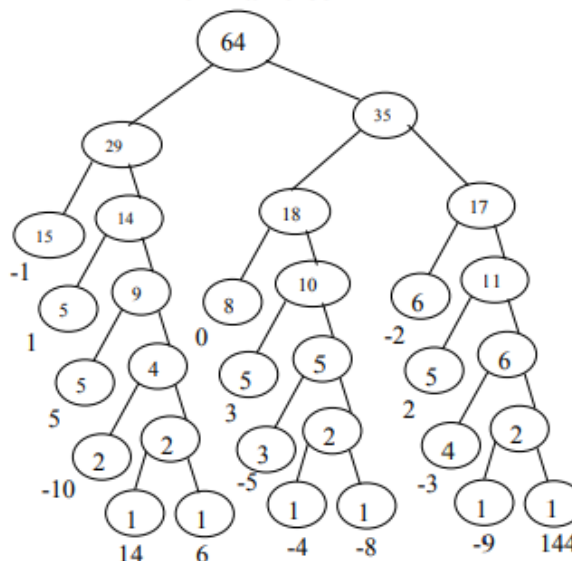
- Append

- ❖ 0 : for left
- ❖ 1 : for right traversal.

**Pixel frequencies**

-1	15x
0	8x
-2	6x
1	5x
2	5x
3	5x
5	5x
-3	4x
-5	3x
-10	2x
144	1x
-9	1x
-8	1x
-4	1x
6	1x
14	1x

**Huffman tree**



**Huffman codes**

-1	00
0	100
-2	110
1	010
2	1110
3	1010
5	0110
-3	11110
-5	10110
-10	01110
144	111111
-9	111110
-8	101111
-4	101110
6	011111
14	011110

## C. The List of Requirements



Product Requirement List					
Doc ID		Product	Low-end Digital Still Camera	Date	/ /
Functional Requirements			Non-Functional Requirements		
F01	Taking photo & processing		N01	Processing fast enough	~ 1 sec. ?
F02	Processing and storing photos in digital format	JPEG?	N02	Cost: IC $\leq$ \$25, Tot $\leq$ \$100	USD
			N03	IC gate count $\leq$ 200K+	
F03	Storing at least 50 photos		N04	Reasonable size with IC	
F04	Image resolution: Low		N05	Reasonable weight suitable for hand-held	
F05	Loading the photo images to a PC computer		N06	Operating w/o cooling fan	$< 50^{\circ}\text{C}$ ?
			N07	Low power consumption for long battery life	
			N08	Time-to-Market $< 6$ Mon.	
Reviewer		/ /	Approved by		/ /

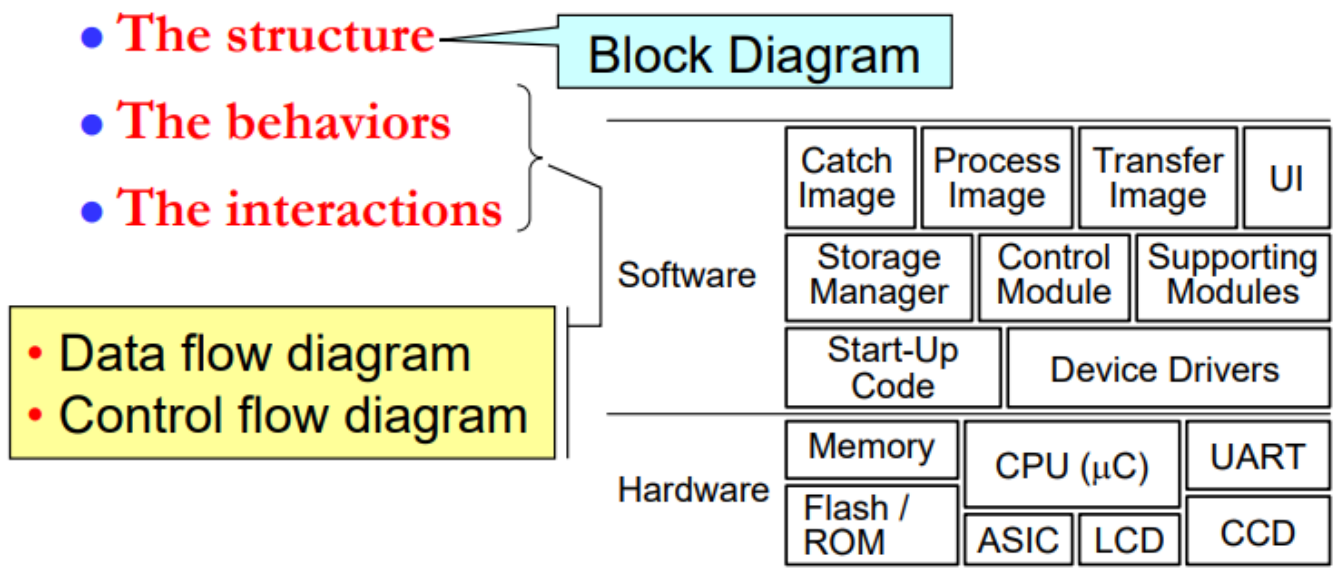
## D. The List of Specifications

Product Specifications										
Doc ID			Product	Low-end Digital Still Camera	Date	/	/			
Item	Function		Specification/Description			Note				
S01	Taking photos		1. Digital image format: jpg of resolution 320 × 160 2. Performance: image processing time about 1 sec.							
S02	Storage		1. Capacity: at least 50 photo images 2. Writing photo image for storing 3. Reading stored photo image for transferring							
S03	Connection		1. Connect to PC computers via RS-232C interface 2. Data Rate: auto-set and at least 9600 bits/sec.			UART				
S04	User Interface		No (Auto transferring or operating at computer side)			Switches				
S05	Miscellaneous		1. Can work at 0 ~ 50°C and no cooling fan is allowed 2. Low power consumption for long battery life 3. Weight (w/o battery) <= 500g and reasonable size							
Reviewer				/	/	Approved by			/	/

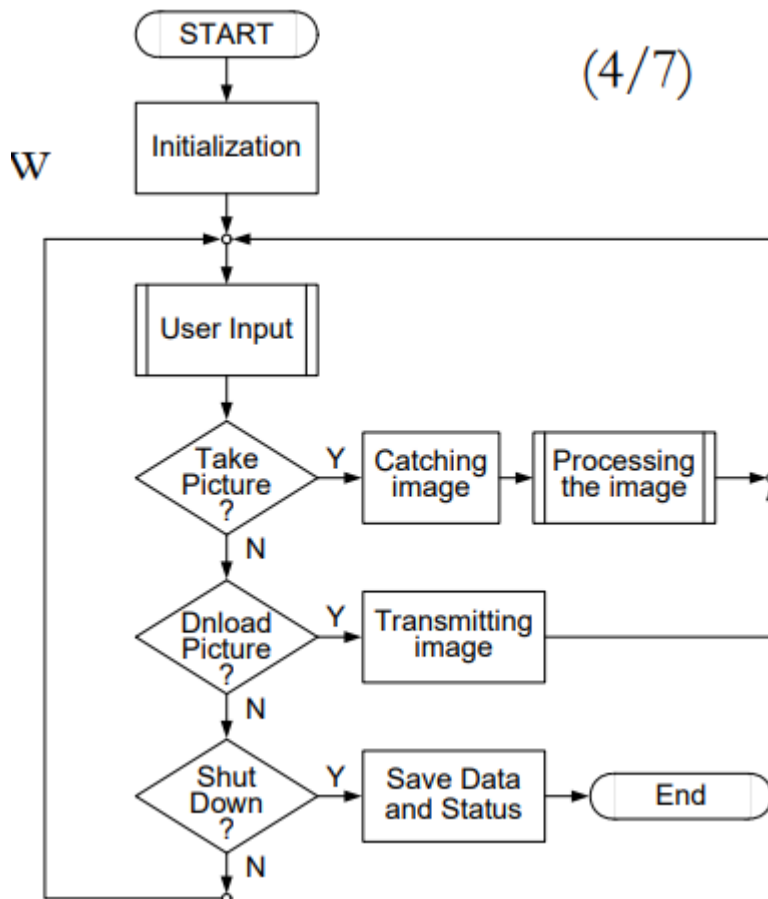
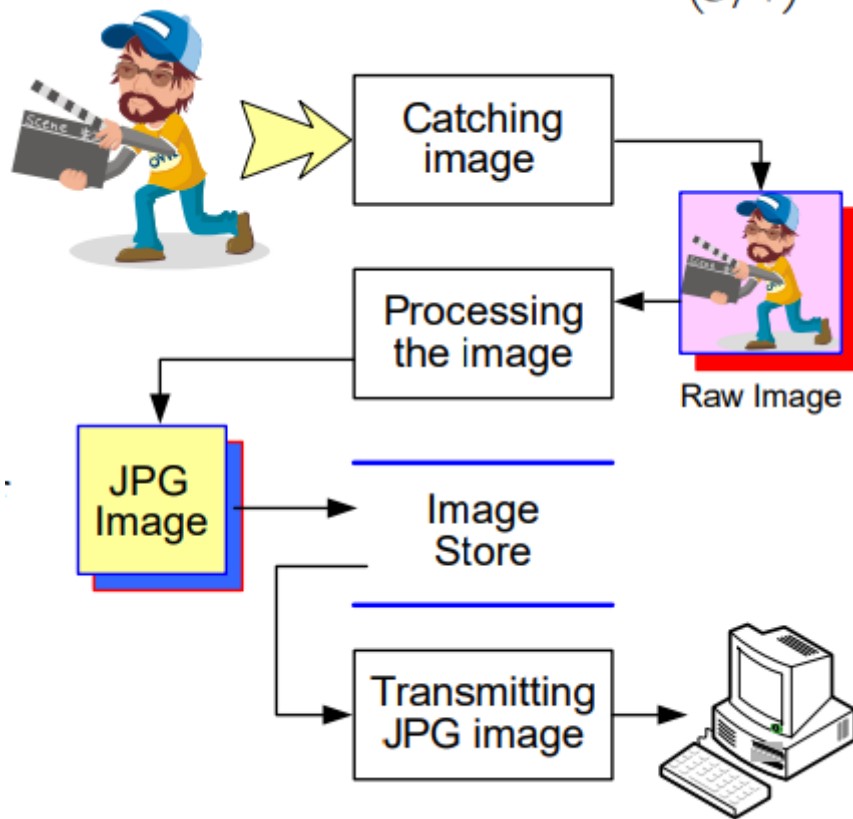
## E. The Design

- Description of system architecture
  - Hardware components
  - Software structure
- Mapping functionality to the architecture
  - One function on one processor
  - One function on many processors

- Many functions on one processor
- One person's specification may be the implementation of another person!

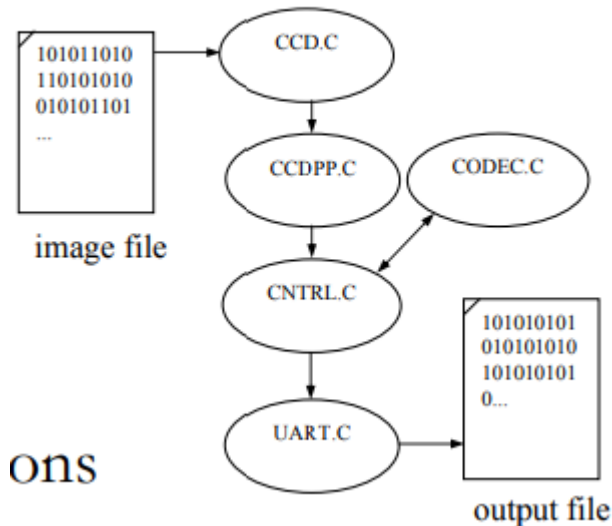


## Using a data flow diagram to describe the functional specifications



A high-level executable model of specifications

### Executable model of digital camera

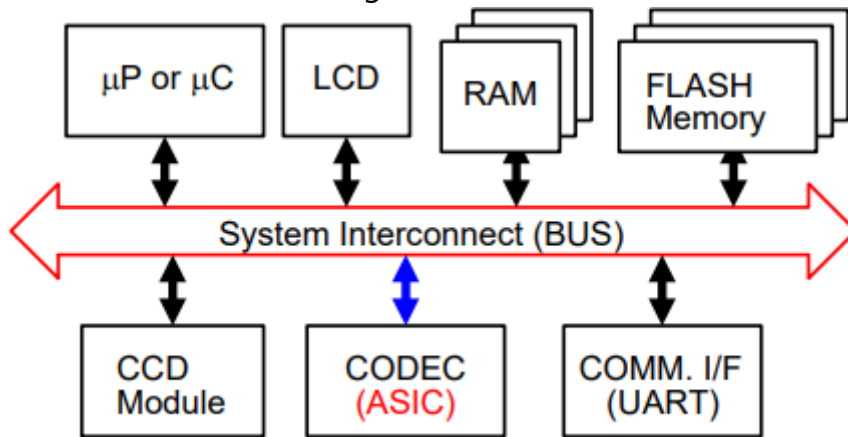


An example of the unified H/W and S/W approach

Function	Operations	Design	Mapping
Capture an image	1. CCD operation 2. Zero-bias adjustment	1. CCD module 2. CCD driver	H/W+S/W
Convert an image into JPG	1. FDCT 2. Quantization 3. Huffman encoding	Encoder	H/W or S/W
Store an image	1. Copy JPG image 2. Manage directory	SaveImage	S/W
Transfer an image	1. UART connection 2. Transmission 3. Manage directory	1. UART module 2. UART driver 3. ReadImage 4. SendImage	H/W+S/W

- System architecture
  - CCD module
  - Processor: General-purpose or special-purpose or both
  - Memory: RAM and Flash Memory
  - Bus
  - I/O Devices
  - Application-specific hardware components (ASIC)
  - Software

- Basic architecture of a digital camera



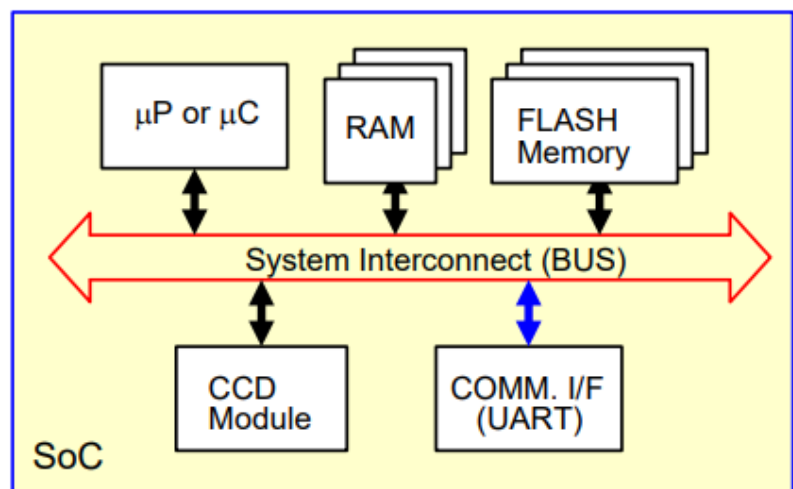
## Different Implementation

### Implementation 1 – Microcontroller (micro C) alone:

- Hardware – min. required hardware with 12MHz 8051 μC
- Software – all function modules running on the 8051

#### The architecture:

- SoC of minimum required hardware components
  - ❖ 8051 μC
  - ❖ RAM/FLASH
  - ❖ CCD Module
  - ❖ UART
- The software





## The software:

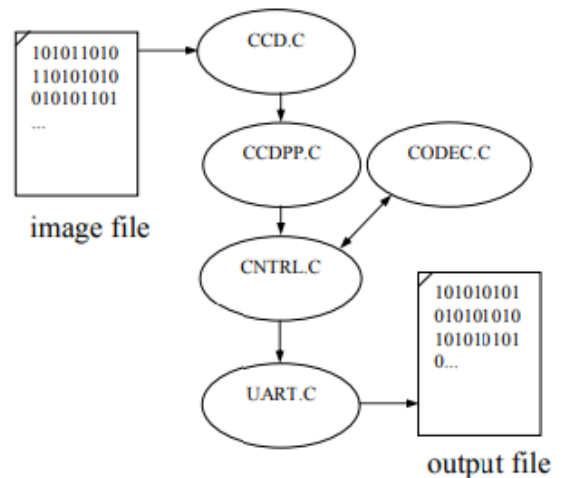
- Based on the high-level executable model of specification
- Main control flow – CNTRL.C
- Function modules:

- ❖ CaptureImage
- ❖ CompressImage
- ❖ SendImage

- Supporting modules:

- ❖ CCDPP.C
- ❖ CODEC.C
- ❖ UART.C

### Executable model of digital camera



## ❑ Analysis

- IC cost (including NRE) – approx. USD\$5 (NT\$160)
- Performance:
  - ❖ Approx. 1 MIPS (12Mhz 8051  $\mu$ C of 12 cycles/instruction)
  - ❖ Reading image at 409,600 instructions/image ( $4096 \times \sim 100$ )
  - ❖ Only  $\sim 0.5$  sec for computation intensive FDCT & encoding
  - ➡ Over-budget (1 image per sec. not possible)
- Power Consumption – well below 200mW
- Energy – not analyzed (not necessary)
- Time-to-Market – about 3 months

## ❑ Decision: **Not feasible!**

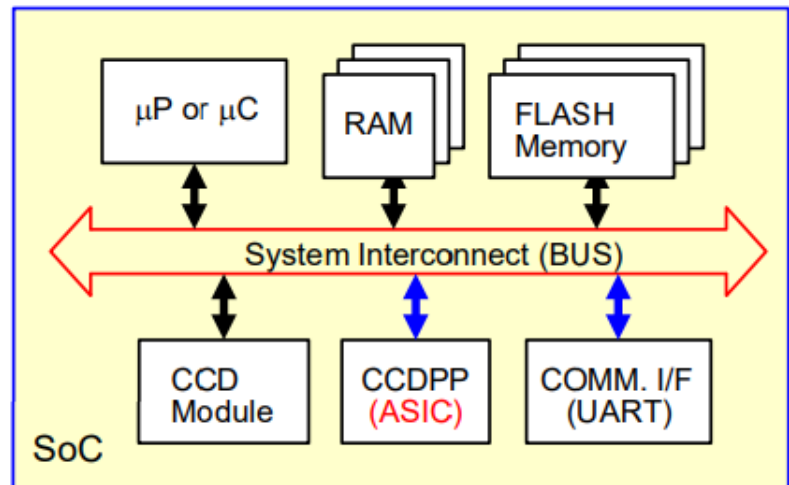
## Implementation 2 – micro C + H/W Function Unit:

- Hardware – SOC of 12MHz 8051 micro C and CCDPP

- Software – function modules and control module of CCDPP

### The architecture:

- SoC of required H/W components
- Processors:
  - ❖ 8051  $\mu$ C
  - ❖ CCDPP
- Bus-structured



### ❑ Analysis

- IC cost (size) – 98000 gates (chip area)
- Performance – **9.1 sec** for processing 1 image
- Power Consumption – 33 mW (0.033 W)
- Energy – 0.30 joule (0.033 W × 9.1 sec)
- Time-to-Market – less than 6 months is possible

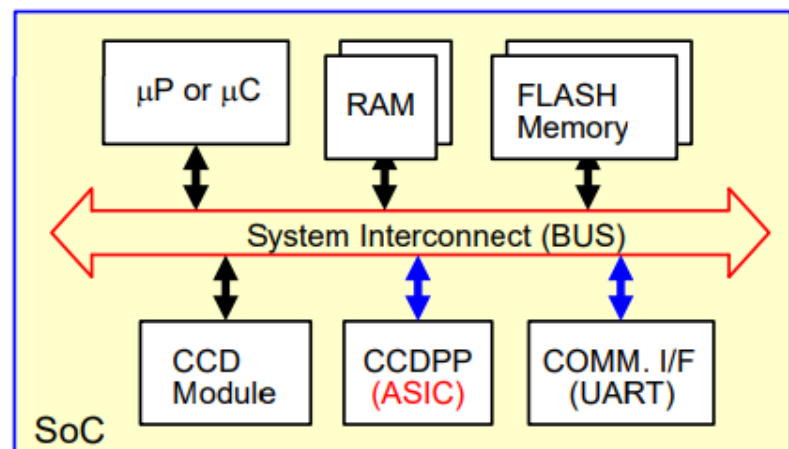
### ❑ Decision: **Not feasible!**

## Implementation 3 – micro C + H/W Function Unit:

- Hardware – SOC of 12MHz 8051 micro C and CCDPP
- Software – function modules with fixed-point FDCT and

### The architecture:

- SoC of required H/W components
- Processors:
  - ❖ 8051  $\mu$ C
  - ❖ CCDPP
- Bus-structured



## ❑ Analysis

- IC cost (size) – 90000 gates (chip area)
- Performance – 1.5 sec for processing 1 image
- Power Consumption – 33 mW (0.033 W)
- Energy – 0.050 joule ( $0.033 \text{ W} \times 1.5 \text{ sec}$ )
- Time-to-Market – less than 6 months is possible

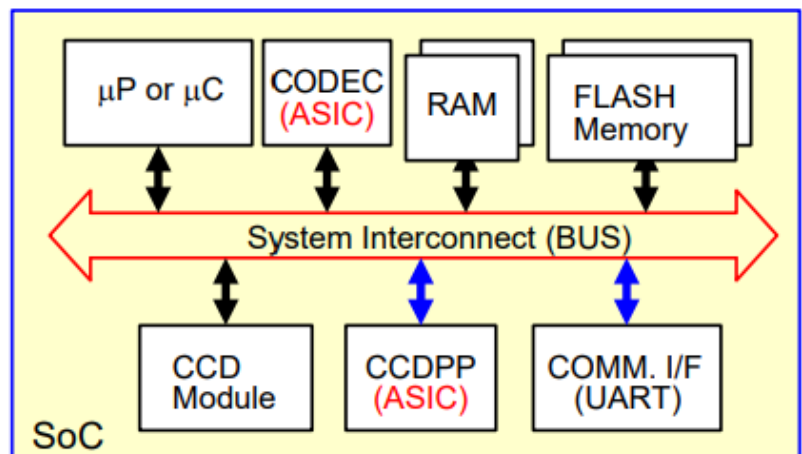
## ❑ Decision: A possible solution

### Implementation 4 – $\mu$ C + H/W Function Units:

- Hardware – SOC of 12MHz 8051 micro C, CCDPP and CODEC
- Software – function modules with fixed-point FDCT and control modules of CCDPP and CODEC

#### The architecture:

- SoC of required H/W components
- Processors:
  - ❖ 8051  $\mu$ C
  - ❖ CCDPP
  - ❖ CODEC
- Bus-structured



## ❑ Analysis

- IC cost (size) – 128000 gates (chip area)
- Performance – 0.099 sec for processing 1 image
- Power Consumption – 40 mW (0.040 W)
- Energy – 0.0040 joule ( $0.040 \text{ W} \times 0.099 \text{ sec}$ )
- Time-to-Market – 6 months might not be possible  
(i.e.  $> 6 \text{ Mon. or } 6^+ \text{ Mon.}$ )

## ❑ Decision: A possible solution

### Comparison and Discussion



## Comparison and Discussion:

Implementation	1	2	3	4
Performance	>> 1 sec.	9.1 sec.	1.5 sec.	0.099 sec.
Size (no. gates)	N/A	98000	90000	128000
Power (mW)	<< 200	33	33	40
Energy (joule)	N/A	0.30	0.050	0.0040
Time-to-Market	~ 3 Mon.	< 6 Mon.	< 6 Mon.	? (6+ Mon.)

❑ Which is better?

❑ Main lesson: Trade-off between H/W and S/W

業界通常選3・性能不要太好