

Pilot Stress Detection Through Physiological Signals Using a Transformer-Based Deep Learning Model

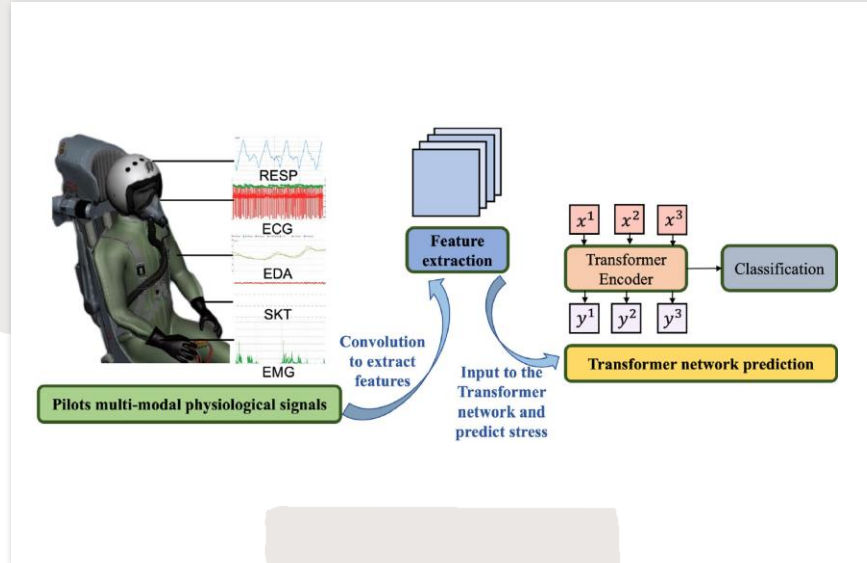
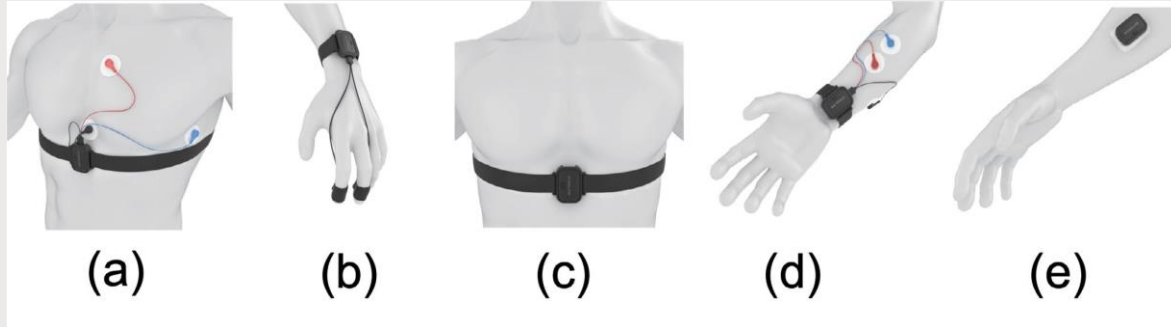
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 - Cited by: 22
- Presenter: Nooshin Taheri
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Why Detecting Pilot Stress Matters

- Pilot stress detection is **crucial** for flight safety and performance.
- **High automation + fewer crew members** → pilots must handle multiple simultaneous tasks, leading to increasing stress.
- Pilot **high stress** leads to:
 - Poor decision-making
 - Reduced situational awareness
 - Decreased performance
- Early detection enables flight systems to adjust workload and prevent performance decline during acute stress events.
- With **wearable physiological sensors** and **AI**, stress can now be detected in real time.



Aim of This Study



- Detect pilot stress caused by mission difficulty or abnormal flight conditions using **multimodal physiological signals**.
- **Signals chosen** for portability & effectiveness:
 - Electrocardiography (ECG)
 - Electromyography (EMG)
 - Electrodermal activity (EDA)
 - Respiration (RESP)
 - Skin temperature (SKT)
- **Contribution of the study:**
 - **Novel CNN + Transformer architecture**
 - CNN module → extracts **local features** and patterns within each signal.
 - Transformer module → captures **global dependencies** and relationships between multiple signals.

Experiment Protocol



- Participants: 14 professionally trained flight cadets
- Equipped with wearable physiological measurement devices.
- Completed State-Trait Anxiety Inventory (STAI-Y1) to confirm stress-free baseline.
- Five maneuvers performed in the simulator (**Takeoff, Level flight, Roll, Hovering, Somersault**)
- **Stress Assessment**
 - **Questionnaire after each maneuver**
 - Overall Rating (OR): 1 = No stress, 5 = High stress
 - Comparative Rating (CR): Rank maneuvers by stress level
 - Scores are standardized using **Z-score**
 - The mean and standard deviation of the scores were calculated

Maneuver	Overall Rating		Comparative Rating	
	μ	σ	μ	σ
Level flight	1.93	0.83	1.29	0.47
Roll	1.93	0.73	2.07	0.83
Hovering	3.14	0.66	3.43	0.85
Takeoff	3.36	0.63	3.29	0.83
Somersault	4.50	0.52	4.93	0.27

Labeling Method

Stress score computed **per second** based on:

- Aircraft attitude change
- G-force variation
 - G-force is the acceleration of an object relative to the Earth's gravitational force, which is output by the flight simulation software.
- Skin conductance variation

Verification:

- Average stress scores for each maneuver were calculated.
- Results exceeded the acceptable threshold.
- This shows the scoring method is **feasible** and produced **consistent results** agreed upon by all scorers.

Maneuver	Level flight	Roll	Hovering	Takeoff	Somersault
Average Stress Score	1.2	2.4	3.9	3.5	5.2

Classes defined:

- **2-class:** Low vs High stress
- **3-class:** Low, Medium, High stress
- **4-class:** None, Low, Medium, High stress

Data Processing & Features

- **Preprocessing:**

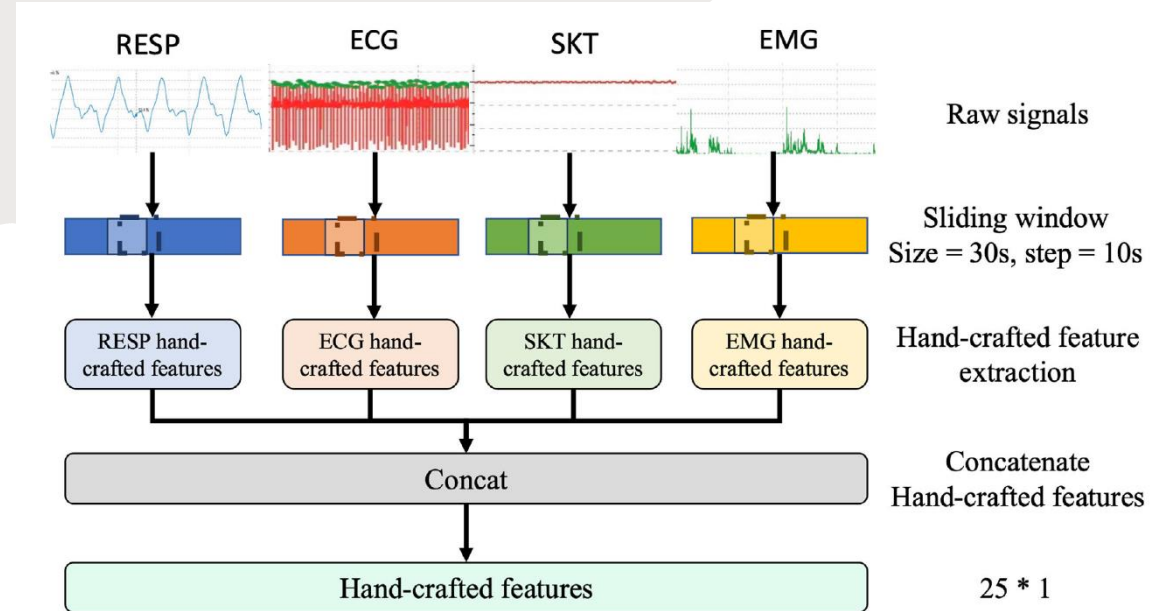
- Handle missing data (interpolation filling)
- denoising (wavelet, filtering)

- **Features:**

- **Handcrafted** (25 features per time window):

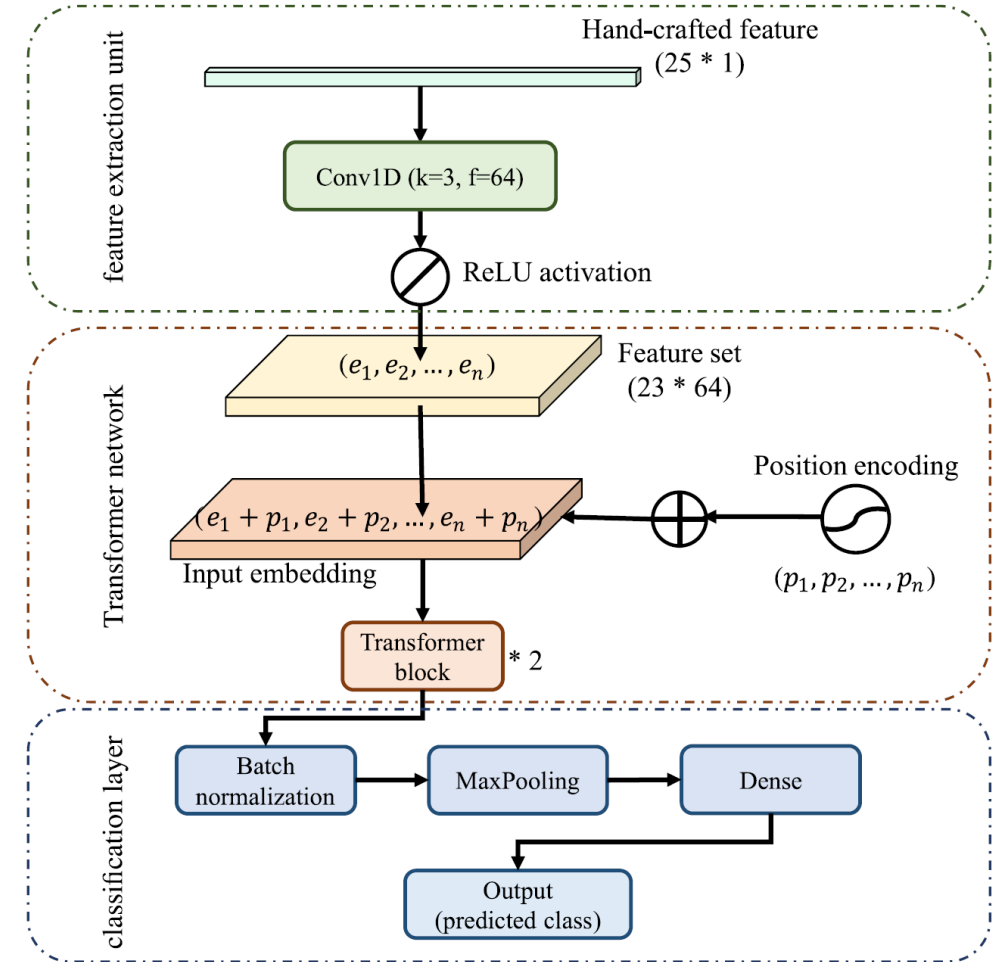
- **ECG/HRV:** Heart rate, NN intervals, SDNN, RMSSD, pNN50, pNN20, VLF, ULF, LF, HF, LF/HF ratio
- **EMG:** Voltage mean, std, RMS, integral EMG, median frequency, mean power frequency
- **RESP:** Respiratory rate (mean, std), respiration power
- **SKT:** Skin temperature

- **Deep features:** Extracted via CNN layers.



Model Architecture

- **Pipeline:**
 - **Feature Extraction Unit** – 1D CNN → captures local patterns. (extract hidden features)
 - **Transformer Block** – self-attention → models dependencies between modalities.
 - **Classification Layer** – predicts stress level.
- Due to the relatively few features and the individual differences between subjects, dropout is replaced by layer normalization (LN) and regularization.
- more attention would be paid to positions with higher activation.



Results

- **Baseline Models Compared**
 - Modified **AlexNet** (1D conv layers for signals)
 - Modified **ResNet18**
 - Light-ResNet (simplified ResNet for fairness in computation)
- All models evaluated with **10-fold cross-validation**.
- A higher number of classes increases difficulty, but the transformer advantage grows.
- Comparable performance to ResNet18 but with **faster training**.
- Position embedding improves accuracy

RESULTS OF WITH/WITHOUT POSITION EMBEDDING

Position Embedding	2-class	3-class	4-class
With	93.28%	88.75%	84.85%
Without	91.01%	86.62%	82.22%

CLASSIFICATION PERFORMANCE OF THREE MODELS

Model	Task	Accuracy	FLOPs (MFLOPs)	Prms
Transformer	2-class	93.28%	12.159	287,298
	3-class	88.75%	12.162	288,771
	4-class	84.85%	12.165	290,244
Modified AlexNet	2-class	82.86%	3.262	912,642
	3-class	77.62%	3.263	913,155
	4-class	70.30%	3.264	913,668
Modified ResNet18	2-class	92.17%	64.191	3,853,442
	3-class	86.32%	64.203	3,856,003
	4-class	80.45%	64.214	3,858,564
Light-ResNet	2-class	91.18%	12.266	711,938
	3-class	85.45%	12.269	713,219
	4-class	78.20%	12.271	714,500

Discussion

- Transformer module captures dependencies between multimodal physiological signals better than CNN alone.
- **Feature extraction unit** (handcrafted + CNN deep features) improves accuracy by:
 - Representing both **time-domain** and **frequency-domain** info.
 - Capturing local correlations before transformer processing.
- **Position embedding:**
 - Encodes location info of features.
- **Attention mechanism:**
 - Focuses on global relationships.
 - The transformer's attention mechanism can directly link any two points in a signal, no matter how far apart they are, making it easier to spot relationships between events separated in time.

Conclusion

- Developed a **CNN + Transformer** model for detecting pilot stress from **multimodal physiological signals** (ECG, EMG, EDA, RESP, SKT).
- **CNN** extracts local patterns; **Transformer** captures global relationships between different signals.
- Achieved **high accuracy**: 93.28% (2-class), 88.75% (3-class), 84.85% (4-class), outperforming AlexNet and matching or exceeding ResNet18 with faster training.
- Combining **handcrafted features** with deep-learned features improves robustness.
- Position embedding and attention mechanism are key for performance.
- **Potential use**: real-time pilot stress monitoring to enhance safety and decision-making.