

A *minimal surface* is a submanifold $\Sigma \subset M$ in a manifold M which minimizes the surface area of Σ subject to a constraint. The problem of finding minimal surfaces is fundamental. Such geometric optimization problems go back to *Dido's problem* of ancient Carthage. They are a basic example in elliptic PDE, and were the original impetus for the development of geometric measure theory. As a sample of the applications, minimal surfaces are used to prove the positive mass theorem in general relativity, to determine the correct shape of artificial hearts¹, and as models for biomolecules². Particularly important examples are *geodesics*, or minimal surfaces of dimension 1. (For example, a geodesic in the euclidean plane is the same thing as a straight line.)

Closely related to minimal surfaces are *least-gradient functions*, which are functions u of bounded variation whose derivatives du minimize $\int |du|$. If U is a region in M , and $u = 1$ on U , $u = 0$ elsewhere, then $\int |du|$ is the surface area of the boundary ∂U , so that if u has least gradient then ∂U is a minimal surface. On the other hand, if u is smooth, then the level sets $\partial\{u > y\}$ are all minimal surfaces.

Thurston³ introduced *best-Lipschitz functions*, those which instead minimize $\sup |du|$, with a view to his theory of *geodesic laminations* – that is, closed sets which can be partitioned into simple closed geodesics. He conjectured a duality theory relating best-Lipschitz and least-gradient functions, inspired by the max-flow/min-cut duality of computer science. Uhlenbeck and my advisor, Daskalopoulos, recently initiated a research program⁴ to develop best-Lipschitz/least-gradient duality. As an application, they deduce that *if v is a best-Lipschitz function on a closed hyperbolic manifold M , then the set of points $x \in M$ which maximize $|dv_x|$ define a geodesic lamination*. Geodesic laminations are a basic object of study in Teichmüller theory, and this theorem gives a powerful tool for constructing them.

Daskalopoulos and Uhlenbeck conjecture that one can prove the above theorem without using best-Lipschitz/least-gradient duality, but rather by studying least-gradient functions directly. To this end, I propose to develop a regularity theory for least-gradient functions on manifolds. Functions of least gradient not even need be $W^{1,1}$, so one needs to make precise what is meant for a least-gradient function to be regular. If u is a least-gradient function, then the level sets $\partial\{u > y\}$, $y \in \mathbb{R}$, are minimal surfaces, which *a priori* may be ill-behaved. A regularity theory would amount to showing that such minimal surfaces are, in fact, smooth. If this is true, then a standard argument implies above the conjecture.

Hilbert's 19th problem posits that the problem of minimizing $\int \mathcal{L}$, where \mathcal{L} is analytic and convex in u , only has analytic solutions. It was proven by de Giorgi⁵. So, to show that the level sets $N = \partial\{u > y\}$ are analytic, one just needs to show that N is a C^1 -differentiable manifold. If this is true, then N can locally be written as the graph of a C^1 -differentiable function f which minimizes the *minimal surface functional*, $A = \int \sqrt{1 + |df|^2}$, which is the surface area of N . The function $x \mapsto \sqrt{1 + |x|^2}$ is analytic and convex, so in this case, N is analytic by Hilbert's 19th problem.

¹Bates, P. W., et al. "Minimal Molecular Surfaces and Their Applications." *J. Comput. Chem.* 29, pp380–391.

²Walker, D. K., et al. "Development and in vitro assessment of a new two-leaflet replacement heart valve designed using computer-generated bubble surfaces." *Med. Biol. Eng. Comput.* 21, pp31–38.

³Thurston, W. *Minimal stretch maps between hyperbolic surfaces*. arXiv:9801039.

⁴Daskalopoulos, G. and Uhlenbeck, K. *Transverse measures and best Lipschitz and least gradient maps*. arXiv:2010.06551.

⁵de Giorgi, E. "Sulla differenziabilità e l'analiticità delle estremali degli integrali multipli regolari". *Memorie della Accademia delle Scienze di Torino. Classe di Scienze Fisiche, Matematiche e Naturali.* 3, 25–43.

The strategy outlined above has been carried out in the euclidean case by the Italian school of de Giorgi, Miranda, et al., in dimensions $\in [2, 7]$.⁶ The key step of the proof is a lemma of de Giorgi concerning the *excess* Λ_r of N in a ball B of radius r centered at a point x , which roughly measures how badly N fails to be a hyperplane in B . According to the de Giorgi lemma, once r is chosen small enough, $\Lambda_{r/2}$ is smaller than one would naively expect just from rescaling Λ_r . By induction, then, $\Lambda_{r/2^n}$ must be tiny.

However, the argument of de Giorgi does not work in the noneuclidean case; once one modifies the statement of the lemma to account for the fact that hyperplanes are not well-defined on arbitrary manifolds, they are faced with the issue that the lemma is proven using a mollification argument, which allows us to assume that N is C^1 . Mollification of submanifolds of Riemannian manifolds is a delicate issue. In the euclidean case, the necessary mollification argument takes twelve pages of tricky estimates in Giusti's book, but Giusti did not have to cope with additional error terms created by the presence of curvature. I would like to show that these error terms can be suitably bounded, so that *on any orientable Riemannian manifold of dimension $\in [2, 7]$, the support of the derivative of a least-gradient function defines a lamination by smooth minimal hypersurfaces*. This includes the above conjecture of Daskalopoulos–Uhlenbeck as a special case.

The above proposal originated as a topics exam given to me by Daskalopoulos. Since then, I have become more ambitious and now hope to resolve some of the other problems posed by Daskalopoulos–Uhlenbeck, making good use of my background in PDE to further develop the theory of best-Lipschitz/least-gradient duality. In their paper, they suggest that one should be able to develop the regularity theory of best-Lipschitz functions on manifolds analogously to the euclidean case.

Evans–Savin showed⁷ that *every best-Lipschitz function on \mathbb{R}^2 is $C^{1+\varepsilon}$ -differentiable*. They start by assuming that the best-Lipschitz function u has a graph which is “close to a hyperplane” (this time in an L^∞ rather than L^1 sense) and show that one can zoom in infinitely far on u to obtain a function that can be approximated well by linear functions. Therefore, after a rescaling, u can be approximated by linear functions in a suitably strong sense that we obtain a bound on $\|du\|_{C^\varepsilon}$. It would be very interesting, and major progress in the program of Daskalopoulos–Uhlenbeck, to show that in fact, best-Lipschitz functions on arbitrary surfaces are $C^{1+\varepsilon}$ -differentiable. Therefore I propose to synthesize the methods of Evans–Savin with the sorts of curvature error bounds I propose to prove above, to show the desired regularity result. More generally, I hope to extend many classical results about PDE to the noneuclidean setting.

⁶Giusti, E. *Minimal surfaces and functions of bounded variation*. Canberra, 1977.

⁷Evans, L. C., and Savin, O. “ $C^{1,\alpha}$ regularity for infinity harmonic functions in two dimensions”. *Calculus of Variations* 32. pp325–347.