Apurva Badithela

apurva@caltech.edu abadithela.github.io

Education

2018– PHD in Control and Dynamical Systems California Institute of Technology

Expected *Thesis:* Formal Methods for Test and Evaluation, and Verification and Validation of Autonomy

Advisor: Richard M. Murray

Committee: Richard M. Murray, Soon-Jo Chung, Aaron D. Ames,

Adam Wierman, Eric Mazumdar

2014 B.S. in Aerospace Engineering and Mechanics University of Minnesota, Twin-Cities

2018 summa cum laude Advisor: Peter J. Seiler

Internships

2021 Autonomy Research Intern in Behavior Planning and Prediction Motional, Boston

Host: Eric Wolff

Project: Counterexample Guided Repair of Inverse Reinforcement Learning Planner

2017 ICES Moncrief Summer Research Fellow University of Texas, Austin

Host: Ufuk Topcu Mentor: Ivan Papusha

Project: Sparse Matrix Methods for Fast Real-time Model Predictive Control

2016 Summer Undergraduate Research Fellowship Purdue University, West-Lafayette

Host: Neera Jain

Mentor: Austin L. Nash

Project: Dynamic Modeling and Validation of micro-CHP systems

Publications

JOURNAL ARTICLES

2017 Austin Nash, Apurva Badithela, and Neera Jain.

Dynamic Modeling of a Sensible Thermal Energy Storage Tank with an Immersed Coil

Heat Exchanger under Three Operation Modes.

Journal of Applied Energy.

Conference Papers

Josefine Graebener*, Apurva Badithela*, and Richard M. Murray.

Towards Better Test Coverage: Merging Unit Tests for Autonomous Systems.

14th NASA Formal Method Symposium, 2022. To appear.

(* denotes equal contribution.)

Apurva Badithela, Tichakorn Wongpiromsarn, and Richard M. Murray.

Leveraging Classification Metrics for Quantitative System-level Analysis of Temporal Logic Spec-

ifications.

 60^{th} IEEE Conference on Decision and Control.

2019 Apurva Badithela and Peter Seiler.

Analysis of the Heavy-ball Algorithm using Integral Quadratic Constraints.

American Control Conference.

Pre-Prints

2020 Apurva Badithela and Richard M. Murray.

Synthesis of Static Test Environments for Generating Sequence-like Behaviors in Autonomous Sys-

tems. Submitted to 13^{th} NASA Formal Methods Symposium, 2021.

Honors and Awards

AIAA Guidance, Navigation and Control Undergraduate Conference Experience Award.

American Institute of Aeronautics and Astronautics.

2016- Robert and John McCollum Scholarship.

2018 Departmental Award

University of Minnesota

2014- Gold Global Excellence Scholarship.

2018 University-wide Award

University of Minnesota

Teaching

CALTECH

Spring'22 Optimal Control (CDS 112 / Ae 103a).

Fall'20 Linear Systems Theory (CDS 131).

Mentoring

Summer Andy Dimnaku 2022 SURF Fellow

Project: Optimization of Autonomous Vehicles Testing through Symmetry Mapping

Summer Edward Zhang, Frida Moreno, Gerard Decker

2022 FSRI Fellows

Project: Setting up Duckietown as a Hardware Platform for Testing Autonomous Vehicles

Summer Berlin Del Aguila
2020 WAVE Fellow

Project: Synthesis of Static Test Environments for Autonomy

Talks

Oct 2022 US-Japan Seminar on Autonomy, AI, Robotics, and Informatics.

Jul 2022 Workshop on Envisioning an Infrastructure for Multi-Robot and Collaborate Autonomy Testing

and Evaluation, Robotics: Science and Systems

May 2022 NASA Formal Methods

Mar 2022 University of California, Berkeley.
Dec 2020 University of California, Berkeley.

Service

DIVERSITY AND INCLUSION

Member of the Computing and Mathematical Sciences (CMS) Diversity, Equity and Inclusion (DEI) Steering Committee. Engage in bi-weekly discussions on creating initiatives to foster inclusion in the department.

- Created and organized the CMS Climate Survey on graduate student experience. Organized
 a department town hall to communicate survey results and solicit feedback from the community.
- Organized a diversity town hall for CMS students and postdocs, and compiled a written document of recommendations to CMS faculty.

Helped organize two workshops on Building Effective Research Collaborations for graduate students.

2022 Helped organize two workshops on Building Effective Research Collaborations for graduate students.

REVIEW ACTIVITIES

- Transactions on Automatic Control (TAC) 2022
- IEEE International Conference on Robotics and Automation (ICRA) 2022
- 60^{th} IEEE Conference on Decision and Control (CDC) 2021