

Algorithms for Programming Contests - Week 11

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Trie

A *Trie* is a tree data structure that is used to store a set of strings:

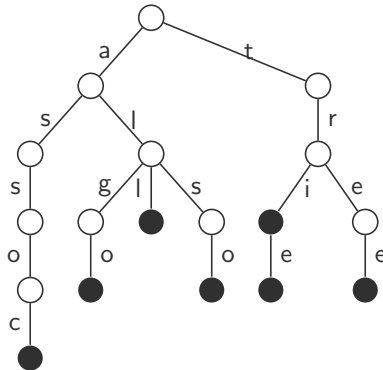
- Root node represents empty string.
 - Outgoing edges are associated with a label (e.g. a letter).
 - Path from root to a node represents a prefix of a word/words.
 - All descendants of a node have the same prefix.
 - Position of a node in the trie defines the associated string.
 - Nodes at which a word ends are tagged.
-
- Invented by René de la Briandais in 1959.
 - Name originates from the term *retrieval*.

Trie - Applications

- Storing a dynamic set of strings.
- Sorting strings lexicographically.
- Autocompletion
- Spell-checking

Trie

The next figure shows a trie with the words “tree”, “trie”, “tri”, “algo”, “assoc”, “all”, and “also”.



Trie - Implementation details

As an example, an array of the following struct can be used:

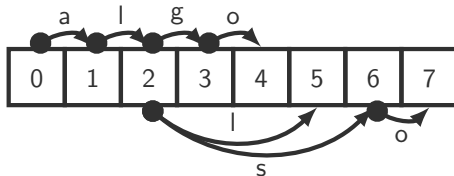
```
struct node{  
    int references[26]; // Size of Alphabet  
    bool end;  
};
```

Or

```
int references[N][26]; // size of Alphabet  
bool end[N];  
  
int lastId;  
//lastId shows the index of last nodes
```

Trie - Implementation details

You may have an array of nodes and references can be used as an index reference. Here is an example of a storage structure for the words inserted in this order: "algo", "all", "also"



Trie - Operations

LOOKUP(s)

- Start at the root node and traverse edges w.r.t. letters of s .
- If no suitable edge exist, s is not contained in the trie.
- If the whole word was processed, check whether the current node marks the end of a word.

INSERT(s)

- Start at the root node and traverse edges w.r.t. letters of s .
- Add non-existing edges along the way.
- Tag last node as the end of a word.

Trie - Additional information

Complexity:

- Insertion in $\mathcal{O}(L)$ time,
- Look-up in $\mathcal{O}(L)$ time.

Want to know something more:

- Compressed Tries,
 useful for `switch()` on string values
- Adaptive Radix Tree - an interesting index structure for
 main-memory databases.

Segment Tree - Motivation

Given an integer array $a[n]$. Implement two operations:

- $\text{ADD}(i, v)$: Add value v to i -th element.
- $\text{SUM}(\ell, r)$: Sum up all elements in interval $[\ell, r]$.

Segment Tree - Motivation

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Alg 1:

- $\text{ADD}(i, v)$: Simply add v to $a[i]$.
- $\text{SUM}(\ell, r)$: Loop from $a[\ell]$ to $a[r]$ and sum up values.
- Complexity: $\text{ADD}(i, v) \in \mathcal{O}(1)$, $\text{SUM}(\ell, r) \in \mathcal{O}(n)$

Segment Tree - Motivation

Alg 2:

- Compute prefix sums and store them in $b[]$.
- $\text{ADD}(i, v)$: Add v to $a[i]$ and recompute $b[]$.
- $\text{SUM}(\ell, r)$: Return $b[r] - b[\ell - 1]$.
- Complexity: $\text{ADD}(i, v) \in \mathcal{O}(n)$, $\text{SUM}(\ell, r) \in \mathcal{O}(1)$

Segment Tree - Motivation

Alg 2:

- Compute prefix sums and store them in $b[]$.
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Conclusion:

- Use Alg 1 if $\#\text{ADD-Queries} \gg \#\text{SUM-Queries}$.
- Use Alg 2 if $\#\text{ADD-Queries} \ll \#\text{SUM-Queries}$.

What if $\#\text{ADD-Queries} \approx \#\text{SUM-Queries}$?

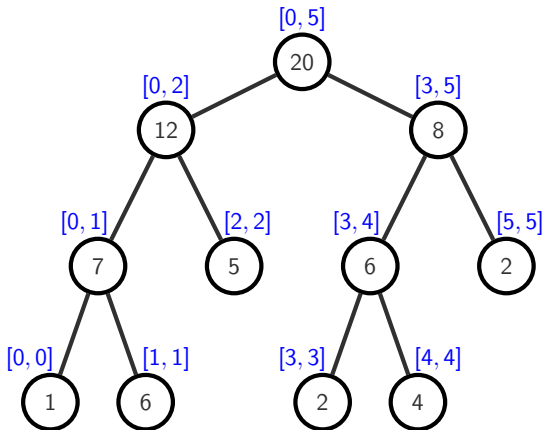
Segment Tree

A *Segment Tree* is a tree data structure used for storing information about intervals.

- A segment tree is a binary tree.
 - Each node stores a value v for an interval $[\ell, r]$.
 - Root represents the full interval $[0, n - 1]$.
 - If node v represents interval $[\ell, r]$, its left child represents $[\ell, m]$ and its right child $[m + 1, r]$ where $m = (\ell + r)/2$.
 - Leaves represent unit-intervals $[t, t]$.
-
- Segment trees were invented by Jon Louis Bentley in 1977.

Segment Tree - Example

Input array: $a[] = [1, 6, 5, 2, 4, 2]$



Segment Tree - Implementation

- Each node holds a value and the associated interval.

```
struct Node {int v,l,r;}
```

- Represent segment tree as an array of nodes.
- Root node is stored at index zero.
- Children of node i are stored at indices $2i + 1$ and $2i + 2$.
- Let n be the size of the input array:
 - Segment tree has height $h = \lceil \log n \rceil$.
 - Segment tree has $2^{h+1} - 1$ nodes.

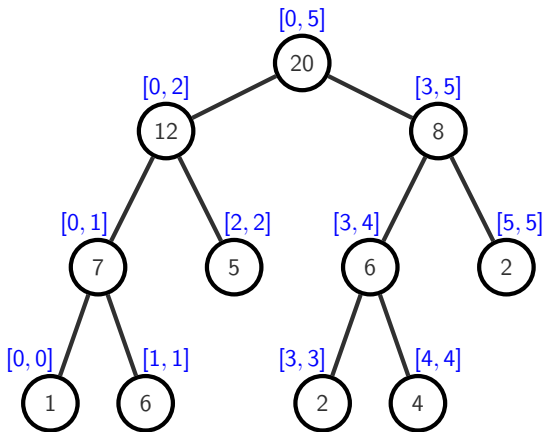
Segment Tree - Implementation tricks

- Round n up to a power of 2, fill tail with 0
- Root node is stored at index 1 (index 0 unused)
- Children of node i are stored at indices $2i$ and $2i + 1$.
- Node at level l out of h containing x :
 $(x / (2^{h-l})) + 2^l = (x \gg (h-l)) + (1 \ll l)$
- Its endpoints: $(x \gg (h-l)) \ll (h-l)$ and
 $((x \gg (h-l)) + 1) \ll (h-l) - 1$
- Only store node values

Segment Tree - Example

Input array: $a[] = [1, 6, 5, 2, 4, 2]$

Segment tree values: $v[] = [20, 12, 8, 7, 5, 6, 2, 1, 6, 0, 0, 2, 4, 0, 0]$



Segment Tree - Build

Algorithm 1 Segment Tree - Build

Input: input $a[]$, segment tree $t[]$, current index p , interval $[\ell, r]$.

Output: Segment tree rooted at p on interval $[\ell, r]$.

procedure BUILD($a[], t[], p, \ell, r$)

$t[p].\ell \leftarrow \ell$

$t[p].r \leftarrow r$

if $\ell = r$ **then**

$t[p].v \leftarrow a[\ell]$

return $t[p].v$

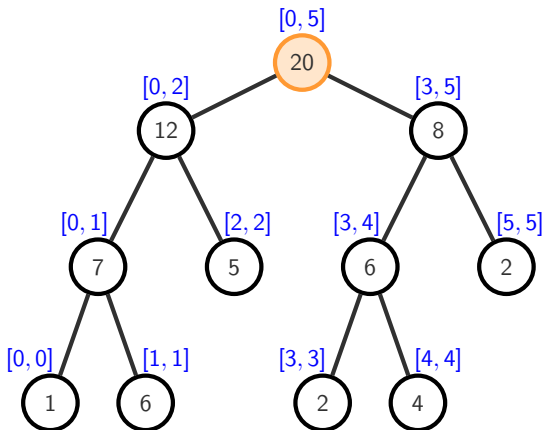
$m \leftarrow (\ell + r)/2$

$t[p].v \leftarrow \text{BUILD}(a, t, 2p + 1, \ell, m) + \text{BUILD}(a, t, 2p + 2, m + 1, r)$

return $t[p].v$

Segment Tree - Sum

SUM(1,5)



Full overlap



Partial overlap



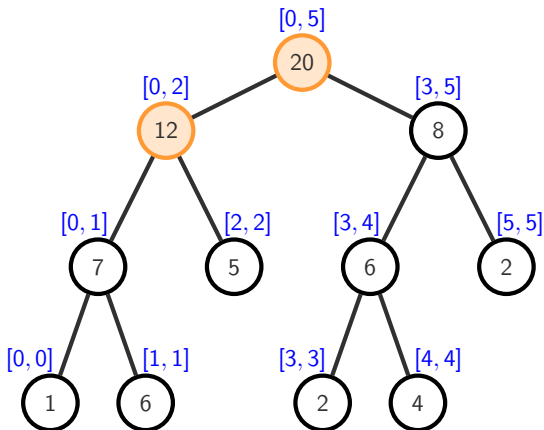
No overlap

42

Return value

Segment Tree - Sum

SUM(1,5)



Full overlap



Partial overlap



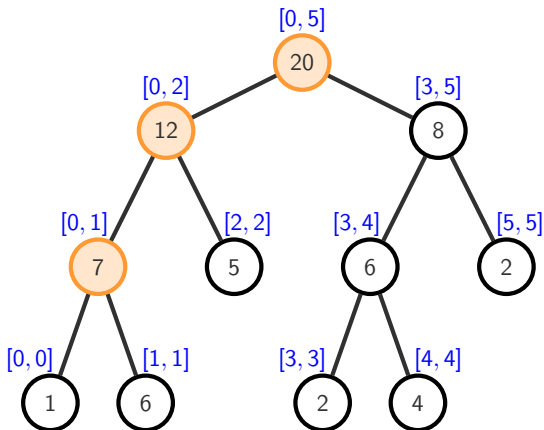
No overlap

42

Return value

Segment Tree - Sum

SUM(1,5)



Full overlap



Partial overlap



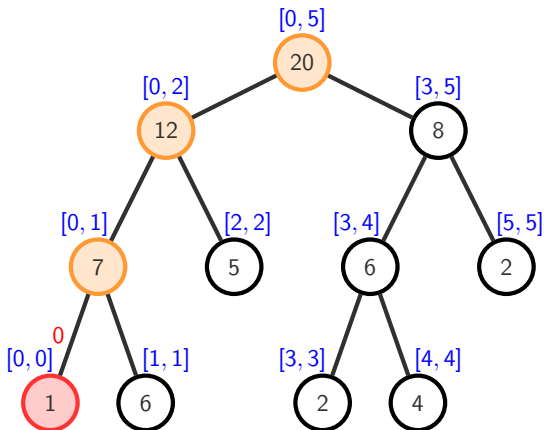
No overlap

42

Return value

Segment Tree - Sum

SUM(1,5)



Full overlap



Partial overlap



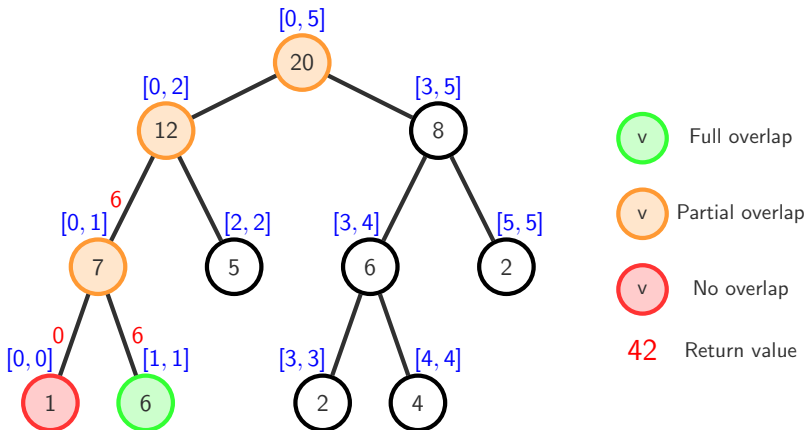
No overlap

42

Return value

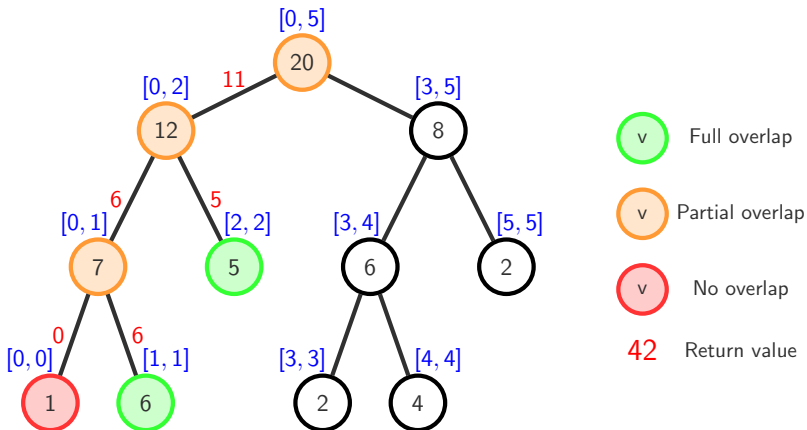
Segment Tree - Sum

SUM(1,5)



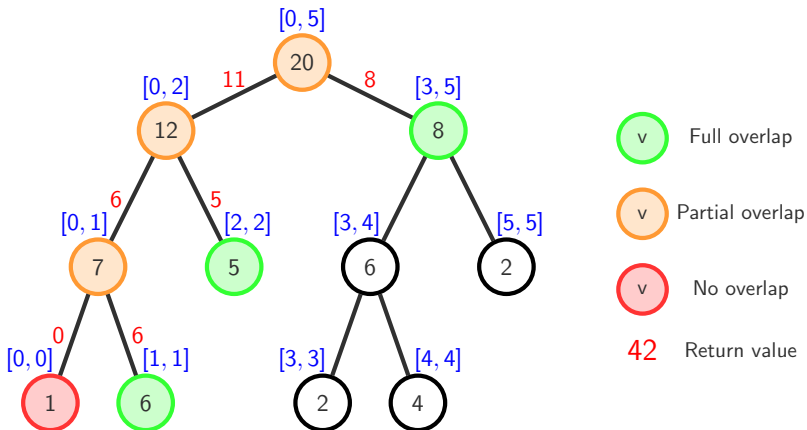
Segment Tree - Sum

SUM(1,5)



Segment Tree - Sum

$$\text{SUM}(1,5) = 19$$



Segment Tree - Sum

Algorithm 2 Segment Tree - Sum

Input: Segment tree $t[]$, current index p , interval $[\ell, r]$.

Output: Sum on interval $[\ell, r]$.

procedure SUM($t[], p, \ell, r$)

if $\ell > t[p].r$ **or** $r < t[p].\ell$ **then**

return 0

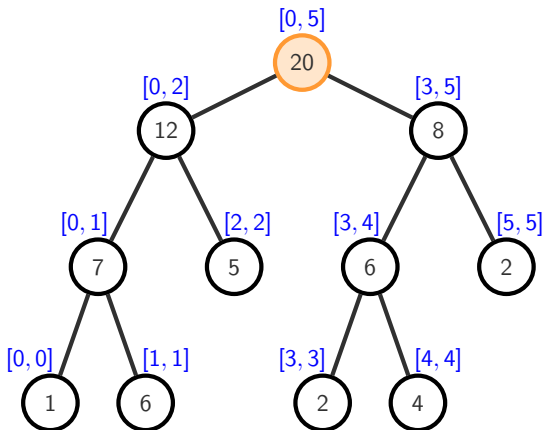
if $\ell \leq t[p].\ell$ **and** $t[p].r \leq r$ **then**

return $t[p].v$

return SUM($t, 2p + 1, \ell, r$) + SUM($t, 2p + 2, \ell, r$)

Segment Tree - Add

ADD 5 to index 3



Full overlap



Partial overlap



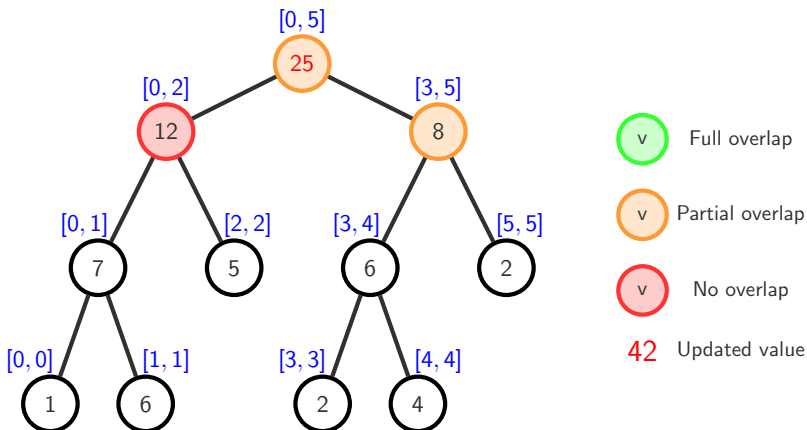
No overlap

42

Updated value

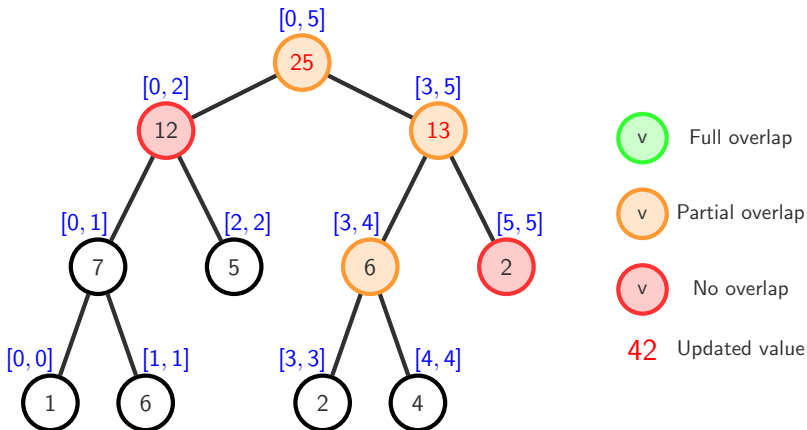
Segment Tree - Add

ADD 5 to index 3



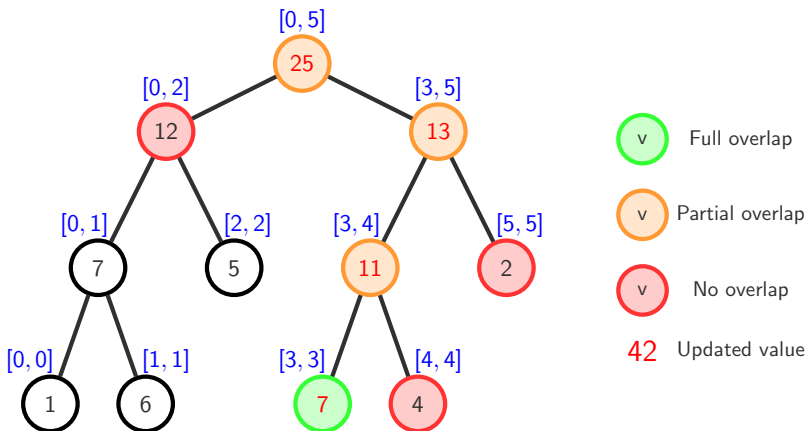
Segment Tree - Add

ADD 5 to index 3



Segment Tree - Add

ADD 5 to index 3



Segment Tree - Add

Algorithm 3 Segment Tree - Add

Input: Segment tree $t[]$, current index p , update index i , update value v .

```
procedure ADD( $t[], p, i, v$ )  
    if  $i < t[p].\ell$  or  $i > t[p].r$  then  
        return  
     $t[p] \leftarrow t[p] + v$   
    if  $t[p].\ell \neq t[p].r$  then  
        ADD( $t, 2p + 1, i, v$ )  
        ADD( $t, 2p + 2, i, v$ )
```

Segment Tree - Complexity

Complexity

Let n be the size of the input array $a[]$.

- BUILD: Each of the $2n - 1$ nodes is visited once. $\mathcal{O}(n)$.
- ADD: At most two nodes are visited on every level. $\mathcal{O}(\log n)$.
- SUM: At most four nodes are visited on every level. $\mathcal{O}(\log n)$.

Iterating with four variables for nodes often faster than recursion

Explicit stack instead of recursion: often faster, sometimes simpler than iteration

Segment Tree - Operations

Segment trees do not only work for sums but for all semigroups.

A *semigroup* is a set S with some associative binary operator

$\bullet : S \times S \rightarrow S$.

Associativity: For all $x, y, z \in S$ it holds that $(x \bullet y) \bullet z = x \bullet (y \bullet z)$.

In particular they work for:

- $(\mathbb{R}, +)$
- (\mathbb{R}, \min)
- (\mathbb{R}, \max)
- $(2^{\mathbb{N}}, XOR)$
- Matrices with matrix multiplication (take care of order!)

Segment Tree - RangeAdd

Implement a new operation:

- $\text{ADD}(i, v)$: Add value v to i -th element.
- $\text{SUM}(\ell, r)$: Sum up all elements in interval $[\ell, r]$.
- $\text{RANGEADD}(\ell, r, v)$: Add value v to each element in range $[\ell, r]$.

Segment Tree - RangeAdd

Implement a new operation:

- $\text{ADD}(i, v)$: Add value v to i -th element.
- $\text{SUM}(\ell, r)$: Sum up all elements in interval $[\ell, r]$.
- $\text{RANGEADD}(\ell, r, v)$: Add value v to each element in range $[\ell, r]$.

Naïve approach:

Call $\text{ADD}(i, v)$ for all $i \in [\ell, r]$. Complexity: $\mathcal{O}(n \log n)$.

Update each node intersecting with the range. Complexity: $\mathcal{O}(n)$.

Can we do better?

Segment Tree - RangeAdd

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- $\text{ADD}(i, v)$: Add value v to i -th element.
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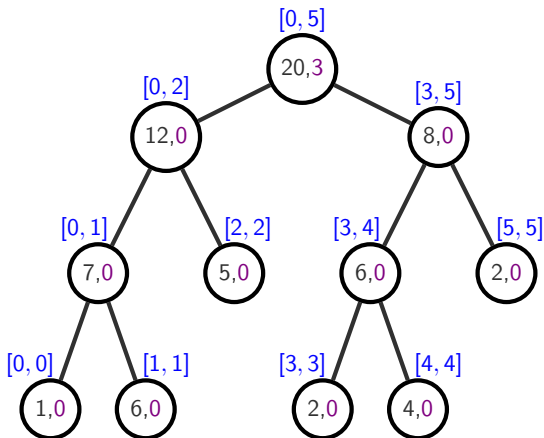
Can we do better? → Yes! Just be lazy...

Segment Tree - Lazy Propagation

- Store an additional integer value *lazy* in each node.
- Do not apply updates immediately but push them to the lazy variable.
- Only propagate lazy value to children when value of node is queried.

Segment Tree - Propagate

PROPAGATE lazy value of root node.

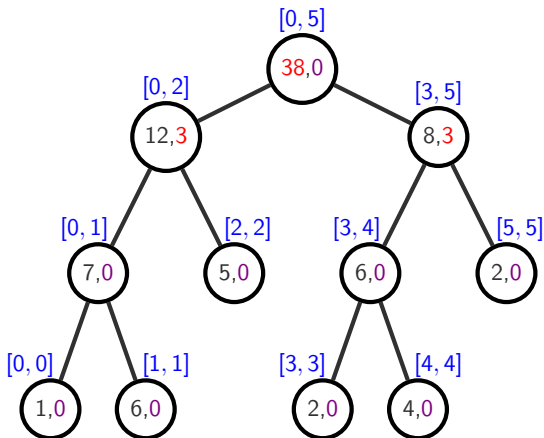


42 Updated value

13 Lazy value

Segment Tree - Propagate

PROPAGATE lazy value of root node.



42 Updated value

13 Lazy value

Segment Tree - Propagate

Algorithm 4 Segment Tree - Propagate

Input: Segment tree $t[]$, current index p .

procedure PROPAGATE($t[], p$)

$t[p].v \leftarrow t[p].v + (t[p].r - t[p].\ell + 1) * t[p].lazy$

if $t[p].\ell \neq t[p].r$ **then**

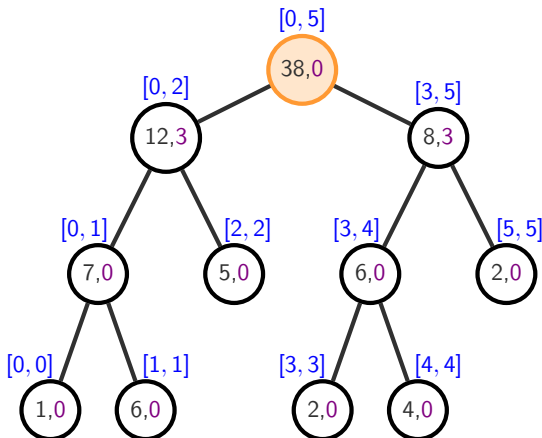
$t[2p + 1].lazy \leftarrow t[2p + 1].lazy + t[p].lazy$

$t[2p + 2].lazy \leftarrow t[2p + 2].lazy + t[p].lazy$

$t[p].lazy \leftarrow 0$

Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4] \rightarrow$ PROPAGATE root



Full overlap



Partial overlap



No overlap

42

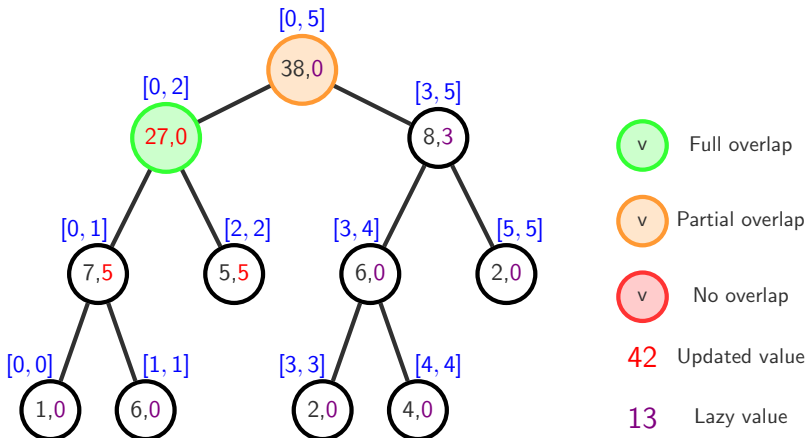
Updated value

13

Lazy value

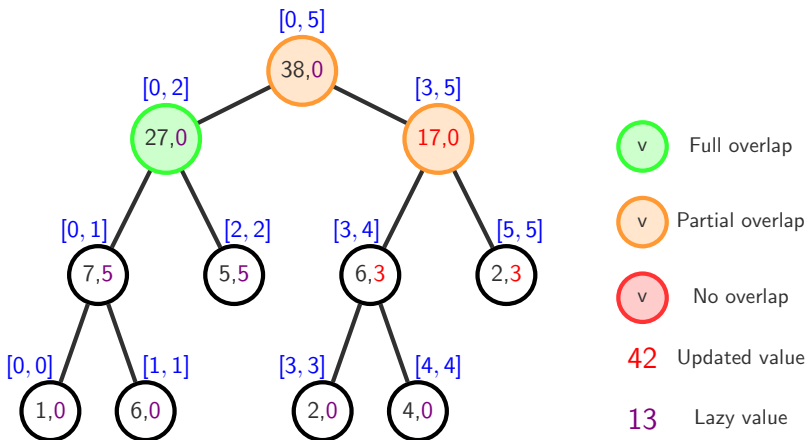
Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4] \rightarrow$ PROPAGATE node 1



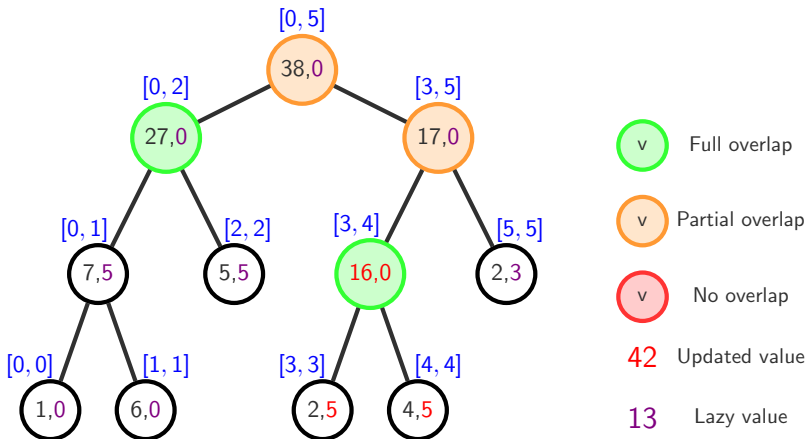
Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4] \rightarrow$ PROPAGATE node 2



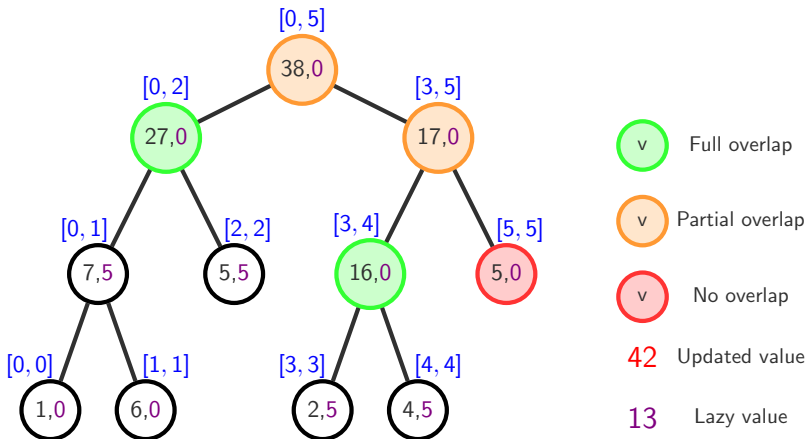
Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4] \rightarrow$ PROPAGATE node 5



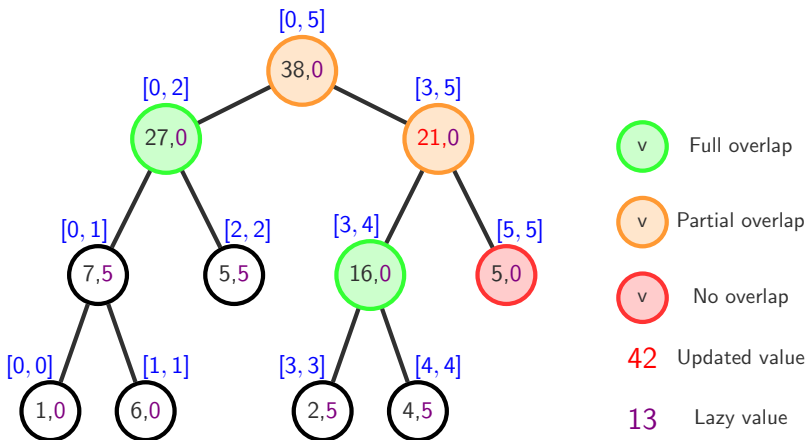
Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4] \rightarrow$ PROPAGATE node 6



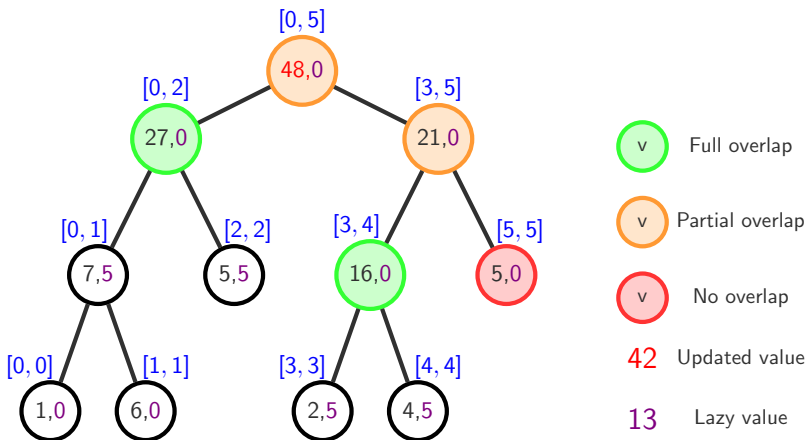
Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4]$ → Update node 1



Segment Tree - Propagate

RANGEADD 2 on interval $[0, 4]$ → Update root



Segment Tree - RangeAdd

Algorithm 5 Segment Tree - RangeAdd

Input: Segment tree $t[]$, current index p , interval $[\ell, r]$, value v .

```
procedure RANGEADD( $t[], p, \ell, r, v$ )  
    PROPAGATE( $t, p$ )  
    if  $\ell > t[p].r$  or  $r < t[p].\ell$  then  
        return  
    if  $\ell \leq t[p].\ell$  and  $t[p].r \leq r$  then  
         $t[p].lazy \leftarrow t[p].lazy + v$   
        PROPAGATE( $t, p$ )  
    else if  $t[p].\ell \neq t[p].r$  then  
        RANGEADD( $t, 2p + 1, \ell, r, v$ )  
        RANGEADD( $t, 2p + 2, \ell, r, v$ )  
         $t[p].v \leftarrow t[2p + 1].v + t[2p + 2].v$ 
```

Segment Tree - Sum

Algorithm 6 Segment Tree - Sum

Input: Segment tree $t[]$, current index p , interval $[\ell, r]$.

Output: Sum on interval $[\ell, r]$.

procedure SUM($t[], p, \ell, r$)

if $\ell > t[p].r$ **or** $r < t[p].\ell$ **then**

return 0

PROPAGATE(t, p)

if $\ell \leq t[p].\ell$ **and** $t[p].r \leq r$ **then**

return $t[p].v$

return SUM($t, 2p + 1, \ell, r$) + SUM($t, 2p + 2, \ell, r$)

Segment Tree - Complexity

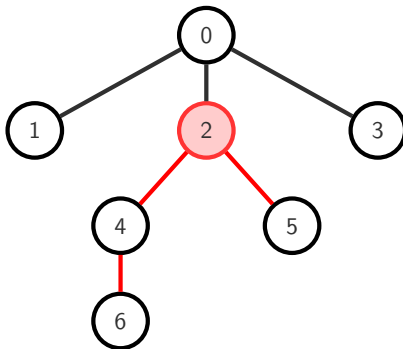
Complexity

Let n be the size of the input array $a[]$.

- BUILD: Each of the $2n - 1$ nodes is visited once. $\mathcal{O}(n)$.
- ADD: At most two nodes are visited on every level. $\mathcal{O}(\log n)$.
- SUM: At most four nodes are visited on every level. $\mathcal{O}(\log n)$.
- RANGEADD: At most four nodes are visited on every level. $\mathcal{O}(\log n)$.

LCA - Example

The *Lowest Common Ancestor (LCA)* of two nodes u and v in a tree is the deepest node that has both u and v as descendants. (A node is assumed to be a descendant of itself.)



$$\text{LCA}(5, 6) = 2$$

LCA - Computation

Naïve approach to compute $\text{LCA}(u, v)$:

- Compute the path from root to u and v .
- Find the first entry at which both paths differ.
- The LCA is the node right before this mismatch.

LCA - Computation

Naïve approach to compute $\text{LCA}(u, v)$:

- Compute the path from root to u and v .
- Find the first entry at which both paths differ.
- The LCA is the node right before this mismatch.
- Example above:
 - Path from root to node 5: $(0, 2, 5)$
 - Path from root to node 6: $(0, 2, 4, 6)$
 - LCA is 2.
- Complexity: $\mathcal{O}(n)$, where n is the number of nodes in the tree.

LCA - Computation

Naïve approach to compute $LCA(u, v)$:

- Compute the path from root to u and v .
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- Example above:
 - Path from root to node 5: $(0, 2, 5)$
 - Path from root to node 6: $(0, 2, 4, 6)$
 - LCA is 2.
- Complexity: $\mathcal{O}(n)$, where n is the number of nodes in the tree.

We can do better using segment trees!

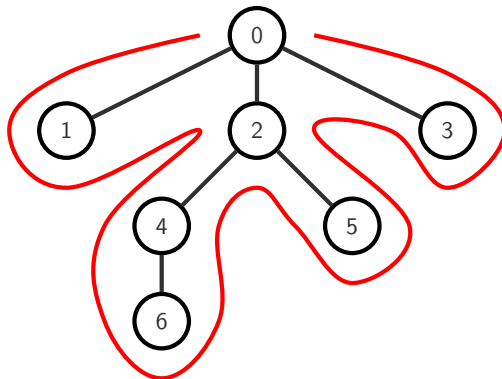
LCA - Eulerian Tour Technique

The *Eulerian Tour Technique* is a special representation of trees:

- Replace every undirected edge $\{u, v\}$ by two directed edges (u, v) and (v, u) .
- Compute an Eulerian cycle starting from the root.

The *Euler Tour Representation* (ETR) of a tree is the traversal order of nodes in the Eulerian cycle.

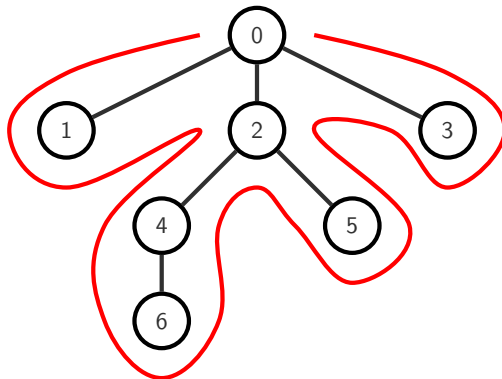
LCA - Eulerian Tour Representation



idx	0	1	2	3	4	5	6	7	8	9	10	11	12
ETR	0	1	0	2	4	6	4	2	5	2	0	3	0
depth	0	1	0	1	2	3	2	1	2	1	0	1	0

first visit

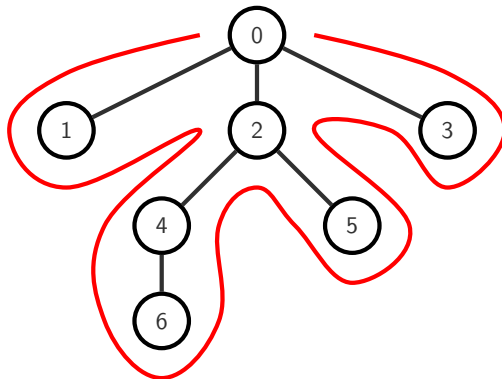
LCA - Eulerian Tour Representation



idx	0	1	2	3	4	5	6	7	8	9	10	11	12
ETR	0	1	0	2	4	6	4	2	5	2	0	3	0
depth	0	1	0	1	2	3	2	1	2	1	0	1	0

Depth of $\text{LCA}(5, 6)$ is 1, and $\text{LCA}(5, 6) = 2$.

LCA - Eulerian Tour Representation



idx	0	1	2	3	4	5	6	7	8	9	10	11	12
ETR	0	1	0	2	4	6	4	2	5	2	0	3	0
depth	0	1	0	1	2	3	2	1	2	1	0	1	0

Depth of $\text{LCA}(1, 3)$ is 0, and $\text{LCA}(1, 3) = 0$.

LCA - Computation

How to compute $\text{LCA}(u, v)$?

- Compute the ETR of the tree.
- Compute the depths corresponding to the nodes in the ETR.
- Store at which index a node is first visited in the ETR.
- Build a segment tree on the depth array using the minimum operator.
- $\text{LCA}(u, v)$ is the node associated to the minimum in the interval $[x, y]$ of the depth array, where x and y are the indices of the first occurrences of u and v in the ETR.

LCA - Complexity

Complexity

- Computing the ETR requires a tree traversal. $\mathcal{O}(n)$.
- Building the segment tree on the depth array. $\mathcal{O}(n)$.
- Any further computation of $\text{LCA}(u, v)$ requires one minimum query in the segment tree. $\mathcal{O}(\log n)$.