

abaisero.sty

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1 Commands

Option [math]

| Symbol | Command | Description | Example |
|--------------|--------------------------|----------------------------|---|
| \mathbb{N} | <code>\naturalset</code> | the set of natural numbers | $\mathbb{N} \doteq \{1, 2, 3, \dots\}$ |
| \mathbb{Z} | <code>\integerset</code> | the set of integer numbers | $\mathbb{Z} \doteq \{0, 1, -1, 2, -3, \dots\}$ |
| \mathbb{R} | <code>\realset</code> | the set of real numbers | $\sqrt{2} \in \mathbb{R}$ |
| $*$ | <code>\kstar</code> | the Kleene star operator | $\mathcal{X}^* \doteq \bigcup_{k=0}^{\infty} \mathcal{X}^k$ |
| $+$ | <code>\kplus</code> | the Kleene plus operator | $\mathcal{X}^+ \doteq \bigcup_{k=1}^{\infty} \mathcal{X}^k$ |
| softmax | <code>\softmax</code> | | |
| softmin | <code>\softmin</code> | | |
| sign | <code>\sign</code> | | $x = \text{sign } x \cdot x $ |

Option [linalg]

| Symbol | Command | Description | Example |
|------------|-------------------------|--|---|
| diag | <code>\diag</code> | | |
| rank | <code>\rank</code> | | |
| tr | <code>\trace</code> | | $\text{tr}(M) \doteq \sum_{i=1}^n M_{ii}$ |
| col | <code>\colspace</code> | | |
| ker | <code>\nullspace</code> | Nullspace (a.k.a kernel) of a linear mapping | |
| span | <code>\spanspace</code> | | |
| $^{\top}$ | <code>\T</code> | Transpose superscript | symmetric $M \implies M = M^{\top}$ |
| $^{-1}$ | <code>\I</code> | Inverse superscript | invertible $M \implies MM^{-1} = I$ |
| $^{+}$ | <code>\PI</code> | Pseudo-inverse superscript | $MM^{+}M = M$ |
| $^{-\top}$ | <code>\IT</code> | Inverse transpose superscript | $M^{-\top} = (M^{-1})^{\top} = (M^{\top})^{-1}$ |
| $^{+\top}$ | <code>\PIT</code> | Pseudo-inverse transpose superscript | $M^{+\top} = (M^{+})^{\top} = (M^{\top})^{+}$ |

Option [optim]

| Symbol | Command | Description | Example |
|-------------------------|----------------------|------------------------|--|
| argmax | <code>\argmax</code> | | $\operatorname{argmax}_a Q^\pi(s, a)$ |
| argmin | <code>\argmin</code> | | $\theta^* \doteq \operatorname{argmin}_\theta \mathcal{L}(\theta)$ |
| $*$ | <code>\opt</code> | Optimality superscript | $\pi^*(s) = \operatorname{argmax}_a Q^*(s, a)$ |

Option [stats]

| Symbol | Command | Description | Example |
|--------------------------------|-------------------|-----------------------------|---|
| \mathbb{C} | <code>\Cov</code> | Covariance | $\mathbb{C}(x, y) = \mathbb{E}[xy] - \mathbb{E}[x] \mathbb{E}[y]$ |
| \mathbb{H} | <code>\Ent</code> | Entropy | $\mathbb{H}[x] = -\mathbb{E}[\log \Pr(x)]$ |
| \mathbb{E} | <code>\Exp</code> | Expectation | $\mathbb{E}[f(x)] = \sum_x \Pr(x) f(x)$ |
| \mathbb{I} | <code>\Ind</code> | Indicator function | $\Pr(x = 0) = \mathbb{E}[\mathbb{I}[x = 0]]$ |
| KL | <code>\KL</code> | KL-divergence | $\operatorname{KL}(p q) \doteq \mathbb{E}_{x \sim p} \left[\log \left(\frac{p(x)}{q(x)} \right) \right]$ |
| $\operatorname{D}_{\text{KL}}$ | <code>\DKL</code> | KL-divergence (alternative) | |
| \mathbb{I} | <code>\MI</code> | Mutual Information | |
| \mathbb{V} | <code>\Var</code> | Variance | $\mathbb{V}[x] = \mathbb{E}[x^2] - \mathbb{E}[x]^2$ |

Option [dists]

| Symbol | Command | Description |
|-------------|---------------------------|-------------|
| Categorical | <code>\Categorical</code> | Categorical |
| Dirichlet | <code>\Dirichlet</code> | Dirichlet |
| Normal | <code>\Normal</code> | Normal |
| Uniform | <code>\Uniform</code> | Uniform |

Option [ml]

| Symbol | Command | Description | Example |
|---------------|--------------------|--------------------|--|
| \mathcal{D} | <code>\data</code> | Data set | $\mathcal{D} \doteq \{(x_i, y_i)\}_{i=1}^N$ |
| \mathcal{L} | <code>\loss</code> | Loss function | $\mathcal{L}(\theta; x, y) = \frac{1}{2} \ y - f(x; \theta)\ ^2$ |
| nll | <code>\nll</code> | Neg-log-likelihood | $\operatorname{nll}(x) \doteq -\log \Pr(x)$ |
| MSE | <code>\mse</code> | Mean-squared-error | |

Option [rl]

| Symbol | Command | Description |
|---------------|-------------------------|----------------------|
| \mathcal{A} | <code>\aset</code> | Action set |
| \mathcal{B} | <code>\bset</code> | Belief set |
| \mathcal{H} | <code>\hset</code> | History set |
| \mathcal{O} | <code>\oset</code> | Observation set |
| \mathcal{R} | <code>\rset</code> | Reward set |
| \mathcal{S} | <code>\sset</code> | State set |
| D | <code>\dfn</code> | Dynamics function |
| G | <code>\gfn</code> | Generative function |
| O | <code>\ofn</code> | Observation function |
| R | <code>\rfn</code> | Reward function |
| T | <code>\tfn</code> | Transition function |
| ε | <code>\nohistory</code> | Empty history |
| π | <code>\policy</code> | policy |
| Q^π | <code>\qpolicy</code> | Policy Q function |
| \hat{Q} | <code>\qmodel</code> | Parametric Q model |
| V^π | <code>\vpolicy</code> | Policy V function |
| \hat{V} | <code>\vmodel</code> | Parametric V model |
| U^π | <code>\upolicy</code> | Policy U function |
| \hat{U} | <code>\umodel</code> | Parametric U model |

Option [marl]

| Symbol | Command | Description |
|-----------------|-------------------------|------------------|
| $\bar{\pi}$ | <code>\policies</code> | Joint policies |
| \bar{h} | <code>\hs</code> | Joint histories |
| \bar{a} | <code>\as</code> | Joint actions |
| $Q^{\bar{\pi}}$ | <code>\qpolicies</code> | Joint Q function |
| $V^{\bar{\pi}}$ | <code>\vpolicies</code> | Joint V function |
| $U^{\bar{\pi}}$ | <code>\upolicies</code> | Joint U function |

Option [misc]

| Symbol | Command | Description |
|----------|-----------------------|----------------------------------|
| $^{(k)}$ | <code>\iter{k}</code> | Superscript indicating iteration |