



Personal Profile

Nationality Italian

Date of Birth 04 July 1988

I am an aspiring researcher in the field of machine learning. My research interests focalise on stochastic models for pattern recognition, reinforcement learning, representation learning, symbol learning and models for joint logic-geometric knowledge, with applications in general-purpose robotics, context-aware autonomous systems, and human-robot interaction.

Professional Experience and Activities

Feb $2013 \rightarrow$ Research Engineer, Machine Learning and Robotics Lab (MLR),

Ongoing University of Stuttgart, Germany.

- Detection of human-object and object-object *interaction phases* during sequential assembly task demonstrations, with extraction of assembly task representation.
- Encoding/decoding object identities into/from vision-based context-dependent human-like symbolic descriptions, and evaluation by means of user studies.
- Logic-geometric knowledge sharing. Developed Bayesian model for the inference of object features/geometry conditional to relational symbolic descriptions.
- Feb 2013 → **Teaching Assistant**, Machine Learning and Robotics Lab (MLR),

Ongoing University of Stuttgart, Germany.

- Teaching responsibilities in machine learning, seminar course in machine learning, mathematics for intelligent systems, optimization, and artificial intelligence.
- o Supervision of Bachelor and Master theses, and of undergraduate student research assistants.
- Sep $2012 \rightarrow$ Research Engineer, Computer Vision and Active Perception Lab (CVAP),
 - Dec 2012 Royal Institute of Technology (KTH), Sweden.
 - Refinement of theoretical and experimental aspects of the Master thesis project.

Education

Feb $2013 \rightarrow PhD$ in Machine Learning, ongoing,

Ongoing Machine Learning and Robotics Lab (MLR), IPVS

University of Stuttgart, Germany.

Supervision by Prof. Marc Toussaint.

Apr 2014 Machine Learning Summer School,

Reykjavik University, Iceland.

10-day summer school with focus on fundamental and advanced methods of machine learning, data analysis, and inference, from theory to practice.

Colocated with AISTATS 2014.

Aug $2010 \rightarrow \mathbf{MSc}$ in Engineering,

Oct 2012 Royal Institute of Technology (KTH), Sweden.

As a double-degree student from the Polytechnic University of Turin.

Sep $2009 \rightarrow \mathbf{MSc}$ in Computer Engineering, full marks (110/110) cum laude,

Nov 2012 Polytechnic University of Turin (PoliTo), Italy.

Sep $2006 \rightarrow \mathbf{BSc}$ in Computer Engineering, full marks (110/110) cum laude,

Oct 2009 Polytechnic University of Turin (PoliTo), Italy.

Master Thesis

Title Encoding Sequential Structures using Kernels – Path-Based Feature Space Embeddings for Sequential Data

Supervision Dr. Carl H. Ek (Senior Researcher) and Dr. Florian T. Pokorny (Postdoctoral Researcher) of the Computer Vision and Active Perception Lab (CVAP), Royal Institute of Technology (KTH).

Description Development of a novel family of modular kernel functions for sequential data embedding. Results published as *The Path Kernel* at ICPRAM 2013.

Honours and Awards

2013 AI Master Thesis Award, Swedish AI Society.

Yearly national award for the best Master thesis in the area of artificial intelligence.

Knowledge and Skills

Mathematics Advanced understanding of linear algebra and probability theory, motivated by the desire of a solid formal theoretical foundation for machine learning and modeling.

Machine Experienced with various machine learning methods, including standard regression and Learning classification models, SVMs, GPs, NNs, latent variable and mixture models, HMMs, CRFs, factor graphs, bayesian inference, and MCMC.

Robotics Working experience with the PR2 robot and the ROS framework.

Programming Proficient in (in order of preference) Python, C/C++, Matlab/Octave, and Bash/Zsh. Coursework experience with Java, JavaScript, ActionScript, and Assembly x86.

Computer Competent with GNU/Linux, git, vim, and LaTeX.

Languages

Self assessment according to CEFR.

Italian Native

English Proficient (C2) in understanding, speaking and writing.

French Independent (B2) in understanding and speaking. Basic (A2) in writing.

German Independent (B1) in understanding and speaking. Basic (A2) in writing.

Swedish Basic (A2) in understanding, speaking and writing.

Misc. Info

Licences Driving Licence (B).

International Life-long international experience gained by traveling the continents since early child-Experience hood, and living for long periods of time in cities including Mogadishu, Moscow, Venice, Johannesburg, Tunis, Paris, Turin, Stockholm and Stuttgart.

Languages Nurtural inclination towards language learning, having studied basics of widely diverse languages including Russian, Afrikaans and Arabic.

Hobbies and Classic and modern board games, with a preference for strategic war abstractions such Interests as Go, Backgammon or Shogi.

Publications

- [1] A. Baisero, F. T. Pokorny, D. Kragic, and C. H. Ek. "The Path Kernel." In: *ICPRAM*. 2013, pp. 50–57. (*Selected to appear as a revised version under the title "The Path Kernel: A Novel Kernel for Sequential Data" in *Pattern Recognition Application and Methods, Springer*, 2015, pp. 71–84).
- [2] A. Baisero, F. T. Pokorny, and C. H. Ek. "On a Family of Decomposable Kernels on Sequences". In: arXiv preprint arXiv:1501.06284 (2015).
- [3] A. Baisero, Y. Mollard, M. Lopes, M. Toussaint, and I. Luetkebohle. "Temporal segmentation of pair-wise interaction phases in sequential manipulation demonstrations". In: *Intelligent Robots* and Systems (IROS), 2015 IEEE/RSJ International Conference on. IEEE, 2015, pp. 478–484.
- [4] Y. Mollard, T. Munzer, A. Baisero, M. Toussaint, and M. Lopes. "Robot programming from demonstration, feedback and transfer". In: *Intelligent Robots and Systems (IROS)*, 2015 IEEE/RSJ International Conference on. IEEE, 2015, pp. 1825–1831.
- [5] A. Baisero, S. Otte, P. Englert, and M. Toussaint. "Identification of Unmodeled Objects from Symbolic Descriptions". In: arXiv:1701.06450 [cs, stat] (Jan. 23, 2017). arXiv: 1701.06450.