```
1
    import threading
 2
    import time
    import string
 3
4
    import secrets
 5
    import digitalio
    import board
 6
 7
    import adafruit_matrixkeypad
8
    from gpiozero import RGBLED, AngularServo
    from guizero import App, Slider
9
    from colorzero import Color
10
    import adafruit_character_lcd.character_lcd_i2c as character_lcd
11
12
    import busio
    from adafruit_ht16k33 import segments
13
    from imutils.video import VideoStream
14
    from imutils import resize
15
    from datetime import datetime, timedelta
16
    import json
17
    import requests
18
    import cv2
19
20
    import numpy as np
21
22
23
    24
     *************************
25
    def pin_check(pin, guess, sec, num, n):
26
27
        #Converts the digits entered list into a number
        guess = guess[0]*1000 + guess[1]*100 + guess[2]*10 + guess[3]
28
29
        #If the user entered the correct passcode
30
        if pin == guess:
31
32
            lcd.clear()
            rgb_led.color = Color(0, 255, 0)
33
34
            #If the user entered the second password correctly
35
            if sec == True:
36
               lcd.message = 'Come in!'
37
               rgb\_led.color = Color(0, 0, 255)
38
               servo_door.angle = 90
39
40
            #If the user entered the first password correctly
41
42
            else:
43
               sec = True
```

```
time.sleep(1.5)
44
45
              lcd.message ='Enter 2nd passcode: '
              n = 0
46
       #If the user entered the password incorrectly
47
       if pin != guess:
48
          lcd.clear()
49
50
           lcd.message = "Password Incorrect: Try Again"
51
           time.sleep(1.5)
          lcd.clear()
52
53
           lcd.message = 'Enter passcode: '
54
          #incorrect password counter
55
          n=n+1
56
57
58
          #If the user has entered the wrong password three consecutive times
          if n==3:
59
              lcd.clear()
60
              lcd.message = "Calling the cops!"
61
62
              time.sleep(1.5)
63
              #Displays a 5 second countdown on the 7-segment display
64
              for i in num:
65
                 display.fill(0)
66
                 display.print(str(i))
67
                 time.sleep(1)
68
69
       return n, sec
70
    def listToString(s):
71
72
73
       # initialize an empty string
       str1 = ""
74
75
76
       # traverse in the string
       for ele in s:
77
          str1 += ele
78
79
       # return string
80
       return str1
81
82
83
84
    85
    *****************
86
```

```
# Initialising I2C bus
 87
      i2c = board.I2C() # uses board.SCL and board.SDA
 88
 89
 90
      # Creating the LED segment class. This creates a 7 segment 4 character display:
      display = segments.Seg7x4(i2c)
 91
      display.fill(0)
 92
 93
 94
      # LCD Display setup
 95
      lcd\_columns = 16
 96
      lcd_rows = 4
 97
      lcd = character_lcd.Character_LCD_I2C(i2c, lcd_columns, lcd_rows)
 98
 99
100
      lcd.backlight = True
101
102
103
      # Setting up the membrane 3x4 matrix keypad on Raspberry Pi -
                                                                                               7
      https://www.adafruit.com/product/419
104
      cols = [digitalio.DigitalInOut(x) for x in (board.D26, board.D20, board.D21)]
      rows = [digitalio.DigitalInOut(x)  for x in (board.D5, board.D6, board.D13, board.D19)]
105
106
      keys = ((1, 2, 3),
107
              (4, 5, 6),
108
109
              (7, 8, 9),
              ("*", 0, "#"))
110
111
112
      keypad = adafruit_matrixkeypad.Matrix_Keypad(rows, cols, keys)
113
      # Setting up the RGB LED and initial color values
114
      rgb\_led = RGBLED(18, 23, 24)
115
116
117
      red = 0
118
      green = 0
      blue=0
119
120
121
      rgb_led.color = Color(255, 0, 0)
122
123
124
      # Setting up the zero
      servo_door = AngularServo(25, min_angle=-90, max_angle=90)
125
126
      servo\_door.angle = -90
127
128
      # Setting up global variables
129
      code=None
      password\_counter = 0
130
```

```
131
     pin_gen= 5678
     second_pin=False
132
133
     numbers = [5,4,3,2,1]
134
135
     pin_guess=[]
     pin_base = input("Please input a 4-digit passcode:\t")
136
137
     pin_base = int(pin_base)
138
     lcd.message = 'System Secure!'
139
140
     time.sleep(3)
141
     lcd.clear()
     lcd.message = 'Enter passcode:'
142
143
144
     145
     motion/face detection with uploading to google
     146
     ## Followed tutorial from https://www.youtube.com/watch?v=JwGzHitUVcU
147
     ## To generate Tokens:
148
     https://developers.google.com/oauthplayground/?code=4/0AVHEtk73eW0ZvkVXY1H_fDGe-vpiEHh 2
     qh1vZSYUH7ZDQTaaK7nrvGbyTl0ErsGYmQbxPnA&scope=https://www.googleapis.com/auth/drive
     diff_threshold = 1000000
149
150
     face_cascade = cv2.CascadeClassifier(cv2.data.haarcascades +
                                                                                     7
     'haarcascade_frontalface_default.xml')
     vs = VideoStream(src=0).start()
151
152
153
     # Header dictionary with a recently generated token
154
     header = {"authorization": "Bearer
     ya29.a0Ael9sCPc9xZqTMQpQ6d7indu3ywp8PD6pGAsaxJltC_QBBv0h8zzfo00xYpPQ05Jkgnj20MV_Hx7krv 7
     e_XBeZR0FDC2yw8WPltcUz6wLzUM9ff_IeNp2PoMDNApx_wFcp0BdkA2sXt2-wDvhPtYTrJM_aL3AaCqYKAWsS 7
     ARASFQF4udJhs558nPcakgz9x0w95cA71Q0163"}
155
     #parameter dictionary with the image file and url location of the folder on the
156
                                                                                     Z
     Google Drive
     param = {"name": "face.jpg",
157
             "parents": ['1AR3SLYY2wgiHyrXQBzQYqjTzHXERiog_']}
158
159
160
     # Converts param dictionary to a json string in order to upload the photo to the
                                                                                     7
     Google drive.
     files = {'data': ('metadata', json.dumps(param), 'application/json;charset=UTF-8'),
161
              'file':('face.jpg', open('face.jpg', 'rb'), 'image/jpeg')}
162
163
164
     face_detected = False
```

```
165
      start_face = None
166
      while True:
167
168
169
          # Starts the camera, saves two images, converts to grayscale, blurs the images,
                                                                                                7
          and finds the absolute difference between them
170
          old_image = vs.read()
171
          old_image = cv2.cvtColor(old_image, cv2.COLOR_BGR2GRAY)
          old_image = cv2.blur(old_image, (20, 20))
172
173
174
          new_image = vs.read()
175
          new_image = cv2.cvtColor(new_image, cv2.COLOR_BGR2GRAY)
          new_image = cv2.blur(new_image, (20, 20))
176
177
178
          diff = cv2.absdiff(old_image, new_image)
          diff_score = np.sum(diff)
179
180
          #If the sum of the difference between the two images is greater than the
181
                                                                                                Z
          difference threshold, then movement was detected
          if diff_score > diff_threshold:
182
              print("Movement detected")
183
184
          #Tries to determine if a face was able to be seen from the image
185
          faces = face_cascade.detectMultiScale(new_image, scaleFactor=1.1,
186
                                                                                                7
          minNeighbors=5, minSize=(30, 30))
187
          if len(faces) > 0:
188
              #If a face has been detected and and the face detection counter is set to
189
                                                                                                \overline{a}
              None (has not started)
190
              if (not face_detected) and (start_face is None):
191
192
                  #Begin the face detection timer
193
                  start_face = datetime.now()
                  print("Face detected")
194
195
196
                  # Take picture and set face_detected flag to True
197
                  cv2.imwrite("face.jpg", new_image)
198
                  #Upload the picture to google drive using the header and files
199
                                                                                                7
                  dictionaries that contain the json string and token
200
                  face_detected = True
                  r = requests.post(
201
202
                      "https://www.googleapis.com/upload/drive/v3/files?uploadType=multipart 7
```

```
203
                      headers = header,
204
                      files = files)
205
206
                  if r.status_code == 200:
207
                      print("File uploaded successfully!")
                  else:
208
209
                      print("Failed to upload files :(")
210
          else:
211
              #If a face has not been detected
212
213
              if face_detected:
214
                  face_detected = False
215
216
          #If the face detection timer is not none (has already begun) and it has been
                                                                                               7
          more than 1 minute since it has begun
217
          if (start_face is not None) and (datetime.now() > start_face +
                                                                                               7
          timedelta(minutes=1)):
218
              print("reset")
219
              #Reset the time
220
221
              start_face = None
222
223
          old_image = new_image
224
225
          #If the keypad has been pressed
226
          if keypad.pressed_keys:
227
228
              #appends to the pressed keys list
229
              pin_guess.append((keypad.pressed_keys)[0])
230
231
              #Clears the LCD screen and displays the keys that hav been entered
232
              lcd.clear()
233
              lcd.message = 'Code: {}'.format(pin_guess)
234
              print(pin_guess)
235
              time.sleep(0.2)
236
237
              #If 4 digits have been entered and the user is on the first passcode
              if (len(pin_guess)>3) & (second_pin == False):
238
                  password_counter,second_pin =
239
                                                                                               7
                  pin_check(pin_base,pin_guess,second_pin,numbers, password_counter)
240
                  pin_guess=[]
241
242
              #If 4 digits have been entered and the user is on the second password
243
              if (len(pin_guess)>3) & (second_pin == True):
                  password_counter,second_pin = pin_check(pin_gen,pin_guess,second_pin,
244
                                                                                               Z
```

/home/abakhtar/Documents/com_no_int.py Page 7 of 7		Wed	26	Apr	2023	09:57:23	PM	EDT
	numbers, password_counter)							
245	pin_guess=[]							
246								
247								
248								
249								
250								