Albert Balbon

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https://github.com/abalbon

EDUCATION

California State University, Fullerton

Expected May 2020

Bachelor of Science, Computer Science

Cumulative GPA: 3.27

Saddleback College

Graduated December 2017

Dean's List 2014-2017

Associates of Science, Computer Science

Cumulative GPA: 3.43

RELATED COURSES

Mobile Dev Programming Web Front-End Engineering

| Operating Systems Concepts

| Data Science and Big Data Analysis

| Algorithm Engineering

| Software Engineering

WORK EXPERIENCE

Starbucks, Barista/Shift Supervisor

Aliso Viejo, CA

August 2016 - Present

- Acting Manager at a high volume store to ensure positive customer service
- Daily cash handling and inventory counts

TECHNICAL SKILLS

- Languages: C++, Python, some experience with Java, HTML, CSS, JavaScript, React.js, Assembly, Machine Language, mySQL
- Technologies: Qt Creator, Github, VS Code, ROS, Linux, DB browser

PROJECTS

Optimism

- Full stack web application that visualizes certain aspects of life based on moods and factors input by the user.
 Developed using HTML, CSS, Javascript, React.js for the front-end and Flask and mongoDB in the back-end
- The goal in creating Optimism is to create a visual guide for individuals to track and improve their moods throughout the day in order to make positive changes in their lives on a daily basis.

College Tour Planner

- Using C++ and Qt creator to develop a College Tour planner using Dijkstra's Algorithm. SQLite was implemented to store various different information about each college.
- College Tour Planner was created as an application for graduating high school students to have the most efficient way of visiting colleges they plan to attend.

EXTRA CURRICULAR

Titan Rover

September 2019 - Present

- Collaboration between CSUF students from different STEM majors to design, create, develop a fully functional Mars Exploration Rover to be entered into the University Rover Challenge
- Main responsibility for programming embedded system devices such as GNSS modules to aid in autonomous
 driving, ultrasonic sensors to provide a fail safe when the rover approaches a cliff, and the ZED stereo camera to
 identify AR codes and complete challenges and objectives set up by the University Rover Challenge