

# Machine Learning Problemset 1

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## Problemset 1

**1. Consider the binary classification problem with a priori probabilities  $P\{Y = 1\} = P\{Y = 0\} = \frac{1}{2}$  and class-conditional densities  $f_0(x) = f(x|Y = 0)$  and  $f_1(x) = f(x|Y = 1)$  on  $X = \mathbb{R}_d$ . Prove that the Bayes risk equals:**

$$R^* = \frac{1}{2} - \frac{1}{4} \int |f_1(x) - f_0(x)| dx$$

We know that:

$$\begin{aligned} R^* &= \int \min(\eta(x), 1 - \eta(x)) dx \\ \eta(x) &= (1 - \frac{1}{2})f_1(x) \\ 1 - \eta(x) &= \frac{1}{2}f_0(x) \end{aligned}$$

Substituting for  $\eta(x)$  gives:

$$\begin{aligned} R^* &= \int \min((1 - \frac{1}{2})f_1(x), \frac{1}{2}f_0(x)) dx \\ &= \int \min(f_1(x) - \frac{1}{2}f_1(x), \frac{1}{2}f_0(x)) dx \\ &= \int \min(\frac{1}{2}f_1(x), \frac{1}{2}f_0(x)) dx \\ &= \frac{1}{2} \int \min(f_1(x), f_0(x)) dx \end{aligned}$$

The minimum of two functions can be expressed:

$$\min(f_1(x), f_0(x)) = \frac{1}{2}[f_1(x) + f_0(x) - |f_1(x) - f_0(x)|]$$

Substituting this equality:

$$\begin{aligned} R^* &= \frac{1}{2} \int \frac{1}{2}[f_1(x) + f_0(x) - |f_1(x) - f_0(x)|] dx \\ &= \frac{1}{4} \left[ \int f_1(x) dx + \int f_0(x) dx - \int |f_1(x) - f_0(x)| dx \right] \end{aligned}$$

Since  $f_0(x)$  and  $f_1(x)$  are probability density functions, the first two terms integrate to 1, so the above can be reduced to:

$$= \frac{1}{2} - \frac{1}{4} \int |f_1(x) - f_0(x)| dx$$

**2. Consider a binary classification problem in which both class-conditional densities are multivariate normal of the form**

$$f_i(x) = \frac{1}{\sqrt{2\pi \det(\Sigma_i)}} e^{-\frac{1}{2}(x-m_i)^T \Sigma_i^{-1}(x-m_i)}$$

**where  $m_i = \mathbb{E}[X|Y = i]$  and  $\Sigma_i$  is the covariance matrix for class  $i$ . Let  $q_0 = P\{Y = 0\}$  and  $q_1 = P\{Y = 1\}$  be the a priori probabilities. Determine the Bayes classifier. Characterize the cases when the Bayes decision is linear (i.e., it is obtained by thresholding a linear function of  $x$ ).**

The Bayes classifier is given by

$$g^* = \begin{cases} 1 & \text{if } q_1 f_1(x) > q_0 f_0(x) \\ 0 & \text{otherwise} \end{cases}$$

To determine when  $q_1 f_1(x) > q_0 f_0(x)$ , take the log of both sides to facilitate an easier equality and reduce to determine when:

$$2 \left[ \log\left(\frac{q_1}{\sqrt{2\pi \det(\Sigma_1)}}\right) - (x - m_1)^T \Sigma_1^{-1}(x - m_1) \right] > 2 \left[ \log\left(\frac{q_0}{\sqrt{2\pi \det(\Sigma_0)}}\right) - (x - m_0)^T \Sigma_0^{-1}(x - m_0) \right]$$

Which can be further reduced to:

$$2 \log(q_1) - \log(\det \Sigma_1) - (x - m_1)^T \Sigma_1^{-1}(x - m_1) > 2 \log(q_0) - \log(\det \Sigma_0) - (x - m_0)^T \Sigma_0^{-1}(x - m_0)$$

We can simplify this expression using the following:

$$r_i^2 = (x - m_i)^T \Sigma_i^{-1}(x - m_i) \text{ (i.e. the Mahalanobis distance)}$$

and we get the Bayes classifier is reduced to:

$$g^* = \begin{cases} 1 & \text{if } r_1^2 > r_0^2 + 2 \log\left(\frac{q_1}{1-q_1}\right) + \log\left(\frac{\det \Sigma_0}{\det \Sigma_1}\right) \\ 0 & \text{otherwise} \end{cases}$$

When  $\Sigma_1 = \Sigma_0 = \Sigma$ , the last term is 0:

$$g^* = \begin{cases} 1 & \text{if } r_1^2 > r_0^2 + 2 \log\left(\frac{q_1}{1-q_1}\right) \\ 0 & \text{otherwise} \end{cases}$$

This inequality is linear in  $x$ , so the classification rule is linear.

**3. Let  $(X, Y)$  be a pair of random variables taking values in  $X \times \mathbb{R}$  and consider a prediction problem in which one desires to guess the value of  $Y$  upon observing  $X$ . Suppose that the loss function is  $\ell(y, y') = (y - y')^2$ . Determine the predictor function  $f : X \rightarrow \mathbb{R}$  that minimizes the expected loss  $E(f(X), Y)$ .**

The expected loss can be expressed as:

$$\mathbb{E}\ell(y, y') = \int \ell(y, y') p(y|x) dy$$

$$= \int (y - y')^2 p(y|x) dy$$

Where  $p(y|x)$  is the conditional distribution of  $y$  on  $x$ .

To determine the predictor function that minimizes the expected loss, we can take the derivative of the expected loss with respect to  $y'$ , set to 0 and solve for  $y'$ :

$$\begin{aligned} 0 &= \frac{\partial}{\partial y'} \int (y - y')^2 p(y|x) dy \\ &= \int \frac{\partial}{\partial y'} \left[ (y - y')^2 p(y|x) \right] dy \\ &= \int 2(y - y') p(y|x) dy \\ &= 2y' \int p(y|x) dy - 2 \int yp(y|x) dy \\ 0 &= y' - \int yp(y|x) dy \end{aligned}$$

The second term is equivalent the expected value of  $y$  at  $x$ , thus:

$$y' = \mathbb{E}[Y|X = x]$$

The predictor function which minimizes the expected loss function is the expected value of  $Y$  at  $X = x$ , in other words the mean of  $Y$  at  $x$ .

**4. Repeat the previous problem but with  $\ell(y, y') = |y - y'|$ . You may assume that for each  $x \in X$ , the conditional distribution of  $Y$ , given  $X = x$ , has a density  $\phi(y|x)$ .**

Similar to 3, we can estimate the expected loss in the following way:

$$\begin{aligned} \mathbb{E}\ell(y, y') &= \int |y - y'| \phi(y|x) dy \\ &= \int_{y'}^{-\infty} (y - y') \phi(y|x) dy + \int_{-\infty}^{y'} (y' - y) \phi(y|x) dy \end{aligned}$$

To find the best prediction function, we minimize the expected loss by taking the derivative, setting to 0 and solving for  $y'$ :

$$\begin{aligned} 0 &= \frac{\partial}{\partial y'} \int_{y'}^{-\infty} (y - y') \phi(y|x) dy + \frac{\partial}{\partial y'} \int_{-\infty}^{y'} (y' - y) \phi(y|x) dy \\ &= \int_{y'}^{-\infty} -\phi(y|x) dy + \int_{-\infty}^{y'} \phi(y|x) dy \\ \int_{y'}^{-\infty} \phi(y|x) dy &= \int_{-\infty}^{y'} \phi(y|x) dy \end{aligned}$$

The above is equivalent to the probability densities:

$$\mathbb{P}(Y \leq y'|x) = \mathbb{P}(Y \geq y'|x)$$

Thus the best predictor function is the  $y'$  where these probabilities are equivalent. These are equal at the median of  $Y$  at  $X = x$ .

**5. Let  $X, X_1, \dots, X_n$  be i.i.d. random vectors, uniformly distributed on  $[0, 1]^d$ . Let  $k$  be a fixed positive integer and let  $X_{(k)}$  denote the  $k$ -th nearest neighbor of  $X$  among  $X_1, \dots, X_n$ . (We assume  $n \geq k$ .) Prove that:**

$$\lim_{n \rightarrow \infty} \|X_{(k)} - X\| = 0 \text{ in probability.}$$

$b_d$  is the unit sphere centered at  $x$ , with radius  $\epsilon$ . The distance of the  $k$  nearest neighbors from  $x$  can only be greater than the radius of the ball centered at  $x$  when there are less than  $k$   $X_i$  in the sphere centered at  $x$ .

$$\mathbb{P}\{\|X_k(x) - X\| > \epsilon\} = 1 - b_d \epsilon^d$$

which is certainly less than:

$$\mathbb{P}\{\|X_k(x) - X\| > \epsilon\} \leq 1 - \frac{b_d}{2^d} \epsilon^d$$

To simplify we set  $c_d = \frac{b_d}{2^d}$ :

$$\mathbb{P}\{\|X_k(x) - X\| > \epsilon\} \leq (1 - c_d \epsilon^d)^n$$

Using the inequality  $1 + x \leq e^x$ :

$$\mathbb{P}\{\|X_k(x) - X\| > \epsilon\} \leq e^{-nc_d \epsilon^d}$$

As  $n$  goes to  $\infty$  this term goes to 0 and

$$\|X_k(x) - X\| = 0 \rightarrow 1$$

in probability.

**6. Show that for any sample size  $n$  there exists a distribution of  $(X, Y)$  such that  $R^* = 0$  but the expected risk of the 1-nearest neighbor classifier is greater than  $\frac{1}{4}$ .**

As described in Theorem 7.1 of *A Probabilistic Theory of Pattern Recognition*, the lower bound for the expected risk of any classifier can be determined by the supremum of the risk for the binary expansion of a uniform random variable  $b \in [0, 1)$  which parameterizations any given distribution of  $(X, Y)$  as follows:

For any distribution  $(X, Y)$ ,  $X$  is defined on the set of positive integers from  $\{1, \dots, K\}$  where  $K$  is an arbitrarily large number to be decided later, such that:

$$p_i = \mathbb{P}(X = i) \begin{cases} \frac{1}{K} & \text{for } i = 1, \dots, K \\ 0 & \text{otherwise} \end{cases}$$

A lower bound for the expectation of the error of any given decision rule  $g_n(X)$  conditional on the observed distribution of data  $D_n$  is  $\mathbb{E}[L_n] = R_n(b)$ .  $b$  is uniformly distributed  $[0, 1)$  and acts as a parameter of the distribution of  $(X, Y)$  such that it determines the distribution of  $Y$  as the binary expansion of  $b$  and  $b_X = Y$ . There exists a  $b$  such the risk of the decision rule  $g_n$  is at a maximum.

The expected value of the risk  $R_n(B)$  must be less than or equal to the maximum risk  $R_n(b)$ .

$$\sup_{b \in [0, 1)} R_n(b) \leq \mathbb{E}\{R_n(B)\}$$

The expected value of this random variable,  $\mathbb{E}\{R_n(B)\}$  is a lower bound for the expected risk of any given decision rule.

$$\begin{aligned}\mathbb{E}\{(R_n(B))\} &= \mathbb{P}\{(g_n(X, D_n)) \neq Y\} \\ &= \mathbb{P}\{(g_n(X, D_n)) \neq B_X\}\end{aligned}$$

When  $g_n$  is the 1-nearest neighbor rule this becomes

$$= \mathbb{P}\{(g_n(X, D_n)) \neq B_{X'}\}$$

Where  $B_{X'}$  is the nearest neighbor of  $B_X$  when trying to classify  $X$

$$\begin{aligned}&= \mathbb{P}\{B_{X'} \neq Y\} \\ &\geq \frac{1}{2} \mathbb{P}\{B_{X'} \neq B_X\}^n \\ &\geq \left(1 - \frac{1}{K}\right)^n\end{aligned}$$

This is  $\frac{1}{2}$  as  $K \rightarrow \infty$ . In other words, as the space on which  $X$  is defined  $\{1, \dots, K\}$  grows, the lower bound for the expected risk for any decision rule is  $\frac{1}{2} - \epsilon$  where  $\epsilon$  is a small number.