

# Andres Barrios

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## EDUCATION

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### The University of Texas at Austin

*Bachelor of Science, Mechanical Engineering Honors*

*Certificate: Programming and Computation*

December 2026

**GPA: 4.0**

## TECHNICAL SKILLS

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**CAD/Analysis:** SolidWorks, Autodesk Inventor, Onshape, Inventor Simulation, DFMA, Tolerance Stack-Up Analysis

**Manufacturing:** 3D Printing, CNC Machining, Injection-Molding, GD&T

**Programming:** Python, MATLAB

## PROFESSIONAL EXPERIENCE

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### Oden Institute: Center of Autonomy – Undergraduate Research Assistant | Austin, TX

September 2025 - Present

- Design and prototype low-cost robotic manipulation platforms by integrating 3D-printed arm assemblies, mobile bases, and custom manipulators for household and lab testbed applications tasks
- Integrate 6-DOF robotic arm with gripper end-effectors into lead screw-driven body, designing custom attachments in Onshape for 80/20 aluminum frame to increase adaptability and enable vertical reach up to 900 mm

### Samsung – Mechanical Design Engineer Intern | Austin, TX

May 2025 - August 2025

- Designed mechanical assembly in Autodesk Inventor implementing electric actuators and custom-built pipe collar to safely lift 200 lb piping within pump input subsystem, eliminating operator handling risks
- Created detailed GD&T drawings for machined pipe collar and adjustable claw clamps, using manufacturer DFM feedback to optimize parts for machining while upholding existing design constraints
- Analyzed potential failure modes of lifting system, confirming via hand calculations that clamping-induced hoop stress remained below pipe yield strength and frictional torque was sufficient to resist actuator-induced rotation
- Evaluated stress under applied torque on steel collar internal corners using Inventor Simulation to prevent lifting failure

### Amazon Robotics – Mechanical Design Engineer Intern | North Reading, MA

January 2025 - May 2025

- Operated within team of mechanical engineers in design development cycle of new fully autonomous drive unit robot releasing in over 1000 distribution centers, including prototyping and validation of hardware components
- Designed bolted wheel hub and taper-lock attachment in SolidWorks for drive unit robot, aimed to facilitate wheel removal from locomotors and to reduce downtime during component testing and inspection by over 50%
- Optimized wheel system assembly by performing tolerance stack-up analyses and updating GD&T drawings for both machined parts, eliminating worst-case interference between critical wheel and locomotor surfaces
- Prototyped six modular ‘skeleton’ drive units, enabling in-facility testing of locomotors and sensor field-of-vision mapping

### BP – Mechanical Reliability Engineer Intern | Whiting, IN

May 2024 - August 2024

- Developed injection quill design to minimize fluid impingement at pipe tee junction, analyzing flow conditions to optimize material selection and evaluate vibration effects on quill stability in piping system
- Coordinated delivery of proper design requirements of injection quill, per ASME B31.3 standards, with third-party vendor
- Designed new drainpipe for condensate removal, improving steam heat transfer efficiency to piping systems by creating new drainage line with ASME-compliant sloping to prevent condensate accumulation in critical fluid lines

## PROJECTS

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### RC Car | SolidWorks, Prototyping

September 2025 - Present

- Design RC racecar in SolidWorks with team of five students and oversee prototype fabrication, material selection, and assembly within \$100 budget for competitive performance against 20+ teams

### Fidget Spinner Manufacturing | SolidWorks, FEA, Prototyping

August 2023 - December 2023

- Developed three fidget spinner models in SolidWorks, with various prototypes manufactured using different machine-shop tools, including a 3D printer, CNC laser cutter, and injection-molding machine
- Analyzed high-stress regions on model with SolidWorks Simulation to help optimize design for stability and durability

## LEADERSHIP AND PROFESSIONAL DEVELOPMENT

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### Management Leadership for Tomorrow (MLT) – Career Preparation Fellow

January 2025 - Present

- Accepted into selective 18-month professional development program for high-achieving talent
- Complete business case studies and assignments to grow leadership and technical skills relevant to technology sectors
- Attend conferences hosted by industry leaders such as Apple, Google, and LinkedIn