Operating Systems: Deadlocks – PART II

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Deadlock Avoidance algorithm Outline

- Given the resource allocation state of a system,
 - The algorithm checks if the system is in a safe state.
 - ➤ If the system is in a safe state, whenever a process requests an instance of a resource type,
 - It checks to see if allocating the resources continues to have the system in a safe state.
 - If yes -- allocate the resources.
 - If no -- have the process wait.

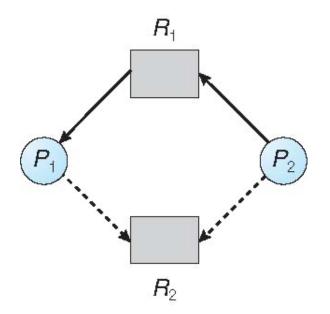
Deadlock Avoidance Algorithms

- Single instance of a resource type
 - ➤ Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the Banker's algorithm

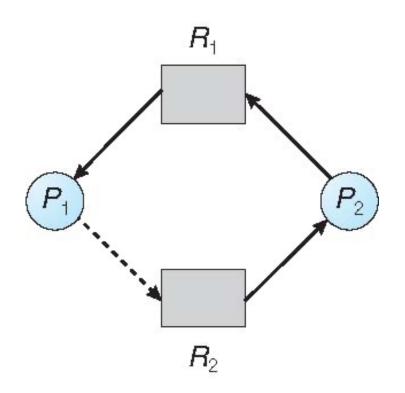
Resource-Allocation Graph Scheme

- Add claim edges to existing resource allocation graph.
- Claim edge $P_i \rightarrow R_j$ indicates that process P_i may request resource R_i ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system



Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_i
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph
- We check for safety by using a cycledetection algorithm.



Unsafe State In Resource- Allocation Graph

Although R_2 is free, we cannot allocate it to P_2 since this will create a cycle!

Banker's Algorithm Outline for multiple instances of a resource type

- The algorithm consists of two parts
 - PART 1 Safety Algorithm checks whether a system is in a safe state or not.
 - ➤ PART 2 Resource-Request Algorithm checks to see if resources requested by a process can be satisfied or not.
- Each process must a priori claim maximum use
- When a process gets all its resources it must return them in a finite amount of time
- When a process requests a resource, it may have to wait

Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type R_i available
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i
- Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_j
- Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$

Example of Data Structures for Banker's Algorithm

• 5 processes P_0 through P_4 ;

3 resource types:

A (10 instances), B (5 instances), and C (7 instances)

Resource allocation state at time T_0 :

	Max. Need			All	ocat	tion	A vailable				
	Α	В	С	Α	В	С	Α	В	С		
P_0	7	5	3	0	1	0	3	3	2		
P_1	3	2	2	2	0	0					
P_2	9	0	2	3	0	2					
P_3	2	2	2	2	1	1					
P_4	4	3	3	0	0	2					

Need matrix for Banker's Algorithm

The content of the matrix *Need* is defined to be *Max. Need – Allocation*

5 processes P₀ through P₄;

3 resource types:

A (10 instances), B (5 instances), and C (7 instances)

Snapshot at time T_0 :

	Max	. Need	I	Allo	cation		Nee	d		Ava	ilable	
	Α	В	С	Α	В	С	A	В	С	Α	В	С
P_0	7	5	3	0	1	0	7	4	3	3	3	2
P_1	3	2	2	2	0	0	1	2	2			
P_2	9	0	2	3	0	2	6	0	0			
P_3	2	2	2	2	1	1	0	1	1			
P ₄	4	3	3	0	0	2	4	3	1			

Part 1 - Safety Algorithm outline explained with an example

Step 1: Maintain *Work* and *Finish* vectors of length *m* and *n*, respectively.

Initialize:

Finish [
$$i$$
] = false, i ∈ [0, n -1]

Work. =
$$(3 \ 3 \ 2)$$

Step 2: Find a process P_i such that both:

(a) Finish [i] = false

P₁ satisfies conditions (a) and (b)

(b) **Need**_i ≤ **Work**

If no such *i* exists, go to step 4

Part 1 - Safety Algorithm outline explained with an example – contd...

Step 3:

Work = Work + Allocation;
Finish[i] = true

Go to step 2

$$Work = Work + Allocation_1$$

$$= (3 3 2) + (2 0 0) = (5 3 2)$$
 $Finish[1] = true$
 $Finish = False True False False False$

Next, we see that process P_3 , P_4 , P_2 , and P_0 all satisfy the conditions in step 2.

Step 4: If Finish[i] == true for all i, then the system is in a safe state

Therefore, the system is in a safe state and the sequence of processes satisfying the safety requirement is -

$$< P_1, P_3, P_4, P_2, P_0 >$$

Part – 2 Resource-Request Algorithm for Process P_i

- **Request**_i = request vector for process P_i . If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i
- Step 1: If Request_i ≤ Need_i go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- Step 2: If Request_i ≤ Available, go to step 3. Otherwise, P_i must wait, since resources are not available
- Step 3: Pretend to allocate requested resources to P_i and update the system state as follows:

Available = Available - Request_i; Allocation_i = Allocation_i + Request_i; Need_i = Need_i - Request_i;

- \triangleright If safe \Rightarrow the resources are allocated to P_i
- ightharpoonup If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored

PART 2 - Resource-Request Algorithm Explained with an Example

- P₁ requests resources (1 0 2)
- Check if Request₁ ≤ Need₁
 - ightharpoonup (1 0 2) \leq (1 2 2) \Rightarrow true
- Check if Request₁ ≤ Available
 - ightharpoonup (1 0 2) \leq (3 2 2) \Rightarrow true
- Pretend that resources requested have be granted.
- Update system state. Max need, Allocation₁ and Need₁ data structures
 - \rightarrow Available₁ = (3 2 2) (1 0 2) = (2 2 0)
 - \rightarrow Allocation₁ = (2 0 0) + (1 0 2) = (3 0 2)
 - ightharpoonup Need₁ = (1 2 2) (1 0 2) = (0 2 0)

PART 2 - Resource-Request Algorithm Explained with an Example contd...

Updated resource allocation state:

		Max. Need		Allocation			Need				Available			
	Α	В	С	Α	В	С	Α	В	С		Α	В	С	
P_0	7	5	3	0	1	0	7	4	3		2	2	0	
P ₁	3	2	2	3	0	2	0	2	0					
P_2	9	0	2	3	0	2	6	0	0					
P_3	2	2	2	2	1	1	0	1	1					
P_4	4	3	3	0	0	2	4	3	1					

PART 2 - Resource-Request Algorithm Explained with an Example contd...

- Run safety algorithm on the updated resource allocation state.
- System is in safe state and the sequence of processes satisfying the safety requirement is $\langle P_1, P_3, P_4, P_2, P_0 \rangle$

Updated Resource allocation state after request has been granted for P₁

	Ma Ne	ix. ed		All	ocat	tion	Ne	ed		Av	ailak	ole
	Α	В	С	Α	В	С	Α	В	С	Α	В	С
P_0	7	5	3	0	1	0	7	4	3	2	2	0
P_1	3	2	2	3	0	2	0	2	0			
P_2	9	0	2	3	0	2	6	0	0			
P_3	2	2	2	2	1	1	0	1	1			
P_4	4	3	3	0	0	2	4	3	1			

Resource-Request Algorithm Example – Cont...

- When system in this state, can request for (3 3 0) by P_4 be granted?
 - Check if Request₄ ≤ Available
 - \circ (3 3 0) \leq (2 2 0) \Rightarrow false
 - The request cannot be granted.
- When system in this state, can request for $(0\ 2\ 0)$ by P_0 be granted?
 - Check if Request₀ ≤ Need₀
 - \circ (0 2 0) \leq (7 4 3) \Rightarrow true
 - Check if Request₀ ≤ Available
 - \circ (0 2 0) \leq (2 2 0) \Rightarrow true
 - > Pretend to grant the resources requested.

Resource-Request Algorithm Example – Cont...

Updated Resource allocation state

	Ma Ne			All	ocat	tion	Ne	ed		Av	ailak	ole
	Α	В	С	Α	В	С	Α	В	С	Α	В	С
P_0	7	5	3	0	3	0	7	2	3	2	0	0
P_1	3	2	2	3	0	2	0	2	0			
P_2	9	0	2	3	0	2	6	0	0			
P_3	2	2	2	2	1	1	0	1	1			
P_4	4	3	3	0	0	2	4	3	1			

➤ However, since no sequence of processes exist that satisfies the safe state requirement, P₀'s request cannot be granted as doing so will leave the system in an unsafe state.

Deadlock Detection

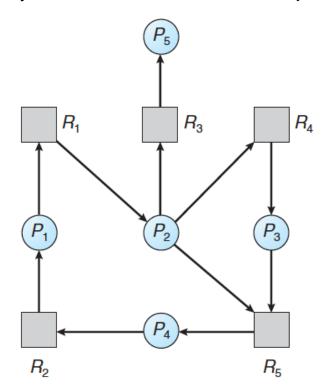
Allow system to enter deadlock state

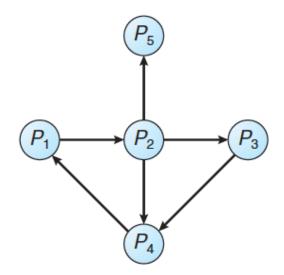
Use deadlock detection algorithm to check if a deadlock exists

If deadlock exists, use a recovery scheme to recover from the deadlock

Deadlock Detection - Single Instance of Each Resource Type

- A variant of the resource-allocation graph if all resources have only a single instance used for deadlock detection
- Nodes are processes, and an edge $P_i \rightarrow P_j$ in the wait for graph implies that P_i is waiting for P_i to release a resource that P_i needs.



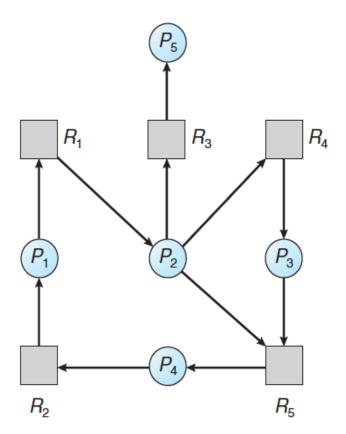


Corresponding wait-for graph

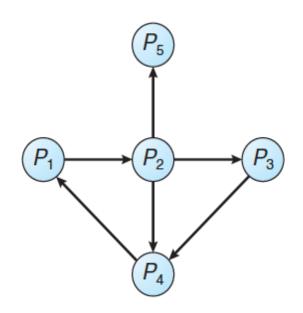
Resource-Allocation Graph

Deadlock Detection - Single Instance of Each Resource Type

If a cycle exists in the wait-for graph, then the system is in deadlock.



Resource-Allocation Graph



Corresponding wait-for graph

Deadlock Detection Algorithm for Multiple Instances of a Resource Type

- The algorithms needs to know
 - ➤ The number of *available resources and allocated resources* for each resource type.
 - > The number of *requested resources* by all processes in the system.
- Given the above,
 - The deadlock detection algorithm checks whether the system is in a deadlocked state or not.
 - If the system is in a deadlocked state, then the algorithm also identifies the processes involved in the deadlock.

Deadlock Detection Algorithm for Multiple Instances of a Resource Type Data Structures

- Available: A vector of length m indicates the number of available resources of each type
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process
- Request: An $n \times m$ matrix indicates the current request of each process. If Request[i][j] = k, then process P_i is requesting k instances of resource type R_j .

Deadlock Detection Algorithm

- Let Work and Finish be vectors of length m and n, respectively Initialize:
 - (a) Work = Available
 - (b) For i = 1, 2, ..., n,
 - if Allocation; ≠ 0, then Finish[i] = false;
 - ii. otherwise, *Finish*[i] = *true*
- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) **Request**_i ≤ **Work**

If no such *i* exists, go to step 4

Items in red highlight the differences in Deadlock detection algorithm and the safety algorithm described under Banker's algorithm.

Detection Algorithm (Cont.)

3. Work = Work + Allocation_i

Finish[i] = true

go to step 2

4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked.

Example for Deadlock Detection Algorithm

- Five processes P₀ through P₄
- Three resource types
 A (7 instances), B (2 instances), and C (6 instances)
- Snapshot of the system at time T_0 :

	Allocation	Request	Available				
	A B C	A B C	A B C				
P_0	0 1 0	0 0 0	0 0 0				
P ₁	2 0 0	2 0 2					
P_2	3 0 3	0 0 0					
P_3	2 1 1	1 0 0					
P ₄	0 0 2	0 0 2					

Example of Detection Algorithm Cont...

Step 1:

1. Work = Available = $(0\ 0\ 0)$

Since Allocation_i \neq 0, for all i \in [1, n]

Step 2: Find an index **i** such that both:

- 1. Finish[i] == false
- 2. $Request_i \leq Work$

If no such i exists, go to step 4

P₀ satisfies the above two conditions.

Example of Detection Algorithm Cont...

- Step 3:
 - Work = Work + Allocation₀ = (0 0 0) + (0 1 0) = (0 1 0)
 Finish[1] = true
 go to step 2
- We see that process P_2 , P_3 , P_1 , and P_4 all satisfy the conditions in step 2.

Finally, in Step 4: Finish =

|--|

Therefore, the system is not in a deadlocked state, as the following sequence of processes results in all values of the Finish vector to be True:

Example of Detection Algorithm Cont...

- Suppose P₂ requests an additional instance of type C.
- Then below is the updated snapshot of the system including this request:

	Allocation	Request	Available
	A B C	A B C	A B C
P_0	0 1 0	0 0 0	0 0 0
P_1	2 0 0	2 0 2	
P_2	3 0 3	0 0 1	
P_3	2 1 1	1. 0 0	
P_4	0. 0 2	0 0 2	

- Can reclaim resources held by process P_0 , but insufficient resources to fulfill other processes' requests
- Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4

Recovery from Deadlock

Process Termination

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated

Resource Preemption

- Selecting a victim minimize cost
- > Rollback return to some safe state, restart process for that state
- ➤ Starvation same process may always be picked as victim. Possible solution include number of rollback in cost factor