

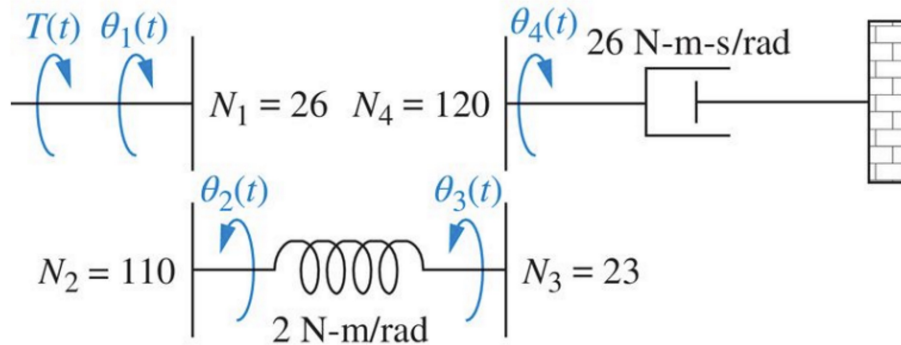
Quiz 4

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1. Rotational Mechanical Systems (10 marks)

Consider the system show below:

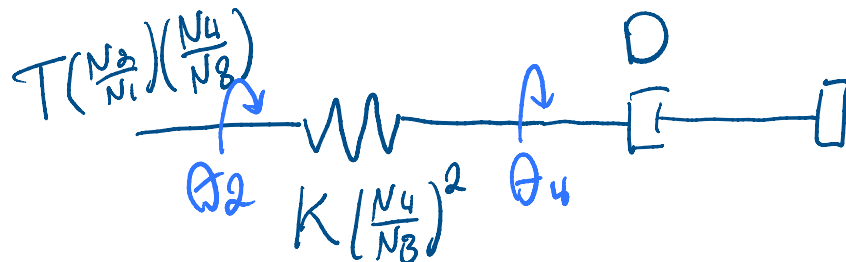
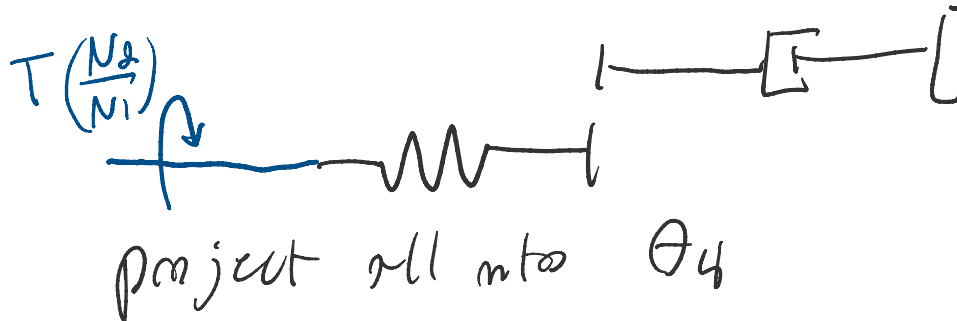


(a) (4 marks) How many degrees of freedom does the system have?

(b) (6 marks) Find the transfer function $G(s) = \frac{\theta_4(s)}{T(s)}$

a) 2 DOF

b) project θ_1 onto θ_2

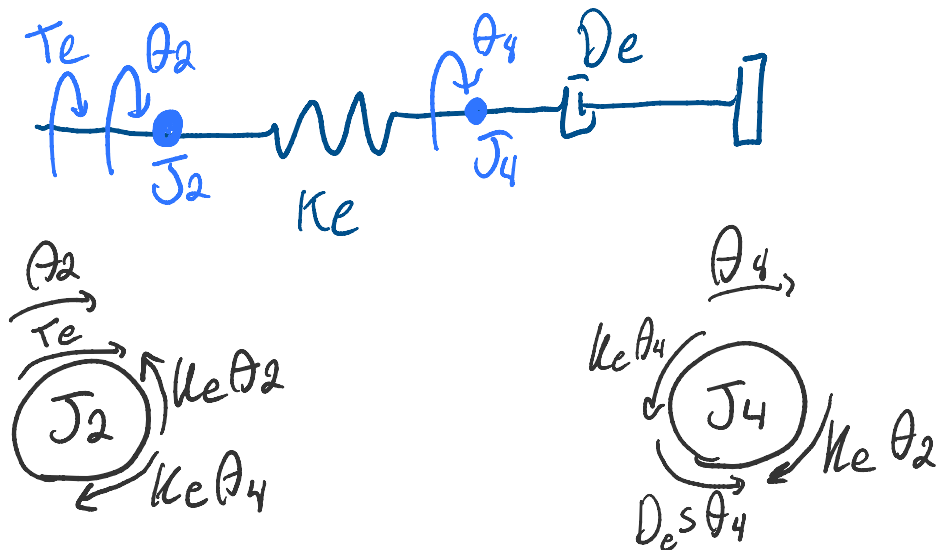


$$T_e = T_1 \left(\frac{N_2 N_4}{N_1 N_3} \right) = T_1 \left(\frac{110}{26} \times \frac{120}{23} \right) = \frac{6600}{299} T_1$$

$$T_e = T_1 \left(\frac{N_2 N_4}{N_1 N_3} \right) = T_1 \left(\frac{11}{26} \times \frac{120}{23} \right) = \frac{11}{249} \text{ l}$$

$$K_e = K_2 \left(\frac{N_4}{N_3} \right)^2 = 2 \left(\frac{120}{23} \right)^2$$

$$D_e = D_4 = 26$$



$$\begin{bmatrix} K_e & -K_e \\ -K_e & K_e + D_e s \end{bmatrix} \begin{bmatrix} \theta_2 \\ \theta_4 \end{bmatrix} = \begin{bmatrix} T_e \\ 0 \end{bmatrix}$$

$$\det(A) = K_e(K_e + D_e s) - K_e^2$$

$$\det(A_2) = \begin{vmatrix} K_e & T_e \\ -K_e & 0 \end{vmatrix} = K_e T_e$$

$$\frac{\det(A_2)}{\det(A)} = \frac{K_e T_e}{K_e(K_e + D_e s) - K_e^2} = \frac{T_e}{K_e + D_e s - K_e} = \theta_4$$

$$\frac{\Theta_4}{T_1} = \frac{6690/249}{26s} = \boxed{\frac{3300}{3887s}}$$

$$\boxed{\frac{\Theta_4}{T} = \frac{3300}{3887s}}$$