ME 4K03 Assignment #4

Due: 11:59pm, November 06, 2024

1. A planar RPR robot is shown below. Its joint variables are A, B and C. Length D is a constant. Its end-effector position and orientation are given by  $P_x$ ,  $P_y$  and  $\phi$ . Derive the inverse kinematics equations for this robot.

