#### **MECHTRON 2MD3**

## Data Structures and Algorithms for Mechatronics Winter 2022

## 30 Sorting

Department of Computing and Software

Instructor:

Omid Isfahanialamdari

April 6, 2022



### Admin

- I will have office hour today at 15:00
  - Virtual and in-person at ITB-159

#### Overview

Sorting: What we have seen so far?

Sorting Algorithm	Time Complexity	Properties
Insertion sort	O(n <sup>2</sup> )	<ul><li>slow</li><li>in-place</li><li>Suitable for small datasets (&lt; 1K)</li></ul>
Selection sort	O(n <sup>2</sup> )	<ul><li>slow</li><li>in-place</li><li>Suitable for small datasets (&lt; 1K)</li></ul>
Heap sort	O(nlogn)	<ul><li>fast</li><li>in-place</li><li>Suitable for large datasets (1K - 1M)</li></ul>

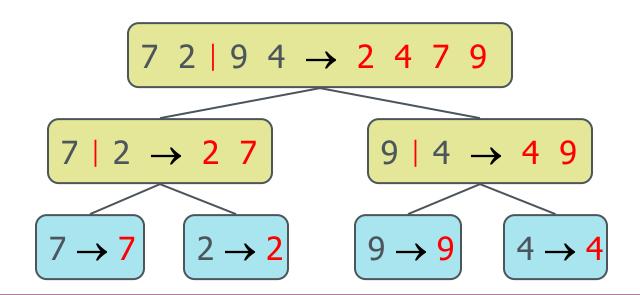
- We will talk about Merge sort and Quick sort
  - Both are very fast algorithms
  - are suitable for very large dataset (>1M)

#### Merge sort

- Merge sort is a sorting algorithm based on the divide-and-conquer paradigm
- Like Heap sort
  - It uses a comparator
  - o It has  $O(n \log n)$  running time ( we will discuss this in more detail)
- Unlike Heap sort
  - It does not use an auxiliary priority queue
  - It accesses data in a sequential manner (suitable to sort data on a disk)
    - It is not in-place.
      - There are methods to implement it as an in-place sorting, but those methods are not in the scope of this course.

#### Merge sort - A quick overview

- An execution of merge-sort is depicted by a binary tree
  - each node represents a recursive call of merge-sort and shows
    - unsorted sequence before the execution and how we partition it
    - sorted sequence at the end of the execution
  - the root is the initial call
  - the leaves are calls on subsequences of size 0 or 1





#### Divide-and-Conquer

- Divide-and conquer is a general algorithm design paradigm:
  - Divide: divide the input data S in two disjoint subsets  $S_1$  and  $S_2$
  - Recur: solve the subproblems associated with  $S_1$  and  $S_2$
  - Conquer: combine the solutions for  $S_1$  and  $S_2$  into a solution for S
- The base case for the recursion are subproblems of size 0 or 1

 Merge sort is a sorting algorithm based on the divideand-conquer paradigm

#### Merge sort - Formal Algorithm

- Merge sort on an input sequence S with n elements consists of three steps:
  - o Divide: partition S into two sequences  $S_1$  and  $S_2$  of about n/2 elements each
  - Recur: recursively sort  $S_1$  and  $S_2$
  - Conquer: merge S<sub>1</sub> and S<sub>2</sub> into a unique sorted sequence

#### Algorithm mergeSort

```
Input sequence S with n elements, comparator C

Output sequence S sorted according to C

if S.size() > 1

(S_1, S_2) \leftarrow partition(S, n/2)

mergeSort(S_1, C)

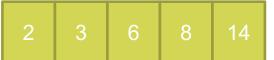
mergeSort(S_2, C)
```

 $S \leftarrow merge(S_1, S_2)$ 

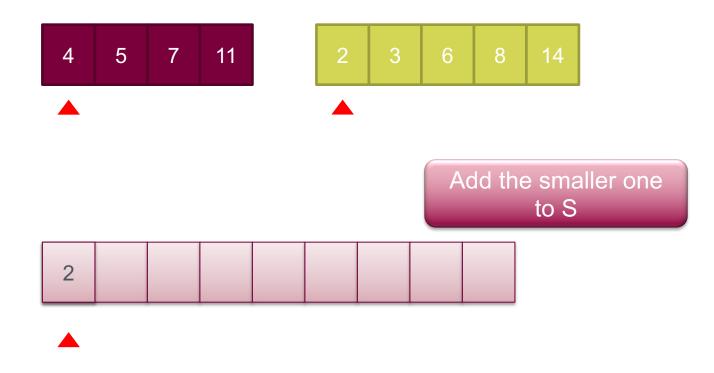
- The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B
- Merging two sorted sequences, each with n/2 elements and implemented by means of a doubly linked list, takes O(n) time
- Similar to the addition of polynomials in Assignment 2

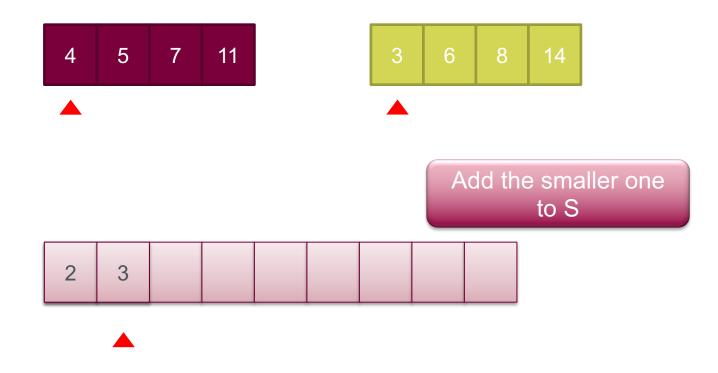
```
Algorithm merge(A, B)
    Input sequences A and B with n/2 elements each
    Output sorted sequence of A \cup B
    S \leftarrow empty sequence
    while \neg A.empty() \land \neg B.empty()
       if A.front() < B.front()
           S.addBack(A.front()); A.eraseFront();
        else
           S.addBack(B.front()); B.eraseFront();
    while \neg A.empty()
       S.addBack(A.front()); A.eraseFront();
    while \neg B.empty()
       S.addBack(B.front()); B.eraseFront();
    return S
```

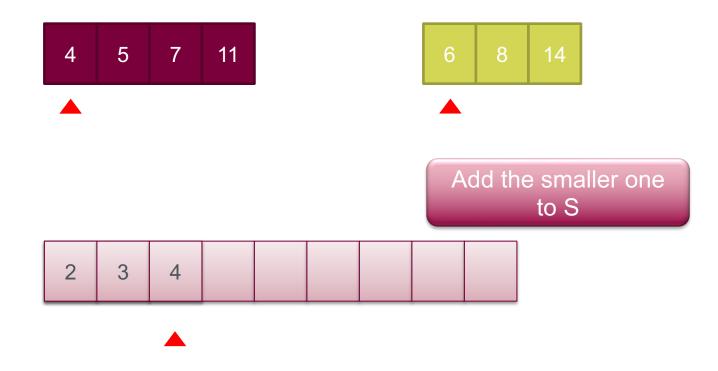


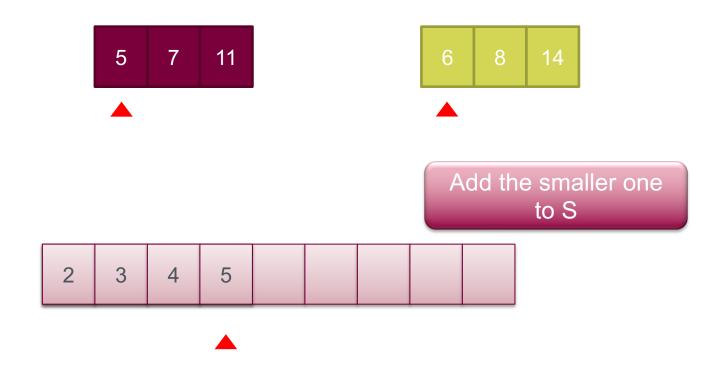


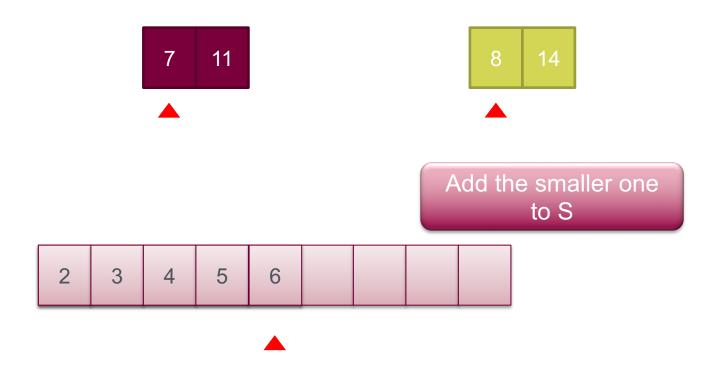


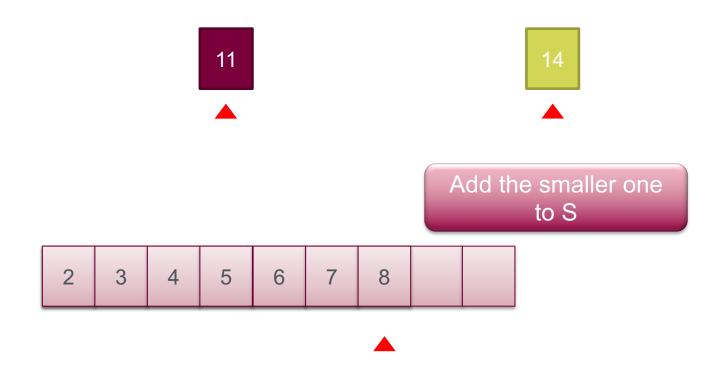


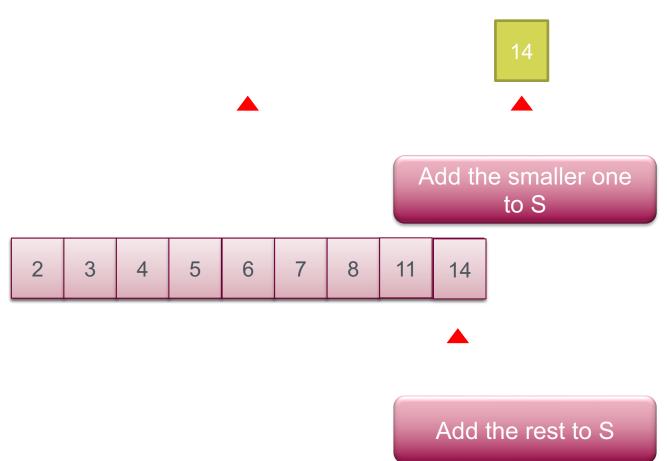




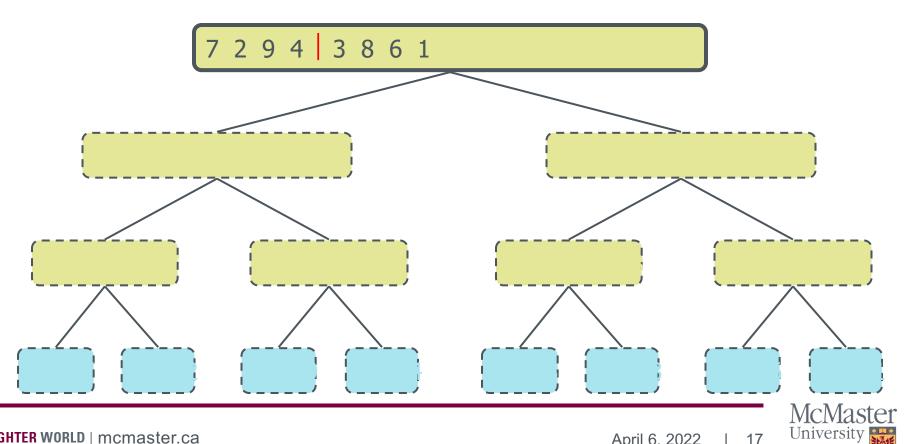




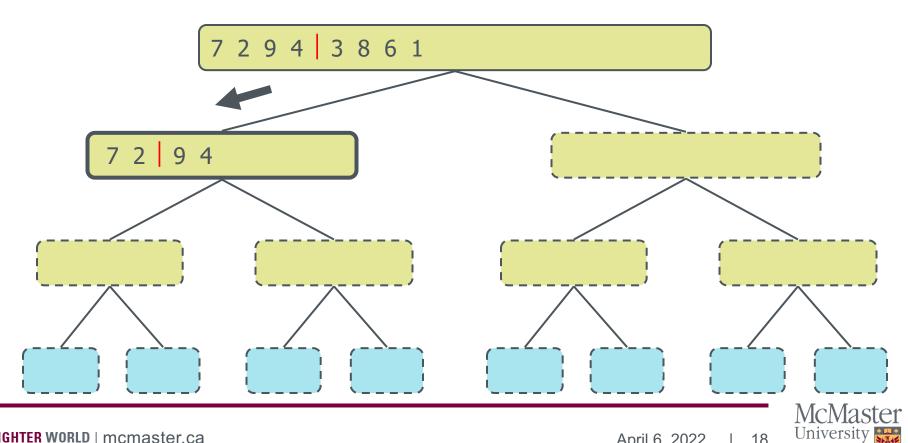




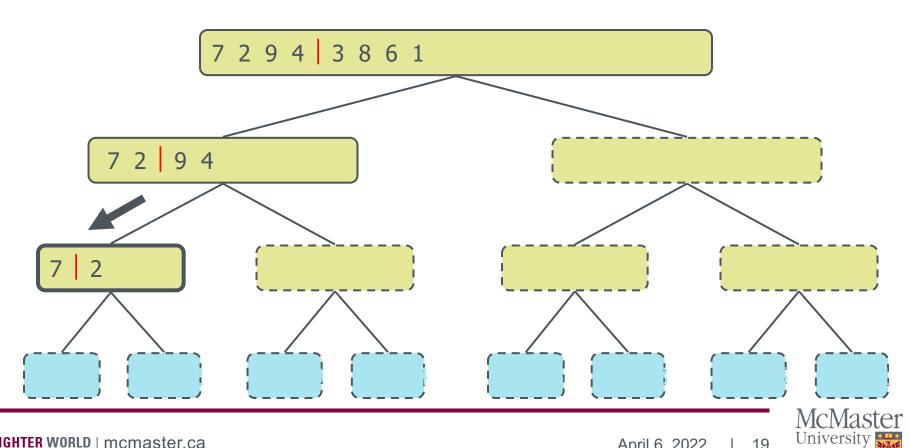
**Partition** 



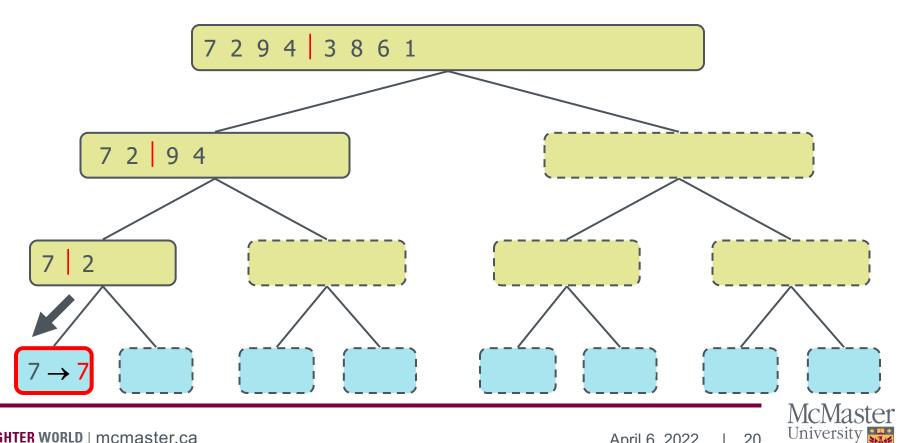
Recursive call, partition



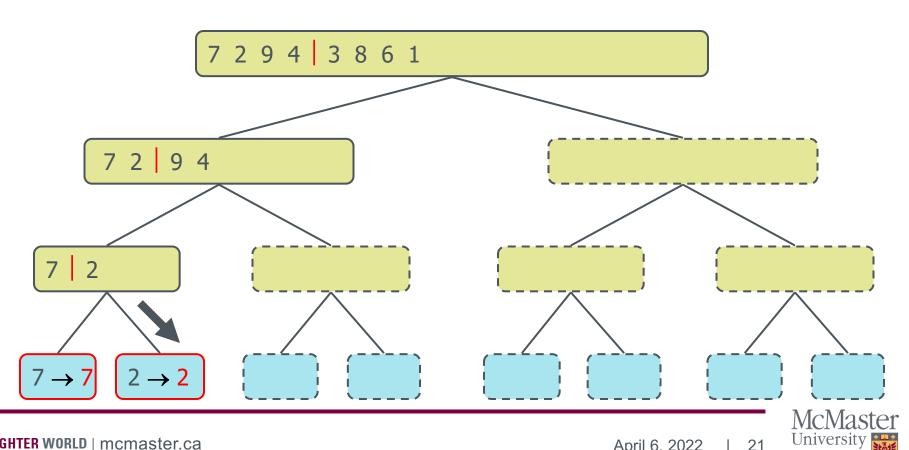
Recursive call, partition



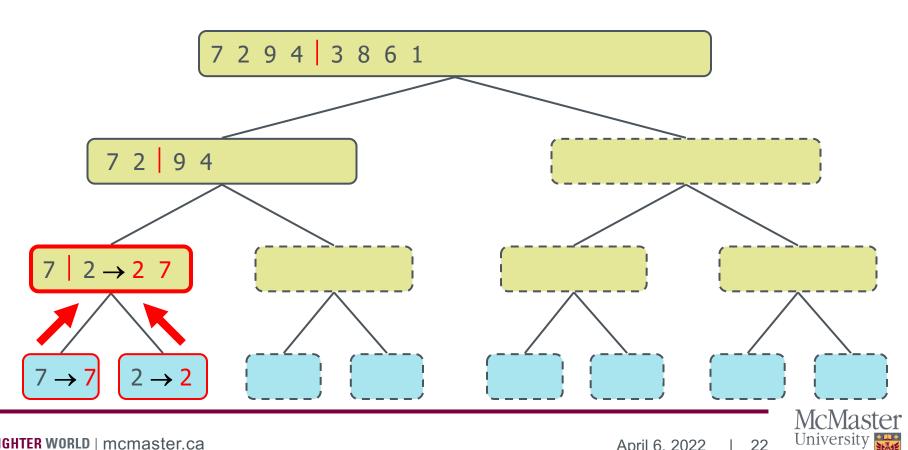
Recursive call, base case



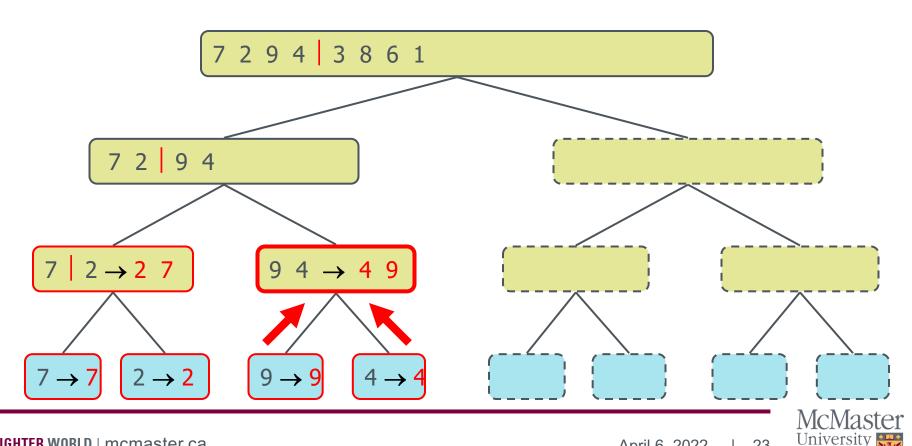
Recursive call, base case



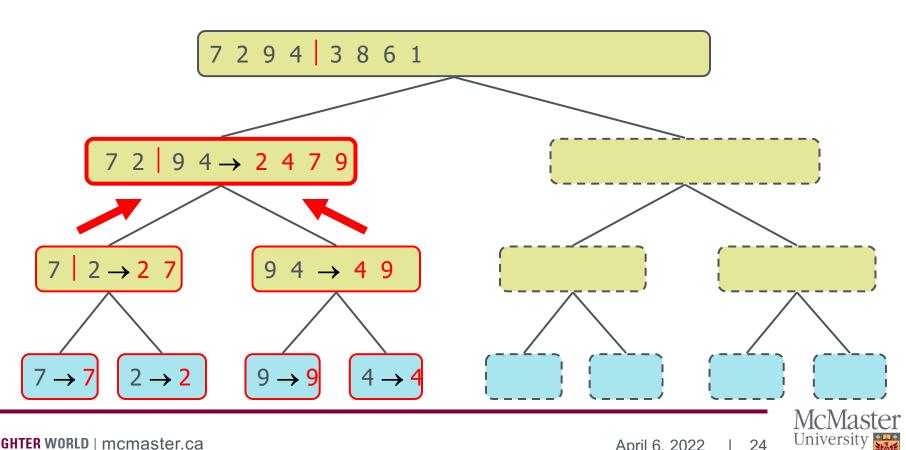
merge



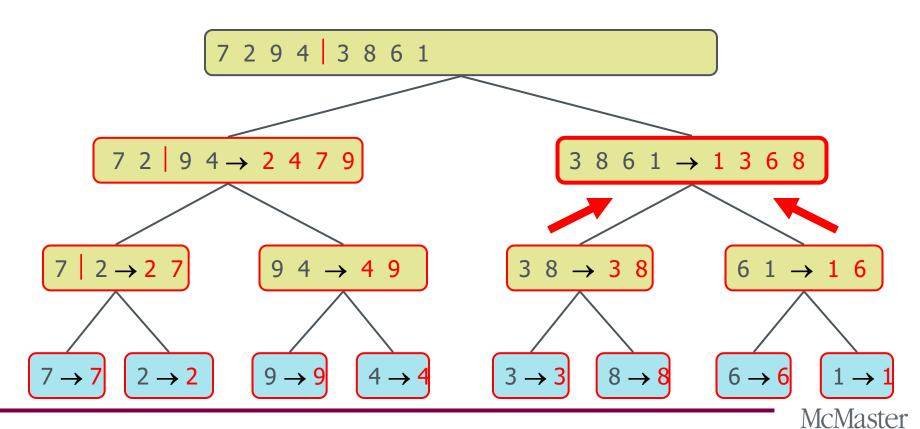
Recursive call, ..., base case, merge



merge

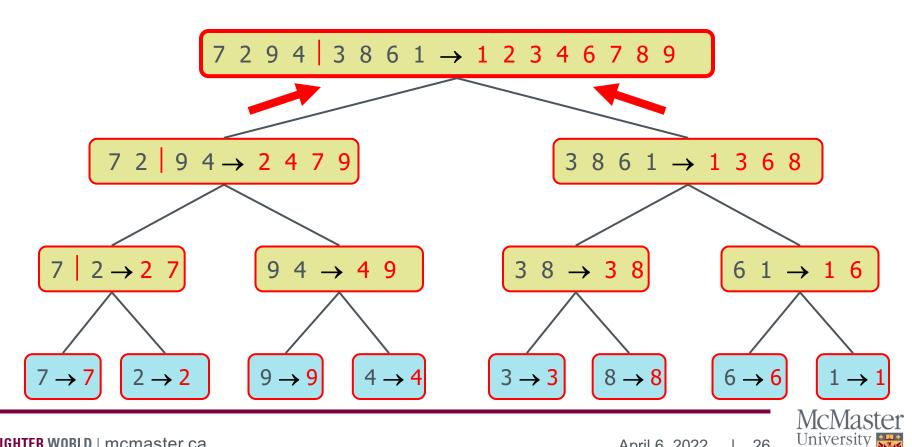


Recursive call, ..., merge, merge



University

merge



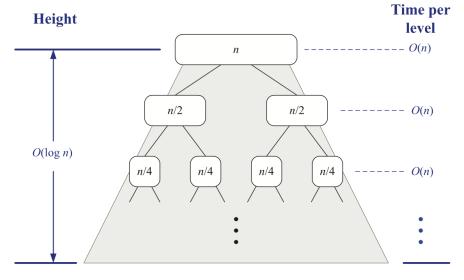
## Analysis of Merge-Sort

- The height h of the merge-sort tree is  $O(\log n)$ 
  - at each recursive call we divide in half the sequence,
- The overall amount or work done at the nodes of depth i is O(n)
  - we partition and merge  $2^i$  sequences of size  $n/2^i$
  - $_{\circ}$  we make  $2^{i+1}$  recursive calls
- Thus, the total running time of merge-sort is  $O(n \log n)$

depth	#seqs	size	
0	1	n	
1	2	<i>n</i> /2	
i	$2^{i}$	$n/2^i$	
•••	•••	• • •	

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- The overall amount or work done at the nodes of depth i is O(n)
  - $_{\circ}$  we partition and merge  $2^{i}$  sequences of size  $n/2^{i}$
  - we make 2i+1 recursive calls
- Thus, the total running time of merge-sort is  $O(n \log n)$



**Total time:**  $O(n \log n)$ 



## Analysis of Merge-Sort - Using Recurrence Relations

- The conquer step of merge-sort consists of merging two sorted sequences, each with n/2 elements and implemented by means of a doubly linked list, takes at most bn steps, for some constant b.
- Likewise, the basis case (n < 2) will take at b most steps.
- Therefore, if we let T(n) denote the running time of merge-sort:

$$T(n) = \begin{cases} b & \text{if } n < 2\\ 2T(n/2) + bn & \text{if } n \ge 2 \end{cases}$$

- We can therefore analyze the running time of merge-sort by finding a closed form solution to the above equation.
  - $\circ$  That is, a solution that has T(n) only on the left-hand side.



## Analysis of Merge-Sort - Using Recurrence Relations

- Iterative Substitution:
- In the iterative substitution, or "plug-and-chug," technique, we iteratively
  apply the recurrence equation to itself and see if we can find a pattern:

$$T(n) = 2T(n/2) + bn$$

$$= 2(2T(n/2^{2})) + b(n/2)) + bn$$

$$= 2^{2}T(n/2^{2}) + 2bn$$

$$= 2^{3}T(n/2^{3}) + 3bn$$

$$= 2^{4}T(n/2^{4}) + 4bn$$

$$= ...$$

$$= 2^{i}T(n/2^{i}) + ibn$$

- Note that base, T(n)=b, case occurs when 2<sup>i</sup>=n. That is, i = log n.
- So,  $T(n) = bn + bn \log n$
- Thus, T(n) is O(n log n).



## Recall

Sorting Algorithm	Time Complexity	Properties
Insertion sort	O(n <sup>2</sup> )	<ul><li>slow</li><li>in-place</li><li>Suitable for small datasets (&lt; 1K)</li></ul>
Selection sort	O(n²)	<ul><li>slow</li><li>in-place</li><li>Suitable for small datasets (&lt; 1K)</li></ul>
Heap sort	O(nlogn)	<ul><li>fast</li><li>in-place</li><li>Suitable for large datasets (1K - 1M)</li></ul>
Merge sort	O(nlogn)	<ul><li>fast</li><li>sequential data access</li><li>Suitable for for huge datasets (&gt;1M)</li></ul>

# Questions?

Please evaluate this course! <a href="https://evals.mcmaster.ca/">https://evals.mcmaster.ca/</a>
Thank you

