Z-Fighting aware Depth Peeling

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1. Abstract

We introduce a methodology for handling Z-fighting in depth peeling techniques. Our method is compatible with commodity graphics hardware. We quantitatively and qualitatively compare the resulting depth peeling Z-aware variants with other depth peeling techniques that have been presented in the literature with respect to performance, robustness and scope. Finally, we provide visual results for a number of applications such as transparency and translucency and a demonstration video.

2. Depth Peeling

- An efficient process of capturing the entire topological and geometric information of a 3D scene peeling off one or more layers per pass.
- Applications: Transparency, Volume rendering and tests, CSG,
 Trimming, Collision detection
- Classification based on the #peeling layers/pass:
- 1. <u>One layer</u>: *O*(*n*)

Front to Back (F2B) [1]: Slow

2. <u>K layers</u>: *O(n/k), extra memory, primitive pre-sorting*

K-Buffer (KB) [2]: RMW hazards

Stencil Routed A-Buffer (SRAB) [3]: MSAA not supported

 None of these methods can correctly peel all fragments due to Z-fighting.

3. Z-fighting

- Two or more primitives have the same z- values.
- Manifests itself through:
- 1. intersecting surfaces that result in intersecting triangles that belong to the same or different objects
- 2. overlapping surfaces

4. Proposed Methods

- Need one extra rendering pass
- Compatible with commodity graphics hardware

F2B_ZF: Extending F2B

Algorithm

- 1. using max blending
- (a) If all fragments at this depth have been peeled extract next depth layer else stay at this layer.
- (b) Extract the **fragment** with the largest ID [4]
- 2. using add/max blending

From the remaining, not peeled z-fighting fragments:

- (a) Calculate the **sum** of them
- (b) Find which of them has the largest ID.

F2BKB_ZF: Combining F2B with KB

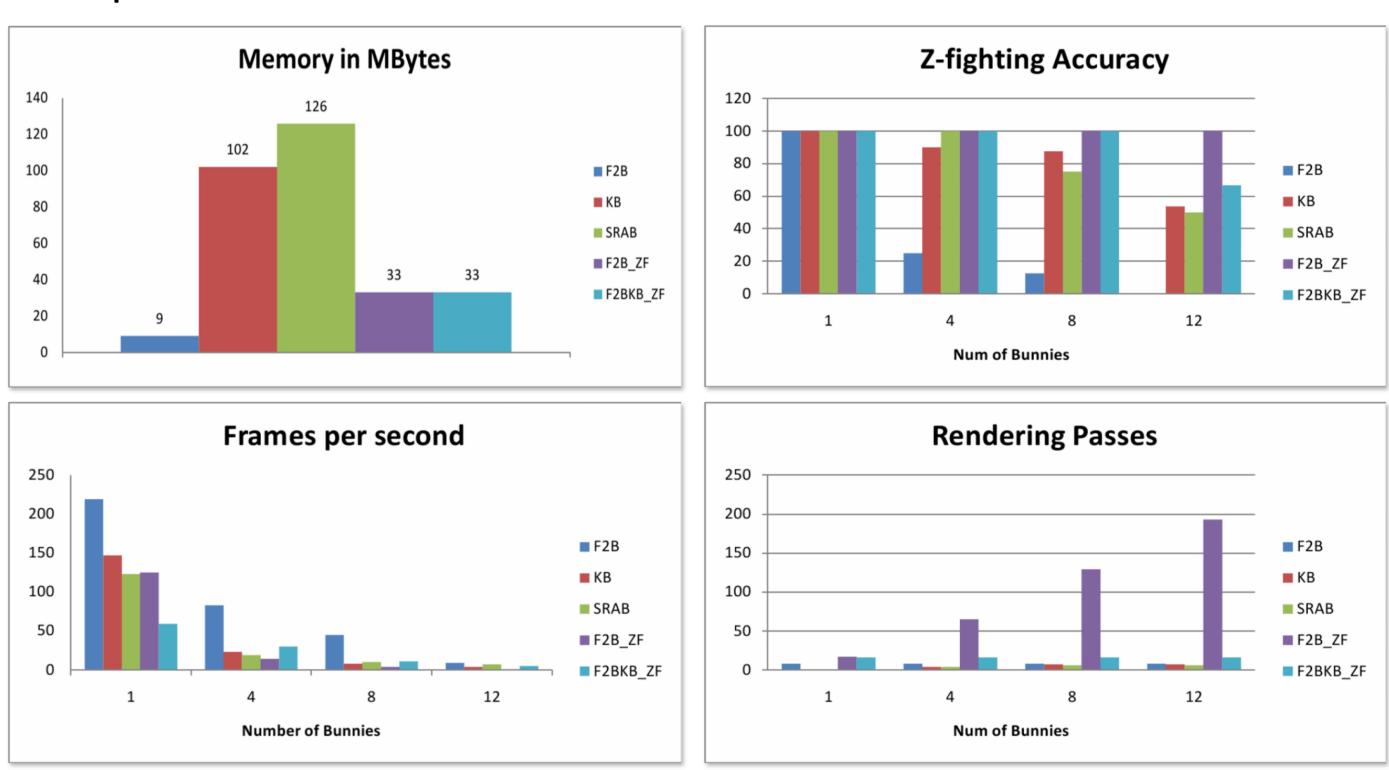
- Approximate method
- Faster for scenes with serious z-fighting artifacts

Algorithm

- 1. Extract next depth layer using the F2B.
- 2. Extract *k* fragments located at the current depth layer using a variation of KB.

5. Results

Following tables show a comparison in terms of peeling accuracy, performance and memory storage of the *F2B*, *KB* and *SRAB* methods and both of our proposed alternatives for a scene consisting of [1, 4, 8, 12] Bunnies (69,451 triangles) at a 1024×768 viewport on an nVidia Geforce GTX 480.



6. Future Work

The idea can be easily extended to other popular depth peeling techniques such as:

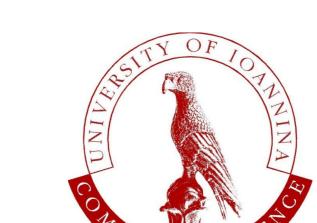
- Dual depth peeling [5]
- Bucket peeling [7]
- Multi K-buffer [6]

7. References

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- 6. Liu, B., Wei, L.-Y., Xu, Y.-Q., and Wu, E. 2009. "Multi-layer depth peeling via fragment sort". 11th IEEE International Conference on CAD/Graphics.
- Liu F., Huang M.-C., Liu X.-H., and Wu E.-H.. 2009. "Efficient depth peeling via bucket sort". In Proceedings of the Conference on High Performance Graphics.

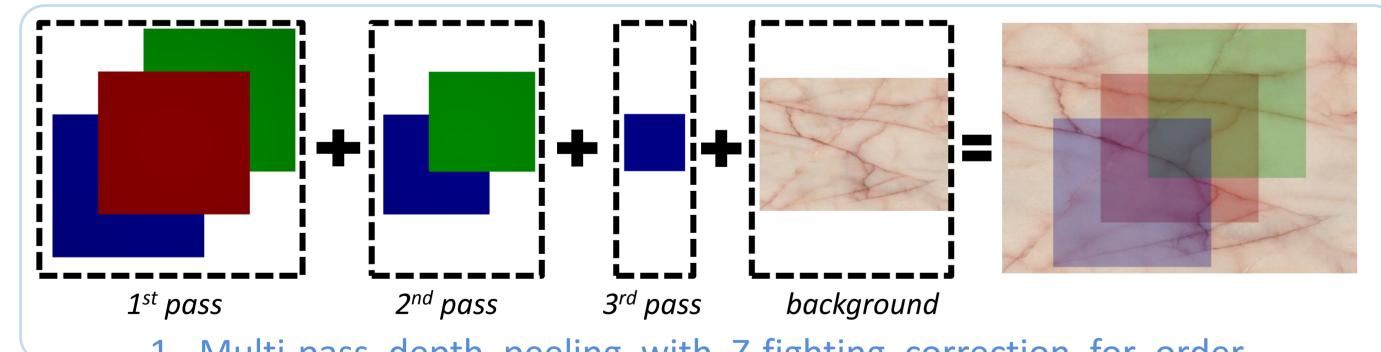
8. Software

http://www.cs.uoi.gr/~fudos/siggraph2011.html

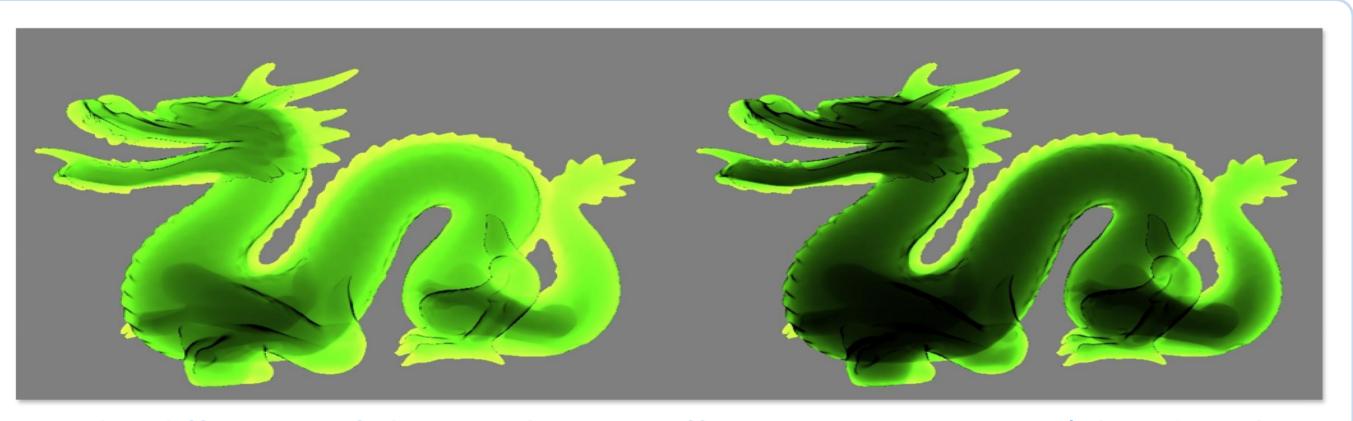




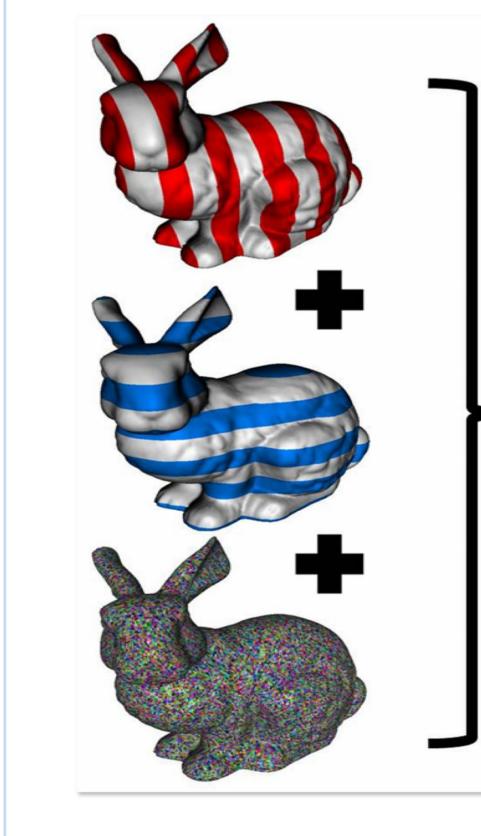
Figures



1. Multi-pass depth peeling with Z-fighting correction for order – independent transparency.



2. The difference of the translucency effect on two instances (placed at the same position) of the Dragon model without (left) and with (right) z-fighting correction.





3. Order independent transparency of three differently rendered Bunnies placed at the same position.





