National University of Computer and Emerging Sciences, Lahore Campus

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Section:	All	Roll No.	
Exam:	Final	Your Section:	

Instruction/Notes: **This is an open notes/book exam. Sharing notes and calculators is NOT ALLOWED.** All the answers should be written in provided space on this paper. Rough sheets can be used but will not be collected and checked. In case of any ambiguity, make reasonable assumptions. Questions during exams are not allowed.

Question 1 [Pipelining] [CLO 6] [10 Marks]:

Important Instruction: Following question is ONLY for section BSCS-A, BSCS-B, BSCS-F and BSCS-G

For the code segment given below, fill-in the following pipeline diagram. Clearly show the stall AND/OR forwarding where required. In case of forwarding, clearly draw the arrow and mention the name of operand that needs forwarding. Assume you have optimized pipelined MIPS Architecture (with all the hazards control implementation) as we have studied in class.

```
sub $1, $2, $3
or $4, $5, $6
lw $6, 100 ($4)
and $7, $6, $8
```

	CC1	CC2	CC3	CC4	CC5	CC6	CC7	CC8	CC9	CC10	CC11	CC12

Important Instruction: Following question is for ALL THE SECTIONS EXCEPT section BSCS-A, BSCS-B, BSCS-F and BSCS-G

Let us consider the following decomposition of the instruction processing
Fetch Instruction (FI): Read the next expected instruction into a buffer.
Decode Instruction (DI): Determine the opcode and the operand specifiers.
Fetch Operands (FO): Calculate the effective address of each source operand and fetch each operand from the memory. Operand in registers need not to be fetched.
Execute Instruction (EI): Perform the indicated operation and store the result if any, in the specified destination operand location.
Write Operand (WO): Store the result in memory.
Following is a set of instructions. Their implementation through pipelining has some data hazards. You have to solve those hazards by using stalling method.

Set of instructions
I1: mov bx, 0
I2: mov word [n1], ax
I3: add word [n1], bx
I4: add word [n1], 01
I5: mov cx, 0
I6: mov word [n2], cx
I7: add bx, [n1]
I8: add bx, word[n2]

Do it with Stalling Method (without Data Forwarding)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	FI	DI	FO	EI	WO															
		FI	DI	FO	EI	WO														
			FI	DI				FO	EI	WO										
				FI	DI						FO	EI	WO							
					FI	DI	FO	EI	WO											
						FI	DI		FO	EI	WO									
							FI	DI						FO	EI	WO				
								FI	DI							FO	EI	WO		

Question 2 [Cache] [CLO 6] [5+5 = 10 Marks]:

Consider a sequence of memory address references given below. In the sequence, each word address is provided in both the decimal and binary formats. Below each address, the relative time at which these references occur is also listed. Memory contents and addresses are shown in the second table.

Memory		
Decimal Address	**Binary Address**	**Data**
0	00 00 00 00	2
120	01 11 10 00	100
248	11 11 10 00	7
170	10 10 10 10	50
187	10 11 10 11	52
51	00 11 00 11	80
15	00 00 11 11	41
174	10 10 11 10	32
150	10 01 01 10	77
9	00 00 10 01	5
4	00 00 01 00	9
253	11 11 11 01	2
1	00 00 00 01	3
7	00 00 01 11	65
6	00 00 0 1 10	90
2	00 00 00 10	55

Memory Access Sequence		
Time	**Address Decimal**	**Address Binary**
1	6	00 00 0 1 10
2	0	00 00 00 00
3	15	00 00 11 11
4	120	01 11 10 00
5	253	11 11 11 01
6	1	00 00 00 01
7	248	11 11 10 00
8	9	00 00 10 01
9	4	00 00 01 00
10	51	00 11 00 11
11	2	00 00 00 10
12	1	00 00 00 01

Now consider two different 8-word caches shown below. Assume that each of the caches was used independently to facilitate memory access for the sequence above. For each cache type, assume that the cache is initially empty. Assume that the least-recently used (LRU) scheme is used where appropriate. Also, when inserting an element into the cache, if there are multiple empty slots for one index, you should insert the new element into the left-most slot (first available slot).

Part (A) [5 Marks]: Use the **direct-mapped cache** to facilitate memory access for the memory sequence above. You should fill in the binary form of the Tag values. **Show the final contents of the cache in the table below.**
Note: V means Valid OR Value Bit.

Index	Direct-Mapped Cache		
	TAG	DATA	V
0	11111	7	0
1	00000	3	0
2	00000	55	0
3	00110	80	0
4	00000	9	0
5	11111	2	0
6	00000	90	0
7	00001	41	0

Hit Rate: 0

Miss Rate: 12

Part (B) [5 Marks]: Use the **2-way set associative cache** to facilitate memory access for the memory sequence above. You should fill in the binary form of the Tag values. **Show the final contents of the cache in the table below.**

Set	2-way Set Associative Cache					
	V	Tag	Data	V	Tag	Data
0	0	111110	7	0	000001	9
1	0	000010	5	0	000000	3
2	0	000001	90	0	000000	55
3	0	000011	41	0	001100	80

Hit Rate: 1

Miss Rate: 11

Question 3 [Performance] [CLO 6] [10 Marks]: It takes 15µs to complete one instruction in a non-pipelined processor. We were able to convert the circuit to a 6 stage pipeline processor. Stage 1 to 6 take 2µs, 1.5µs, 3µs, 4µs, 1.5µs, 3µs resp. Time to move from one pipe stage to another is 2µs. **(Note for Section BSCS-A, BSCS-B, BSCS-F and BSCS-G:** Assume the transition time, to move from one pipe stage to another, is zero.)

Calculate the following values for pipeline and non-pipelined processor (Write the answer in the given table)

Value	Non-Pipeline	Pipeline
Clock Cycle	15 µs	6 µs
Clock Speed	0.067 Ms	0.167 Ms
Latency	15 µs	36 µs
Throughput for 46 instructions	0.067 Ms	0.15 Ms
Throughput for 1 instruction	0.067 Ms	0.027 Ms
Speedup of pipeline processor for 1 instruction	0.416s	
Speedup of pipeline processor for 75 instructions	2.345s	

Question 4 [Short Questions] [CLO 1,2,3,4,5] [5x6 = 30 Marks]:

a. The following program is trying to add the first three numbers in the array num1 and store the sum in the fourth index of the num1 array. However, after running the program, the final sum generated is incorrect. **Identify mistakes in the program and write the correct code in the box on the right side.**

```
 ; a program to add three numbers
[org 0x0100]
mov ax, [num1]
mov bx, [num1+1]
add ax, bx
mov bx, [num1+2]
add ax, bx
mov [num1+3], ax
mov ax, 0x4c00
int 0x21
num1: dw 5, 10, 15, 0
```

; Write Correct Code here

```
[org 0x0100]
mov ax, [num1]
mov bx, [num1+2]
add ax, bx
mov bx, [num1+4]
add ax, bx
mov [num1+6], ax
mov ax, 0x4c00
int 0x21
num1: dw 5, 10, 15, 0
```

b. Write a piece of code to check if a number 'num' is a power of two or not. If the number is power of two, set the PowerOfTwo flag to 1. You are only allowed to use shifting and logical instructions. You are not allowed to use DIV instruction.

```
[org 0x0100]
jmp start
PowerOfTwo :db 0
num: dw 0

start:
mov ax, [num]
push ax
call CheckPowerOfTwo
terminate:
mov ax,0x4c00
int 0x21
```

```
CheckPowerOfTwo:
push bp
mov bp,sp
push ax
push bx
mov ax,[bp+4]
;write your code here
mov bx,ax
sub bx,1
AND ax,bx
jnz l2
l1:
mov byte[PowerOfTwo],1
l2:
pop bx
pop ax
pop bp
ret 2
```

c. Following program has a function add1 that takes 2 numbers from stack and if sum of these two numbers is greater than 0, it returns their sum through stack otherwise it returns 0 through stack. Code has some logical errors. **Highlight the errors and correct those errors so that you can pop the correct answer in the dx register. You can add or modify existing lines but you cannot remove any line.**

```
jmp start
add1:
push bp
mov bp, sp
sub sp,2
push ax
mov ax, [bp+2]
mov [bp-2], ax
mov ax, [bp+4]
add [bp+8],ax
cmp word [bp+8],0
ja end
mov [bp+8], 0
end:
pop bp
ret 2
start:
sub sp, 2
push 8
push 5
call add1
pop dx
```

```
add1:
jmp start
push bp
mov bp, sp
sub sp,2
push ax
mov ax, [bp+4]
mov [bp+8], ax
mov ax, [bp+6]
add [bp+8],ax
cmp word [bp+8],0
jg end
mov [bp+8], 0
end:
pop ax
mov sp, bp
pop bp
ret 4
start:
sub sp, 2
push 8
push 5
call add1
pop dx
```

d. Answer the following questions:

(i) Which interrupt will be hooked after execution of following code?

_____68d/44h_____

```
[org 0x100]
;;;; myISR is written here
xor ax,ax
mov es, ax
mov [es: 0x110 ] , myISR
mov [es : 0x112] , CS
mov ax, 4c00h
Int 21h
```

(ii) What is the total size (in bytes) of the interrupt vector table?

_____1KB_____

The first 22 words (in hex) of the 0th segment of the physical memory are shown in the following table (starting from data 0120).

0120
0140
0280
123F
124A
A198
BCD6
78D2
197B
CD79
E106
56AB
9851
0CDA
6502
AB69
F156
49D8
12E5
9857
146B
98A2

(iii) What is the segment and offset of the interrupt service routine corresponding to interrupt 1?

Offset: _____8002_____ **Segment: _____3F12_____**

(iv) What is the segment and offset of the interrupt service routine corresponding to interrupt 5?

Offset: _____06E1_____ **Segment: ___AB56_____**

(v) What is the segment and offset of the interrupt service routine corresponding to interrupt 10h?

Offset: __Not in tab_____ **Segment: __Not in tab_____**

e. Write a piece of code that disables the timer interrupt in the PIC mask register.

```
[org 0x0100]
in al, 0x21
or al, 1
out 0x21, al
mov ax, 0x4c00
int 0x21
```

Question 5 [CLO 1,2,3,4,5] [30 Marks]: You are required to implement **Notepad** Application according to the functionality as described below:

1- Notepad application will start/load with following specifications:
   a. Notepad will have two partitions in the display memory. Upper half (1st 12 rows) will be editor window while 2nd half (last 12 rows) will be read-only window. 13th row will be boundary line like "========". Both the editor and read-only windows will be space with white background initially. **[4 marks]**
   b. A blinking cursor '|' (attribute: black on white background) will be on top-left cell of the Editor Window (1st half). For now, ignore the default cursor due to time constraint. **[4 marks]**

2- Editor window can be edited with following specifications (DO NOT take characters from user using software interrupts)
   a. If user enters any key, that character or digit will be displayed at the position of cursor and cursor will move by one cell towards right. If cursor was at last cell of a row, it will move to 1st cell of next row within editor boundary. Due to time constraint, we assume that user will not write at bottom-right cell of Editor Window and beyond. You do not need to check this boundary condition. Assume that user will press only characters and numeric keys. Also assume that you are already given a function ScanCodeToAsciiConverter that reads scancode from AL and saves corresponding ascii in AH (You do not need to push or pop any parameter or return value and you do not need to re-write this converter, just use it wisely). **[6 marks]**
   b. Make sure that your application doesn't write anything on Editor Window on key release. **[2 marks]**
   c. Within Editor Window, user can move the cursor up, down, left or right by pressing Up, Down, Left, Right ARROW KEYS respectively. Due to time constraint we will implement only DOWN ARROW KEY (i.e. scancode 0x50). If user presses DOWN ARROW key, the cursor moves to same column of next row. Assume that user will not cross the Editor Window's boundary; you do not need to implement this boundary check. Make sure you properly handle previous position of cursor. This cursor movement is allowed even if there is no text written in editor window. **[6 marks]**

3- After every minute, Read-only window updates/refreshes itself with the latest content available on Editor Window i.e. after every minute, paste the content of Editor Window on Read-only Window (You do not need to remove cursor from read-only window). **[8 marks]**

Important Instructions:

- Credit will be given on code efficiency, so use string instructions where required.
- You may use the functions given in book examples. Give proper reference and use them wisely. Function calls should exactly support the required functionality.

```
; Write your code here
; Data Declarations (if required)
; and Start/Main Functionality here
jmp start

oldisr: dd 0
cursorPosition: dw 0
buffer: times 4000 db 0 ; space for
4000 bytes
tickcount: dw 0
message1: db 10, 13, 'Program started.
$'
message2: db 10, 13, 'Message 22222...
$'
message3: db 10, 13, 'Message 333... $'
exitFlag: db 0

start:
xor ax, ax
mov es, ax ; point es to IVT base
mov ax, [es:9*4]
mov [oldisr], ax ; save offset of old
routine
mov ax, [es:9*4+2]
mov [oldisr+2], ax ; save segment of
old routine
cli ; disable interrupts
mov word [es:9*4], kbisr ; store offset
at n*4
mov [es:9*4+2], cs ; store segment at
n*4+2

mov word [es:8*4], timer; store offset
at n*4
mov [es:8*4+2], cs
sti ; enable interrupts
call clrscr
jmp $
l1: mov ah, 0 ; service 0 – get
keystroke
int 0x16 ; call BIOS keyboard service
cmp al, 27 ; is the Esc key pressed
jne l1 ; if no, check for next key
mov ax, [oldisr] ; read old offset in
ax
mov bx, [oldisr+2] ; read old segment
in bx
cli ; disable interrupts
mov [es:9*4], ax ; restore old offset
from ax
mov [es:9*4+2], bx ; restore old
segment from bx
sti ; enable interrupts
mov ax, 0x4c00 ; terminate program
int 0x21
```

```
;Write Timer Code here (if required)

timer: push ax

inc word [cs:tickcount]; increment tick
count
cmp word [cs:tickcount], 1080
je oneMinute
jmp exitTimer

oneMinute:
mov word [cs:tickcount], 0
call saveScreen

exitTimer:
mov al, 0x20
out 0x20, al ; end of interrupt

pop ax
iret
```

```
;Write KBISR here (if required)

kbisr: push ax

               in al, 0x60 ; read a char
from keyboard port

               test al, 0x80
               jnz exit ; ignore release
keys

;              cmp al, 0xD0 ; DOWN
Release
;              je exit


               push es
               push di
               push ds
               push bx


               push cs
               pop ds

               mov bx, 0xb800
               mov es, bx ; point es to
video memory

               cmp al, 0x50
               jne checkDown

Up:            mov di, [cursorPosition]
               mov byte[es:di] , ' '
               add di, 1
               xor byte [es:di], 0x80
               add di, 159
               jmp UpdateCursor

checkDown:




               mov byte[es:2],'*'

               mov di, [cursorPosition]

               mov byte [es:di], al ;
yes, print R at top left


UpdatePrevCursor:
               add di, 1
               xor byte [es:di], 0x80
```

```
;Write KBISR here (if required)

       add di, 1

UpdateCursor:
               mov ah, 0xF0
               mov al, '|'
               mov word[es:di], ax
               mov [cursorPosition], di


nomatch:
pop bx
pop ds
pop di
pop es
pop ax

jmp far [cs:oldisr] ; call the original
ISR
; iret

exit:
pop ax
jmp far [cs:oldisr]
```

```
;Other Functions (if required)
sleep:          push cx

                mov cx, 0xFFFF
delay:          loop delay

                pop cx
                ret
clrscr:         push es
                        push ax
                        push di

                        mov ax, 0xb800
                        mov es, ax
                        mov di, 0

nextloc:        mov word [es:di], 0x7020
                        add di, 2
                        cmp di, 1920
                        jne nextloc

                mov ah, 0x07
                mov al, '='
nextloc2:       mov word [es:di], ax  ;
clear next char on screen
                        add di, 2
                        cmp di, 2080
                        jne nextloc2

nextloc3:       mov word [es:di], 0x7020
                        add di, 2
                        cmp di, 4000
                        jne nextloc3

                mov ah, 0xF0
                mov al, '|'
                mov word[es:0], ax

                        pop di
                        pop ax
                        pop es
                        ret
```

```
;Other Functions (if required)


saveScreen:     pusha

                        mov ax, 0xb800
                        mov ds, ax ; ds =
0xb800
                        mov es, ax

                        mov cx, 1920 ;
number of screen locations

                        mov si, 0
                        mov di, 2080

                        cld ; set auto
increment mode
                        rep movsb ; save
screen

                        ;[es:di] =
[ds:si]

popa
                        ret
restoreScreen:          pusha


                        mov cx, 4000 ;
number of screen locations

                        mov ax, 0xb800
                        mov es, ax ; ds =
0xb800

                        push cs
                        pop ds

                        mov si, buffer
                        mov di, 0

                        cld ; set auto
increment mode
                        rep movsb ; save
screen

                        ;[es:di] =
[ds:si]


popa
                        ret
```