

ECE 6350

**3D Electrostatic Potential
Integral Equation**

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New Features of Static 3D Potential Integral Equation

- 3D geometry and Green's function
- Triangular elements
 - Data structure
 - Local coordinate system
(area coordinates—both for IE and FEM)
 - Linear interpolation on triangles
 - Numerical integration on triangles
- Handling $1/R$ singularities in 3D

Equations of Electrostatics in Homogeneous Media

- $\nabla \times \mathbf{E} = \mathbf{0} \Rightarrow \mathbf{E} = -\nabla \Phi$
- $\nabla \cdot \mathbf{D} = \varepsilon \nabla \cdot \mathbf{E} = q \quad [\text{C/m}^3]$
 $\Rightarrow \nabla^2 \Phi = -\frac{q}{\varepsilon}$

where

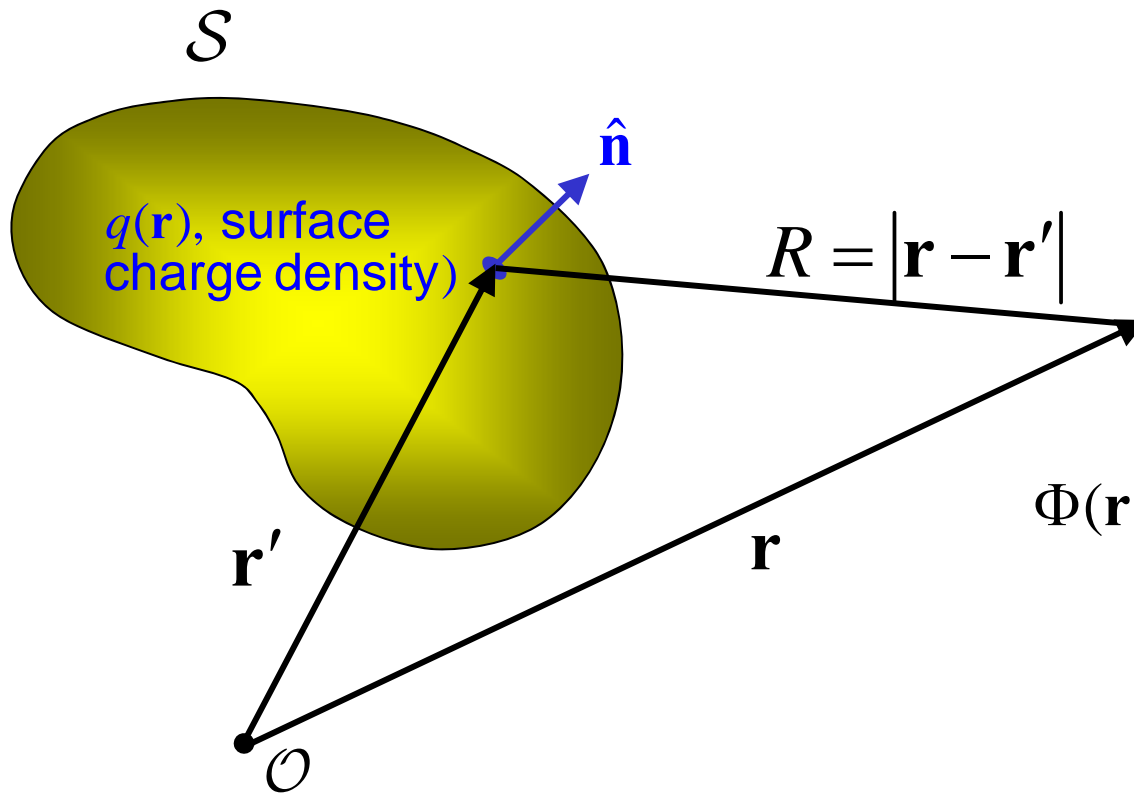
$$\Phi = \frac{1}{\varepsilon} \int_{\mathcal{V}} G(\mathbf{r}, \mathbf{r}') q(\mathbf{r}') d\mathcal{V}'$$

$$\text{and } G(\mathbf{r}, \mathbf{r}') = \frac{1}{4\pi R}, \quad R = |\mathbf{r} - \mathbf{r}'|$$

Note :

$$\nabla^2 G = -\delta(\mathbf{r} - \mathbf{r}')$$

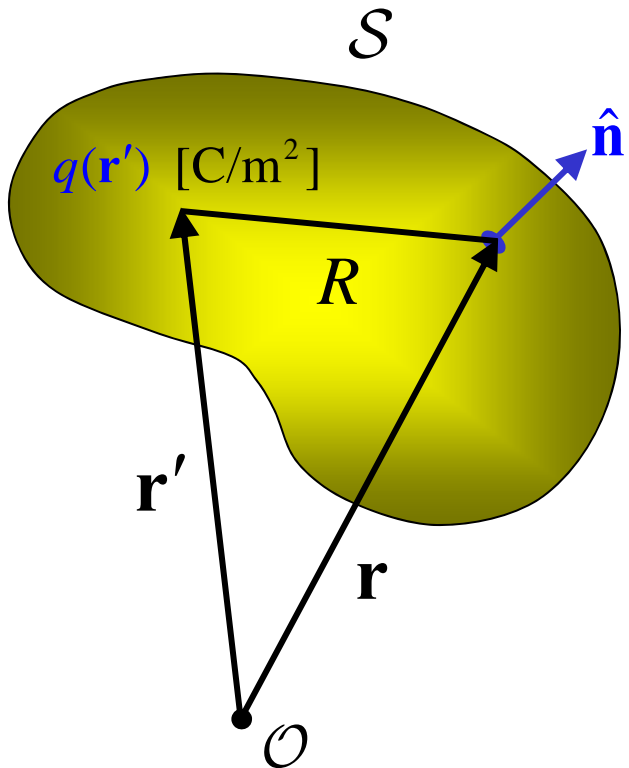
Definitions of Geometrical and Electrical Quantities for Charges on a **Surface**



$$\Phi(\mathbf{r}) = \frac{1}{\varepsilon} \int_S G(\mathbf{r}, \mathbf{r}') q(\mathbf{r}') dS'$$

$$G(\mathbf{r}, \mathbf{r}') = \frac{1}{4\pi R}$$

Conductor Charged to a Given, Constant Potential Φ_0



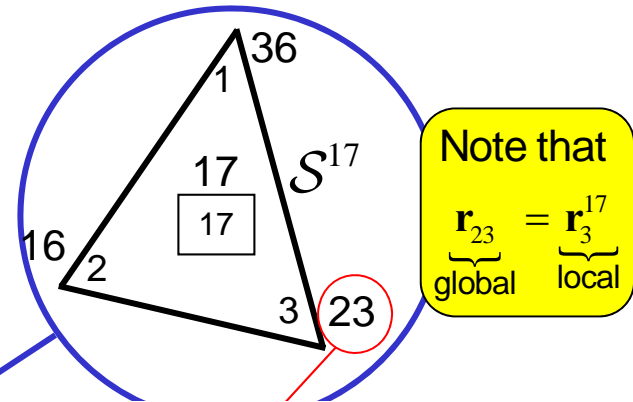
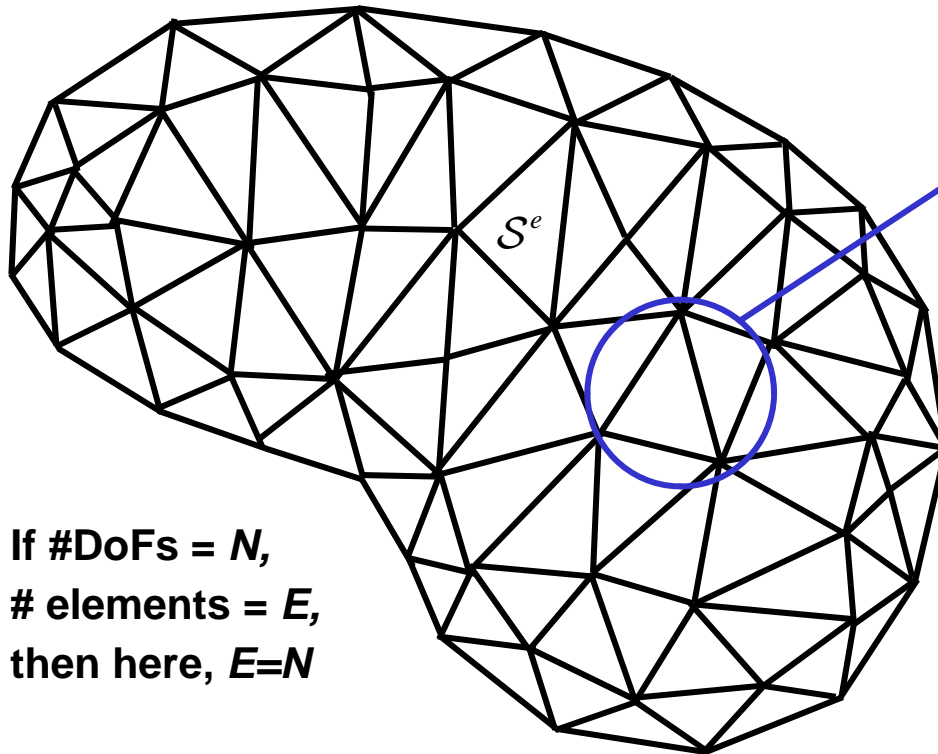
Apply the boundary condition,

$$\frac{1}{\varepsilon} \int_S G(\mathbf{r}, \mathbf{r}') \underbrace{q(\mathbf{r}')}_{\text{unknown}} dS' = \underbrace{\Phi_0}_{\text{known}}, \quad \mathbf{r} \in S$$

Reminder : Here $q(\mathbf{r})$ denotes a *surface* charge density!

Surface Discretization

$$\mathcal{S} \approx \tilde{\mathcal{S}} = \bigcup_{e=1}^N \mathcal{S}^e$$



- A **Global Node list** defines vertex locations

Node #	x	y	z
...
<u>23</u>	x_{23}	y_{23}	z_{23}
...

- An **element list** contains the global node numbers; here DoF# = element #

Element e	DoF	1	2	3
...
17	17	36	16	<u>23</u>
...

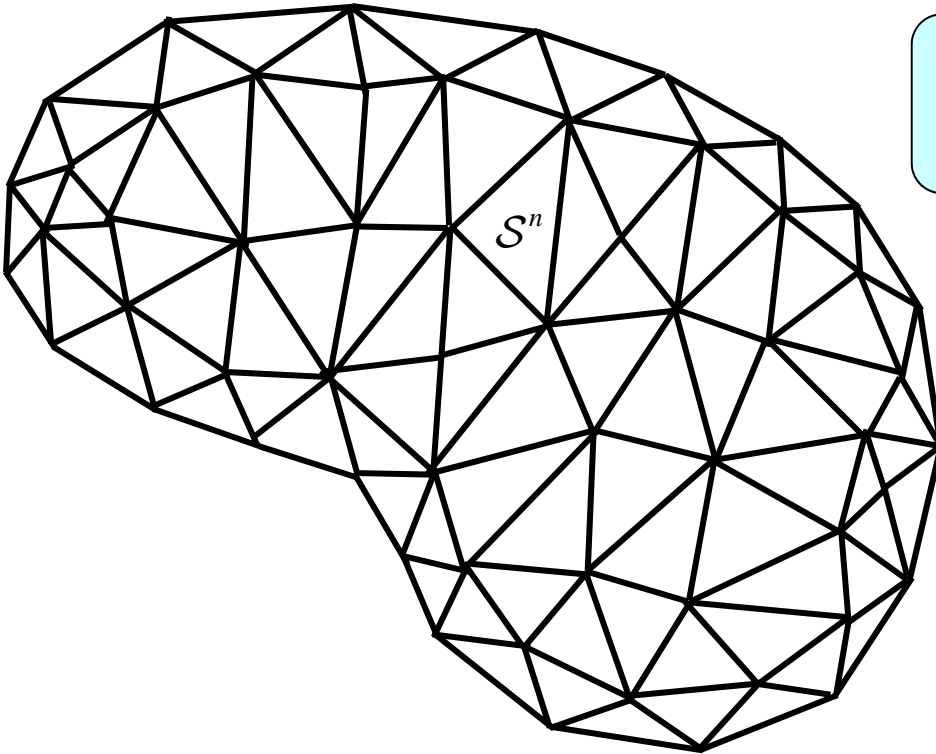
If #DoFs = N ,
elements = E ,
then here, $E=N$

Constant surface charge density
assumed in each triangle =>
Piecewise constant representation

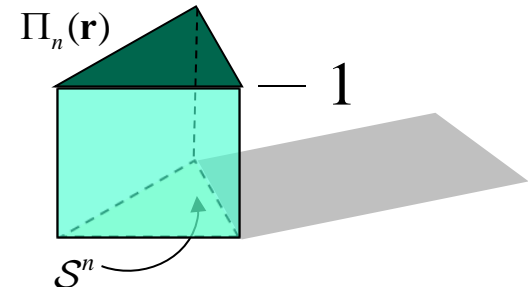
Piecewise Constant Surface Charge Approximation

$$e \rightarrow n, \quad \mathcal{S} \approx \tilde{\mathcal{S}} = \bigcup_{n=1}^N \mathcal{S}^n$$

Constant surface charge density assumed in each triangle \Rightarrow Piecewise constant representation



$$q(\mathbf{r}') \approx \sum_{n=1}^N Q_n \Pi_n(\mathbf{r}')$$
$$\Pi_n(\mathbf{r}) = \begin{cases} 1, & \mathbf{r} \in \mathcal{S}^n \\ 0, & \text{otherwise} \end{cases}$$



Substitute Charge Approximation and Enforce Equality at Subdomain Centroids

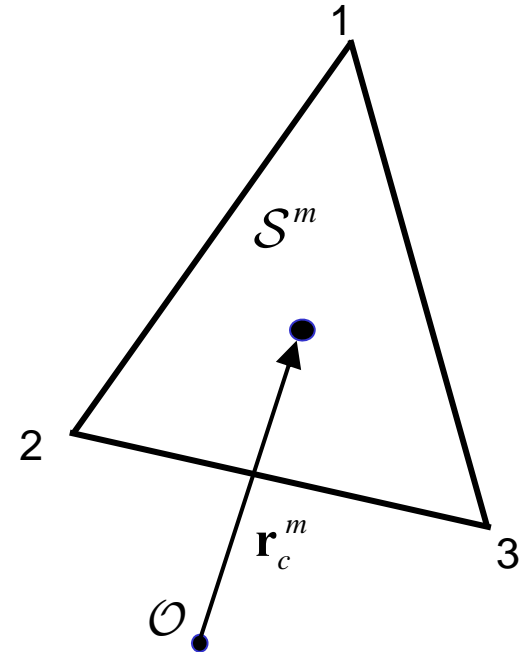
$$q(\mathbf{r}') \approx \sum_{n=1}^N Q_n \Pi_n(\mathbf{r}') \quad [\text{C/m}^2],$$

$$\int_S \frac{q(\mathbf{r}')}{4\pi\epsilon |\mathbf{r} - \mathbf{r}'|} dS' = \Phi_0 \quad [\text{V}], \quad \mathbf{r} \in S$$

$$\Rightarrow \sum_{n=1}^N Q_n \int_{\tilde{S}} \frac{\Pi_n(\mathbf{r}')}{4\pi\epsilon |\mathbf{r} - \mathbf{r}'|} dS' \approx \Phi_0,$$

Enforce equality at centroid of S^m :

$$\text{let } \mathbf{r} = \mathbf{r}_c^m \equiv \frac{\mathbf{r}_1^m + \mathbf{r}_2^m + \mathbf{r}_3^m}{3}, \quad m=1, 2, \dots, N$$



Matrix Equation for Approximate Surface Charge Distribution

$$\sum_{n=1}^N Q_n \int_{\tilde{S}} \frac{\Pi_n(\mathbf{r}')}{4\pi\epsilon |\mathbf{r}_c^m - \mathbf{r}'|} dS' = \Phi_0, \quad m = 1, 2, \dots, N$$

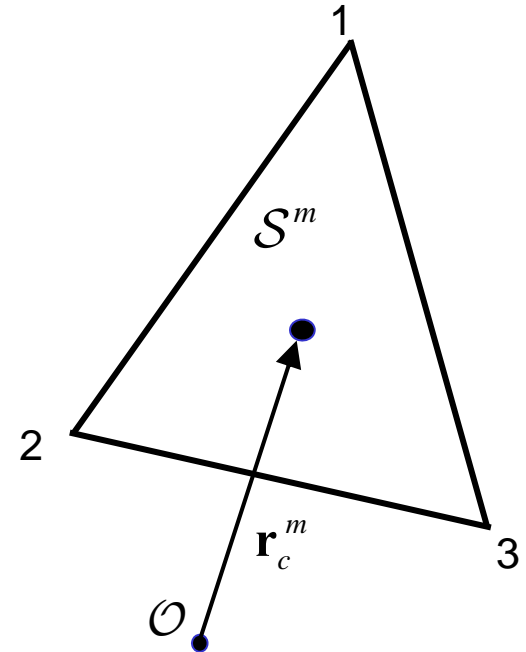
or

$$[S_{mn}][Q_n] = [V_m]$$

where

$$S_{mn} = \int_{\tilde{S}} \frac{\Pi_n(\mathbf{r}')}{4\pi\epsilon |\mathbf{r}_c^m - \mathbf{r}'|} dS' = \int_{S^n} \frac{dS'}{4\pi\epsilon |\mathbf{r}_c^m - \mathbf{r}'|}$$

$$\mathbf{r}_c^m = \frac{\mathbf{r}_1^m + \mathbf{r}_2^m + \mathbf{r}_3^m}{3}, \quad V_m = \Phi_0$$

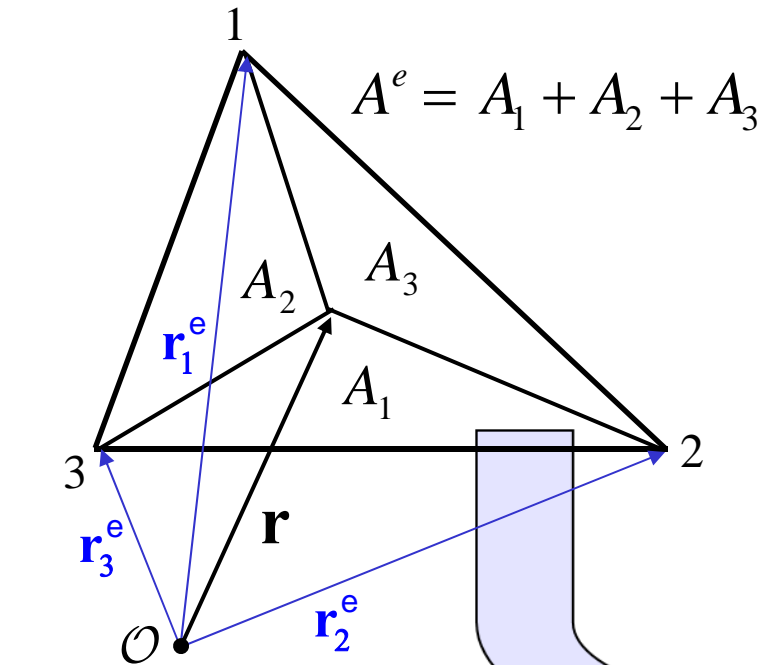


Alternative interpretation as delta f'n testing:

$$S_{mn} = \frac{1}{\epsilon} \iint_{\tilde{S}} \delta(\mathbf{r} - \mathbf{r}_c^m) G(\mathbf{r} - \mathbf{r}') \Pi_n(\mathbf{r}') dS' dS$$

$$\equiv \frac{1}{\epsilon} \langle \delta(\mathbf{r} - \mathbf{r}_c^m), G, \Pi_n \rangle$$

Area Coordinates Are Used to Represent Bases and Parameterize Element Geometry

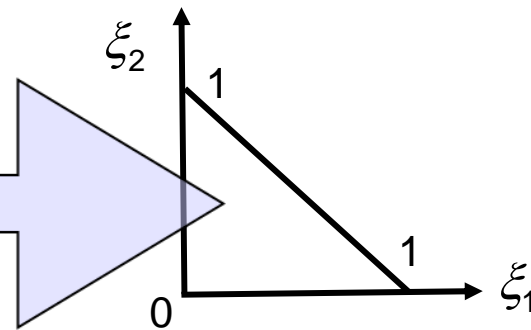


$$\mathbf{r} = \xi_1 \mathbf{r}_1^e + \xi_2 \mathbf{r}_2^e + \xi_3 \mathbf{r}_3^e$$

(proved later!)

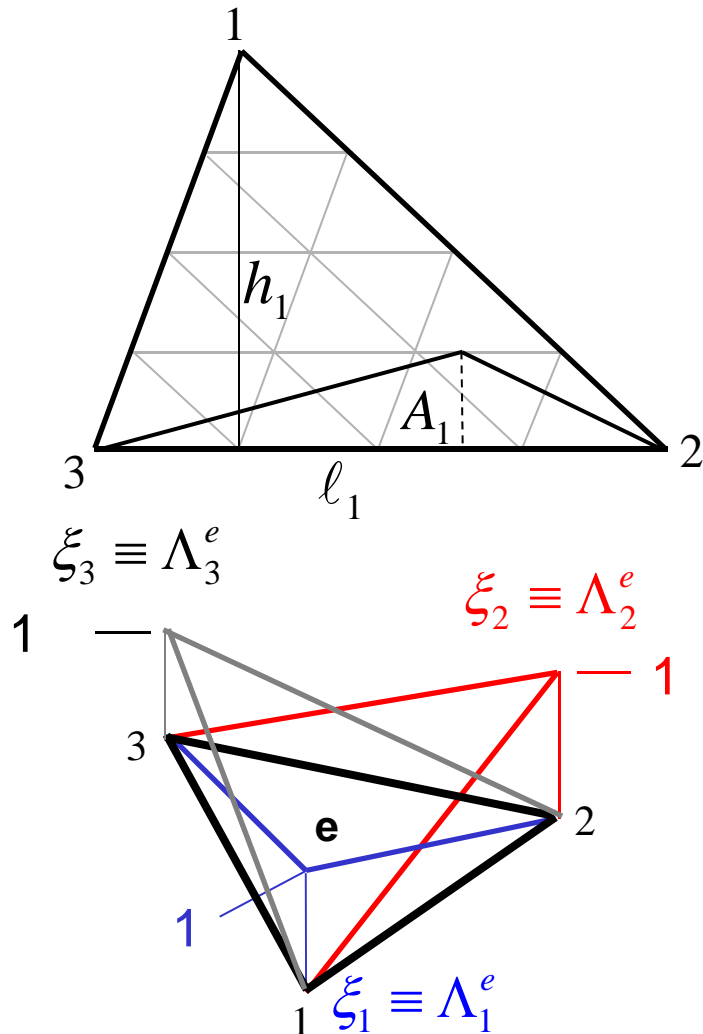
$$\xi_i = \frac{A_i}{A^e}, \quad i = 1, 2, 3$$

$$\Rightarrow \xi_1 + \xi_2 + \xi_3 = 1$$

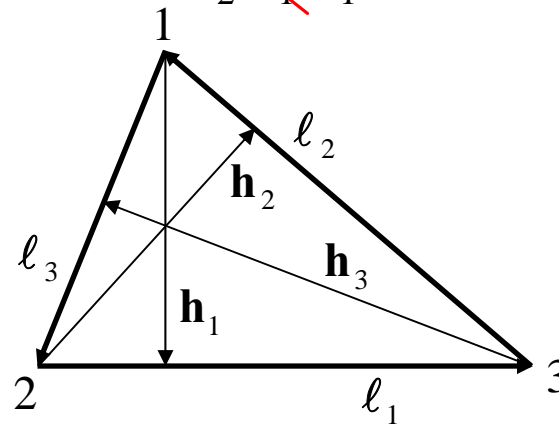


All elements mapped to
“parent element”

An Area Coordinate Is Also the Fractional Distance from an Edge to the Opposite Vertex

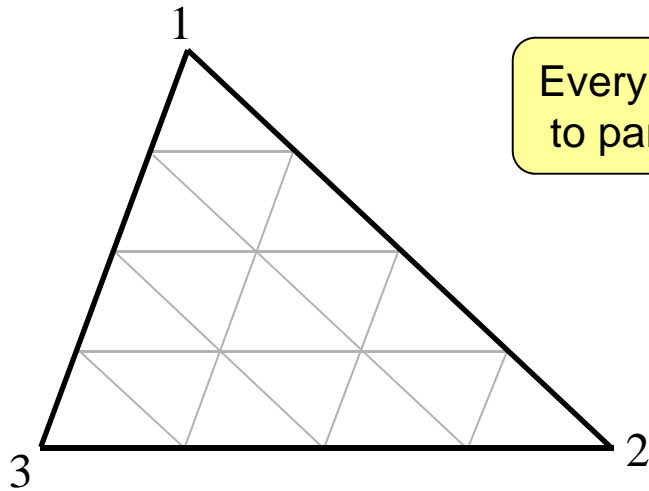


$$\xi_1 = \frac{\cancel{\frac{1}{2} \ell_1} \times \text{height of } A_1}{\cancel{\frac{1}{2} \ell_1} h_1} = \frac{\text{height of } A_1}{h_1}$$

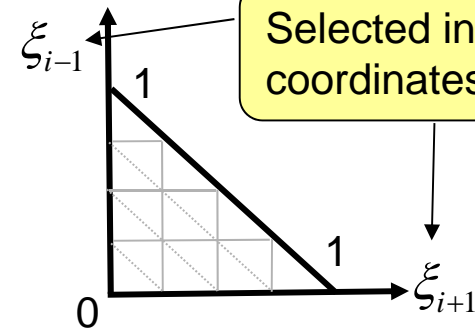
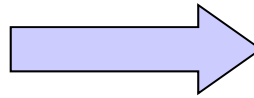


It is convenient to define local edge vectors ℓ_i associated with the edge opposite each vertex and local height vectors h_i associated with each vertex.

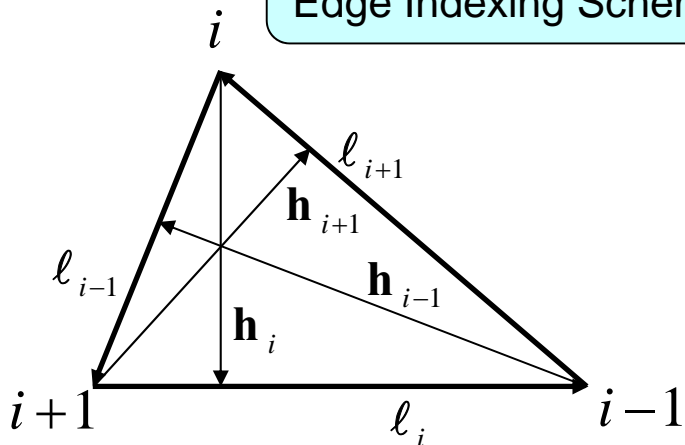
Coordinate Mapping and Modulo 3 Indexing



Every triangle is mapped to parent triangle



Modulo Vertex & Edge Indexing Scheme



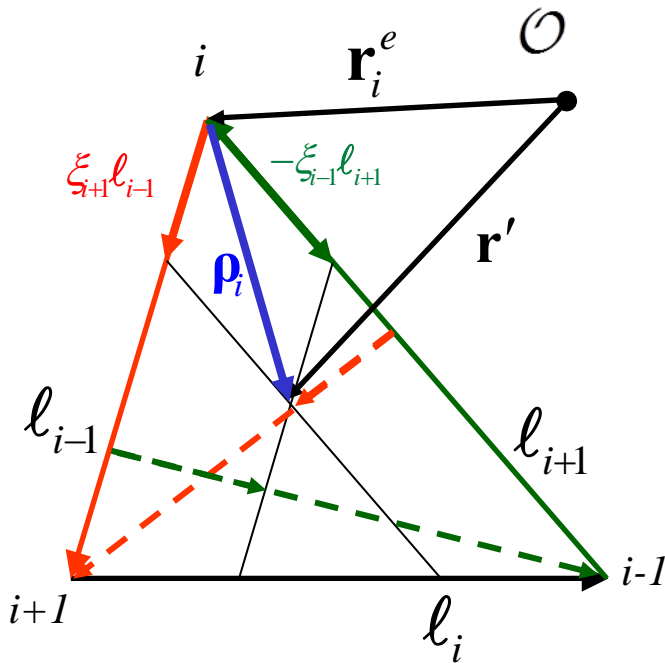
i	i+1 (= i-2)	i-1 (= i+2)
1	2	3
2	3	1
3	1	2

Index arithmetic performed modulo 3 :

$$i \pm j \equiv (i \pm j - 1)_{\text{mod } 3} + 1$$

Parameterization of a Triangular Patch

Parameterization **proof:**



$$\mathbf{r}' = \mathbf{r}_i^e + \underbrace{\xi_{i+1} \mathbf{l}_{i-1} - \xi_{i-1} \mathbf{l}_{i+1}}_{\rho_i}$$

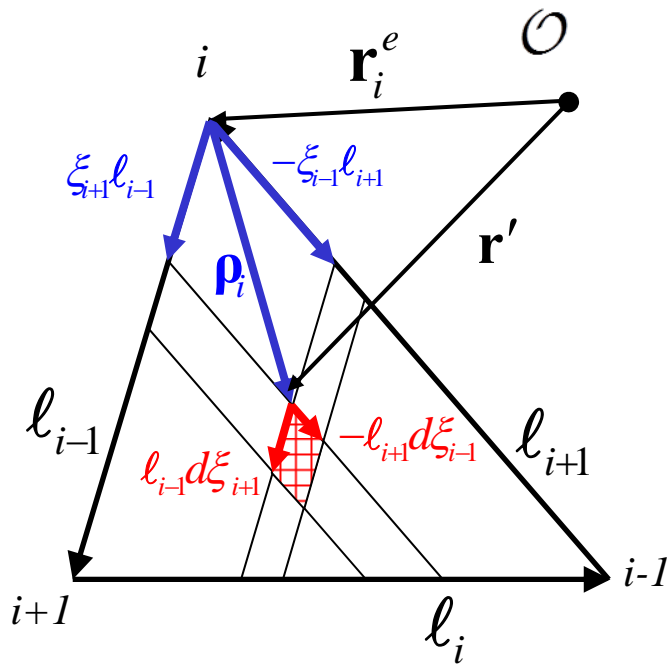
$$= \mathbf{r}_i^e + \xi_{i+1} (\mathbf{r}_{i+1}^e - \mathbf{r}_i^e) - \xi_{i-1} (\mathbf{r}_i^e - \mathbf{r}_{i-1}^e)$$

$$= \mathbf{r}_i^e (1 - \xi_{i+1} - \xi_{i-1}) + \mathbf{r}_{i+1}^e \xi_{i+1} + \mathbf{r}_{i-1}^e \xi_{i-1}$$

$$\Rightarrow \boxed{\mathbf{r}' = \mathbf{r}_i^e \xi_i + \mathbf{r}_{i+1}^e \xi_{i+1} + \mathbf{r}_{i-1}^e \xi_{i-1}}$$

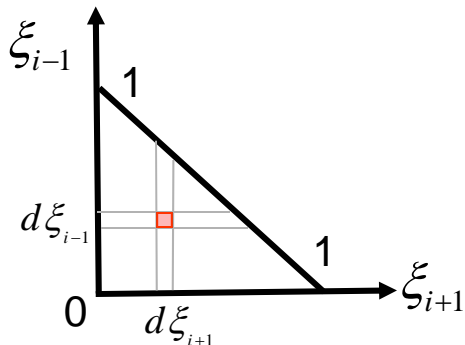
$$\Rightarrow \boxed{\mathbf{r}' = \sum_{i=1}^3 \mathbf{r}_i^e \xi_i}$$

Parameterization of Integrals



If ξ_{i+1} and ξ_{i-1} are independent variables, what is the surface area dS swept out when (ξ_{i+1}, ξ_{i-1}) changes to $(\xi_{i+1} + d\xi_{i+1}, \xi_{i-1} + d\xi_{i-1})$?

Ans: $dS = |\ell_{i-1} \times \ell_{i+1}| d\xi_{i+1} d\xi_{i-1}$



Hence integrals are evaluated as

$$\begin{aligned} \int_{A^e} f(\mathbf{r}) dS &= |\ell_{i-1} \times \ell_{i+1}| \int_0^1 \int_0^{1-\xi_{i-1}} f(\mathbf{r}_1^e \xi_1 + \mathbf{r}_2^e \xi_2 + \mathbf{r}_3^e \xi_3) d\xi_{i+1} d\xi_{i-1} \\ &= \underbrace{2A^e}_{\mathcal{J}} \int_0^1 \int_0^{1-\xi_{i-1}} f(\mathbf{r}_1^e \xi_1 + \mathbf{r}_2^e \xi_2 + \mathbf{r}_3^e \xi_3) d\xi_{i+1} d\xi_{i-1} \end{aligned}$$

For $m \neq n$, Integrate over Triangles Using Gaussian Area Coordinate Rules

$$\begin{aligned}
 & \int_{A^e} f(\mathbf{r}) dS \\
 &= 2A^e \int_0^1 \int_0^{1-\xi_2} f(\xi_1 \mathbf{r}_1^e + \xi_2 \mathbf{r}_2^e + \xi_3 \mathbf{r}_3^e) d\xi_1 d\xi_2 \\
 &\approx 2A^e \underbrace{\sum_{k=1}^K w_k f(\xi_1^{(k)} \mathbf{r}_1^e + \xi_2^{(k)} \mathbf{r}_2^e + \xi_3^{(k)} \mathbf{r}_3^e)}_{\text{Numerical integration}}
 \end{aligned}$$

Hence,

$$\begin{aligned}
 S_{mn} &= \int_{S^n} \frac{dS'}{4\pi\epsilon |\mathbf{r}_c^m - \mathbf{r}'|} \\
 &\approx \frac{2A^n}{\epsilon} \sum_{k=1}^K w_k G\left(\frac{\mathbf{r}_1^m + \mathbf{r}_2^m + \mathbf{r}_3^m}{3}, \xi_1^{(k)} \mathbf{r}_1^n + \xi_2^{(k)} \mathbf{r}_2^n + \xi_3^{(k)} \mathbf{r}_3^n\right)
 \end{aligned}$$

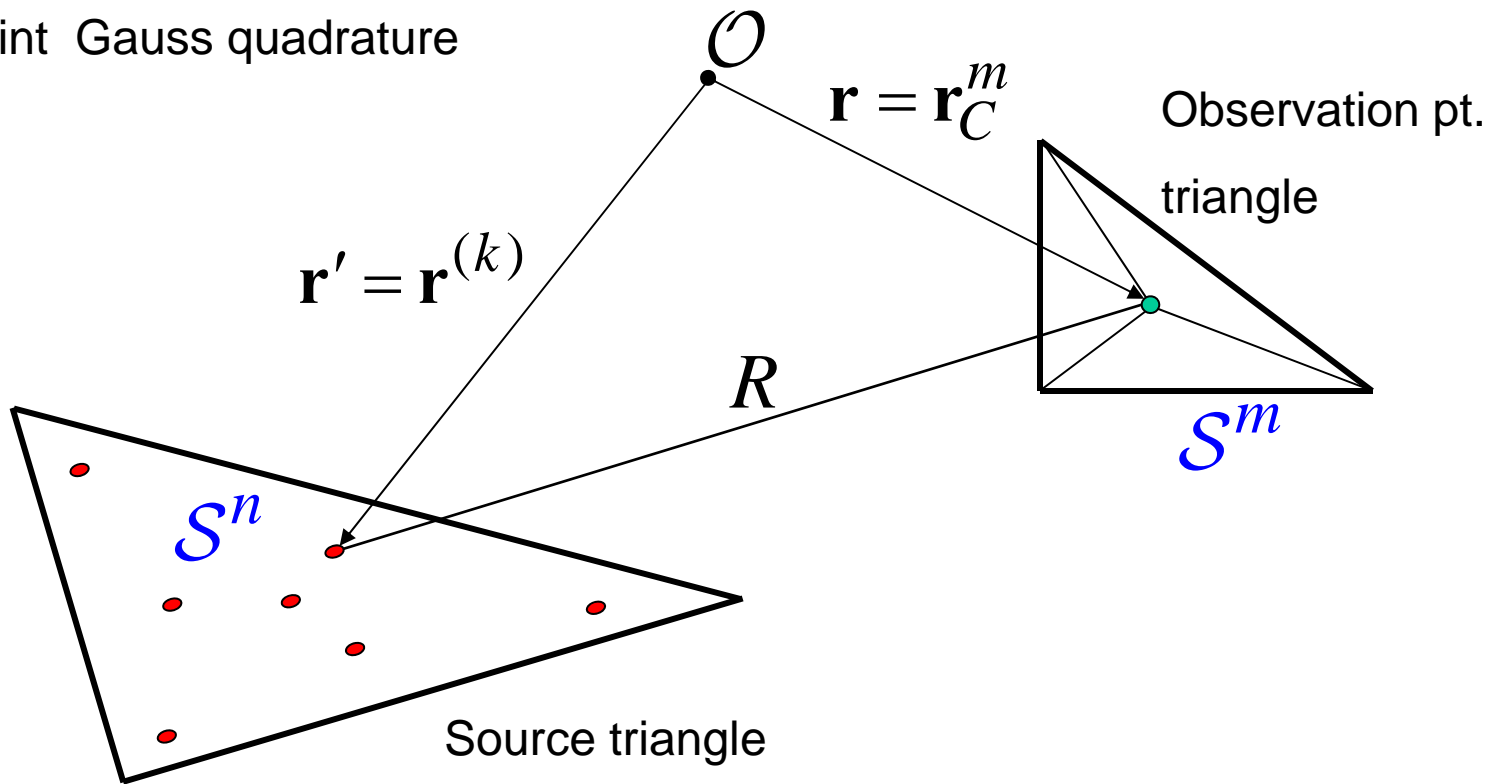
Table 9 Sample points and weighting coefficients for K -point quadrature on triangles.

Sample Points, $(\xi_1^{(k)}, \xi_2^{(k)})$ $(\xi_3^{(k)} = 1 - \xi_1^{(k)} - \xi_2^{(k)})$	Weights, w_k
K=1, error $\mathcal{O}(\xi_i^2)$: (0.33333333333333, 0.33333333333333)	0.50000000000000
K=3, error $\mathcal{O}(\xi_i^3)$: (0.66666666666667, 0.16666666666667) (0.16666666666667, 0.66666666666667) (0.16666666666667, 0.16666666666667)	0.16666666666667 0.16666666666667 0.16666666666667
K=7, error $\mathcal{O}(\xi_i^6)$: (0.33333333333333, 0.33333333333333) (0.79742698535309, 0.10128650732346) (0.10128650732346, 0.79742698535309) (0.10128650732346, 0.10128650732346) (0.47014206410512, 0.47014206410512) (0.47014206410512, 0.05971587178977) (0.05971587178977, 0.47014206410512)	0.11250000000000 0.06296959027241 0.06296959027241 0.06296959027241 0.06619707639425 0.06619707639425 0.06619707639425

Integration for Non-Self Terms, $m \neq n$

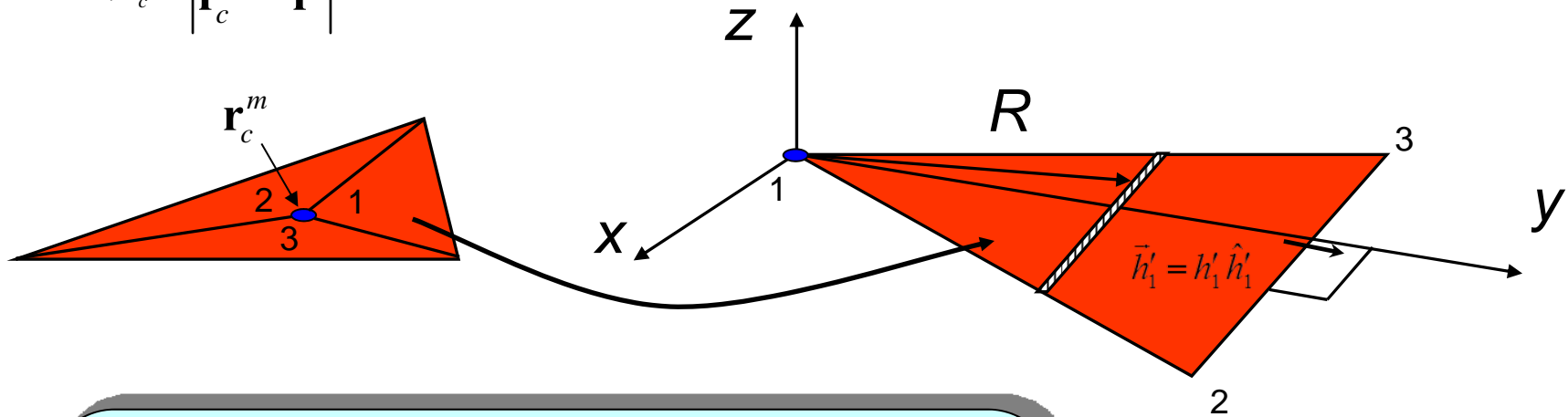
Non-singular case,

7 point Gauss quadrature



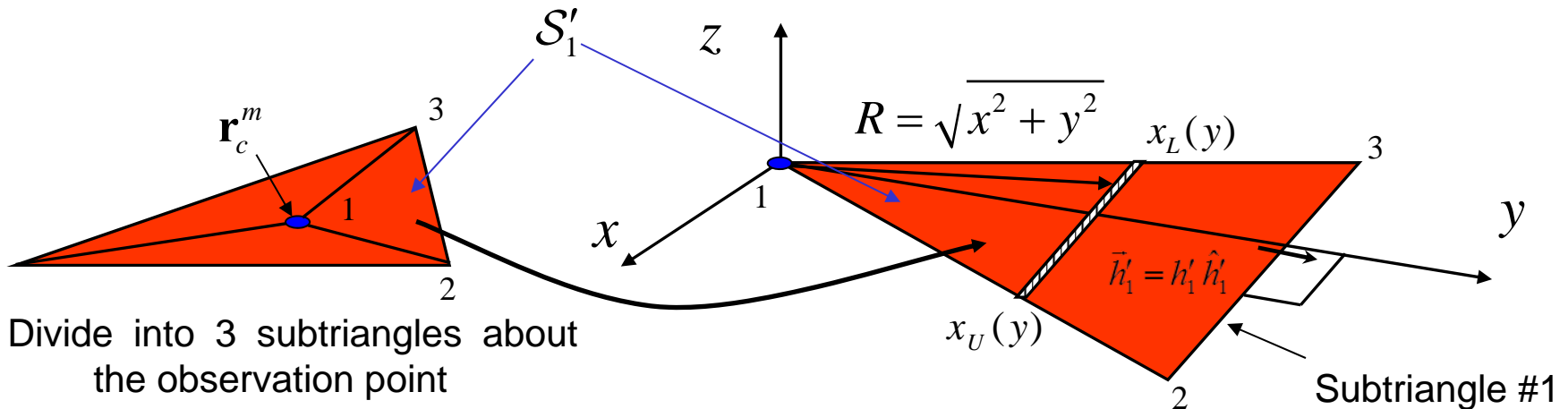
For $m = n$, Use a Singularity Cancellation Approach

$$\lim_{\mathbf{r}' \rightarrow \mathbf{r}_c^m} \frac{1}{|\mathbf{r}_c^m - \mathbf{r}'|} = \infty$$



- Split observation triangle into three subtriangles about the observation point
- Each subtriangle, which has a singularity at one of its vertices, is treated separately using a local x - y coordinate system

Transformation to Remove Singularity

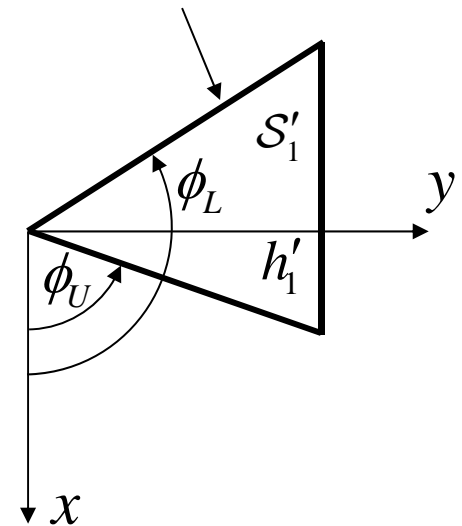


$$\int_{S'_1} \frac{1}{4\pi R} dS' = \int_0^{h'_1} \int_{x_L(y)}^{x_U(y)} \frac{1}{4\pi R} dx dy$$

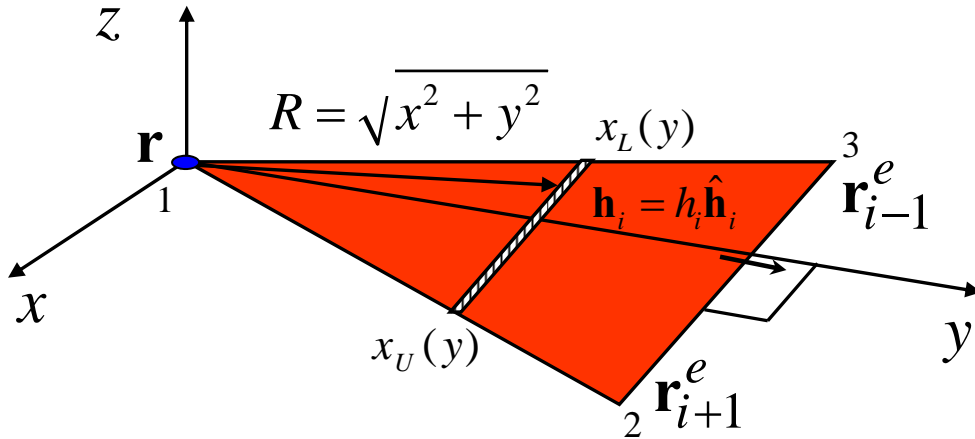
Let $du = \frac{dx}{R} \Rightarrow u = \sinh^{-1} \left(\frac{x}{y} \right) \left(= \ln \frac{x + \sqrt{x^2 + y^2}}{y} \right),$

$$\Rightarrow x = y \sinh u, \quad R = \sqrt{x^2 + y^2} = y \sqrt{1 + \sinh^2 u} = y \cosh u$$

$$\sinh u_L = \frac{x_L(y)}{y} = \cot \phi_L; \quad \sinh u_U = \frac{x_U(y)}{y} = \cot \phi_U$$



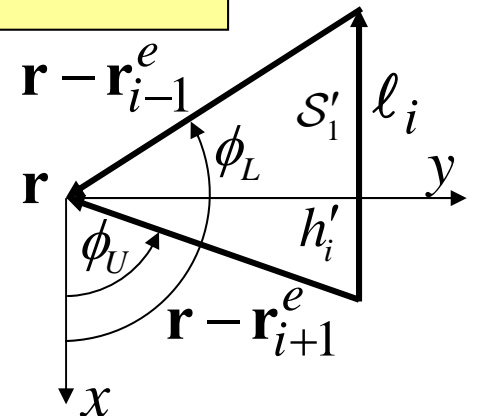
Evaluation of Integral



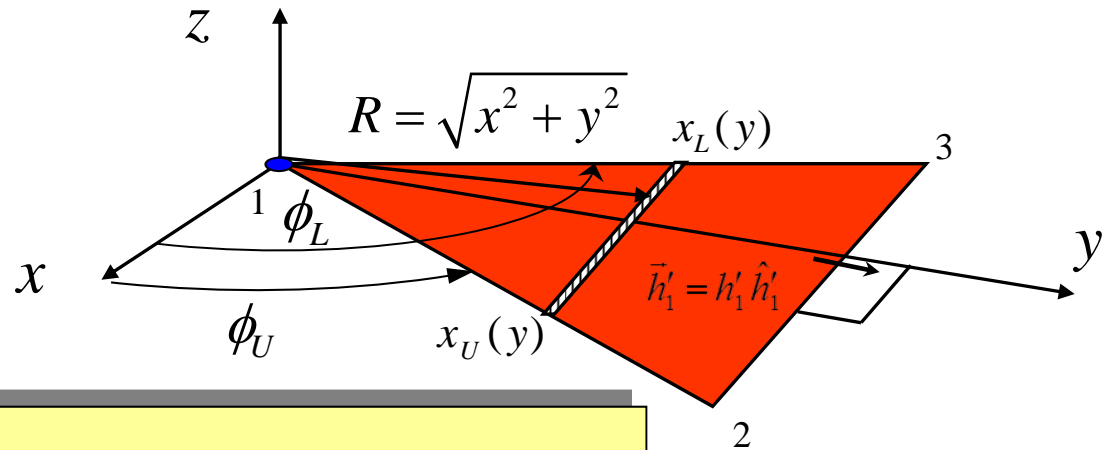
$$\begin{aligned} \int_{S'_i} \frac{1}{4\pi R} dS' &= \int_0^{h'_i} \int_{x_L(y)}^{x_U(y)} \frac{1}{4\pi R} dx dy = \frac{1}{4\pi} \int_0^{h'_i} \int_{u_L = \sinh^{-1} \cot \phi_L}^{u_U = \sinh^{-1} \cot \phi_U} du dy \\ &= \frac{h'_i}{4\pi} \left(\sinh^{-1} \cot \phi_U - \sinh^{-1} \cot \phi_L \right) \end{aligned}$$

Repeat and sum over all three subtriangles

$$\cot \phi_U = \frac{\ell_i \cdot (\mathbf{r} - \mathbf{r}_{i+1}^e)}{\left| \ell_i \times (\mathbf{r} - \mathbf{r}_{i+1}^e) \right|}, \quad \cot \phi_L = \frac{\ell_i \cdot (\mathbf{r} - \mathbf{r}_{i-1}^e)}{\left| \ell_i \times (\mathbf{r} - \mathbf{r}_{i-1}^e) \right|}$$



Determining a Quadrature Rule



generalized to
allow for phase
factor, bases, etc.

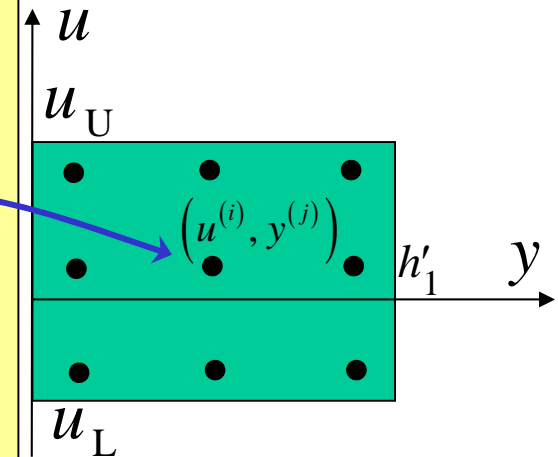
$$\int_{S'_1} \frac{f(\mathbf{r})}{4\pi R} dS' = \frac{1}{4\pi} \int_0^{h'_1} \int_{u_L}^{u_U} \overbrace{f(\mathbf{r}(u, y))}^{\text{smoothed integrand}} du dy$$

$$= \frac{h'_1(u_U - u_L)}{4\pi} \sum_i \sum_j w_i w_j f(\mathbf{r}(u^{(i)}, y^{(j)}))$$

where $u^{(i)} = u_U \xi_1^{(i)} + u_L \xi_2^{(i)}$, $y^{(j)} = h'_1 \xi_1^{(j)}$,

$(w_k, \xi_1^{(k)})$ are Gauss - Legendre weights & samples,

$$u_{U,L} = \sinh^{-1} \frac{x_{U,L}(y)}{y} = \sinh^{-1}(\cot \phi_{U,L})$$



Note only *one* sample pt.
needed to integrate
exactly if $f(\mathbf{r})=1$!

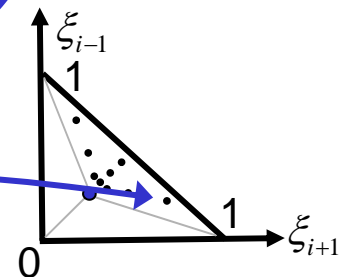
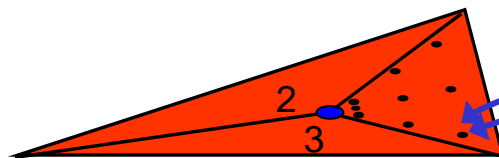
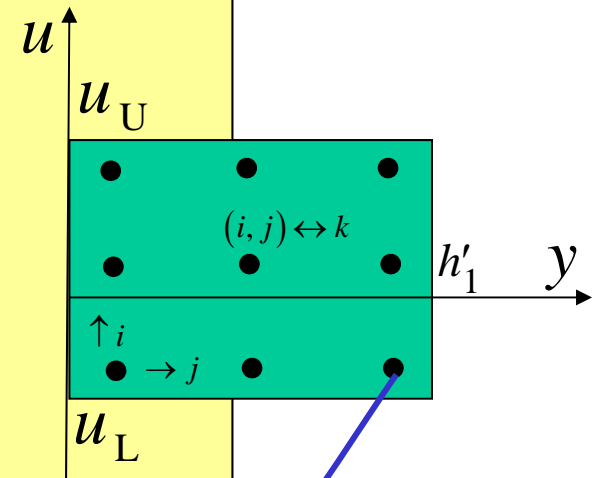
We Can Hide Transformation Details by Mapping Weights & Sample Points Back to Parent Triangle

- Map the index pair (i, j) to a single index k : $k \leftrightarrow (i, j)$
- Then *force* the integral into the standard parent triangle form,

$$\int_{S'_1} \frac{f(\mathbf{r})}{4\pi R} dS' \approx 2A^e \sum_{k=(i,j)} W_k \underbrace{\frac{f(\mathbf{r}^{(k)})}{4\pi R^{(k)}}}_{\text{Sampled values of integrand}}$$

• Since
$$\int_{S'_1} \frac{f(\mathbf{r})}{4\pi R} dS' \approx \frac{h'_1(u_U - u_L)}{4\pi} \sum_i \sum_j w_i w_j f(\mathbf{r}^{(i,j)})$$

$$\Rightarrow W_k = \frac{w_i w_j h'_1(u_U - u_L) R^{(k)}}{2A^e} \quad (\text{repeat for each subtriangle})$$



Mapping (u, y) Sample Points & Weights Back to ξ_i Coordinates

- Find corner of i -th subtriangle in local $\mathbf{p}_{\text{loc}} = (x_{\text{loc}}, y_{\text{loc}})$ coordinates:

$$\mathbf{p}_U \equiv (x_U(h'_i), h'_i), \mathbf{p}_L \equiv (x_L(h'_i), h'_i),$$

where $h'_i = \hat{\mathbf{h}}_i \cdot (\mathbf{r}_{i\pm 1}^e - \mathbf{r})$, $x_L(h'_i) = -\hat{\ell}_i \cdot (\mathbf{r}_{i-1}^e - \mathbf{r})$

$$x_U(h'_i) = -\hat{\ell}_i \cdot (\mathbf{r}_{i+1}^e - \mathbf{r}) \quad (\text{Note } \hat{\mathbf{x}}_{\text{loc}} = -\hat{\ell}_i, \hat{\mathbf{y}}_{\text{loc}} = \hat{\mathbf{h}}_i!)$$

- Determine angular limits: $\cot \phi_{L,U} = \frac{x_{L,U}(h'_i)}{h'_i}$
- Determine u -parameter limits: $u_{U,L} = \sinh^{-1}(\cot \phi_{U,L})$
- Determine transverse and radial sample points:

$$u^{(i)} = u_U \xi_1^{(i)} + u_L \xi_2^{(i)}, \quad i = 1, 2, \dots, K_{\text{transverse}}$$

$$y^{(j)} = h'_i \xi_1^{(j)}, \quad j = 1, 2, \dots, K_{\text{radial}}$$

- Map (u, y) sample points back to $(x_{\text{loc}}, y_{\text{loc}})$, then global (x, y, z) coordinates:

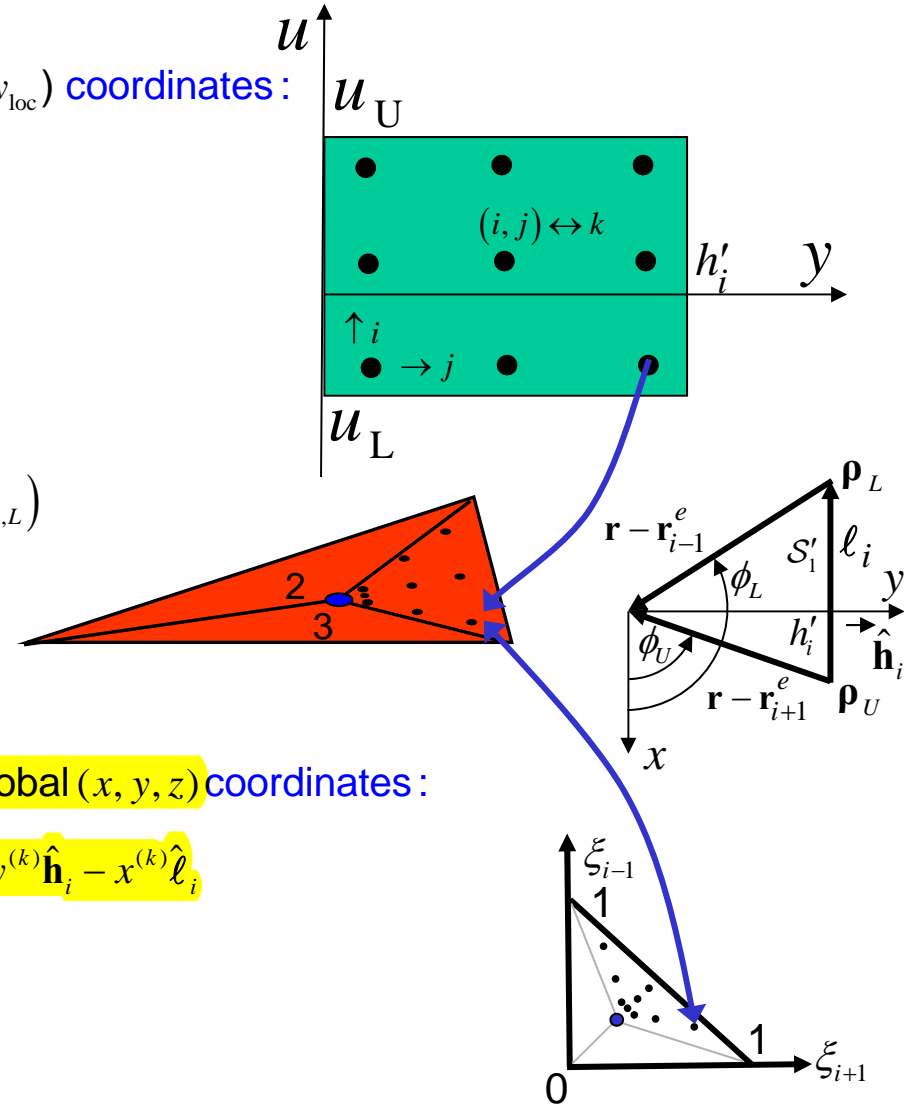
$$\mathbf{p}^{(k)} \equiv (x^{(k)}, y^{(k)}) \xrightarrow{k \leftrightarrow (i,j)} (y^{(j)} \sinh u^{(i)}, y^{(j)}) \Rightarrow \mathbf{r}^{(k)} = \mathbf{r} + y^{(k)} \hat{\mathbf{h}}_i - x^{(k)} \hat{\ell}_i$$

- Map $\mathbf{r}^{(k)}$ coordinates to area coordinates:

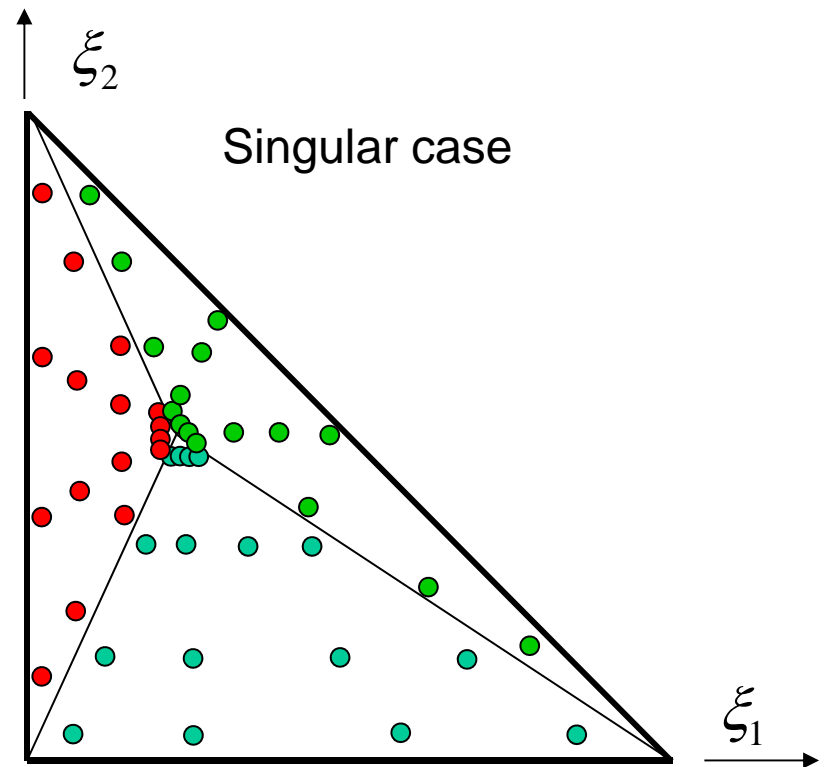
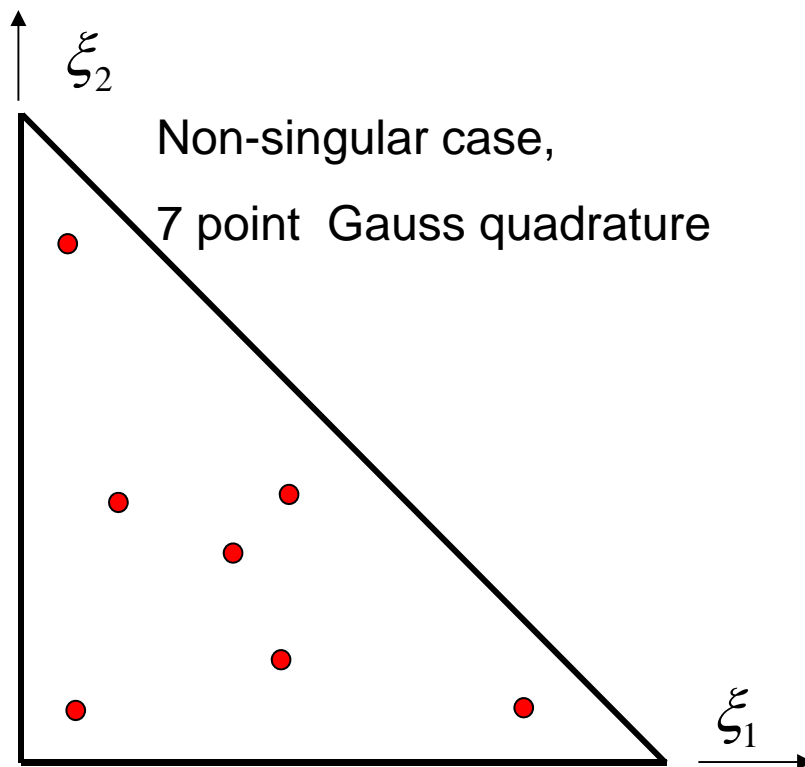
$$A_i^{(k)} = |\ell_i \times (\mathbf{r}^{(k)} - \mathbf{r}_{i+1}^e)|/2, \quad A_{i-1}^{(k)} = |\ell_{i-1} \times (\mathbf{r}^{(k)} - \mathbf{r}_{i+1}^e)|/2,$$

$$(\xi_i^{(k)}, \xi_{i-1}^{(k)}, \xi_{i+1}^{(k)}) = (A_i^{(k)}/A^e, A_{i-1}^{(k)}/A^e, 1 - \xi_i^{(k)} - \xi_{i-1}^{(k)})$$

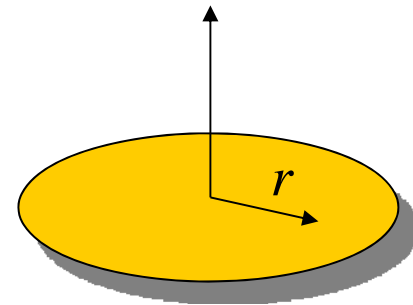
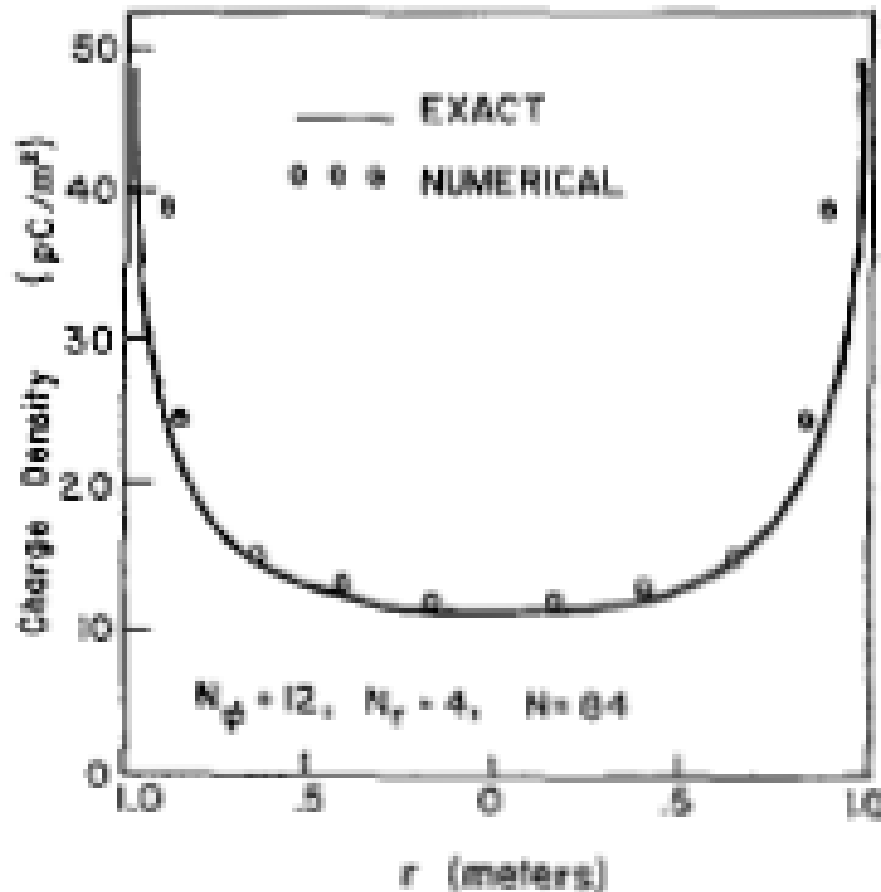
$$W_k = \frac{w_i w_j h'_1 (u_U - u_L) y^{(j)} \cosh u^{(i)}}{2A^e}$$



Typical Sample Point Schemes



Charge Distribution on a Conducting Circular Disk



Capacitance of a Conducting Sphere

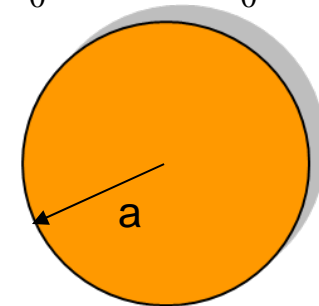
TABLE I
NORMALIZED CAPACITANCE OF A SPHERE (IN PICO FARADS/
METER)

N_ϕ	N_θ	N	C/a
6	3	24	94.03
6	4	36	98.33
6	5	48	100.39
6	6	60	101.51
6	8	84	102.64
8	3	32	96.81
8	4	48	101.20
8	5	64	103.28
8	6	80	104.43
EXACT			111.26

$$C = 4\pi\epsilon_0 a \text{ [F]}$$

$$C = \frac{Q}{\Phi_0} \approx \frac{\int_S \sum_{n=1}^N Q_n \Pi_n(\mathbf{r}) dS}{\Phi_0}$$

$$\approx \frac{\sum_{n=1}^N Q_n S^n}{\Phi_0} = \frac{1}{\Phi_0} [Q_n]^t [S^n]$$



Charge Distribution on a Bent Conducting Circular Disk

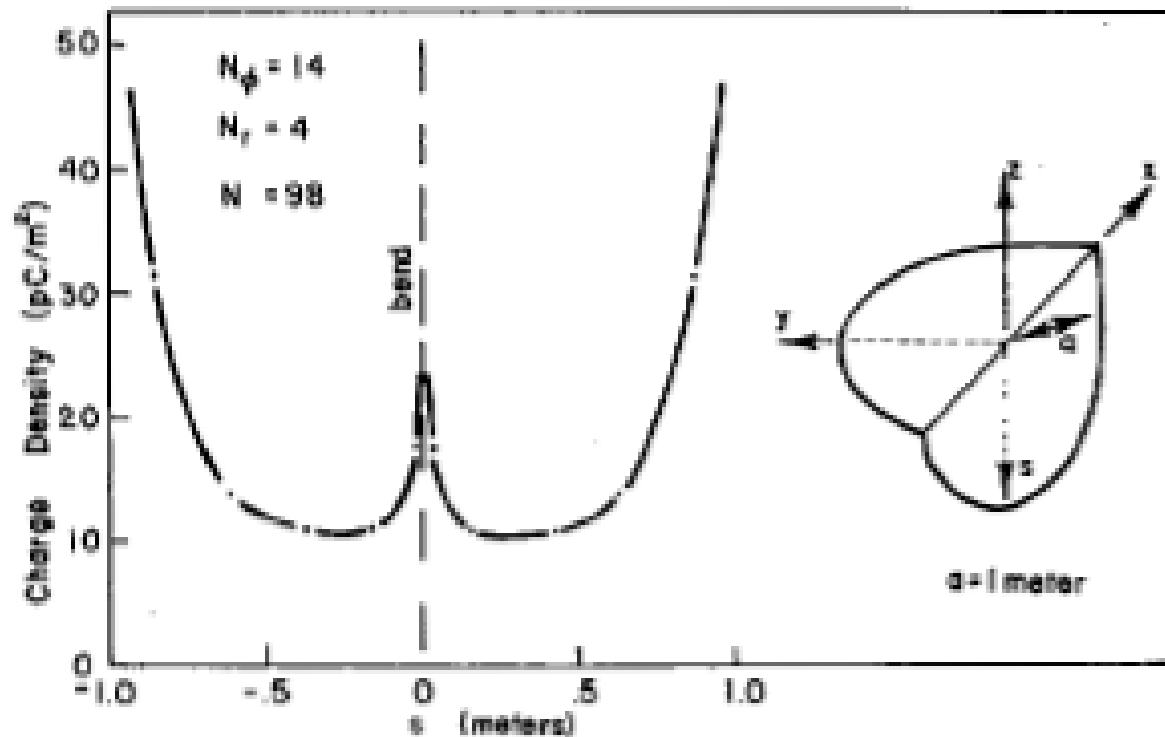
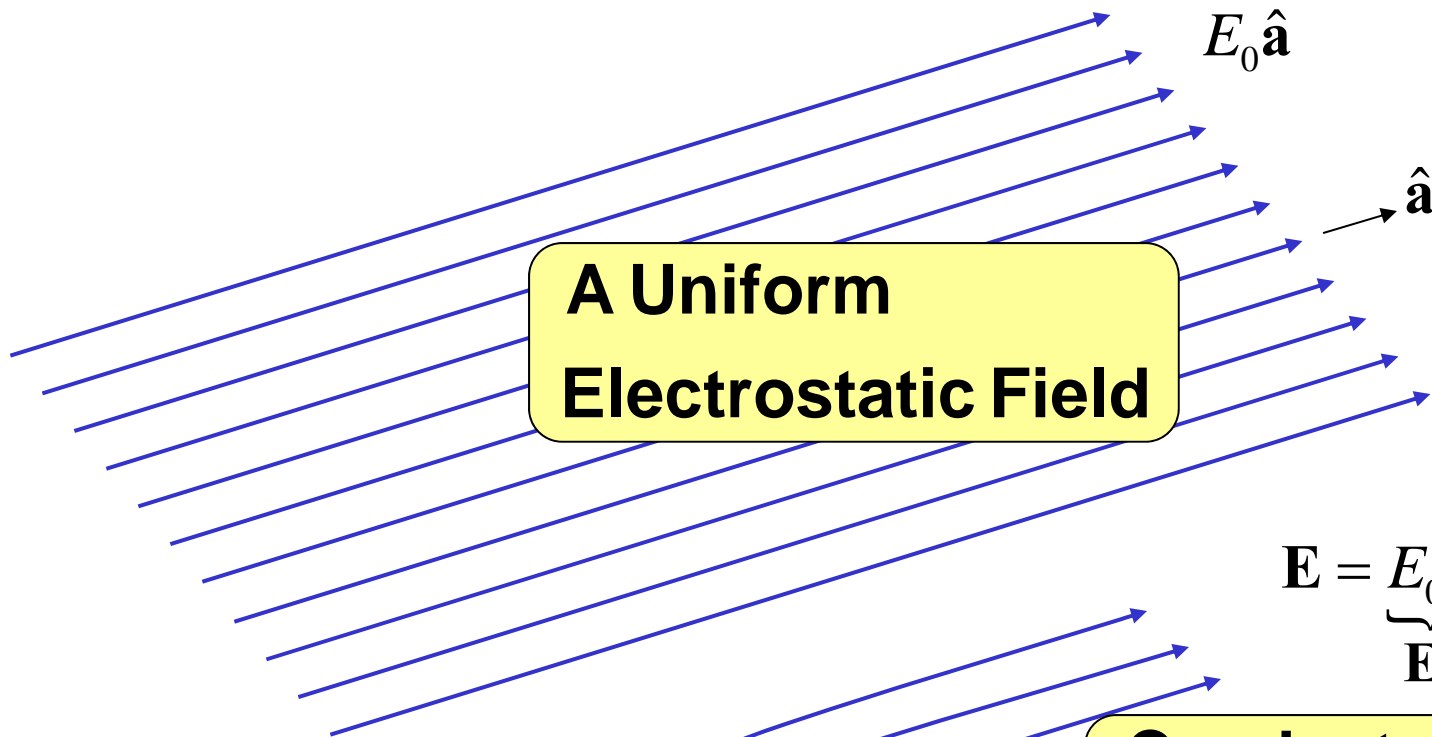
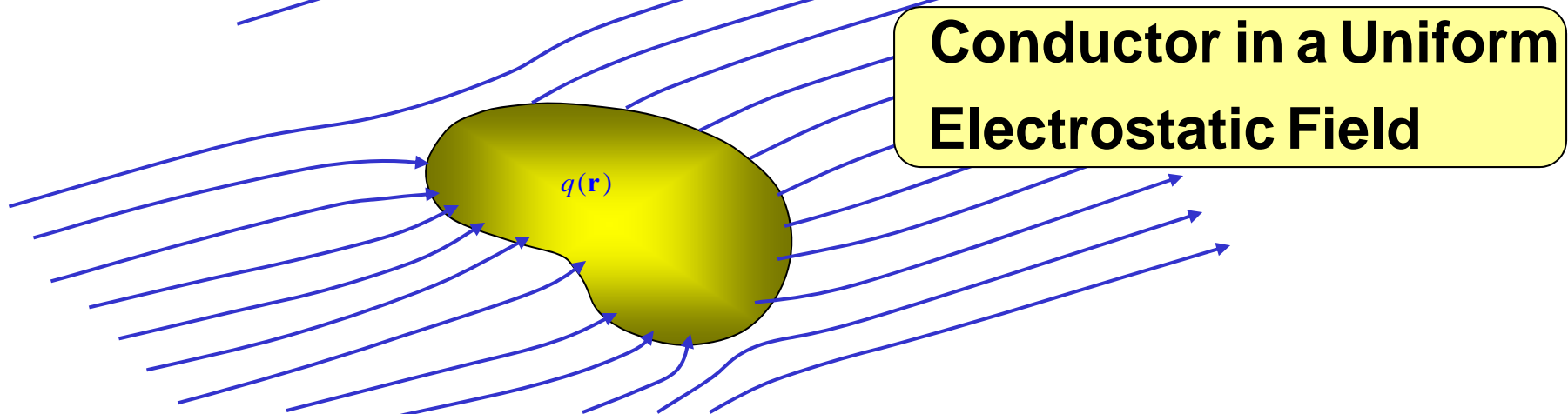


Fig. 3. Calculated charge density distribution on unit disk bent 90° along diameter. Distribution is plotted along symmetry plane perpendicular to bend.

Conductor in a Uniform Static Electric Field



$$\mathbf{E} = \underbrace{E_0 \hat{\mathbf{a}}}_{\mathbf{E}^i} + \mathbf{E}^s(q)$$



Modifications for a Conductor in a Uniform Impressed Field

- To produce a constant electric field in the direction of $\hat{\mathbf{a}}$, choose

$$\Phi^i = -E_0 \hat{\mathbf{a}} \cdot \mathbf{r} = -E_0 (\hat{a}_x x + \hat{a}_y y + \hat{a}_z z)$$

since

$$\mathbf{E}^i = -\nabla \Phi^i = E_0 (\hat{a}_x \hat{\mathbf{x}} + \hat{a}_y \hat{\mathbf{y}} + \hat{a}_z \hat{\mathbf{z}}) = E_0 \hat{\mathbf{a}} \quad \text{Assumed given!}$$

- $(\mathbf{E}^i + \mathbf{E}^s)_{\text{tan}} = 0 \quad \text{on } \mathcal{S}$

$$\Rightarrow -\nabla_{\text{tan}} (\Phi^i + \Phi^s) = 0 \quad \text{on } \mathcal{S}$$

$$\Rightarrow \Phi^i + \Phi^s = \Phi_0 \quad \text{on } \mathcal{S}$$

$$\Rightarrow \frac{1}{\epsilon} \int_{\mathcal{S}} G(\mathbf{r}, \mathbf{r}') q(\mathbf{r}') dS' = \underbrace{-\Phi^i(\mathbf{r})}_{=E_0 \hat{\mathbf{a}} \cdot \mathbf{r}} + \Phi_0, \quad \mathbf{r} \text{ on } \mathcal{S}$$

$$\text{Constraint: } \int_{\mathcal{S}} q(\mathbf{r}') dS' = Q_0 \quad \text{Assumed given!}$$

Problem Discretization

Potential integral equation:

$$\Rightarrow \frac{1}{\varepsilon} \int_S G(\mathbf{r}_c^m, \mathbf{r}') q(\mathbf{r}') dS' \approx \sum_{n=1}^N Q_n \int_{\tilde{S}} \frac{\Pi_n(\mathbf{r}')}{4\pi\varepsilon |\mathbf{r}_c^m - \mathbf{r}'|} dS' = -\Phi^i(\mathbf{r}_c^m) + \Phi_0,$$

Charge constraint:

$$m = 1, 2, \dots, N$$

$$\Rightarrow \int_S q(\mathbf{r}') dS' \approx \sum_{n=1}^N Q_n \int_{\tilde{S}} \Pi_n(\mathbf{r}') dS' = \sum_{n=1}^N Q_n S^n = [\mathcal{S}^n]^t [Q_n] = Q_0$$

$$\Rightarrow \begin{bmatrix} [S_{mn}] & [-1] \\ [\mathcal{S}^n]^t & 0 \end{bmatrix} \begin{bmatrix} [Q_n] \\ \Phi_0 \end{bmatrix} = \begin{bmatrix} [V_m] \\ Q_0 \end{bmatrix}$$

$$S^n \equiv \text{area of } \mathcal{S}^n$$

where

$$S_{mn} = \int_{\tilde{S}} \frac{\Pi_n(\mathbf{r}')}{4\pi\varepsilon |\mathbf{r}_c^m - \mathbf{r}'|} dS' = \int_{\mathcal{S}^n} \frac{dS'}{4\pi\varepsilon |\mathbf{r}_c^m - \mathbf{r}'|}$$

$$V_m = -\Phi^i(\mathbf{r}_c^m) = E_0 \hat{\mathbf{a}} \cdot \mathbf{r}_c^m$$

The End