Finite Element Solution of Helmholtz Equation for Inhomogeneously Filled Cylindrical Waveguide

D. R. Wilton and T. Kennedy

University of Houston

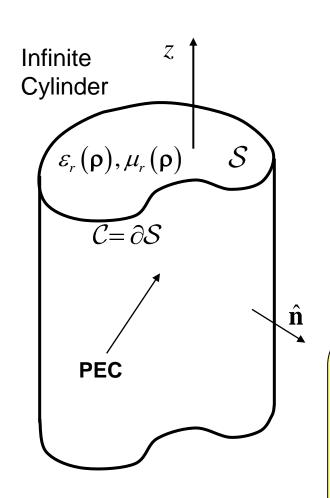
2.5D --- Main Extensions from the 2D, TM Case

• Both axial (E_z) and transverse (E_t) component exist and they are coupled

• We can model E_z as before, but now with $\exp(-jk_z z)$ phase variation

• Also must model E_t , which also has $exp(-jk_zz)$ phase variation

Helmholtz Equation for Inhomogeneously Filled Cylindrical Waveguide



Obtain the Helmholtz wave equation by eliminating the magnetic field between Maxwell's curl equations:

$$\nabla \times \mathbf{E} = -j\omega \,\mu_0 \mu_r(\mathbf{\rho}) \mathbf{H}$$

$$\nabla \times \mathbf{H} = j\omega \,\varepsilon_0 \varepsilon_r(\mathbf{p}) \mathbf{E} + \mathbf{J}$$

$$\Rightarrow \nabla \times (\mu_r^{-1} \nabla \times \mathbf{E}) - k_0^2 \varepsilon_r \mathbf{E} = -j\omega \,\mu_0 \mathbf{J}$$

Strong form,

(unreduced)

wave eq.

Assume fields and current

vary as e^{-jk_zz} :

$$\mathbf{J}(\mathbf{r}) = \tilde{\mathbf{J}}(\mathbf{\rho}) \left[e^{-jk_z z} \right]$$

$$\mathbf{E}(\mathbf{r}) = \tilde{\mathbf{E}}(\mathbf{o}) \left[e^{-jk_z z} \right]$$

$$\mathbf{H}(\mathbf{r}) = \tilde{\mathbf{H}}(\mathbf{p}) \left[e^{-jk_z z} \right]$$

$$\mathbf{J}(\mathbf{r}) = \tilde{\mathbf{J}}(\boldsymbol{\rho}) \left[e^{-jk_z z} \right]$$
 e.g. $\frac{\partial}{\partial z} \mathbf{J}(\mathbf{r}) = -jk_z \tilde{\mathbf{J}}(\boldsymbol{\rho}) \left[e^{-jk_z z} \right]$

$$\frac{\mathbf{E}(\mathbf{r}) = \tilde{\mathbf{E}}(\mathbf{\rho}) [e^{-jk_z z}]}{\mathbf{H}(\mathbf{r}) = \tilde{\mathbf{H}}(\mathbf{\rho}) [e^{-jk_z z}]} \Rightarrow \frac{\partial}{\partial z} \Leftrightarrow -jk_z$$

Reduced Helmholtz Equation

no z dependence

Strong form of "reduced" Helmholtz equation: $\nabla_{t} \equiv \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y}$

$$\tilde{\nabla} \times (\mu_r^{-1} \tilde{\nabla} \times \tilde{\mathbf{E}}) - k_0^2 \varepsilon_r \tilde{\mathbf{E}} = -j\omega \mu_0 \tilde{\mathbf{J}}, \quad \rho \in \mathcal{S}$$

$$\tilde{\mathbf{\nabla}} \times \left(\left(j\omega\mu \right)^{-1} \tilde{\mathbf{\nabla}} \times \tilde{\mathbf{E}} \right) + j\omega\varepsilon \tilde{\mathbf{E}} = -\tilde{\mathbf{J}}, \ \mathbf{\rho} \in \mathcal{S}$$

$$\nabla_{t} \equiv \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y}$$

$$\tilde{\nabla} \equiv \nabla_t - jk_z \hat{\mathbf{z}}$$

$$\tilde{\boldsymbol{\nabla}}^* \equiv \boldsymbol{\nabla}_{t} + j k_{z} \hat{\mathbf{z}}$$

for both real and complex k_{z}

• Test *un*reduced equation with $\Omega_m(\rho) [e^{+jk_z z}]$, obtaining

$$<\Omega_m; \nabla \times (\mu_r^{-1} \nabla \times \mathbf{E}) > -k_0^2 < \Omega_m; \varepsilon_r \mathbf{E} > = -j\omega \mu_0 < \Omega_m; \mathbf{J} >$$

$$\rho \in \mathcal{S}, z \in (-\infty, \infty),$$
 and where $\langle \mathbf{A}; \mathbf{B} \rangle \equiv \int_{\mathcal{S}} \mathbf{A} \cdot \mathbf{B} \, d\mathcal{S}.$

Reduce differentiability requirement on E using

 $\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot \nabla \times \mathbf{A} - \mathbf{A} \cdot \nabla \times \mathbf{B}$ and divergence theorem, yielding the weak form of the Helmholtz equation:

$$\frac{1}{j\omega\mu_{0}} < \tilde{\nabla}^{*} \times \Omega_{m}; \mu_{r}^{-1}\tilde{\nabla} \times \tilde{\mathbf{E}} > + j\omega\varepsilon_{0} < \Omega_{m}; \varepsilon_{r}\tilde{\mathbf{E}} >
= - < \Omega_{m}; \tilde{\mathbf{J}} > - \oint_{\mathcal{C}} \Omega_{m} \cdot (\tilde{\mathbf{H}} \times \hat{\mathbf{n}}) d\mathcal{C}$$

$$\frac{1}{j\omega\mu_{0}} \int_{\mathcal{S}} \nabla \cdot \left[\Omega_{m} \times (\mu_{r}^{-1}\nabla \times \mathbf{E}) \right] d\mathcal{S}
= \frac{1}{j\omega\mu_{0}} \int_{\mathcal{C}} \left[\Omega_{m} \times (\mu_{r}^{-1}\nabla \times \mathbf{E}) \right] \cdot \hat{\mathbf{n}} d\mathcal{C}$$

$$= - \oint_{\mathcal{C}} \Omega_{m} \cdot (\mathbf{H} \times \hat{\mathbf{n}}) d\mathcal{C}$$

$$\frac{1}{i\omega\mu_{0}} \int_{\mathcal{S}} \nabla \cdot \left[\mathbf{\Omega}_{m} \times \left(\mu_{r}^{-1} \nabla \times \mathbf{E} \right) \right] d\mathcal{S}$$

$$= \frac{1}{j\omega\mu_{0}} \int_{\mathcal{C}} \left[\mathbf{\Omega}_{m} \times \left(\mu_{r}^{-1} \nabla \times \mathbf{E} \right) \right] \cdot \hat{\mathbf{n}} \ d\mathcal{C}$$

$$= -\oint_{\mathbf{\Omega}} \mathbf{\Omega}_{m} \cdot (\mathbf{H} \times \hat{\mathbf{n}}) d\mathcal{C}$$

System Matrix

The boundary integral vanishes if $\Omega_m(\rho) \lceil e^{-jk_z z} \rceil$ are also interpolatory basis functions for $\tilde{\mathbf{E}}$, (or tangential $\tilde{\mathbf{E}}$)

$$\Rightarrow \widetilde{\mathbf{E}} = \sum_{n=1}^{N} V_n \, \mathbf{\Omega}_n \, (\mathbf{\rho}),$$

since $\hat{\mathbf{n}} \times \tilde{\mathbf{E}} = \sum_{n=0}^{N} V_n \left[\hat{\mathbf{n}} \times \mathbf{\Omega}_n \left(\mathbf{\rho} \right) \right] = \mathbf{0}$ on the boundary $\Rightarrow \hat{\mathbf{n}} \times \mathbf{\Omega}_n = \mathbf{0}$ on \mathcal{C} .

Substituting $\tilde{\mathbf{E}}$ into the weak form yields $| [Y_{mn}] [V_n] = [I_m] |$ where

$$ig|ig[Y_{mn}ig]ig[V_nig]\!=\!ig[I_mig]ig|$$
 where

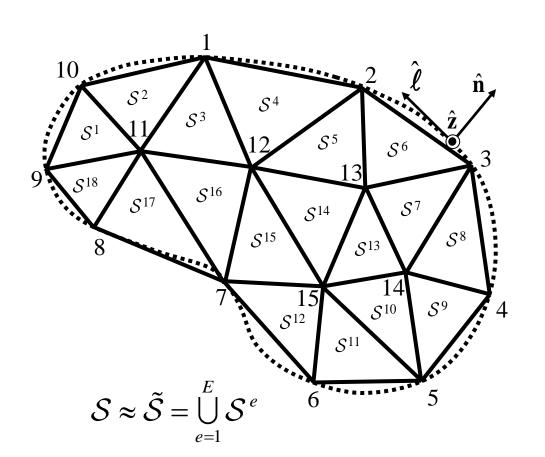
$$[Y_{mn}] = \frac{1}{i\omega} [\Gamma_{mn}] + j\omega [C_{mn}],$$
 (admittance or system matrix)

$$\left[\Gamma_{mn}\right] = \frac{1}{\mu_0} \left[<\tilde{\nabla}^* \times \Omega_m; \mu_r^{-1} \tilde{\nabla} \times \Omega_n > \right], \text{ (reciprocal inductance matrix)}$$

$$[C_{mn}] = \varepsilon_0 [<\Omega_m; \varepsilon_r \Omega_n>],$$
 (capacitance matrix)

$$[I_m] = [-<\Omega_m; \tilde{\mathbf{J}}>]$$
 (excitation vector)

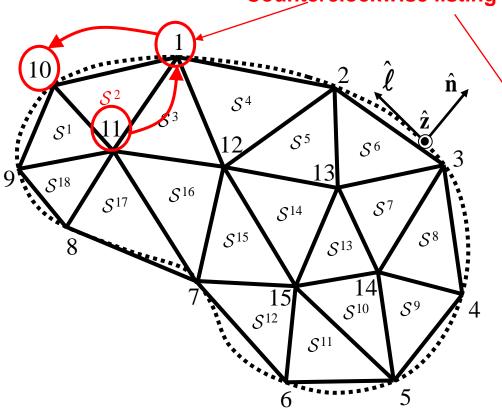
Discretize the Guide Cross Section --- Nodal Data



| Global | Coordinates | |
|----------------|-------------|--------|
| Node Index v | x_v | y_v |
| 1 | -0.500 | 1.100 |
| 2 | 1.100 | 0.700 |
| : | : | |
| 12 | 0.000 | 0.000 |
| : | : | : : |
| 15 | 0.700 | -1.100 |

Element Connection Data

Counterclockwise listing



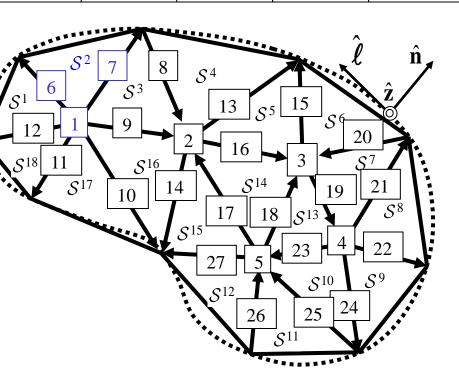
| | Local Node 1 2 3 | | | | |
|----|---------------------|--------------------|--------------------|--|--|
| е | Global Node No. | Global Node No. | Global Node No. | | |
| 1 | 9 | 11 | 10 | | |
| 2 | 11 | 1 | 10 | | |
| i | : | i | : | | |
| 14 | 15 | 13 | 12 | | |
| i | : | i | : | | |
| 18 | 8 | 11 | 9 | | |

Element DoF Data

| Loca | ıl ← Tra | ansverse | DoFs→ | ← Ax | cial DoFs | \rightarrow |
|------|----------------|----------------|----------------|----------------|----------------|----------------|
| DoF | # 1 | 2 | 3 | 4 | 5 | 6 |
| е | Global DoF# | Global DoF# | Global DoF# | Global DoF# | Global DoF# | Global DoF# |
| 1 | 6 | 0 | -12 | 0 | 1 | 0 |
| 2 | 0 | -6 | 7 | 1 | 0 | 0 |
| ÷ | : / | / : | i | i | i | i |

Ref. direction is *opposite* counterclockwise direction

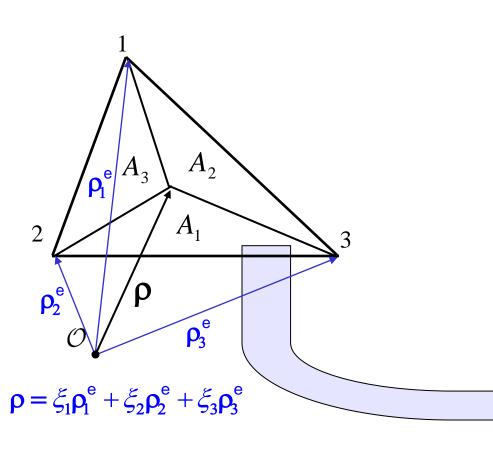
$$\Rightarrow \sigma_2^e = -1$$



 $\hat{\mathbf{z}}$

6

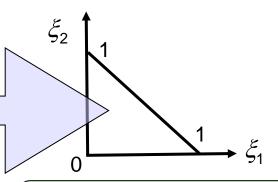
Area Coordinates Used to Represent Bases, Parameterize Element Geometry



$$\xi_i = \frac{A_i}{A^e}, \quad i = 1, 2, 3$$

$$\Rightarrow \xi_1 + \xi_2 + \xi_3 = 1$$

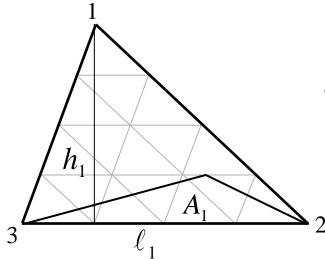
$$\Rightarrow \Lambda_i^e = \xi_i, \quad i = 1, 2, 3$$



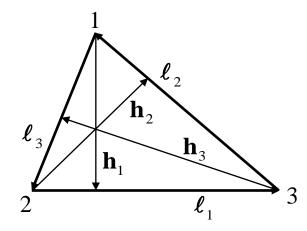
$$\Rightarrow \left| \Lambda_i^e = \xi_i = \frac{\hat{\mathbf{z}} \cdot \boldsymbol{\ell}_i \times (\boldsymbol{\rho} - \boldsymbol{\rho}_{i+1}^e)}{\hat{\mathbf{z}} \cdot \boldsymbol{\ell}_{i+1} \times \boldsymbol{\ell}_{i-1}}, \quad i = 1, 2, 3 \right|$$

All elements mapped to "parent element"

An Area Coordinate Is Also the Fractional Distance from an Edge to the Opposite Vertex

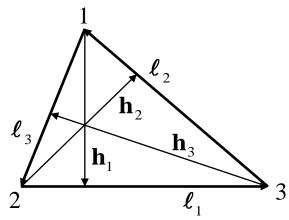


$$\xi_1 = \frac{\frac{1}{2}\ell_1 \times (\text{height of } A_1)}{\frac{1}{2}\ell_1 h_1} = \frac{\text{height of } A_1}{h_1}$$



It is convenient to define edge vectors associated with each edge and height vectors associated with each vertex.

Recall Local Geometry Definitions

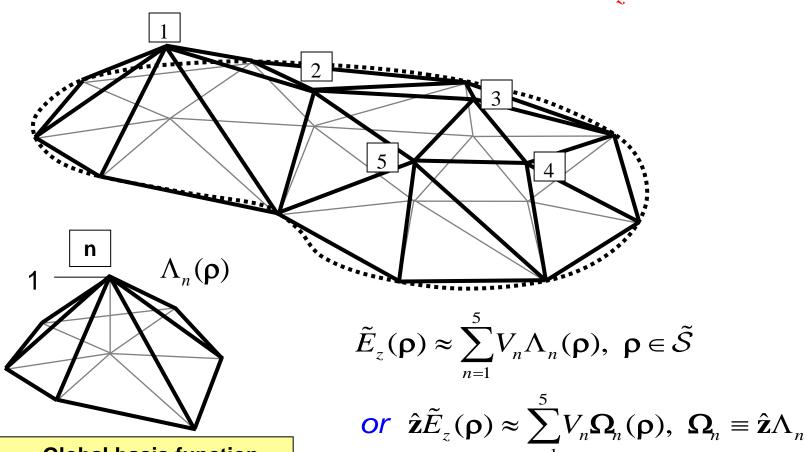


$$\hat{\mathbf{n}} = \frac{\boldsymbol{\ell}_{i+1} \times \boldsymbol{\ell}_{i-1}}{2A^e}$$

Table 8 Geometrical quantities defined on triangular elements.

| | Edge vectors | $\boldsymbol{\ell}_i = \boldsymbol{ ho}_{i-1}^e - \boldsymbol{ ho}_{i+1}^e; \;\; \ell_i = \boldsymbol{\ell}_i ;$ |
|---|----------------------|---|
| | | $\hat{m{\ell}}_i = rac{m{\ell}_i}{\ell_i}$, $i=1,2,3$ |
| 8 | Area | $A^e = \frac{ \boldsymbol{\ell}_{i-1} \times \boldsymbol{\ell}_{i+1} }{2}$, $i=1,2,$ or 3 |
| | Height vectors | $h_i = \frac{2A^e}{\ell_i}; \ \hat{\boldsymbol{h}}_i = -\hat{\boldsymbol{n}} \times \hat{\boldsymbol{\ell}}_i;$ |
| | | $oldsymbol{h}_i = h_i \hat{oldsymbol{h}}_i$, $i = 1, 2, 3$ |
| | Coordinate gradients | $oldsymbol{ abla} \xi_i = -rac{\hat{oldsymbol{h}}_i}{h_i}$, $i=1,2,3$ |

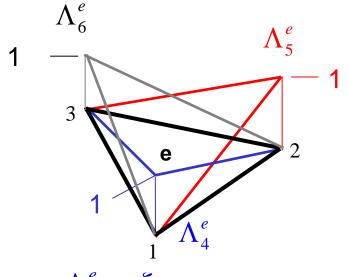
Piecewise Linear Model of Axial Electric Field, \tilde{E}_{τ}



Global basis function associated with DoF *n*

Global Representation

Local Representations of \tilde{E}_z



$$\Lambda_4^e = \xi_1$$

$$\Lambda_5^e = \xi_2$$

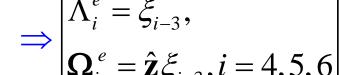
$$\Lambda_6^e = \xi_3$$

$$\tilde{E}_{z}(\mathbf{p}) \approx \sum_{i=4}^{6} V_{i}^{e} \Lambda_{i}^{e}(\mathbf{p}), \ \mathbf{p} \in \mathcal{S}^{e}$$

Local Scalar Representation

and
$$\tilde{\nabla} \times [\hat{\mathbf{z}} \Lambda_i^e(\mathbf{p})] = \nabla \xi_{i-3} \times \hat{\mathbf{z}}, \, \mathbf{p} \in \mathcal{S}^e$$
,

Local Vector Representation



Local bases and triangle parameterization can be easily expressed in area coordinates

Properties of ρ_n^{\pm} Vectors



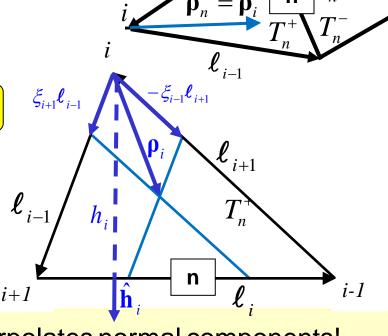
$$\mathbf{p}_{n}^{+} = \mathbf{p}_{i} = \xi_{i+1} \ell_{i-1} - \xi_{i-1} \ell_{i+1},$$

$$\rho_n^- = -\rho_j = \xi_{j-1} \ell_{j+1} - \xi_{i+1} \ell_{i-1}$$

Unit normal component at edges:

$$\hat{\mathbf{h}}_{i} \cdot \frac{\mathbf{p}_{n}^{+}|_{\xi_{i}=0}}{h_{i}} = \frac{\mathbf{p}_{i} \cdot \mathbf{h}_{i}|_{\xi_{i}=0}}{h_{i}} = \frac{h_{i}}{h_{i}} = 1,$$

$$-\hat{\mathbf{h}}_{j} \cdot \frac{\mathbf{p}_{n}^{-}|_{\xi_{j}=0}}{h_{j}} = \frac{\mathbf{p}_{j} \cdot \hat{\mathbf{h}}_{j}|_{\xi_{j}=0}}{h_{j}} = \frac{h_{j}}{h_{j}} = 1$$

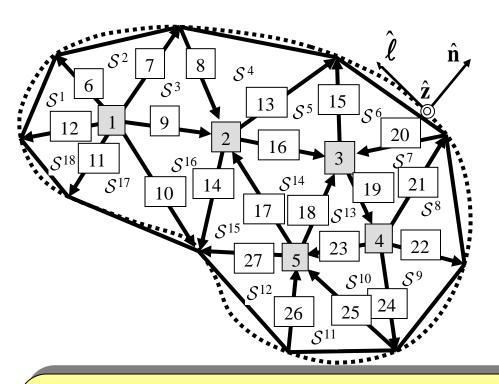


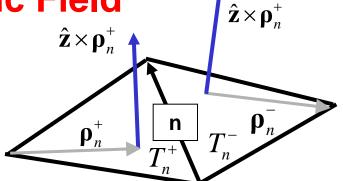
• Since $\mathbf{p}_i \cdot \hat{\mathbf{h}}_{i\pm 1} = \mathbf{p}_j \cdot \hat{\mathbf{h}}_{j\pm 1} = 0$, $\frac{\mathbf{p}_n^-}{\mathbf{h}_n^\pm}$ interpolates normal components!

I.e., given normal components, $\mathbf{A} \cdot \hat{\mathbf{h}}_i$, i = 1, 2, 3, of a vector \mathbf{A} at triangle edges, a possible approximation for \mathbf{A} is $\mathbf{A} \approx \sum_{i=1}^{3} (\mathbf{A} \cdot \hat{\mathbf{h}}_i) \frac{\mathbf{p}_i}{h_i}$. Similarly,

$$\mathbf{A} \approx \sum_{i=1}^{3} \left(\mathbf{A} \cdot \hat{\boldsymbol{\ell}}_{i} \right) \frac{\mathbf{n} \times \boldsymbol{\rho}_{i}}{h}$$
 interpolates tangential components!

Representation of Transverse **Vector Electric Field**





Global basis representation:

$$\frac{\mathbf{\Omega}_{n}(\mathbf{\rho})}{\hat{h}_{n}^{\pm}}, \mathbf{\rho} \in T_{n}^{\pm}$$

$$=\hat{\mathbf{z}} \times \mathbf{\Lambda}_{n}(\mathbf{\rho})$$

$$=\hat{\mathbf{z}} \times \mathbf{\Lambda}_{n}(\mathbf{\rho})$$

$$=\hat{\mathbf{0}}, \text{ otherwise}$$

$$\tilde{\nabla} \times \Omega_n(\mathbf{p})$$

- DoFs defined at edge centers
- DoF is the component of the transverse electric field parallel to edge
- Component is positive if directed the same direction there, negative otherwise

$$=\frac{\pm 2}{h_n^{\pm}}\,\hat{\mathbf{z}}-jk_z\hat{\mathbf{z}}\times\mathbf{\Omega}_n,\,\boldsymbol{\rho}\in T_n^{\pm}$$

as the reference (counterclockwise)
$$\nabla \times \left[\Omega_n(\mathbf{p})e^{-jk_zz}\right] = \left[\nabla \times \Omega_n(\mathbf{p})\right]e^{-jk_zz} - jk_z\hat{\mathbf{z}} \times \Omega_n e^{-jk_zz}$$
 direction there, negative otherwise

$$\nabla \times [\mathbf{A} \times \mathbf{B}] = \mathbf{A} \nabla \cdot \mathbf{B} - \mathbf{B} \nabla \cdot \mathbf{A} + (\mathbf{B} \cdot \nabla) \mathbf{A} - (\mathbf{A} \cdot \nabla) \mathbf{B}$$

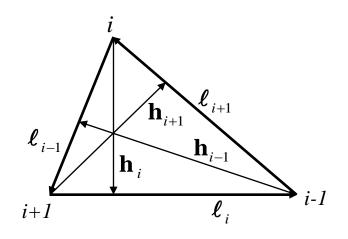
Local Representation of Transverse Bases

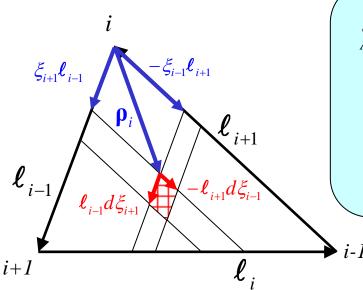
$$\Omega_{i}^{e}(\mathbf{p}) = \frac{\hat{\mathbf{z}} \times \mathbf{p}_{i}}{h_{i}} = \ell_{i} \frac{\hat{\mathbf{z}} \times (\boldsymbol{\xi}_{i+1} \boldsymbol{\ell}_{i-1} - \boldsymbol{\xi}_{i-1} \boldsymbol{\ell}_{i+1})}{2A^{e}}$$

$$= \ell_{i} \left(\frac{-\boldsymbol{\xi}_{i+1} \boldsymbol{\ell}_{i-1} \hat{\mathbf{h}}_{i-1}}{\boldsymbol{\ell}_{i-1} h_{i-1}} + \frac{\boldsymbol{\xi}_{i-1} \boldsymbol{\ell}_{i+1} \hat{\mathbf{h}}_{i+1}}{\boldsymbol{\ell}_{i+1} h_{i+1}} \right)$$

$$\Rightarrow \Omega_{i}^{e}(\mathbf{p}) = \ell_{i} (\boldsymbol{\xi}_{i+1} \nabla \boldsymbol{\xi}_{i-1} - \boldsymbol{\xi}_{i-1} \nabla \boldsymbol{\xi}_{i+1})$$

$$\tilde{\nabla} \times \Omega_{i}^{e}(\mathbf{p}) = \frac{2}{h_{i}} \hat{\mathbf{z}} - j k_{z} \hat{\mathbf{z}} \times \Omega_{i}^{e}$$





$$\int_{A^{e}} f(\mathbf{p}) dS$$

$$= \left| \ell_{i-1} \times \ell_{i+1} \right| \int_{0}^{1} \int_{0}^{1-\xi_{i-1}} f\left(\mathbf{p}_{1}^{e} \xi_{1} + \mathbf{p}_{2}^{e} \xi_{2} + \mathbf{p}_{3}^{e} \xi_{3}\right) d\xi_{i+1} d\xi_{i-1}$$

$$= 2A^{e} \int_{0}^{1} \int_{0}^{1-\xi_{i-1}} f\left(\mathbf{p}_{1}^{e} \xi_{1} + \mathbf{p}_{2}^{e} \xi_{2} + \mathbf{p}_{3}^{e} \xi_{3}\right) d\xi_{i+1} d\xi_{i-1}$$

$$\mathcal{J} \int_{0}^{1} \int_{0}^{1-\xi_{i-1}} f\left(\mathbf{p}_{1}^{e} \xi_{1} + \mathbf{p}_{2}^{e} \xi_{2} + \mathbf{p}_{3}^{e} \xi_{3}\right) d\xi_{i+1} d\xi_{i-1}$$

Summary of Vectorized Bases and Field Representation

Global representation,
$$\tilde{\mathbf{E}} \approx \sum_{n=1}^{N} V_n \, \Omega_n(\rho), \, \rho \in \mathcal{S}$$
,
$$\Omega_n(\rho) \equiv \begin{cases} \hat{\mathbf{z}} \times \Lambda_n(\rho) & \text{(edge-based DoFs)} \\ \hat{\mathbf{z}} \, \Lambda_n(\rho) & \text{(vertex-based DoFs)} \end{cases}$$

Local representation,
$$\tilde{\mathbf{E}} \approx \sum_{i=1}^{6} V_i^e \mathbf{\Omega}_i^e(\mathbf{p}), \ \mathbf{p} \in \mathcal{S}^e$$
:

$$\mathbf{\Omega}_1^e(\mathbf{\rho}) = \ell_1 \left(\xi_2 \nabla \xi_3 - \xi_3 \nabla \xi_2 \right)$$

$$\Omega_2^e(\mathbf{p}) = \ell_2\left(\xi_3\nabla\xi_1 - \xi_1\nabla\xi_3\right) \left\{ \text{edge-based DoFs: } \Omega_i^e(\mathbf{p}) = \ell_i\left(\xi_{i+1}\nabla\xi_{i-1} - \xi_{i-1}\nabla\xi_{i+1}\right) \right\}$$

$$\mathbf{\Omega}_{3}^{e}(\mathbf{\rho}) = \ell_{3} \left(\xi_{1} \nabla \xi_{2} - \xi_{2} \nabla \xi_{1} \right)$$

$$\mathbf{\Omega}_4^e(\mathbf{\rho}) = \hat{\mathbf{z}}\xi_1$$

$$\mathbf{\Omega}_5^e(\mathbf{\rho}) = \hat{\mathbf{z}} \xi_2$$

$$\mathbf{\Omega}_6^e(\mathbf{\rho}) = \hat{\mathbf{z}}\boldsymbol{\xi}_3$$

tex-based DoFs:
$$\Omega^{e}(\mathbf{o}) = \hat{\mathbf{z}}\mathcal{E}$$
.

$$\mathbf{\Omega}_i^e(\mathbf{p}) = \hat{\mathbf{z}}\xi_{i-3}$$

$$\Omega_{4}^{e}(\mathbf{p}) = \hat{\mathbf{z}}\xi_{1}$$

$$\Omega_{5}^{e}(\mathbf{p}) = \hat{\mathbf{z}}\xi_{2}$$
vertex - based DoFs:
$$\Omega_{i}^{e}(\mathbf{p}) = \hat{\mathbf{z}}\xi_{i-3}$$

$$\tilde{\nabla} \times \Omega_{i}^{e}(\mathbf{p}) = \frac{2}{h_{i}}\hat{\mathbf{z}} - jk_{z}\hat{\mathbf{z}} \times \Omega_{i}^{e}$$

$$\tilde{\nabla} \times \Omega_{i+3}^{e} = \nabla \xi_{i} \times \hat{\mathbf{z}}, \qquad i = 1, 2, 3$$

$$\tilde{\nabla} \times \mathbf{\Omega}_{i+3}^e = \nabla \xi_i \times \hat{\mathbf{z}}, \qquad i = 1, 2, 3$$

Element Matrix and Excitation Vector

Local admittance matrices and current column vectors

corresponding to
$$[Y_{mn}][V_n] = \frac{1}{j\omega} [\Gamma_{mn}][V_n] + j\omega [C_{mn}][V_n] = [I_m]$$
:

$$\left[Y_{ij}^{e}\right] = \frac{1}{i\omega} \left[\Gamma_{ij}^{e}\right] + j\omega \left[C_{ij}^{e}\right], \quad \text{(admittance element matrix)}$$

$$\begin{bmatrix} \Gamma_{ij}^e \end{bmatrix} = \frac{1}{\mu_0} \begin{bmatrix} \langle \tilde{\nabla}^* \times \Omega_i^e; \mu_r^{-1} \tilde{\nabla} \times \Omega_j^e \rangle \end{bmatrix}, \text{ (reciprocal inductance element matrix)}$$

$$\left[C_{ij}^{e}\right] = \varepsilon_{0}\left[\langle \Omega_{i}^{e}; \varepsilon_{r}\Omega_{j}^{e} \rangle\right], \text{ (capacitance element matrix)}$$

$$[I_i^e] = [-<\Omega_i^e; \tilde{\mathbf{J}}>]$$
 (excitation current element vector)

Add $\sigma_i^e \sigma_j^e Y_{ij}^e$ to system matrix

using matrix assembly rule!

Integration over Triangles Using Area Coordinates

$$\int_{A^{e}} f(\mathbf{p}) dS$$
= $2A^{e} \int_{0}^{1} \int_{0}^{1-\xi_{2}} f(\xi_{1} \mathbf{p}_{1}^{e} + \xi_{2} \mathbf{p}_{2}^{e} + \xi_{3} \mathbf{p}_{3}^{e}) d\xi_{1} d\xi_{2}$
 $\approx 2A^{e} \sum_{k=1}^{K} w_{k} f(\xi_{1}^{(k)} \mathbf{p}_{1}^{e} + \xi_{2}^{(k)} \mathbf{p}_{2}^{e} + \xi_{3}^{(k)} \mathbf{p}_{3}^{e})$

Numerical integration

Or evaluate analytically using

$$\int_0^1 \int_0^{1-\xi_2} \xi_1^{\alpha} \xi_2^{\beta} \xi_3^{\gamma} d\xi_1 d\xi_2$$

$$= \frac{\alpha! \beta! \gamma!}{(\alpha+\beta+\gamma+2)!}$$

Table 9 Sample points and weighting coefficients for K-point quadrature on triangles.

| Sample Points, $\left(\xi_1^{(k)}, \xi_2^{(k)}\right)$ | Weights, \boldsymbol{w}_k |
|--|-----------------------------|
| $(\xi_3^{(k)} = 1 - \xi_1^{(k)} - \xi_2^{(k)})$ | |
| K=1, error $\mathcal{O}(\xi_i^2)$: | |
| (0.33333333333333, 0.33333333333333) | 0.500000000000000 |
| K=3, error $\mathcal{O}(\xi_i^3)$: | |
| (0.66666666666667, 0.16666666666667) | 0.16666666666667 |
| (0.16666666666667, 0.6666666666667) | 0.16666666666667 |
| (0.16666666666667, 0.1666666666667) | 0.16666666666667 |
| K=7, error $\mathcal{O}(\xi_i^6)$: | |
| (0.33333333333333, 0.33333333333333) | 0.112500000000000 |
| (0.79742698535309, 0.10128650732346) | 0.06296959027241 |
| (0.10128650732346, 0.79742698535309) | 0.06296959027241 |
| (0.10128650732346, 0.10128650732346) | 0.06296959027241 |
| (0.47014206410512, 0.47014206410512) | 0.06619707639425 |
| (0.47014206410512, 0.05971587178977) | 0.06619707639425 |
| (0.05971587178977, 0.47014206410512) | 0.06619707639425 |

Source-Free Problems—Waveguide Cutoff Frequencies and Dispersion Data

• $\mathbf{J} = \mathbf{0} \Rightarrow \begin{bmatrix} I_m \end{bmatrix} = 0 \Rightarrow \begin{bmatrix} V_n \end{bmatrix} = 0$ except for eigenfrequencies: $\begin{bmatrix} \Gamma_{mn} \end{bmatrix} \begin{bmatrix} V_n^p \end{bmatrix} = \omega_p^2 \begin{bmatrix} C_{mn} \end{bmatrix} \begin{bmatrix} V_n^p \end{bmatrix}, \quad p = 1, 2, \dots, N$

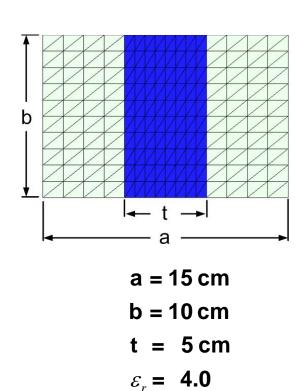
Generalized eigenvalue

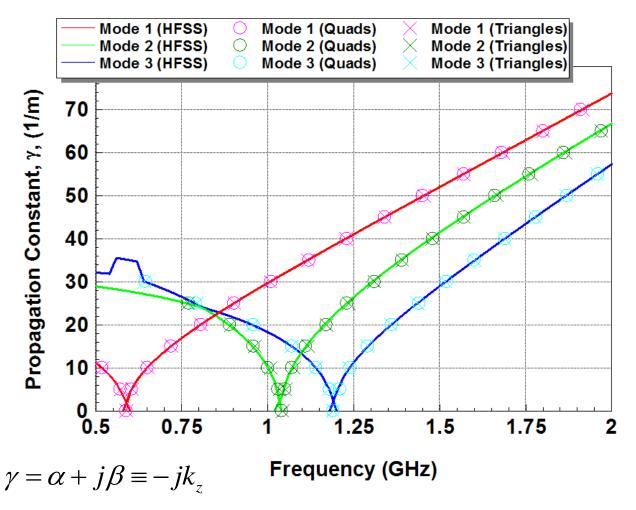
where

 $\begin{bmatrix} \Gamma_{mn} \end{bmatrix} = \frac{1}{\mu_0} \begin{bmatrix} <\tilde{\nabla}^* \times \mathbf{\Omega}_m; \mu_r^{-1} \tilde{\nabla} \times \mathbf{\Omega}_n > \end{bmatrix}$ problem of the form $[A] [\mathbf{x}^p] = \lambda_p [B] [\mathbf{x}^p]$ A quadratic function of k_z ! $\begin{bmatrix} C_{mn} \end{bmatrix} = \varepsilon_0 \begin{bmatrix} <\mathbf{\Omega}_m; \varepsilon_r \mathbf{\Omega}_n > \end{bmatrix}$

- Setting $k_z = 0$ yields cutoff frequencies
- For $k_z \neq 0$, obtain dispersion information in the form $\omega_p(k_z)$ for mode p
- Field distribution for mode p is $\mathbf{E}_p = \sum V_n^p \Omega_n e^{-jk_z z}$

Example: Slab-loaded Rectangular Waveguide





The End