Soft Computing Page No.	
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details with example (	
details  Diving logic is an approach to	0
don	
"degree of buth" another than tradition binon logic meth values range between 0 f	
2 In fuzzy logic meth values range between 0 & 1	
3) It is grespecially useful for dealing with uncertain	
9 Similar to have him	
9 Similar to how human make decision	
Consider the consept of temporali	
THE COUNTY COUNTY	
If temp > 30°C -> Hot (Tour)	
If temp < 30°C -> Not Hot (take)	
In fuzzy	
At 25°C > Hot = 0.3 (Para-141)	J. Section
177 30 C -> Hot = 0.6	
At 35°C -> Hot = 0.9	
Personnance Value of the State	
Control (116 tem (in a since reasoning , especially in	
gsign (the Gib Conditioners conshing machine)	and hours of
1) 1929 Operations - many hospital will have	201
are mathematical functions used to perform logic based	
8) appraisant are	
8) operations are  • fuzzu union (ap anneantin)	1
· fuzzy union (or representation) · fuzzy intersection (AND operation)	
· fuzzy complement (NOT operation	
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ed on	9 fuzzy upian (	
0 8 1 C 200	Symbol - AUB operation)	
ertain	(10) fuzzeu Int	
	formula - 116 as	
	$ex - \mu_{A(x)} = 0.6  \mu_{B(x)} = 0.6$ MANB(x) = $\frac{m_{A(x)}}{m_{A(x)}} = \frac{m_{A(x)}}{m_{A(x)}} = $	
	Symbol - AC (Not operation)	Inchese Park
	ex - MA(x) = 0.7	malilees parutas
alarant.	$MA^{c}(x) = 1 - 0.7 = 0.3$	& bright
<b>a</b> )	MAUB(a) = Al max(MA(a), MB(a))	Signon
based	one should former to the first to be able to the	Service -
	$MA^{c}(x) = 1 - MA(a)$	Earthurd
	MA (N)	datal or
	MACN	

that minice human trasoning method that relies as where experience high - deals with low-requires exacting and condition to uncertainty and condition.  Computation Approximate & hearistic Precise & deterministic - class method and condition for action from the properties of the pro				
Lempitum Approximate & hearistic Precise & deterministic - class method fuzzy logic, Neutral netrone, Algerithm, mathematical main component Genetic Algerithm binary logic (0 ft)  Problem & flexible con work with Rigid, requires well-tehned property incomplete or noise data inputs and model  Inspired human brain & neural classical mathematics & thean by intelligence from allogic rather system, Image processing control system with fixed rules fuzzy system, Image processing control system with fixed rules fuzzy party of the carried can be assigned to cannot handle error and control cannot learn; must be control for the carried control for the control for the carried contr	toleran	soft computing vs he firey computing vs he soft computing approach that mimics human reasoning handles uncertainty	conserset and computing  k mean  Hard computing  A traditional computing  ng method that relies on  binany logic	Jeggy Set fuzzy reas pfuzzy set where ele membersh
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Example Speech recognition, control Calculators, transaction process  System, Image processing Control system with fixed rules fuzz  error can tolerate & adapt to cannot handle error inf  easily before  cannot learn and evolve cannot learn; mut be  aptability over time (eg neural explicitly programmed © s.		incomplete or noise data	Rigid, requires well-defined inputs and model	9 fuzzy
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Date No.	
to expose a solution of the second se	3 fuzzy get Theory , Fuzzy logic -basic, fuzzy nules &
sizes esections	ofazzy set theory is an extension of classical set theory where elements can partially belong to a set with a membership value between 0 &1
teaminishis .	Demembership function (MA(x)): Represents the degree  to which an element x belongs to set A  - classical - MA(x) & {0,1}  - fazey - MA(x) & [0,1]
ell-defined	B example  Let set A = "Tall People"  Person with height \$60 cm: Leta (100) = 0.3  Person with height \$100 cm: Leta (100) = 0.3
ics s	(3) fuzzy logic is a reasoning
process	rather than fixed and exact.
rules	S core component -> fuzzification: converting crisp input values into fuzzy  Values using membership function  Inference engine -> Applies (
	Inference engine > Applies fuzzy neles to make decision.  Defuzzification > Converting fuzzy Dutput Into a misp  tup result
6	furry operation $\rightarrow$ Union=max(MA(x), MB(x)), Introceetion-min(MA(x), MB(A))  Complement = MA <sup>C</sup> (x) = 1-MA(x)
	Complement Min (N = 1 - MA(X)

IF Sturry Concline > Then Sturry actions  ex - If temperature is high then tan steed is tall  shew temperature is high and steed is tall  shew temperature is high and steed is tall  or lamables the defined using transfer  (9) furry measoning is the process of deriving the  conclusion from furry rule & turry input  (10) steek of turry reasoning  1. turry the inputs using membership tuntion  2. Apply turry miles to furrified output  3 Aggregate the result of each rule  4 peturrify the output to get coils value  ex - fan control system  Input - Temperature 30°C  turry set - Temperature -> lace, ligh, medium  tan speed -> slow, medium, face  Rule ->  If temp is low then tan speed slow  if II medium				
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