

# Chapter 4

- 4.1 Normal approximation (Laplace's method)
- 4.2 Large-sample theory
- 4.3 Counter examples
  - includes examples of difficult posteriors for MCMC, too
- 4.4 Frequency evaluation\*
- 4.5 Other statistical methods\*

# Normal approximation (Laplace approximation)

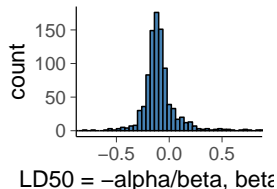
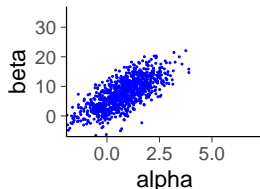
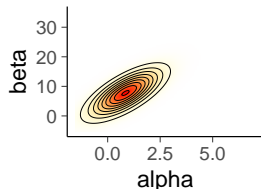
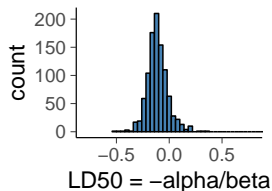
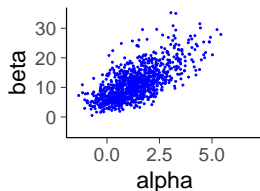
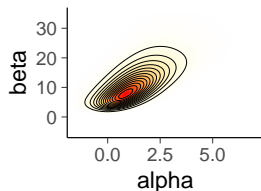
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  - Laplace used this (before Gauss) to approximate the posterior of binomial model to infer ratio of girls and boys born

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- We can approximate  $p(\theta|y)$  with normal distribution

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- if  $\hat{\theta}$  is at mode, then  $f'(\hat{\theta}) = 0$
- often when  $n \rightarrow \infty$ ,  $\frac{f^{(3)}(\hat{\theta})}{3!}(\theta - \hat{\theta})^3 + \dots$  is small



# Multivariate Taylor series

- Multivariate series expansion

$$f(\theta) = f(\hat{\theta}) + \frac{df(\theta')}{d\theta'} \Big|_{\theta'=\hat{\theta}} (\theta - \hat{\theta}) + \frac{1}{2!} (\theta - \hat{\theta})^T \frac{d^2f(\theta')}{d\theta'^2} \Big|_{\theta'=\hat{\theta}} (\theta - \hat{\theta}) + \dots$$

# Normal approximation

- Taylor series expansion of the log posterior around the posterior mode  $\hat{\theta}$

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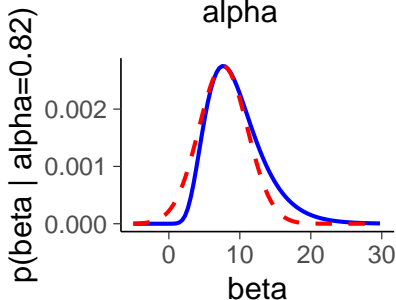
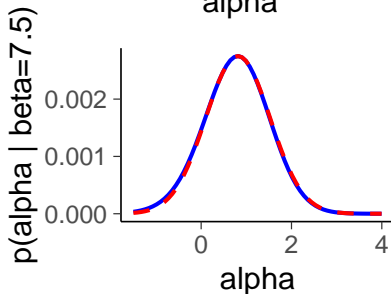
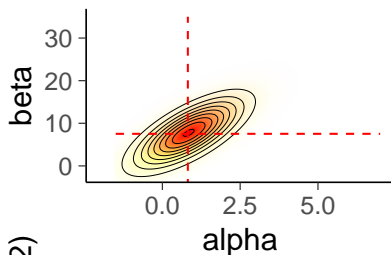
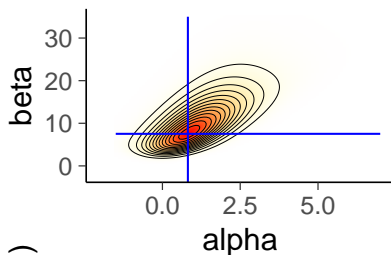
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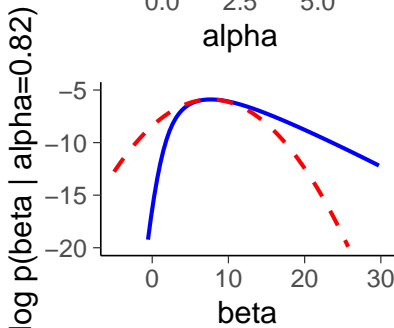
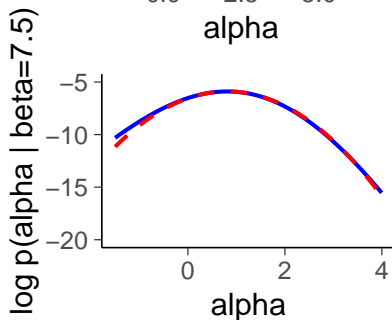
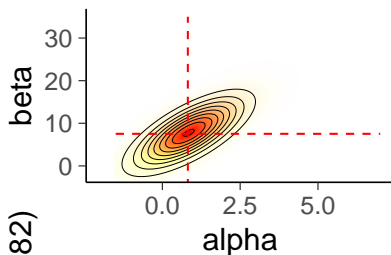
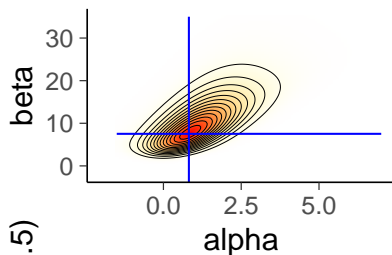
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$$\text{Hessian } H(\theta) = -I(\theta)$$

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- $I(\hat{\theta})$  is the second derivatives at the mode and thus describes the curvature at the mode
- if the mode is inside the parameter space,  $I(\hat{\theta})$  is positive
- if  $\theta$  is a vector, then  $I(\theta)$  is a matrix



## Normal approximation

- BDA3 Ch 4 has an example where it is easy to compute first and second derivatives and there is easy analytic solution to find where the first derivatives are zero

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  - e.g. in R, demo4\_1.R:

```
bioassayfun <- function(w, df) {  
  z <- w[1] + w[2]*df$x  
  -sum(df$y*(z) - df$n*log1p(exp(z)))  
}
```

```
theta0 <- c(0,0)  
optimres <- optim(w0, bioassayfun, gr=NULL, df1, hessian=T)  
thetahat <- optimres$par  
Sigma <- solve(optimres$hessian)
```

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    - second order autodiff in progress

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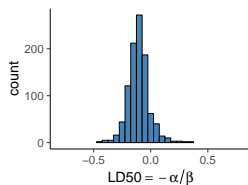
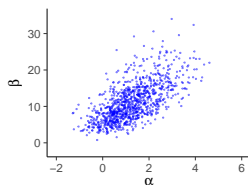
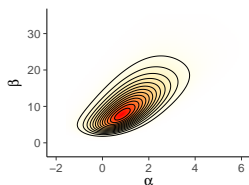
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- In some cases accuracy for a conditional distribution is sufficient (Ch 13)
  - e.g. Gaussian latent variable models, such as Gaussian processes (Ch 21) and Gaussian Markov random fields
  - Rasmussen & Williams: Gaussian Processes for Machine Learning
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- Accuracy can be improved by importance sampling (Ch 10)

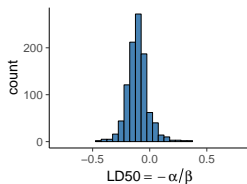
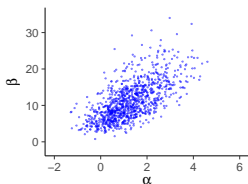
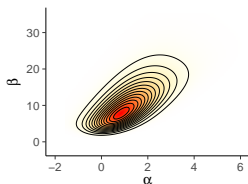
# Example: Importance sampling in Bioassay

Grid

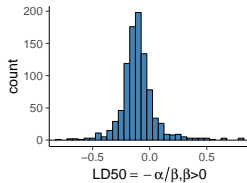
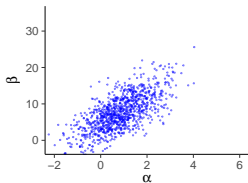
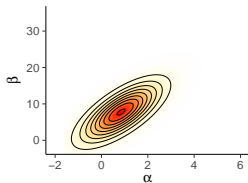


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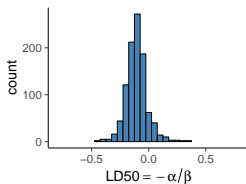
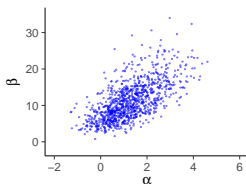
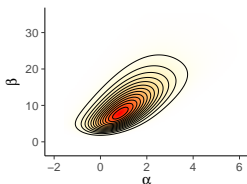


Normal

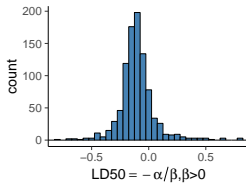
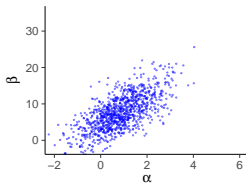
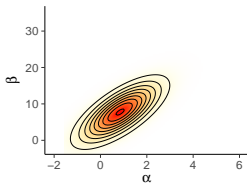


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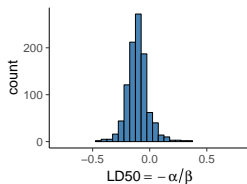
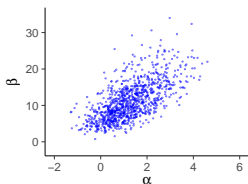
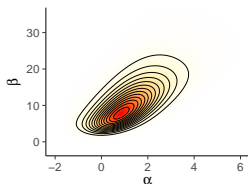
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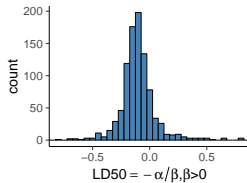
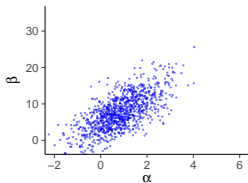
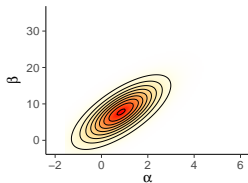
But the normal approximation is not that good here:  
Grid  $sd(LD50) \approx 0.1$ , Normal  $sd(LD50) \approx .75$ !

# Example: Importance sampling in Bioassay

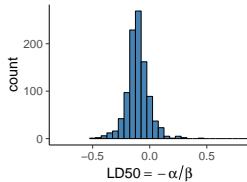
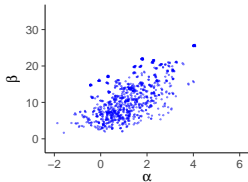
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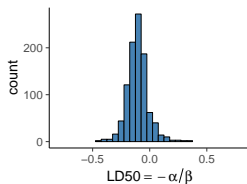
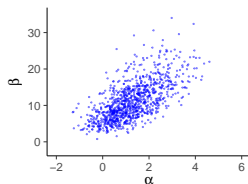
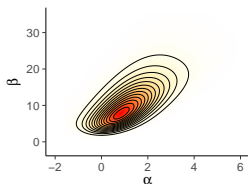


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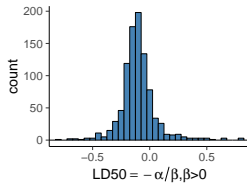
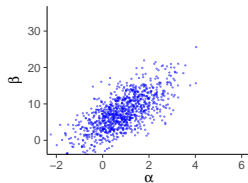
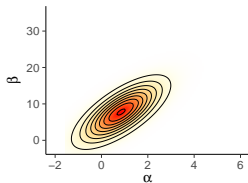


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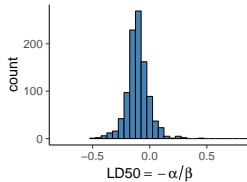
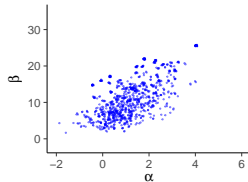
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IS



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- CmdStan(R) has Laplace algorithm
  - since version 2.33 (2023)
    - + Pareto- $k$  diagnostic via posterior package
    - + importance resampling (IR) via posterior package

# Normal approximation and parameter transformations

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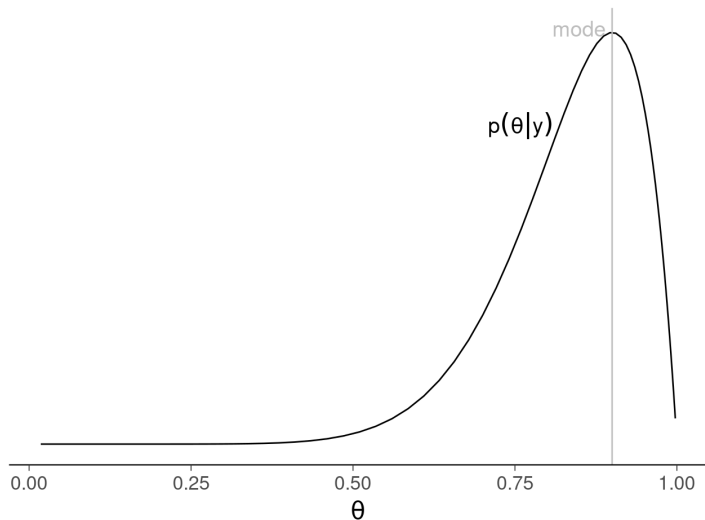
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  - for this, Stan does the inference in unconstrained space using logit transformation
  - density of the transformed parameter needs to include Jacobian of the transformation (BDA3 p. 21)

# Normal approximation and parameter transformations

Binomial model  $y \sim \text{Bin}(\theta, N)$ , with data  $y = 9, N = 10$

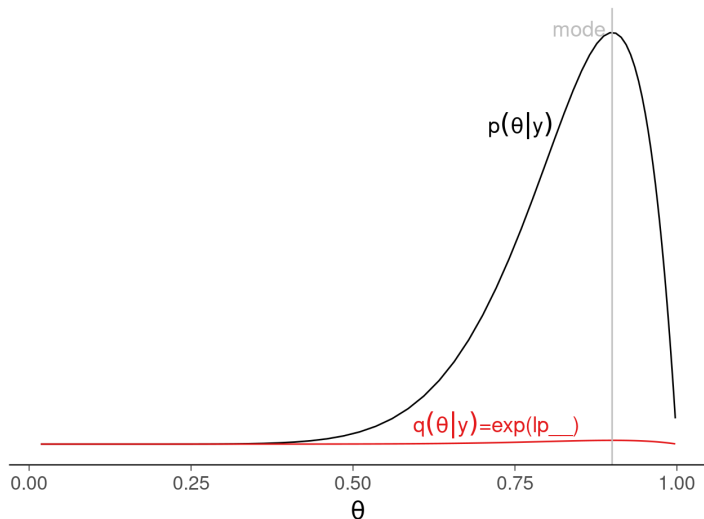
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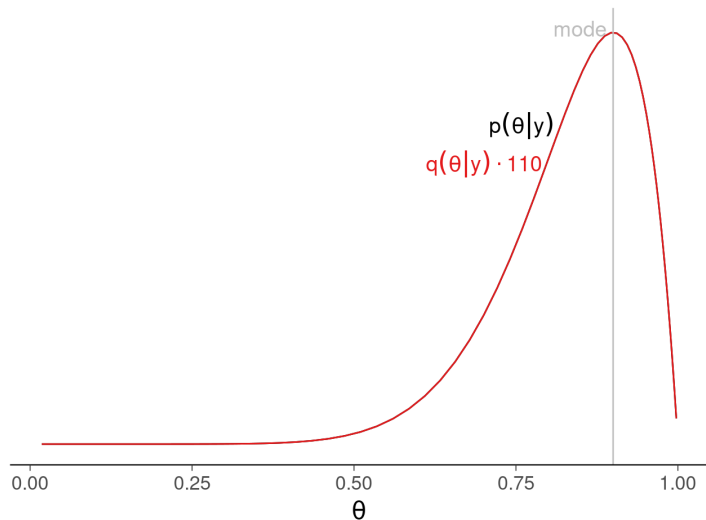
Stan computes only the unnormalized posterior  $q(\theta|y)$



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For illustration purposes we normalize Stan result  $q(\theta|y)$

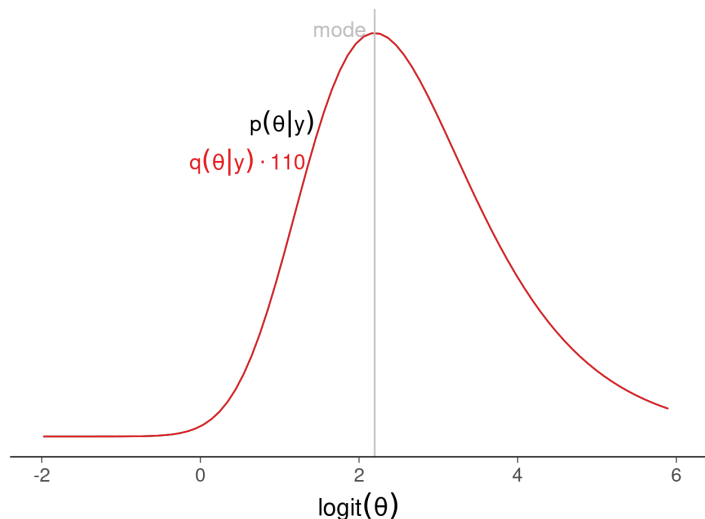




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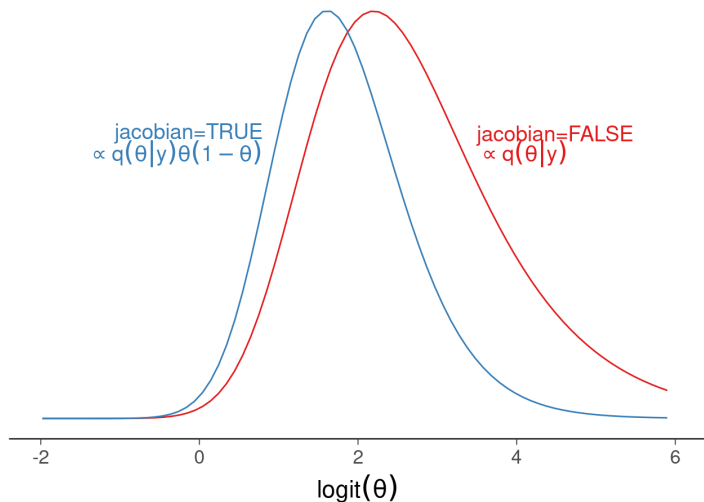
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$\text{Beta}(9 + 1, 1 + 1)$ , but x-axis shows the unconstrained  $\text{logit}(\theta)$



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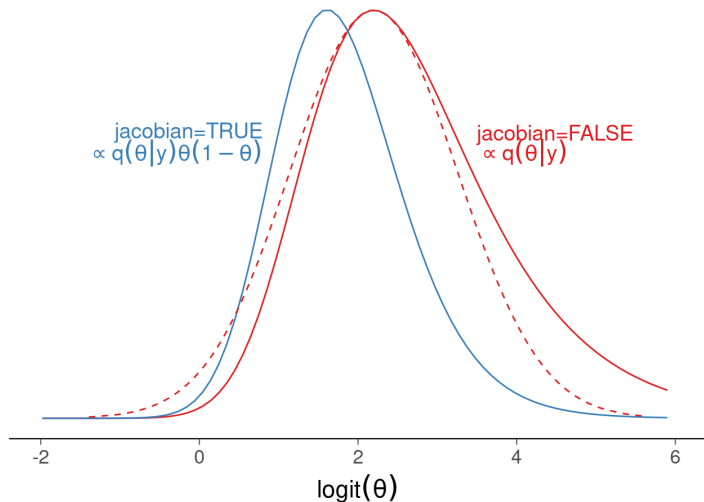
...but we need to take into account the absolute value of the determinant of the Jacobian of the transformation  $\theta(1 - \theta)$



# Normal approximation and parameter transformations

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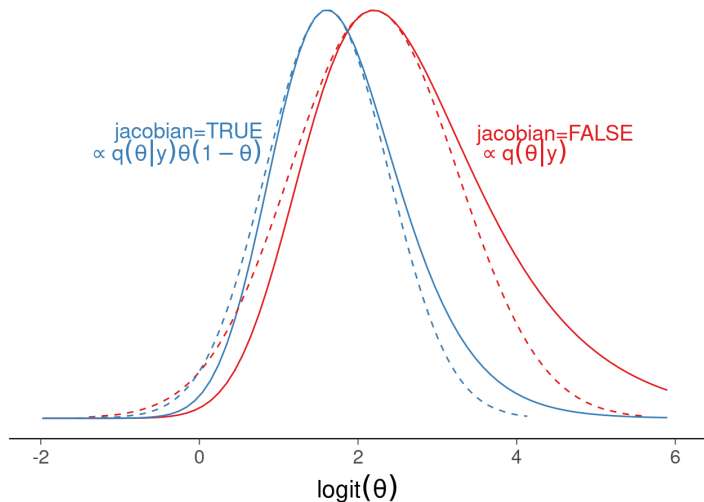
Let's compare a wrong normal approximation...



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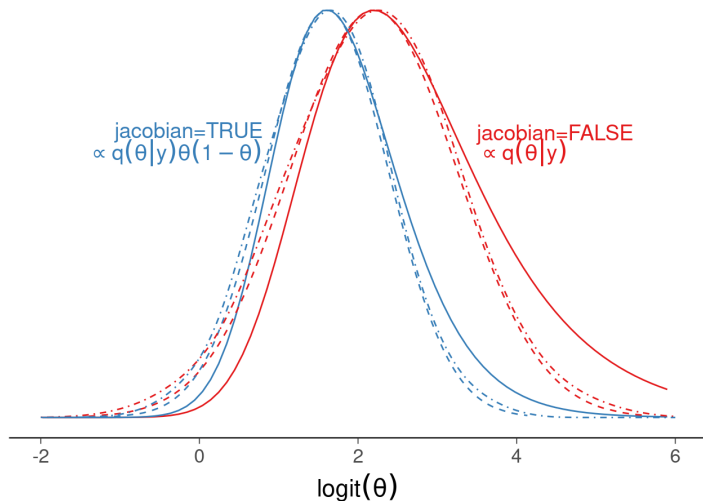
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# Normal approximation and parameter transformations

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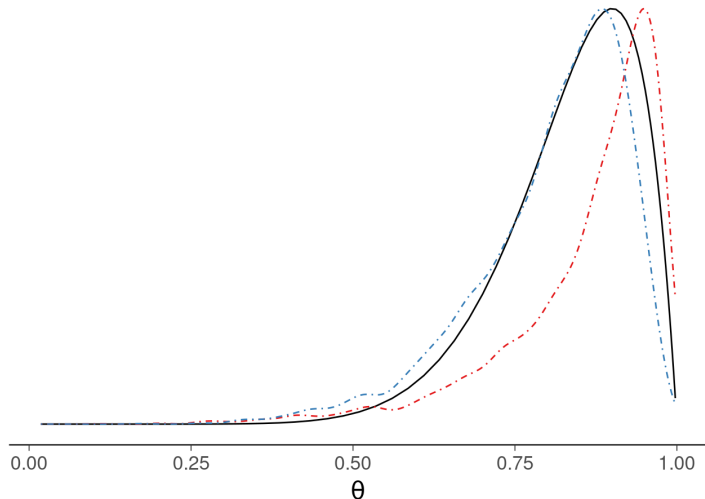
Sample from both approximations and show KDEs for draws



# Normal approximation and parameter transformations

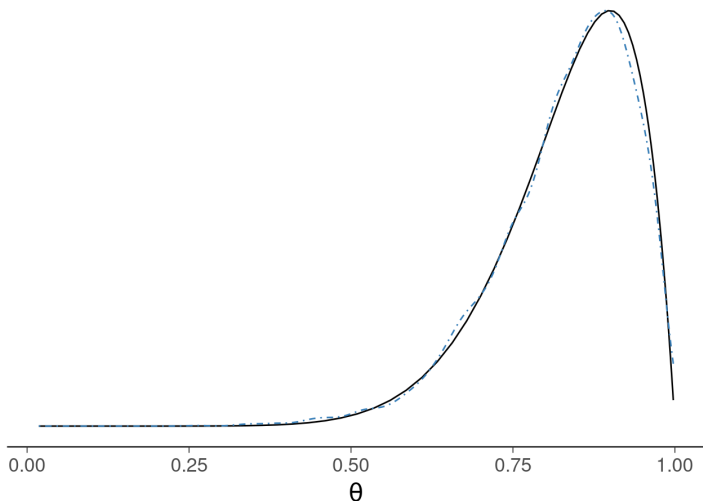
Let's compare a wrong normal approximation and correct one

Inverse transform draws and show KDEs



# Normal approximation and parameter transformations

Laplace approximation can be further improved with importance resampling



## Other distributional approximations

- Higher order derivatives at the mode can be used



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- Split-normal and split- $t$  by Geweke (1989) use additional scaling along different principal axes

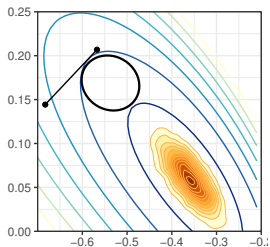
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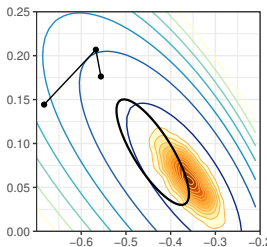
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- Instead of mode and Hessian at mode, e.g.
  - variational inference (Ch 13)
    - CS-E4820 - Machine Learning: Advanced Probabilistic Methods
    - CS-E4895 - Gaussian Processes
    - Stan has the ADVI algorithm (not very good implementation)
    - Stan has Pathfinder algorithm (CmdStanR github version)
    - instead of normal, methods with flexible flow transformations
  - expectation propagation (Ch 13)
  - speed of these is usually between optimization and MCMC
    - stochastic variational inference can be even slower than MCMC

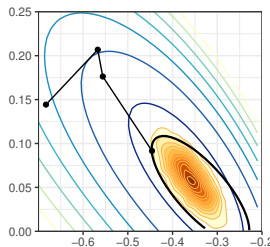
# Pathfinder: Parallel quasi-Newton variational inference.



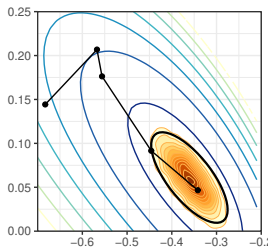
iteration 3  
estimated ELBO: -340.5



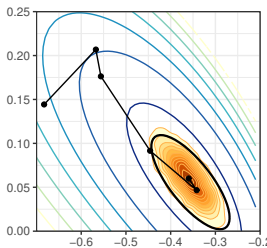
iteration 4  
estimated ELBO: -332.2



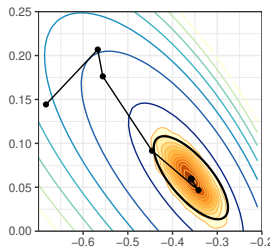
iteration 5  
estimated ELBO: -329.7



iteration 6  
estimated ELBO: -329.6



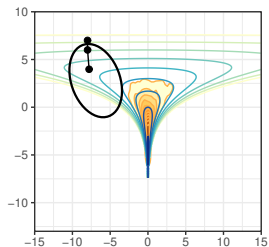
iteration 7  
estimated ELBO: -329.6



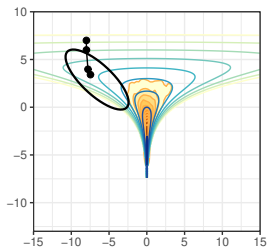
iteration 8  
estimated ELBO: -329.7

Zhang, Carpenter, Gelman, and Vehtari (2022). Pathfinder: Parallel quasi-Newton variational inference. *Journal of Machine Learning Research*, 23(306):1–49.

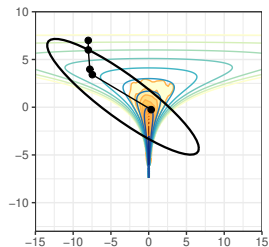
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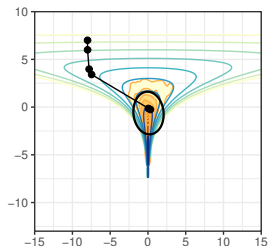
iteration 3  
estimated ELBO: -4.3



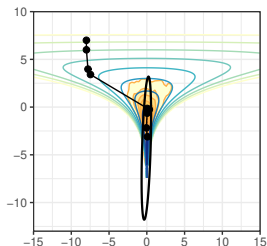
iteration 4  
estimated ELBO: -0.4



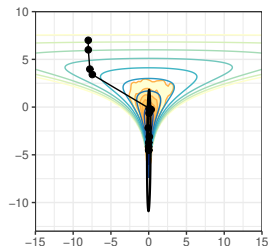
iteration 5  
estimated ELBO: -132.1



iteration 6  
estimated ELBO: 1.4



iteration 9  
estimated ELBO: -579.9

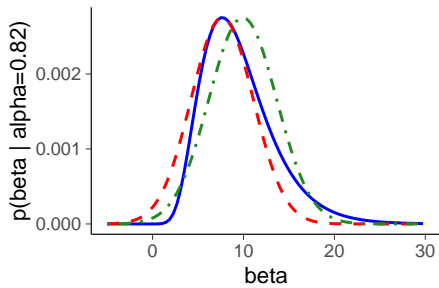
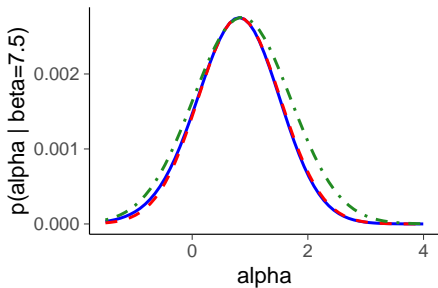
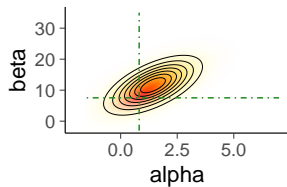
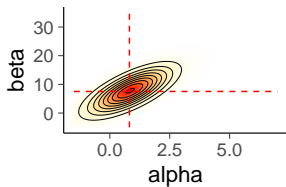
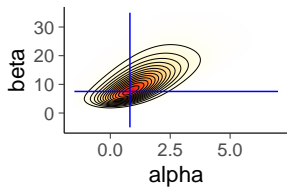


iteration 13  
estimated ELBO: -5.7

Zhang, Carpenter, Gelman, and Vehtari (2022). Pathfinder: Parallel quasi-Newton variational inference. *Journal of Machine Learning Research*, 23(306):1–49.

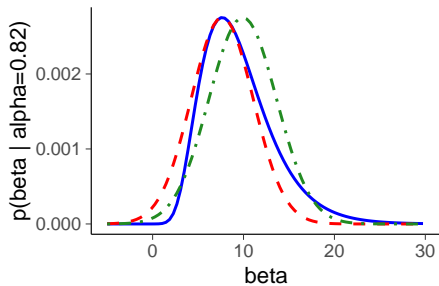
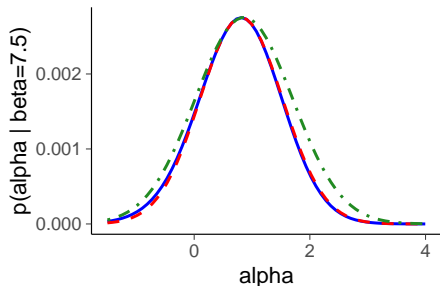
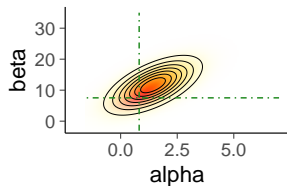
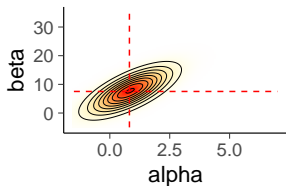
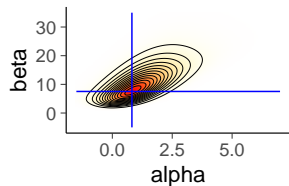
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Exact, Normal at mode, Normal with variational inference



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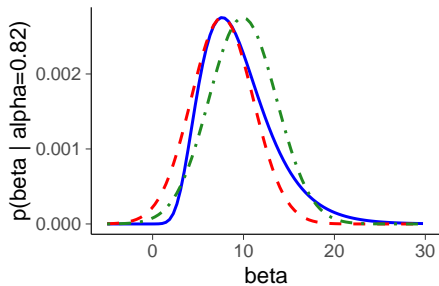
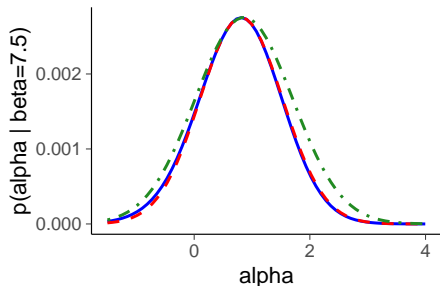
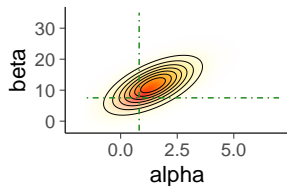
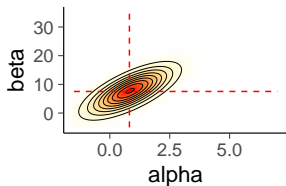
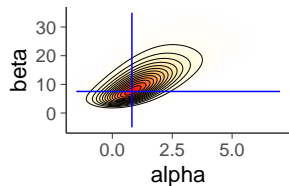


Grid  $\text{sd}(\text{LD50}) \approx 0.090$ ,

Normal  $\text{sd}(\text{LD50}) \approx .75$ , Normal + IR  $\text{sd}(\text{LD50}) \approx 0.096$  (Pareto- $k = 0.57$ )

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  - with increasing number of posterior dimensions, the stochastic divergence estimate gets worse and flows have problems, too (Dhaka, Catalina, Andersen, Welandawe, Huggins, and Vehtari, 2021)



# Large sample theory

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  - see counter examples

# Large sample theory

- Assume "true" underlying data distribution  $f(y)$ 
  - observations  $y_1, \dots, y_n$  are independent samples from the joint distribution  $f(y)$
  - "true" data distribution  $f(y)$  is not always well defined
  - in the following we proceed as if there were true underlying data distribution
  - for the theory the exact form of  $f(y)$  is not important as long as it has certain regularity conditions

# Large sample theory

- Consistency
  - if true distribution is included in the parametric family, so that  $f(y) = p(y|\theta_0)$  for some  $\theta_0$ , then posterior converges to a point  $\theta_0$ , when  $n \rightarrow \infty$

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# Large sample theory – counter examples

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$$\begin{pmatrix} u \\ v \end{pmatrix} \sim N \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$$

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- Problem also for other inference methods like MCMC

## Asymptotic identifiability vs finite data case

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- But a finite data from this data generating process may lack the joint height and weight observations, and thus the the finite data likelihood doesn't have information about  $\rho$
- If the likelihood is weakly informative for some parameters, priors and integration are more important

# Large sample theory – counter examples

- If the number of parameter increases as the number of observation increases
  - in some models number of parameters depends on the number of observations
  - e.g. time series models  $y_t \sim N(\theta_t, \sigma^2)$  and  $\theta_t$  has prior in time
  - posterior of  $\theta_t$  does not converge to a point, if additional observations do not bring enough information

# Large sample theory – counter examples

- Aliasing (**valetoisto** in Finnish)
  - special case of under-identifiability where likelihood repeats in separate points
  - e.g. mixture of normals

$$p(y_i | \mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \lambda) = \lambda N(\mu_1, \sigma_1^2) + (1 - \lambda) N(\mu_2, \sigma_2^2)$$

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- For MCMC makes the convergence diagnostics more difficult, as it is difficult to identify aliasing from other multimodality

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- Problem for any inference method including MCMC
  - can be avoided with good priors
  - a prior close to a prior allowing unbounded posterior may produce almost unbounded posterior

# Large sample theory – counter examples

- Improper posterior
  - asymptotic results assume that probability sums to 1
  - e.g. Binomial model, with Beta(0, 0) prior and observation  $y = n$ 
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  - a prior close to a improper prior may produce almost improper posterior

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- Should have a positive prior probability/density where needed



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  - e.g.  $y_i \sim N(\theta, 1)$  with a restriction  $\theta \geq 0$  and assume that  $\theta_0 = 0$ 
    - posterior of  $\theta$  is left truncated normal distribution with  $\mu = \bar{y}$
    - in the limit  $n \rightarrow \infty$  posterior is half normal distribution
- Can be easy or difficult for MCMC

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  - Calibration
    - $\alpha\%$ -posterior interval has the true value in  $\alpha\%$  cases
    - $\alpha\%$ -predictive interval has the true future values in  $\alpha\%$  cases
    - approximate calibration with shorter intervals for likely true values more important than exact calibration with very bad intervals for all possible values.

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  - unbiased estimate for strictly positive parameter can be negative
- Confidence interval is defined to have true value inside the interval in  $\alpha\%$  cases of repeated data generation from the data generating mechanism
  - doesn't need be useful to have perfect calibration

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- Bayesian inference
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- A lot of machine learning is not pure frequentist or Bayesian