

Popular NN Architectures

...and a little bit on the No Free Lunch theorems

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LAMBD A • HSE

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Side note: No Free Lunch



A question from an IQ test

- ▶ Given the following pattern of numbers:

1, 8, 27, ?, 125, 216

what is the missing number?

- a) 36
- b) 45
- c) 46
- d) 64
- e) 99

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- ▶ No free lunch theorem (roughly speaking): without prior knowledge all solutions are equally good (or bad)

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- ▶ Generalization performance:
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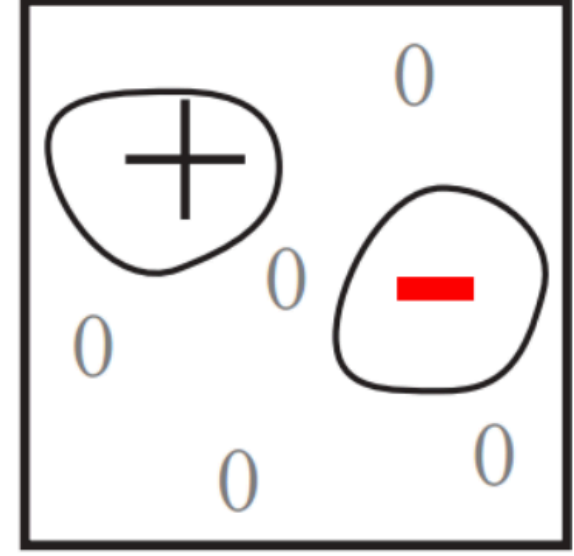
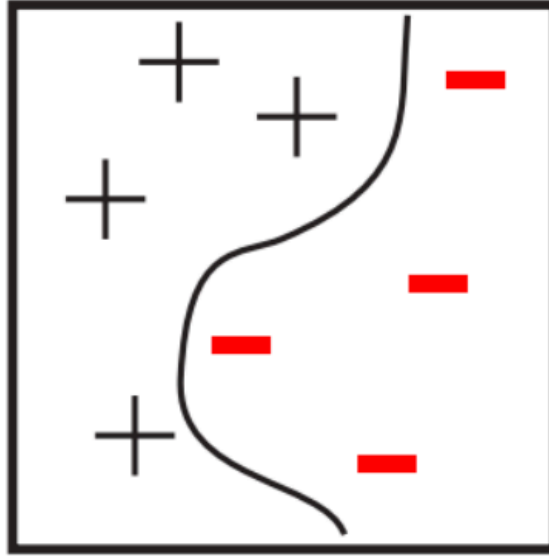
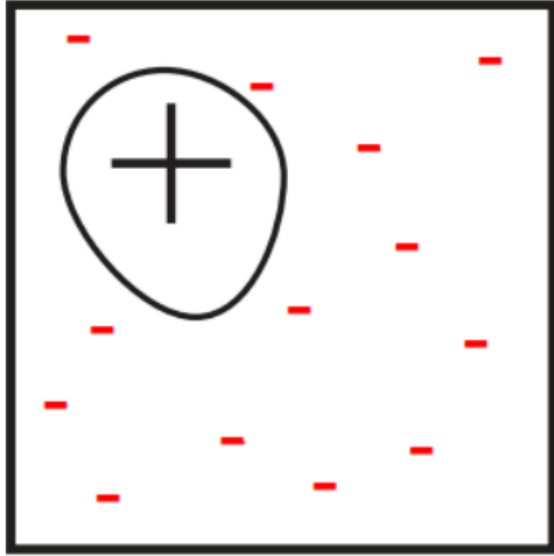
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$$\sum_{f, D_{\text{train}}} \text{gP}(\mathcal{A}, D_{\text{train}}) = 0$$

In the problem space



- Possible performance of learning algorithms:
 - Worse than average (-)
 - Better than average (+)

Back to the IQ test problem

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- ▶ To solve the test one must think like the authors of the test
- ▶ To solve a real world ML problem one must think like... the real world.

NFL theorem: critique

- ▶ Not all problems are equally likely (in the real world):
 - continuity;
 - human bias: e.g. feature preselection
 - prior knowledge of the problem at hand
- ▶ E.g. memorization + interpolation becomes an effective strategy for continuous data
- ▶ The following still holds though:

To improve the performance on one class of problems one must sacrifice the performance on others.

The role of data scientist

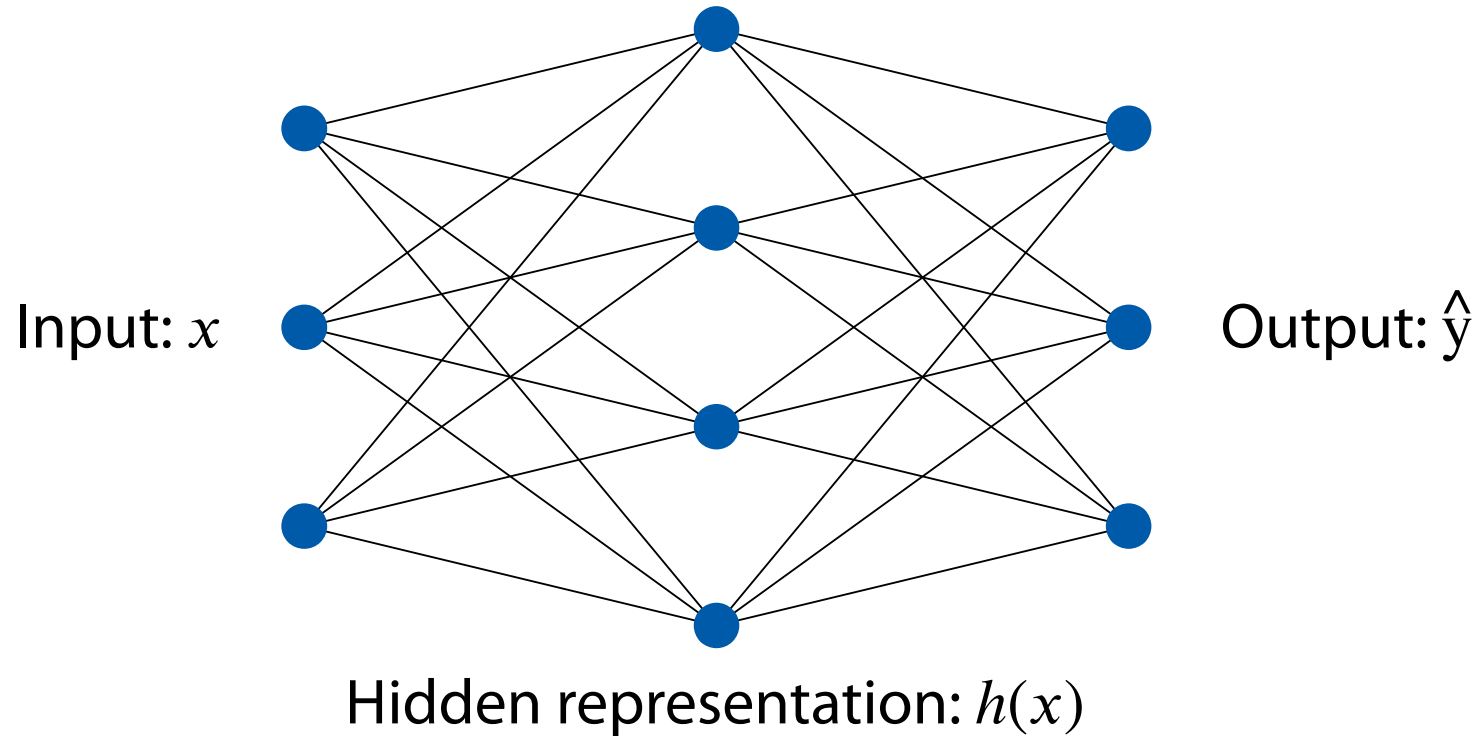
- ▶ Identify the suitable learning algorithm using the prior knowledge:
 - continuity;
 - structure of the data;
 - quality of the data;
 - domain knowledge;
 - size of the dataset;
 - common sense;
 - etc.
- ▶ In the context of deep learning: **find a suitable architecture**

NN architecture: simple examples



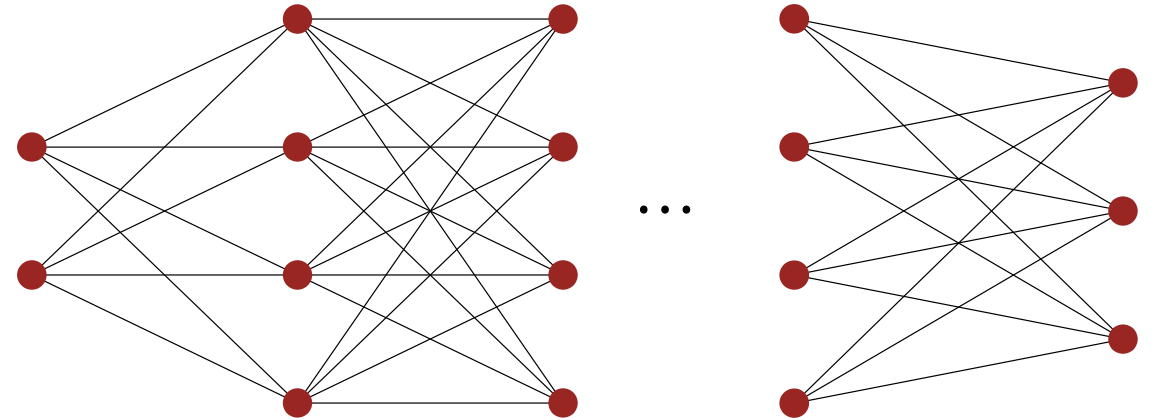
Single hidden layer fully-connected network

- ▶ Universal approximator
- ▶ May require infeasibly large hidden representation for more complex dependencies



Deep fully-connected network

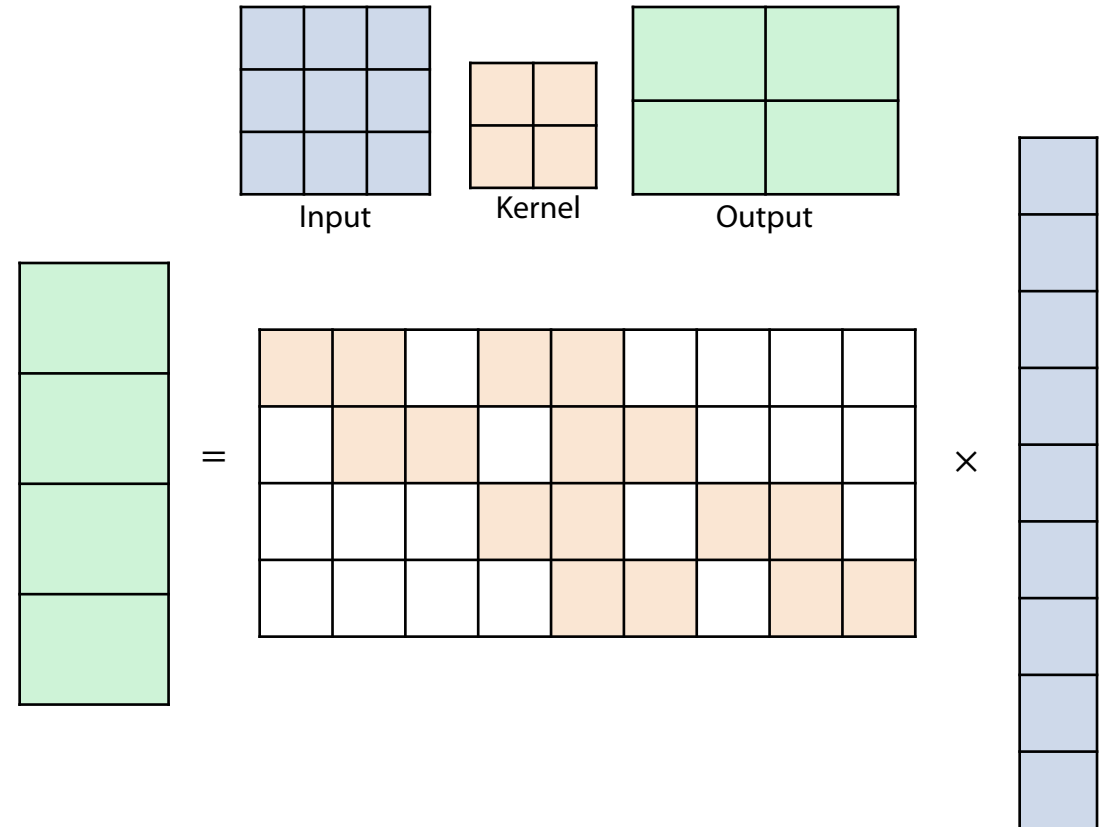
- ▶ May use smaller representations
- ▶ Suitable for many real-world problems
- ▶ Harder to optimize
 - Typically becomes quite challenging for 10+ layers
- ▶ An initial point for other architectures.



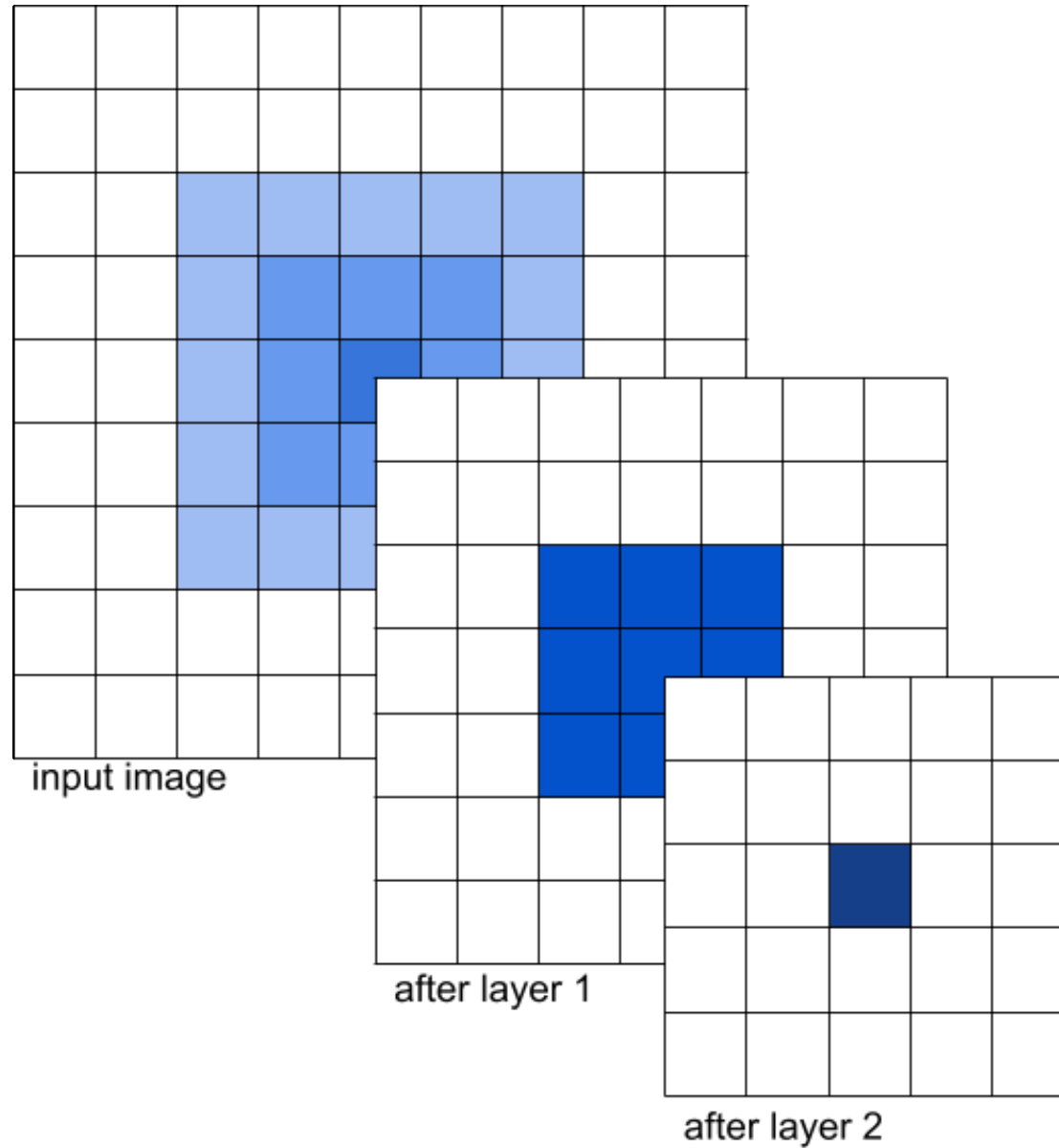
Convolution

- ▶ Spatial/temporal structure of the data
- ▶ Can be described in terms of a fully connected layer
- ▶ Uses much less parameters
 - Re-uses weights in a sliding window

2D convolution as a matrix multiplication

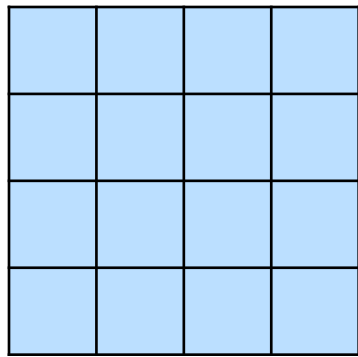


Receptive field

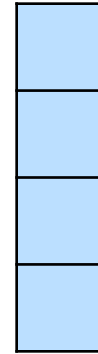


Combining simpler convolutions

- ▶ Replacing a $n \times n$ convolution with two subsequent convolutions with kernels $n \times 1$ and $1 \times n$:



$n \times n$ convolution



$n \times 1$ convolution

+



$1 \times n$ convolution

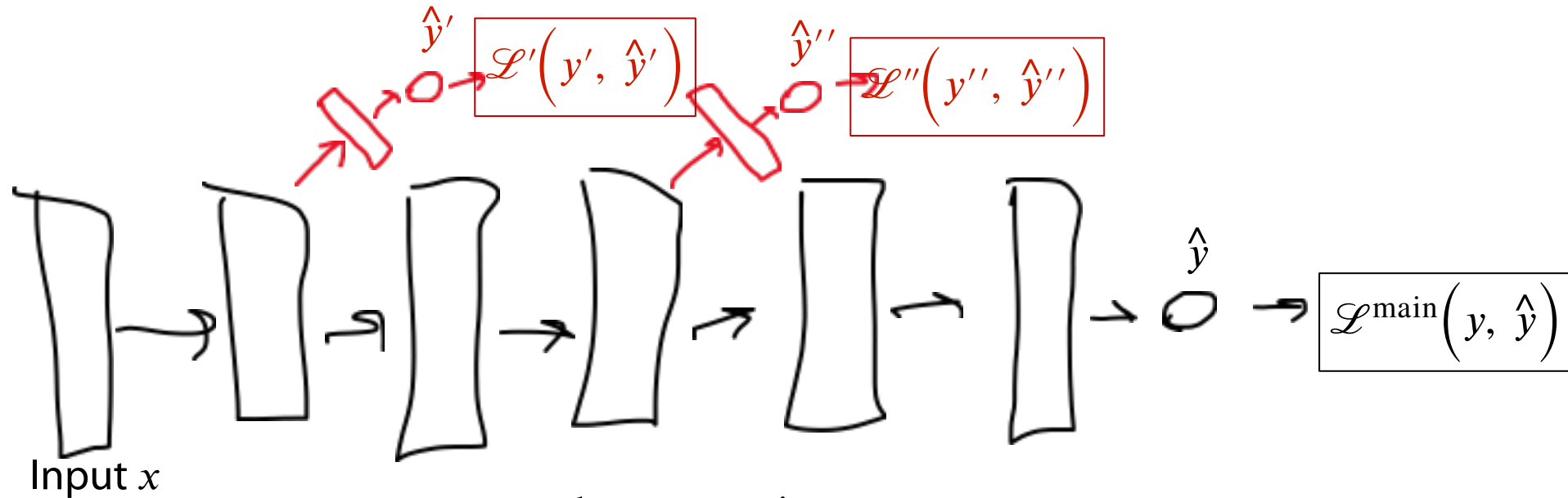
- ▶ Same receptive field, fewer parameters

Deeply supervised architectures



Main idea

- ▶ Hard to optimize deep network due to vanishing gradients
- ▶ Encourage good gradients by introducing additional “heads” from the intermediate layers



$$\mathcal{L}^{\text{total}} = \mathcal{L}^{\text{main}} + \alpha' \mathcal{L}' + \alpha'' \mathcal{L}''$$

- ▶ Typically, does not lead to good hidden representations
 - Makes sense to decay α' and α'' to 0 during training

Auxiliary tasks

- ▶ Introduce multiheaded models to solve similar tasks
 - E.g. when detecting images of people in glasses
 - add a head to predict the color of their hair
- ▶ The multiple heads may share common features and lead to a better result for the main task

Transfer learning and fine-tuning

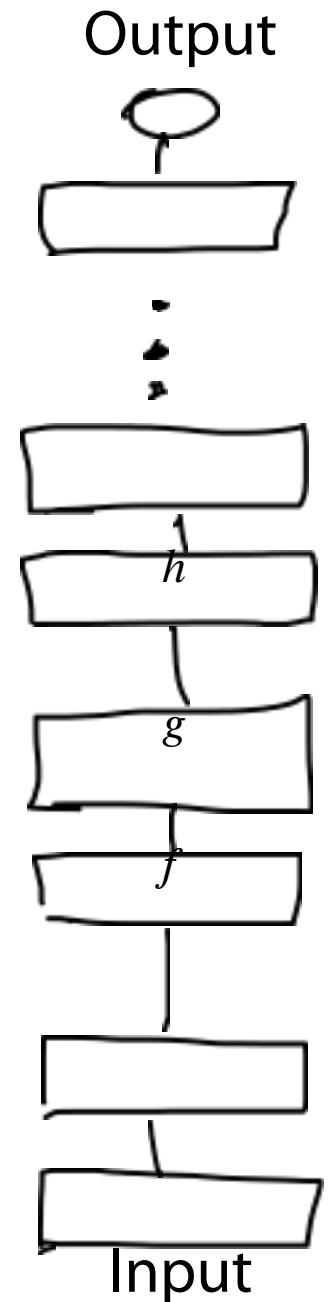
- ▶ Assume your problem provides a dataset too little to train a full-scale model from scratch
- ▶ Yet there exists a similar or a more general large dataset with a trained model that solves it well enough
- ▶ Transfer learning:
 - take first N layers of the trained model and freeze them
 - attach a new untrained head
 - train the whole thing (with only the head parameters being trainable)
- ▶ Fine-tuning:
 - After having trained the head, release the frozen weights and train the whole model further (with very small learning rate)

Residual connections



Residual connections

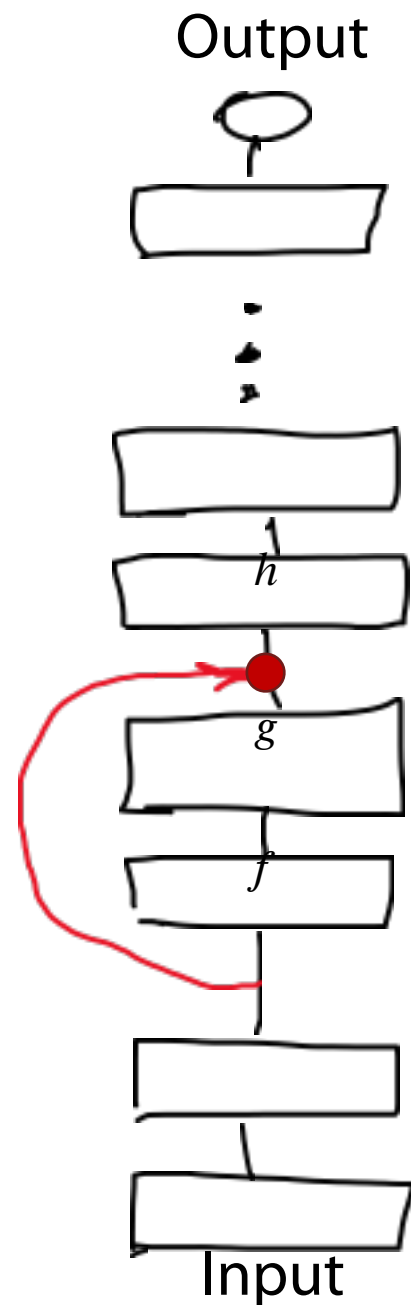
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- ▶ Solution: add residual connections (skip-connections)

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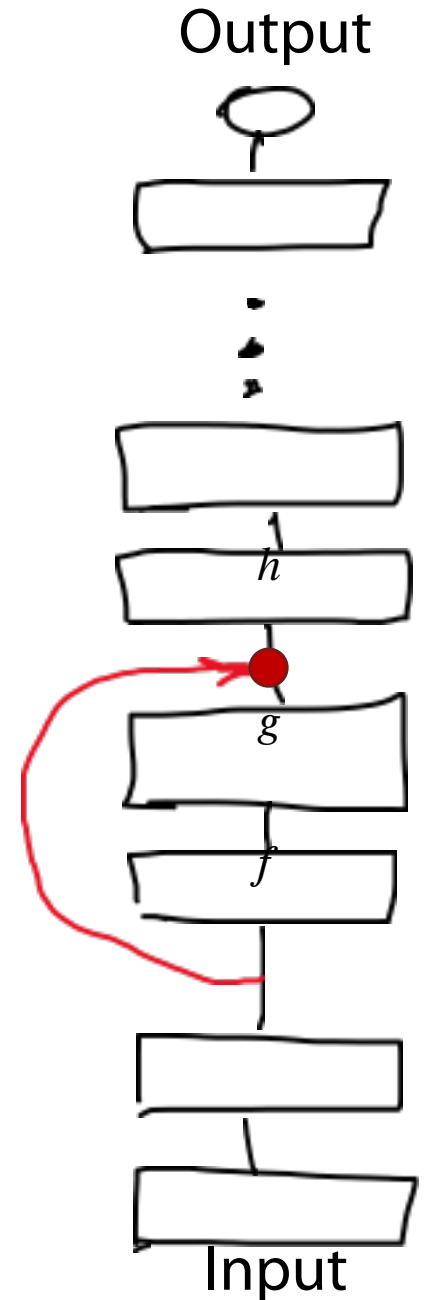


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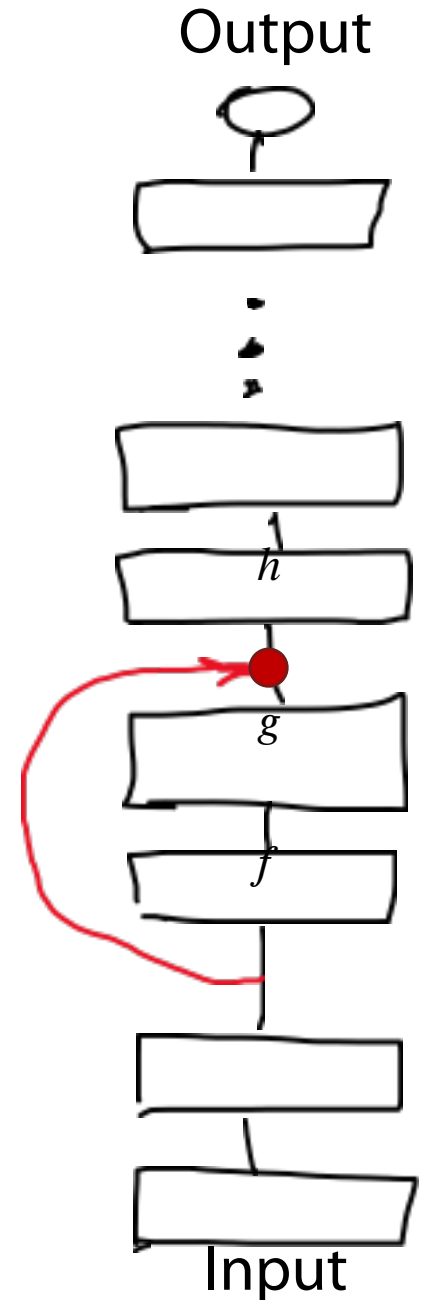


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- ▶ Note: is this always possible to do?

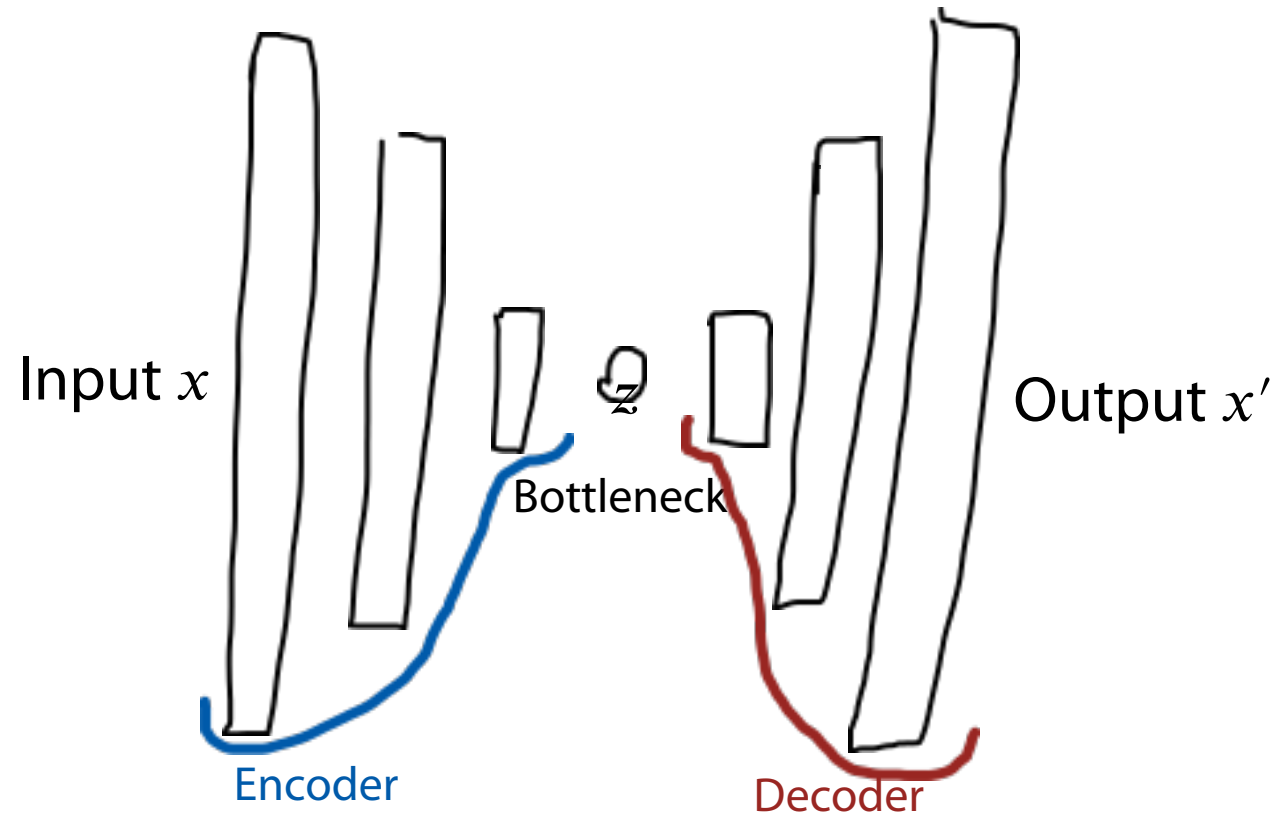


Autoencoders



Autoencoders

- ▶ A network that reconstructs its own input
- ▶ Has a 'bottleneck' representation
- ▶ Common use cases:
 - Dimensionality reduction
 - Anomaly detection
 - Denoising
 - Pretraining
 - Auxiliary loss, regularization





Semi-supervised learning with AE

- ▶ Note that training an AE doesn't require any targets!
- ▶ Imagine a situation having a small labelled dataset and large unlabelled
- ▶ Semi-supervised approach:
 - train an AE on the unlabelled dataset
 - then train a classification head on top of a hidden representation from the AE
 - may also train both models simultaneously

U-net

- Problems involving image to image transformation or image segmentation

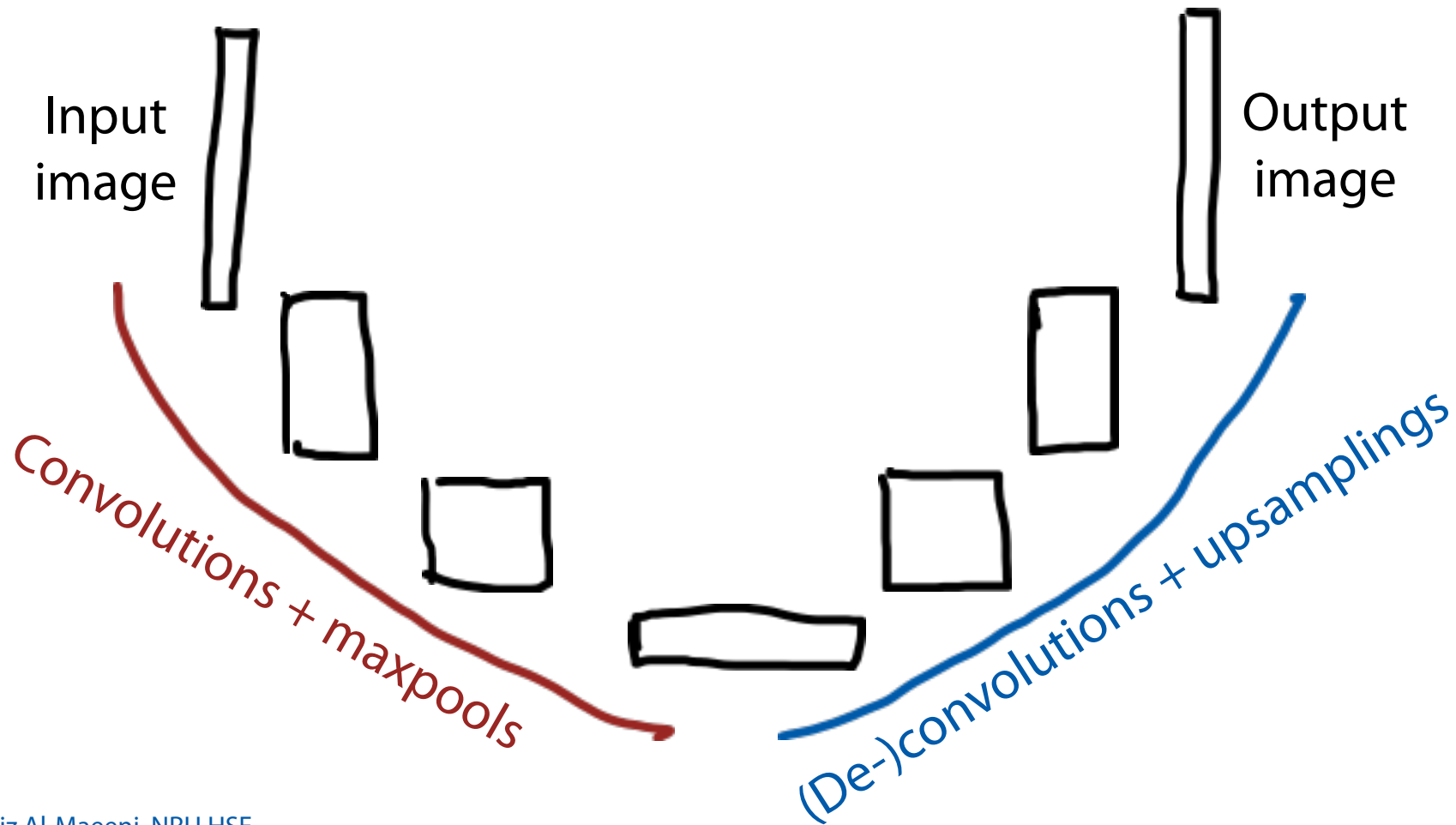
Input
image



Output
image

U-net

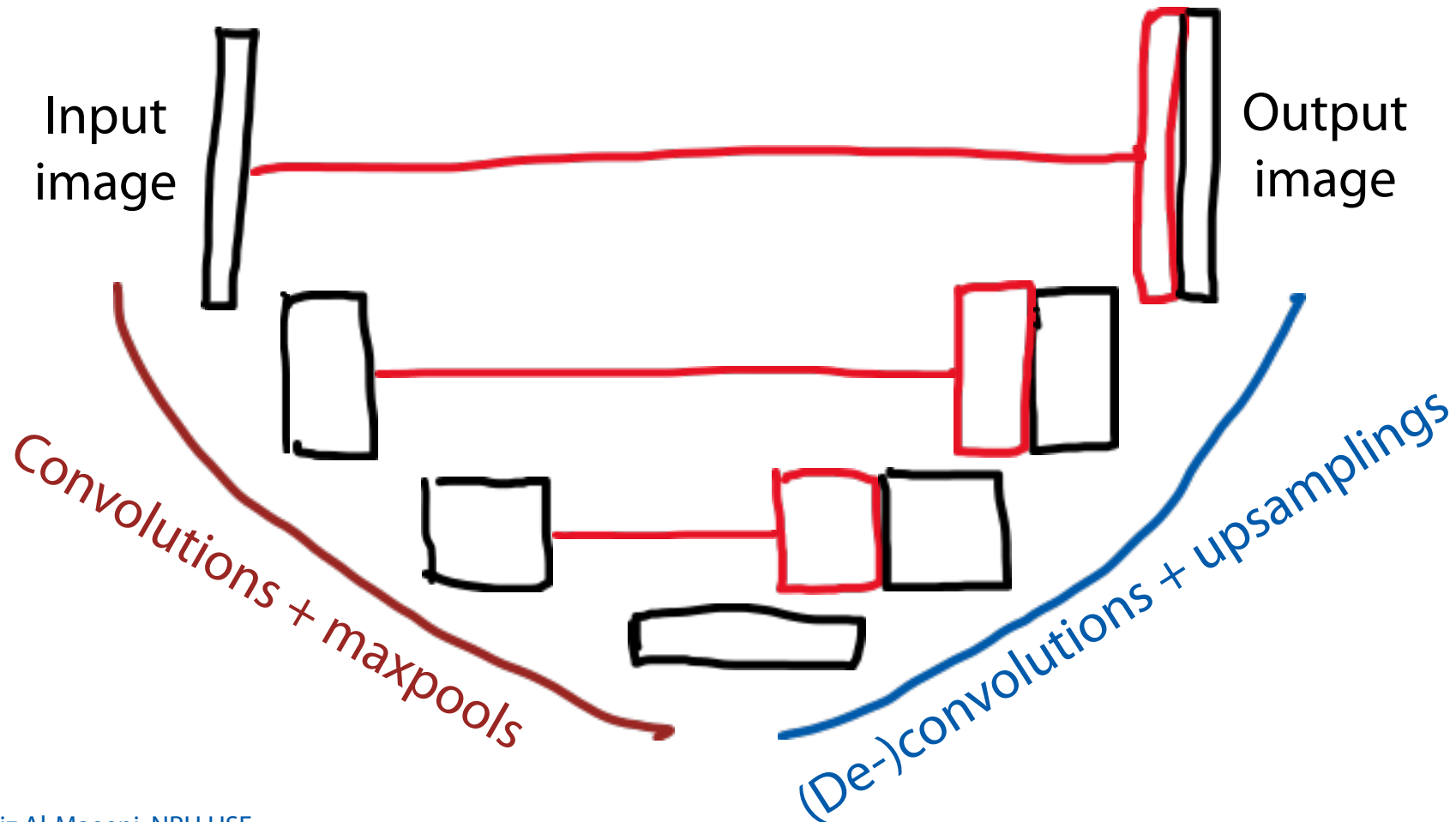
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Typical approach:
autoencoder-like
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Additional detail:
skip-connections
(typically
concatenated)

- this combines low- and high-level information in the “decoder” branch

Summary

- ▶ According to the no-free-lunch theorem, all learning algorithms are equally useless
- ▶ It's the goal of the data scientist to make them useful leveraging the prior knowledge about the problem
- ▶ In the context of deep learning this typically involves finding (inventing) a suitable architecture
- ▶ As you can see, neural networks are extremely flexible
 - Finding a good architecture may require some creativity
- ▶ The list of shown architectures is by no means comprehensive
 - Countless other architectures and tricks

Thank you!



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