

# Arduino snake game

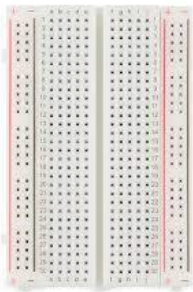
## *The idea of the project*

The idea is to make a snake game using LEDs.

## *MATERIALS*



Arduino



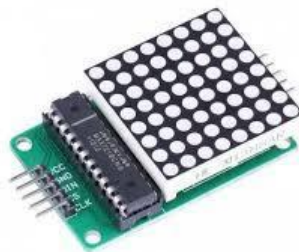
Bread board



wires



joystick

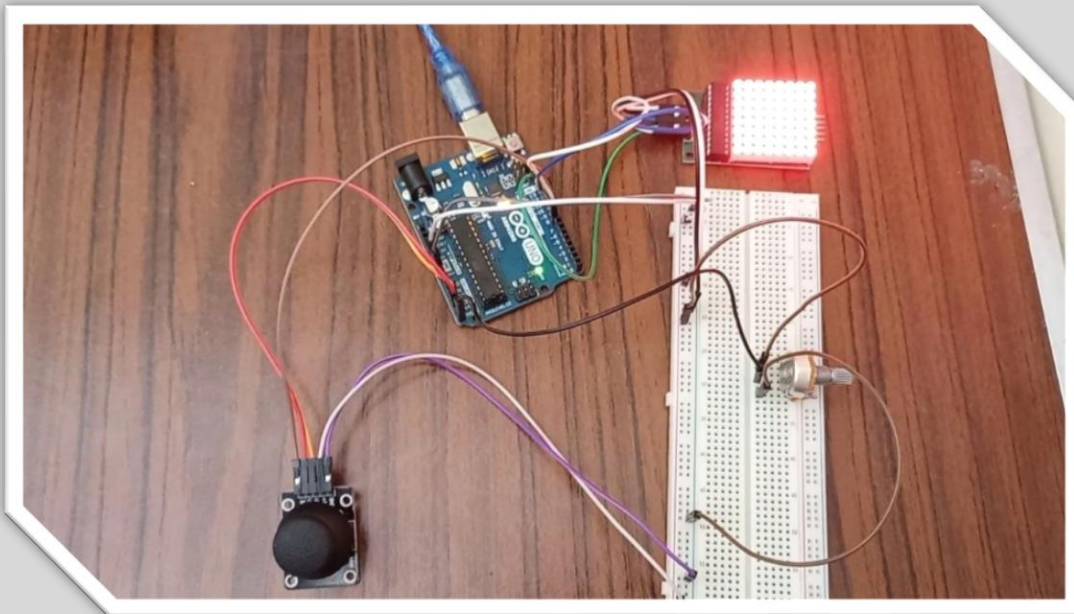


matrix

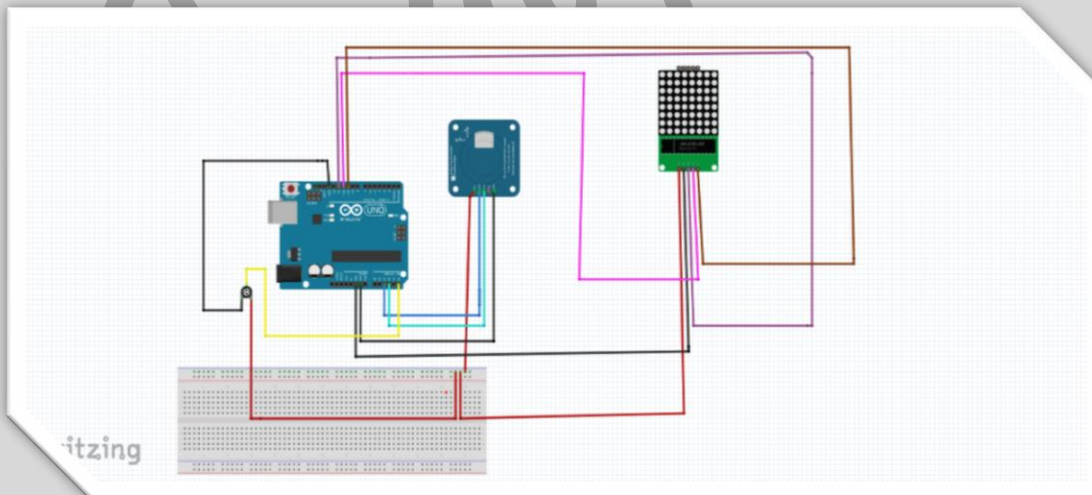


potentiometer

## OUR PROTOTYPE



Our prototype in Real life



simulation to Our prototype

## CODE

```
#include "LedControl.h"

struct Pin {

    static const short joystickX = A2;

    static const short joystickY = A3;

    static const short joystickVCC = 1;

    static const short joystickGND = 2;


    static const short potentiometer = A5;


    static const short CLK = 8;

    static const short CS = 9;

    static const short DIN = 10;

};

// LED matrix brightness: between 0(darkest) and 15(brightest)
const short intensity = 8;

const short messageSpeed = 5;

const short initialSnakeLength = 3;


void setup() {

    Serial.begin(115200);

    initialize();
```

```
calibrateJoystick();  
showSnakeMessage();  
}
```

```
void loop() {  
    generateFood();  
    scanJoystick();  
    calculateSnake();  
    handleGameStates();
```

```
    // uncomment this if you want the current game board to be printed to the serial (slows down the  
    game a bit)
```

```
    // dumpGameBoard();  
}
```

```
// ----- //  
// ----- supporting variables ----- //  
// ----- //
```

```
LedControl matrix(Pin::DIN, Pin::CLK, Pin::CS, 1);
```

```
struct Point {  
    int row = 0, col = 0;  
    Point(int row = 0, int col = 0): row(row), col(col) {}
```

```
};
```

```
struct Coordinate {  
    int x = 0, y = 0;  
    Coordinate(int x = 0, int y = 0): x(x), y(y) {}  
};
```

```
bool win = false;  
bool gameOver = false;
```

```
// primary snake head coordinates (snake head), it will be randomly generated  
Point snake;
```

```
// food is not anywhere yet  
Point food(-1, -1);
```

```
// construct with default values in case the user turns off the calibration  
Coordinate joystickHome(500, 500);
```

```
// snake parameters  
int snakeLength = initialSnakeLength;  
int snakeSpeed = 1;  
int snakeDirection = 0;
```

```
// direction constants  
const short up    = 1;  
const short right = 2;  
const short down  = 3;  
const short left  = 4;
```

```
const int joystickThreshold = 160;
```

```
const float logarithmity = 0.4;
```

```
int gameboard[8][5] = {};
```

```
// -----  
// ----- functions -----  
// -----
```

```
// if there is no food, generate one, also check for victory
```

```
void generateFood() {  
    if (food.row == -1 || food.col == -1) {  
        // self-explanatory  
        if (snakeLength >= 64) {  
            win = true;  
            return;  
        }  
    }  
}
```

```
do {  
    food.col = random(5);
```

```

    food.row = random(8);
  } while (gameboard[food.row][food.col] > 0);
}
}

void scanJoystick() {
  int previousDirection = snakeDirection;
  long timestamp = millis();

  while (millis() < timestamp + snakeSpeed) {
    float raw = mapf(analogRead(Pin::potentiometer), 0, 1023, 0, 1);
    snakeSpeed = mapf(pow(raw, 3.5), 0, 1, 10, 1000);
    if (snakeSpeed == 0) snakeSpeed = 1;

    analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold ? snakeDirection = up : 0;
    analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold ? snakeDirection = down : 0;
    analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold ? snakeDirection = left : 0;
    analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold ? snakeDirection = right : 0;

    snakeDirection + 2 == previousDirection && previousDirection != 0 ? snakeDirection =
previousDirection : 0;

    snakeDirection - 2 == previousDirection && previousDirection != 0 ? snakeDirection =
previousDirection : 0;

    matrix.setLed(0, food.row, food.col, millis() % 100 < 50 ? 1 : 0);
  }
}

void calculateSnake() {
  switch (snakeDirection) {
    case up:
      snake.row--;

```

```
fixEdge();

matrix.setLed(0, snake.row, snake.col, 1);

break;

case right:
    snake.col++;
    fixEdge();
    matrix.setLed(0, snake.row, snake.col, 1);
    break;

case down:
    snake.row++;
    fixEdge();
    matrix.setLed(0, snake.row, snake.col, 1);
    break;

case left:
    snake.col--;
    fixEdge();
    matrix.setLed(0, snake.row, snake.col, 1);
    break;

default:
    return;
}

if (gameboard[snake.row][snake.col] > 1 && snakeDirection != 0) {
    gameOver = true;
    return;
}
```



```

if (snake.row == food.row && snake.col == food.col) {

    food.row = -1;

    food.col = -1;

    snakeLength++;

    for (int row = 0; row < 8; row++) {

        for (int col = 0; col < 5; col++) {

            if (gameboard[row][col] > 0 ) {

                gameboard[row][col]++;

            }

        }

    }

    gameboard[snake.row][snake.col] = snakeLength + 1;

    for (int row = 0; row < 8; row++) {

        for (int col = 0; col < 5; col++) {

            if (gameboard[row][col] > 0 ) {

                gameboard[row][col]--;

            }

            matrix.setLed(0, row, col, gameboard[row][col] == 0 ? 0 : 1);

        }

    }

}

void fixEdge() {

    snake.col < 0 ? snake.col += 5 : 0;

    snake.col > 4 ? snake.col -= 5 : 0;

    snake.row < 0 ? snake.row += 8 : 0;

    snake.row > 7 ? snake.row -= 8 : 0;

}

void handleGameStates() {

```

```
if (gameOver || win) {  
    unrollSnake();  
    showScoreMessage(snakeLength - initialSnakeLength);  
    if (gameOver) showGameOverMessage();  
    else if (win) showWinMessage();  
    win = false;  
    gameOver = false;  
    snake.row = random(8);  
    snake.col = random(5);  
    food.row = -1;  
    food.col = -1;  
    snakeLength = initialSnakeLength;  
    snakeDirection = 0;  
    memset(gameboard, 0, sizeof(gameboard[0][0]) * 8 * 5);  
    matrix.clearDisplay(0);  
}  
}  
  
void unrollSnake() {  
    matrix.setLed(0, food.row, food.col, 0);  
    delay(800);  
    for (int i = 0; i < 5; i++) {  
        for (int row = 0; row < 8; row++) {  
            for (int col = 0; col < 5; col++) {  
                matrix.setLed(0, row, col, gameboard[row][col] == 0 ? 1 : 0);  
            }  
        }  
    }  
    delay(20);  
  
    for (int row = 0; row < 8; row++) {
```

```

    for (int col = 0; col < 5; col++) {
        matrix.setLed(0, row, col, gameboard[row][col] == 0 ? 0 : 1);
    }
}
delay(50);
}
delay(600);
for (int i = 1; i <= snakeLength; i++) {
    for (int row = 0; row < 8; row++) {
        for (int col = 0; col < 5; col++) {
            if (gameboard[row][col] == i) {
                matrix.setLed(0, row, col, 0);
                delay(100);
            }
        }
    }
}
}

```

// continue from here for norhan

// calibrate the joystick home for 10 times

```
void calibrateJoystick() {
```

```
    Coordinate values;
```

```
    for (int i = 0; i < 10; i++) {
```

```
        values.x += analogRead(Pin::joystickX);
```

```
        values.y += analogRead(Pin::joystickY);
```

```
    }
```

```
joystickHome.x = values.x / 10;  
joystickHome.y = values.y / 10;  
}
```

```
void initialize() {  
    pinMode(Pin::joystickVCC, OUTPUT);  
    digitalWrite(Pin::joystickVCC, HIGH);  
  
    pinMode(Pin::joystickGND, OUTPUT);  
    digitalWrite(Pin::joystickGND, LOW);
```

```
matrix.shutdown(0, false);  
matrix.setIntensity(0, intensity);  
matrix.clearDisplay(0);
```

```
randomSeed(analogRead(A2));  
snake.row = random(8);  
snake.col = random(5);  
}
```

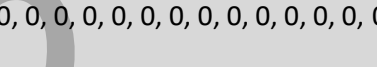
```
void dumpGameBoard() {  
    String buff = "\n\n\n";  
    for (int row = 0; row < 8; row++) {  
        for (int col = 0; col < 5; col++) {  
            if (gameboard[row][col] < 10) buff += " ";  
            if (gameboard[row][col] != 0) buff += gameboard[row][col];  
            else if (col == food.col && row == food.row) buff += "@";
```

```
//-----  
//----- messages ----- //  
//----- //  
  
GMEM bool snakeMessage[8][84] = {  
0,0,0, 0,1,1,0,0,0,0,1,1,0,1,1,1,1,0,0,0,0,0,0,0,0,0, 0,  
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,  
0,0,0, 0,1,1,1,0,0,1,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0, 1,  
0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1, 1, 0, 0, 0, 0, 0, 0,  
0,0,0, 0,1,1,0,1,1,0,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0, 1,  
1, 0, 0, 1, 1, 0, 1, 1, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0,  
0,0,0, 0,1,1,0,1,1,0,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0, 1,  
1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0,
```

```
GMEM bool snakeMessage[8][84] = {
0,0,0, 0,1,1,0,0,0,0,1,1,0,1,1,1,1,1,0,0,0,0,0,0,0,0,0, 0,
0,0,0, 0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,
0,0,0, 0,1,1,1,0,0,1,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0,0, 1,
0,0,0, 0,1,1,0,0,1,1,0,0,1,1,1,1,1,1,1,0,0,0,0,0,0,0,0,
0,0,0, 0,1,1,0,1,1,0,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0,1, 1,
1,0,0, 1,1,0,1,1,0,0,0,1,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,
0,0,0, 0,1,1,0,1,1,0,1,1,0,1,1,0,0,0,1,0,0,0,0,0,0,0,1, 1,
1,0,0, 1,1,1,1,0,0,0,0,1,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,
```

};

{0,  
0,  
0, 0, 0, 0},



$\{0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 1, 0, 1, 1, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0,$   
 $0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0,$   
 $0, 0, 0, 0\},$

{0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1, 0, 0, 1, 1, 0, 1, 0, 1, 1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0},

$\{0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0,$   
 $0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,$   
 $0, 0, 0, 0\},$

$$\};$$
[illegible]

```

    {0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1,
    1, 1, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1,
    0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1,
    0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1,
    1, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1,
    0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0, 1, 1, 0, 0, 0, 1, 1,
    0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0},

    {0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1, 0, 0, 1, 1,
    1, 1, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0},

};

```

```

const PROGMEM bool digits[][8][8] = {

```

```

{
    {0, 0, 0, 0, 0, 0, 0, 0},
    {0, 0, 1, 1, 1, 1, 0, 0},
    {0, 1, 1, 0, 0, 1, 1, 0},
    {0, 1, 1, 0, 1, 1, 1, 0},
    {0, 1, 1, 1, 0, 1, 1, 0},
    {0, 1, 1, 0, 0, 1, 1, 0},
    {0, 1, 1, 0, 0, 1, 1, 0},
    {0, 0, 1, 1, 1, 1, 0, 0}
},

```

```

{
    {0, 0, 0, 0, 0, 0, 0, 0},
    {0, 0, 0, 1, 1, 0, 0, 0},
    {0, 0, 0, 1, 1, 0, 0, 0},

```

{0, 0, 1, 1, 1, 0, 0, 0},  
{0, 0, 0, 1, 1, 0, 0, 0},  
{0, 0, 0, 1, 1, 0, 0, 0},  
{0, 0, 0, 1, 1, 0, 0, 0},  
{0, 1, 1, 1, 1, 1, 1, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},  
{0, 0, 1, 1, 1, 1, 0, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 0, 0, 0, 0, 1, 1, 0},  
{0, 0, 0, 0, 1, 1, 0, 0},  
{0, 0, 1, 1, 0, 0, 0, 0},  
{0, 1, 1, 0, 0, 0, 0, 0},  
{0, 1, 1, 1, 1, 1, 1, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},  
{0, 0, 1, 1, 1, 1, 0, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 0, 0, 0, 0, 1, 1, 0},  
{0, 0, 0, 1, 1, 1, 0, 0},  
{0, 0, 0, 0, 0, 1, 1, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 0, 1, 1, 1, 1, 0, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},  
{0, 0, 0, 0, 1, 1, 0, 0},



{0, 0, 0, 1, 1, 1, 0, 0},  
{0, 0, 1, 0, 1, 1, 0, 0},  
{0, 1, 0, 0, 1, 1, 0, 0},  
{0, 1, 1, 1, 1, 1, 1, 0},  
{0, 0, 0, 0, 1, 1, 0, 0},  
{0, 0, 0, 0, 1, 1, 0, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},  
{0, 1, 1, 1, 1, 1, 1, 0},  
{0, 1, 1, 0, 0, 0, 0, 0},  
{0, 1, 1, 1, 1, 1, 0, 0},  
{0, 0, 0, 0, 0, 1, 1, 0},  
{0, 0, 0, 0, 0, 1, 1, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 0, 1, 1, 1, 1, 0, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},  
{0, 0, 1, 1, 1, 1, 0, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 1, 1, 0, 0, 0, 0, 0},  
{0, 1, 1, 1, 1, 1, 0, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 1, 1, 0, 0, 1, 1, 0},  
{0, 0, 1, 1, 1, 1, 0, 0}

},

{

{0, 0, 0, 0, 0, 0, 0, 0},

```
{0, 1, 1, 1, 1, 1, 1, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 0, 0, 0, 1, 1, 0, 0},
{0, 0, 0, 0, 1, 1, 0, 0},
{0, 0, 0, 1, 1, 0, 0, 0},
{0, 0, 0, 1, 1, 0, 0, 0},
{0, 0, 0, 1, 1, 0, 0, 0}
},
{
{0, 0, 0, 0, 0, 0, 0, 0},
{0, 0, 1, 1, 1, 1, 0, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 0, 1, 1, 1, 1, 0, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 0, 1, 1, 1, 1, 0, 0}
},
{
{0, 0, 0, 0, 0, 0, 0, 0},
{0, 0, 1, 1, 1, 1, 0, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 0, 1, 1, 1, 1, 0, 0},
{0, 0, 0, 0, 0, 1, 1, 0},
{0, 1, 1, 0, 0, 1, 1, 0},
{0, 0, 1, 1, 1, 1, 0, 0}
}
};
```

```

// scrolls the 'snake' message around the matrix
void showSnakeMessage() {
    [&] {
        for (int d = 0; d < sizeof(snakeMessage[0]) - 4; d++) {
            for (int col = 0; col < 5; col++) {
                delay(messageSpeed);
                for (int row = 0; row < 8; row++) {
                    // this reads the byte from the PROGMEM and displays it on the screen
                    matrix.setLed(0, row, col, pgm_read_byte(&(snakeMessage[row][col + d])));
                }
            }

            // if the joystick is moved, exit the message
            if (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
                || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold
                || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
                || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {
                return; // return the lambda function
            }
        }
    }();

    matrix.clearDisplay(0);

    // wait for joystick to come back
    while (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
        || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold

```

```

    || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
    || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {}

}

// scrolls the 'game over' message around the matrix
void showGameOverMessage() {
    [&] {
        for (int d = 0; d < sizeof(gameOverMessage[0]) - 4; d++) {
            for (int col = 0; col < 5; col++) {
                delay(messageSpeed);
                for (int row = 0; row < 8; row++) {
                    // this reads the byte from the PROGMEM and displays it on the screen
                    matrix.setLed(0, row, col, pgm_read_byte(&(gameOverMessage[row][col + d])));
                }
            }
        }

        // if the joystick is moved, exit the message
        if (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
            || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold
            || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
            || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {
            return; // return the lambda function
        }
    }
}

}();

matrix.clearDisplay(0);

```

```
// wait for joystick to come back
while (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
    || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold
    || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
    || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {}

}
```

```
// scrolls the 'win' message around the matrix
void showWinMessage() {
    // not implemented yet // TODO: implement it
}
```

```
// scrolls the 'score' message with numbers around the matrix
void showScoreMessage(int score) {
    if (score < 0 || score > 99) return;
```

```
// specify score digits
int second = score % 10;
int first = (score / 10) % 10;
```

```
[&] {
    for (int d = 0; d < sizeof(scoreMessage[0]) + 2 * sizeof(digits[0][0]); d++) {
        for (int col = 0; col < 5; col++) {
            delay(messageSpeed);
            for (int row = 0; row < 8; row++) {
```

```

if (d <= sizeof(scoreMessage[0]) - 8) {
    matrix.setLed(0, row, col, pgm_read_byte(&(scoreMessage[row][col + d])));
}

int c = col + d - sizeof(scoreMessage[0]) + 6; // move 6 px in front of the previous message

// if the score is < 10, shift out the first digit (zero)
if (score < 10) c += 8;

if (c >= 0 && c < 8) {
    if (first > 0) matrix.setLed(0, row, col, pgm_read_byte(&(digits[first][row][c]))); // show only if
    score is >= 10 (see above)
} else {
    c -= 8;
    if (c >= 0 && c < 8) {
        matrix.setLed(0, row, col, pgm_read_byte(&(digits[second][row][c]))); // show always
    }
}
}

// if the joystick is moved, exit the message
if (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
    || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold
    || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
    || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {
    return; // return the lambda function
}
}

```

```
}());
```

```
matrix.clearDisplay(0);
```

```
// // wait for joystick co come back
```

```
// while (analogRead(Pin::joystickY) < joystickHome.y - joystickThreshold
```

```
//      || analogRead(Pin::joystickY) > joystickHome.y + joystickThreshold
```

```
//      || analogRead(Pin::joystickX) < joystickHome.x - joystickThreshold
```

```
//      || analogRead(Pin::joystickX) > joystickHome.x + joystickThreshold) {}
```

```
}
```

```
// standard map function, but with floats
```

```
float mapf(float x, float in_min, float in_max, float out_min, float out_max) {
```

```
    return (x - in_min) * (out_max - out_min) / (in_max - in_min) + out_min;
```

```
}
```