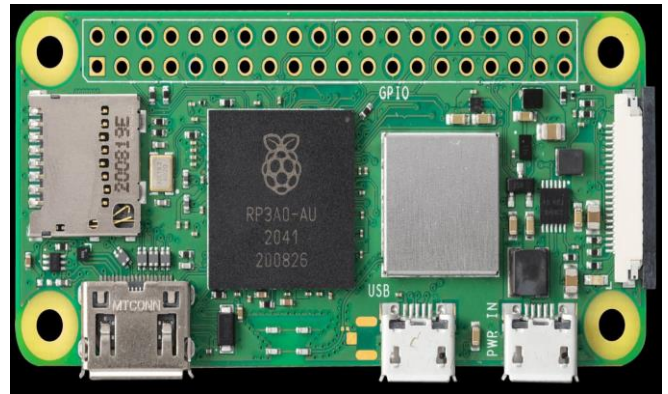


# **plan to build a plant disease detection device with a camera and soil sensors**

## **Steps to Build the Device:**

### **1. Setup Raspberry Pi Zero W:**

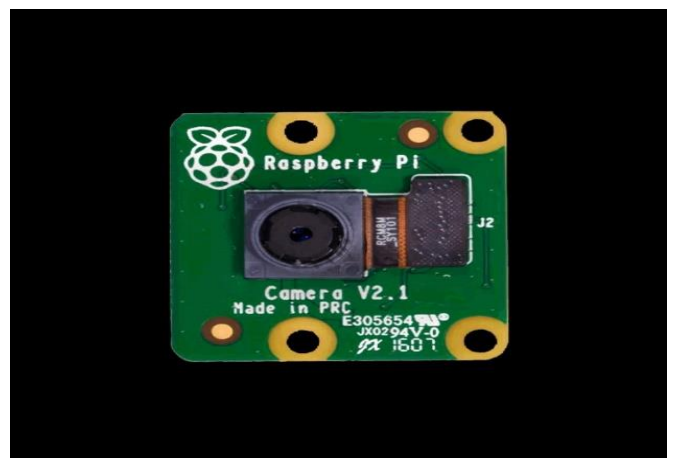
- Install Raspbian OS on the MicroSD card.
- Connect the Raspberry Pi to a power source and configure it.



**Figure [Setup Raspberry Pi Zero W\*]**

### **2. Connect the Camera Module:**

- Attach the camera module to the Raspberry Pi's CSI port.
- Enable the camera interface in the Raspberry Pi configuration settings



**Figure [Raspberry Pi Camera Module V2]**

### 3. Install Soil Sensors:

- Connect the DFRobot Capacitive Soil Moisture Sensor to the Raspberry Pi's GPIO pins.
- Connect the NPK Soil Sensor similarly, possibly using an ADC (analog-to-digital converter) if needed.

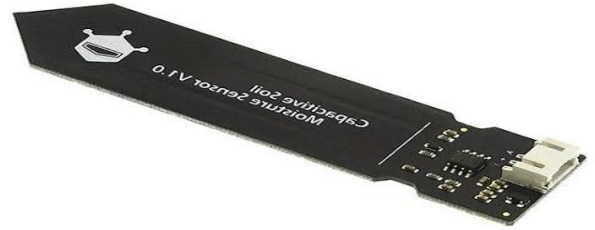


Figure [DFROBOT soil sensor]

### 4. Integrate BME680 Sensor:

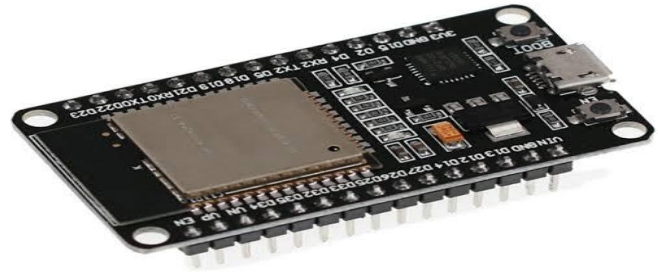
- Connect the BME680 to the Raspberry Pi using I2C communication.



Figure [BME680 sensor]

## **5. Connect ESP32:**

- Setup the ESP32 for additional processing or to act as a Wi-Fi module.



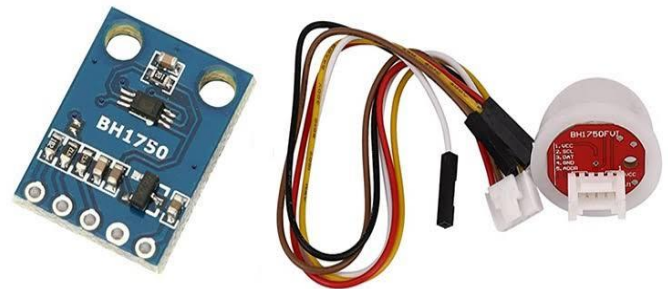
**Figure [ESP32 Wi-Fi and Bluetooth Module ]**

## **6. Programming:**

- Write a Python script to capture images with the camera.
- Write code to read data from the soil sensors and BME680.
- Use machine learning models (e.g., TensorFlow Lite) to analyze images and detect plant diseases.
- Store sensor data and disease detection results locally or on a cloud service.

## **7. Develop Mobile App:**

- Use Flutter or React Native to create a mobile app that displays the data and alerts users about detected plant diseases.
- Integrate the disease detection model into the app using TensorFlow Lite.



**Figure [BH1750 Light Intensity Sensor]**

## **8. Dashboard and Website:**

- Create a web dashboard using React.js or Angular to visualize the data.
- Build a website with sections for your research paper, app download, and real-time data from the device.

**The measurements of your device will depend on the components and how you assemble them. Here's a rough estimate based on the components you've mentioned**

<b>Components</b>	<b>Approximate Sizes</b>
<b>1. *Raspberry Pi Zero W*:</b>	<b>- Dimensions: 65mm x 30mm x 5mm</b>
<b>2. *Raspberry Pi Camera Module*:</b>	<b>25mm x 24mm x 9mm</b>
<b>3. *DFRobot Capacitive Soil Moisture Sensor*:</b>	<b>99mm x 16mm x 4mm</b>
<b>4. *NPK Soil Sensor*:</b>	<b>150mm x 20mm x 20mm</b>
<b>5. *BME680 Sensor*:</b>	<b>3.3mm x 3.3mm x 1mm</b>
<b>6. *ESP32 Module*:</b>	<b>25mm x 18mm x 2.8mm</b>

### **Assembly Considerations:**

- **Enclosure:** You might want to use a project box to house these components. A box measuring around **\*\*200mm x 100mm x 50mm\*** should provide enough space for all components, wiring, and allow for some ventilation.

- **Mounting:** Ensure that the sensors are mounted in a way that they can interact with the soil and environment effectively. For example, the soil moisture sensor needs to be inserted into the soil, while the camera should have a clear line of sight to the plants.