

Electronics Handbook

2nd Year Electrical Engineering

Eng. Abdalrahman Shaban Mohamed

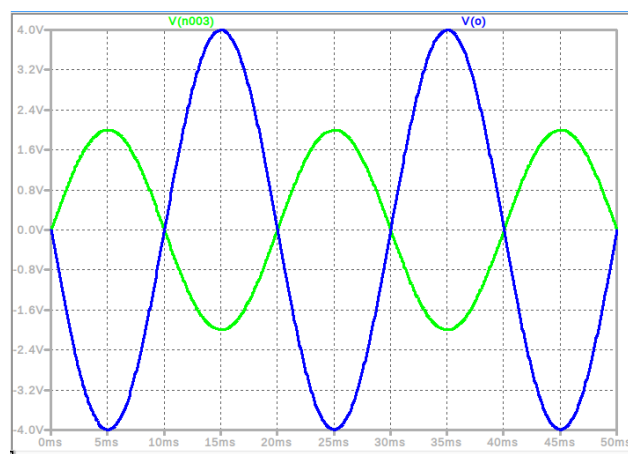
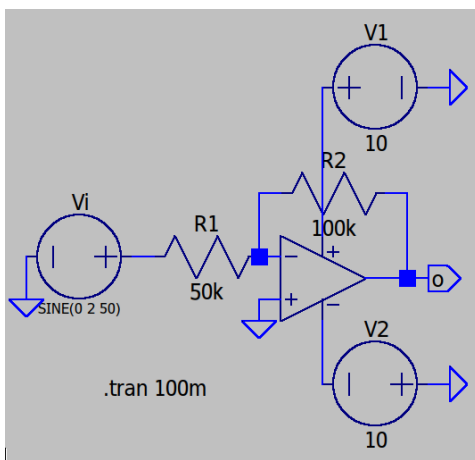
Contents

1	Operational Amplifier	
	(Linear Applications)	2
1.1	Inverting	2
1.2	Effect of Finite Open-loop Gain	2
1.3	Non-Inverting	3
1.4	Inverting Summer	3
1.5	NonInverting Summer	4
1.6	Difference	4
1.7	Buffer	5
1.8	Trans-Impedance	5
1.9	Integrator	6
	1.9.1 Inverting Integrator	6
	1.9.2 Miller Integrator	6
1.10	Differentiator	7
1.11	Common Mode Gain	7
1.12	Instrumentation	8
2	Operational Amplifier	
	(Non-Linear Applications)	9
2.1	Comparator	9
	2.1.1 Zero-level detector	9
	2.1.2 NonZero-level detector	9
	2.1.3 Schmitt Trigger	10
2.2	Practical Triangular-Wave Oscillator	10
2.3	Square-Wave Oscillator (Astable Multivibrator)	11
2.4	Log and Antilog Amplifier	12
	2.4.1 Basic log Amplifier	12
	2.4.2 Log Amplifier with BJT	12
	2.4.3 Basic Antilog	12
2.5	Multiplier	13
2.6	Divider	13
2.7	Positive half-wave rectifier	13
2.8	Full-wave Rectifier	14
3	Timer 555	15
3.1	Monostable Multivibrator	15
3.2	Astable Multivibrator	16

Chapter 1

Operational Amplifier (Linear Applications)

1.1 Inverting

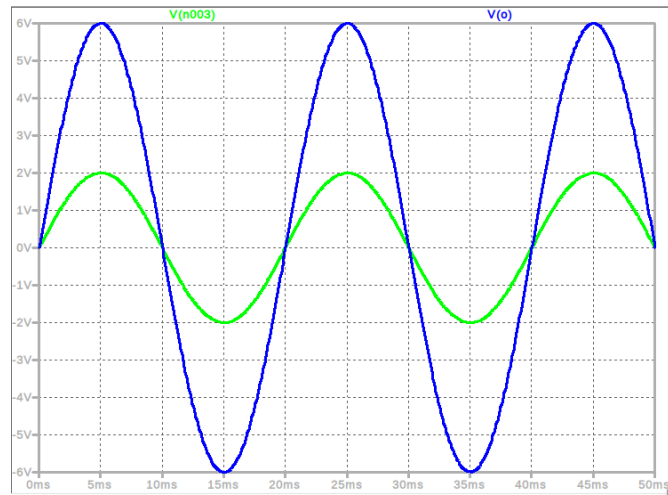
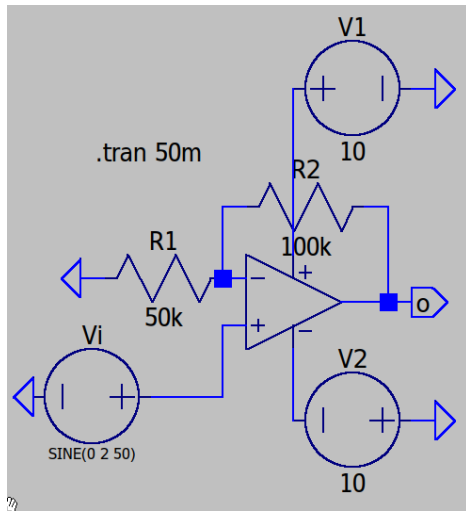


$$\begin{aligned}
 I_{R1} &= I_{R2} \\
 \frac{V_i - 0}{R_1} &= \frac{0 - V_o}{R_2} \\
 R_2 V_i &= -R_1 V_o \\
 \therefore V_o &= -\frac{R_2}{R_1} V_i
 \end{aligned}$$

1.2 Effect of Finite Open-loop Gain

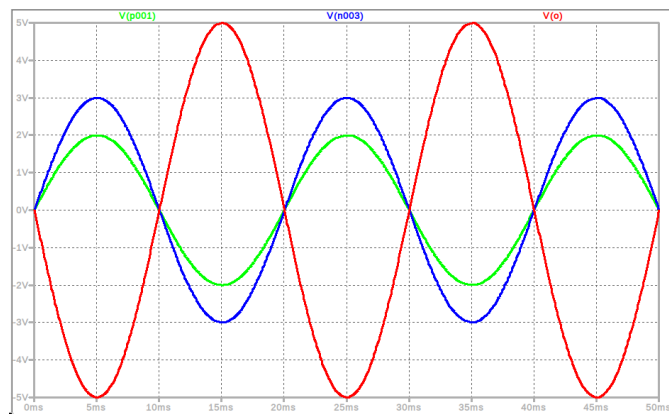
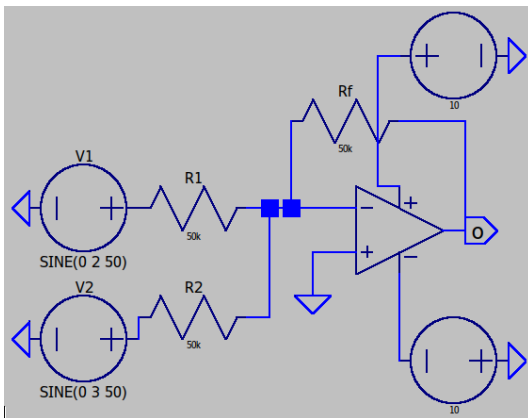
$$\begin{aligned}
 V_o &= A(V^+ - V^-) \\
 V^+ &= 0 \quad \text{and} \quad V^- = -\frac{V_o}{A} \\
 \frac{V_i - (-\frac{V_o}{A})}{R_1} &= \frac{-\frac{V_o}{A} - V_o}{R_2} \\
 R_2 V_i + R_2 \frac{V_o}{A} &= -R_1 \frac{V_o}{A} - R_1 V_o \\
 R_2 V_i &= -V_o \left(\frac{R_2}{A} + \frac{R_1}{A} + R_1 \right) \\
 \frac{R_2}{R_1} V_i &= -V_o \left(\frac{R_2}{AR_1} + \frac{1}{A} + 1 \right) \\
 \therefore G = \frac{V_o}{V_i} &= \frac{-R_2/R_1}{1 + (1 + \frac{R_2}{R_1})/A}
 \end{aligned}$$

1.3 Non-Inverting



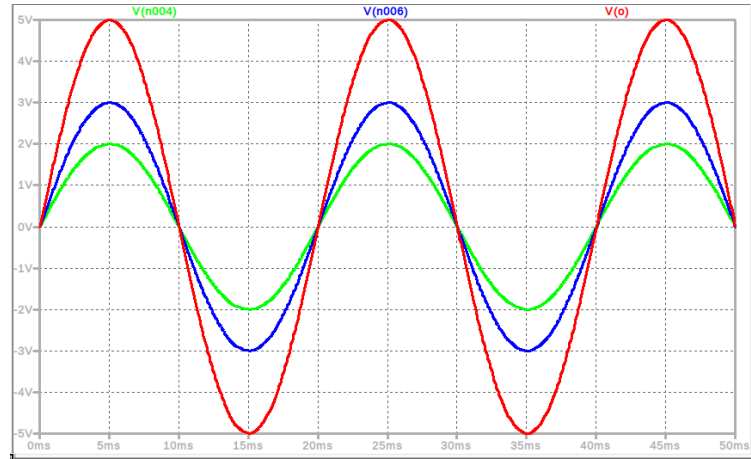
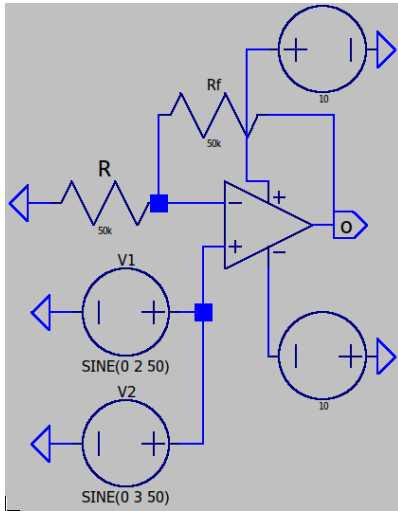
$$\begin{aligned}
 I_{R1} &= I_{R2} \\
 \frac{0 - V_i}{R_1} &= \frac{V_i - V_o}{R_2} \\
 -R_2 V_i &= R_1 V_i - R_1 V_o \\
 -V_i(R_2 + R_1) &= -R_1 V_o \\
 \therefore V_o &= V_i(1 + R_2/R_1)
 \end{aligned}$$

1.4 Inverting Summer



$$\begin{aligned}
 \therefore I_{R1} + I_{R2} &= I_{R_f} \\
 \frac{V_1 - 0}{R_1} + \frac{V_2 - 0}{R_2} &= \frac{0 - V_o}{R_f} \\
 \therefore V_o &= -\left(\frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2\right)
 \end{aligned}$$

1.5 NonInverting Summer



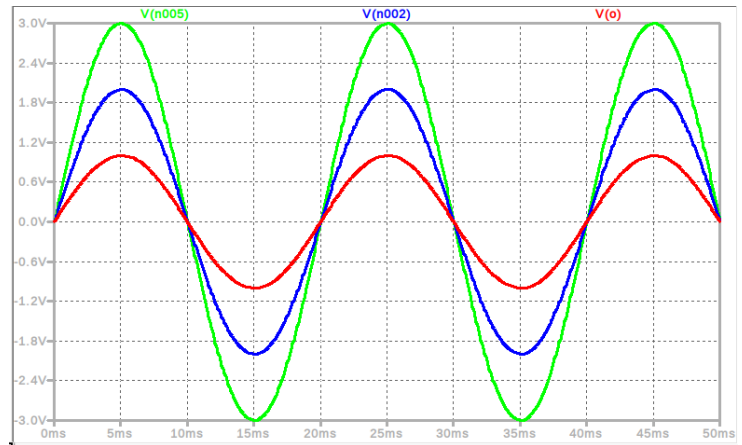
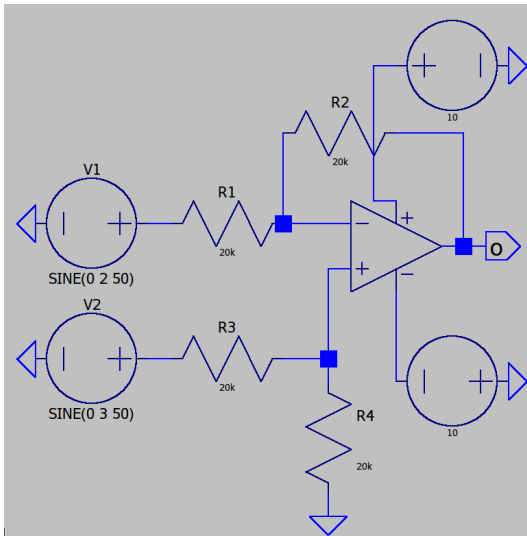
$$\therefore V^- = V^+$$

$$\frac{0 - (V_1 + V_2)}{R} = \frac{(V_1 + V_2) - V_o}{R_f}$$

$$-R_f(V_1 + V_2) = R(V_1 + V_2) - R V_o$$

$$\therefore V_o = (1 + R_f/R)(V_1 + V_2)$$

1.6 Difference



Using Super position:

kill V2:

$$V_{o1} = -\frac{R_2}{R_1} V_1$$

kill V1:

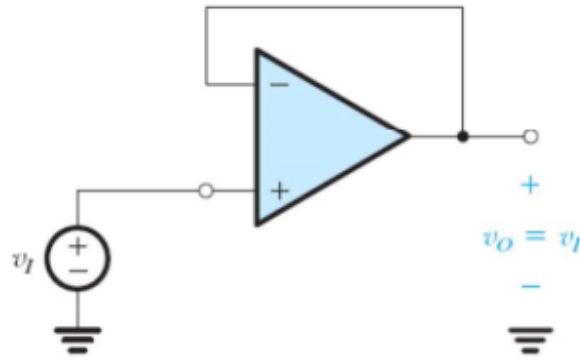
$$\frac{0 - \frac{R_4}{R_3 + R_4} V_2}{R_1} = \frac{\frac{R_4}{R_3 + R_4} V_2 - V_{o2}}{R_2}$$

$$\frac{-R_4 R_2}{R_3 + R_4} V_2 = \frac{R_4 R_1}{R_3 + R_4} V_2 - R_1 V_{o2}$$

$$V_{o2} = \frac{R_2}{R_1} \frac{R_4}{R_3 + R_4} V_2 + \frac{R_4}{R_3 + R_4} V_2$$

$$\begin{aligned}
V_o &= V_{o1} + V_{o2} \\
V_o &= -\frac{R_2}{R_1}V_1 + \frac{R_2}{R_1} \frac{R_4}{R_3 + R_4}V_2 + \frac{R_4}{R_3 + R_4}V_2 \\
V_o &= -\frac{R_2}{R_1}V_1 + \frac{R_4}{R_3 + R_4} \left(\frac{R_2}{R_1} + 1 \right) V_2 \\
\text{When } R_1 &= R_3, R_2 = R_4 \\
V_o &= -\frac{R_2}{R_1}V_1 + \frac{R_2}{R_1 + R_2} \left(\frac{R_2}{R_1} + 1 \right) V_2 \\
V_o &= -\frac{R_2}{R_1}V_1 + \frac{R_2}{R_1 + R_2} \left(\frac{R_1 + R_2}{R_1} \right) V_2 \\
\therefore V_o &= -\frac{R_2}{R_1}(V_2 - V_1)
\end{aligned}$$

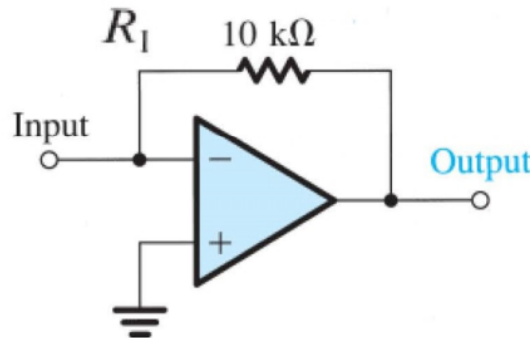
1.7 Buffer



$$V_o = V_i \quad (1.1)$$

The main function of an op-amp buffer is to provide a high input impedance and a low output impedance, which helps to reduce the loading effect on the circuit it is connected to.

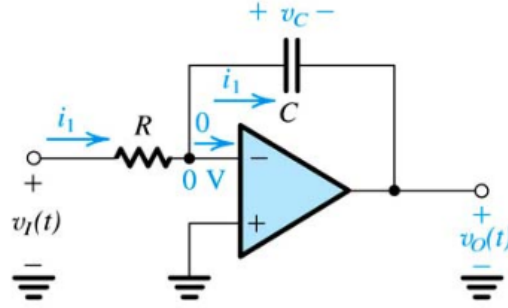
1.8 Trans-Impedance



$$\begin{aligned}
I_i &= I_R \\
I_i &= \frac{0 - V_o}{R_f} \\
\therefore V_o &= -R_f I_i
\end{aligned}$$

1.9 Integrator

1.9.1 Inverting Integrator



$$\frac{V_i - 0}{R} = I_c$$

$$\therefore V_o = -V_c$$

$$\frac{V_i - 0}{R} = -C \frac{dV_o}{dt}$$

$$\therefore V_o = \frac{-1}{RC} \int V_i dt$$

In s domain:

$$V_o = \frac{-1}{sRC} V_i$$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-1}{(j\omega)RC}$$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = \frac{-(-j)}{(\omega)RC}$$

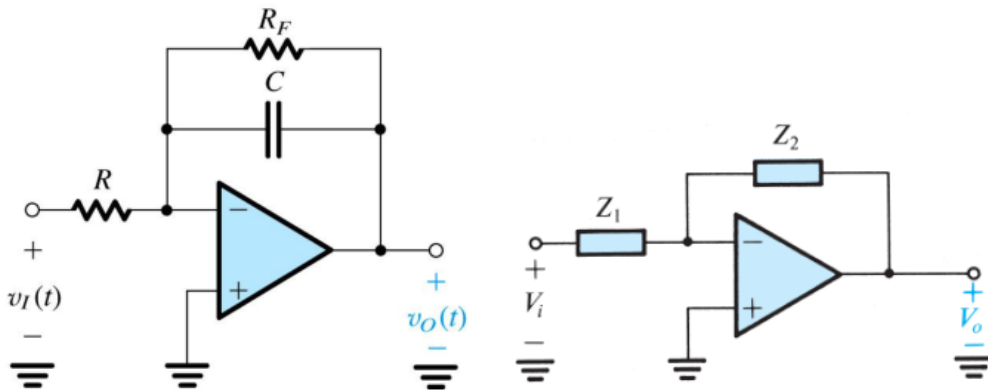
$$\text{As } j = \cos\left(\frac{\pi}{2}\right) + j\sin\left(\frac{\pi}{2}\right) = e^{j\frac{\pi}{2}}$$

$$\frac{V_o(\omega)}{V_i(\omega)} = \frac{e^{j\frac{\pi}{2}}}{\omega RC}$$

$$\therefore \left| \frac{V_o}{V_i} \right| = \left| \frac{1}{\omega RC} \right|$$

$$\phi = +90$$

1.9.2 Miller Integrator



The Miller integrator with a large resistance R_F connected in parallel with C in order to provide negative feedback and hence finite gain at dc ($A = \frac{R_F}{R}$).

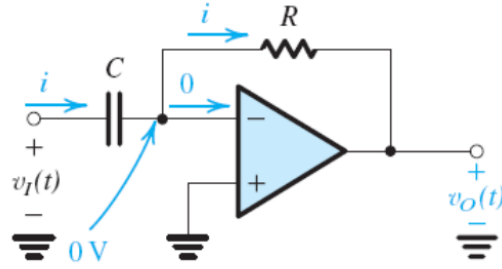
$$V_o = -\frac{Z_2}{Z_1}$$

$$Z_2 = \frac{R_f \cdot \frac{1}{sC}}{R_f + \frac{1}{sC}}$$

$$Z_2 = \frac{R_f}{sR_fC + 1}$$

$$\therefore V_o = \frac{-R_f/R}{sR_fC + 1} \cdot V_i$$

1.10 Differentiator

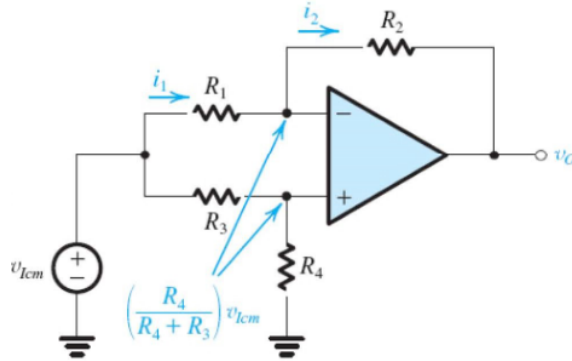


$$I_C = I_R$$

$$C \frac{dV_i}{dt} = \frac{0 - V_o}{R}$$

$$\therefore V_o = -RC \frac{dV_i}{dt}$$

1.11 Common Mode Gain



$$V^- = \frac{R_4}{R_4 + R_3} V_{Icm}$$

$$\frac{V_{Icm} - V^-}{R_1} = \frac{V_{Icm} - V_o}{R_2}$$

$$R_2 V_{Icm} - \frac{R_4 R_2}{R_4 + R_3} V_{Icm} = \frac{R_4 R_1}{R_4 + R_3} V_{Icm} - R_1 V_o$$

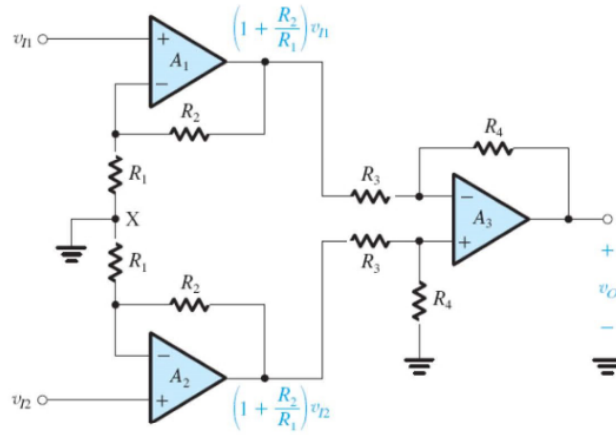
$$V_o = \frac{R_2}{R_1} \frac{R_4}{R_4 + R_3} V_{Icm} + \frac{R_4}{R_4 + R_3} V_{Icm} - \frac{R_2}{R_1} V_{Icm}$$

$$\begin{aligned}\frac{V_o}{V_{\text{Icm}}} &= \frac{R_4}{R_4 + R_3} \left(\frac{R_2}{R_1} + 1 - \frac{R_4 + R_3}{R_4} \cdot \frac{R_2}{R_1} \right) \\ \frac{V_o}{V_{\text{Icm}}} &= \frac{R_4}{R_4 + R_3} \left(\frac{R_2}{R_1} \left(1 - \frac{R_4 + R_3}{R_4} \right) + 1 \right) \\ \frac{V_o}{V_{\text{Icm}}} &= \frac{R_4}{R_4 + R_3} \left(\frac{R_2}{R_1} \left(1 - 1 - \frac{R_3}{R_4} \right) + 1 \right) \\ \therefore A_{\text{cm}} &= \frac{V_o}{V_{\text{Icm}}} = \frac{R_4}{R_4 + R_3} \left(1 - \frac{R_2}{R_1} \frac{R_3}{R_4} \right)\end{aligned}$$

When $R_3 = R_1$ and $R_4 = R_2$
 $A_{\text{cm}} = 0$

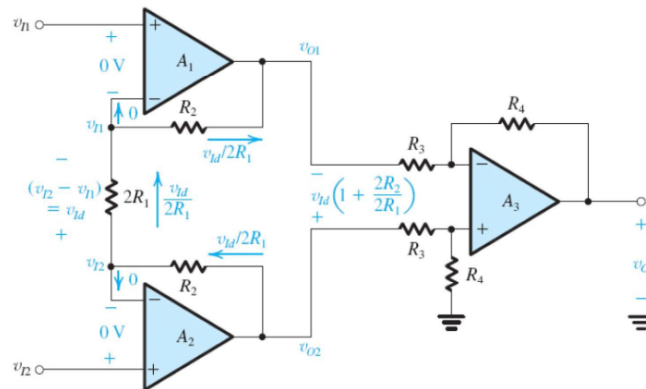
1.12 Instrumentation

To get high input impedance and zero common mode gain (less noise) we can use instrumentation Amplifier.



What're the major disadvantages of this configuration?

- 1- Saturation due to the common mode voltage.
- 2- Common mode voltage will be amplified unless we make perfect matching between the resistors which is very hard in practical.
- 3- We have to change at least 2 resistors to change the gain.



$$A_{\text{cm}} = 0$$

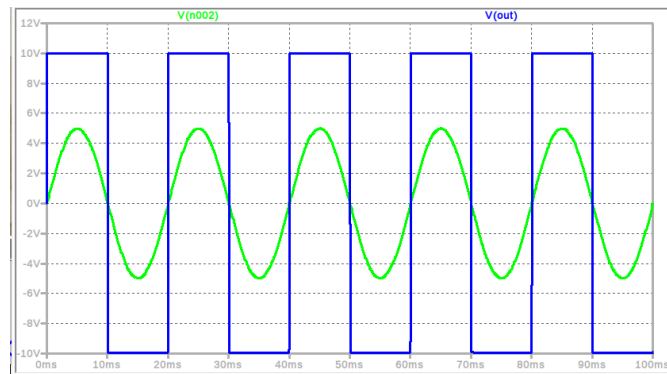
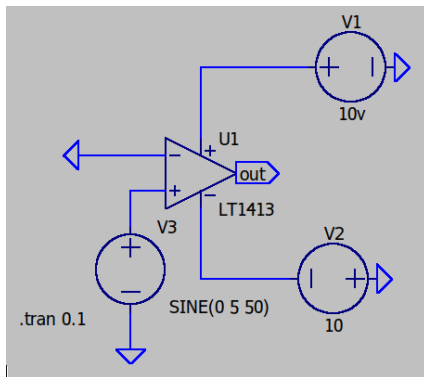
$$A_d = \frac{R_4}{R_3} \left(1 + \frac{2R_2}{2R_1} \right)$$

Chapter 2

Operational Amplifier (Non-Linear Applications)

2.1 Comparator

2.1.1 Zero-level detector

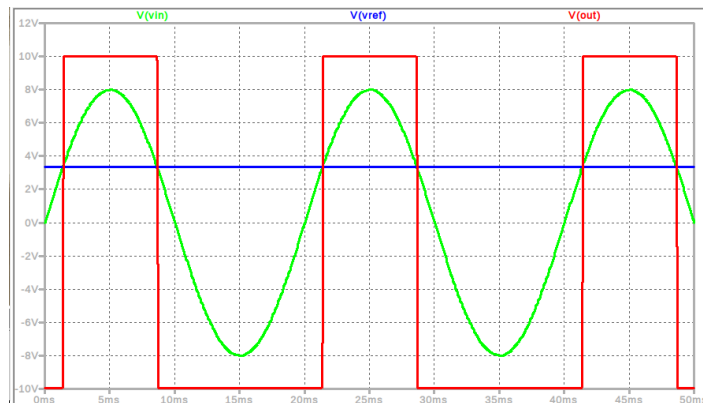
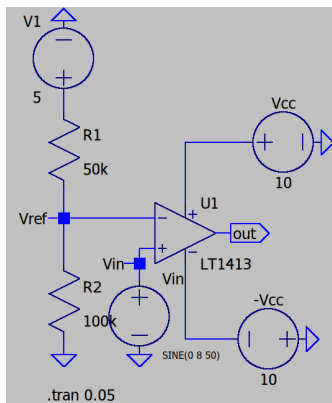


$$V_o = A(V^+ - V^-)$$

$$\because V^- = 0$$

$$V_o = V_{cc}$$

2.1.2 NonZero-level detector



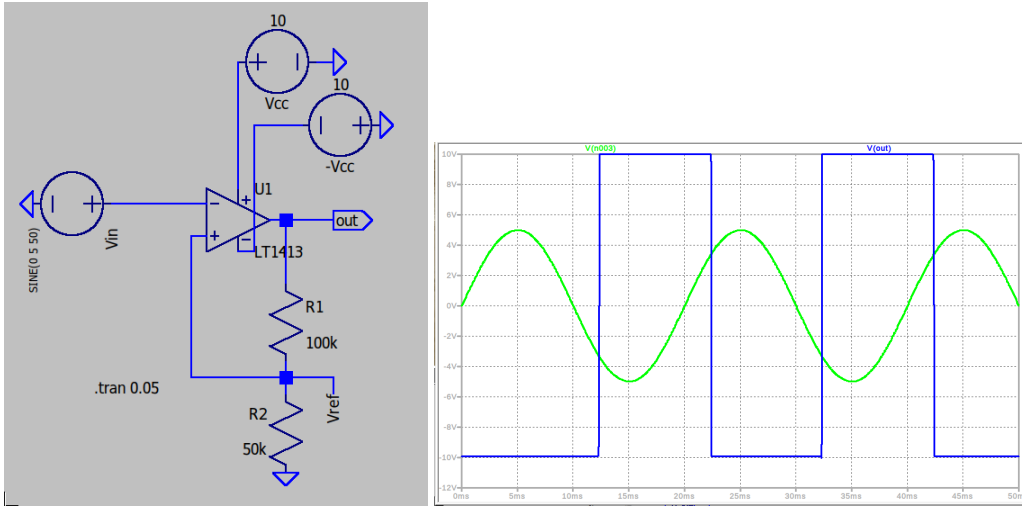
$$\because V_o = A(V^+ - V^-)$$

$$\because V^- = V_{ref} = V_1 \cdot \frac{R_2}{R_2 + R_1}$$

$$\therefore V_o = +V_{cc} \quad \text{when} \quad V^+ > V_{ref}$$

$$\therefore V_o = -V_{cc} \quad \text{when} \quad V^+ \leq V_{ref}$$

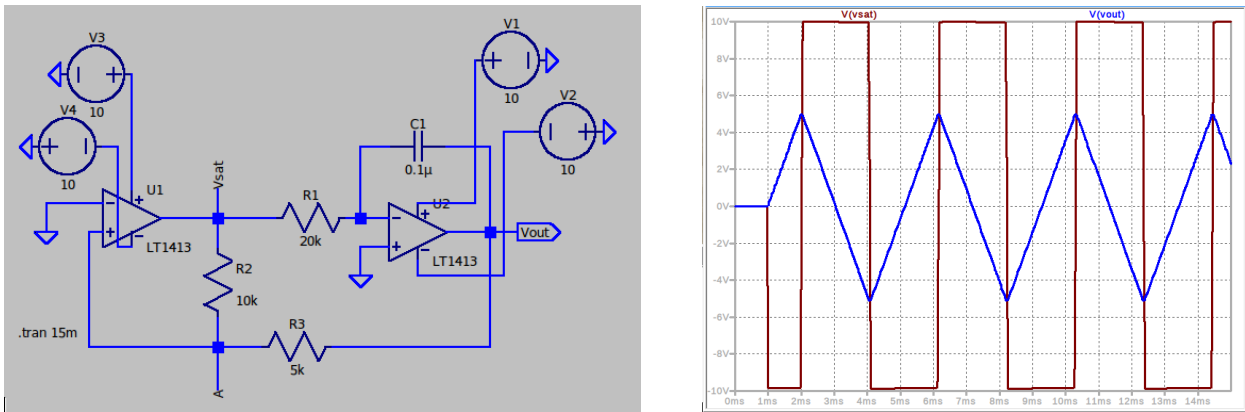
2.1.3 Schmitt Trigger



Using Schmitt Trigger reduces noise effects with hysteresis.

$$\begin{aligned} \because V_o &= A(V^+ - V^-) \\ &= V_o = A(V_{ref} - V_{in}) \\ \text{As } V_{ref} &= V_{cc} \cdot \frac{R_2}{R_2 + R_1} \end{aligned}$$

2.2 Practical Triangular-Wave Oscillator



Let V_{UTP} be the Upper Trigger Point (UTP) (V_{out})

And V_{LTP} be the Lower Trigger Point (LTP)

KCL at pint A:

$$\begin{aligned} \frac{V_{out} - V_A}{R_3} &= \frac{V_A - V_{sat}}{R_2} \\ \text{As } V_{out} &= V_{UTP} = |V_{LTP}| \\ R_2 V_o - R_2 V_A &= R_3 V_A - R_3 V_{sat} \\ V_o &= \frac{R_3}{R_2} V_A - \frac{R_3}{R_2} V_{sat} + V_A \\ &= \frac{R_3}{R_2} (V_A - V_{sat}) + V_A \\ \text{At } V_A &= 0 \\ V_o &= -V_{sat} \frac{R_3}{R_2} \end{aligned}$$

So we can find out that:

$$V_{UTP} = \frac{R_3}{R_2} V_{sat}$$

$$V_{LTP} = -\frac{R_3}{R_2} V_{sat}$$

4 of the capacitor charging time is the Periodic time.

$$V_{UTP} = \frac{1}{R_1 C} \int dV_{sat} dt$$

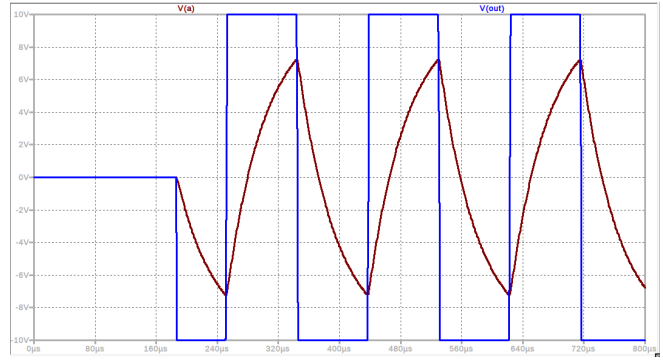
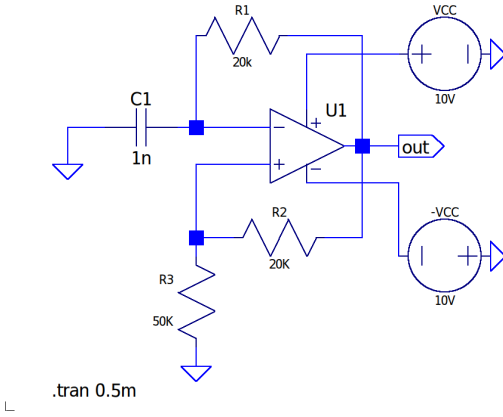
$$\frac{R_3}{R_2} V_{sat} = \frac{1}{R_1 C} V_{sat} t$$

$$t = R_1 C \frac{R_3}{R_2}$$

$$T = 4t = 4 \frac{R_3}{R_2} R_1 C$$

$$\therefore F = \frac{1}{T} = \frac{1}{4R_1 C} \cdot \frac{R_2}{R_3}$$

2.3 Square-Wave Oscillator (Astable Multivibrator)



When $V_c = 0$ and Capacitor begins charging

$$\therefore V_o = A \cdot (V_f - V_c)$$

$$\therefore V_f > V_c$$

$$\therefore V_o = V_{sat}$$

When $V_c \geq V_f$

$$V_o = -V_{sat}$$

$$\therefore V_f = \beta V_{sat} \quad \text{As } \beta = \frac{R_3}{R_3 + R_2}$$

Using KCL

$$\frac{V_{sat} - V_c}{R_1} = C \frac{dV_c}{dt}$$

$$\frac{V_{sat} - V_c}{R_1 C} = \frac{dV_c}{dt}$$

$$\int_0^t \frac{dt}{R_1 C} = \int_{-V_f}^{V_f} \frac{dV_c}{V_{sat} - V_c}$$

$$\frac{t}{R_1 C} = \ln(V_{sat} + V_f) - \ln(V_{sat} - V_f)$$

$$\frac{t}{R_1 C} = \ln\left(\frac{V_{\text{sat}} + V_f}{V_{\text{sat}} - V_f}\right)$$

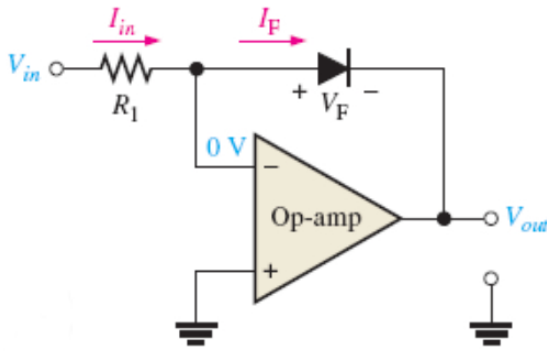
$$t = R_1 C \cdot \ln\left(\frac{1 + \beta}{1 - \beta}\right)$$

$$T = 2t = 2R_1 C \cdot \ln\left(\frac{1 + \beta}{1 - \beta}\right)$$

$$\therefore F = \frac{1}{2R_1 C \cdot \ln\left(\frac{1 + \beta}{1 - \beta}\right)}$$

2.4 Log and Antilog Amplifier

2.4.1 Basic log Amplifier



$$I_D = I_F = I_R e^{\frac{V_F}{V_T}}$$

I_R is const

$$V_T = \frac{q}{kt} \approx 26mV$$

$$V_o = -V_F$$

Using KCL:

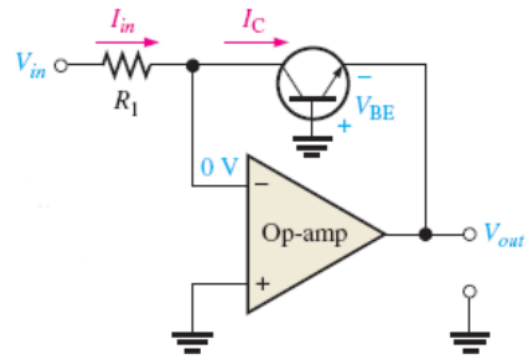
$$I_{\text{in}} = I_F$$

$$\frac{V_{\text{in}}}{R_1} = I_R e^{\frac{-V_o}{V_T}}$$

$$\frac{-V_o}{V_T} = \ln\left(\frac{V_{\text{in}}}{R_1 I_R}\right)$$

$$\therefore V_o = -V_T \ln\left(\frac{V_{\text{in}}}{R_1 I_R}\right)$$

2.4.2 Log Amplifier with BJT



$$I_E = I_C + I_B$$

$$I_C \gg I_B$$

$$I_E \approx I_C$$

$$I_C = I_{\text{EBO}} e^{\frac{V_{\text{BE}}}{V_T}}$$

$$I_{\text{in}} = I_C$$

$$\frac{V_i}{R_1} = I_{\text{EBO}} e^{\frac{-V_o}{V_T}}$$

$$\therefore V_o = -V_T \ln\left(\frac{V_{\text{in}}}{R_1 I_{\text{EBO}}}\right)$$

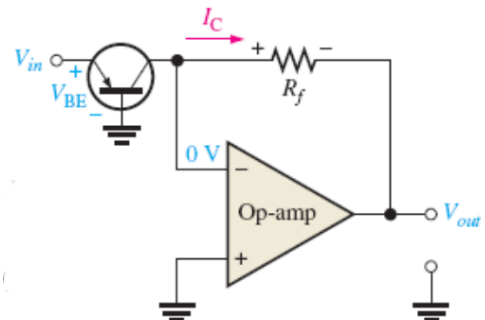
2.4.3 Basic Antilog

$$V_o = -R_f I_C$$

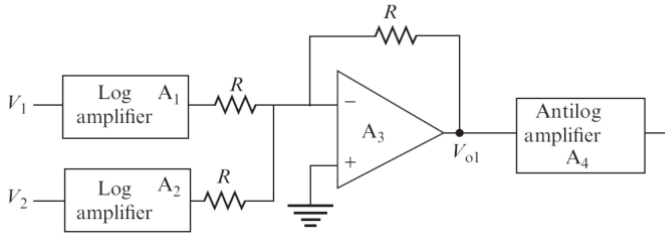
$$I_C = I_{\text{EBO}} e^{\frac{V_i}{V_T}}$$

$$\therefore V_o = -R_f I_{\text{EBO}} e^{\frac{V_i}{V_T}}$$

$$V_o = -R_f I_{\text{EBO}} \text{antilog}\left(\frac{V_i}{26mV}\right)$$

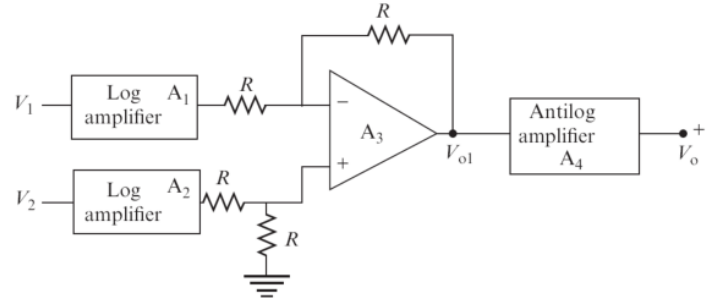


2.5 Multiplier



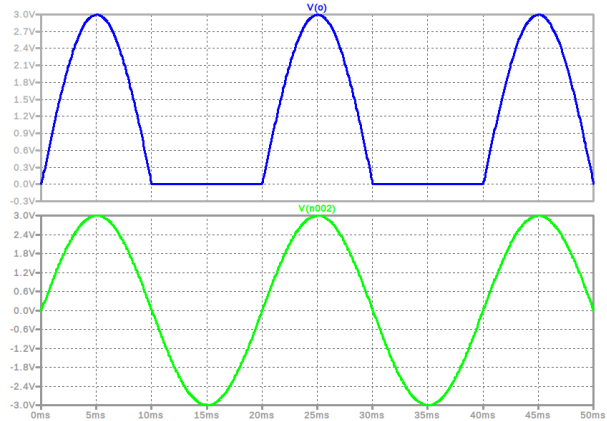
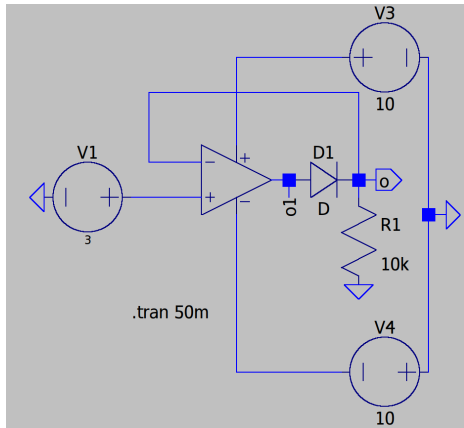
$$\begin{aligned}
 V_{o1} &= V_T \left(\ln\left(\frac{V_1}{RI_{EBO}}\right) + \ln\left(\frac{V_2}{RI_{EBO}}\right) \right) \\
 &= V_T \left(\ln\left(\frac{V_1 V_2}{R^2 I_{EBO}^2}\right) \right) \\
 V_o &= -RI_{EBO} e^{\ln\left(\frac{V_1 V_2}{R^2 I_{EBO}^2}\right)} \\
 &= -RI_{EBO} \frac{V_1 V_2}{R^2 I_{EBO}^2} \\
 \therefore V_o &= -\frac{V_1 V_2}{RI_{EBO}}
 \end{aligned}$$

2.6 Divider



$$\begin{aligned}
 V_{o1} &= -V_T \ln\left(\frac{V_2}{RI_{EBO}}\right) + V_T \ln\left(\frac{V_1}{RI_{EBO}}\right) \\
 &= V_T \left(\ln\left(\frac{V_1}{V_2}\right) \right) \\
 V_o &= -RI_{EBO} e^{\ln\left(\frac{V_1}{V_2}\right)} \\
 \therefore V_o &= -RI_{EBO} \frac{V_1}{V_2}
 \end{aligned}$$

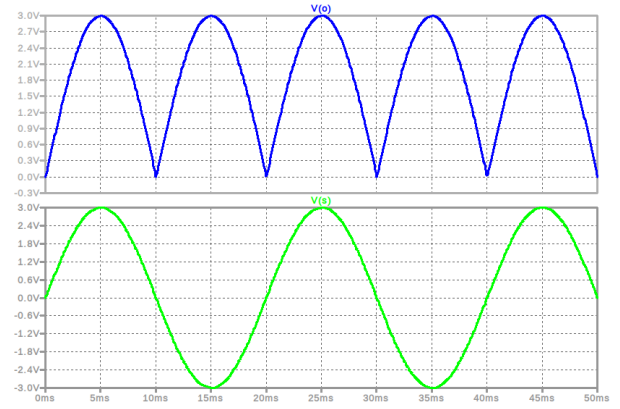
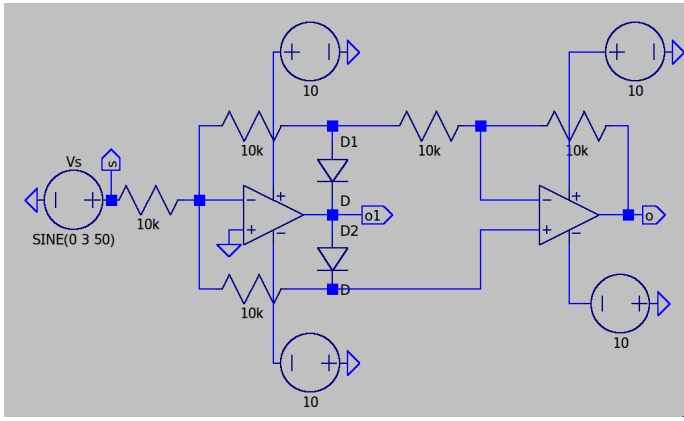
2.7 Positive half-wave rectifier



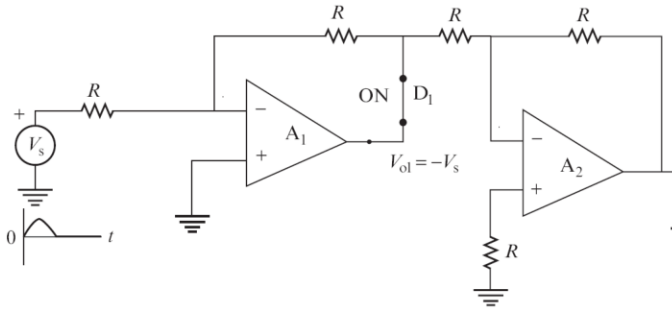
$$V_{o1} \approx V_1 + 0.623$$

$$V_o = V_1 \text{ Rectified}$$

2.8 Full-wave Rectifier

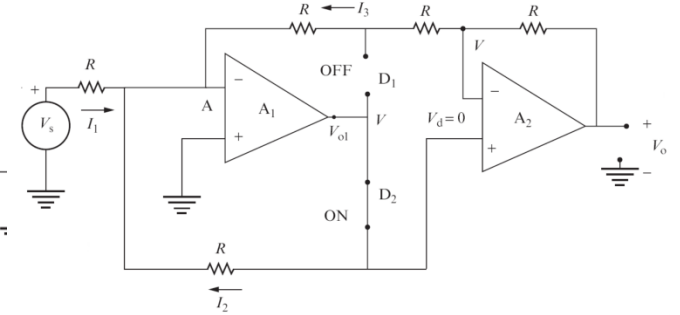


During positive half cycle



$$\begin{aligned}\frac{V_s - 0}{R} &= \frac{0 - V_{o1}}{R} \\ V_{o1} &= -V_s \\ \frac{V_{o1} - 0}{R} &= \frac{0 - V_o}{R} \\ V_o &= -V_{o1} \\ \therefore V_o &= V_s\end{aligned}$$

During negative half cycle

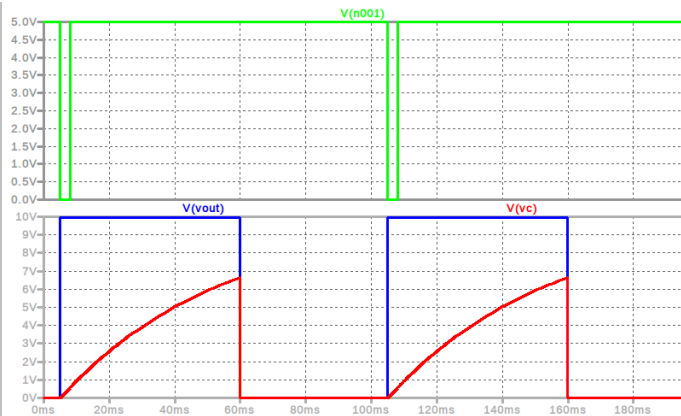
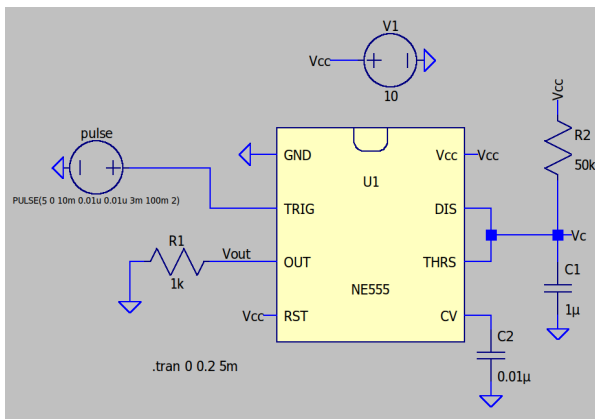
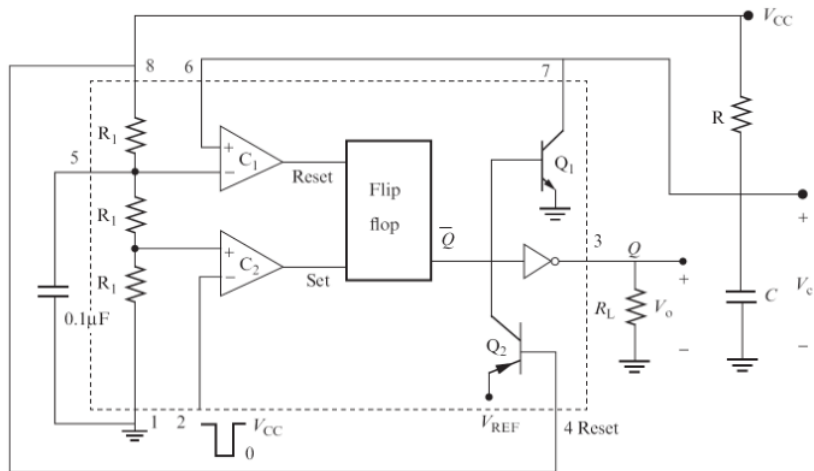


$$\begin{aligned}I_1 + I_2 + I_3 &= 0 \\ \frac{V_s}{R} + \frac{V}{R} + \frac{V}{2R} &= 0 \\ V &= -\frac{2}{3}V_s \\ \frac{0 - V}{2R} &= \frac{V - V_o}{R} \\ V_o &= \frac{3}{2}V \\ V_o &= \frac{3}{2} \left(-\frac{2}{3}V_s \right) \\ \therefore V_o &= -V_s\end{aligned}$$

Chapter 3

Timer 555

3.1 Monostable Multivibrator



$$V_c(t) = V_F - (V_F - V_I)e^{\frac{-t}{\tau}}$$

$$V_c(t) = V_{cc} - (V_{cc} - o)e^{\frac{-t}{RC}}$$

$$\text{At } t = T, V_c(t) = \frac{2}{3}V_{cc}$$

$$\frac{2}{3}V_{cc} = V_{cc}\left(1 - e^{\frac{-T}{RC}}\right)$$

$$e^{\frac{-T}{RC}} = \frac{1}{3}$$

$$\frac{-T}{RC} \approx -1.1$$

$$\therefore T = 1.1RC$$

3.2 Astable Multivibrator