

Recall conformal transformation preserves angles

$$(1) \quad g^{\alpha\beta} \rightarrow \tilde{g}^{\alpha\beta}(\zeta) \text{ s.t. } g_{\alpha\beta}(\zeta) \rightarrow \Omega^2 \tilde{g}_{\alpha\beta}(\zeta)$$

A CFT is a field theory which is invariant under such (conformal)  $\chi$ -Forms.

We will consider the case of a CFT in a fixed (not dynamical) background metric.

↳ Meaning (1) is a global symmetry with associated conserved (Noether) currents.

Not worried about particles, S-matrices.

"We will be concerned with correlation functions and the behavior of different operators under conformal  $\chi$ -Forms".

Start with 2D Minkowski coordinates

$$\rightarrow (\zeta^0, \zeta^1)$$

Now get Euclidean worldsheets

$$\rightarrow (\zeta^1, \zeta^2) = (\zeta^1, i\zeta^0)$$

Now form complex coordinates from Euclidean coordinates

$$\rightarrow z = \zeta^1 + i\zeta^2, \quad \bar{z} = \zeta^1 - i\zeta^2 \\ = \zeta^1 - \zeta^0 \quad \quad \quad = \zeta^1 + \zeta^0$$

$(z, \bar{z})$  are "Euclidean analogue of light cone/null coordinates". Length always equal to zero/all intervals are null.

Recall: Holomorphic is like analytic.

Every holomorphic function is analytic,

(according to GPT-4)

Holomorphic for "left-moving" and anti-holomorphic  
 "right-moving"

The holomorphic derivatives are:

$$\partial_z = \partial = \frac{1}{2}(\partial_1 - i\partial_2)$$

$$\partial_{\bar{z}} = \bar{\partial} = \frac{1}{2}(\partial_1 + i\partial_2)$$

- $\partial_z \partial_{\bar{z}} = \bar{\partial} \partial_{\bar{z}} = 1$

- $\partial_z \partial_{\bar{z}} = \bar{\partial} \partial_{\bar{z}} = 0$

We will usually work in Flat, Euclidean

space:  $ds^2 = (d\partial^1)^2 + (d\partial^2)^2 = dz d\bar{z}$

$$\Rightarrow g_{zz} = g_{\bar{z}\bar{z}} = 0$$

$$g_{z\bar{z}} = g_{\bar{z}z} = \frac{1}{2}$$

The measure factor is:

$$dz d\bar{z} = 2db^1 db^2$$

Define delta-fn:  $\int d^2 z \delta(z, \bar{z}) = 1$

Also:  $\int d^2 b \delta(b) = 1$

meaning  $\delta(b) = 2 \delta(z, \bar{z})$  (I think. Might be  $\frac{1}{2}$ ).

Contravariant vectors:  $v^{\bar{z}} = v^1 + i v^2$

$$v^{\bar{z}} = v^1 - i v^2$$

Covariant:  $v_z = \frac{1}{2} (v^1 - i v^2)$

$$v_{\bar{z}} = \frac{1}{2} (v^1 + i v^2)$$

In Flat Euclidean space, complex coordinates, conformal  $\chi$ -forms are any holomorphic change of coordinates:

$$z \rightarrow z' = F(z), \quad \bar{z} \rightarrow \bar{z}' = \bar{F}(\bar{z})$$

$$\text{Then } ds^2 = dz d\bar{z} \rightarrow \left| \frac{df}{dz} \right|^2 dz d\bar{z}$$

- $\forall$  Infinite number of conformal  $\chi$ -forms  
 $\rightarrow$  special to 2D CFTs

In higher dimensions, space of conformal  $\chi$ -forms is finite-dimensional group.

- \* For a  $\mathbb{R}^{p,q}$  theory, the conformal group is  $SO(p+1, q+1)$  when  $p+q > 2$ . \*

Some simple + important examples:

- $z \rightarrow z + a$ ; translation
- $z \rightarrow \zeta z$ 
  - if  $|\zeta| = 1$ , rotation
  - if  $\zeta \neq 1$ ,  $\zeta \in \mathbb{R}$ , then scale x-form aka dilatation
- If we treat  $z, \bar{z}$  as independent variables (i.e.  $\bar{z}$  is not defined as  $\bar{z} = z^*$ ), we extend the worldsheet from  $\mathbb{R}^2 + \mathbb{C}^2$ .
  - Just recall that at the end of the day, we're sitting on the real slice  $\mathbb{R}^2 \subset \mathbb{C}^2$  defined by  $\bar{z} = z^*$ .

### 4.1.1 : Stress-Energy Tensor

Aka energy-momentum tensor

\* "Defined in the usual way as the matrix of conserved currents which arise from translational invariance"

$$\rightarrow \delta \sigma^\alpha = \epsilon^\alpha \quad (\text{i.e. } \delta^\alpha \rightarrow \delta^\alpha + \epsilon^\alpha)$$

$$\rightarrow \delta S = \int d^2\delta J^\alpha \partial_\alpha \epsilon, \text{ for some function of the } \underline{\text{fields}} \ J^\alpha$$

•  $\delta S$  must be zero when  $\epsilon$  constant; this is the definition of  $\Rightarrow$  symmetry.

•  $\delta S=0$  also when EOMs obeyed, for all variations of  $\epsilon(\delta)$ . So when EOMs obeyed:

$\partial_\alpha J^\alpha = 0$ ,  $J^\alpha$  is the conserved current.

Let's see this for translational invariance:

- Promote  $t$  to a fn. of coordinates/worldsheet variables:  $\epsilon^\alpha = \epsilon^\alpha(b)$
- Then translation given by  $\delta b^\alpha = \epsilon^\alpha(b)$ .
  - Under a dynamical metric, this is a diffeomorphism (recall, we're assuming theory is invariant under  $x$ -form), so the change:  $\delta g_{AB} = \partial_A \epsilon_B + \partial_B \epsilon_A$  leaves theory unchanged.
- So in a fixed metric, change in action is opposite to what we get if we just change the metric (since both changes together give an invariant action).

$$\text{Thus: } S = \int d^2\sigma J^\alpha \partial_\alpha \epsilon$$

should technically be  $\frac{\delta S}{\delta g^{\alpha\beta}}$

$$= -S d^2\sigma \frac{\partial S}{\partial g_{\alpha\beta}} \delta g^{\alpha\beta} = -2 S d^2\sigma \frac{\partial S}{\partial g_{\alpha\beta}} \partial_\alpha \epsilon_\beta$$

The conserved current is  $J_\alpha = -2 \frac{\partial S}{\partial g^{\alpha\beta}}$

Add a normalization (standard in string theory, not necessarily others) to get the

stress-energy tensor.

$S$  as in the density,  
the one inside the integral  
of  $S$

$$\star T_{\alpha\beta} = -\frac{4\pi}{\sqrt{g}} \frac{\partial S}{\partial g^{\alpha\beta}} \quad (4.4)$$

Recall the "usual definition": "The matrix of conserved currents which arise from translational invariance".

In flat space:  $\partial^\alpha T_{\alpha\beta} = 0$

In curved space:  $\nabla^\alpha T_{\alpha\beta} = 0$  (covariantly conserved)

\* Stress-Energy Tensor is Traceless in a CFT.

(consider scale  $\chi$ -form (special case of conformal  $\chi$ -form))

$$\delta g_{\alpha\beta} = \epsilon g_{\alpha\beta}$$



$$\delta S = \int d^2\delta \frac{\partial S}{\partial g_{\alpha\beta}} \delta g_{\alpha\beta}$$



Partial w.r.t. contravariant is covariant

Partial w.r.t. covariant is contravariant

$$\delta S = \int d^2\delta \left( -\frac{\sqrt{g}}{4\pi} T^{\alpha\beta} \right) (\epsilon g_{\alpha\beta})$$

$$= -\frac{1}{4\pi} \int d^2\delta \sqrt{g} \epsilon T^2$$

CFT invariant under such  $\chi$ -forms meaning

$$\delta S = 0 \Rightarrow T^2 = 0, T_{\alpha\beta} \text{ traceless}$$

Many theories have traceless  $T_{\alpha\beta}$  at classical level, but this often fails at quantum level.

"Technically the difficulty arises due to the need to introduce a scale when regulating the theories"

\* "We will be interested in 2D theories that succeed in preserving conformal symmetry at quantum level".

\* "Looking ahead: Even when the conformal invariance survives in a 2D quantum theory, the vanishing trace  $T^{\alpha}_{\alpha} = 0$  will only turn out to hold in flat space. We will derive this result in 4.4.2".

In complex coordinates

$$T_{\alpha}^{\alpha} = 0 \rightarrow T_{z\bar{z}} = 0$$

$$\partial T^{z\bar{z}} = 0$$

"conservation eqn."  $\partial_z T^{\alpha\beta} = 0 \rightarrow \begin{cases} \bar{\partial} T_{zz} = 0 \\ \partial T_{\bar{z}\bar{z}} = 0 \\ \bar{\partial} T^{\bar{z}\bar{z}} = 0 \end{cases}$

In other words,  $T_{zz} = T_{zz}(z)$  is holomorphic  
 $T_{\bar{z}\bar{z}} = T_{\bar{z}\bar{z}}(\bar{z})$  is anti-holomorphic

Simplified notation moving forward:

$$T_{zz}(z) = T(z), \quad T_{\bar{z}\bar{z}}(\bar{z}) \equiv \bar{T}(\bar{z})$$

skimming 4.1.2 : Noether currents, invariance of  $T$   
under independent x-forms of  $z, \bar{z}$

\* First two lines of 4.6 important for learning how

$$\delta g^{\alpha\beta} = \alpha^\alpha \delta g^\beta_\alpha$$

## H.I.2: Noether Currents

$T_{\alpha\beta}$  provides Noether currents for translation

How about other conformal  $x$ -forms?

Consider  $z' = z + \varepsilon(z)$ ,  $\bar{z}' = \bar{z} + \bar{\varepsilon}(\bar{z})$

$\varepsilon = \text{constant} \rightarrow \text{translation}$

$\varepsilon \sim z \rightarrow \text{rotation, dilatation}$

First promote  $\varepsilon(z) \rightarrow \varepsilon(z, \bar{z})$  (so it depends on the coordinates. Not just scales with the coordinate  $z$  or  $\bar{z}$ ).

$$\Rightarrow \delta S = - \int d^2\sigma \sqrt{g} \frac{\partial S}{\partial g^{\alpha\beta}} \delta g^{\alpha\beta}$$

$\downarrow$

$$= - \frac{1}{4\pi} T_{\alpha\beta} \quad = 2 \delta^\alpha \varepsilon^\beta \text{ because } g^{\alpha\beta} \text{ symmetric}$$

$\downarrow$

$$= 2 \delta^\alpha \delta^\beta$$

$\swarrow$

$$= \frac{1}{2\pi} \int d^2\sigma T_{\alpha\beta} (\delta^\alpha \delta^\beta)$$

Important take away from 4.1.2:

Noether currents of conformal  $\chi$ -forms

are proportional to the stress-energy tensor

\* For  $\delta z = \epsilon(z)$ ,  $\delta \bar{z} = 0$

$$\hookrightarrow J^z = 0, \quad J^{\bar{z}} = T_{zz}(z) \epsilon(z) \equiv T(z) \epsilon(z)$$

For  $\delta z = 0$ ,  $\delta \bar{z} = \bar{\epsilon}(\bar{z})$

$$\hookrightarrow \bar{J}^z = \bar{T}(\bar{z}) \bar{\epsilon}(z), \quad \bar{J}^{\bar{z}} = 0$$

### 4.1.3 Example: Free Scalar Field

$$X = X(\sigma), \quad S = \frac{1}{4\pi d^1} \int d^2\sigma \partial_\mu X \partial^\mu X$$

(No minus sign because Euclidean signature)

1. Check if conformal.

Consider rescaling:  $\sigma^\alpha \rightarrow \lambda \sigma^\alpha$

Viewed as an active  $x$ -form, coordinates remain fixed but value of field  $X$  at  $\sigma$  gets moved to point  $\lambda \sigma$ . Meaning:

$$X(\sigma) \rightarrow X(\lambda^{-1}\sigma)$$

$$\begin{aligned} \frac{\partial X(\sigma)}{\partial \sigma^\alpha} &\rightarrow \frac{\partial X(\lambda^{-1}\sigma)}{\partial \sigma^\alpha} = \frac{\partial (\lambda^{-1}\sigma^\alpha)}{\partial \sigma^\alpha} \frac{\partial X(\lambda^{-1}\sigma)}{\partial (\lambda^{-1}\sigma^\alpha)} \\ &= \frac{1}{\lambda} \frac{\partial X(\tilde{\sigma})}{\partial \tilde{\sigma}} \quad \text{where } \tilde{\sigma} = \lambda^{-1}\sigma \end{aligned}$$

$$\frac{\partial X(\sigma)}{\partial \sigma^\alpha} \rightarrow \frac{1}{\lambda} \frac{\partial X(\tilde{\sigma})}{\partial \tilde{\sigma}}$$

$$\text{Also } d^2\delta = d^2(\lambda x^\alpha \delta) = d^2(\lambda \tilde{\gamma}) = \lambda^2 d^2\tilde{\gamma}$$

$$\Rightarrow S = \frac{1}{4\pi\alpha'} \int d^2\delta \partial_\alpha X \partial^\alpha X$$

$$\rightarrow \tilde{S} = \frac{1}{4\pi\alpha'} \int d^2\tilde{\gamma} \partial_\alpha X \partial^\alpha X$$

Note that any polynomial interaction term for  $X$  would thus break conformal invariance.

Since  $\delta_0 \in (-\infty, \infty)$  OR  $(0, \infty)$

And  $\delta_1 \in (-\infty, \infty)$ , then the limits of integration are the same. This means  $S = \tilde{S}$ , the action is invariant under the generalized conformal x-form  $\Rightarrow$  theory is conformal!!!

Probably the more rigorous way to do this is explicit evaluation of  $S$ . But we're on a tight schedule.

$$2. T_{\alpha B} = - \frac{4\pi}{\sqrt{g}} \frac{\partial S}{\partial g^{\alpha B}}, \quad S = \frac{1}{4\pi\alpha'} \int d^2\theta \partial_\alpha X \partial^\alpha X$$

$\sqrt{g}$  always implicit

$$S = \frac{1}{4\pi\alpha'} \int d^2\theta \sqrt{g} \partial_\alpha X \partial^\alpha X$$

$$\text{"S"} = \frac{1}{4\pi\alpha'} \sqrt{g} \partial_\alpha X \partial^\alpha X$$

$$T_{\alpha B} = - \frac{4\pi}{\sqrt{g}} \frac{\partial \text{"S"} }{\partial g^{\alpha B}}$$

$$\sqrt{g} = \sqrt{g_{\alpha B} g^{\alpha B}} = \sqrt{\begin{bmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 6 \end{bmatrix} \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix}}$$

$$= \sqrt{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}} = \sqrt{1} = 1$$

$$T_{\alpha B} = -4\pi \frac{\partial \text{"S"} }{\partial g^{\alpha B}} = -4\pi \frac{\partial}{\partial g^{\alpha B}} \left( \frac{1}{4\pi\alpha'} \sqrt{g} \partial_\alpha X \partial^\alpha X \right)$$

$$= - \frac{1}{\alpha'} \frac{\partial}{\partial g^{\alpha B}} \left( \sqrt{g} \partial_\alpha X \partial^\alpha X \right)$$

$$\begin{aligned}
T_{\alpha B} &= -\frac{1}{\alpha'} \frac{\partial}{\partial g^{\alpha B}} \left( \sqrt{g^{M\bar{N}} g_{M\bar{N}}} \partial_\alpha X g^{\alpha\bar{P}} \partial_{\bar{P}} X \right) \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X \frac{\partial}{\partial g^{\alpha B}} \left( g^{\alpha\bar{P}} \sqrt{g^{M\bar{N}} g_{M\bar{N}}} \right) \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X \left( \frac{\partial g^{\alpha\bar{P}}}{\partial g^{\alpha B}} \sqrt{g^{M\bar{N}} g_{M\bar{N}}} + g^{\alpha\bar{P}} \frac{\partial}{\partial g^{\alpha B}} \sqrt{g^{M\bar{N}} g_{M\bar{N}}} \right) \\
&\quad \star \text{ Carroll II 4.69} \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X \left[ \delta_{\beta}^{\bar{P}} \sqrt{g} + g^{\alpha\bar{P}} \left( -\frac{1}{2} \sqrt{g} g_{\alpha B} \right) \right] \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X \left[ \delta_{\beta}^{\bar{P}} - \frac{1}{2} g^{\alpha\bar{P}} g_{\alpha B} \right] \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X \delta_{\beta}^{\bar{P}} + \frac{1}{2} \frac{1}{\alpha'} \partial_\alpha X \partial_{\bar{P}} X g^{\alpha\bar{P}} g_{\alpha B} \\
&= -\frac{1}{\alpha'} \partial_\alpha X \partial_B X + \frac{1}{2} \frac{1}{\alpha'} \partial_\alpha X \partial^\alpha X g_{\alpha B} \\
&\quad \downarrow \qquad \qquad \qquad \text{in flat Euclidean space} \\
&\quad = \delta_{\alpha B} \text{ in flat Euclidean space}
\end{aligned}$$

$\star 4.9:$   $T_{\alpha B} = -\frac{1}{\alpha'} \left[ \partial_\alpha X \partial_B X - \frac{1}{2} (\partial X)^2 \delta_{\alpha B} \right]$

3. Check  $T_{\alpha}^{\alpha} = 0$

$$T_{\alpha}^{\alpha} = -\frac{1}{2} \left( \partial_{\alpha} X \partial^{\alpha} X - \frac{1}{2} g_{\alpha}^{\alpha} (\partial X)^2 \right)$$

$$= -\frac{1}{2} \left[ \partial_0 X \partial^0 X - \frac{1}{2} g_0^0 (\partial X)^2 \right. \\ \left. + \partial_1 X \partial^1 X - \frac{1}{2} g_1^1 (\partial X)^2 \right] \checkmark$$

Meaning non-covariant gradient, NOT  
i.e. partial gradient  $\underline{\partial = \partial_Z}$ .

(NOT  $\partial X = \partial_Z X$ . Annoying, ik)

4. Check  $T_{\bar{z}\bar{z}} = 0$

\*  $T_{\alpha\beta} = -\frac{1}{2!} \left[ \partial_\alpha X \partial_\beta X - \frac{1}{2} (\partial X)^2 S_{\alpha\beta} \right]$  is a tensor statement, meaning either LHS or RHS transform as tensors. Therefore the statement is true in any coordinate system (so long as you're consistent in employing the correct coordinate x-forms / Jacobians).

Although partial derivatives are not tensors necessarily, in flat space they are equivalent to the covariant derivative, which is a tensor.

\* Important to be clear on choice of coordinates though. As stated, T4.9, we have:

$$\alpha \in [b_1, b_2], \beta \in [b_1, b_2] \Rightarrow \alpha' E[z, \bar{z}], \beta' E[z, \bar{z}]$$

We know this from  $S = \frac{1}{4\pi d!} \int d^2 z \partial_\alpha X \partial^\alpha X$  (not numbered, top of Tong section 4.1.3), used to define  $T_{\alpha\beta}$  as given, because the integral measure is  $d^2 z$ .

$$T_{\alpha' \beta'} = \Lambda_{\alpha'}^{\alpha} \Lambda_{\beta'}^{\beta} T_{\alpha \beta} = \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \frac{\partial x^{\beta}}{\partial x^{\beta'}} T_{\alpha \beta} \quad \text{X}$$

$$T_{z\bar{z}} = \frac{\partial b'}{\partial z} \frac{\partial b'}{\partial \bar{z}} T_{b_1 b_1} + \frac{\partial b'}{\partial z} \frac{\partial b^2}{\partial \bar{z}} T_{b_1 b_2}$$

$$+ \frac{\partial b^2}{\partial z} \frac{\partial b'}{\partial \bar{z}} T_{b_2 b_1} + \frac{\partial b^2}{\partial z} \frac{\partial b^2}{\partial \bar{z}} T_{b_2 b_2}$$

i.  $\frac{\partial b'}{\partial z} \frac{\partial b'}{\partial \bar{z}} = \frac{1}{2} \left(\frac{1}{2}\right) = \frac{1}{4}$

$$\frac{\partial b^2}{\partial z} \frac{\partial b^2}{\partial \bar{z}} = \frac{1}{2i} \left(-\frac{1}{2i}\right) = \frac{1}{4}$$

$$\Rightarrow \frac{\partial b'}{\partial z} \frac{\partial b'}{\partial \bar{z}} T_{b_1 b_1} + \frac{\partial b^2}{\partial z} \frac{\partial b^2}{\partial \bar{z}} T_{b_2 b_2} = \frac{1}{4} T^{\alpha}_{\alpha} = 0$$

because  $T_{\alpha \beta}$  traceless

$$\Rightarrow T_{z\bar{z}} = \frac{\partial b'}{\partial z} \frac{\partial b^2}{\partial \bar{z}} T_{b_1 b_2} + \frac{\partial b^2}{\partial z} \frac{\partial b'}{\partial \bar{z}} T_{b_2 b_1}$$

ii.  $T_{b_1 b_2} = -\frac{1}{2i} \left( \partial_{b_1} X \partial_{b_2} X - \frac{1}{2} \delta_{b_1 b_2} (2X)^2 \right)$

$$T_{b_1} T_{b_2} = -\frac{1}{\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right), \quad T_{b_2} T_{b_1} = -\frac{1}{\alpha'} \left( \frac{\partial X}{\partial b_2} \frac{\partial X}{\partial b_1} \right)$$



Nobody has explicitly said that the stress-energy tensor is symmetric, yet. Just so happens to be symmetric here.

$$\Rightarrow T_{z\bar{z}} = \left( \frac{\partial b_1}{\partial z} \frac{\partial b_2}{\partial \bar{z}} + \frac{\partial b_2}{\partial z} \frac{\partial b_1}{\partial \bar{z}} \right) T_{b_1 b_2}$$

$$\text{iii. } b_1 = \frac{1}{2}(z + \bar{z}), \quad b_2 = \frac{1}{2i}(z - \bar{z})$$
$$\Rightarrow T_{z\bar{z}} = \left[ \frac{1}{2} \left( -\frac{1}{2i} \right) + \frac{1}{2i} \left( \frac{1}{2} \right) \right] T_{b_1 b_2}$$
$$T_{z\bar{z}} = 0 \quad \checkmark$$

$$5. T_{\alpha' \beta'} = \frac{\partial \delta_1}{\partial x^{\alpha'}} \frac{\partial \delta_1}{\partial x^{\beta'}} T_{b_1 b_1} + \frac{\partial \delta_1}{\partial x^{\alpha'}} \frac{\partial \delta_2}{\partial x^{\beta'}} T_{b_1 b_2} \\ + \frac{\partial \delta_2}{\partial x^{\alpha'}} \frac{\partial \delta_1}{\partial x^{\beta'}} T_{b_2 b_1} + \frac{\partial \delta_2}{\partial x^{\alpha'}} \frac{\partial \delta_2}{\partial x^{\beta'}} T_{b_2 b_2}$$

2. Confirm  $T = T_{zz} = -\frac{1}{2} \partial X \partial X$

$$T_{zz} = \frac{\partial \delta_1}{\partial z} \frac{\partial \delta_1}{\partial z} T_{b_1 b_1} + \frac{\partial \delta_1}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_1 b_2} \\ + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_1}{\partial z} T_{b_2 b_1} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_2 b_2}$$

$$T_{zz} = \frac{1}{4} \left[ -\frac{1}{2} \left( \partial_{b_1} \times \partial_{b_1} \times - \frac{1}{2} (\partial X)^2 \right) \right] \\ + \frac{\partial \delta_1}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_1 b_2} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_1}{\partial z} T_{b_2 b_1} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_2 b_2} \\ = \frac{1}{4} \left[ -\frac{1}{2} \left( \partial_{b_1} \times \partial_{b_1} \times - \frac{1}{2} (\partial X)^2 \right) \right] \\ + \frac{\partial \delta_1}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_1 b_2} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_1}{\partial z} T_{b_2 b_1} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_2 b_2} \\ = \frac{1}{4} \left[ -\frac{1}{2} \left( \partial_{b_1} \times \partial_{b_1} \times - \frac{1}{2} (\partial X)^2 \right) \right] \\ + \left(\frac{1}{2}\right)\left(\frac{1}{2}\right) T_{b_1 b_2} + \left(\frac{1}{2}\right)\left(\frac{1}{2}\right) T_{b_2 b_1} + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_2 b_2} \\ = \frac{1}{4} \left[ -\frac{1}{2} \left( \partial_{b_1} \times \partial_{b_1} \times - \frac{1}{2} (\partial X)^2 \right) \right] \\ + \frac{1}{4} (T_{b_1 b_2} + T_{b_2 b_1}) + \frac{\partial \delta_2}{\partial z} \frac{\partial \delta_2}{\partial z} T_{b_2 b_2}$$

$$= \frac{1}{4} \left[ -\frac{1}{2i} \left( \partial_{b_1} X \partial_{b_1} X - \frac{1}{2} (\partial X)^2 \right) \right]$$

$$+ \frac{1}{4i} \left( T_{b_1 b_2} + T_{b_2 b_1} \right) + \frac{\partial \theta_2}{\partial z} \frac{\partial \theta_2}{\partial z} T_{b_2 b_2}$$

$$= \frac{1}{4} \left[ -\frac{1}{2i} \left( \partial_{b_1} X \partial_{b_1} X - \frac{1}{2} (\partial X)^2 \right) \right]$$

$$+ \frac{1}{4i} \left[ -\frac{1}{2i} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right) - \frac{1}{2i} \left( \frac{\partial X}{\partial b_2} \frac{\partial X}{\partial b_1} \right) \right] + \frac{\partial \theta_2}{\partial z} \frac{\partial \theta_2}{\partial z} T_{b_2 b_2}$$

$$= \frac{1}{4} \left[ -\frac{1}{2i} \left( \partial_{b_1} X \partial_{b_1} X - \frac{1}{2} (\partial X)^2 \right) \right]$$

$$- \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right) + \frac{\partial \theta_2}{\partial z} \frac{\partial \theta_2}{\partial z} T_{b_2 b_2}$$

$$= \frac{1}{4} \left[ -\frac{1}{2i} \left( \partial_{b_1} X \partial_{b_1} X - \frac{1}{2} (\partial X)^2 \right) \right]$$

$$- \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right) - \frac{1}{4} \left[ -\frac{1}{2i} \left( \partial_{b_2} X \partial_{b_2} X - \frac{1}{2} (\partial X)^2 \right) \right]$$

$$= \frac{1}{4\alpha'} \left[ - \left( \partial_{b_1} X \partial_{b_1} X - \frac{1}{2} (\cancel{\partial X})^2 \right) + \left( \partial_{b_2} X \partial_{b_2} X - \frac{1}{2} (\cancel{\partial X})^2 \right) \right]$$

$$- \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right)$$

$$= \frac{1}{4\alpha'} \left( \partial_{b_2} X \partial_{b_2} X - \partial_{b_1} X \partial_{b_1} X \right) - \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right)$$

$$= \frac{1}{4\alpha'} \left( \frac{\partial X}{\partial b_2} \frac{\partial X}{\partial b_2} - \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_1} \right) - \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right)$$

$$= \frac{1}{4\alpha'} \left[ \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_2} \right)^2 - \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_1} \right)^2 \right] - \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right)$$

$$= \frac{1}{4\alpha'} \left[ \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_2} \right)^2 - \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_1} \right)^2 \right] - \frac{1}{2i\alpha'} \left( \frac{\partial X}{\partial b_1} \frac{\partial X}{\partial b_2} \right)$$

$$= \frac{1}{4\alpha'} \left[ \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_2} \right)^2 - \left( \frac{\partial X}{\partial Z} \frac{\partial Z}{\partial b_1} \right)^2 \right] - \frac{1}{2i\alpha'} \left[ \left( \frac{\partial X}{\partial Z} \right)^2 \frac{\partial Z}{\partial b_1} \frac{\partial Z}{\partial b_2} \right]$$

$$= \frac{1}{4\alpha'} \left( \frac{\partial X}{\partial Z} \right)^2 \left[ \left( \frac{\partial Z}{\partial b_2} \right)^2 - \left( \frac{\partial Z}{\partial b_1} \right)^2 \right]$$

$$- \frac{1}{2i\alpha} \left( \frac{\partial X}{\partial Z} \right)^2 \left( \frac{\partial Z}{\partial b_2} \frac{\partial Z}{\partial b_1} \right)$$

$$= \frac{1}{4\alpha'} \left( \frac{\partial X}{\partial Z} \right)^2 \left( i^2 - 1^2 \right) - \frac{1}{2i\alpha} \left( \frac{\partial X}{\partial Z} \right)^2 (i \cdot 1)$$

$$= -\frac{2}{4\alpha'} \left( \frac{\partial X}{\partial Z} \right)^2 - \frac{1}{2\alpha} \left( \frac{\partial X}{\partial Z} \right)^2$$

$$= -\frac{1}{\alpha'} \partial X \partial X \quad \checkmark$$

Skimming 6. Derive EOM  $\partial\bar{\partial}X = 0$

7. Derive general soln. for EOM :

$$X(z, \bar{z}) = X(z) + \bar{X}(\bar{z})$$

8. Why  $T$  holomorphic,  $\bar{T}$  anti-holomorphic  
when evaluated on soln. from

# 7.

## 4.2.1: Operator Product Expansion

- Terminology: "Field" refers to both primary and derivative/"descendant" fields
  - e.g.  $\phi, \partial^\mu \phi, e^{i\phi}$
  - "In CFT the term 'field' refers to any local expression that we can write down". As opposed to QFT, where it only refers to primary fields.
- "The OPE is a statement about what happens as local operators approach each other. The idea is that two local operators inserted at nearby points can be closely approximated by a string of operators at one of these points."



\* 4.10:

$$\langle \mathcal{O}_i(z, \bar{z}) \mathcal{O}_j(w, \bar{w}) \rangle = \sum_k C_{ij}^k(z-w, \bar{z}-\bar{w}) \underbrace{\langle \mathcal{O}_k(w, \bar{w}) \rangle}$$

set of  $\mathcal{O}_k$  which, because of translation invariance, depend only on the separation between the two operators.

\* 4.10 holds as an operator insertion  
Inside time-ordered functions.

$$\langle \mathcal{O}_i(z, \bar{z}) \mathcal{O}_j(w, \bar{w}) \dots \rangle = \sum_k C_{ij}^k(z-w, \bar{z}-\bar{w}) \langle \mathcal{O}_k(w, \bar{w}) \dots \rangle$$

The ... is not always explicitly written, usually implicit.

- Correlation fns always assumed to be time-ordered (or path-ordered?)

→ "This means that, as far as the OPE is concerned, everything commutes since the ordering of the operators is determined inside the correlation fn. anyway".



This seems like an oxymoron. Ask Gustavo.

- The other operator insertions are arbitrary except they should be at a large distance wrt.  $|z-w|$ .
- In a CFT the OPE is an exact statement, has "radius of convergence" equal to distance to nearest other insertion.
- OPEs have singular behavior at  $z \rightarrow w$ . This is what Hartman means

by "hitting other operator insertions  
(inside correlation functions)". This singular  
behavior will be the only thing we  
care about.  $\star$  "IT WILL TURN OUT  
TO CONTAIN THE SAME INFORMATION  
AS COMMUTATION RELATIONS, AS WELL  
AS TELLING US HOW OPERATORS  
TRANSFORM UNDER SYMMETRIES"



SINGULAR BEHAVIOR AT OPERATOR  
COLLISIONS DETERMINES THE  
ALGEBRA OF OBSERVABLES

$\star$  "Indeed, in many equations we will simply  
write the singular terms in the OPE and denote  
the non-singular terms as '+...'. "

## 4.2.2. Ward Identities

- Set of operator equations
- Like Noether's theorem but quantized, for QFTs.

"we start by considering a general theory with a symmetry. Later we will restrict to conformal symmetries".

Recall path integral  $Z = \int \mathcal{D}\phi e^{-S[\phi]}$

QFT rigorous defn. of fields. Primary fields

A symmetry of the quantum theory is st. the infinitesimal  $x$ -form:  $\phi' = \phi + \varepsilon \delta\phi$  leaves both the action and the measure invariant:  $S[\phi'] = S[\phi]$ ,  $\mathcal{D}\phi' = \mathcal{D}\phi$

"To first order, charge has to be prop. to  $\epsilon$ ":

$$\phi \rightarrow \phi + \epsilon \delta\phi$$

$$Z \rightarrow \int D\phi' \exp(-S[\phi']) \quad \downarrow \text{By definition of } S[\phi']$$

$$= \int D\phi \exp\left(-S[\phi] - \frac{1}{2\pi} \int J^\alpha \partial_\alpha \epsilon\right)$$

$$= \int D\phi e^{-S[\phi]} \left(1 - \frac{1}{2\pi} \int J^\alpha \partial_\alpha \epsilon\right) \quad \begin{matrix} \text{Taylor expand} \\ e^x, \text{ drop quad} \\ \text{order and higher} \end{matrix}$$

\* Not clear why this must be equal to  $\int D\phi e^{-S[\phi]}$  for finite number of fields. Or even maybe some cardinality of infinite number of

\* fields (e.g. for a countably infinite set, you should be able to distinguish between

$\phi$  and  $\phi'$ ).  $\leftarrow$  Ahhh, but each one still weighted appropriately by  $e^{-S[\phi]}$  or  $e^{-S[\phi']}$ ,

respectfully. I think that answers my question.

\* Also, we stated if  $\epsilon \delta\phi$  is symmetry, then action and measure invariant  $S[\phi] = S[\phi']$ ,  $D\phi' = D\phi$

$$Z \rightarrow \int D\phi e^{-S[\phi]} \left( 1 - \frac{1}{2\pi} \int J^\mu \partial_\mu \epsilon \right)$$

$$\star = \int D\phi e^{-S[\phi]}$$

$$\Rightarrow \int D\phi e^{-S[\phi]} \left( \int J^\mu \partial_\mu \epsilon \right) = 0$$

"This must hold for all  $\epsilon\dots$ "

$$\Rightarrow \langle \partial_\mu J^\mu \rangle = 0$$

"This gives the quantum version of Noether's theorem: the **vacuum expectation value** of the divergence of the  $\uparrow$  [conserved] current vanishes"

Why specifically the vacuum state?

di Francesco et al. pg. 45: "Remembering that the correlation function is the vacuum expectation value of a time-ordered product in the operator formalism"

→ Also, recall: In the UV all finite-energy states look the same. Might as well use vacuum since most tractable.

Employ the same trick for time-ordered correlation functions:

$$\langle \phi_i(b_1) \dots \phi_n(b_n) \rangle = \frac{1}{Z} \int D\phi e^{-S[\phi]} \underbrace{\phi_i(b_1) \dots \phi_n(b_n)}$$

These operators can be primary or descendant fields

Under x-form:  $\phi_i \rightarrow \phi_i + \epsilon \delta \phi_i$

Once again promote  $\epsilon \rightarrow \epsilon(\delta)$ .

$$\langle \phi_i(b_1) \dots \phi_n(b_n) \rangle \rightarrow \frac{1}{Z} \int D\phi' e^{-S[\phi']} \phi'_i(b_1) \dots \phi'_n(b_n)$$

$$e^{-S[\phi']} = \frac{1}{Z} \int D\phi' \exp(-S[\phi']) \phi'_i(b_1) \dots \phi'_n(b_n)$$

Because we chose  $\epsilon(\delta)$  to only have support away from the other operator insertions, i.e  
 $\phi_i \rightarrow \phi_i + \epsilon \delta \phi_i = \phi_i$

$$= \frac{1}{Z} \int D\phi \exp \left( -S[\phi] - \frac{1}{2\pi} \int J^\alpha \partial_\alpha \epsilon \right) \phi_i(b_1) \dots \phi_n(b_n)$$

$$\stackrel{1st \text{ order}}{\approx} \frac{1}{Z} \int D\phi e^{-S[\phi]} \left( 1 - \frac{1}{2\pi} \int J^\alpha \partial_\alpha \epsilon \right) \phi_i(b_1) \dots \phi_n(b_n)$$

Phillipe says integration by parts

still not 100% sure about switching order

$$\Rightarrow \oint D\phi e^{-S[\phi]} (\oint_{\partial J^\alpha(\varepsilon)} \partial_1(b_1) \dots \partial_n(b_n)) = 0$$

↓ holds for all  $\varepsilon$ ...

$$\Rightarrow \langle \oint_{\partial J^\alpha(b)} \partial_1(b_1) \dots \partial_n(b_n) \rangle = 0$$

For  $b$  not belonging to  $\{b_1, \dots, b_n\}$

What if  $b \in \{b_1, \dots, b_n\}$

\* See "di Francesco 2.4" notes for derivation  
of Ward identity.

As stated by Tong, the Ward identity is:

$$4.11 : -\frac{1}{2\pi} \int_{\varepsilon}^1 \oint_{\partial J^\alpha(b)} \langle \partial_1(b_1) \dots \rangle = \langle \delta \partial_1(b_1) \dots \rangle$$

over region of support for  $\varepsilon$ , i.e. where  $\varepsilon \neq 0$

As stated by Hartman H. 23.36:

$$\partial_M \langle J^M(y) \partial_1(x_1) \dots \partial_n(x_n) \rangle = \sum_i \delta(y-x_i) \langle \partial_1 \dots \delta \partial_i \dots \rangle$$

# \* Ward Identities For Conformal x-Forms

For any vector  $J^\alpha \dots$

$$\oint_{\partial E} J_\alpha \hat{J}^\alpha = \oint_{\partial E} (J_1 d\delta^2 - J_2 d\delta^1)$$

stokes      2D, Euclidean signature

$$= -i \oint_{\partial E} (J_z dz - \bar{J}_{\bar{z}} d\bar{z})$$

switch to  $z$  coordinates

Apply this to LHS of Ward identity (4.11)



$$\frac{i}{2\pi} \oint_{\partial E} dz \langle J_z(z, \bar{z}) \theta_1(\delta_1) \dots \rangle - \frac{i}{2\pi} \oint_{\partial E} d\bar{z} \langle \bar{J}_z(z, \bar{z}) \theta_1(\delta_1) \dots \rangle$$

$$= \langle \delta \theta_1(\delta_1) \dots \rangle$$

For conformal x-forms, we know  $J$  is holomorphic and  $\bar{J}$  anti-holomorphic (see Tong section 4.1.2). (Recall holomorphic  $\sim$  analytic)

which means we can use residue theorem  
for the contour integral



$$\frac{i}{2\pi} \oint_C dz J_z(z) \phi_i(b_i) = -\text{Res}[J_z \phi_i]$$

$$\frac{i}{2\pi} \oint_C d\bar{z} J_{\bar{z}}(\bar{z}) \phi_i(b_i) = -\text{Res}[J_{\bar{z}} \phi_i]$$

Employing OPE (Tong 4.10)

$$J_{\bar{z}}(z, \bar{z}) \phi_i(b_i) = \sum_k C^k(z - z(b_i), \bar{z} - \bar{z}(b_i)) \phi_k(b_i)$$

$$\text{OR} = \sum_k C^k \left( b_i - \frac{z+\bar{z}}{2}, b_i - \frac{\bar{z}-\bar{z}}{2} \right) \phi_k(z, \bar{z})$$

$$\downarrow \quad \text{For } \delta z = \epsilon(z)$$

$$\underbrace{\delta \phi_i(b_i)}_{=} = -\text{Res}[J_z(z) \phi_i(b_i)] = -\text{Res}[\epsilon(z) T(z) \phi_i(b_i)]$$

Not sure how this equal to  $J_z \phi_i$ . Possibly:  $\delta \phi = \phi' - \phi$

In general: if we know OPE between an operator and the stress-tensors  $T(z), \bar{T}(\bar{z}),$

we know how the operator transforms under conformal symmetry.

Shouldn't this word be  $x$ -form?

Alternatively, if we know how it transforms then we know at least part of its OPE with  $T$  and  $\bar{T}$ .

To understand why

$$J(z)\theta_1(w, \bar{w}) = -\text{Res}[J_z\theta_1] = \dots + \frac{\text{Res}[J_z\theta_1(w, \bar{w})]}{z-w} + \dots$$

Re-read residue theorem in Boas.

Possibly something to do with principal term in Laurent expansion.

\* Maybe ask Gustavo:

The residue is the principal term in the Laurent expansion

\* Important definition:

" An operator  $\theta$  is said to have

weight  $(h, \tilde{h})$  if, under  $\delta z = \epsilon z$  and

$\delta \bar{z} = \epsilon \bar{z}$ ,  $\theta$  transforms as

$$\delta \theta = -\epsilon(h\theta + z\partial_z\theta) - \bar{\epsilon}(\tilde{h}\theta + \bar{z}\partial_{\bar{z}}\theta)$$

\* Both  $h$  and  $\tilde{h}$  are real numbers.

\* In a unitary CFT,  $h, \tilde{h} \geq 0$  for all operators.

\* Recall spin is the eigenvalue under

$$\text{rotation: } s = h - \tilde{h}$$

\* Recall scaling dimension is  $\Delta = h + \tilde{h}$

\* Recall rotations are implemented (generated?) by the angular momentum operator:

$$L = -i(b^1\partial_{b^2} - b^2\partial_{b^1})$$

And scalings are generated by the dilation operator:

$$D = \delta^z \partial_z = z \partial_z + \bar{z} \partial_{\bar{z}}$$

Read up on scaling dimension

Compare transformation law,

$$4.16: S\theta = -\epsilon(h\theta + z\partial_z\theta) - \bar{\epsilon}(\bar{h}\theta + \bar{z}\partial_{\bar{z}}\theta)$$

With Ward identity,

(4.12)

$$S\theta_1(b_1) = -\text{Res}[J_z(z)\theta_1(b_1)] = -\text{Res}[\epsilon(z)T(z)\theta_1(b_1)]$$

Keeping in mind the Noether current due to rotation + scaling  $S\bar{z} = \epsilon\bar{z}$

$$4.7: J^z = 0, J^{\bar{z}} = T_{zz}(z)\epsilon(z) \equiv T(z)\epsilon(z)$$

(From  $S\bar{z} = \epsilon\bar{z}$  we get  $\bar{J}^{\bar{z}} = 0, \bar{J}^z = \bar{T}(\bar{z})\bar{\epsilon}(\bar{z})$ )

The residue of the  $T\bar{O}$  OPE will determine the  $\frac{1}{z^2}$  terms in the  $T\bar{O}$  OPE. From transformation law, we know the OPE between  $T$  and operator  $O$  with weight  $(h, \tilde{h})$  must take the form: Very important for Hartman 4.4.2: Weyl

$$T(z) O(w, \bar{w}) = \dots + h \frac{O(w, \bar{w})}{(z-w)^2} + \frac{\partial O(w, \bar{w})}{z-w}$$

Toog bottom of pg. 75

Residue only due to the principal term

right?

$$\bar{T}(\bar{z}) O(w, \bar{w}) = \dots + \tilde{h} \frac{O(w, \bar{w})}{(\bar{z}-\bar{w})^2} + \frac{\bar{T}O(w, \bar{w})}{\bar{z}-\bar{w}}$$

A primary operator is one whose OPE with  $T$  and  $\bar{T}$  has no higher singularities than  $(z-w)^{-2}$  or  $(\bar{z}-\bar{w})^{-2}$ , respectively.

For a primary operator,

$$T(z)\theta(w, \bar{w}) = h \frac{\theta(w, \bar{w})}{(z-w)^2} + \frac{\partial\theta(w, \bar{w})}{z-w} + \text{non-singular}$$

$$\bar{T}(\bar{z})\theta(w, \bar{w}) = \bar{h} \frac{\theta(w, \bar{w})}{(\bar{z}-\bar{w})^2} + \frac{\bar{\partial}\theta(w, \bar{w})}{\bar{z}-\bar{w}} + \text{non-singular}$$

Since we know all the singularities in the OPE <sup>of a primary operator</sup>, we can reconstruct the  $x$ -form of the operator under all conformal  $x$ -forms:

Focusing on just  $\delta z = \epsilon(z) \dots$

$$\delta\theta(w, \bar{w}) = -\text{Res}_{z=w} [\epsilon(z) T(z) \theta(w, \bar{w})]$$

w

Still not sure relation between  $\delta\theta$  and  $\theta$ . H says  $\delta\theta = \theta' - \theta$ . But not sure how to derive this expression.

$T\theta$  and  $\delta\theta$  \*singularities in OPE determine how it  $x$ -forms.

$$= -\text{Res}_{z=w} \left[ \epsilon(z) \left( h \frac{\theta(w, \bar{w})}{(z-w)^2} + \frac{\partial\theta(w, \bar{w})}{z-w} + \dots \right) \right]$$

↑  
Tong 4.2.2  
bottom of pg 73

For smooth, conformal  $\alpha$ -forms,  $\varepsilon(z)$  has no singularities at  $z=w$ , so it can be Taylor expanded about  $z=w$ :

$$\varepsilon(z) = \varepsilon(w) + \varepsilon'(w)(z-w) + \frac{\varepsilon''(w)}{2}(z-w)^2 + \dots$$

plugging this into the residue expression on the RHS of  $\delta\theta(w, \bar{w}) \dots$

$$\delta\theta(w, \bar{w}) = -h \varepsilon'(w)\theta(w, \bar{w}) - \varepsilon(w)\partial\theta(w, \bar{w})$$

A

Since no singularities higher than  $(z-w)^{-2}$ , the Taylor expansion ensures no singularities at all besides these 2 (since it has powers of  $(z-w)^n$  for  $n \in [0, \infty]$ )

For anti-holomorphic  $\alpha$ -form  $\delta\bar{z} = \bar{\varepsilon}(\bar{z})$ :

My guess ↓

$$\delta\theta(w, \bar{w}) = -\tilde{h} \bar{\varepsilon}'(\bar{w})\theta(w, \bar{w}) - \bar{\varepsilon}(\bar{w}) \bar{\partial}\theta(w, \bar{w})$$

That's for an infinitesimal  $x$ -form. For finite  $x$ -form  $z \rightarrow z'(z)$  and  $\bar{z} \rightarrow \bar{z}'(\bar{z})$ , just integrate up.

\* In general, the transformation of a primary operator [under conformal  $x$ -forms] is given by:

$$\theta(z, \bar{z}) \rightarrow \theta'(z', \bar{z}') = \underbrace{\left( \frac{\partial z'}{\partial z} \right)^{-h} \left( \frac{\partial \bar{z}'}{\partial \bar{z}} \right)^{-\tilde{h}}}_{T \text{ 4.18}} \theta(z, \bar{z})$$

One of our main interests for a CFT is finding the spectrum of weights  $(h, \tilde{h})$  of primary fields. This will be equivalent to computing the particle mass spectrum in a QFT. In stat. mech., the weights of primary operators are the critical exponents.

↑  
Don't know what those  
are

### 4.3 Example: Free Scalar Field

$$S = \frac{1}{4\pi\alpha'} \int d^2\sigma \partial_\alpha X \partial^\alpha X$$

Classical EOM is  $\partial^2 X = 0$  (in terms of  $\sigma$ ).

Top of pg. 83: Why must TT OPE take that form based on the weight of  $T\bar{T}$ ? ← Tong bottom of pg. 75  
These (my) notes, Pg. 41

\*  $T$  is not primary unless  $c=0$   
 $\Rightarrow$  In general this is never the case

\* Mapping between Euclidean cylinder and Euclidean plane ( $\approx$  conformal)

\*  $\frac{E}{2\pi} = -\frac{1}{12}$ , Grand state energy of free-scalar field (on a cylinder)

Funny, that's equal to  $\sum_{n=0}^{\infty} n$ !

That's exactly what Tong uses to derive the same result in section 2.2.2!

## 4.2.2.: The Weyl anomaly

"The purpose of this section is to show that:

$$\langle T_{\alpha}^{\alpha} \rangle = -\frac{c}{12} R \quad (4.35)$$

which obviously vanishes in flat space.

So, in curved space, stress-energy not necessarily traceless.

Gravitational anomaly: require  $c=\tilde{c}$ , so theory can be consistent in fixed, curved backgrounds

↑  
What about in a dynamical metric?

Why must  $c=\tilde{c}$  for "theories to be consistent", and why specifically in a fixed background?



4.4.3:  $c$  is also responsible for the density of high-energy states.

Euclidean torus (with compactified time) tells us that the high- and low-energy partition function are related.

$$\rightarrow \text{"Modular invariance": } Z\left[\frac{4\pi^2}{B}\right] = Z[B]$$

\* "In a CFT, the entropy of high-energy states is given by:

$$\text{(Cardy's formula: } S(E) \sim \sqrt{cE}$$

And the high-energy density scales as

$$S(E) \rightarrow 2\pi \sqrt{\frac{c}{6} \left( E R - \frac{c}{24} \right)} \quad (4.44)$$

\* Familiar topics Tong has touched upon:

- Central charge counts degrees of freedom, but now from an entirely new approach. Pg. 83. "This is true in a deep sense!"
- C-theorem

"We expect information is lost as we flow from a UV theory to the IR. The C-theorem makes this intuition precise"

Never thought of that: Could the C-theorem be related to the information paradox.

↳ Like I said before, it's all about

degrees-of-freedom. The inside of

a black hole has so few,

it's like a theory with very small  $c_0$  (a long way down the)

RG flow).

must be  
↳ Related to area-law  
Scaling.

"It may be that the final theory is gapped - meaning that every thing is massless"

← That's a good one. Ask Gustavo maybe.