

CE PLC Sheet 2

- We were not presented with a formal way to identify system states in the lecture

→ TA used 'State flow graphs' (drawing the state diagram as we read through the problem)

Problem 1)

- System consists of a single load, red lamp, yellow lamp with Start and Stop push buttons

Inputs

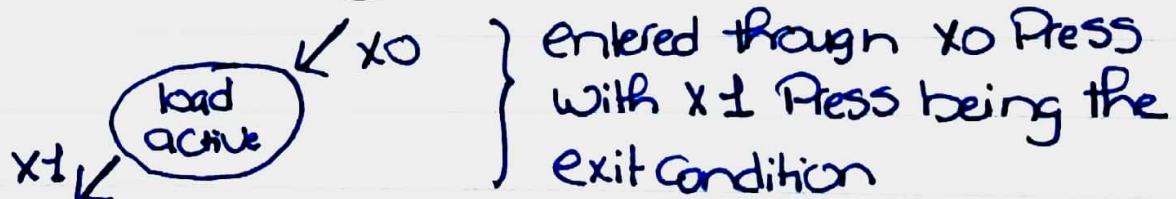
Start P.B.: x_0
Stop P.B.: x_1

Outputs

Load: y_0
Red Lamp: y_1
Yellow Lamp: y_2

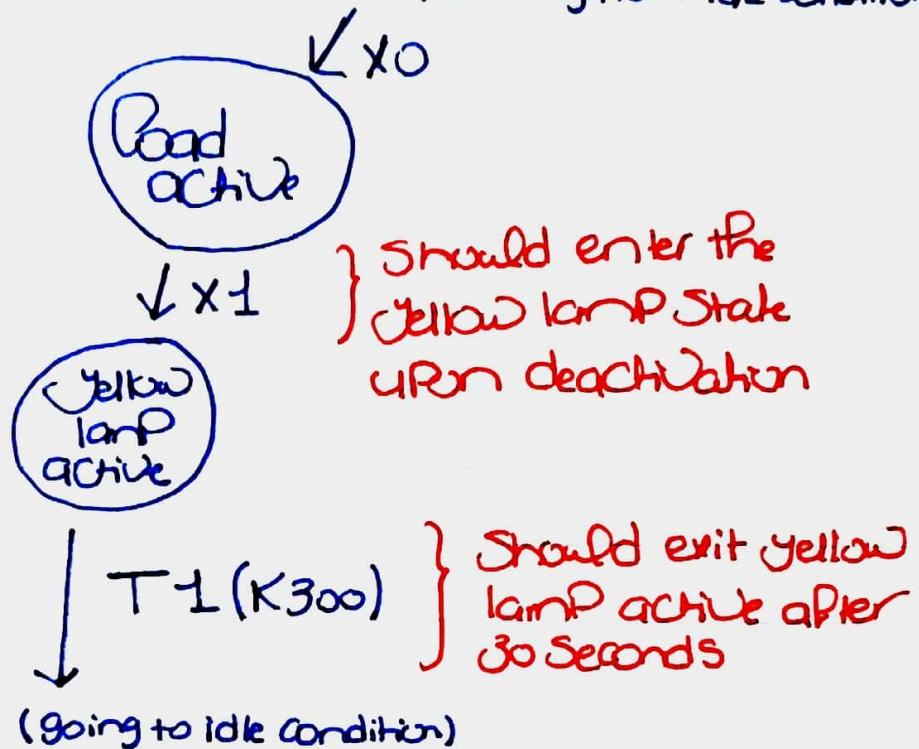
- When Start Pushbutton is Pressed, load is activated. To deactivate the load, STOP P.B. Should be Pressed (while it's active.)

→ Hence, we identify a "load active state"

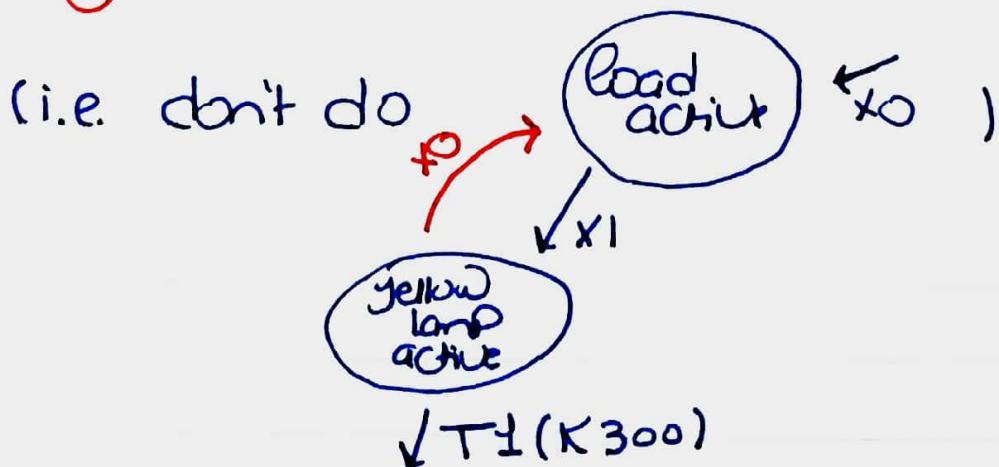


- When the load is deactivated, by Pressing STOP P.B. the yellow lamp is turned on for 30 seconds

(coming from idle condition: all states OFF)



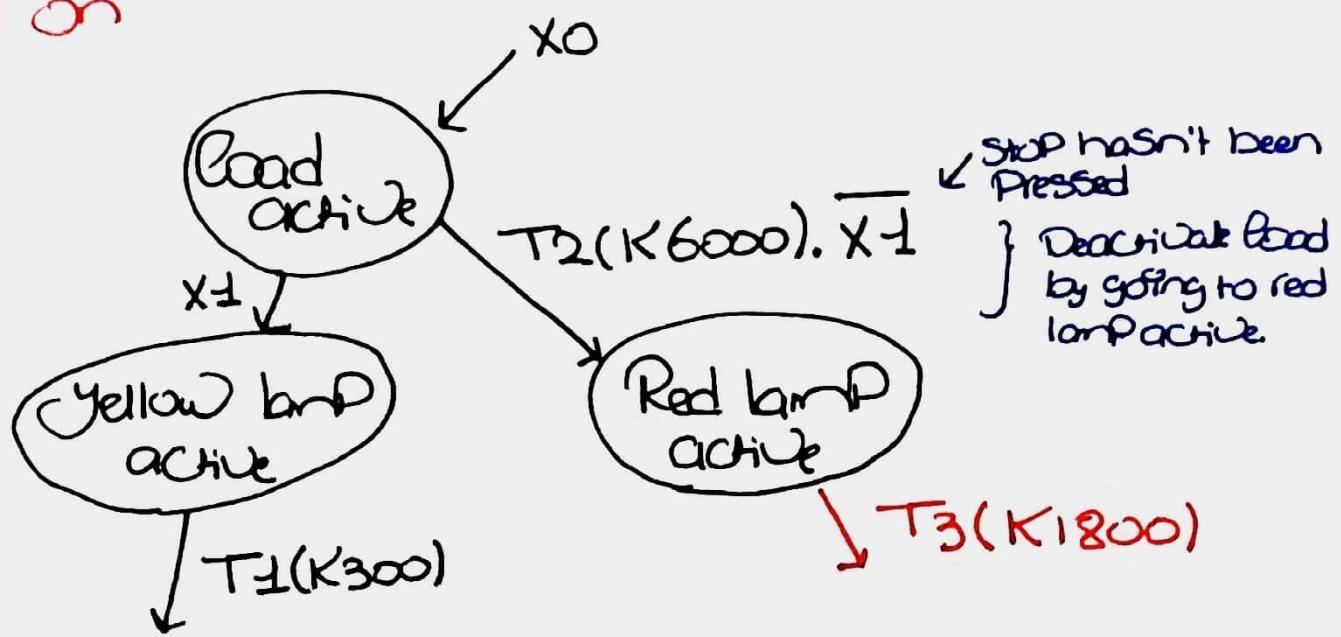
- During this Period, Can't reStart lamp



- After this delay, Yellow lamp should be turned OFF and load can be started again by START.

→ This is already satisfied by diagram (since we go to idle condition after the 30 seconds)

If the load remains active for 10 minutes and Stop has not been Pressed then load should be automatically deactivated and red lamp is turned on



- It should remain on for 3 minutes during which the load cannot be restarted \leftarrow implicitly satisfied
- After this, red lamp should be turned off and load can be started by pressing Start (satisfied as we go to the idle (initial) condition)

2) Markers:

(active, logic)

M1: Load active

M2: Yellow lamp active

M3: Red lamp active

3)

$$M_1 \equiv (X_0 \bar{M}_2 \bar{M}_3 + M_1) \cdot \bar{M}_2 \bar{M}_3$$

↓ ↓ ↓
 Start Pressed Coming From entering any of the other
 idle condition 2 = exiting this one (interlock)
 (can't activate load in 2 other states)

#Load logic

why not $\bar{X}_1 \bar{T}_2$?
 • check M_1
 in [Pec10, 10]

$$M_2 \equiv (X_1 \cdot M_1 + M_2) \cdot \bar{T}_1$$

↓ ↓ ↓
 Stop entering Go to Idle upon
 Pressed from M_1 time out (exit)
 #Yellow lamp (no new state is activated)

$$M_3 \equiv (T_2 M_1 \bar{\bar{Y}}_1 + M_3) \cdot \bar{T}_3$$

↓ ↓ ↓
 load timer entering 3 minutes Passed
 times out from Stop not
 #Red lamp M_1 Pressed

$$T_1(K_{300}) \equiv M_2 \quad (\text{Yellow lamp})$$

$$T_2(K_{6000}) \equiv M_1 \quad (\text{Load})$$

$$T_3(K_{1800}) \equiv M_3 \quad (\text{Red lamp})$$

$$Y_0 \equiv M_1$$

$$Y_1 \equiv M_3$$

$$Y_2 \equiv M_2$$

. Raster has grings with
3 self-latches (rowline)

Problem 2)

System consists of a single load, yellow lamp, red lamp with a single START/STOP P.B.

1) Inputs

Start/Stop P.B. (togg.): X0

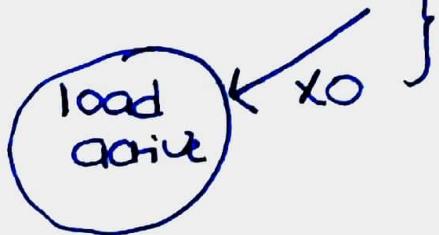
Outputs

Load: Y0

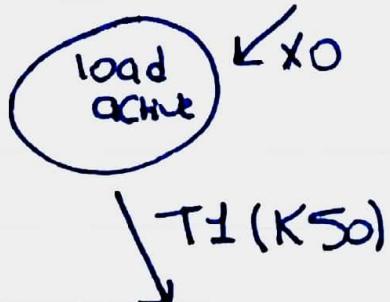
Yellow lamp: Y1

Red lamp: Y2

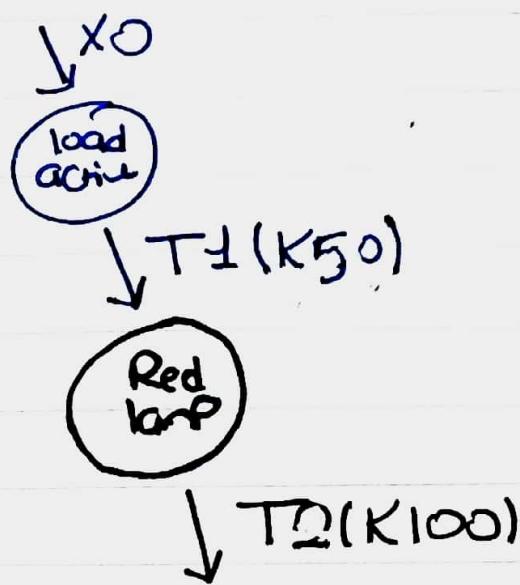
- While load isn't active and the red lamp is off, Pressing X0 activates the load
- } comes from idle, can't enter from red lamp



- While load is active if X0 is continuously pressed for 5 seconds the load is deactivated



- The yellow lamp should be turned on when X_0 is pressed while the load is active (i.e. we are still in the active load state) and turned off once X_0 is released
 - The yellow lamp output is hence $X_0 \text{N}1$ (no new state or anything, this pertains to the same load active state but triggers some output under some given condition)
- After the load is deactivated, the red lamp should be on for 10 seconds during which, the load cannot be started.



2)

Markers

 M_1 : load logic M_2 : Red Lamp logic

3)

$$M_1 \equiv (X \cdot \overline{M_2} + M_1) \cdot \overline{M_2}$$

- must be entering from idle state

- entering M_2 = exiting M_1

- simplify

$$M_2 \equiv (\overline{T_1} \cdot M_1 + M_2) \cdot \overline{T_2}$$

- coming from M_1 when its exit cond. is satisfied

- go back to idle state when T_2 times out

$$T_1 (K50) \equiv X_O \quad (\text{Press duration})$$

$$T_2 (K100) \equiv M_2 \quad (\text{red lamp duration})$$

$$Y_0 \equiv M_1$$

$$Y_1 \equiv X \cdot M_1$$

$$Y_2 \equiv M_2$$

- Buzzer has 7 rings with 2 self-latches

Problem 3)

- The Control Panel of an indicator has STEADY, FLASH, STOP Push Buttons

InPuts:

STEADY P.B.: X0

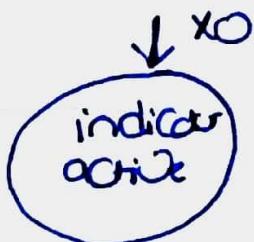
Flash P.B.: X1

STOP P.B.: X2

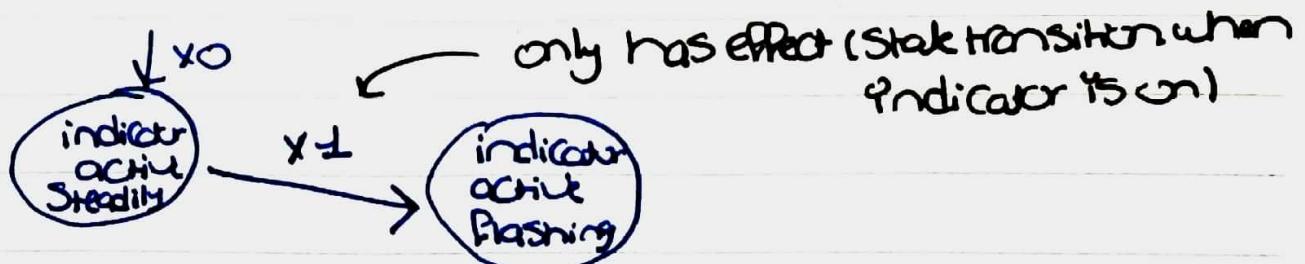
OutPuts

Indicator: Y0

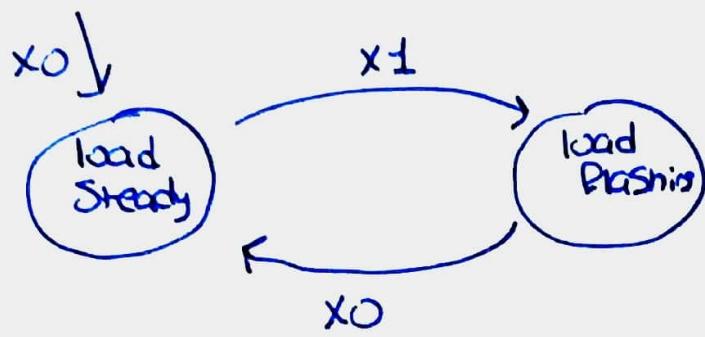
- When STEADY is Pressed, Indicator is turned on



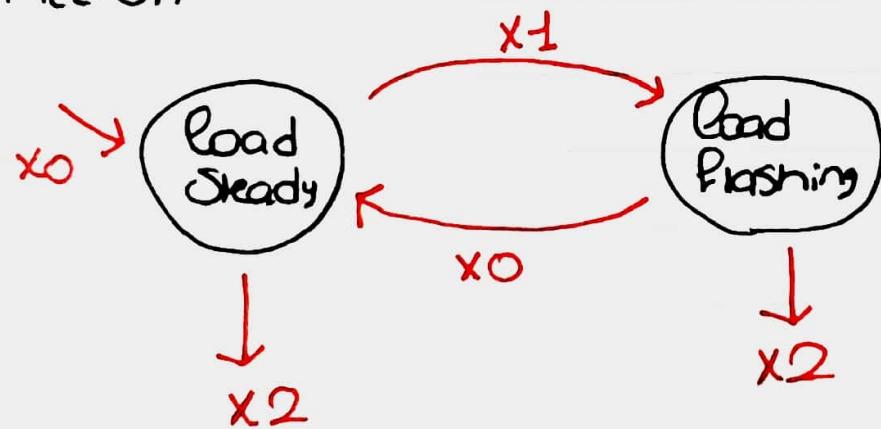
- When Flash is Pressed while Indicator is Steadily on it will Start Flashing (0.5s off and 1s on), Pressing Flash while its off should have no effect.



- If Steady is Pressed while Indicator is Flashing it becomes on Steadily



- When STOP is Pressed in either case the indicator is turned off



Markers)

M1: Load Steady logic
M2: Load Flashing logic

$$M_1 \equiv (X_0 + M_1) \cdot \overline{X_2} \cdot \overline{M_2}$$

This can't be $\overline{X_1}$
 (else would never
 enter M_2)
 • Hence, we
 interlock

↑ ↗
 STEADY Set latch
 Pressed ↓
 (coming from Idle Stop
 or Flashing is okay) (leads to idle)

→ enter Flashing
 → exit Steady

$$M_2 \equiv (X_1 \cdot M_1 + M_2) \cdot \overline{X_2} \cdot X_0$$

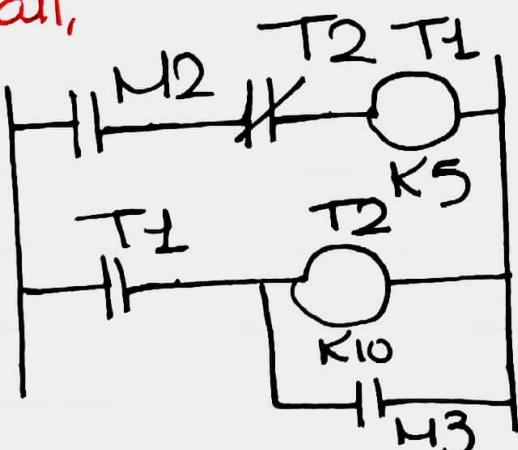
We can't have
 $\overline{M_1}$ here ($\overline{M_2}$ is
 in M_1 so M_1
 would never be
 on while $M_2 \equiv 1$)
 Thus,
 $M_2 = 0$ { 1- go from M_2 to
 Idle condition ($\overline{X_0}$)
 2- Since $X_0 = 1$, it takes
 you to $M_1 = 1$

↑ ↗
 Flash Must
 Pressed be coming
 from Steady

↓
 Stop

- Now we need to include timers to implement M_2 's Flashing logic (Output should flash as long as M_2 is high)

• Recall,



$$T_1(K5) \equiv M_2 \overline{T_2}$$

$$T_2(K10) \equiv T_1 \equiv M_3$$

- Now M_3 is what should be passed to output (driven by Flashing State M_2)

→ this should be included in main ladder diagram

Now,

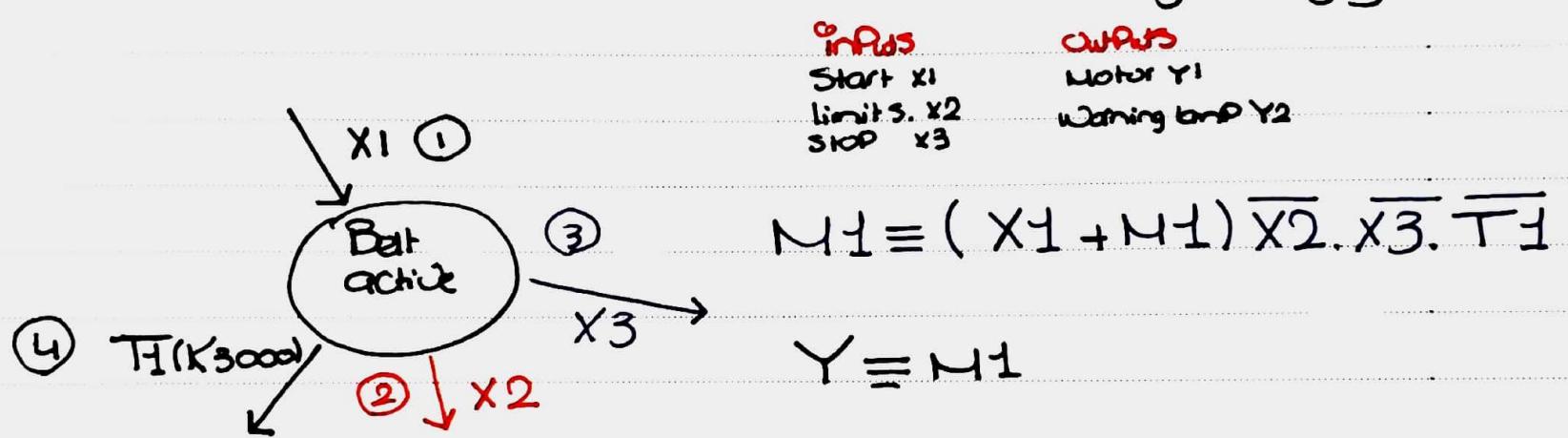
$$Y_0 \equiv M_1 + M_3$$

- and we know only one of them is ever active.

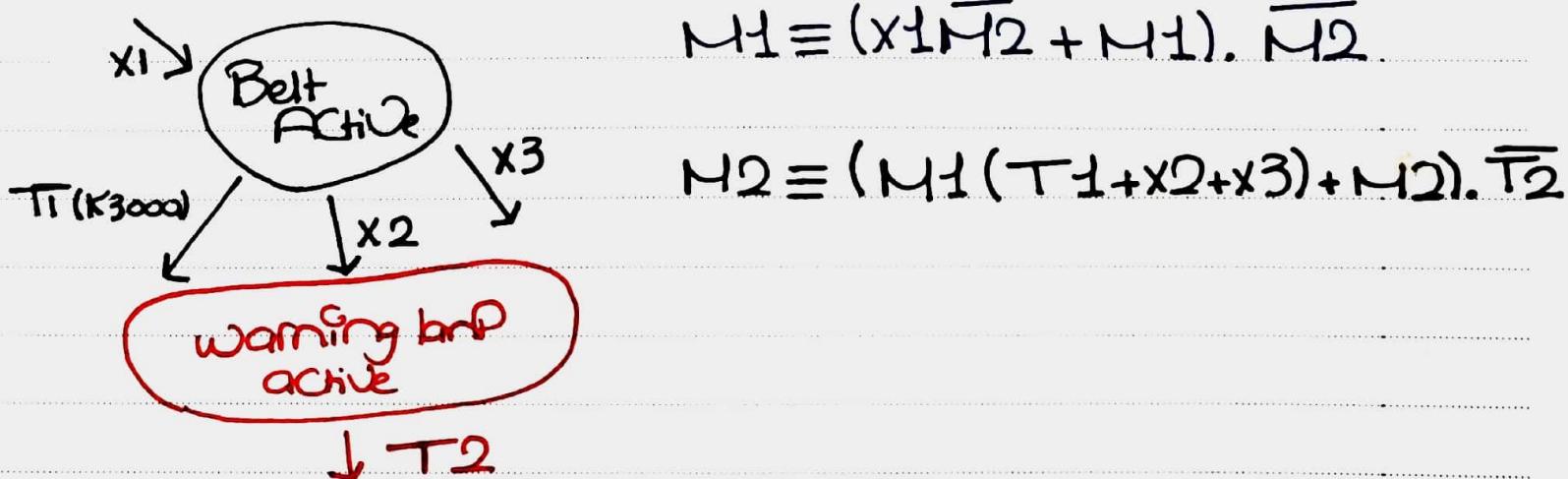
Sheet Assignment

[CE Lecture 10, 5]

- validating the method by reading then trying to draw it.



[CE Lecture 10, 8]



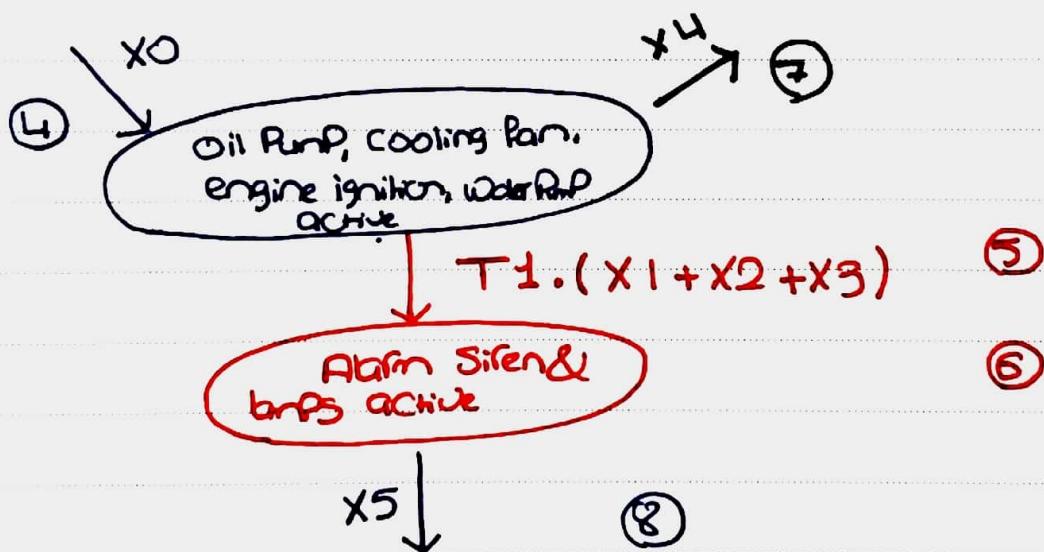
[CE Lecture 10, 12]

Inputs

Start: x_0
 Temp. Sensor: x_1
 Oil level Sensor: x_2
 Oil Pressure Sensor: x_3
 Stop: x_4
 Reset Alarm: x_5

Outputs

Oil Pump: y_1
 Cooling Fan: y_2
 Cooling Water Pump: y_3
 Engine Ignition: y_4
 Alarm Siren: y_5
 Temp. Warning Lamp: y_{11}
 Oil Level Lamp: y_{12}
 Oil Pressure Lamp: y_{13}



$$M_1 \equiv (\overline{M_2} x_0 + M_1) \cdot \overline{x_4} \cdot \overline{M_2}$$

$$M_2 \equiv (M_1 \cdot T_1 \cdot (x_1 + x_2 + x_3) + M_2) \cdot \overline{x_5}$$

$$\therefore Y_1 \equiv Y_2 \equiv Y_3 \equiv Y_4 \equiv M_1$$

$$\therefore Y_5 \equiv M_2 \quad \therefore Y_{11} \equiv (M_2 \cdot T_1 x_4 + Y_{11}) \overline{x_5}$$

* After Checking the Sol.:

→ Can be good B&F to break down big States like M_2

[CE lecture 10, 14], last point.

Similarly, y_{12} and y_{13}
 Alarm & $\begin{matrix} \nearrow bnp_1 \\ \searrow bnp_2 \\ bnp_3 \end{matrix}$