# **AVR Interfacing**

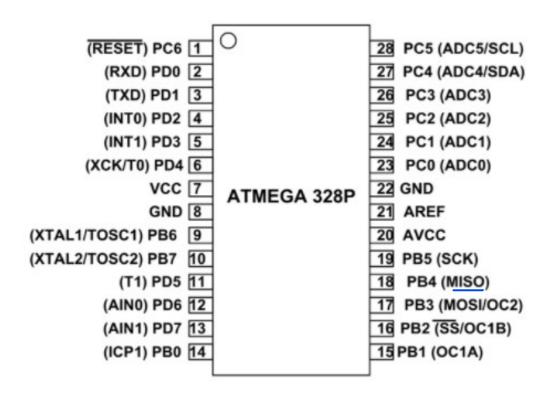
**IO Ports** 

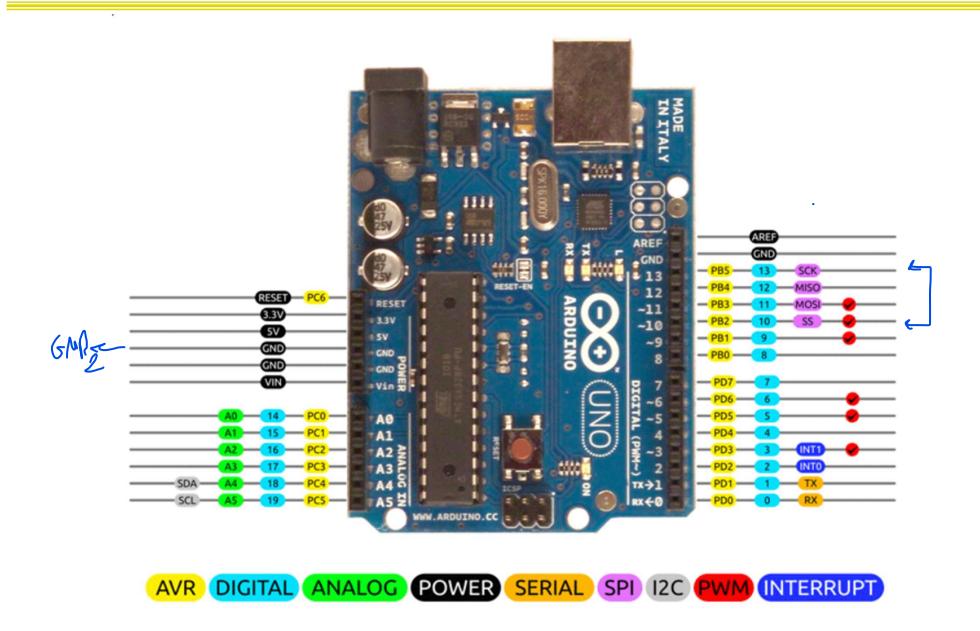
## **Agenda**

- I/O Ports.
- I/O Ports Programming.
- Interfacing with Switches and Leds.
- Interfacing with 7-Segment.
- Interfacing with DC-Motor.
- Interfacing with LCD.
- Interfacing with Keypad.

- ATmega328p has programmable I/O lines divided into:
  - ➤ PORTB(PB7.....PB0)
  - > PORTC(PCo.....PC0)
  - ➤ PORTD(PD7.....PD0)
- Each PORT is controlled by 3 registers:
  - > DDRx:
    Data Direction Register to set the pin either output or input pin.
  - PORTx
     Output Register to assign a value to the port (from μC to interface).
  - PINx:
    Input Register where it holds the input value from interface.

Note: Most pins in µC make more than one function (multiplexed functions)







Port A Data Register – PORTA

Bit	7	6	5	4	3	2	1	0	
	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	PORTA
Read/Write	R/W	RW	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

Port A Data Direction Register – DDRA

Bit	7	6	5	4	3	2	1	0	
	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	DDRA
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

Port A Input Pins Address - PINA

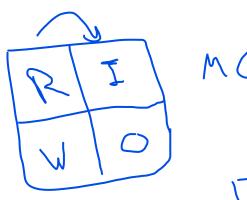
Bit	7	6	5	4	3	2	1	0	
	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	PINA
Read/Write	R	R	R	R	R	R	R	R	
Initial Value	N/A								

PiN -> mc





- To decided which Port is input and which is output:
  - Configure the port direction use register DDRX
    - $\underline{1} \rightarrow$  for Output.
    - $0 \rightarrow$  for Input.
- To Read(input case):
  - Use register PINx
- To Write(output case) :
  - Use register PORTx.





#### Note:

In case you set any PIN as **input** you can activate the **internal pull up** resistor by setting the corresponding bit in **PORTX** register.

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## **I/O Ports Programming**

## How to set values in registers



- > DDRA=5; /\*(decimal)mean I activate pin 0 and pin 2 as output and the rest as input pins \*/
- ➤ DDRB=0x14; /\*(hexadecimal)mean I activate pin 2 and pin 4 as output and the rest as input pins \*/
- ➤ DDRC=0b0000011; /\*(binary)mean I activate pin 0 and pin 1 as output pins and the rest as input pins \*/

## How to deal with a specific pin with conserving other pins

- To set specified bit in register
  Make OR operation on the register with The pin number.
  - ☐ For example if we want to set pin number 5 in PORTA

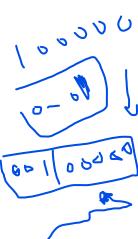
$$PORTA = PORTA \mid (1 << PA5);$$

> To clear specified bit in register

Make AND operation on the register with (NOT) The pin number.

☐ For example if we want to set pin number 3 in PORTB

$$PORTB = PORTB \& (\sim (1 << PB3));$$



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Make XOR operation on the register with The pin number

☐ For example if we want to toggle pin number 2 in PORTC

$$PORTC = PORTC \land (1 << PC2);$$



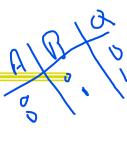
To set the pin 2 in PORTB as input pin and use the internal pull up resistor of this pin.

$$DDRB = DDRB & (\sim (1 \ll PB2))$$

$$PORTB = PORTB \mid (1 \ll PB2)$$



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```
DDRA = 0xFF; //initialize portA as output
DDRB = 0x00; //initialize portB as input
if ((PINB & 0b00000001) == 1) //read a switch on PB0
                         //All LEDs on
      PORTA = 0xFF;
else
      PORTA = 0x00; //All LEDs off
```

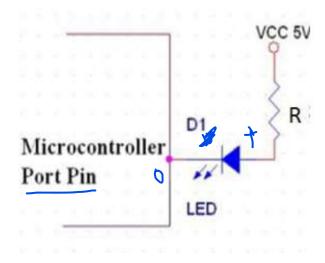
#### I/O Port applications

- As Output
  - LED and 7-Segemnt
  - LCD display
  - Motors.
  - Buzzer.
  - Signal to another μC.
  - Output to PC through PC Serial Port.
- As Input
  - Switches(push button, keypad etc.)
  - Analog/Digital sensors.
  - Signal from another μC.
  - Input from PC through PC Serial Port.

## **Interfacing with Switches and Leds**

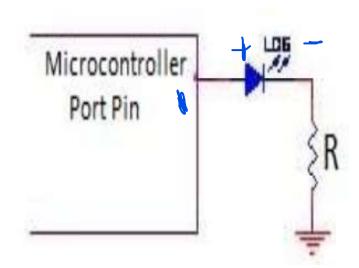
#### **LED Configuration**

#### **Negative Logic**



#### **Positive Logic**

34an el led teshtghl lazm a7ot 1





34an el led teshtghl lazm a7ot 0

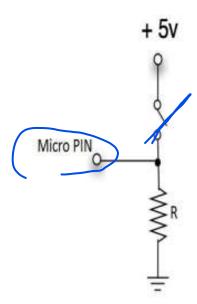
## **Interfacing with Switches and Leds**

#### **Switch Configuration**

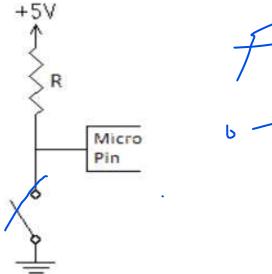


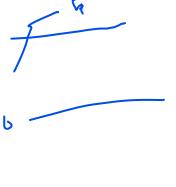


#### **Pull Down Resistor**



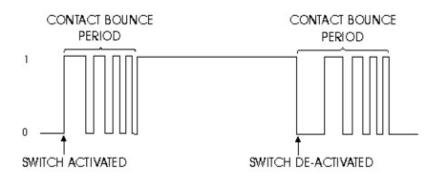
#### **Pull UP Resistor**

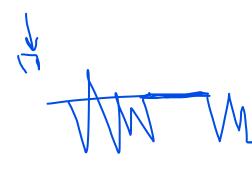




## **Interfacing with Switches and Leds**

#### Switch de-bounce problem

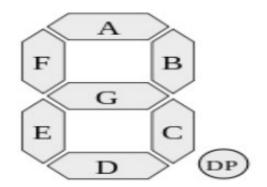


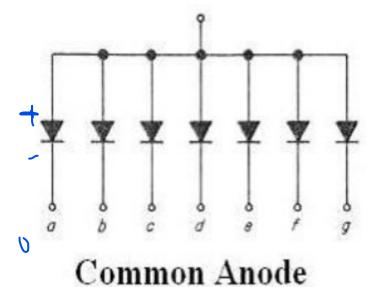


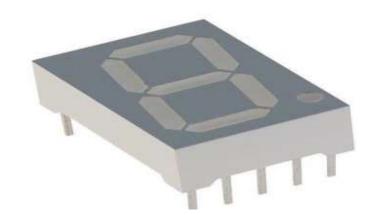
Could be handled using software or hardware.

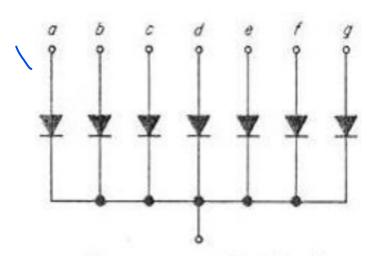
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- It relies on the fact that bouncing takes a maximum period of 20-30 ms.
- The basic idea is to implement a delay after the first detected edge, during which no scanning for the switch is done. after the delay period is finished, scanning can proceed (Exercise 3).

## **Interfacing with 7-Segment**









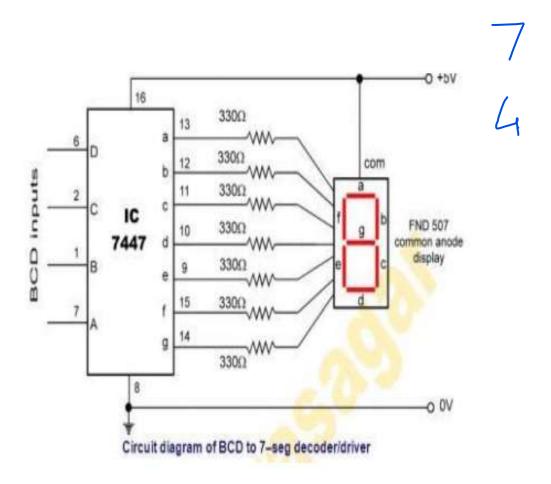
Common Cathode





## **Interfacing with 7-Segment**

In order to reduce the number of pins can be used to interface the 7 segment, we use decoder connected and follows;



Digit	Decoder inputs							
Digit	C3	C2	C1	CO				
0	0	0	0	0				
1	0	0	0	1				
2	0	0	1	0				
3	0	0	1	1				
4	0	1	0	0				
5	0	1	0	1				
6	0	1	1	0				
7	0	1	1	1				
8	1	0	0	0				
9	1	0	0	1				