



## Midterm Exam

**300 points**

290

- 45.** True or False and CORRECT when false [15 points each]:

**15a.** Lighting is performed before the viewing transformation in the 3D rendering pipeline. True

**15b.** Clipping using image-based techniques is faster than object-based techniques since it avoids computations in 3D space. Slower

*it draws many hidden things*

False.

**15c.** In parallel projection, the direction of projection (DOP) is the same for all points and parallel to the viewing direction as well as the view plane.

False

*and Perpendicular to the view plane*

- 50.** Complete the following:

**10a.** [10 points] Addition of a point and a vector = new Point while addition of two points = meaningless (nothing)

**10b.** [10 points] Viewport transformation converts from Projection's 2D coordinate to Device's 2D coordinate.

**10c.** [10 points] Clipping planes are specified by zNear and zFar

**5d.** [10 points] Parallel projection has two types; orthogonal and .....

**15e.** [15 points] In the camera model, the camera is defined by

i. Camera Position

ii. Look vector

iii. up Vector

3. [10 points] What caused vector displays to be favored in the 1970s compared to raster displays?

- no need for very high resolution
- cost memory

4. [15 points] Mention three ways to find out if a polygon is concave or not?

- vector method
- rotational method

(The line joining any two points is not completely inside the Polygon)

40. In Cohen-Sutherland line clipping algorithms, mention the condition checked on the codes of the two endpoints for:

20a. [20 points] Trivial accept

OR operation & If the two endpoint is equal to 0000

20b. [20 points] Trivial reject

And operation & If the two endpoint is not equal to 0000

25. [25 points] Simplify the transformations  $(R(\theta)S(s_x, s_y)T(t))^{-1} R(\theta)S(s_{x_2}, s_{y_2})T(t)$

$$= T(t)^{-1} S(s_{x_1}, s_{y_1}) R^{-1}(\theta) R\theta S(s_{x_2}, s_{y_2}) T(t)$$

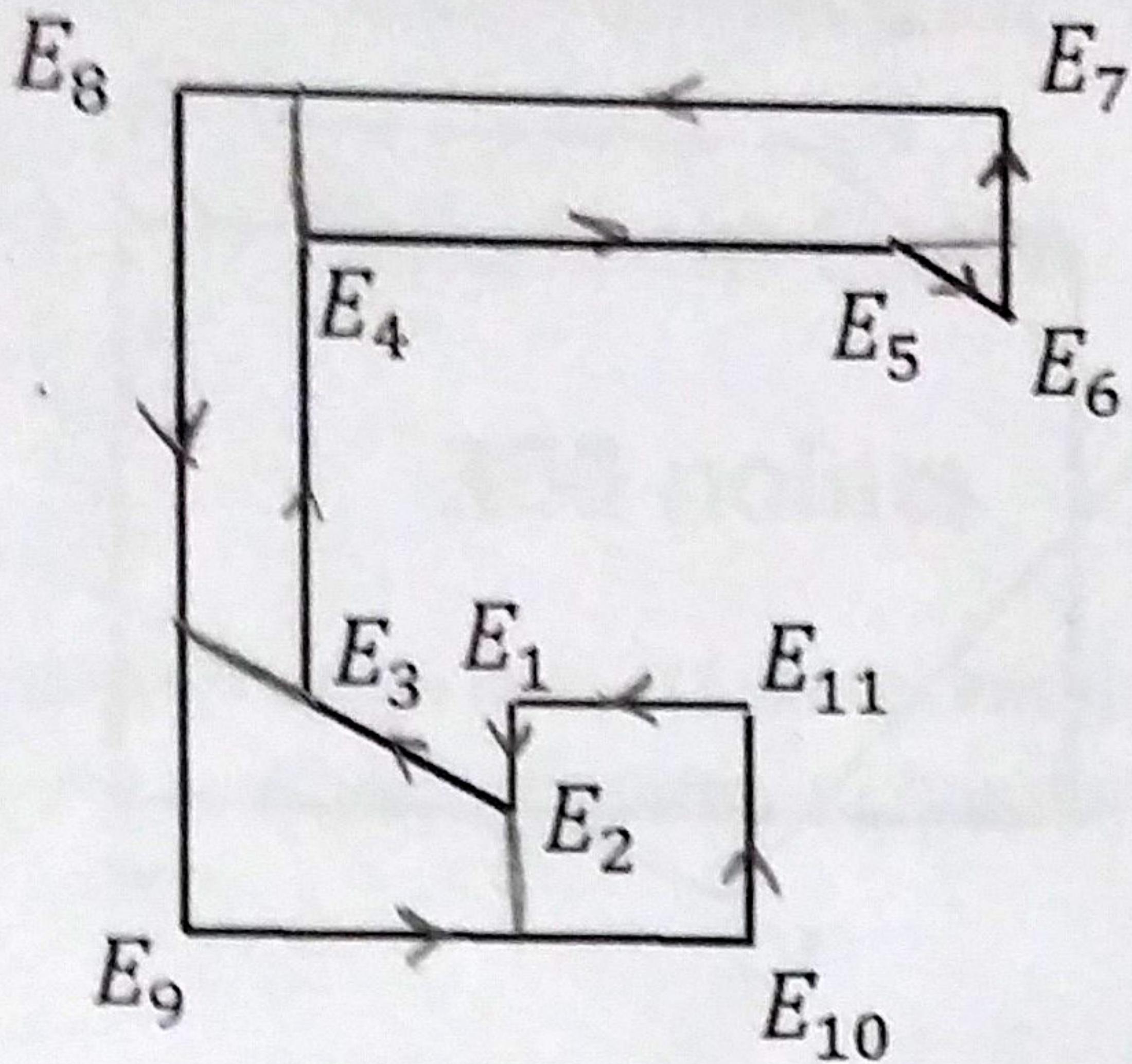
$$= T(-t) S(k_{x_1}, k_{y_1}) R(\theta) R\theta S(s_{x_2}, s_{y_2}) T(t)$$

$$= T(-t) S(k_{x_1}, k_{y_1}) S(s_{x_2}, s_{y_2}) T(t)$$

$$= T(-t) S\left(\frac{s_{x_2}}{s_{x_1}}, \frac{s_{y_2}}{s_{y_1}}\right) T(t)$$

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20. [20 points] Apply the vector method to split the following polygon. You do not need to show intermediate steps, just show the lines splitting the polygon based on processing the vertices in their order shown below.



30. [30 points] Use Bresenham's line drawing algorithm to render the line between the two endpoints  $P_1=(-2, 4)$  and  $P_2=(1, -3)$ .

$\text{oPC} \rightarrow \text{offset scaled vector} = 2dx - dy$

$$\frac{dy}{dx} = \frac{-7}{3}, \quad dx = 3$$

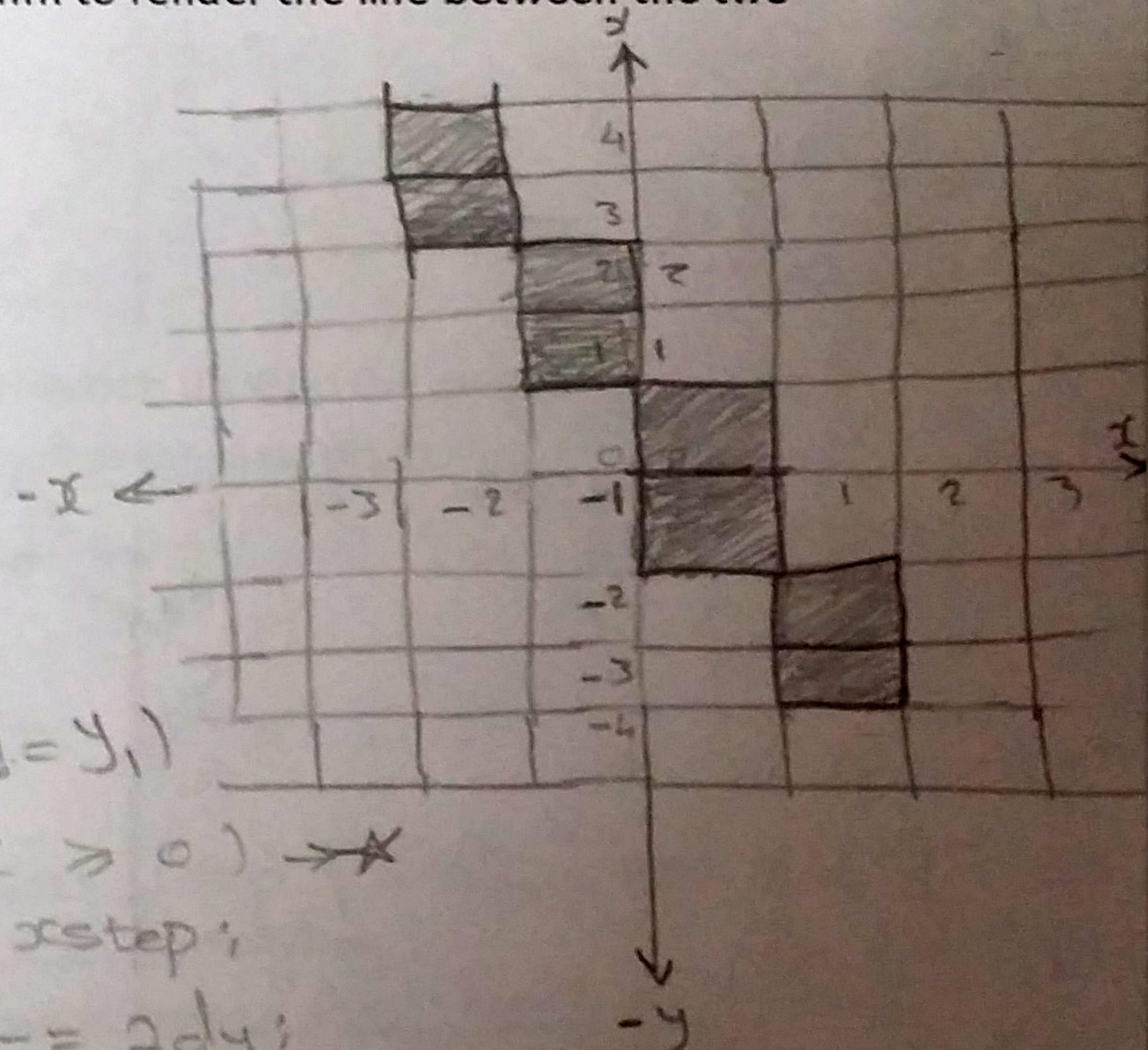
$$\text{abs}(dx) < \text{abs}(dy)$$

$\Rightarrow \text{slope} > 1$

$$y_2 < y_1 \rightarrow y\text{Step} = -1$$

$$x_2 > x_1 \rightarrow x\text{Step} = 1$$

| y  | x  | oPC      |
|----|----|----------|
| 4  | -2 | -1 → 5   |
| 3  | -2 | * 5 → -3 |
| 2  | -1 | -3 → 3   |
| 1  | -1 | * 3 → -5 |
| 0  | 0  | 5 → 1    |
| -1 | 0  | * 1 → -7 |
| -2 | 1  | -7 → -1  |
| -3 | 1  | -1 → 5   |



```

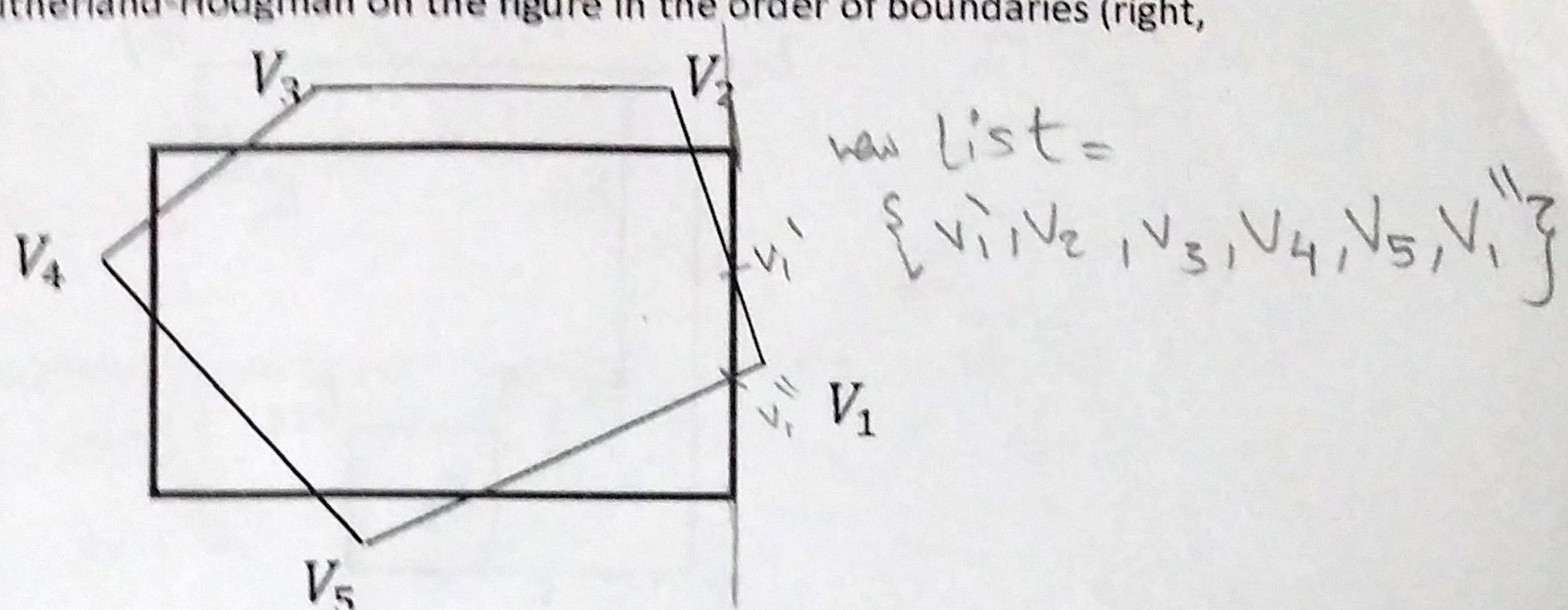
while(y != y1)
{
    if(oPC >= 0) -->
    {
        x += xstep;
        oPC -= 2dy;
    }
    oPC += 2dx
    y += ystep
    draw(x, y);
}

```

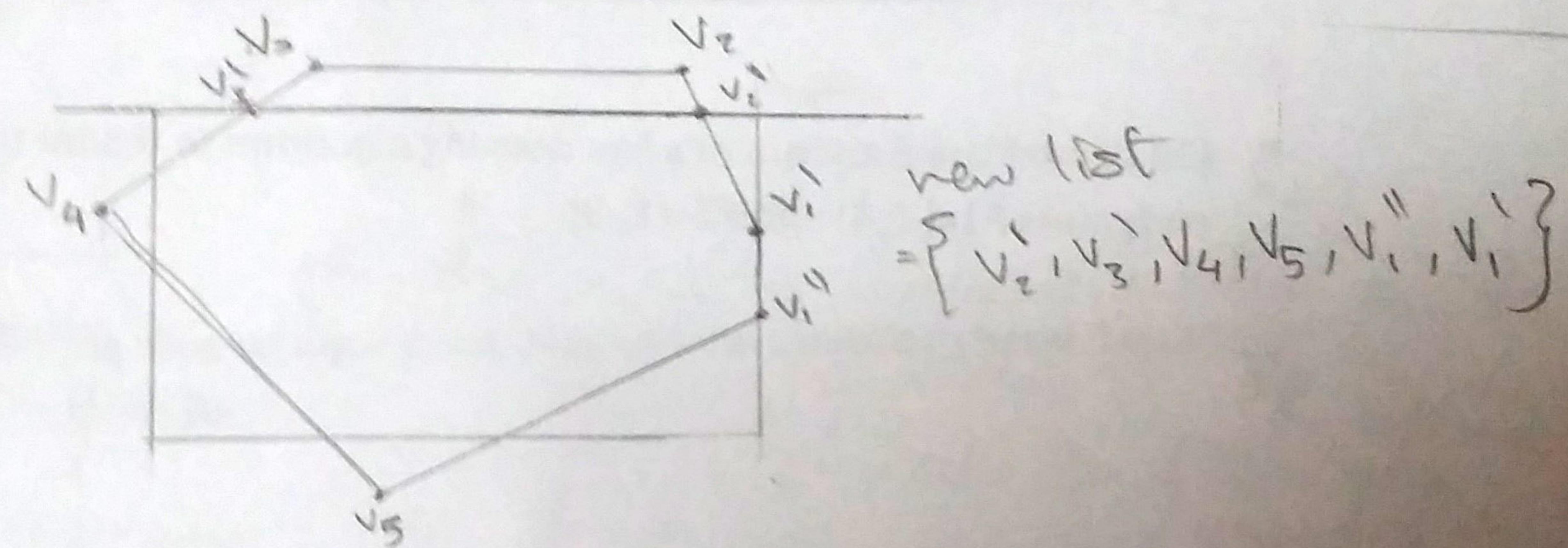
- \* 1st out / 2nd in  $\rightarrow$  move 1st to boundary and accept 1st and 2nd
- \* 1st in / 2nd in  $\rightarrow$  accept Second
- \* 1st in / 2nd out  $\rightarrow$  move 2nd to boundary & accept second
- \* 1st out / 2nd out  $\rightarrow$  reject both

60 [60 points] Apply Sutherland-Hodgman on the figure in the order of boundaries (right, top, left, bottom):

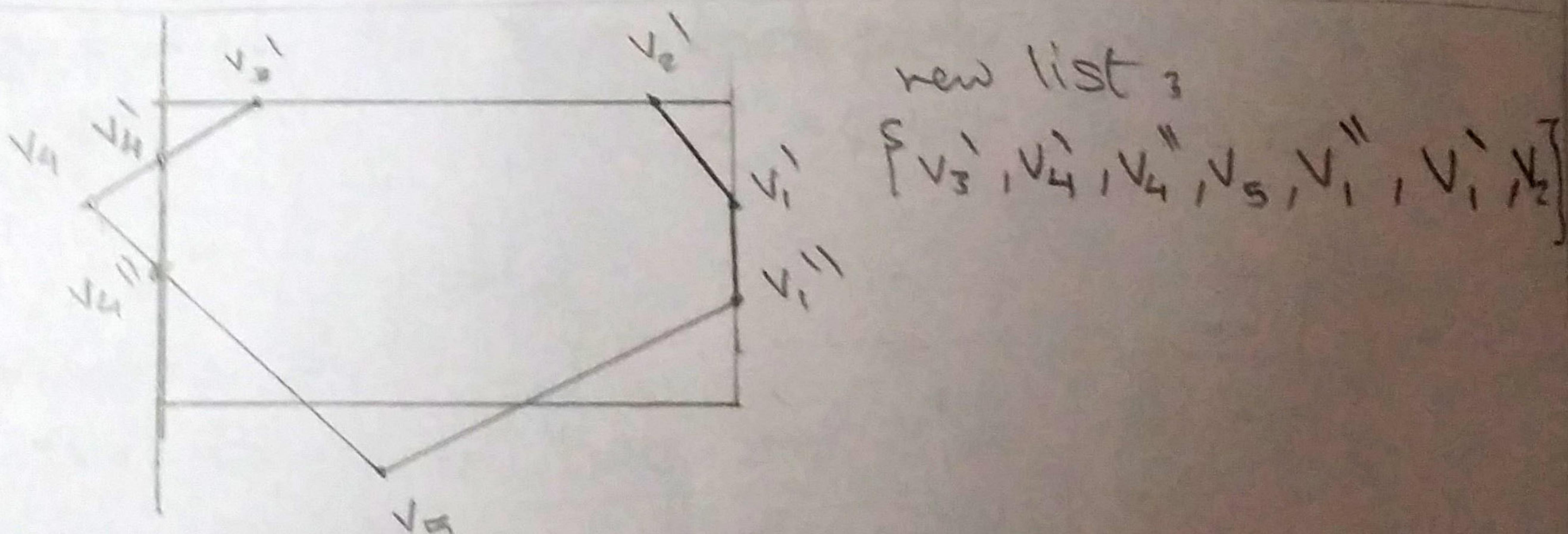
$V_1, V_2 \rightarrow V'_1, V'_2$   
 $V_2, V_3 \rightarrow V_3$   
 $V_3, V_4 \rightarrow V_4$   
 $V_4, V_5 \rightarrow V_5$   
 $V_5, V_1 \rightarrow V''_1$



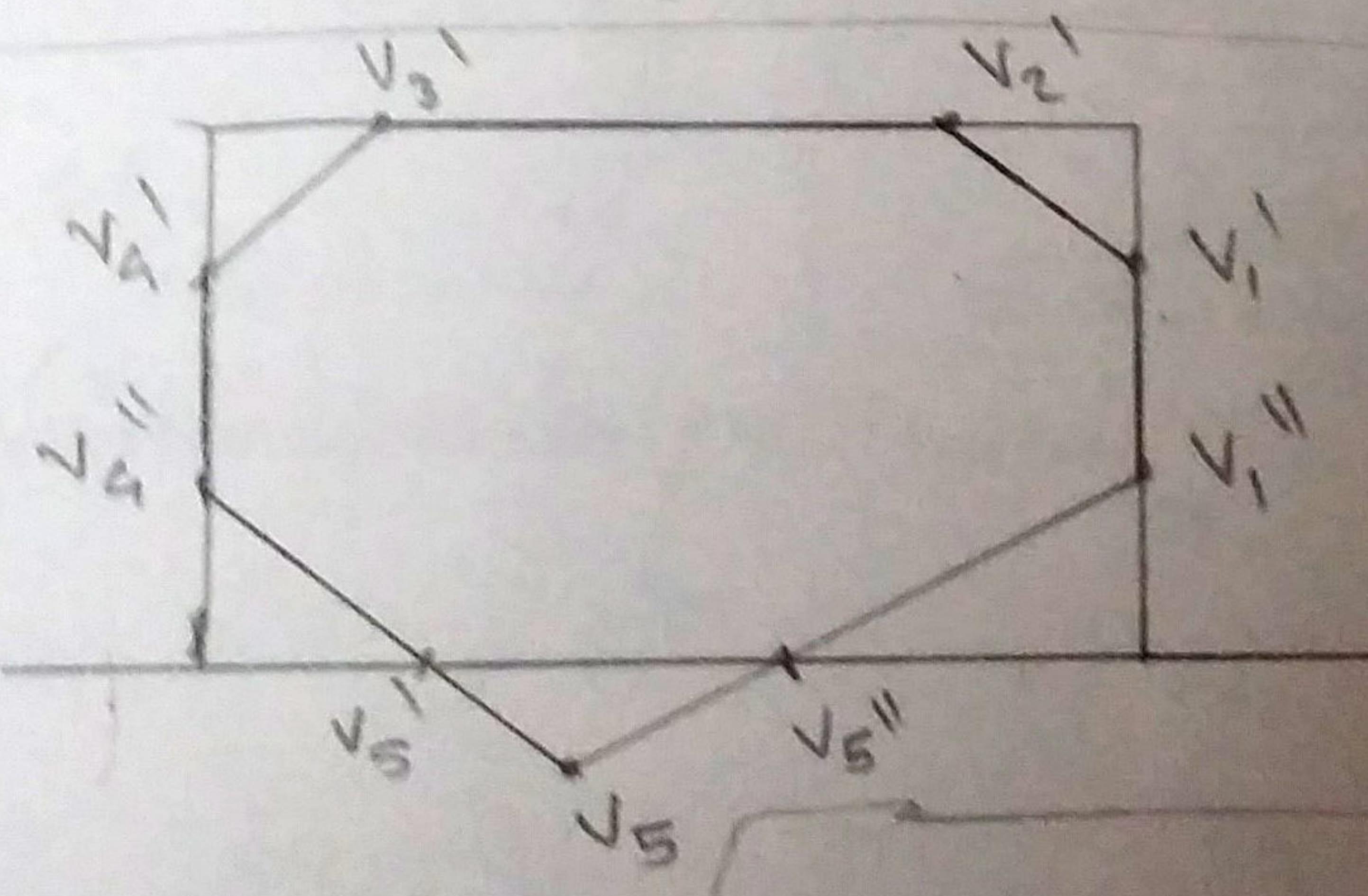
$V'_1, V'_2 \rightarrow V'_2$   
 $V'_2, V'_3 \rightarrow \text{none}$   
 $V'_3, V'_4 \rightarrow V'_3, V'_4$   
 $V'_4, V'_5 \rightarrow V'_5$   
 $V'_5, V'_1 \rightarrow V'_1$   
 $V'_1, V'_1 \rightarrow V'_1$



$V'_1, V'_2, V'_3 \rightarrow V'_3$   
 $V'_2, V'_4 \rightarrow V'_4$   
 $V'_4, V'_5 \rightarrow V''_4, V'_5$   
 $V'_5, V'_1 \rightarrow V'_1$   
 $V'_1, V'_2 \rightarrow V'_2$



$V'_1, V'_2, V'_3 \rightarrow V'_4$   
 $V'_2, V'_4 \rightarrow V''_4$   
 $V'_4, V'_5 \rightarrow V'_5$   
 $V'_5, V'_1 \rightarrow V'_1$   
 $V'_1, V'_2 \rightarrow V'_3$



final list:

$\{V'_1, V''_4, V'_5, V''_5, V''_1, V'_1, V'_2, V'_3\}$

