- 1- ... suffer from a pixelization effect on zoom in.
- i- Raster Images
- ii- Vector Images
- iii- Both of them
- iv- None of them
- 2- To solve the issue of non-linear response on screens we use ...
- i- Deferred Correction
- ii- Raster Correction
- iii- Gamma Correction
- iv- Bonferroni correction
- 3- Vector images are resolution-dependent.
- i- True
- ii- False
- 4- Given 3 triangles A, B, and C, with C being the nearest and A the furthest. Fill colors (RGBA) of each triangle are:

$$C_A = (0.5, 0.5, 0.5, 1)$$

$$C_B = (0.1, 0.7, 0.5, 0.5)$$

$$C_C = (0.7, 0.6, 0.9, 0.75)$$

Then the final color of a pixel covered by the 3 triangles: C =

$$i-(0.5, 0.5, 0.5)$$

ii-
$$(0.6, 0.6, 0.8)$$

iii-
$$(0.3, 0.6, 0.5)$$

5- For the line represented by f(x,y) = Ax + By + C = 0 and passing by (x_0, y_0) and (x_1, y_1) , the values of A and B are

i- A =
$$y_0$$
 - y_1 and B = x_1 - x_0
ii- A = y_1 - y_0 and B = x_1 - x_0
iii- A = y_0 - y_1 and B = x_0 - x_1
iv- A = y_1 - y_0 and B = x_0 - x_1

6- If we add an RGB color [255, 0, 0] to another color [0, 255, 0], the result is the color [255, 255, 0].

i- True

ii- False

7- for f(x,y) = ax + by + c, the vector $[a\ b]$ represents:

i- The normal vector on the line f(x, y) = 0

ii- the gradient vector of f(x, y)

iii- The direction in which the distance from the line doesn't change

iv- None of the above

8- The following line-drawing algorithm suffers from the following problems:

```
y = y_0
d = f(x_0 + 1, y_0 + 0.5)
for x = x_0 to x_1 do
    draw(x,y)
    if d < 0 then
    y = y + 1
    d = d + (x_1 - x_0) + (y_0 - y_1)
    else
    d = d + (y_0 - y_1)</pre>
```

- i- Excessive evaluation for the function of the line
- ii- Floating-point calculations
- iii- Both of them
- iv- None of them

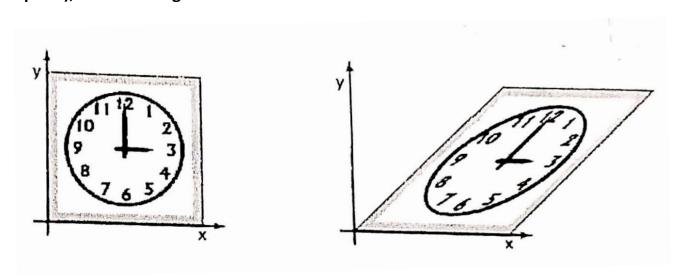
9- Which of the following transformations has an orthonormal matrix?

- i- Scaling
- ii- Rotation
- iii- Shearing
- iv- Translation

10- The 2D Reflection around the line y=x is orthonormal.

- i- True
- ii- False

11- To transform the shape on the left to the shape on the right (square -> skewed square), the following transformation matrix is needed.



```
iii- [1, 1; 0, 1] iv- [1, 0; 1, 1]
```

12- The following triangle drawing algorithm can be optimized by modifying the line:

```
1 for all x[0:screen_width] do: for all y[0:screen_height] do:
2    compute (alpha, beta, gamma) for (x,y)
3    // Inside?
4    if (alpha in (0,1) AND beta in (0,1) AND gamma in (0,1)) then
5         c = alpha*c0 + beta*c1 + gamma*c2
6         drawpixel(x,y) with color c
```

i- #1

ii- #4

iii- Both of them

iv- None of them

13- if a rectangle defined by the points A (1,1), B (3,1), C (1,3) and D (3,3) is transformed to the new points A' (5,2), B' (9,2), C'(6,4), D'(10, 4). What is the order of transformations needed to transform ABCD to A'B'C'D'?

i- Translation, Uniform Scaling, Shearing in x-direction, Translation.

ii- Translation, Non-uniform Scaling, Shearing in x-direction, Translation.

iii- Translation, Non-uniform Scaling, Shearing in y-direction, Translation.

iv- None of the above

14-16 - Given triangle ABC,
$$A = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
, $B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $C = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, With color values at each respectively: $C_A = \begin{bmatrix} 0.6 \\ 0.4 \\ 0.1 \end{bmatrix}$, $C_B = \begin{bmatrix} 0 \\ 0.5 \\ 0.7 \end{bmatrix}$, $C_C = \begin{bmatrix} 0.6 \\ 0.6 \\ 1 \end{bmatrix}$.

Given arbitrary point P:

14- if $\beta=0$ and P is on the edge CA, $\gamma=....$

i- 0

ii- 0.5

iii- 1

iv- Not enough Information

15- Given $\beta=0.5~$ and P is inside ABC, $\gamma=.....$

i- 0.0

ii- 0.3

iii- 0.5

iv- 0.7

16- Given P = $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ Color at point P (C_P) =

 $i-[0.6\ 0.9\ 0.8]^T$

 $ii-[0.3\ 0.3\ 0.5]^T$

iii- $[0.4 \ 0.5 \ 0.6]^T$

iv- Not enough Information

17- If rotation $R(\theta)$ is applied to point P = (x,y), followed by reflection about the x-axis, followed by reflection about the y-axis and finally a uniform scaling is applied by factor σ to obtain the point P' then which of the following is correct about the transformation of point P to point P'?

i- P' = R(
$$\theta$$
) * R(180) * S(σ) * P
ii- P' = S(σ) * R(-180) * R(θ) * P
iii- P' = S(σ) * R(90) * R(90) * R(θ) * P
iv- None of the above

18- The off-diagonal elements in a transformation matrix may be non-zeros only if the transformation applied is:

- i- Scaling
- ii- Shearing
- iii- Reflection
- iv- Scaling followed by reflection.

19-22- The next four questions are related:

19- What are the transformations needed for a reflection about an arbitrary line y = mx + c? (c>0) (regardless of the order of transformations).

- i- Translation
- ii- Scaling
- iii- Reflection
- iv- Rotation

20- if translation is needed, how many translation operations are needed?

- i- 1
- ii- 2
- iii- 3
- iv- Translation is not needed.

21- If scaling is needed, what are the scaling factors Sx and Sy?

$$i-Sx = m, Sy = 1$$

ii-
$$Sx = 1$$
, $Sy = m$

iii-
$$Sx = m/c$$
, $Sy = 1/c$

iv- Scaling is not needed.

22- If rotation is needed, what will be the absolute value of the angle of rotation?

- i- |m|
- ii- |tan⁻¹ (m)|
- iii- |tan-1(m/c)|
- iv-Rotation is not needed.

23- The rotation matrix [$\cos \theta$, $\sin \theta$; - $\sin \theta$, $\cos \theta$]

- i- Rotates points around the X-axis using an angle θ counter-clockwise.
- ii- Rotates points around the Y-axis using an angle θ clockwise.
- iii- Rotates points around the origin using an angle θ counter-clockwise,
- iv- Rotates points around the origin using an angle θ clockwise.

24- The transformation matrix [-1, 0; 0, 1]

- i- Reflects points around the X-axis
- ii- Reflects points around the Y-axis
- iii- None of them
- 25- If we transform a point by a transformation matrix M_1 followed by another transformation matrix M_2 this is equivalent to the transformation matrix $M = M_1M_2$.
- i- True
- ii- False

26- The inverse of [$\cos \theta$, $-\sin \theta$, $\sin \theta \cos \theta$] is

i- [$\cos \theta$, $\sin \theta$; - $\sin \theta$, $\cos \theta$]

ii- [$\cos \theta$, - $\sin \theta$; $\sin \theta$, $\cos \theta$]

iii- $[\cos -\theta, -\sin -\theta; \sin -\theta, \cos -\theta]$

iv- None of the above

27- Given that R = $[\cos \theta, -\sin \theta; \sin \theta, \cos \theta]$ and S = $[\cos \alpha, -\sin \alpha; \sin \alpha, \cos \alpha]$

i- RS != SR because the order of transformations matter.

ii- RS=SR

iii- It depends on θ and $\alpha.$

28- The 2D point [1 5] is represented in homogeneous coordinates as

iv- None of the above

29- The 2D vector [1 5] is represented in homogeneous coordinates as

i-[151]

ii- [150]

iii- [2 10 2]

iv- None of the above

30- The following matrix represents

$$\begin{bmatrix} R_{2\times 2} & t_{2\times 1} \\ 0^T & 1 \end{bmatrix}$$

i- A translation then a rotation in the 2D space

ii- A translation then a rotation in the 3D space

iii- A rotation then a translation in the 3D space

iv- None of the above

31- Given that xyz is the canonical frame, the following matrix

$$\begin{bmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{bmatrix}$$

i- Rotates uvw to xyz

ii- Rotates xyz to uvw

iii- Changes the coordinate system from uvw to xyz

iv- Changes the coordinatet system from xyz to uvw

32- Given the canonical frame xy and another arbitrary frame uv that is located at e, the following matrix represents

$$\begin{bmatrix} x_u & y_u & 0 \\ x_v & y_v & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_e \\ 0 & 1 & -y_e \\ 0 & 0 & 1 \end{bmatrix}$$

- i- The canonical to frame transformation
- ii- The frame to canonical transformation
- iii- Either of the above
- iv- None of the above

33-if we rotate the points of a surface using the rotation matrix M, the surface normal vectors can be transformed by the matrix

- i- M⁻¹
- ii- MT
- iii- M
- iv- None of the above

34- A windowing transform may be obtained by

- i- Translation then scaling then translation
- ii- Translation then scaling
- iii- Scaling then translation
- iv- None of the above

35- Which of the following projections have parallel lines remain parallel and never intersect?

- i- Orthographic projection
- ii- Perspective Projection
- iii- None of them

36- In the perspective projection, there is a single vanishing point in any image because parallel lines intersect at this point.

- i- True
- ii- False

37- The modeling transformation converts points from object space into the world space.

- i- True
- ii- False

38- The viewport transformation is a

- i- Rotation transformation
- ii- Windowing transform
- iii- Canonical to frame transformation
- iv- Frame to canonical transformation

39- The camera transformation is a

- i- Rotation transformation
- ii- Windowing transform
- iii- Canonical to frame transformation
- iv- Frame to canonical transformation

40- The orthographic projection transformation is

- i- Rotation transformation
- ii- Windowing transform
- iii- Canonical to frame transformation
- iv- Frame to canonical transformation

41- The modeling transformation is a

- i- Rotation transformation
- ii- Windowing transform
- iii- Canonical to frame transformation
- iv- Frame to canonical transformation

42- Which transformation depends on the object position and orientation?

- i- Camera transformation
- ii- Viewport transformation
- iii- Modeling transformation
- iv- Projection transformation

43- Which transformation depends on the resolution of the output image?

- i- Camera transformation
- ii- Viewport transformation
- iii- Modeling transformation
- iv- Projection transformation
- 44- if the camera was located at the origin of the world coordinates, then the camera transformation matrix must be the identity matrix.
- i- True
- ii- False
- 45- If the distance between point A and point B is 2. Assume that there is a camera at location (0, 10,0), looking at the origin and its up vector points in the direction (1,0,1). What will be the distance between A and B after applying the camera transform to them?

i- 4

ii- sqrt(2)

iii- 2

iv- Cannot be determined using the given information.

46 - (In Barycentric Coordinates of Triangle ABC). We can calculate $\beta = \frac{Area(\Delta APC)}{Area(\Delta ABC)}$

i- True

ii- False

47 - Raster images are made up of Pixels and do not depend on the resolution. What is wrong about this sentence?

- i- The first part is wrong. Instead, raster Images are made up of object description.
- ii- The second part is wrong. Instead, raster images depend on the resolution.
- iii- None of the above. The sentence is already correct.

48 – Of the following components, which depend on the eye (viewpoint) position

i- diffuse

ii- specular

iii- ambient

iv- None of the above.

49 - Of the following components, which depend on the light source position

i- diffuse

ii- specular

iii- ambient

iv- None of the above.

50 – Rasterization is/does

- i- Readily available in GPUs
- ii- Produce realistic images
- iii- Parallelizable
- iv- Loop over pixels and for each, loops over each triangle.

51- The factor of reflected light ray between entering a refractive medium depends on:

- i- The normal vector of the surface separating the mediums
- ii- The direction of the ray falling on the surface
- iii- The intensity of the light
- iv- The distance between light source and surface

52 - As described in the Ray intersection with 2D boxes, we determine

 t_{min} and t_{max} using t_{xmin} , t_{xmax} , t_{ymin} , and t_{ymax} . These four values can take distinct value/s

- i- 1
- ii- 2
- iii- 3
- iv- 4

53 – We say that there is an intersection between the ray and a rectangle in 3D if

.....

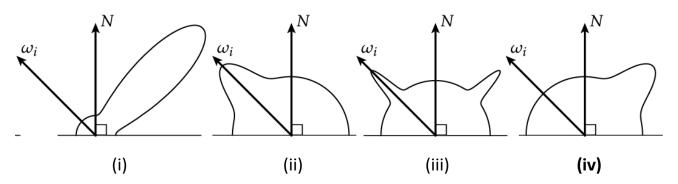
i- The ranges $[t_{xmin}$, $t_{xmax}]$, $[t_{ymin}, t_{yman}]$ overlap ii- $max(t_{xmin}, t_{ymin}) < min(t_{xmax}, t_{ymax})$ ii- $max(t_{xmin}, t_{ymin}) > min(t_{xmax}, t_{ymax})$

iv – The ranges $[t_{xmin}$, $t_{xmax}]$, $[t_{ymin}, t_{yman}]$ don't overlap

54- To get the depth values for pixels inside a triangle, we use

- i- Barycentric Coordinates
- ii- Homogenous Coordinates
- iii- None of the above

55- To decorate your new bedroom, you decide to paint it with a unique painting. you first paint it with a bright white diffuse paint, then a dull glossy (specular) glaze. For a given light direction wi. Which material BRDF looks most like your paint?



56- To check for faces that will not be drawn (back face culling), A face is not drawn if: (n is the normal vector to the face, v_{cam} is the viewpoint vector)

$$\begin{split} & \text{i-} \ n \cdot v_{cam} > 0 \\ & \text{ii-} \ n \cdot v_{cam} < 0 \\ & \text{iii-} \ \| n + v_{cam} \| < 0 \\ & \text{iv-} \ \| n + v_{cam} \| > 0 \end{split}$$

57- Raytracing's runtime complexity scales with ...

i- Number of pixels (resolution)

ii- Number of objects

iii- Number of lights

iv- None of the above

58- By using Z-Buffering in rasterization, for each pixel, we loop over all triangles to check the depth at this point and color it with triangle color having the minimum depth value

i- True

ii- False

59- By using Z-Buffering in rasterization, for each pixel, we loop over all triangles to check the depth at this point and color it with triangle color having the minimum depth value

i- True

ii- False

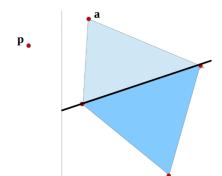
60- A 2D vector can be written as a linear combination of any two non-parallel vectors. This is called And the two vectors are called

i- Non-linear Independence, origin vectors.

ii- Non-linear Independence, basis vectors.

iii- linear Independence, basis vectors.

iv- linear Independence, origin vectors.



61- What is the value of $f(b) \times f(p)$?

i - < 0

ii - > 0

iii = 0

iv- Not enough information.

62- In which step in the 3D viewing pipeline, we drop the z coordinate?

i- Modelling Transformation.

ii- Camera Transformation.

iii- Projection Transformation.

iv- Viewport Transformation.

63 – To implement soft shadows using ray tracing you can.......

i- Shoot rays from each pixel to different points of the area light source

ii- Shoot rays from different pixels and average those meeting at the same point in

the area light source

- iii Shoot rays from the light source to all other pixels
- iv Shoot one ray from the pixel to the middle of the light source

64- Flat shading

i- computes Shading Once per vertex

ii- is very cheap computationally

iii- results in a faceted appearance

iv- None of the above

65- Gourard Shading ..

i- suffers from Mach banding

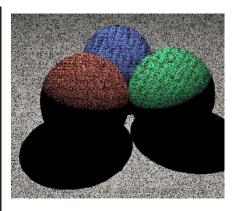
ii- is very fast

iii- is more realistic than Phong shading

iv- None of the above

66- The following Code snippet produces a noisy result as shown below, which line can be changed to avoid this issue.

```
1 function ComputeShading(ray, t0, t1)
2   Get intersection of ray with scene
3   if intersection != NULL
4     Color = ambient
5     Get n, h, l
6     if !blocked(shadowray, 0, ∞)
7     Color += kd * max(0, <n,l>) + ks * <h,n> * p
8   else
9   Color = background
```



i- #6

ii- #7

iii- #9

iv- None of the above

67- Raytracing handles objects:

- i- With parameterized equations (Spheres, planes, etc..)
- ii- With arbitrary shapes
- iii- With meshes

68- Phong shading computes shading at each vertex using vertex normal then interpolates across triangle using Barycentric Coordinates.

i- True

ii- False

69-BRDF stands for

- i- Bidirectional Refraction Distribution Function
- ii- Bidirectional Reflectance Distribution Function
- iii- Bounded Refraction Distribution Function
- iv- Bounded Reflectance Distribution Function

70- is modelled as a constant lighting component depending on the material of the object

i- diffusion

ii- specular

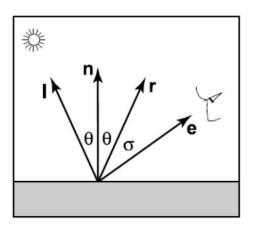
iii- alpha

iv- ambient

71-75: Next 5 questions are related: A light source hits a surface with, Given that:

$$I = [-0.707 \ 0.707]$$

 $n = [0 \ 1]$
 $e = [0.8 \ 0.6]$
 $k_{spec} = 0.5, k_{diff} = 0.2, k_{amb} = 0.2$
 $I = 0.5, I_a = 0.2, p = 4$



l: Light direction n: Surface normal

e: To eye vector p: Specular exponent

I: Light source intensity Ia: Surrounding light intensity

kspec, kdiff, kamb: material constants for specular, diffusion and ambient components respectively

71- r =

i- [0.707 0.707]

ii- [0.6 0.8]

iii- [0.354 0.354]

iv- [-0.354 0.354]

72- Specular Component of reflected light, *Rspec*=

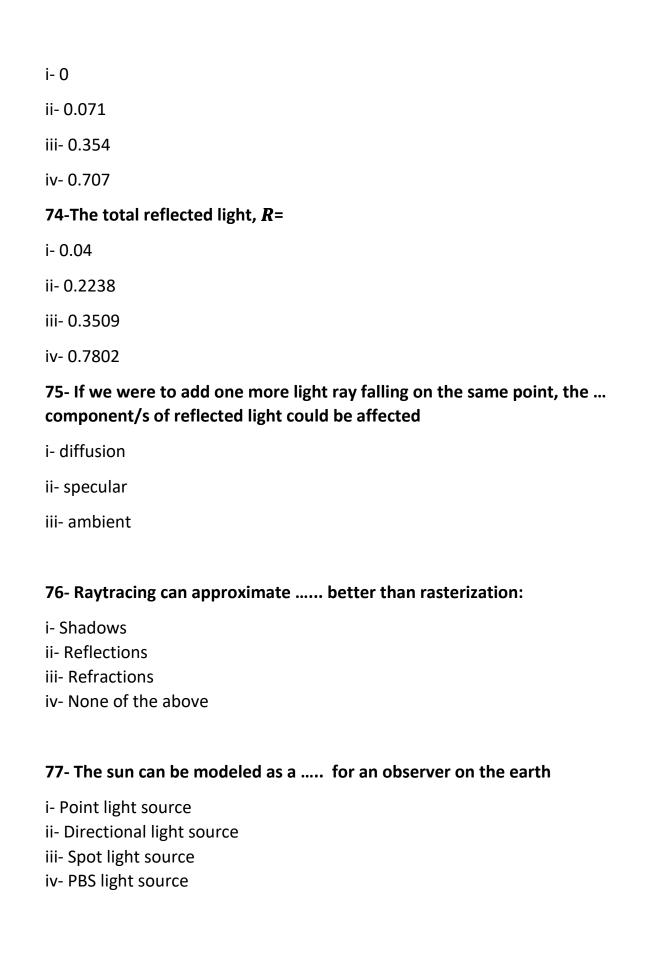
i- 0

ii- 0.2399

iii- 0.2475

iv- 0.9598

73- Diffuse Component of reflected light, Rdiff=



78- Distribution raytracing can be used for ...

- i- Anti-aliasing (super-sampling)
- ii- Glossy reflections
- iii- Glossy refractions
- iv- Soft shadows

79- One of the drawbacks of Ray tracing with single Ray is that it looks too clean and crisp

- i- True
- ii- False

80- One To compute the normal of a triangle face ABC, n =

 $i-A \cdot B$

$$ii-(A-B)\cdot(A-C)$$

iii- $A \times B$

$$iv-(A-B)\times(A-C)$$

81- In ray tracing, we can define the ray by its starting and ending points

- i- True
- ii- False

82- The phenomenon of light being trapped in a material.

- i- Inter-material trapping.
- ii- Inter-material refraction.
- iii- Total Internal Refraction.
- iv- Total Internal Reflection.

- 83- Ray tracing computation is mainly based on the concept
- i- recursion
- ii- parallelism
- iii- memory sharing
- iv- gamma correction
- 84- Barycentric coordinates are only used with rasterization rendering.
- i- True
- ii- False
- 85- Of the following values for d, which causes a total internal reflection?

i-
$$[0 - 1]$$

ii-
$$[0.707 - 0.707]$$

iii-
$$[0.8 - 0.6]$$

iv-
$$[0.6 - 0.8]$$

86- given that d = [0.8 - 0.6], compute t =

i-
$$[0.436 - 0.9]$$

ii-
$$[0.9 - 0.436]$$

iii-
$$[0.634 - 0.773]$$

iv-
$$[0.773 - 0.634]$$

87- It would be correct to apply perspective projection using the matrix

$$\begin{pmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & a & b \\ 0 & 0 & 1 & 0 \end{pmatrix} \text{ on a point } \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} i$$

i-a = 0 and $b = 0$
ii- a = 1 and b = -1
iii- a = 1 and b =0 iv- a = 2 and b = 0
88 – According the to the right answer in the question above, if the near plane is at $z = 4$ and the far plane is at $z = 10$ then an object whose z value satisfies would not be rendered.
i- z < 0.75 ii- z > 0.9 iii- z > 0 iv- z < 0.8
89 – Projection lines are parallel to the camera's in an orthographic projection
i- gaze direction ii- turn-up vector iii- w-axis iv- u-axis
90 – An orthographic projection on camera's position meanwhile a perspective projection on camera's position
i- depends, depends ii- depends, does not depend iii- does not depend, does not depend iv- does not depend, depends
91 – After the camera transformation, normalizing the view volume
i- is a step incorporated in the projection transformation ii- makes it such that objects with $z>1$ or $z<-1$ should not be drawn

iii- is a windowing transformation
iv- can be ignored if that's taken into account in further steps
92 – If your height is 160 cm then your height becomes after perspective
projection with the near plane being at $z = 10$, far plane being at $z = 20$ and your feet having $z = 15$ and $y = 0$
i- 106.6 cm
ii- 125 cm
iii- 80 cm
iv- 160 cm
93 – In ray tracing with orthographic projection, we shoot rays if our display is 200x200 and all of them emerge from point in the near plane.
i- 40000, the same
ii- 400, the same iii- 800, a different
iv- 40000, a different
94 – In ray tracing with perspective projection, we shoot rays if our display is 20x20 and we are using anti-aliasing with supersampling at 100 times the resolution and all of them emerge from point in the near plane.
i- 40000, the same
ii- 400, the same
iii- 800, a different iv- 40000, a different
95 – Ray Tracing is
i- Readily supported by GPUs
ii- Includes a unified, parallelizable way of dealing with reflections

iii- For each triangle, it loops on every pixel to decide which color iv- Can be too slow for interactive applications
96 – Each pixel on the screen corresponds one-to-one to a point on the near plane from which we shoot a ray and check where it hits.
i- True ii- False
97 – Once we shoot a ray through the near plane, its sufficient to stop at the first object hit and record its color in the corresponding pixel
i- True ii- False
98 – If there are 10 objects in the scene and 3 light sources then the number of total rays shot due to one pixel is assuming handling of shadows i- 2 ii- 13 iii – at least 13 iv – at most 4
99 – A ray may have at most intersections with a sphere, meanwhile at most Intersections with a plane where the ray does not live
i- 2, 1 ii- 1, 2 iii - 1, 1 iv - 2, 2
100 – To check the intersection between a ray and a triangle mesh, the efficient approach is to

- i- Start with each triangle's plane and inequalities for each of its sides
- ii- Use barycentric coordinates and find α , β , γ , t
- iii Breakdown the mesh into bounding boxes and check intersections there first
- iv Find intersections between the ray and the three straight lines forming the triangles side