

Digital Communications (ELC 325b)

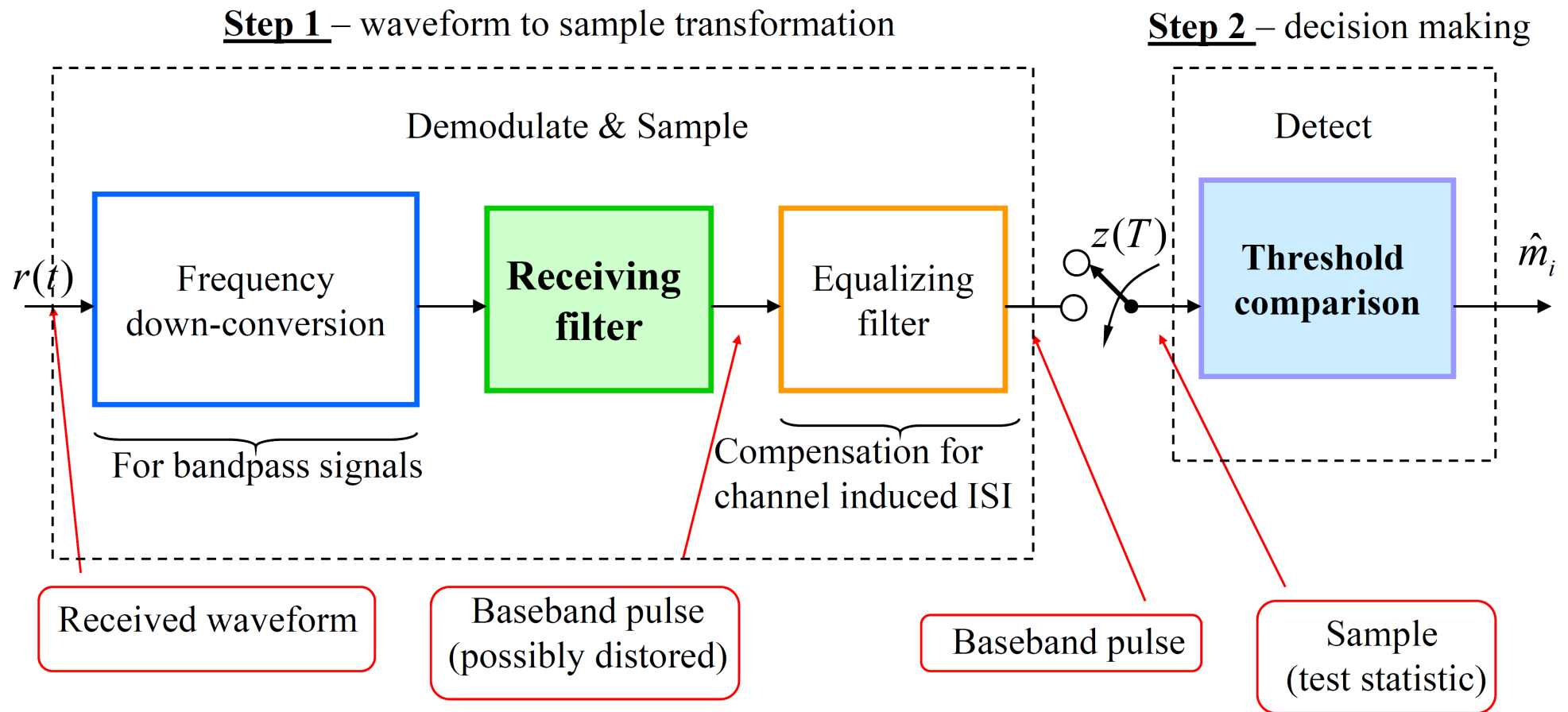
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Structure of Receiver

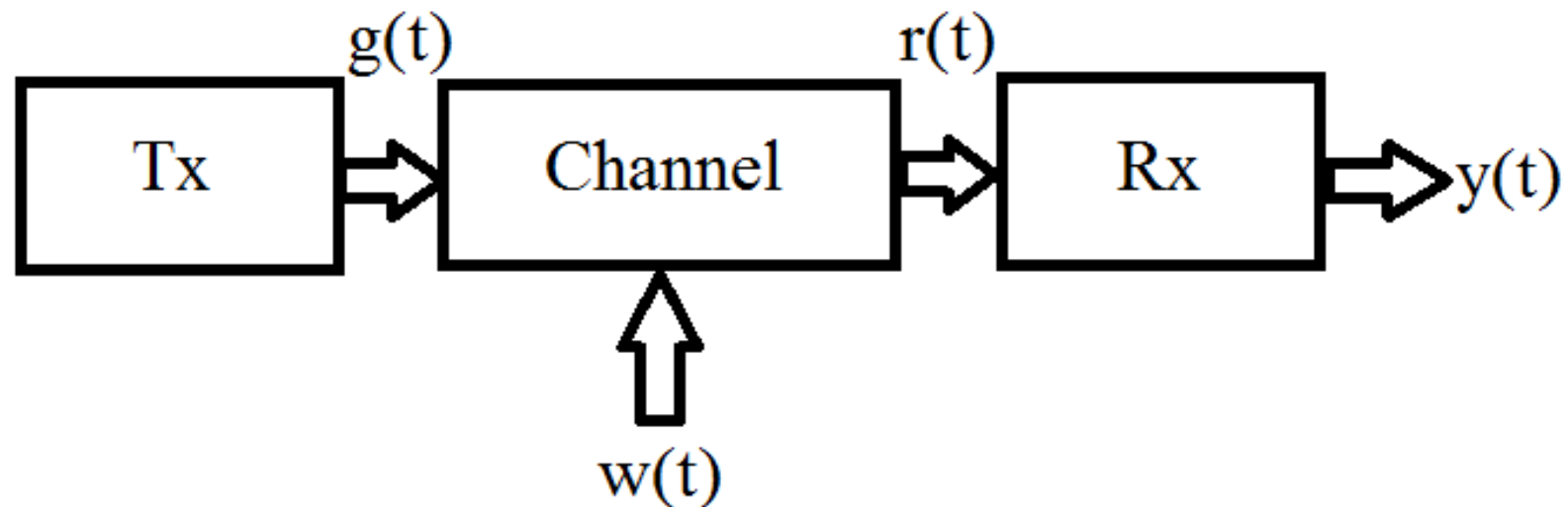


Base-Band Pulse Transmission

Characteristics

- Digital data have a broad spectrum with low frequency content
- Base-Band transmission of digital data requires the use of low-pass channel with large bandwidth
- Generally, channels are not ideal and are rather dispersive
- Transmission over non-ideal channels causes that the received pulse is affected by adjacent pulses causing inter-symbol interference

Design of Optimum Receiver in AWGN Channel



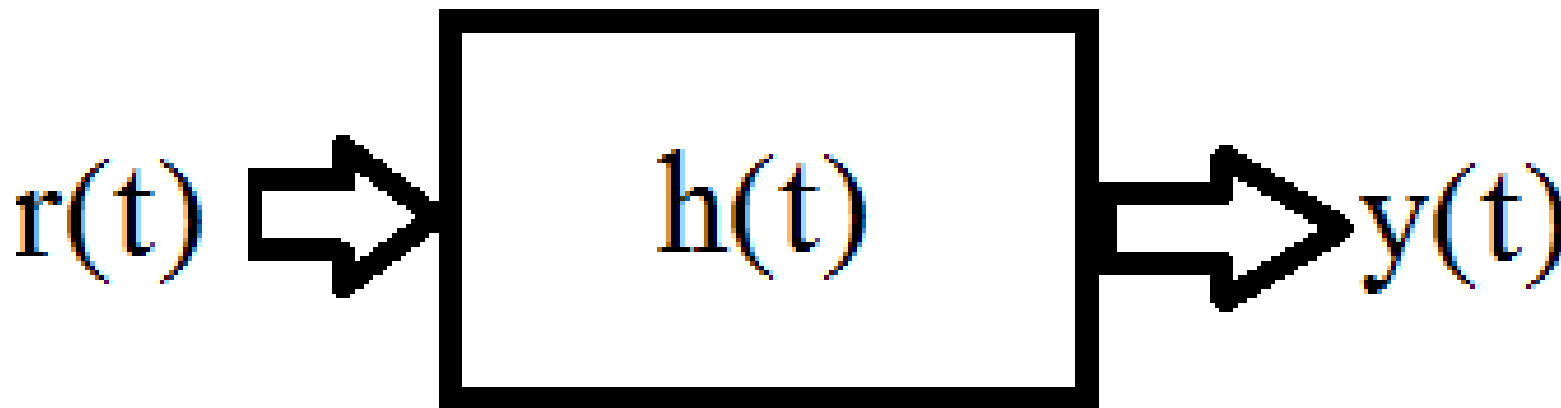
- The receiver receives a pulse signal, $r(t)$, of known waveform, $g(t)$, immersed in AWGN, $w(t)$
- The receiver should be able to detect the pulse shape ($g(t)$ or $-g(t)$) irrespective the noise added from the channel
- For now, we assume the channel is **not bandlimited**, i.e. the pulse shape is not distorted, but may be scaled
- It is assumed the receiver is a filter $h(t)$

Design of Optimum Receiver in AWGN Channel

Optimality Criteria

The optimality of the receiver design can be based on:

- 1 **Bit Error Rate (BER)** = Probability of errors in the received bits
An optimum receiver (filter), minimizes the BER
- 2 **Signal-to-Noise Ratio (SNR)** = Signal power to noise power
An optimum receiver (filter), maximizes the SNR



Matched Filter

1 The Filter Input

$$r(t) = g(t) + w(t), \quad 0 \leq t \leq T$$

2 The Filter Output

$$\begin{aligned} y(t) &= r(t) * h(t) \\ &= g(t) * h(t) + w(t) * h(t) \\ &= g_o(t) + n(t) \end{aligned}$$

It is required that the receiver causes the instantaneous power of the output signal $g_o(t)$ measured at $t = T$ as large as possible compared to the average power of the output noise $n(t)$.

That is equivalent to **maximizing the peak pulse SNR**

$$\eta = \frac{|g_o(T)|^2}{\mathcal{E}\{|n(t)|^2\}}$$

Matched Filter

- The output signal

$$\begin{aligned}g_o(t) &= \mathcal{F}^{-1}\{G(f)H(f)\} \\&= \int_{-\infty}^{\infty} G(f)H(f)e^{j2\pi ft} df \\|g_o(t)|^2 &= \left| \int_{-\infty}^{\infty} G(f)H(f)e^{j2\pi ft} df \right|^2 \\|g_o(T)|^2 &= \left| \int_{-\infty}^{\infty} G(f)H(f)e^{j2\pi fT} df \right|^2\end{aligned}$$

- The output noise

$$\begin{aligned}S_N(f) &= |H(f)|^2 S_W(f) = |H(f)|^2 \frac{N_0}{2} \\ \mathcal{E}\{|n(t)|^2\} &= \int_{-\infty}^{\infty} S_N(f) df = \frac{N_0}{2} \int_{-\infty}^{\infty} |H(f)|^2 df\end{aligned}$$

Matched Filter

$$\eta = \frac{\left| \int_{-\infty}^{\infty} G(f)H(f)e^{j2\pi fT} df \right|^2}{\frac{N_0}{2} \int_{-\infty}^{\infty} |H(f)|^2 df}$$

Cauchy-Schwarz Inequality

$$\left| \int_{-\infty}^{\infty} \phi_1(x)\phi_2(x)dx \right|^2 \leq \int_{-\infty}^{\infty} |\phi_1(x)|^2 dx \int_{-\infty}^{\infty} |\phi_2(x)|^2 dx$$

Equality hold iff $\phi_1(x) = k\phi_2^*(x)$

$$\left| \int_{-\infty}^{\infty} H(f)G(f)e^{j2\pi fT} df \right|^2 \leq \int_{-\infty}^{\infty} |H(f)|^2 df \int_{-\infty}^{\infty} |G(f)|^2 df$$

Matched Filter

$$\eta \leq \frac{2}{N_0} \int_{-\infty}^{\infty} |G(f)|^2 df$$
$$\eta_{\max} = \frac{2}{N_0} \int_{-\infty}^{\infty} |G(f)|^2 df = \frac{2}{N_0} \int_{-\infty}^{\infty} |f(t)|^2 dt$$

The maximum SNR is achieved when $H(f) = kG^*(f)e^{-j2\pi fT}$

Matched Filter

$$H_{\text{opt}}(f) = kG^*(f)e^{-j2\pi fT}$$

$$h_{\text{opt}}(t) = kg(T - t)$$

$$\eta_{\max} = \frac{E}{N_0/2}$$

Matched Filtes

Properties of Matched Filter

- 1 The impulse response $h_{opt}(t)$ is uniquely defined by the waveform of the pulse signal $g(t)$, the time delay T and a scaling factor k .
- 2 The peak pulse SNR of the MF depends only on the ratio of the signal energy to the PSD of the white noise at the filter input.

$$\begin{aligned} G_o(f) &= H_{opt}(f)G(f) = k |G(f)|^2 e^{-j2\pi fT} \\ g_o(T) &= \int_{-\infty}^{\infty} G_o(f) e^{j2\pi fT} df \\ &= k \int_{-\infty}^{\infty} |G(f)|^2 df \\ &= k \int_{-\infty}^{\infty} |g(t)|^2 dt = kE \\ \mathcal{E}\{|n(t)|^2\} &= \frac{N_0}{2} k^2 E \quad \Rightarrow \quad \eta_{\max} = \frac{E}{N_0/2} \end{aligned}$$

Correlator Receiver

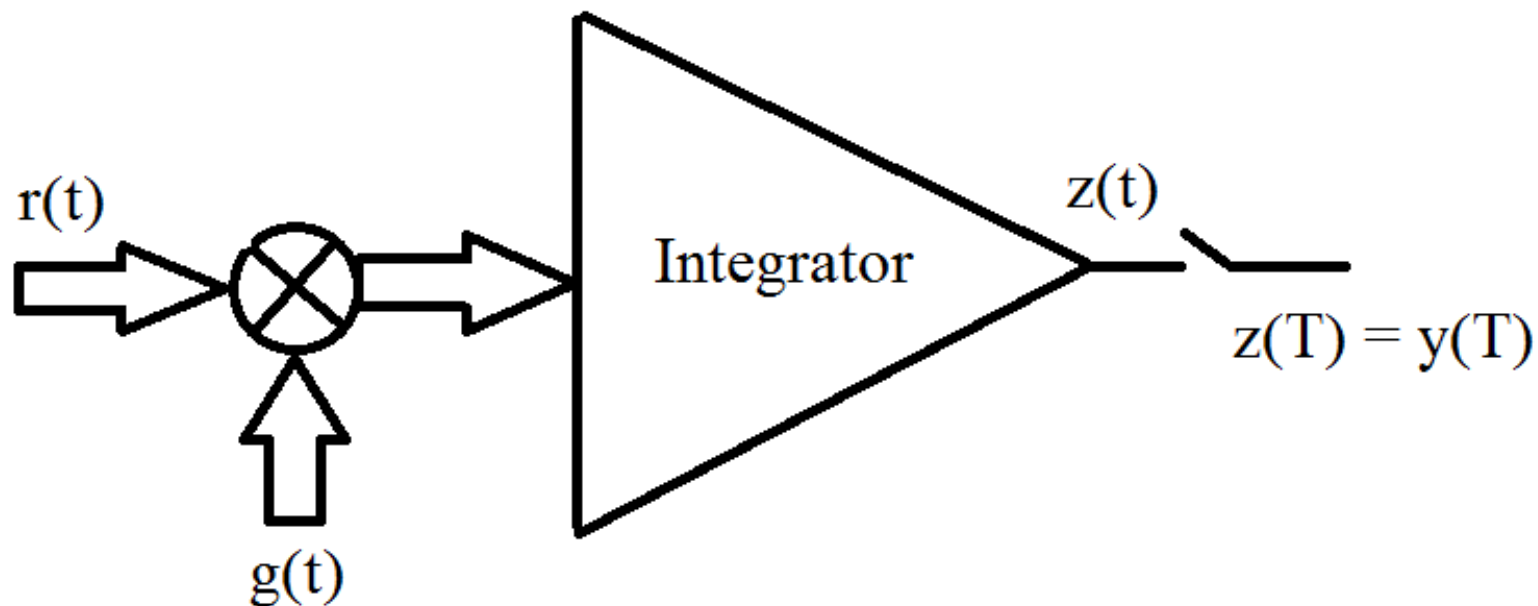
$$h(t) = g(T - t)$$

$$y(t) = r(t) * h(t)$$

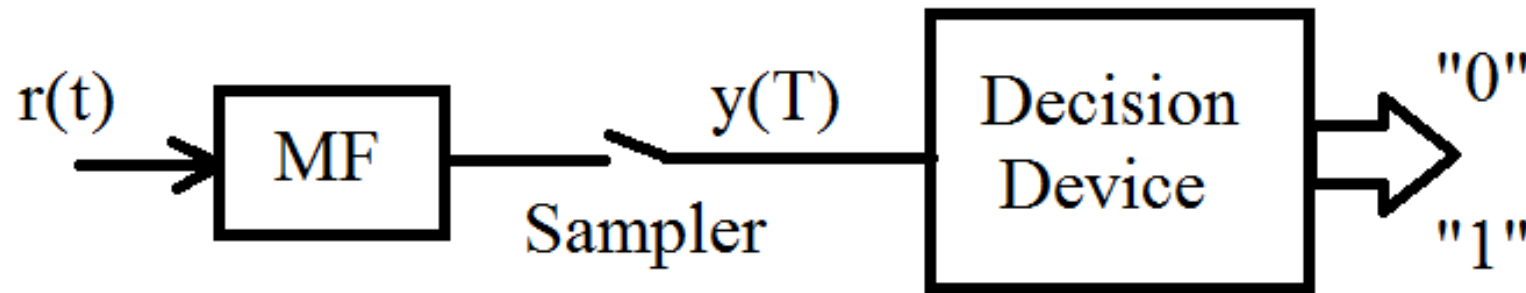
$$= \int_{-\infty}^{\infty} r(\tau) h(t - \tau) d\tau$$

$$y(T) = \int_{-\infty}^{\infty} r(\tau) h(T - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} r(\tau) g(\tau) d\tau$$



Error Rate Calculations



Considering a Polar NRZ signaling,

$$r(t) = \begin{cases} +A + w(t), & \text{for bit '1', } 0 \leq t \leq T_b \\ -A + w(t), & \text{for bit '0', } 0 \leq t \leq T_b \end{cases}$$

The receiver is required to make a decision for each signaling interval

Note: For this signaling, the MF is matched to a rectangular pulse (A, T_b)

The filter output is sampled at the end of each signaling interval

The sample values are compared to a preset threshold λ to make a decision

Error Rate Calculations

$$\begin{aligned}y(T_b) &= \int_{-\infty}^{\infty} r(\tau)g(\tau)d\tau \\&= \int_0^{T_b} kAr(t)dt \\&= \int_0^{T_b} \frac{1}{T_b} r(t)dt\end{aligned}\quad kAT_b = 1$$

Then,

$$y = y(T_b) = \pm A + n(t), \quad n(t) = \frac{1}{T_b} \int_0^{T_b} w(t)d\tau$$

Note:

$n(t)$ is Gaussian distributed, with zero mean and variance $\sigma^2 = \frac{1}{T_b} N_0/2$

$y(T_b)$ is Gaussian distributed, with $\pm A$ mean and variance $\sigma^2 = \frac{1}{T_b} N_0/2$

Error Rate Calculations

The conditional PDF of the sampled output signal is expressed as

$$p(y|'0') = \frac{1}{\sqrt{\pi N_0/T_b}} \exp \left[-\frac{(y + A)^2}{N_0/T_b} \right] \quad (1)$$

$$p(y|'1') = \frac{1}{\sqrt{\pi N_0/T_b}} \exp \left[-\frac{(y - A)^2}{N_0/T_b} \right] \quad (2)$$

Assume bit '0' was transmitted, a decision is considered erroneous if the receiver decides that bit '1' was transmitted. The receiver makes such decision if $y > \lambda$. The probability of such decision is

$$P(e|'0') = P\{y > \lambda|'0'\} = \int_{\lambda}^{\infty} p(y|'0') dy$$

Similarly,

$$P(e|'1') = P\{y < \lambda|'1'\} = \int_{-\infty}^{\lambda} p(y|'1') dy$$

Error Rate Calculations

Probability of Error if '0' was Transmitted

$$\begin{aligned} P(e|'0') &= \frac{1}{\sqrt{\pi N_0/T_b}} \int_{\lambda}^{\infty} \exp \left[-\frac{(y+A)^2}{N_0/T_b} \right] dy \\ &= \frac{1}{\sqrt{\pi}} \int_{\frac{\lambda+A}{\sqrt{N_0/T_b}}}^{\infty} \exp [-z^2] dz \quad \Leftarrow \left[z = \frac{y+A}{\sqrt{N_0/T_b}} \right] \\ &= \frac{1}{2} \operatorname{erfc} \left(\frac{\lambda+A}{\sqrt{N_0/T_b}} \right) \end{aligned}$$

Note:

$$\begin{aligned} \operatorname{erfc}(x) &= \frac{2}{\sqrt{\pi}} \int_x^{\infty} e^{-t^2} dt \\ \operatorname{erf}(x) &= \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \end{aligned}$$

Error Rate Calculations

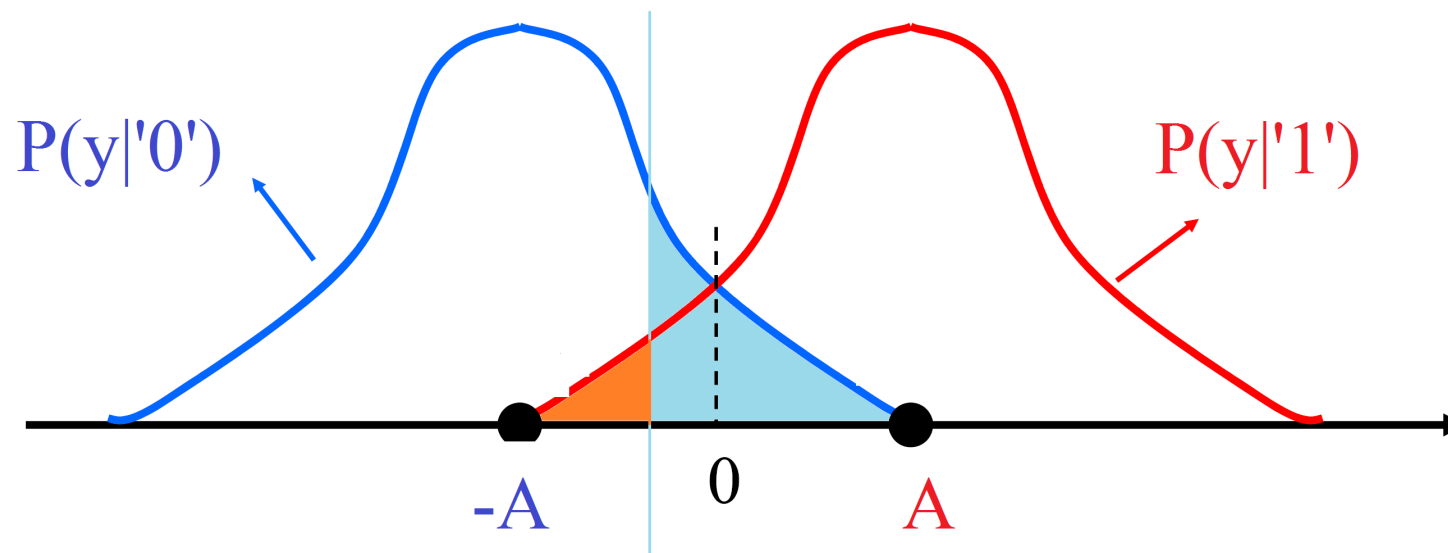
Probability of Error if '1' was Transmitted

$$\begin{aligned} P(e|'1') &= \frac{1}{\sqrt{\pi N_0/T_b}} \int_{-\infty}^{\lambda} \exp \left[-\frac{(y-A)^2}{N_0/T_b} \right] dy \\ &= \frac{1}{\sqrt{\pi}} \int_{\frac{-\lambda+A}{\sqrt{N_0/T_b}}}^{\infty} \exp [-z^2] dz \quad \Leftarrow \left[z = -\frac{y-A}{\sqrt{N_0/T_b}} \right] \\ &= \frac{1}{2} \operatorname{erfc} \left(\frac{-\lambda+A}{\sqrt{N_0/T_b}} \right) \end{aligned}$$

Note:

$$\begin{aligned} \operatorname{erfc}(x) &= \frac{2}{\sqrt{\pi}} \int_x^{\infty} e^{-t^2} dt \\ Q(x) &= \frac{1}{\sqrt{2\pi}} \int_x^{\infty} e^{-\frac{t^2}{2}} dt \end{aligned}$$

Error Rate Calculations



Error Rate Calculations

Average Error Probability

$$P(e) = P(e|'0')P('0') + P(e|'1')P('1') = f(\lambda)$$

In order to minimize the average error probability, λ should be optimally chosen. This is achieved for

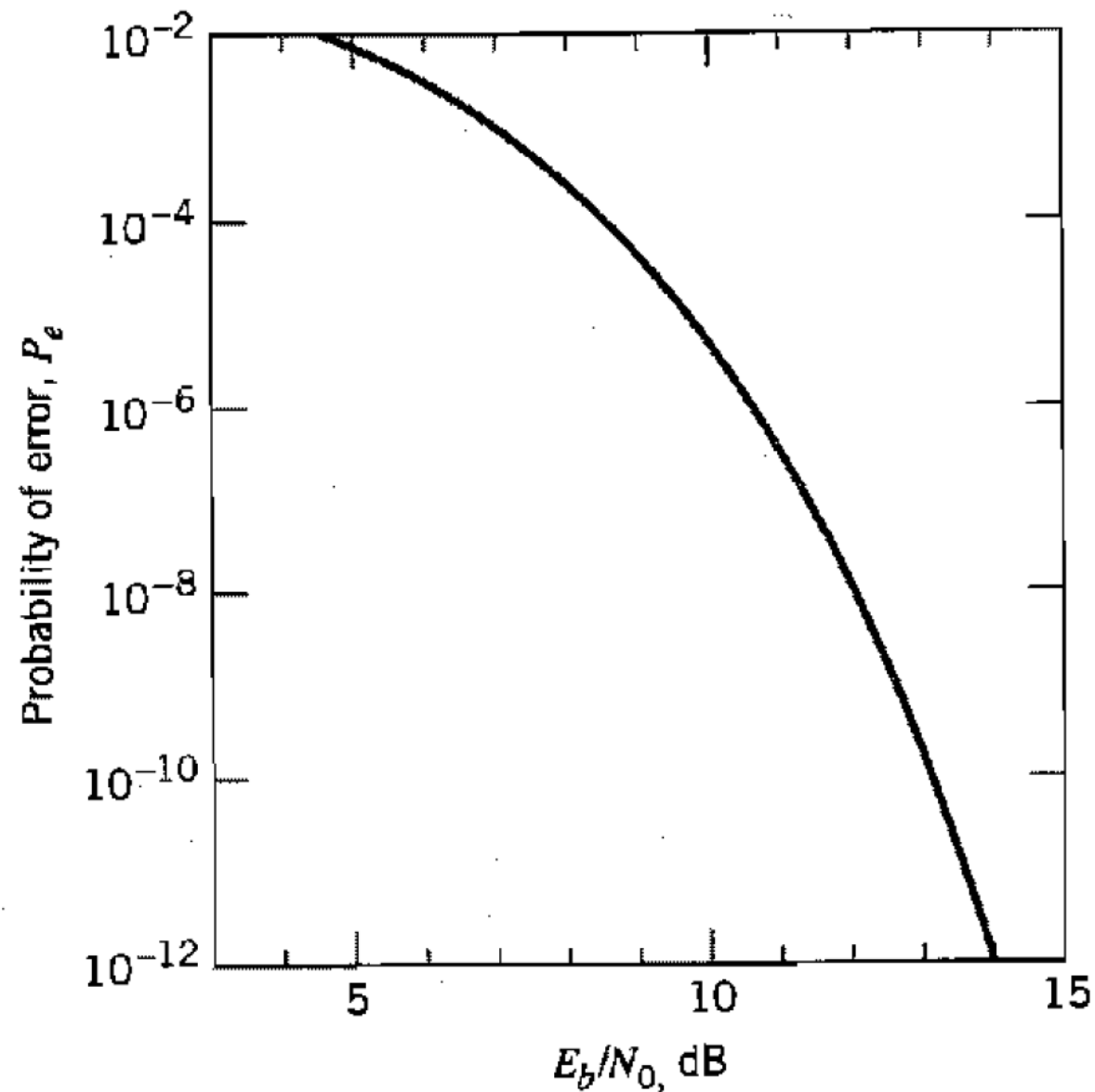
$$\lambda_{opt} = \frac{N_0}{4AT_b} \ln \left(\frac{P('0')}{P('1')} \right)$$

Special Case

If $P('0') = P('1') = 0.5$, then $\lambda_{opt} = 0$. In this case

$$P(e) = P(e|'0') = P(e|'1') = \frac{1}{2} \operatorname{erfc} \left(\frac{A}{\sqrt{N_0/T_b}} \right) = \frac{1}{2} \operatorname{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right)$$

Error Rate Calculations



Error Rate Calculations

Notes

- 1 Binary Symmetric Channel

$$P(e|'0') = P(e|'1')$$

- 2 The average error probability decreases rapidly as E_b/N_0 increases
- 3 If $P('0') \gg P('1')$, $\lambda_{opt} \approx \infty$ in order to reduce $P(e|'0')$
- 4 If $P('0') \ll P('1')$, $\lambda_{opt} \approx -\infty$ in order to reduce $P(e|'1')$

References



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Thank You

Questions ?