

Digital Communications (ELC 325b)

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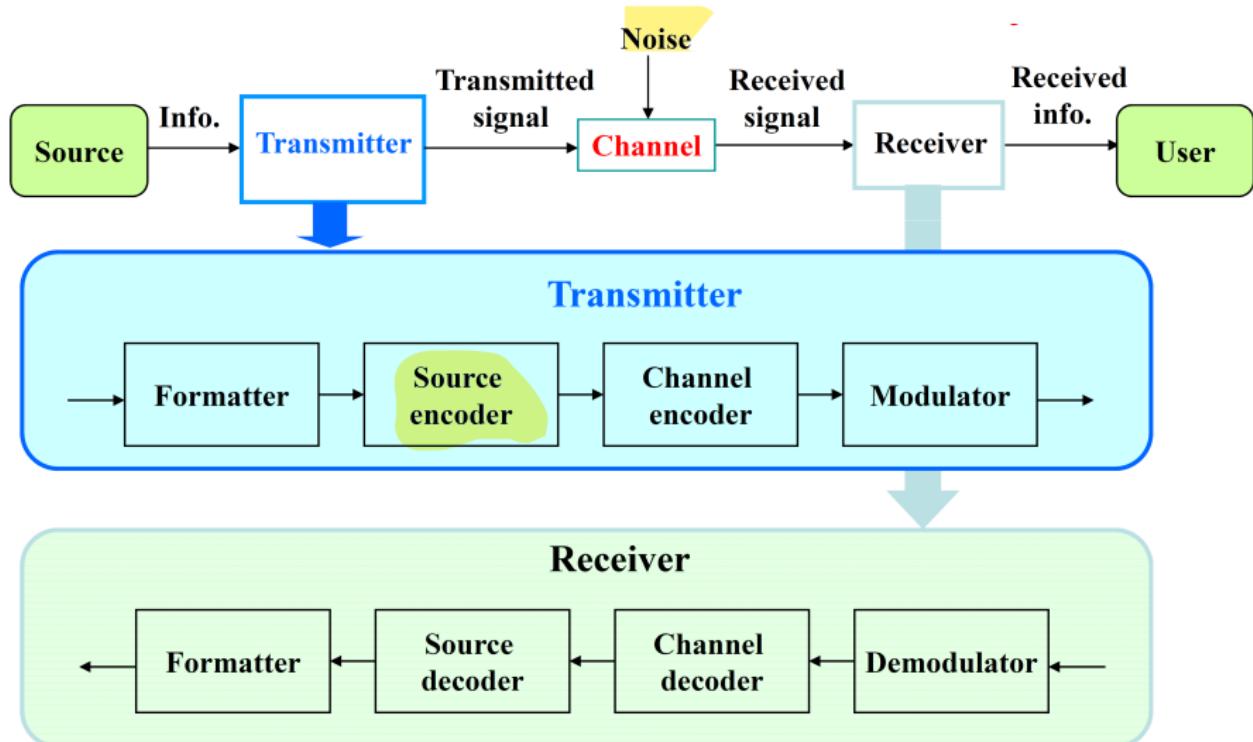
Spring 2016

Outline

1 Introduction to Digital Communication Systems

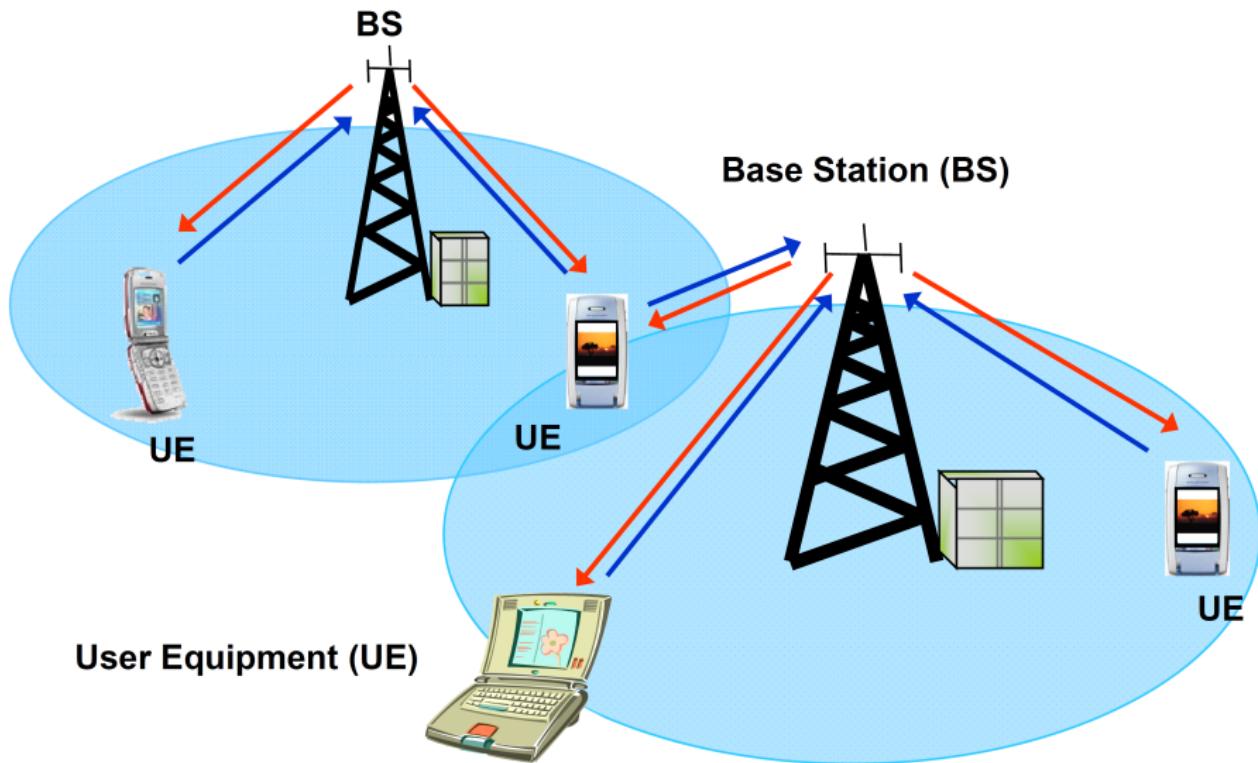
- Structure of Digital Communication Systems
- Classification of Signals
- Review on Sampling, Quantization, PCM
 - Sampling
 - Quantization
 - Encoding
- Random Processes
- Noise In Communication Systems
- Signal Transmission Through Linear Systems
- Baseband versus Passband - Signal Bandwidth

Structure of Digital Communication Systems



Examples of Digital Communication Systems

Wireless Cellular System



Why Digital Communication Systems?

Features of Digital Communication Systems

- Transmitter sends a waveform from a **finite set** of possible waveforms during a **limited time**
- Channel distorts, attenuates and adds noise to the transmitted signal
- Receiver decides which waveform was transmitted from the noisy received signal
- Probability of **erroneous decision** is an important measure for the **system performance**

Advantages of Digital Communication Systems

- The ability to use **regenerative repeaters**
- Different kinds of digital signals are **treated identically**
- **Immunity to noise**

Necessary Knowledge/Tools for the Design of DCS

- ① Classification of signals
- ② Random processes
- ③ Noise in communication systems
- ④ Signal transmission through linear systems
- ⑤ Bandwidth of signal

Classification of Signals

Signal Classifications

- Periodic - Aperiodic
- Continuous - Discrete
- Analog - Digital
- Power - Energy
- Deterministic - Random

Classification of Signals

Energy Signal - Power Signal

- **Energy Signal:** A signal is an energy signal if, and only if, it has nonzero but finite energy for all time, i.e. $0 < E < \infty$

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt = \lim_{T \rightarrow \infty} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

- **Power Signal:** A signal is a power signal if, and only if, it has finite but nonzero power for all time, i.e. $0 < P < \infty$

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

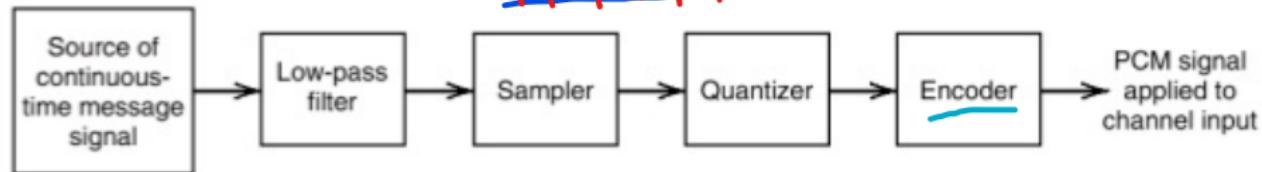
Classification of Signals

Deterministic - Random

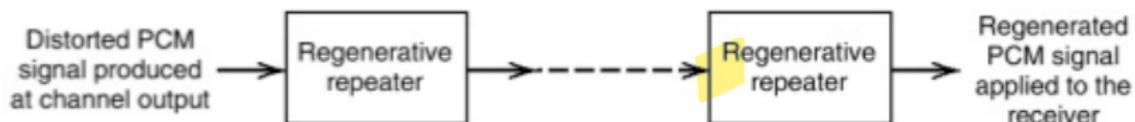
- **Deterministic signal:** No uncertainty with respect to the signal value at any time.
- **Random signal:** Some degree of uncertainty in signal values before it actually occurs.
 - ① Thermal noise in electronic circuits due to the random movement of electrons.
 - ② Reflection of radio waves from different layers of ionosphere.

General rule: Periodic and random signals are power signals. Signals that are both deterministic and non-periodic are energy signals

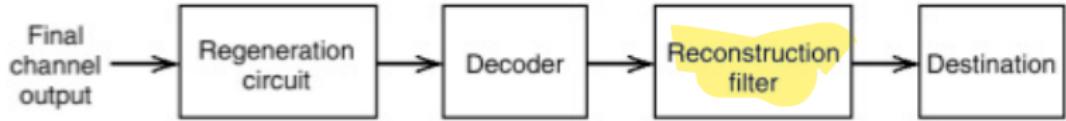
Pulse Code Modulation: Basic Elements



(a) Transmitter



(b) Transmission path



(c) Receiver

$$F = \frac{1}{\lambda}$$

Instantaneous Sampling

Definition

It is the process of transforming a message signal $m(t)$ into an **analog discrete** signal $m_s(t) = m(nT_s)$ with a sampling frequency f_s which is higher than **twice the highest frequency component W** of the message signal

$$m_s(t) = m(t)\delta_{T_s}(t)$$

$$M_s(f) = f_s \sum M(f - nf_s)$$



- Ensure **perfect reconstruction** at the Receiver
- Narrow rectangular pulses \Rightarrow instantaneous sampling
- Proceeded by an **anti-aliasing filter**
- Reduces the continuously varying message signal to a limited number of discrete values per second

Instantaneous Sampling: Sampling Theorem

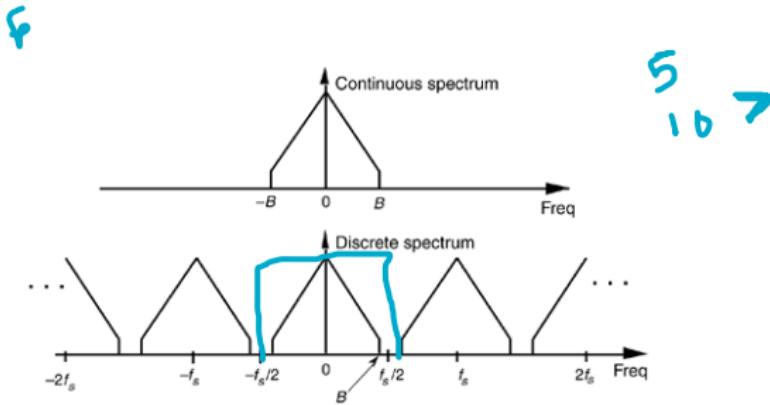
Theorem (Sampling Theorem)

A band-limited signal of finite energy, which has no frequency components higher than B Hz, is completely described by the values of the signal at instants of time separated by $\frac{1}{2B}$ seconds.

The signal may be completely recovered from the knowledge of its samples.

$$\text{Nyquist rate} = 2B$$

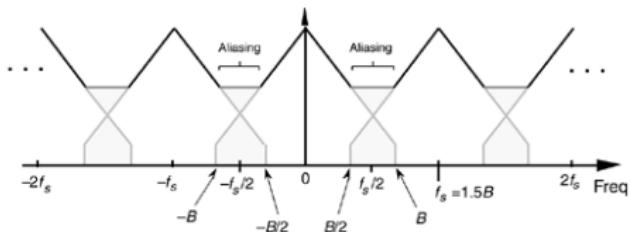
$$\text{Nyquist interval} = \frac{1}{2B}$$



Instantaneous Sampling: Aliasing

Definition of Aliasing

Aliasing is the phenomenon of a high-frequency component in the spectrum of the signal, seemingly taking on the identity of a lower frequency in the spectrum of its sampled version (occurs if $f_s < 2B$)



To combat the effects of aliasing;

- ① An anti-aliasing LPF is used prior to sampling to attenuate the non-essential high-frequency components of the signal
- ② The filtered signal is sampled at a rate slightly higher than the Nyquist rate

Reconstruction

In order to reconstruct the signal, a LPF is used such that

$$\begin{aligned} M_{\text{reconstructed}}(f) &= T_s M_s(f), \quad -f_s/2 < f < f_s/2 \\ &= \underline{M(f)} \end{aligned}$$

Then,

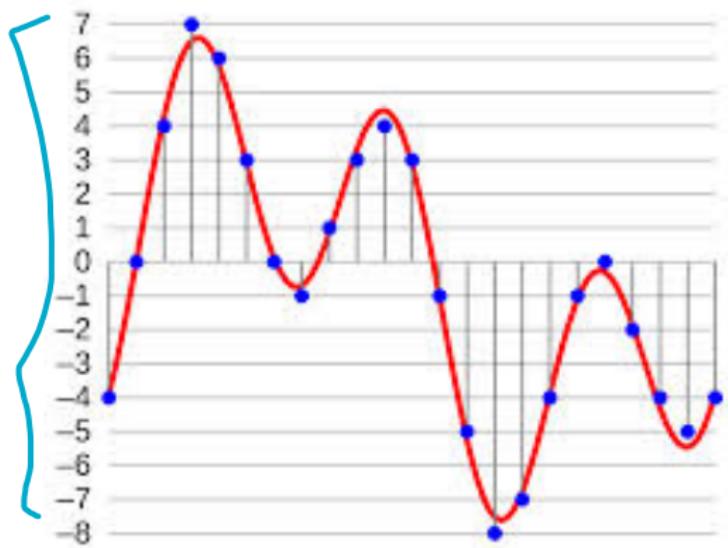
The Reconstructed Signal

$$m_{\text{reconstructed}}(t) = \sum m(nT_s) \operatorname{sinc}(f_s t - n)$$

Quantization

Definition

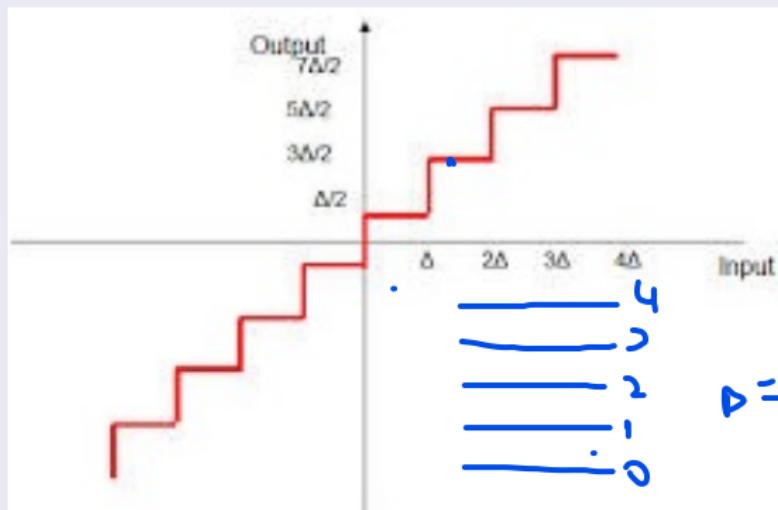
It is the process of transforming the sample amplitude $m(nT_s)$ into a **discrete amplitude** $\nu(nT_s)$ taken from a finite set of possible amplitudes



Uniform Mid-Rise Quantization

Quantizer Characteristic: Mid-Rise Staircase

The origin lies in the **middle of a rise**



1

$$v = 1.5$$

$$i = v$$

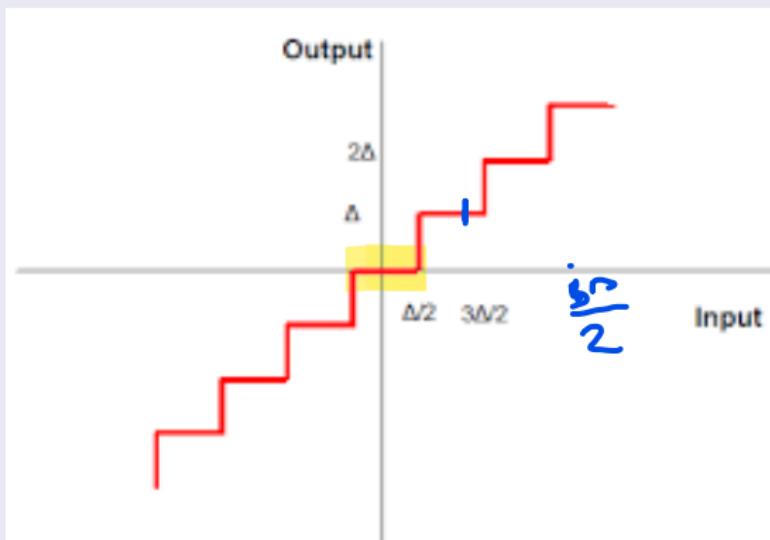
$$i = 1.2$$

$$Q = 1$$

Uniform Mid-Tread Quantization

Quantizer Characteristic: **Mid-Tread Staircase**

The origin lies in the **middle of a tread**



$$\Delta = 2$$

$$i = 1$$

$$\frac{\Delta}{2} = 1$$

$$i = 1.5$$

Quantization Error

Definition

It is the difference between the input signal, m , and the output signal ν

$$q = m - \nu$$



Notes:

- Maximum error: $q_{max} = \pm \frac{1}{2}$ step size
- Step size: $\Delta = \frac{\max - \min}{L-1}$
- As the step width \downarrow , the quantization error \downarrow
- It is better to use binary weighted number of levels, i.e. $L = 2^R$ bits/sample

Signal-to-Noise Ratio (SNR)

The signal-to-noise ratio (SNR) is one of the performance measures used to describe communication systems.

Quantization error is usually more significant than pulse detection errors.

SNR

It is the ratio of the useful signal power to the noise power.

Assuming a uniform quantizer with $\pm m_p$ peak levels, the average quantization noise level can be evaluated as

$$N_q = \widetilde{q^2} = \frac{\Delta^2}{12} = \frac{m_p^2}{3L^2}$$

Nq \rightarrow quantization noise

Quantizer's Output SNR

$$SNR = \frac{\widetilde{m^2}}{N_q} = \frac{3L^2}{m_p^2} P$$

Motivation

- The SNR is a function of the signal average power, it can be different from one user to another. It is needed to have SNR levels close to each other.
- The solution is to use smaller quantization steps for smaller signal amplitudes.
- Achieved through **compressing** the signal (μ -Law or A-Law), then applying a uniform quantizer. This is equivalent to non-uniform quantization.
- At the reconstruction end, and inverse process is applied using **expander**.
- The combined system is called **Compander**.

Non-Uniform Quantization

μ -Law Quantizer

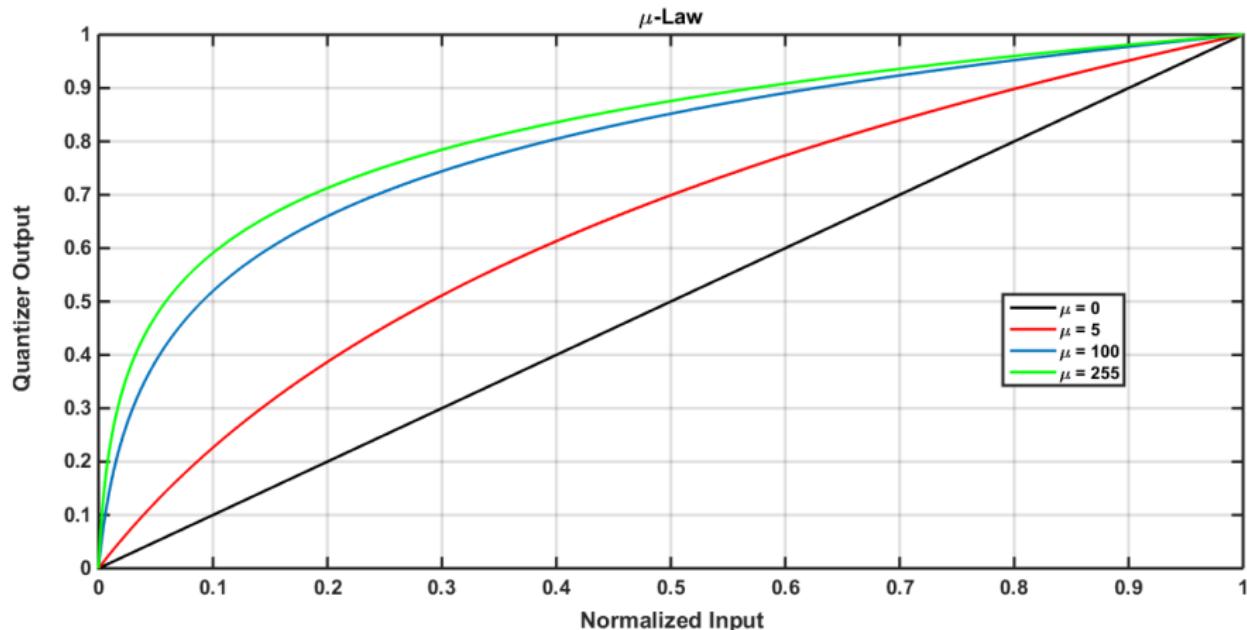
$$y = \frac{\ln(1 + \mu \hat{m})}{\ln(1 + \mu)}$$

A -Law Quantizer

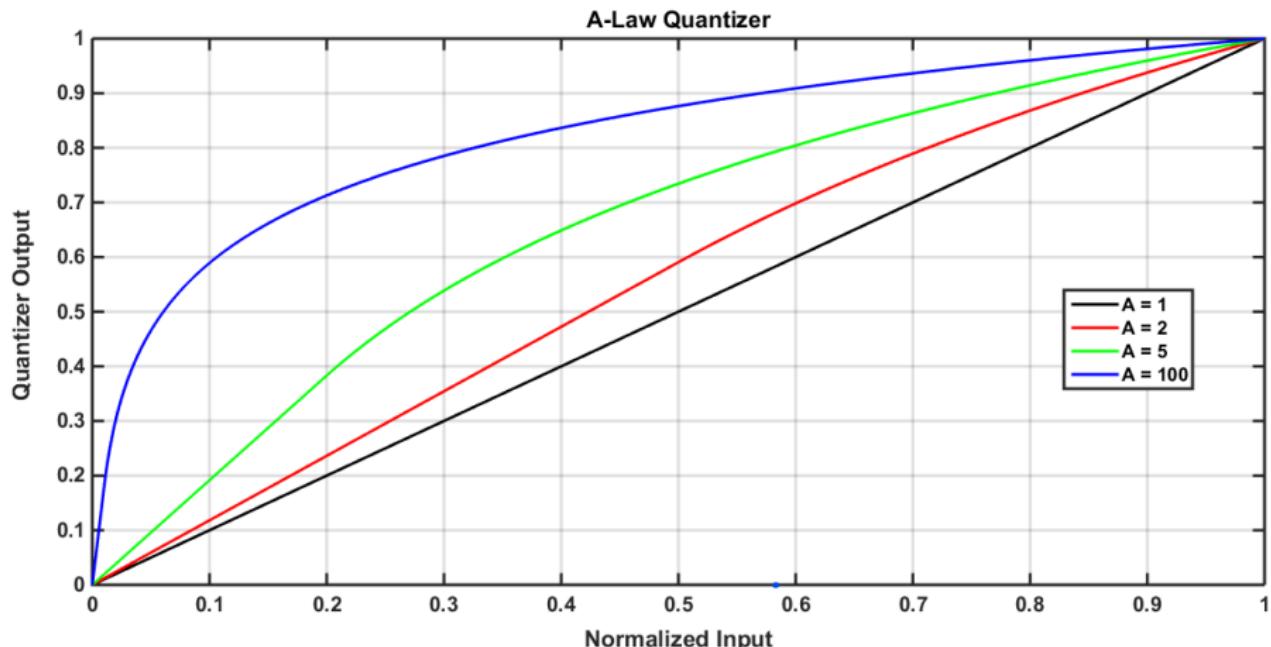
$$y = \begin{cases} \frac{A\hat{m}}{1 + \ln(A)}, & 0 \leq \hat{m} \leq 1/A \\ \frac{1 + \ln(A\hat{m})}{1 + \ln(A)}, & 1/A \leq \hat{m} \leq 1 \end{cases}$$

$$SNR \simeq \frac{3L^2}{[\ln(1 + \mu)]^2}$$

Non-Uniform μ -Law Quantization



Non-Uniform A-Law Quantization



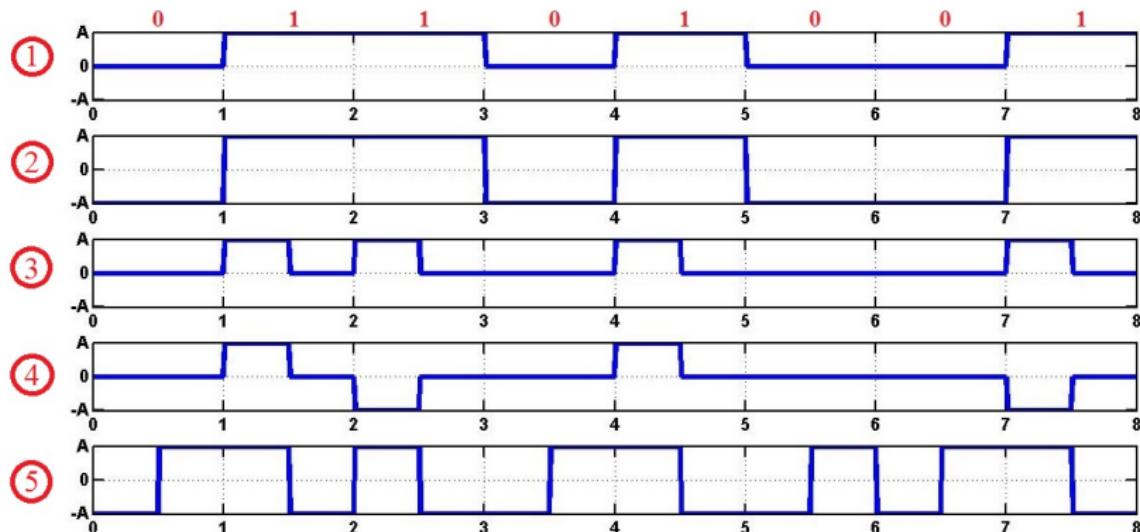
Encoding (Digital Baseband Modulation)

- ① Encoding is used to make the transmitted signal more robust to noise, interference and other channel impairments.
- ② It translates the discrete set of sample values to a more appropriate form.
- ③ Binary codes give the maximum advantage over the effects of noise in a transmission medium, because a binary symbol withstands a relatively high level of noise and it is easy to generate.

Line Codes

Line codes are used for the electrical representation of binary data stream.

- ① Unipolar NRZ signaling
- ② Polar NRZ signaling
- ③ Unipolar RZ signaling
- ④ Bipolar BRZ signaling (Alternate Mark Inversion)
- ⑤ Split-Phase signaling (Manchester Code)



Line codes usually differ in:

- ① **Spectral characteristics** (power spectral density and bandwidth efficiency): BW should be as small as possible + no DC component.
- ② **Power Efficiency**: for a given BW and a specified detection error probability, the transmitted power should be as small as possible.
- ③ **Error detection capability** (Interference and noise immunity): should be possible to detect and preferably correct errors.
- ④ **Bit synchronization capability**: should be possible to extract timing or clock information from the line code.
- ⑤ **Implementation cost and complexity**

Bit Rate - Transmission Bandwidth - Output SNR

A baseband signal with maximum power **P Watts** and bandwidth **B Hz**, sampled at the Nyquist rate, **2B Hz**, and quantized into **L = 2^R PCM levels**, using a uniform quantizer with $\pm m_p$ **peak levels**, to be transmitted over a channel of efficiency η **bits/sec/Hz**

Bit Rate

$$R_b = 2BR$$

Transmission Bandwidth

$$B_T = \frac{R_b}{\eta}$$

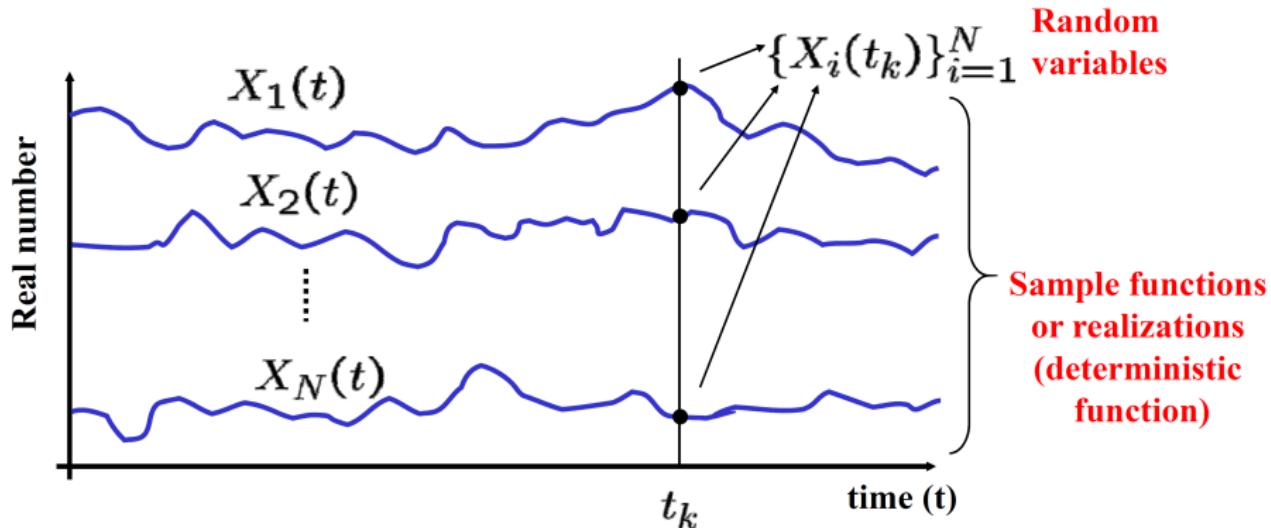
Output SNR

$$SNR = \frac{3P}{m_p^2} 2^{2R}$$

Random Processes

What is a Random Process?

A random process is a collection of **time functions**, or signals, corresponding to various outcomes of a random experiment. For each outcome, there exists a deterministic function, which is called a sample function or a realization.



Autocorrelation Function

ACF of a Random Process

$$R_x(t_i, t_j) = \mathcal{E}\{X(t_i)X^*(t_j)\}$$

ACF of a WSS Process

$$R_x(\tau) = \mathcal{E}\{X(t)X^*(t - \tau)\}$$

Properties of ACF

The ACF of a real WSS process is characterized by:

- ① Autocorrelation is symmetric around zero.
- ② Its maximum value occurs at the origin.
- ③ Its value at the origin is equal to the average power or energy.
- ④ The Fourier Transform of the ACF is called the **Spectral Density**



Spectral Density



Power SD of a WSS Random Process

$$G_X(f) = \mathcal{F}\{R_X(\tau)\}$$

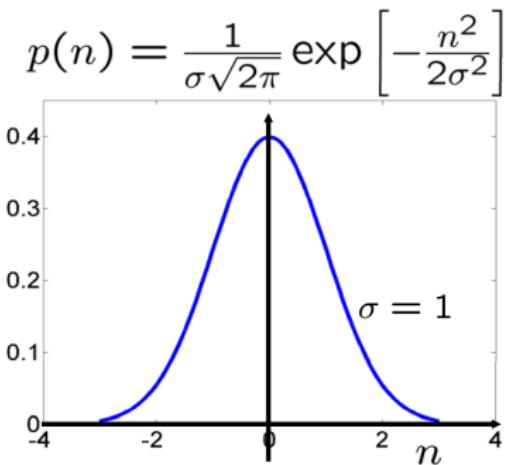
Energy SD of an Energy Signal

$$\Psi_X(f) = |\mathcal{F}\{x(t)\}|^2 = |X(f)|^2$$

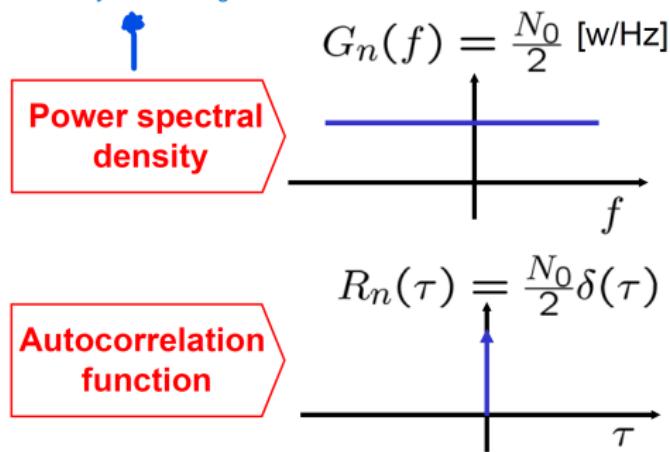
Noise In Communication Systems

There are many types of noise (unwanted signals) in communications systems. The most common type of noise is the **White Gaussian Noise**.

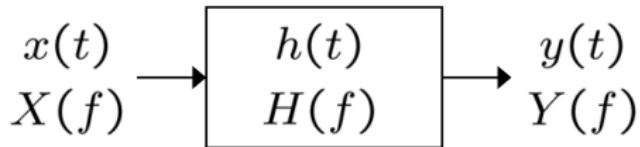
- ① **Gaussian:** because it is a **random process** that can be described by a zero-mean Gaussian distribution.
- ② **White:** because its **PSD** is flat.



density 34an el power lw7do hwa aslun scalar, lakin enta btshof el 3laka benha w ben el time, fa lw 3auz tgeb el power fe interval mo3yna bt3ml integeration



Signal Transmission Through Linear Systems



Input - Output Relationship

Deterministic Signals : $Y(f) = X(f)H(f)$ this is in the frequency domain

Random Signals : $G_Y(f) = G_X(f)|H(f)|^2$
power spectral density

Ideal Distortionless Transmission

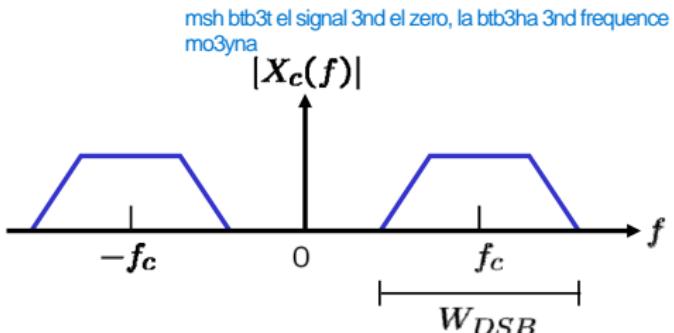
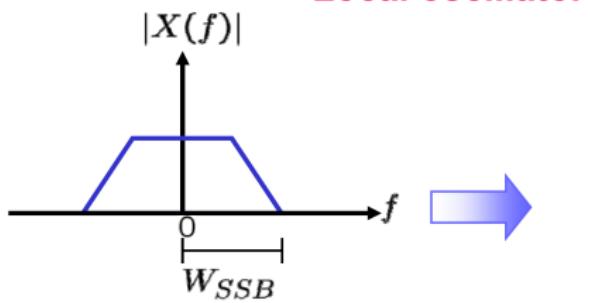
All the frequency components of the signal arrive at the destination with an **identical time delay**, and they are amplified or attenuated equally.

$$y(t) = K x(t - t_o) \quad \Rightarrow \quad Y(f) = K X(f) e^{-j2\pi f t_o}$$

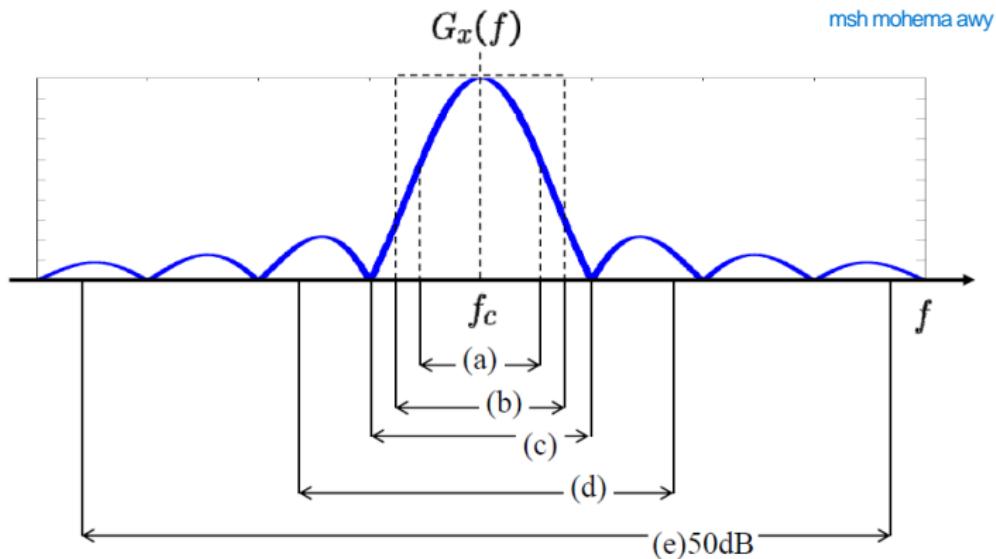
Baseband versus Passband

mshakel el channel enha tkon bt3ml attenuation w enha tkon bandlimited fa da bykhly el shape el tal3lk msh mzbot

$$x(t) \xrightarrow{\text{Baseband signal}} \textcircled{X} \xrightarrow{\cos(2\pi f_{ct})} x_c(t) = x(t) \cos(2\pi f_{ct}) \xrightarrow{\text{Bandpass signal}}$$



Definitions of Bandwidth



- (a) Half-power bandwidth
- (b) Noise equivalent bandwidth
- (c) Null-to-null bandwidth
- (d) Fractional power containment bandwidth
- (e) Bounded power spectral density
- (f) Absolute bandwidth

References



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Thank You

Questions ?

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