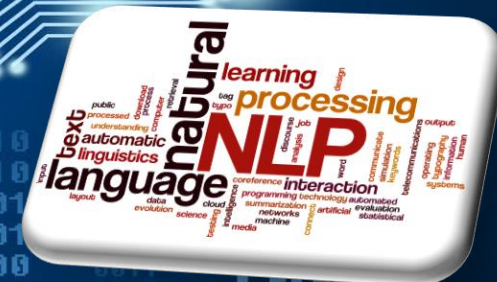




## ΣΥΛΟΓΗ ΔΕΛΤΙΩΝ

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# Machine Translation

- It is the use of computers to translate from one language to another.
- Machine translation (MT) focuses on a number of very **practical tasks**:
  - **Information access**: translate information on the web such as articles, reviews, ...
  - **Computer-aided translation (CAT)**: produce a draft translation that is fixed up in a post-editing phase by a human translator.
  - **In-the-moment human communication needs**: incremental translation, translating speech on-the-fly before the entire sentence is complete.
  - **Image-centric translation**: use OCR of the text on a phone camera image as input to an MT system to translate menus or street signs.
- The standard algorithm for MT is the **encoder-decoder network**, also called the **sequence to sequence network**, an architecture that can be implemented with RNNs or with Transformers.



# Machine Translation

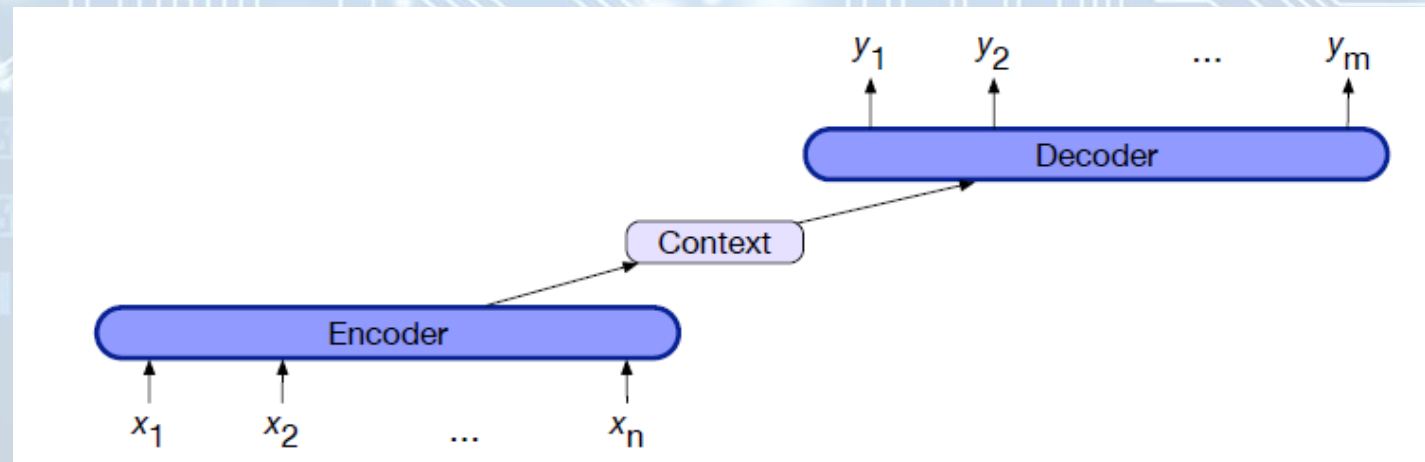
- Encoder-decoder or sequence-to-sequence models are used for a different kind of sequence modeling (either than POS-tagging/NER) in which the output sequence is a complex function of the entire input sequencer
  - mapping from a sequence of input words or tokens to a sequence of tags that are **not merely direct mappings from individual words**.
- Example: 

English:	<i>He wrote a letter to a friend</i>		
Japanese:	<i>tomodachi ni</i>	<i>tegami-o</i>	<i>kaita</i>
	friend	to letter	wrote

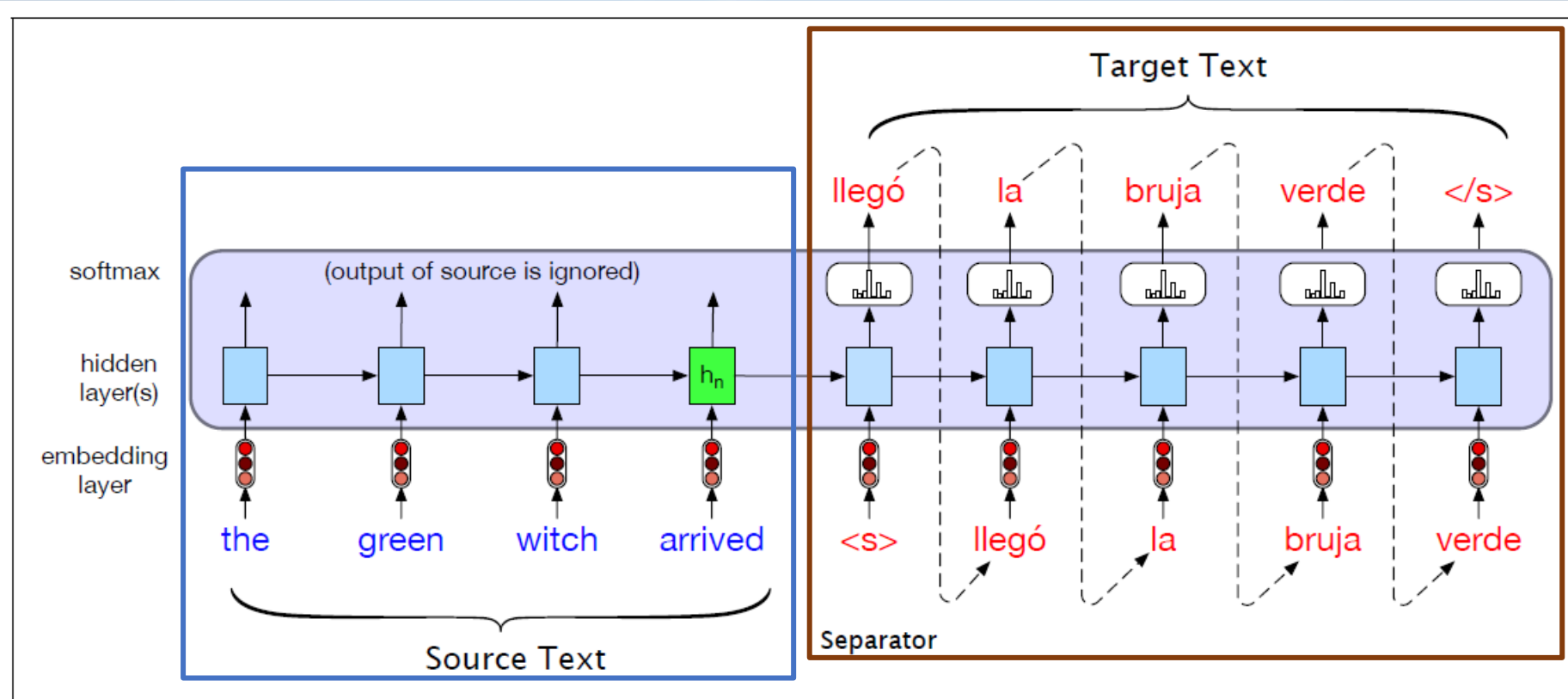
  - In English, the verb is in the middle of the sentence, while in Japanese, the verb *kaita* comes at the end. The Japanese sentence doesn't require the pronoun *he*, while English does.
- Encoder-decoder networks are very successful at handling these sorts of complicated cases of sequence mappings.
- The encoder-decoder algorithm is not just for MT, it's the state of the art for many other tasks where complex mappings between two sequences are involved:
  - **summarization** (where we map from a long text to its summary, like a title or an abstract)
  - **dialogue** (where we map from what the user said to what our dialogue system should respond)
  - **semantic parsing** (where we map from a string of words to a semantic representation like logic or SQL).

# Encoder-Decoder Model

- Are models capable of generating contextually appropriate, **arbitrary length**, output sequences.
- Applied to a very wide range of applications including machine translation, summarization, question answering, and dialogue.
- The key idea: is the use of an **encoder** network that takes an input sequence and creates a contextualized representation of it, often called the **context**. This representation is then passed to a **decoder** which generates a task-specific output sequence.



# Encoder-Decoder with RNNs



$$\mathbf{h}_t = g(\mathbf{h}_{t-1}, \mathbf{x}_t)$$
$$\mathbf{y}_t = f(\mathbf{h}_t)$$

- $g$  is an activation function like **tanh** or **ReLU**, a function of the input at time  $t$  and the hidden state at time  $t-1$ .

$$f(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

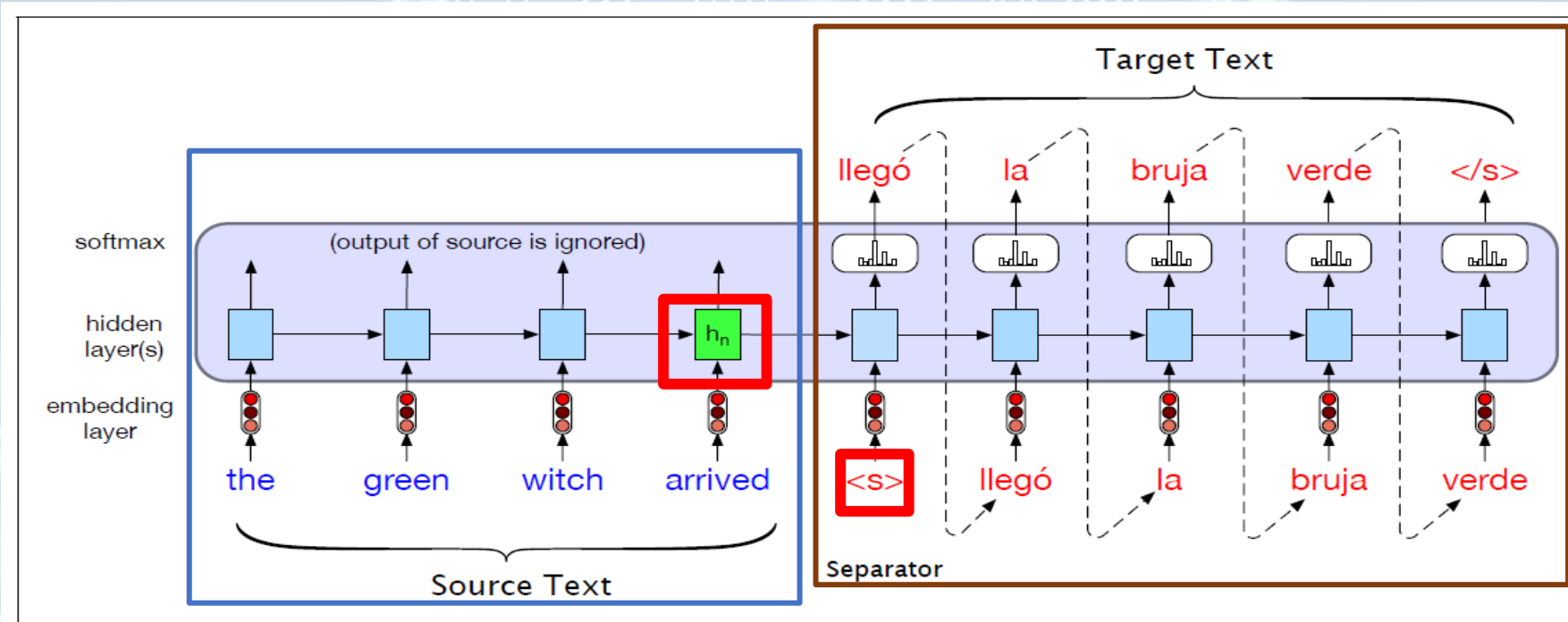
$$f(x) = \max(0, x)$$

- $f$  is a softmax over the set of possible vocabulary items.



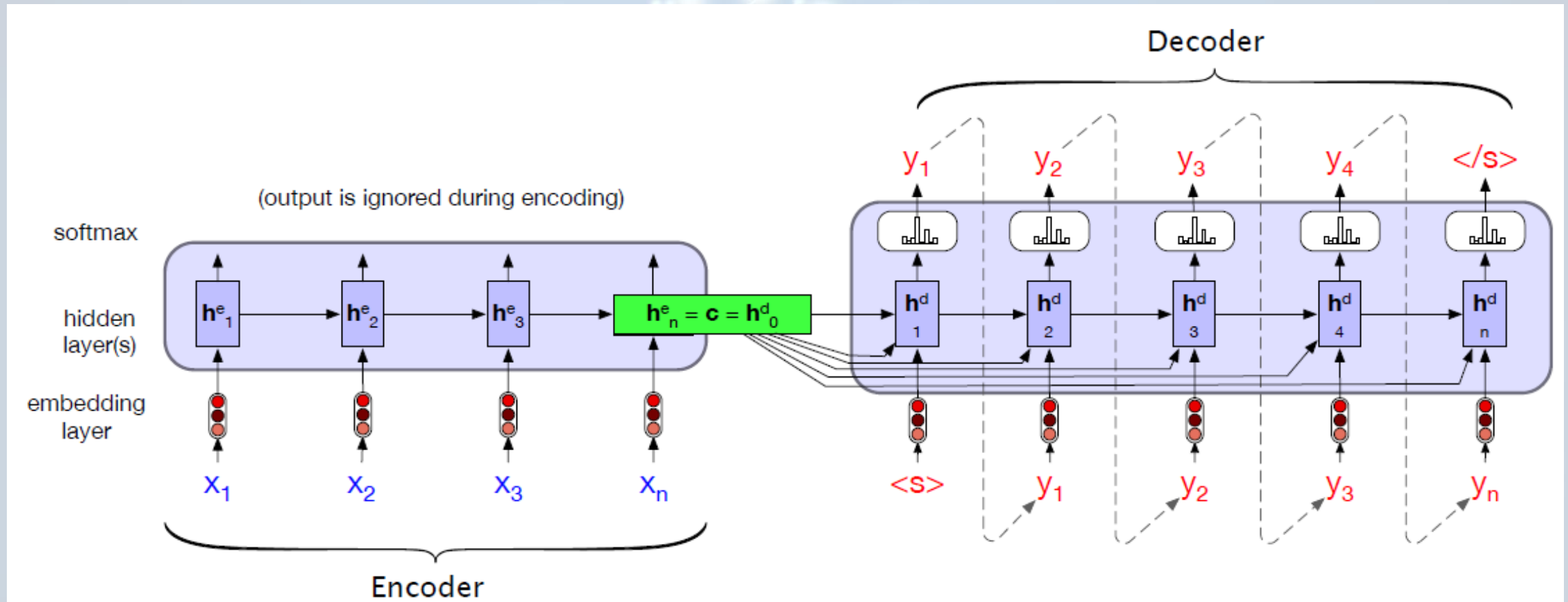
# Encoder-Decoder with RNNs

- In MT, note the addition of a **sentence separation marker** at the end of the source text, and then simply concatenate the target text.



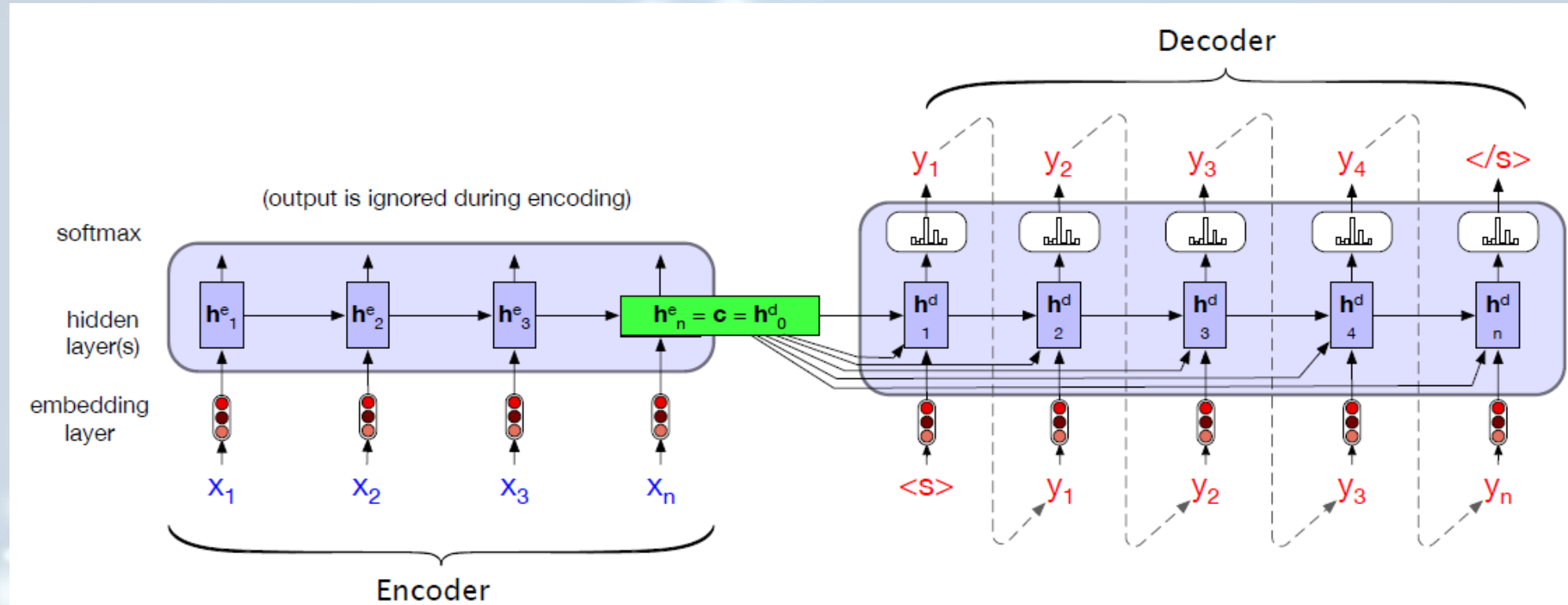
- An English source text ("the green witch arrived"), a sentence separator token  $\langle s \rangle$ , and a Spanish target text ("llegó la bruja verde").
- To translate a source text, we run it through the network performing forward inference to generate hidden states until we get to the end of the source " $h_n$ ". Then we begin **autoregressive generation**, asking for a word in the context of the hidden layer from the end of the source input.
- Subsequent words are conditioned on the previous hidden state and the embedding for the last word generated.

# Encoder-Decoder with RNNs



- The elements of the network on the left process the input sequence  $x$  and comprise the **encoder**.
- While our simplified figure shows only a single network layer for the encoder, stacked architectures are the norm, where the output states from the top layer of the stack are taken as the final representation.

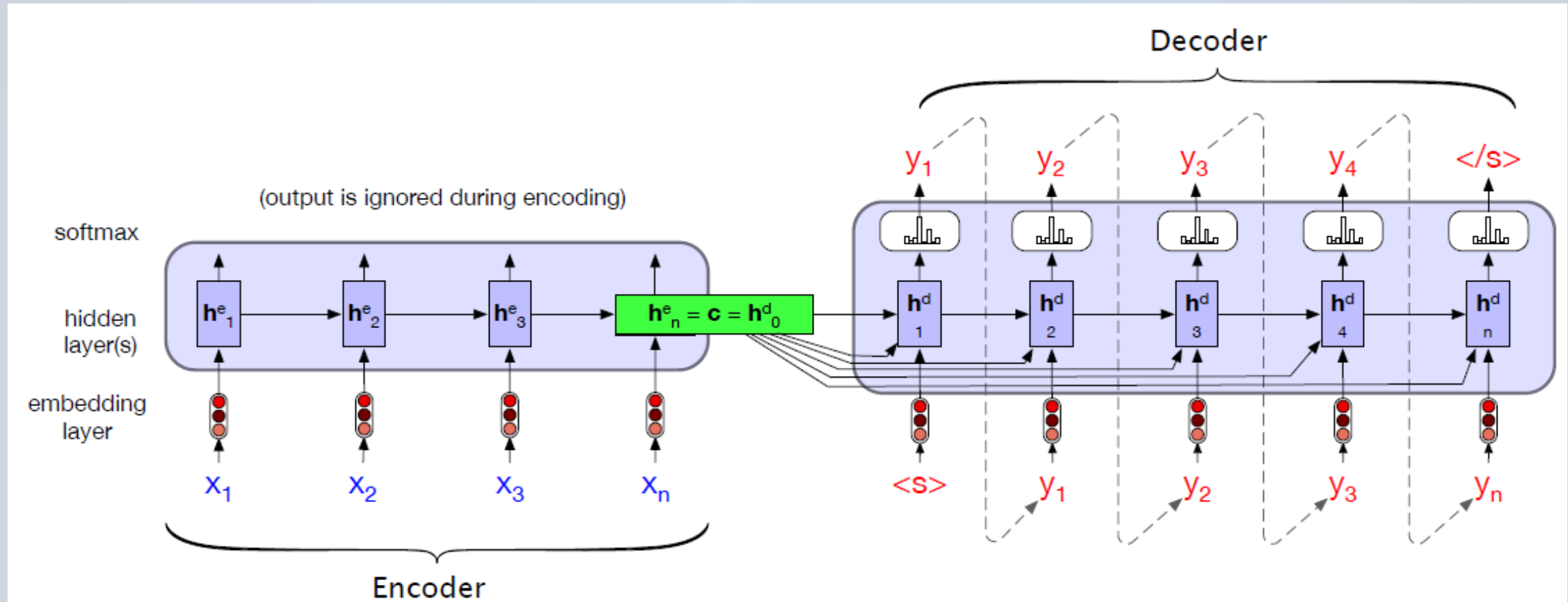
# Encoder-Decoder with RNNs



- The entire purpose of the encoder is to generate a contextualized representation of the input. This representation is embodied in the final hidden state of the encoder  $h^e_n$  called  $c$  for **context**, is then passed to the decoder.
- The **decoder** network on the right takes this state and uses it to initialize the first hidden state of the decoder. That is, the first decoder RNN cell uses  $c$  as its prior hidden state  $h^d_0$ .



# Encoder-Decoder with RNNs



- The decoder autoregressively generates a sequence of outputs, an element at a time, until an **end-of-sequence marker** is generated.
- Each hidden state is conditioned on the previous hidden state and the output generated in the previous state.

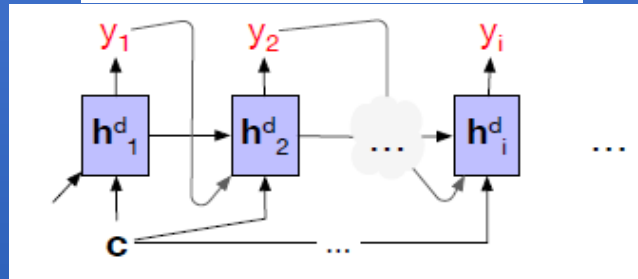
# Encoder-Decoder with RNNs

- One weakness of this approach as described so far is that the influence of the context vector  $c$  will decrease as the output sequence is generated.

## Solution:

Make the context vector  $c$  available at each step in the decoding process by adding it as a parameter to the computation of the current hidden state:

$$\mathbf{h}_t^d = g(\hat{y}_{t-1}, \mathbf{h}_{t-1}^d, \mathbf{c})$$



- Full equations for this version of the decoder in the basic encoder-decoder model:

In case of multiple layers

$$\begin{aligned} \mathbf{c} &= \mathbf{h}_n^e \\ \mathbf{h}_0^d &= \mathbf{c} \\ \mathbf{h}_t^d &= g(\hat{y}_{t-1}, \mathbf{h}_{t-1}^d, \mathbf{c}) \\ \mathbf{z}_t &= f(\mathbf{h}_t^d) \\ y_t &= \text{softmax}(\mathbf{z}_t) \end{aligned}$$

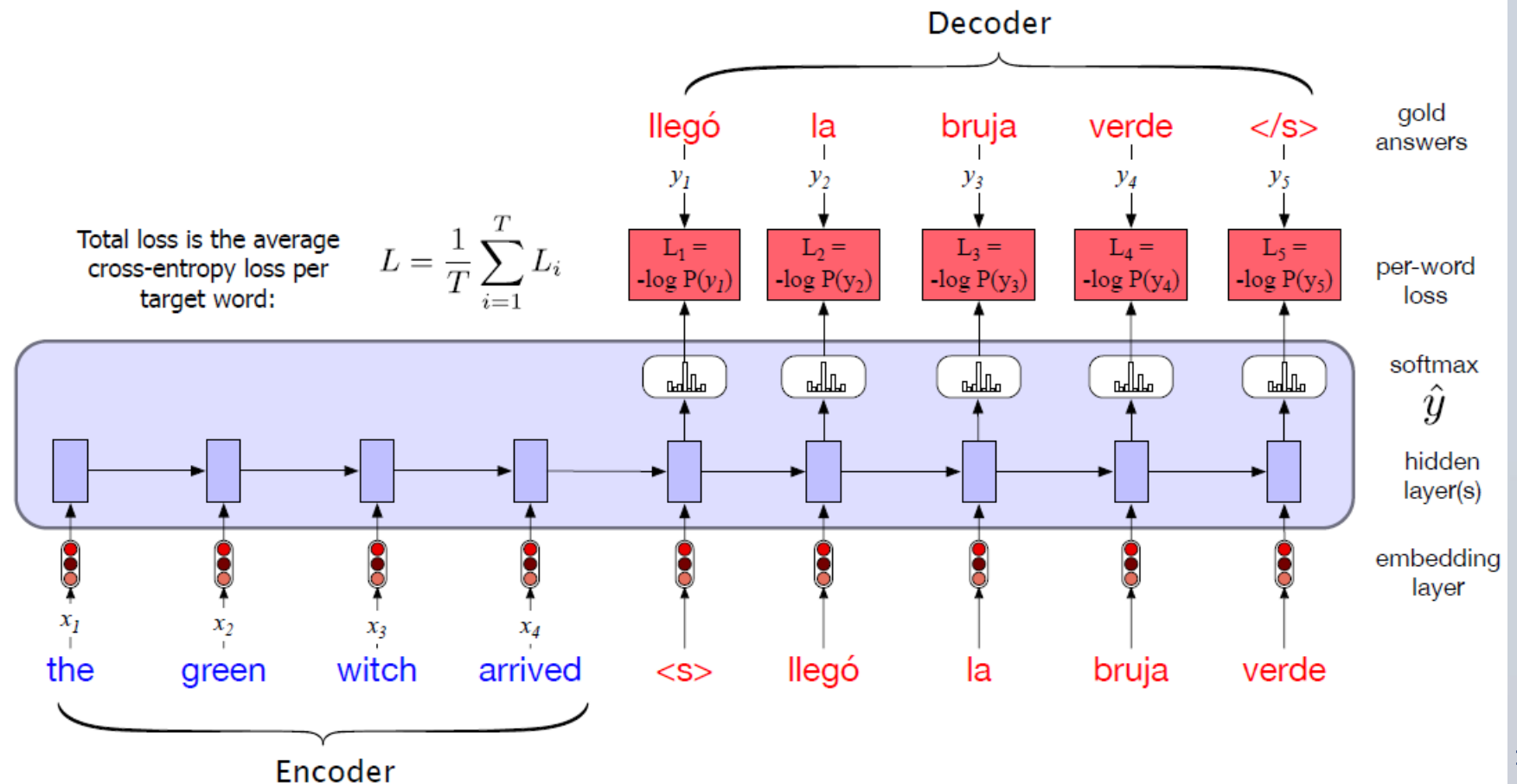
is the embedding for the output sampled from the softmax at the previous step

# Training the Encoder-Decoder Model

- Each training example is a tuple of paired strings, a source and a target.
- Concatenated with a separator token, these source-target pairs serve as training data.
- The training itself proceeds as with any RNN-based language model.
- The network is given the source text and then starting with the separator token is trained autoregressively to predict the next word.

In the decoder:

- **During inference:** it uses its own estimated output  $\hat{y}_t$  as the input for the next time step  $x_{t+1}$ .
- **During Training:** we usually don't propagate the model's softmax outputs, but use **teacher forcing** to force each input to the correct gold value → this speeds up training. We compute the softmax output distribution over  $\hat{y}_t$  to compute the loss at each token.





# Attention

- The simplicity of the encoder-decoder model is its clean separation of the encoder—which builds a representation of the source text—from the decoder, which uses this context to generate a target text.
  - this context vector is  **$h_n$** , the hidden state of the last (nth) time step of the source text.
- This final hidden state is thus acting as a **bottleneck**: it must represent absolutely everything about the meaning of the source text, since the only thing the decoder knows about the source text is what's in this context vector.
- Information at the beginning of the sentence, especially for long sentences, may not be equally well represented in the context vector.

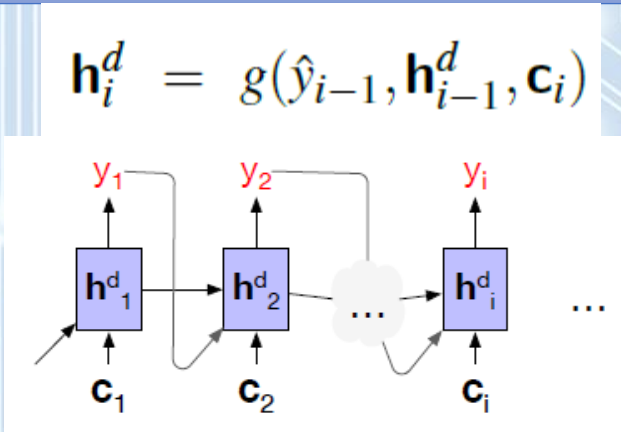
## Solution:

**attention mechanism** a way of mechanism allowing the decoder to get information from all the hidden states of the encoder, not just the last hidden state.

# Attention

- Create a **fixed-length** vector  $c$  by taking a **weighted sum** of all the encoder hidden states.
- The weights focus on ('attend to') a particular part of the source text that is relevant for the token the decoder is currently producing.

Attention thus replaces the static context vector with one that is **dynamic**, different for each token in decoding



- The first step in computing  $c_i$  is to compute how much to focus on each encoder state  $\rightarrow$  how relevant each encoder state is to the decoder state captured in  $h_{i-1}^d$

# Attention

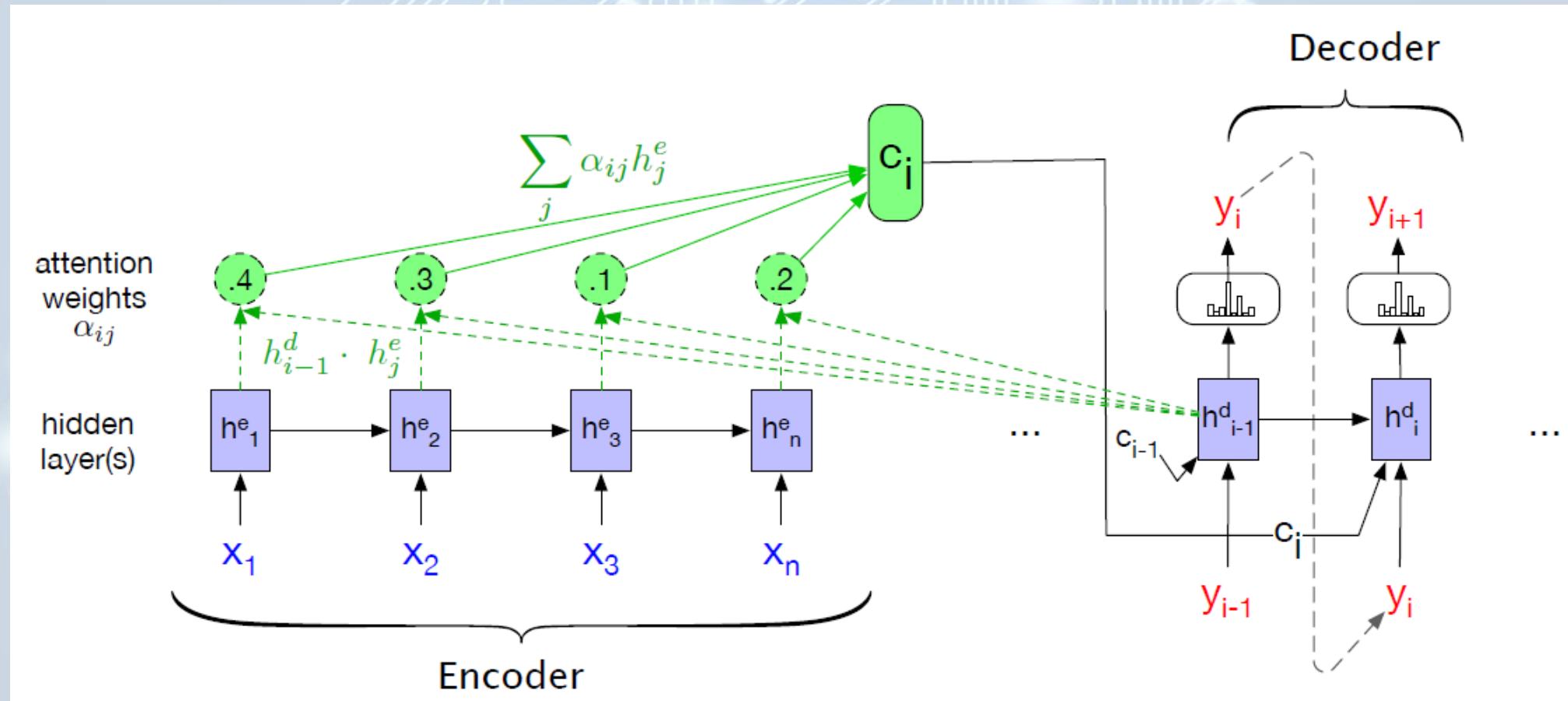
- To capture relevance: at each state  $i$  during decoding a score for each encoder state  $j$  is computed  $score(\mathbf{h}_{i-1}^d, \mathbf{h}_j^e)$
- The simplest such score “dot-product attention”  
$$score(\mathbf{h}_{i-1}^d, \mathbf{h}_j^e) = \mathbf{h}_{i-1}^d \cdot \mathbf{h}_j^e$$
- The score that results from this dot product is a scalar that reflects the degree of similarity between the two vectors.
- The vector of these scores across all the encoder hidden states gives us the relevance of each encoder state to the current step of the decoder.
- We normalize these scores with a softmax to create a vector of weights  $\alpha_{ij}$ , that tells us the **proportional relevance** of each encoder hidden state  $j$  to the prior hidden decoder state  $\mathbf{h}_{i-1}^d$ .

$$\begin{aligned}\alpha_{ij} &= \text{softmax}(score(\mathbf{h}_{i-1}^d, \mathbf{h}_j^e) \quad \forall j \in e) \\ &= \frac{\exp(score(\mathbf{h}_{i-1}^d, \mathbf{h}_j^e))}{\sum_k \exp(score(\mathbf{h}_{i-1}^d, \mathbf{h}_k^e))}\end{aligned}$$



# Attention

- The context vector for the current decoder state: 
$$\mathbf{c}_i = \sum_j \alpha_{ij} \mathbf{h}_j^e$$



Note: the encoder and decoder hidden states must have the same dimensionality.

# Note

- The described decoding is **greedy**: at each time step in decoding, the output  $y_t$  is chosen by computing a softmax over the set of possible outputs (the vocabulary, in the case of language modeling or MT), and then choosing the **highest probability token** → the choice is **locally optimal**
- Greedy search is not optimal, and may not find the highest probability translation → the problem is that the token that looks good to the decoder now might turn out later to have been the wrong choice!
- Another generally used decoding method in MT is called **beam search**. In beam search, instead of choosing the best token to generate at each timestep, we keep  $k$  possible tokens at each step.





# Thank You

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