



# Lecture 7

## Time Series Analysis

Dr. Lydia Wahid

# Agenda

-  Time Series Analysis Introduction
-  Time Series Analysis Techniques
-  Exponential Smoothing
-  Auto Regression
-  Moving Average Model
-  ACF
-  PACF
-  ARMA
-  ARIMA

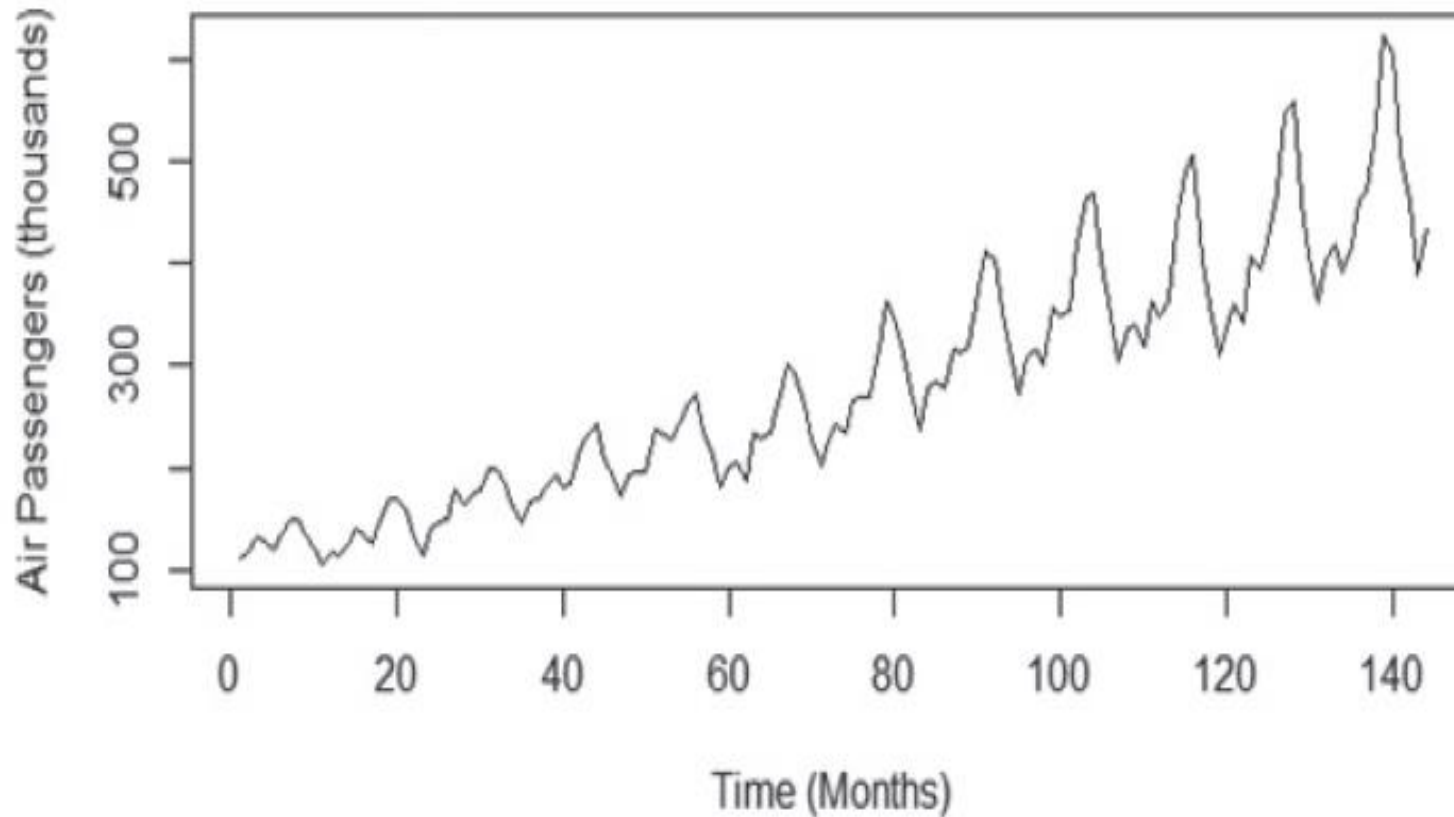


# Time Series Analysis Introduction

# Time Series Analysis Introduction

- **Time series analysis** attempts to model the underlying structure of observations taken over time.
- A *time series* is an ordered sequence of equally spaced values over time.
- For example, the following figure provides a plot of the monthly number of international airline passengers over a 12-year period:

# Time Series Analysis Introduction



In this example, the time series consists of an ordered sequence of 144 values.

# Time Series Analysis Introduction

- Following are the goals of Time Series Analysis:
  - Identify and model the structure of the time series.
  - Forecast future values in the time series.
- Time series analysis has many applications in finance, economics, biology, engineering, retail, and manufacturing.

# Time Series Analysis Introduction

- **Univariate Time Series** consists of the values taken by a *single* variable at periodic time instances over a period.
- **Multivariate Time Series** consists of the values taken by *multiple* variables at the same periodic time instances over a period.
- A time series can consist of the following components:
  - Trend
  - Seasonality
  - Cyclic
  - Random

# Time Series Analysis Introduction

- ***Trend*** refers to the long-term movement in a time series.
  - It indicates whether the observation values are increasing or decreasing over time.
  - Examples of trends are a steady increase in sales month over month.
- ***Seasonality*** component describes the fixed, periodic fluctuation in the observations over time.
  - As the name suggests, the seasonality component is often related to the calendar.
  - For example, monthly retail sales can fluctuate over the year due to the weather and holidays.



# Time Series Analysis Introduction

- ***Cyclic*** component also refers to a periodic fluctuation, but one that is not as fixed as in the case of a seasonality component.
  - For example, retail sales are influenced by the general state of the economy.
  - Thus, a retail sales time series can often follow the lengthy boom-bust cycles of the economy.
- ***Random*** component refers to random fluctuations.
  - These fluctuations are unforeseen, uncontrollable and unpredictable.
  - For example: earthquakes, wars, floods.



# Time Series Analysis Techniques

# Time Series Analysis Techniques

- **Naïve Methods:** These are simple estimation techniques, such as the predicted value is given the value equal to **mean of preceding values** of the time dependent variable, or **previous actual value**.
- **Exponential Smoothing:** Exponential smoothing uses a **weighted average of past time series values** as a forecast.
- **Auto Regression:** Auto regression predicts the values of future time periods as a **function of values at previous time periods**.

# Time Series Analysis Techniques

- **Moving Average Model:** The value of a time series is a linear function of the **errors at previous time steps** of a stationary timeseries.
- **ARMA Model:** Auto-**R**egressive **M**oving-**A**verage models the value of a time series as a linear function of previous values and errors at previous time steps of a stationary timeseries.
- **ARIMA Model:** Auto-**R**egressive **I**ntegrated **M**oving-**A**verage is similar to ARMA with *differencing* applied to use it for nonstationary time series.

# Time Series Analysis: Exponential Smoothing

- Exponential smoothing uses a weighted average of past time series values as a forecast.
- The weights become smaller as the observations move farther into the past. The exponential smoothing equation follows:

$$F_{t+1} = \alpha Y_t + (1 - \alpha)F_t$$

where

$F_{t+1}$  = forecast of the time series for period  $t + 1$

$Y_t$  = actual value of the time series in period  $t$

$F_t$  = forecast of the time series for period  $t$

$\alpha$  = smoothing constant ( $0 \leq \alpha \leq 1$ )

# Time Series Analysis: Exponential Smoothing

- The forecast for period  $t + 1$  is a weighted average of the **actual value in period  $t$**  and the **forecast for period  $t$** .
- The weight given to the actual value in period  $t$  is the **smoothing constant  $\alpha$**  and the weight given to the forecast in period  $t$  is  **$1 - \alpha$** .
- The exponential smoothing forecast for any period is actually a weighted average of all the previous actual values of the time series.

# Time Series Analysis: Exponential Smoothing

- The general equation will be:

$$\hat{y}_{T+1|T} = \sum_{j=0}^{T-1} \alpha(1 - \alpha)^j y_{T-j} + (1 - \alpha)^T \ell_0.$$

The process has to start somewhere, so we let the first fitted value at time 1 be denoted by  $\ell_0$

- The last term becomes tiny for large T. So, the weighted average form leads to the forecast Equation:

$$\hat{y}_{T+1|T} = \alpha y_T + \alpha(1 - \alpha)y_{T-1} + \alpha(1 - \alpha)^2 y_{T-2} + \cdots,$$

# Time Series Analysis: Exponential Smoothing

- Let us illustrate by working with a time series involving only three periods of data:  $Y_1$ ,  $Y_2$ , and  $Y_3$ .
- To initiate the calculations, we let  $F_1$  equal the actual value of the time series in period 1; that is,  **$F_1 = Y_1$** . Hence, the forecast for period 2 is:

$$\begin{aligned} F_2 &= \alpha Y_1 + (1 - \alpha)F_1 \\ &= \alpha Y_1 + (1 - \alpha)Y_1 \\ &= Y_1 \end{aligned}$$



# Time Series Analysis: Exponential Smoothing

- The forecast for period 3 is:

$$F_3 = \alpha Y_2 + (1 - \alpha)F_2 = \alpha Y_2 + (1 - \alpha)Y_1$$

- Finally, substituting this expression for  $F_3$  in the expression for  $F_4$ , we obtain:

$$\begin{aligned} F_4 &= \alpha Y_3 + (1 - \alpha)F_3 \\ &= \alpha Y_3 + (1 - \alpha)[\alpha Y_2 + (1 - \alpha)Y_1] \\ &= \alpha Y_3 + \alpha(1 - \alpha)Y_2 + (1 - \alpha)^2 Y_1 \end{aligned}$$

# Time Series Analysis: Exponential Smoothing

➤ **Example:** Consider the following data:

Week	Time Series Value
1	17
2	21
3	19
4	23
5	18
6	16
7	20

- To start the calculations we set the exponential smoothing forecast for period 2 equal to the actual value of the time series in period 1.
- Thus, with  $Y_1 = 17$ , we set  $F_2 = 17$  to initiate the computations.
- Referring to the time series data, we find an actual time series value in period 2 of  $Y_2 = 21$ . Thus, period 2 has a forecast error of  $21 - 17 = 4$ .

# Time Series Analysis: Exponential Smoothing

- **Example:** Continuing with the exponential smoothing computations using a smoothing constant of  $\alpha = 0.2$ , we obtain the following forecast for period 3:

$$F_3 = .2Y_2 + .8F_2 = .2(21) + .8(17) = 17.8$$

- Once the actual time series value in period 3,  $Y_3 = 19$ , is known, we can generate a forecast for period 4 as follows:

$$F_4 = .2Y_3 + .8F_3 = .2(19) + .8(17.8) = 18.04$$

- ...and so on.

# Time Series Analysis: Exponential Smoothing

## ➤ How to choose the value of the smoothing constant $\alpha$ ?

- Although any value of  $\alpha$  between 0 and 1 is acceptable, some values will yield better forecasts than others.
- The new forecast  $F_{t+1}$  is equal to the previous forecast  $F_t$  plus an adjustment, which is the smoothing constant  $\alpha$  times the most recent forecast error,  $Y_t - F_t$ .
- That is, the forecast in period  $t + 1$  is obtained by adjusting the forecast in period  $t$  by a fraction of the forecast error.

# Time Series Analysis: Exponential Smoothing

## ➤ How to choose the value of the smoothing constant $\alpha$ ?

- If the time series contains large random variability, a small value of the smoothing constant is preferred.
- For a time series with relatively little random variability, forecast errors are more likely to represent a change in the level of the series. Thus, larger values of the smoothing constant provide the advantage of quickly adjusting the forecasts; this allows the forecasts to react more quickly to changing conditions.
- We will choose the value of  $\alpha$  based on the **Mean Squared Error (MSE)**.

# Time Series Analysis: Exponential Smoothing

- The table shows the MSE for  $\alpha=0.2$

Sales Time Series with Smoothing Constant $\alpha = .2$				
Week	Time Series Value	Forecast	Forecast Error	Squared Forecast Error
1	17			
2	21	17.00	4.00	16.00
3	19	17.80	1.20	1.44
4	23	18.04	4.96	24.60
5	18	19.03	-1.03	1.06
6	16	18.83	-2.83	8.01
7	20	18.26	1.74	3.03
8	18	18.61	-.61	.37
9	22	18.49	3.51	12.32
10	20	19.19	.81	.66
11	15	19.35	-4.35	18.92
12	22	18.48	3.52	12.39
		Totals	10.92	98.80

# Time Series Analysis: Exponential Smoothing

## ➤ How to choose the value of the smoothing constant $\alpha$ ?

- Would a different value of  $\alpha$  provide better results in terms of a lower MSE value?
- The most straightforward way to answer this question is simply to try another value for  $\alpha$

# Time Series Analysis: Exponential Smoothing

- The table shows the MSE for  $\alpha=0.3$
- Thus, after trying  $\alpha=0.2$  and  $\alpha=0.3$ ,  $\alpha=0.2$  is preferred since it yields lower MSE.

Sales Time Series with Smoothing Constant $\alpha = .3$				
Week	Time Series Value	Forecast	Forecast Error	Squared Forecast Error
1	17			
2	21	17.00	4.00	16.00
3	19	18.20	.80	.64
4	23	18.44	4.56	20.79
5	18	19.81	-1.81	3.28
6	16	19.27	-3.27	10.69
7	20	18.29	1.71	2.92
8	18	18.80	-.80	.64
9	22	18.56	3.44	11.83
10	20	19.59	.41	.17
11	15	19.71	-4.71	22.18
12	22	18.30	3.70	13.69
		Totals	8.03	102.83



# Time Series Analysis: Auto Regression

- For a stationary time series,  $y_t$ , an *autoregressive model of order  $p$* , denoted AR( $p$ ), is expressed as shown in the equation:

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} + \varepsilon_t$$

where  $\delta$  is a constant for a nonzero-centered time series:

$\phi_j$  is a constant for  $j = 1, 2, \dots, p$

$y_{t-j}$  is the value of the time series at time  $t - j$

$\phi_p \neq 0$

$\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$  for all  $t$

A particular point in the time series can be expressed as a **linear combination of the prior  $p$  values** of the time series plus a **random error term**.

# Time Series Analysis: Auto Regression

- $\mathcal{E}t$  is often called a *white noise process* and is used to represent random, independent fluctuations that are part of the time series.
- **Stationary Time Series** means that behavior of a system is characterized by **non**-changing statistical properties over **time** such as the mean, variance and autocorrelation.
- **Time series** are **stationary** if they do not have trend or seasonal effects.

# Time Series Analysis: Auto Regression

- Different methods can be used for parameters estimations such as:
  - Maximum-Likelihood estimation
  - Expectation Maximization (EM) algorithm
  - Kalman Filter

# Time Series Analysis: Auto Regression

- Once the parameters of the autoregression have been estimated, the autoregression can be used to forecast an arbitrary number of periods into the future.
- First use  $t$  to refer to the first period for which data is not yet available; substitute the known preceding values into the autoregressive equation.
- Next, use  $t$  to refer to the next period for which data is not yet available; again the autoregressive equation is used to make the forecast.

# Time Series Analysis: Moving Average Model

- For a time series,  $y_t$ , a *moving average model of order  $q$* , denoted MA( $q$ ), is expressed as shown in the following equation:

$$y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \cdots + \theta_q \varepsilon_{t-q},$$

where  $C$  is a constant

$\varepsilon_{t-j}$  is the value of error at time series  $y_{t-j}$

$\theta_j$  for  $j=1,2,..q$  are constants

The value of a time series is a **linear combination** of the **current white noise** term and the **prior  $q$  white noise** terms.

# Stationary Time Series

- It is necessary to remove any trends or seasonality in the time series. This step is necessary to achieve a time series with certain properties to which autoregressive and moving average models can be applied.
- Such a time series is known as a **stationary time series**. A time series,  $y_t$  for  $t=1,2,3,\dots$  is a stationary time series if the following three conditions are met:
  - a. The expected value (mean) of  $y_t$  is a constant for all values of  $t$ .
  - b. The variance of  $y_t$  is finite.  $\sigma^2 = \frac{\sum (x_i - \mu)^2}{n}$
  - c. The covariance of  $y_t$  and  $y_{t+h}$  depends only on the value of  $h=0,1,2,\dots$  for all  $t$  (not  $t$ ).

# Stationary Time Series

## ➤ Covariance:

- The covariance of  $y_t$  and  $y_{t+h}$  is a measure of how the two variables, vary together.
- If two variables are independent of each other, their **covariance is zero**.
- If the variables change together in the same direction, the variables have a **positive covariance**.
- Conversely, if the variables change together in the opposite direction, the variables have a **negative covariance**.

# Stationary Time Series

## ➤ Covariance:

- For a stationary time series, by condition (a), the mean is a constant, the covariance notation is:

$$\text{cov}(h) = E[(y_t - \mu)(y_{t+h} - \mu)]$$

- By part (c), the covariance between two points in the time series can be nonzero, as long as the value of the covariance is only a function of  $h$ . An example for  $h = 3$ :

$$\text{cov}(3) = \text{cov}(y_1, y_4) = \text{cov}(y_2, y_5) = \dots$$



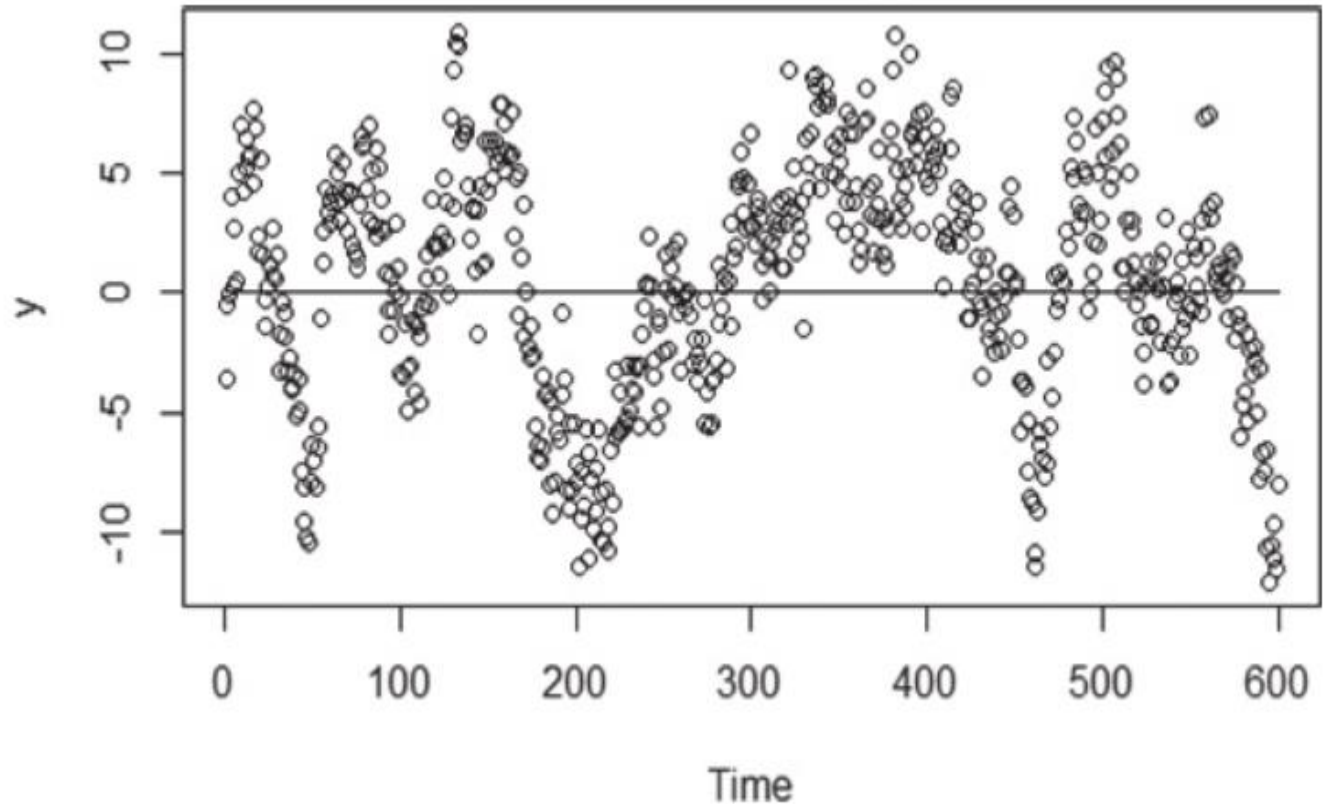
# Autocorrelation Function (ACF)

## ➤ Covariance VS Correlation

- Covariance is a quantitative measure of the degree to which the deviation of one variable from its mean is related to the deviation of another variable from its mean.
- Correlation quantifies the **strength** and **direction** of relationship between two variables (normalized covariance).
- Correlation can only take values between +1 and -1. A correlation of +1 indicates that random variables have a direct and strong relationship.

# Autocorrelation Function (ACF)

- It appears that each point is somewhat dependent on the past points.
- The difficulty is that the plot does not provide insight into the covariance of the variables in the time series and its underlying structure.



# Autocorrelation Function (ACF)

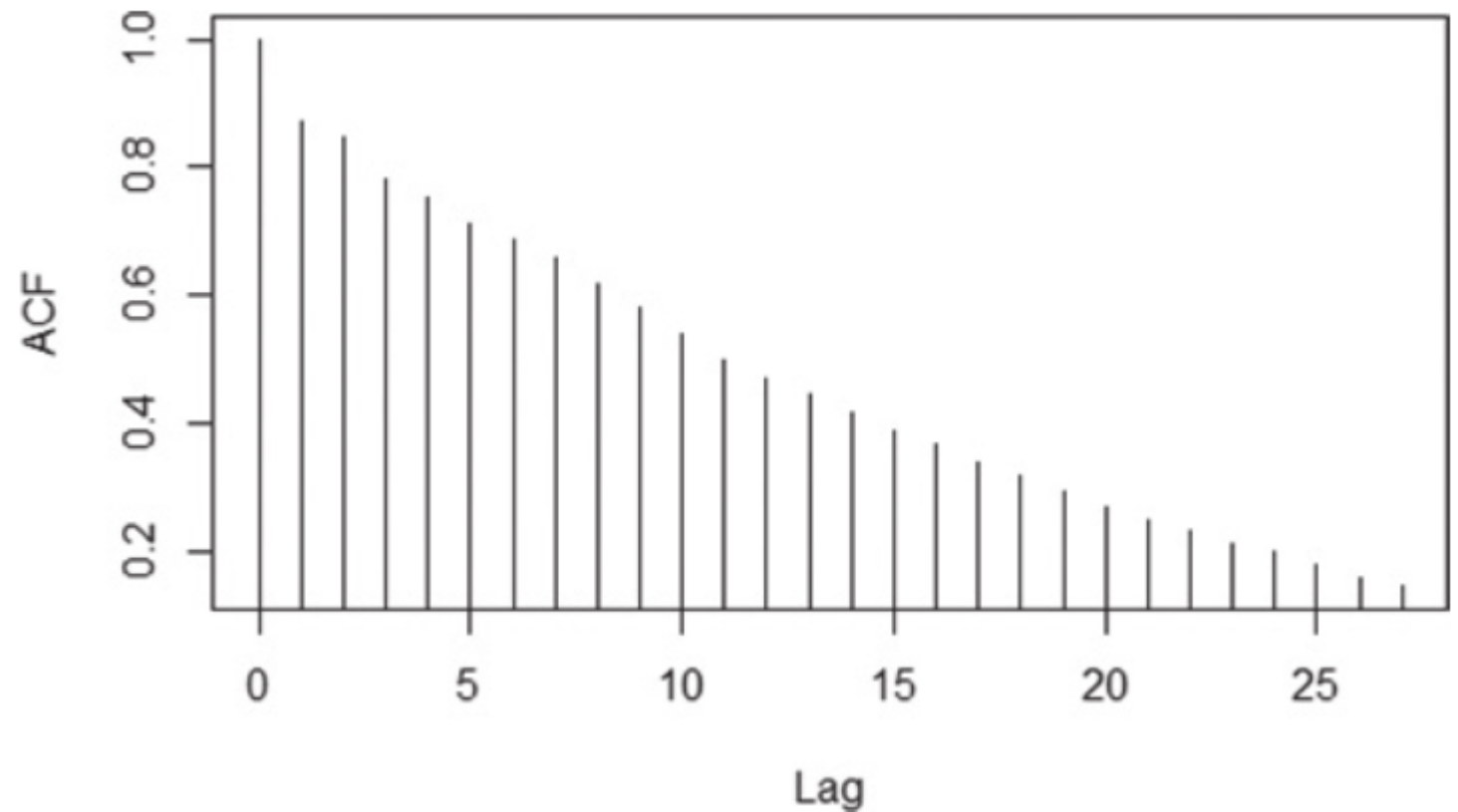
- The plot of autocorrelation function (ACF) provides this insight. For a stationary time series, the ACF is defined as:

$$ACF(h) = \frac{cov(y_t, y_{t+h})}{\sqrt{cov(y_t, y_t) cov(y_{t+h}, y_{t+h})}} = \frac{cov(h)}{cov(0)}$$

- Because the  $cov(0)$  is the variance, the ACF is analogous to the correlation function of two variables and the value of the ACF falls between  $-1$  and  $1$ .
- Thus, the closer the absolute value of  $ACF(h)$  is to  $1$ , the more useful  $y_t$  can be a predictor of  $y_{t+h}$

# Autocorrelation Function (ACF)

- Using the same dataset, the plot of the ACF is as shown in the figure.
- By convention, the quantity  $h$  in the ACF is referred to as the lag, the difference between the time points  $t$  and  $t + h$ .



# Autocorrelation Function (ACF)

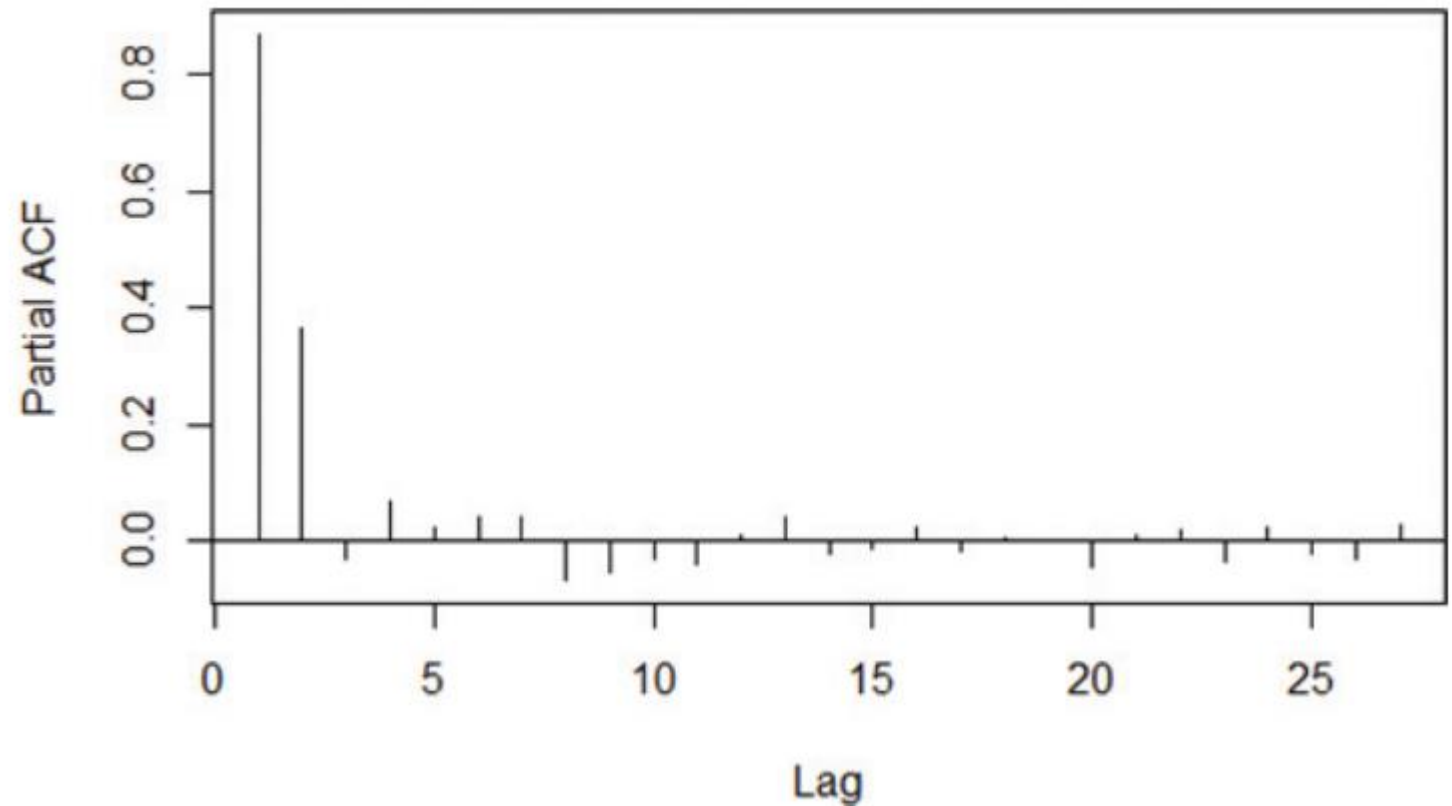
- At lag 0, the ACF provides the correlation of every point with itself. So ACF(0) always equals 1.
- According to the ACF plot, at lag 1 the correlation between  $y_t$  and  $y_{t+h}$  is approximately 0.9, which is very close to 1. So  $y_{t-1}$  appears to be a good predictor of the value of  $y_t$ .
- Because ACF(2) is around 0.8,  $y_{t-2}$  also appears to be a good predictor of the value of  $y_t$ .
- A similar argument could be made for lag 3 to lag 8. (All the autocorrelations are greater than 0.6.)
- In other words, a model can be considered that would express  $y_t$  as a linear sum of its previous 8 terms. Such a model is known as an autoregressive model of order 8.

# Partial autocorrelation function (PACF)

- If  $y_t$  and  $y_{t-1}$  are correlated, then  $y_{t-1}$  and  $y_{t-2}$  are also correlated.  $y_t$  and  $y_{t-2}$  might be correlated because they are both connected to  $y_{t-1}$  not because  $y_{t-2}$  contains information that can be used to forecast  $y_t$
- What is needed is a measure of the autocorrelation between  $y_t$  and  $y_{t+h}$  for  $h = 1, 2, 3...$  with the effect of  $y_{t+1}$  to  $y_{t+h-1}$  values excluded from the measure.
- The partial autocorrelation function (PACF) provides such a measure.

# Partial autocorrelation function (PACF)

- For the earlier example, the PACF plot illustrates that after lag 2, the value of the PACF is sharply reduced.
- Such a plot indicates that an **AR(2)** is a good candidate model for the time series given.



# Time Series Analysis: ARMA

- In fact, it is often useful to combine the two representations  $AR(p)$  and an  $MA(q)$  into one model.
- The combination of these two models for a stationary time series results in an *Autoregressive Moving Average model*,  $ARMA(p,q)$ , which is expressed as shown in the following equation:



# Time Series Analysis: ARMA

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} \\ + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}$$

where  $\delta$  is a constant for a nonzero-centered time series

$\phi_j$  is a constant for  $j = 1, 2, \dots, p$

$\phi_p \neq 0$

$\theta_k$  is a constant for  $k = 1, 2, \dots, q$

$\theta_q \neq 0$

$\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$  for all  $t$

# Time Series Analysis: ARIMA

- Time series may not be stationary.
- Since such a time series does not meet the requirement of a constant expected value (mean), the data needs to be adjusted.
- An option is to compute the difference between successive y-values. This is known as *differencing*.
- In other words, for the n values in a given time series compute the differences as shown in the following equation:

$$d_t = y_t - y_{t-1} \quad \text{for } t=2,3,\dots,n$$

# Time Series Analysis: ARIMA

- It is often necessary to account for seasonal patterns in time series. The seasonal pattern could be determined, and the time series appropriately adjusted.
- An alternative is to use a seasonal autoregressive integrated moving average model, denoted  $ARIMA(p,d,q) \times (P,D,Q)_s$  where:
  - $p$ ,  $d$ , and  $q$  are the same as defined previously.
  - $s$  denotes the seasonal period.
  - $P$  is the number of terms in the AR model across the  $s$  periods.
  - $D$  is the number of differences applied across the  $s$  periods.
  - $Q$  is the number of terms in the MA model across the  $s$  periods.

# Time Series Analysis: ARIMA

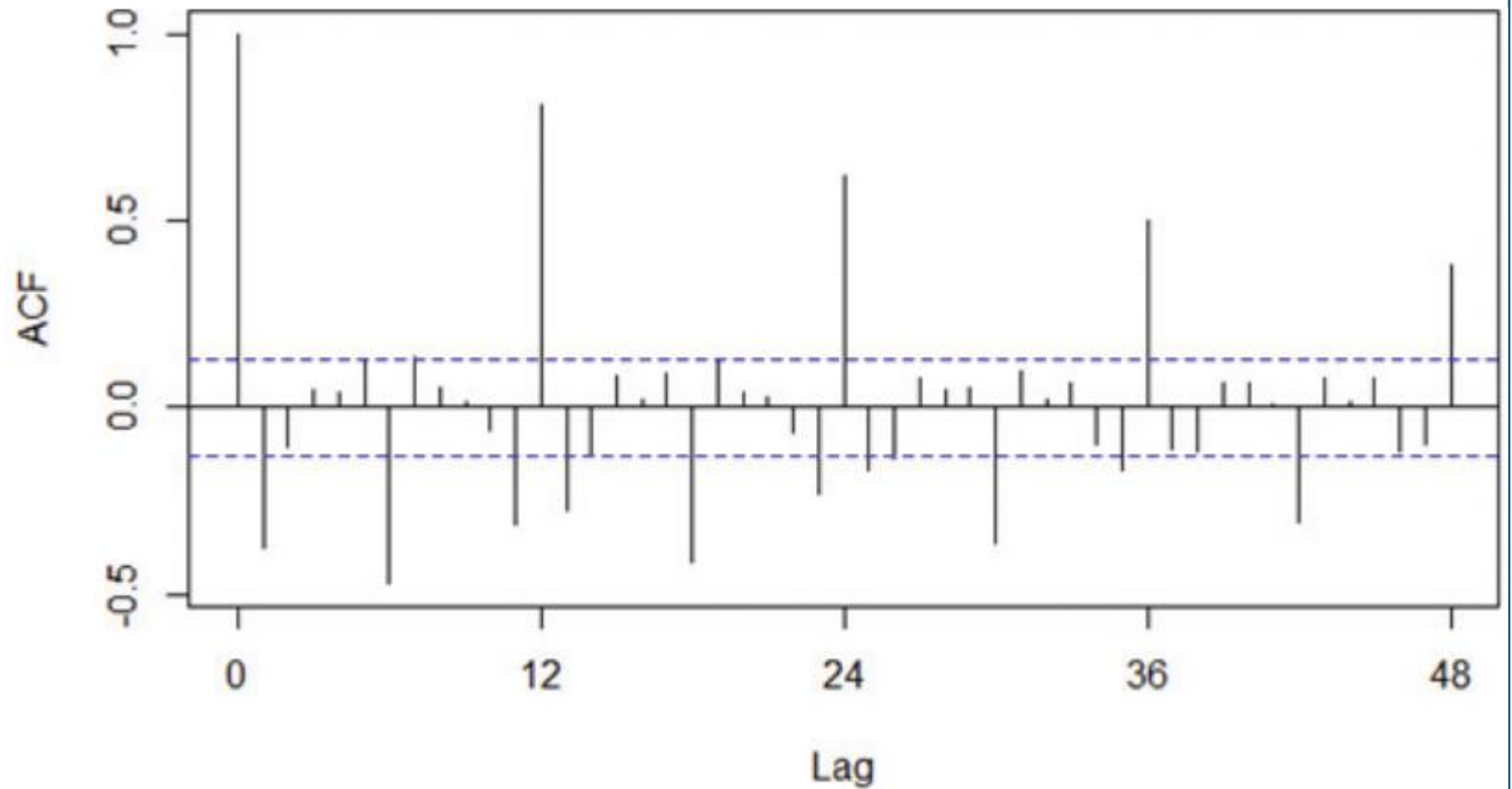
- For a time series with a seasonal pattern, following are typical values of  $s$ :
- 52 for weekly data
  - 12 for monthly data
  - 7 for daily data

# Time Series Analysis: ARIMA

- For a large country, the monthly gasoline production measured in millions of barrels has been obtained for the past 240 months (20 years).
- A market research firm requires some short-term gasoline production forecasts to assess the petroleum industry's ability to deliver future gasoline supplies and the effect on gasoline prices.

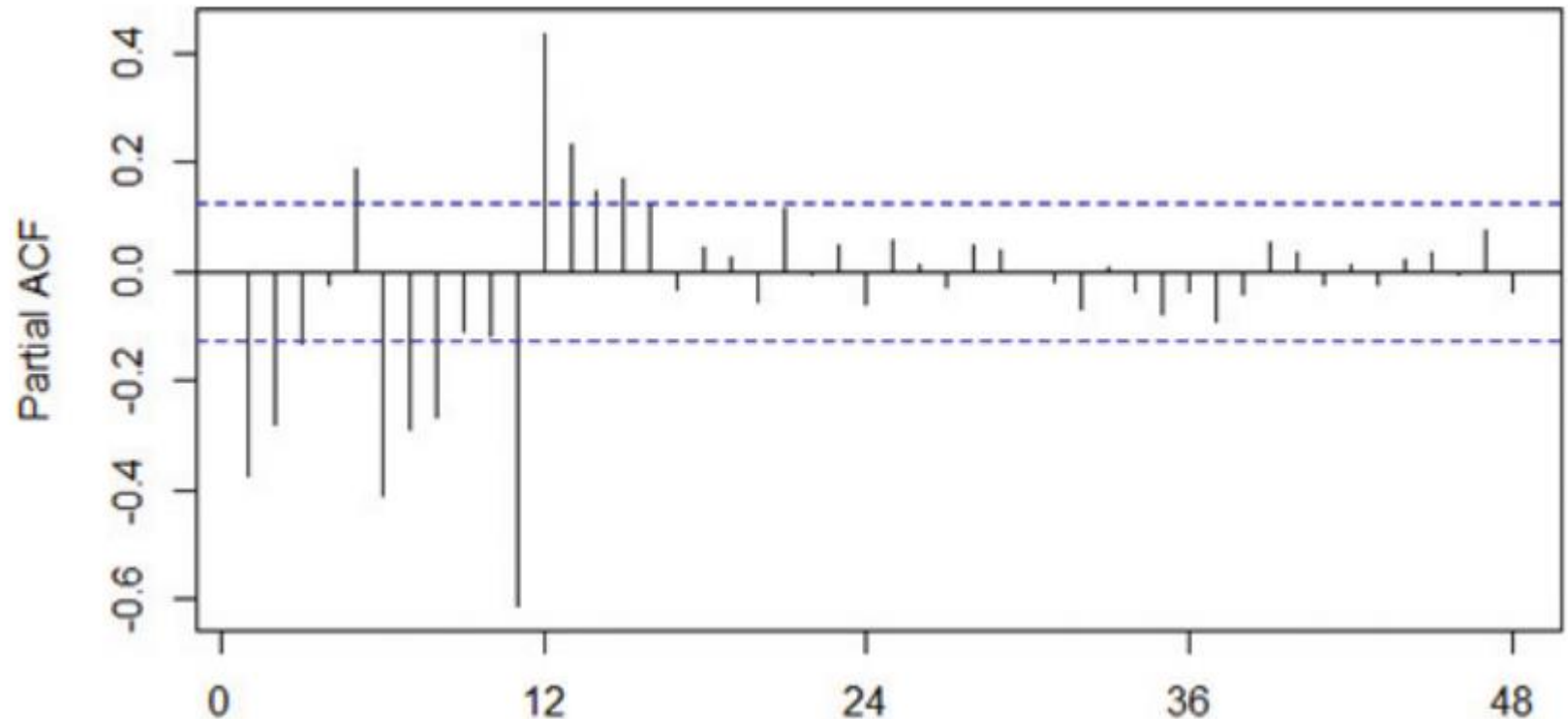
# Time Series Analysis: ARIMA

- The figure shows several significant ACF values. The slowly decaying ACF values at lags 12, 24, 36, and 48 are of particular interest.
- The figure indicates a seasonal autoregressive pattern every 12 months.



# Time Series Analysis: ARIMA

- In the PACF plot, value at lag 12 is quite large, but the PACF values are close to zero at lags 24, 36, and 48.
- Thus, a seasonal AR(1) model with period = 12 will be considered.



# Time Series Analysis: ARIMA

- The `arima()` function in R uses Maximum Likelihood Estimation (MLE) to estimate the model coefficients.
- The values of the model coefficients are determined such that the value of the log likelihood function is maximized.
- The R output provides several measures that are useful for comparing the appropriateness of one fitted model against another fitted model. These measures are:
  - AIC (Akaike Information Criterion)
  - AICc (Akaike Information Criterion, corrected)
  - BIC (Bayesian Information Criterion)



# Time Series Analysis: ARIMA

- Because these criteria impose a penalty based on the number of parameters included in the models, the preferred model is the fitted model with the smallest AIC, AICc, or BIC value.
- The following table provides the information criteria measures for the ARIMA fitted models of the gasoline problem.

# Time Series Analysis: ARIMA

ARIMA Model (p,d,q) × (P,Q,D) <sub>s</sub>	AIC	AICc	BIC
(0,1,0) × (1,0,0) <sub>12</sub>	1561.38	1561.43	1568.33
(0,1,1) × (1,0,0) <sub>12</sub>	1472.43	1472.53	1482.86
(0,1,2) × (1,0,0) <sub>12</sub>	1474.25	1474.42	1488.16
(1,1,0) × (1,0,0) <sub>12</sub>	1504.29	1504.39	1514.72
(1,1,1) × (1,0,0) <sub>12</sub>	1474.22	1474.39	1488.12

In this dataset, the  $(0,1,1) \times (1,0,0)_{12}$  model does have the lowest AIC, AICc, and BIC values compared to the same criterion measures for the other ARIMA models.

# Time Series Analysis: Box-Jenkins

- Developed by George Box and Gwilym Jenkins, is the **Box-Jenkins** methodology for time series analysis.
- Box-Jenkins methodology is used to apply an **ARIMA** (or **ARMA**) model to a given time series.
- The Box-Jenkins method applies iteratively the following three steps:
  1. Identification
  2. Estimation
  3. Diagnostic Checking

# Time Series Analysis: Box-Jenkins

## 1. Identification:

- Assess whether the time series is stationary, and if not, make it stationary.
- Identify the parameters of an ARIMA model for the data (i.e.  $p$  and  $q$ )
  - Two diagnostic plots can be used to help choose the  $p$  and  $q$ :  
**Autocorrelation Function** and **Partial Autocorrelation Function**

## 2. Estimation:

- Calculate the coefficients of the model.

## 3. Diagnostic Checking:

- Evaluate the fitted model in the context of the available data and check for areas where the model may be improved.



Thank You