

### Motivation

Save energy, save Earth

Maximize lifetime of mobile nodes operated by batteries

Maximize spatial reuse of the constrained radio resource

# **Energy Conservation Approaches**

#### Power Save

Turn off transceivers when possible

### Power Control

Lower transmission power as much as possible

## Sample Power Management Protocols

Power Save

- PAMAS
- Power Save in IEEE 802.11 Ad Hoc Mode

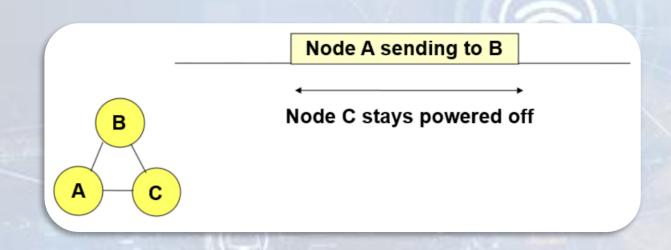
Power Control

Power Control in 802.11

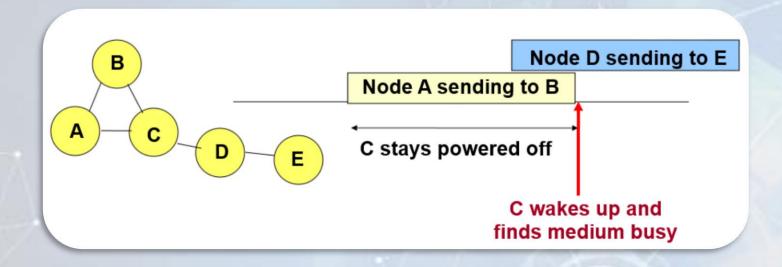
#### **PAMAS**

Power-Aware Multi-Access Protocol with Signaling

- Power off while any neighbor is transmitting to someone else.
- Node knows to keep off for how long from the message header.



### **PAMA Problem**



- How does node C know its remaining sleep duration if it wakes up to finds that D is transmitting to someone else?
- As C misses the message header.

# **PAMAS Signaling Solution**

Use separate control channel

- If a node wakes up to find the medium busy:
  - Determine the longest remaining transmission time using binary probe
    - Send a probe with parameter L (longest packet duration)
      - → "I'll power off for duration L"
    - Neighbors transmitting respond if remaining time between [L/2, L] → (>=L/2)
    - So the node goes back to sleep.
    - If no response, probe [L/4,L/2]
    - · And so on.

# Disadvantages of PAMAS

- Use of a separate control channel
  - Nodes have to be able to receive on the control channel while they are transmitting on the data channel
  - And also transmit on data and control channels simultaneously

 A node (such as C) should be able to determine when probe responses from multiple senders collide

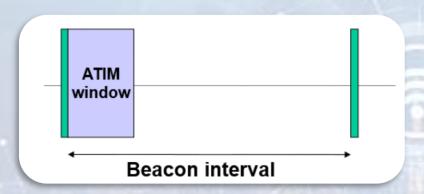
## Another Proposal in PAMAS

- To avoid the probing, a node should switch off the interface for data channel, but not for the control channel (which carries RTS/CTS packets)
  - Advantage:
    - Each sleeping node always knows how long to sleep by watching the control channel
  - Disadvantage:
    - This may not be useful when hardware is shared for the control and data channels
    - Interference may happen on the control channel

# Power Save in IEEE 802.11 Ad Hoc Mode

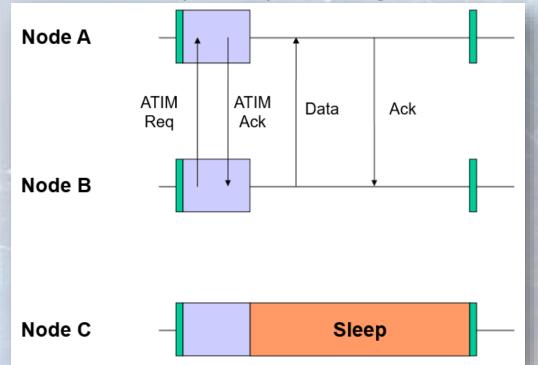
Time is divided into beacon intervals

Each beacon interval begins with an ATIM window



### Power Save in IEEE 802.11 Ad Hoc Mode

- If host A has a packet to transmit to B, A must send an ATIM Request to B during an ATIM Window
- On receipt of ATIM Request from A, B will reply by sending an ATIM Ack, and stay up during the rest of the beacon interval
- If a host does not receive an ATIM Request during an ATIM window, and has no pending packets to transmit, it may sleep during rest of the beacon interval



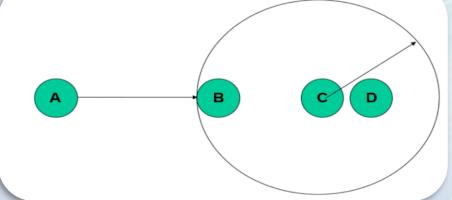
# Power Save in IEEE 802.11 Ad Hoc Mode

- Size of ATIM window and beacon interval affects performance
  - If ATIM window is too large, power saving is reduced
    - Energy consumed during ATIM window.
  - If ATIM window is too small, not enough time to send ATIM request
    - Delay increases, specially in high load conditions since ATIM requests will collide so nodes won't receive ACKs and will wait for the next beacon interval.
- How to choose ATIM window dynamically?
  - Based on observed load: load increase → increase ATIM window
  - (power saving decreases but delay decreases as well)
- How to synchronize hosts?
  - If two hosts' ATIM windows do not overlap in time, they cannot exchange ATIM requests.
  - Coordination requires that each host stay awake long enough (at least periodically) to discover out-of-sync neighbors.

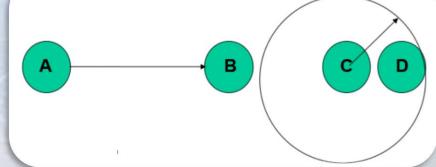
### **Power Control**

When C transmits to D at a high power level, B cannot receive A's transmission

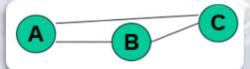
due to interference from C.



- If C reduces transmit power, it can still communicate with D
  - Reduces energy consumption at node C
  - Allows B to receive A's transmission (spatial reuse)

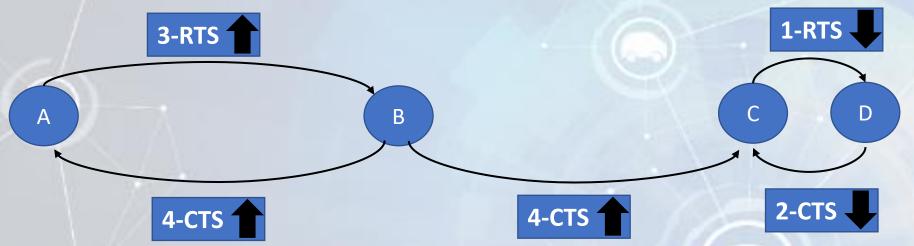


- Shorter hops typically preferred for energy consumption
  - Transmit to C from A via B, instead of directly from A to C



### Power Control in 802.11

 Transmit RTS/CTS/DATA/ACK at the least power level needed to communicate with the receiver



- B won't get RTS from C, C will get CTS from B so interference happens at C "hidden terminal problem" returns.
- Solution: send RTS/CTS at the highest power, and DATA/ACK at the smallest necessary power level.
  - Drawback:
    - Transmitting RTS at the highest power level also reduces spatial reuse
    - Nodes receiving RTS/CTS have to defer transmissions

