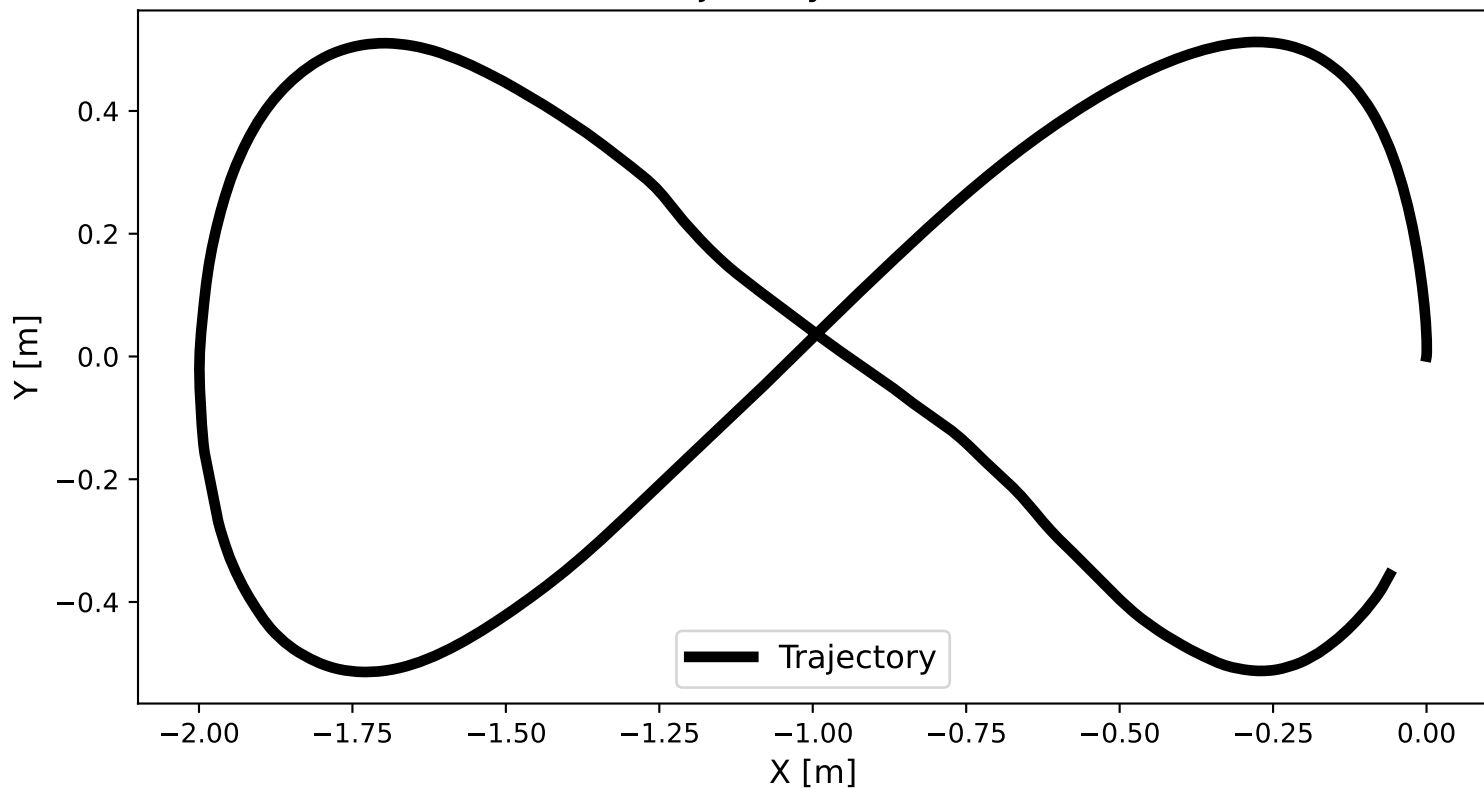
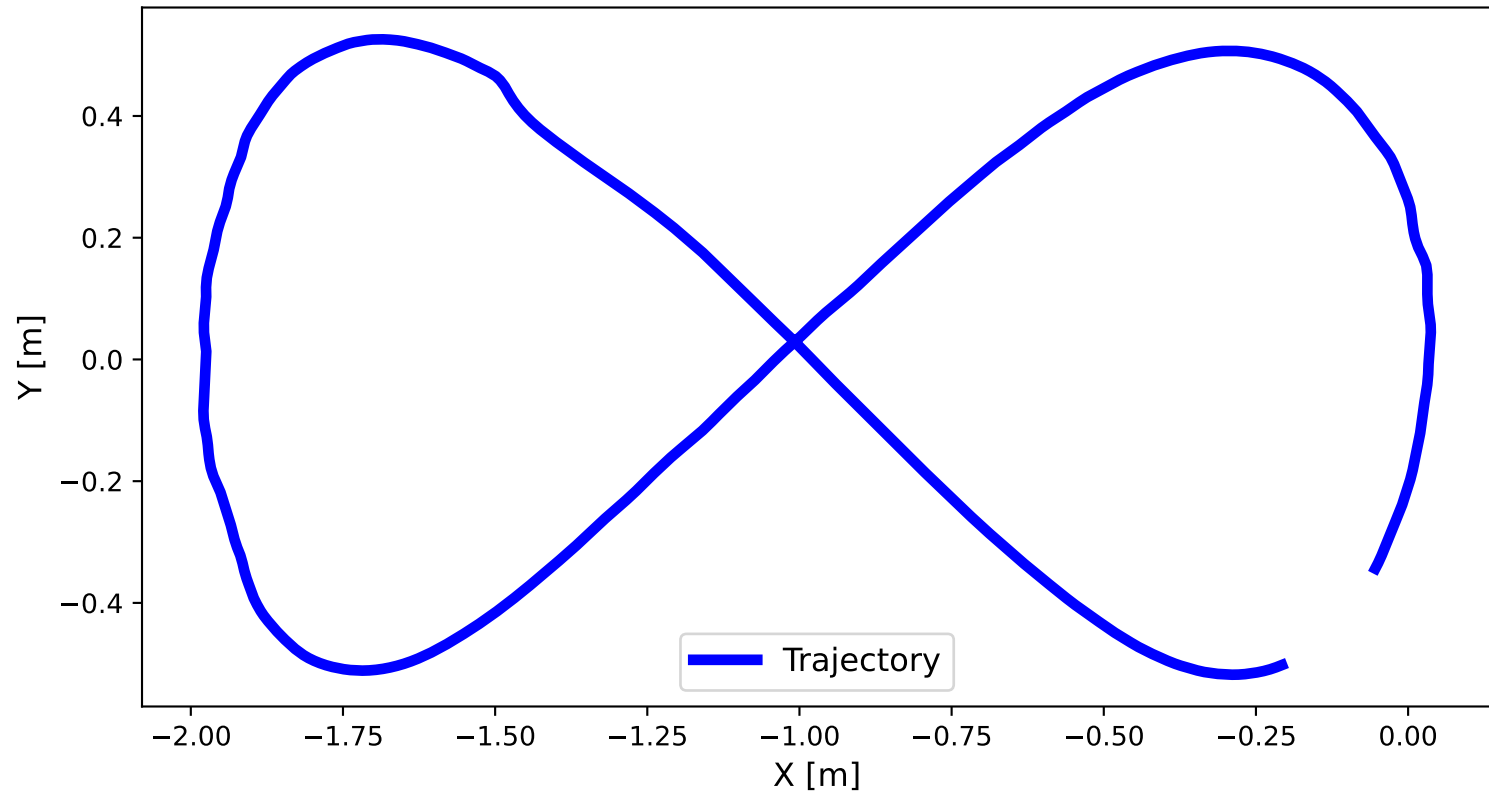


Trajectory: 0 - 400



Trajectory: 400 - 800



Trajectory: 800 - 1200

