
Optimization

EMINES - 2023



Day 5 - Detailed schedule

Morning

9h – 10h	Refresher on Combinatorial optimization. Scheduling pb + The index Fund
10h - 10h30	Multi-criteria optimization
10h30-10h45	<i>Break</i>
10h45- 11h30	Considering uncertainty
11h30 – 12h15	The efficient portfolio The newsvendor

Afternoon

13h – 13h45	The savvy farmer
13h45 – 14h30	The savvy farmer
14h30-14h45	<i>Break</i>
14h45 – 16h	Play with simplex The red tomato Wrap-up

Refresher

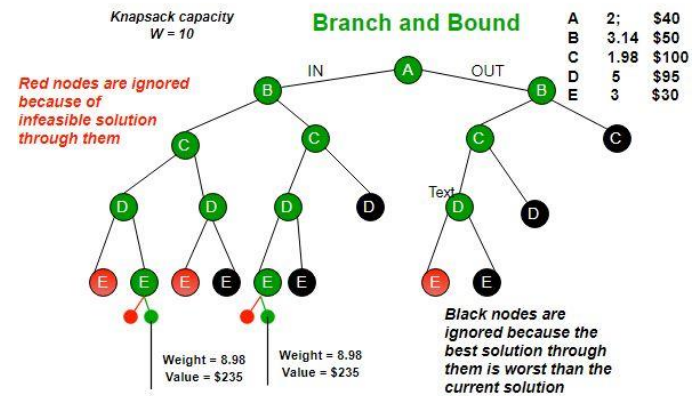
Several algorithms exist for solving MILPs

Principle

Illustration

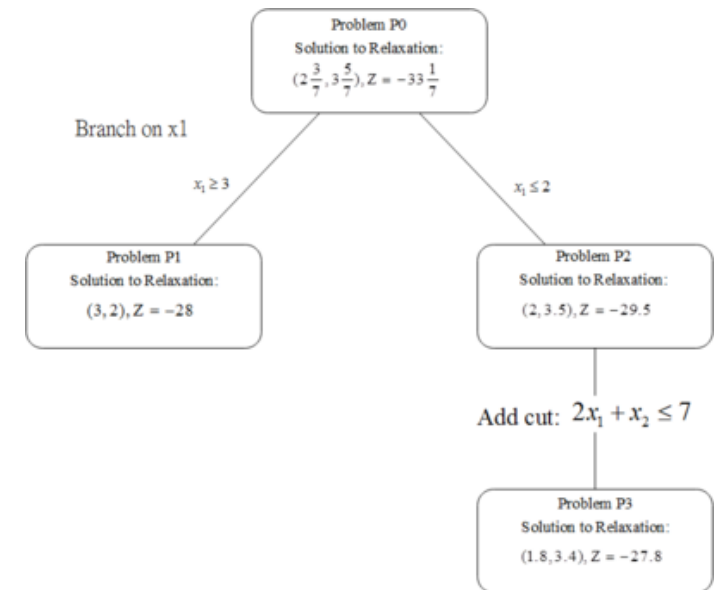
Branch & Bound

Use the Linear relaxation to eliminate (= prune) some « infertile » branches of the tree



Branch & Cut

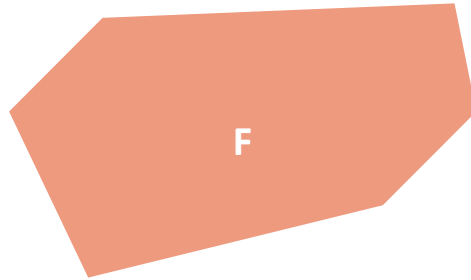
Add valid constraints, in order to tighten the linear relaxation (and get closer to the convex hull)



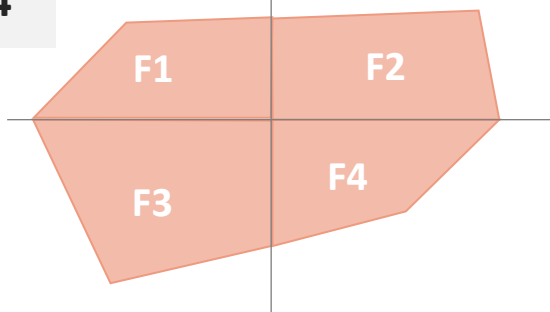
The Branch & Bound algorithms combines two basic tenets

Divide & conquer (= branching)

$$p^* = \min_{x \in F} f(x)$$



$$p_i^* = \min_{x \in F_i} f(x), i=1, \dots, 4$$



$$p^* = \min_{i=1, \dots, 4} \{p_i^*\}$$

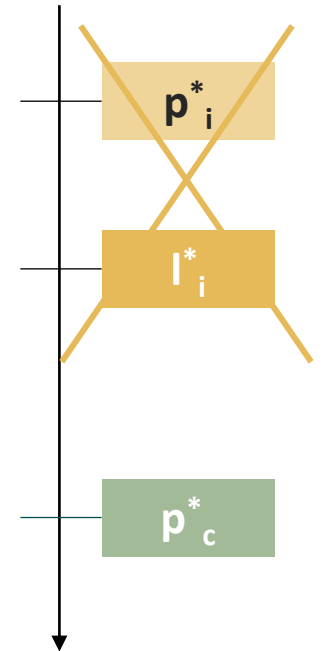
Detect and eliminate the none promising parts

Assume that F has been split into F_1, \dots, F_N

Let $i \in \{1, \dots, N\}$ and assume that p_c^* is the optimal value on UF_j , for all $j < i$.

Suppose that we are able to compute (easily) l_i^* a lower bound of $p_i^* : l_i^* \leq p_i^*$

If l_i^* is such that $p_c^* < l_i^*$ then there is no hope that F_i contains the optimal solution. **So no need to explore it further.** Move on to $i+1$

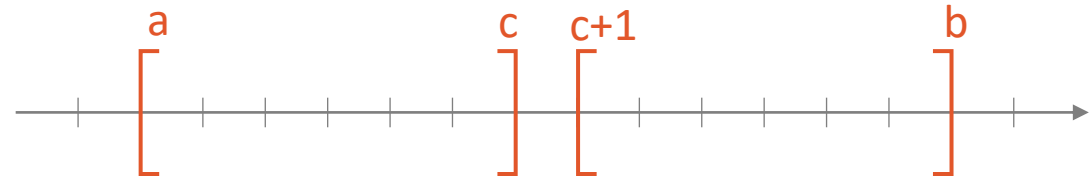


In the case of an integer optimization problem, there is a smart way to divide the feasible set into subsets

- Consider an integer variable x_1
- Without loss of generality, we can consider that x_1 lies in the range $[a, b]$



- Let c an integer in $[a, b]$.
- Then we can split the feasible set in the following way :



At the same time we divide the feasible set in two and we eliminate non-integer solutions

$$Z^* = \min c(x) \text{ s.t. } x \in F$$

Branch & bound : what do we mean by branching ?

Suppose the variable x_1 has to be integer.

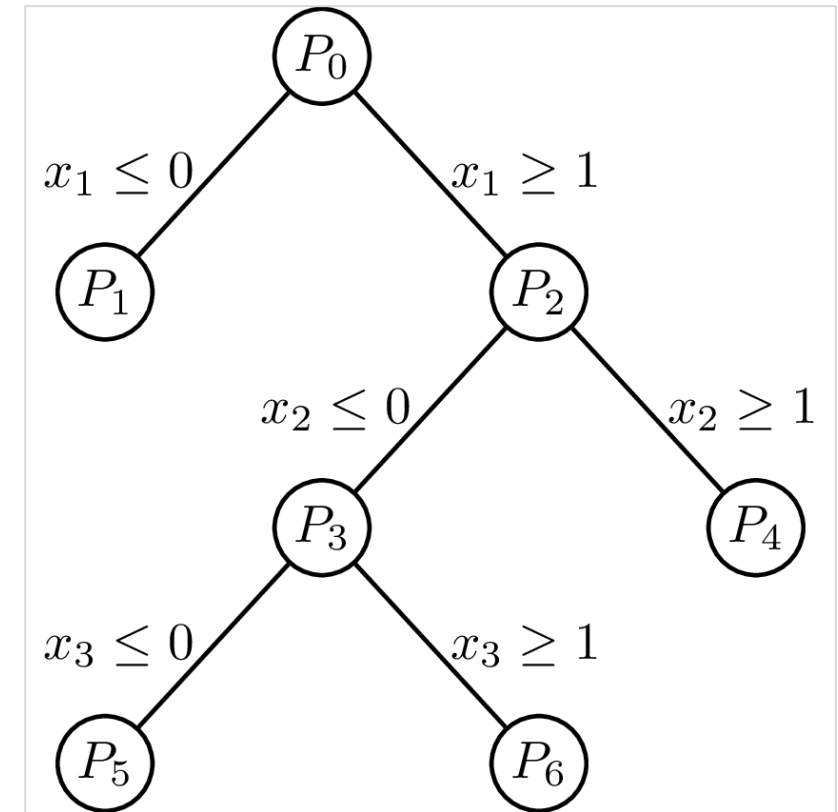
Solve the linear relaxation and get $x_1 = 0.57$

Then define 2 subproblems (branches)

P_1 : by adding $x_1 \leq 0$

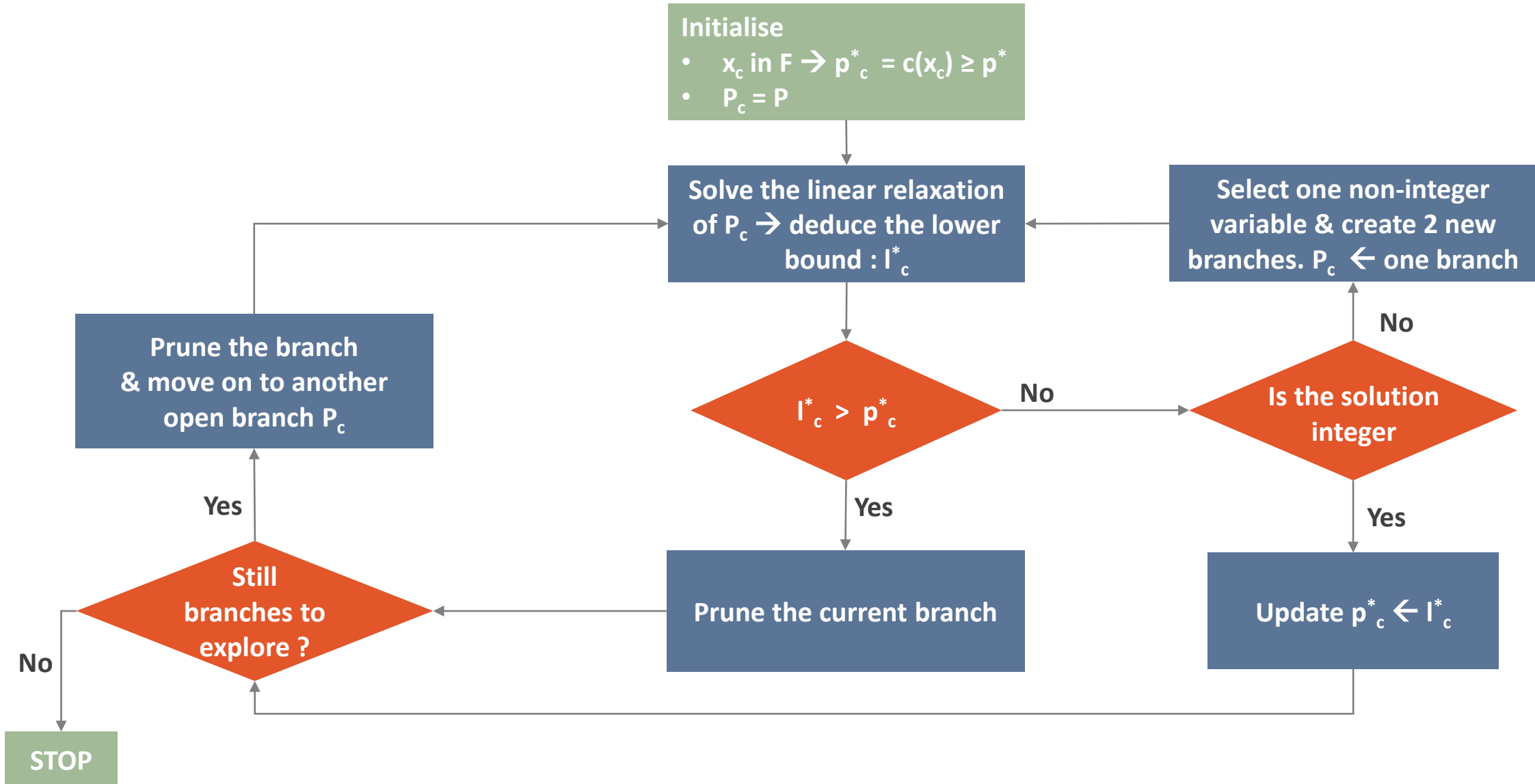
P_2 : by adding $x_1 \geq 1$

$$Z^* = \min \{Z_1^*, Z_2^*\}$$



Branch & bound

$$Z^* = \min c(x) \text{ s.t. } x \text{ in } F$$



$$Z^* = \min c(x) \text{ s.t. } x \text{ in } F$$

How to prune ?

Let p_1^* the optimal value of P_1

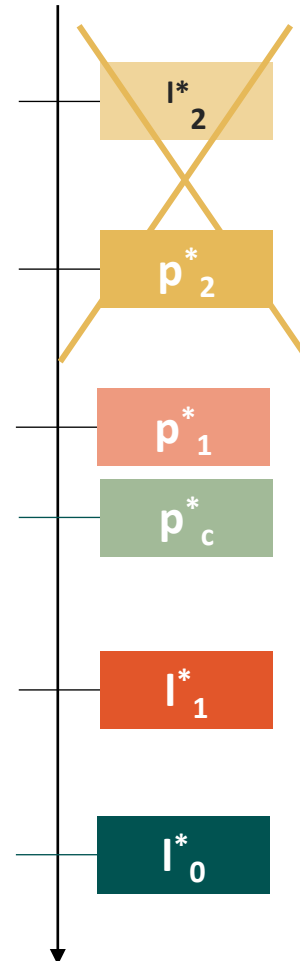
Let l_1^* the optimal value of the linear relaxation of P_1

Let p_2^* the optimal value of P_2

Let l_2^* the optimal value of the linear relaxation of P_2

p_c^* the best current solution

l_0^* the linear relaxation of the ascendant branch of P_1 & P_2

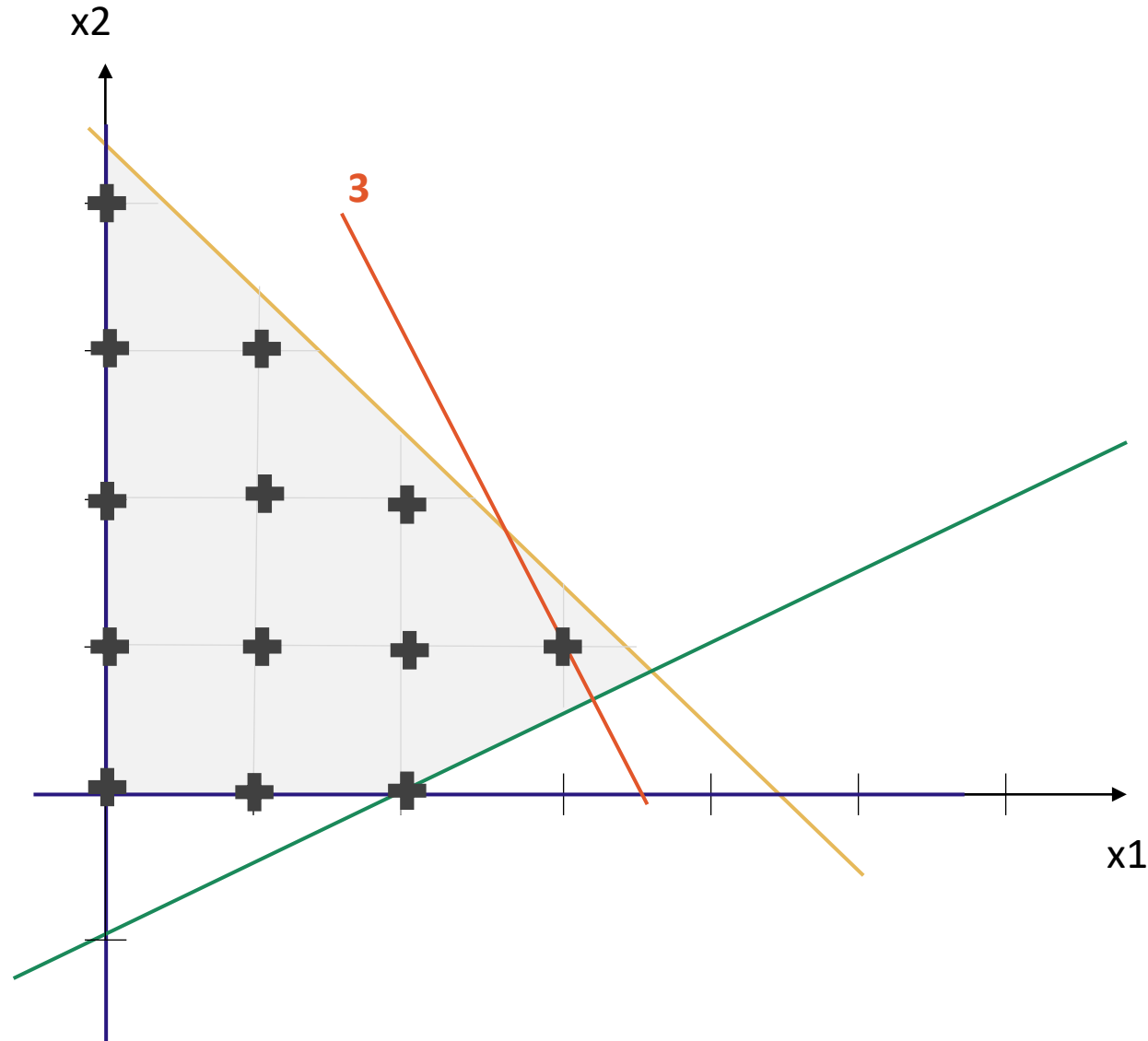


All descendants of a branch have an optimal value that is higher (= less good) than that of their ancestor, since the more you get in the tree, the more you add constraints

So if the ancestor is already worse than the current solution, we can delete the branch
→ no hope of improving the current solution on this branch

→ So we can prune P_2

Geometry of Integer Linear Programming



The feasible set is a countable set with 13 solutions (+)

Max $2x_1 + x_2$

$x_1 + x_2 \leq 4.5$

$-x_1 + 2x_2 \geq -2$

$x_1 \geq 0, x_2 \geq 0$

x_1, x_2 integer

WARNING : different formulation may work for a same problem.
Which one is the best ?

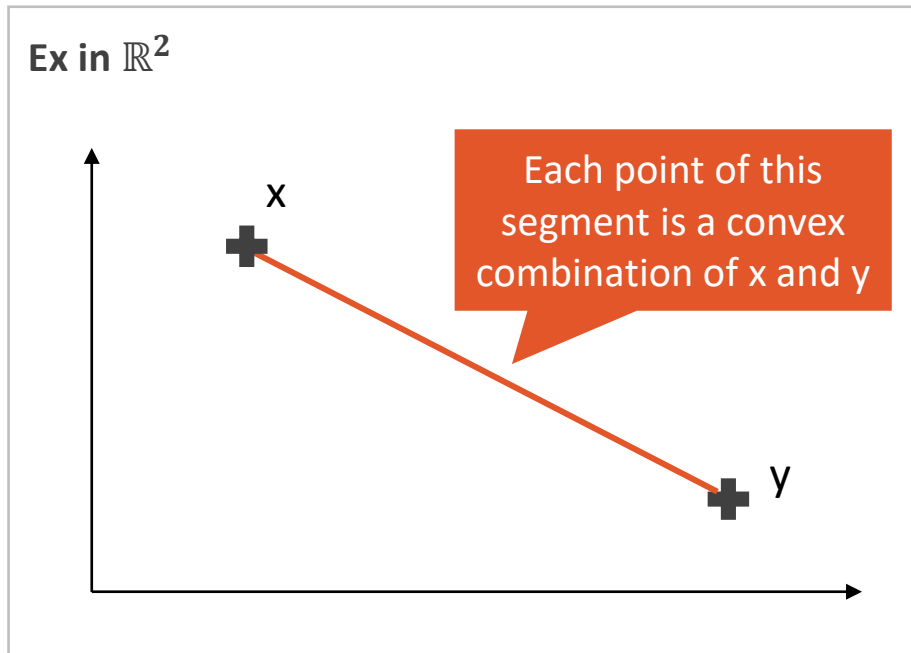
Refresher : convexity

Definition

Convex combination

z is a **convex combination** of x and y if there exists λ in $[0, 1]$ such that $z = \lambda x + (1 - \lambda) y$

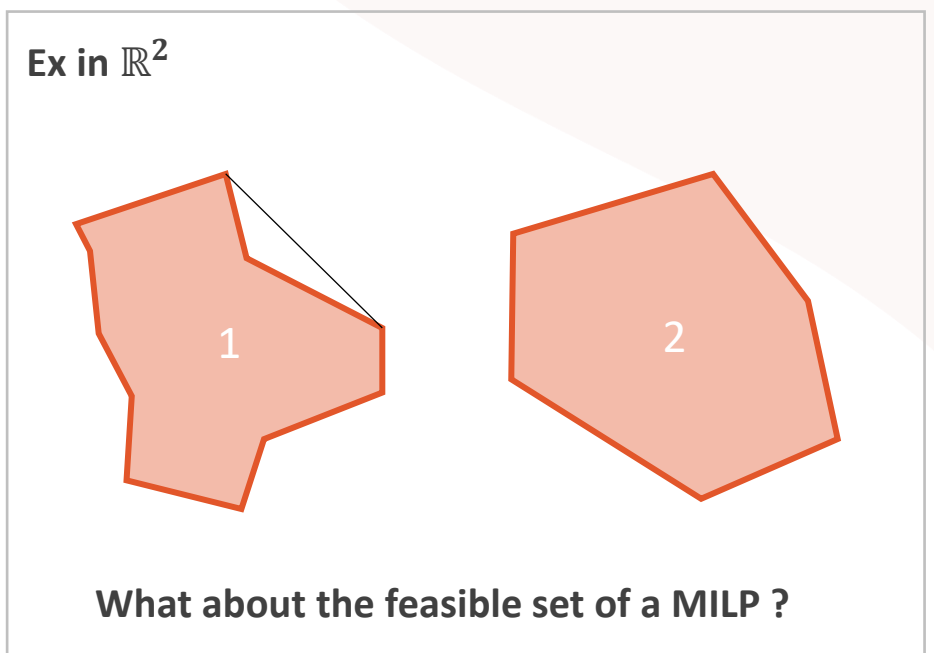
Illustration



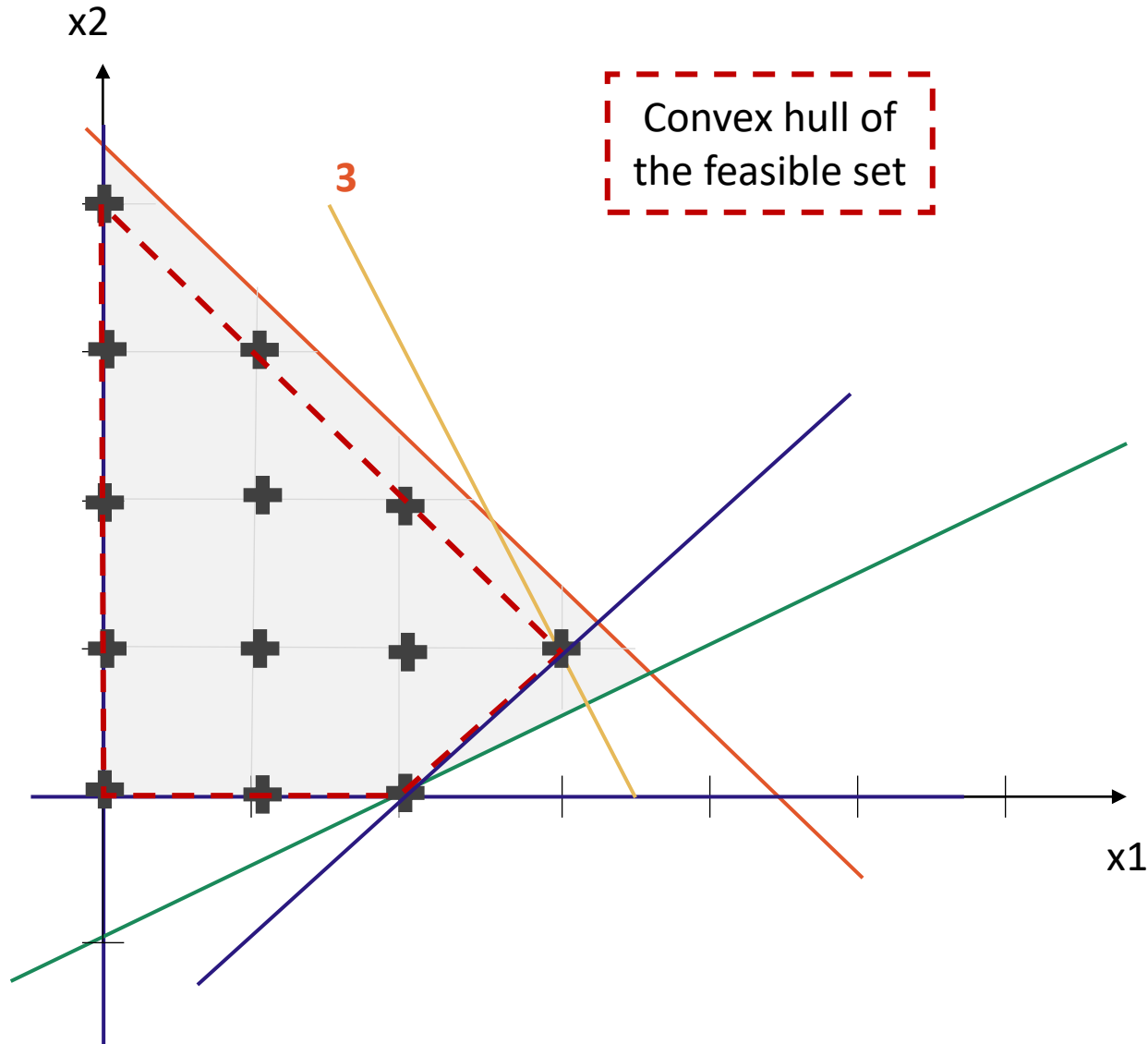
Convex set

S is **convex** if and only if :

x, y in $S \implies z$ in S , for any z convex combination of x and y



Notion of convex hull



Definition : a **convex hull** is the smallest LP feasible region that contains all of the integer solutions

If you are able to describe **the convex hull** through a set of **linear constraints**, then **the integer solution is obtained by solving this new linear program**

Pb : determining the convex hull may be a very difficult problem

Definition : a constraint is **valid** if adding it does not reduce the feasible set

Branch & cut, or cutting planes method

Overview

To iteratively refine the feasible set of the relaxed problem (P) using linear inequalities, termed **cuts**

Basic idea

Let consider a linear constraint C added to the problem.

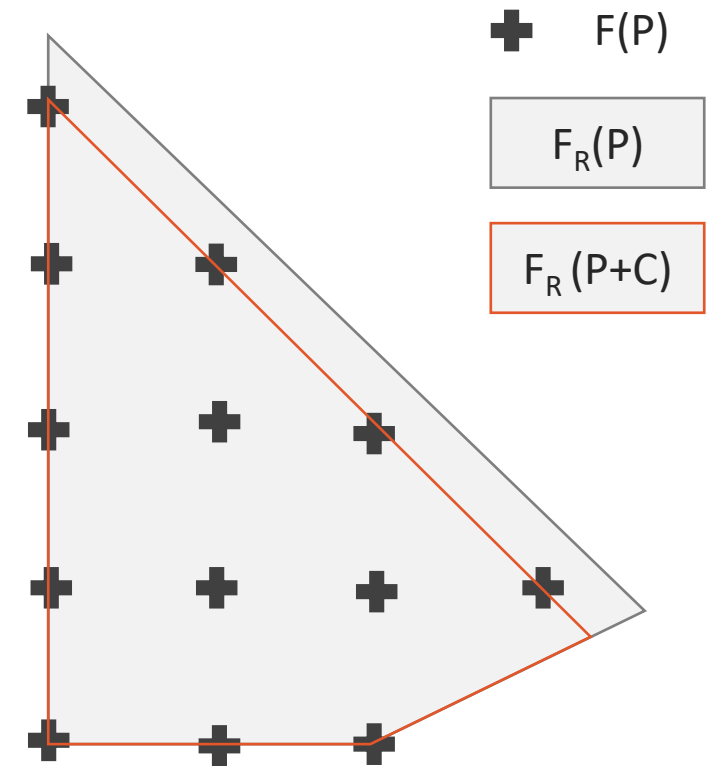
- Let F be the feasible set of a problem, and F_R the feasible set of its linear relaxation
- Let (P) be the initial problem and (P+C) the problem augmented with the constraint C.

Then, **the constraint C is a cut if :**

- $F(P+C) = F(P)$: It does not eliminate feasible solutions of the original IP problem.
- $F_R(P+C) \subset F_R(P)$: The cut removes the optimal solution of the relaxed LP problem.

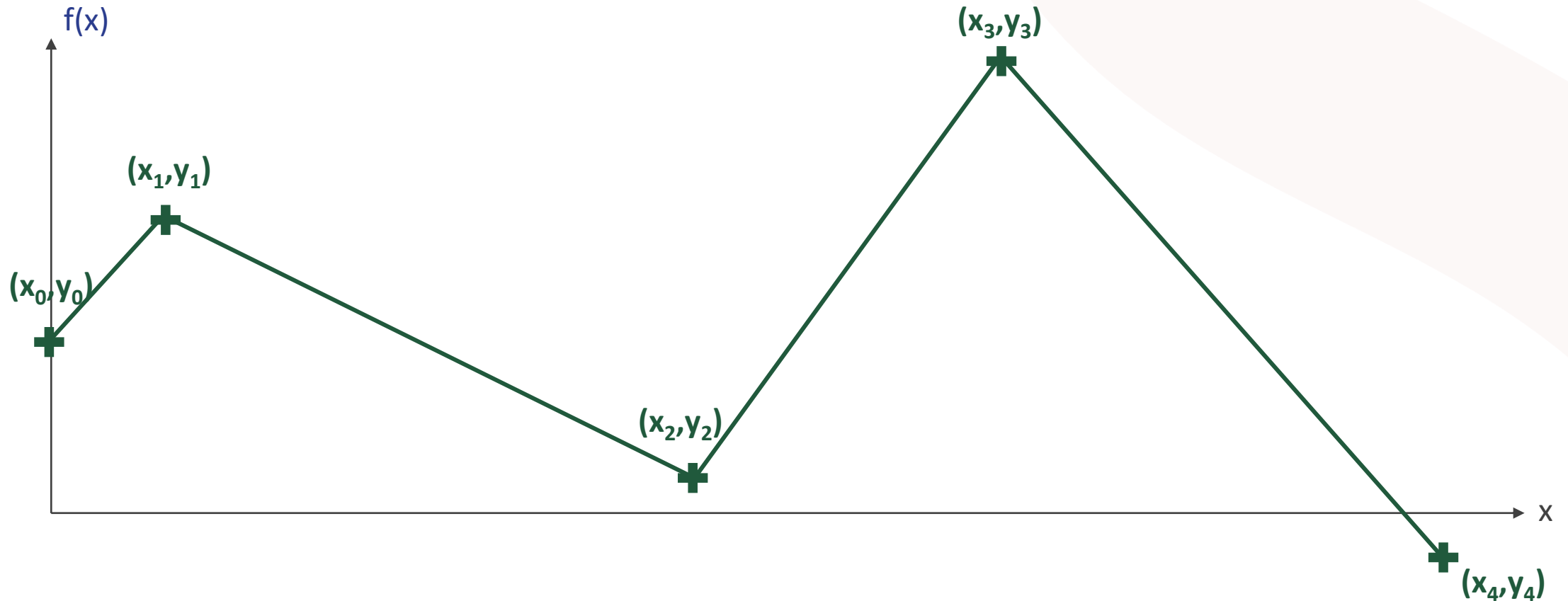
Ultimate goal

The optimal integer solution becomes an extreme point and therefore can be found by solving the LP problem.



Tips 5 : Use binary variables to formulate arbitrary piecewise linear functions

The function f is specified by ordered pairs (x_i, y_i)



Let's practice. How to compute $f(x)$ using binary variables ?

Data : n pieces

$(x_i, y_i) \quad \forall i = 0, \dots, n$

Constraints

- $f(x) =$

Solution. How to model this using binary variables ?

Data : n pieces

$$(x_i, y_i) \quad \forall i = 0, \dots, n$$

Variables

$$z_i \in \{0, 1\} \quad \forall i = 1, \dots, n$$

\rightarrow indicate whether $x_{i-1} \leq x \leq x_i$

$$\lambda_i \in [0, 1] \quad \forall i = 0, \dots, n$$

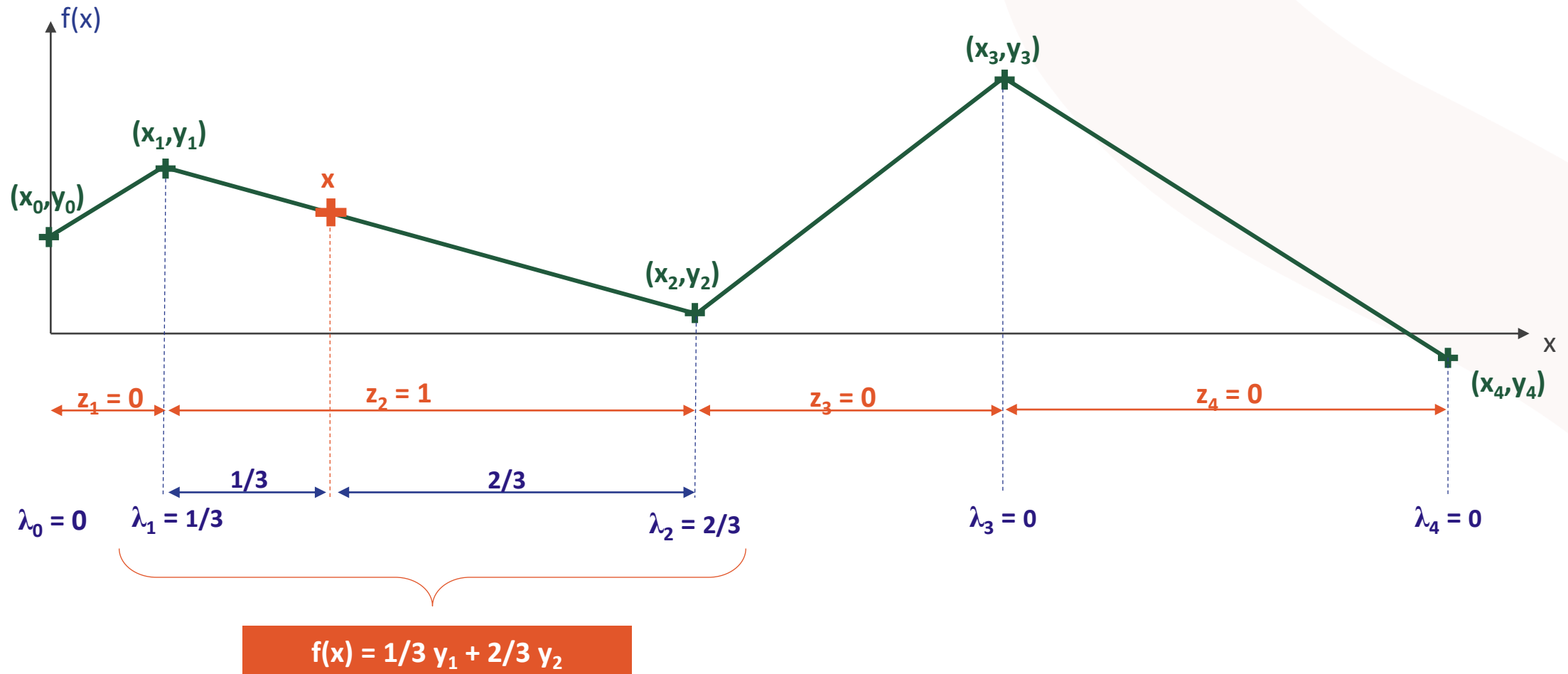
\rightarrow indicate the position over $[x_{i-1}, x_i]$ or $[x_i, x_{i+1}]$

\rightarrow equals 0 if x does not lie in $[x_{i-1}, x_i]$ or $[x_i, x_{i+1}]$

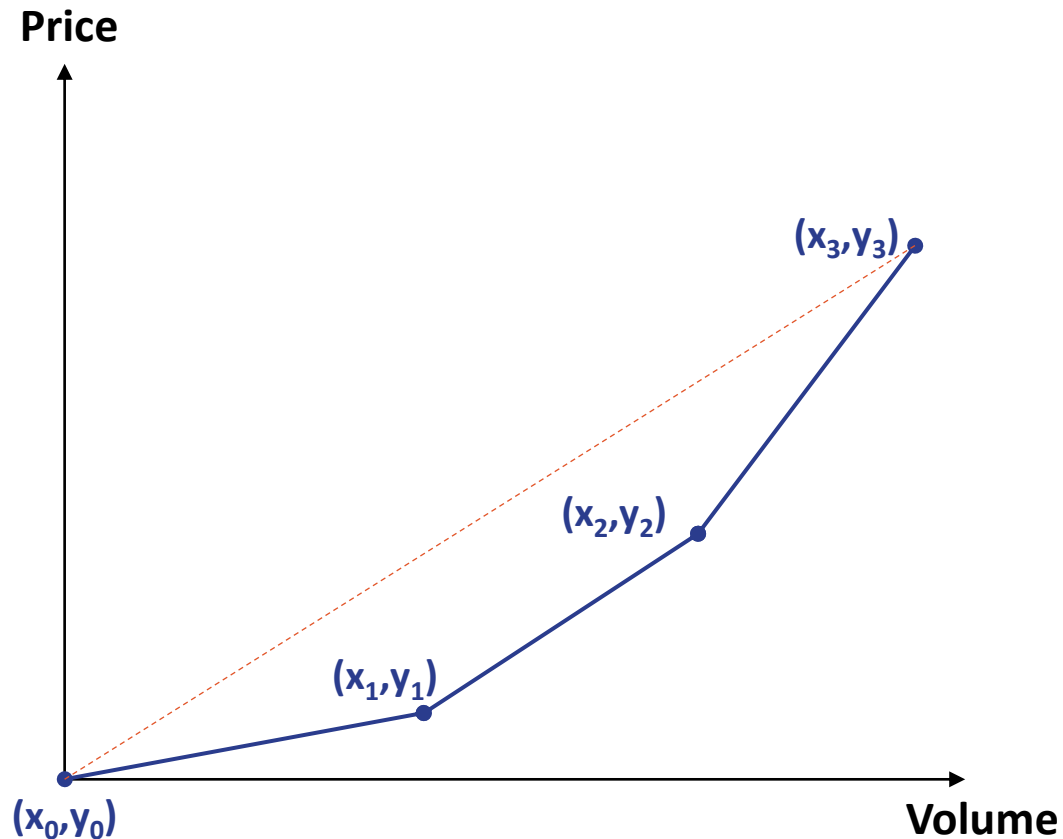
Constraints

- $f(x) = \sum_{i=0}^n \lambda_i y_i$
- $x = \sum_{i=0}^n \lambda_i x_i$
- $\sum_{i=0}^n \lambda_i = 1$
- $\lambda_i \leq z_i + z_{i+1}, \quad i = 1, \dots, n-1$
- $\lambda_0 \leq z_1$
- $\lambda_n \leq z_n$
- $\sum_{i=1}^n z_i = 1$
- $\lambda_i \in [0, 1]$
- $z_i \in \{0, 1\}$

Illustration



When you try to minimize a convex function (or maximize a concave function), you don't need binary variables any more



Variables

$$\lambda_i \in [0, 1] \quad \forall i = 0, \dots, n$$

→ indicate the position over $[x_{i-1}, x_i]$ or $[x_i, x_{i+1}]$

Constraints

$$\text{Min} \quad \sum_{i=0}^n \lambda_i y_i$$

- $x = \sum_{i=0}^n \lambda_i x_i$
- $\sum_{i=0}^n \lambda_i = 1$
- $\lambda_i \in [0, 1]$

The model will pick the right values of λ_i since they are the ones that minimize the objective value

Tips 6 : Special Ordered Sets (SOS)

SOS1

A set of variables, **at most one of which can take a non-zero value**, all others being at 0
→ choose at most one from a set of possibilities.

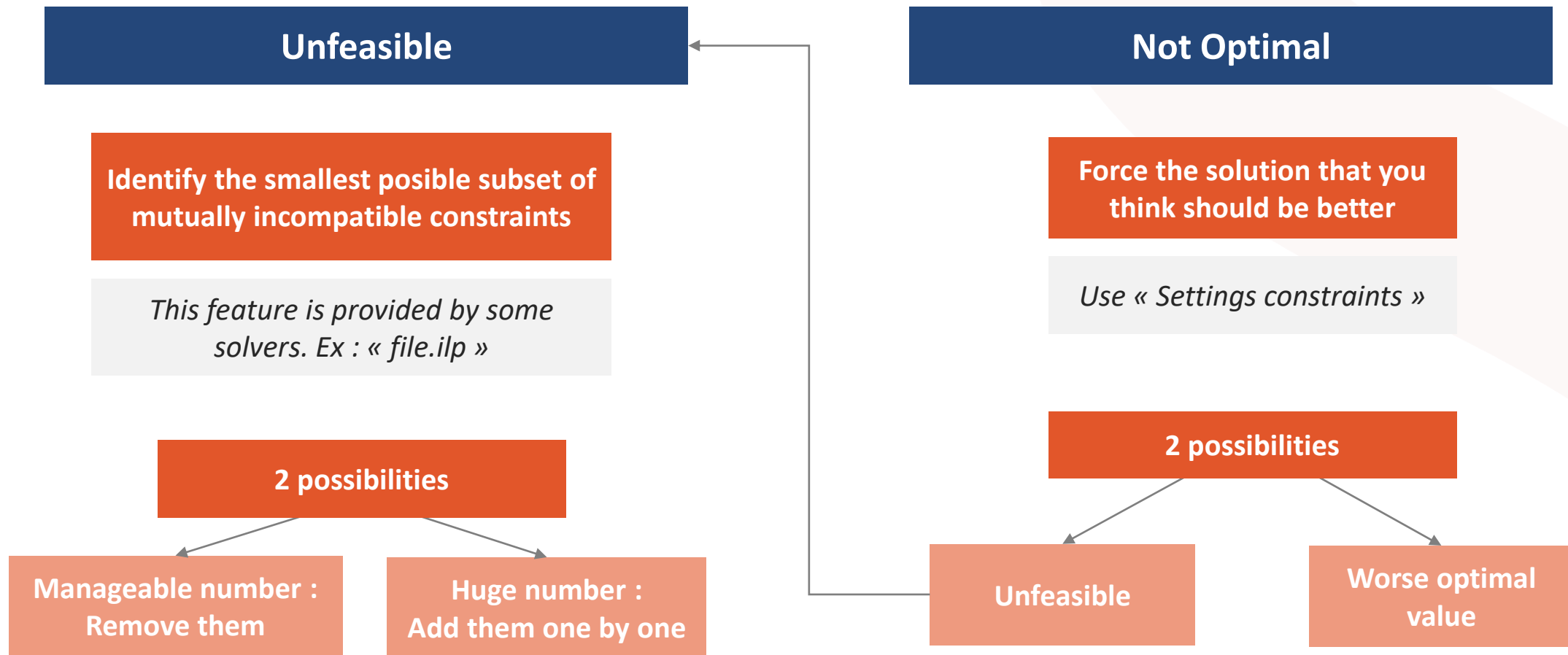
Ex : what size of factory to build, when we have a set of options, perhaps small, medium, large or no factory at all

SOS2

An **ordered** set of non-negative variables, of which **at most two can be non-zero**, and if two are non-zero these must be **consecutive** in their ordering.

Special Ordered Sets of type 2 are typically used to model non-linear functions of a variable in a linear model.

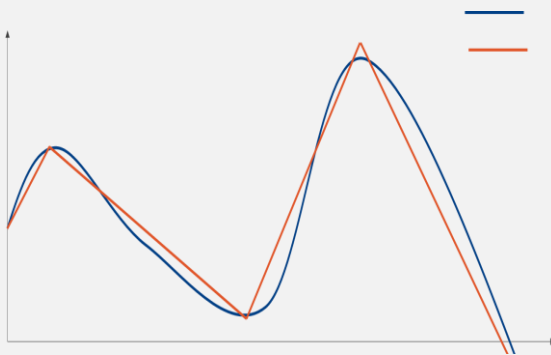
What if the solution is not satisfying ?



Mixed-Integer Linear Programming in a nutshell

Extremely powerful

- All analytical problems can be approximated with MILP



But difficult to solve

- Unfortunately very hard (NP-hard) to solve, even for a small number of binary variables (> 1000)
- Not an unique formulation. Generally many of them that can be more or less efficient

May require alternative methods

- Decomposition-coordination
 - In the model
 - During the resolution
- Algorithms without guarantee of optimality (metaheuristics)

Formulation

Classical optimization problem

Knapsack problem

Transportation
problem

Blending problem

Set covering problem

Packing problem

Shortest path

Scheduling

Warehouse location

Assignment problem

Traveling Salesman
problem

Assortment problem

Portfolio investment

Min distance / Least-
square

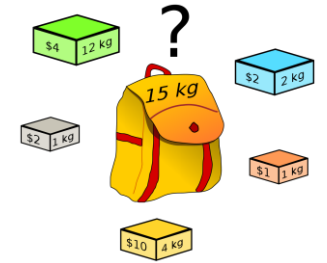
Vehicle Routing
problem

Inventory
management = Lot-
sizing

Revenue
management

Sorting

Knapsack



Description

- You are the owner of a knapsack (=resource) with a limited size (=capacity)
- You want to fill it (=use it) with the best possible set of items, among a given list $\{item_1, \dots, item_N\}$
- « Best » means the set that will bring the maximal value, since each item has a given value
- You cannot take parts of an item. « all or nothing »

Application

- Hiking
- Business planning
- Investment

Questions

- Imagine a greedy heuristic for solving this problem
- What would be the decision variables ? What would be their nature ?

Data

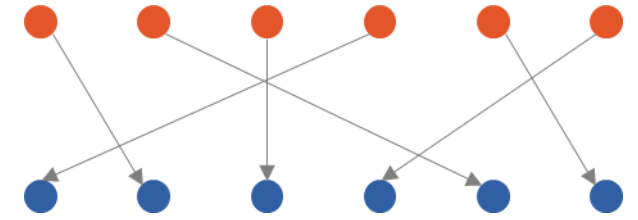
- Capacity : C
- $i=1, \dots, N$ possible items
- Value : $V[i]$
- Weight : $W[i]$

Limitations / extensions

- Multiple constraints
- Combined values

Capacity		500
i	W[i]	V[i]
1	61	46
2	55	32
3	49	42
4	76	32
5	88	21
6	56	9
7	12	17
8	69	19
9	40	20
10	91	42
11	85	12
12	83	1
13	32	45
14	85	49
15	89	43
16	19	17
17	26	7
18	58	21
19	73	24
20	71	37

Assignment problem



Description

- You have a list of **supply items** and a list of **demand items** (same number of supply and demand items)
- Each pair supply-demand brings a value
- Find the **matching supply-demand** that maximize the value
- Each supply item shall be allocated once and each demand item shall receive one of them

Data

- $i=1, \dots, N$ unit of supply
- $j=1, \dots, N$ unit of demand
- For each i, j : value $V[i][j]$

Supply i	Demand j	$V[i][j]$
1	1	5
1	2	19
1	3	7
1	4	13
1	5	13
2	1	16
2	2	2
2	3	5
2	4	9
2	5	5
3	1	14
3	2	21
3	3	13
3	4	13
3	5	11
4	1	10
4	2	20
4	3	22
4	4	15
4	5	2
5	1	13
5	2	13
5	3	16
5	4	22
5	5	5

Application

- Agent-task assignment (ex : taxi-customers)
- Efficient market
- Pairing (marriage, roommates, ..)

Limitations / extensions

- **Unbalanced assignment**
- **Oversupply / over demand market**
- **Transportation problem**

The assignment problem

Find the **matching X** that maximize the value = $\sum_{[i][j]} v[i][j] X[i][j]$

Such that each supply i is allocated once and each demand receives one of them.

v	Supply[i]			
Demand[j]	5	4	7	5
	8	5	3	8
	9	2	3	7
	4	6	2	9



X	Supply[i]			
Demand[j]	0	0	1	0
	0	1	0	0
	1	0	0	0
	0	0	0	1

v	Supply[i]			
Demand[j]	5	4	7	5
	8	5	3	8
	9	2	3	7
	4	6	2	9

Total = 30

Warehouse location = Facility location problem



Description

- You must decide **which of n warehouse to open** for meeting the demands of m customers
- Once you've decided to operate a warehouse, you have to decide **how much to ship** from this warehouse to the customers
- Your goal is to minimize the cost, made of two lines :
 - Fixed operating cost** per warehouse i , if opened
 - Per unit** sum of operating cost at warehouse i and shipping cost from i to customer j
- Good can be shipped from a warehouse only if it opened

Data

- $i=1, \dots, N$ potential warehouse location
- $j=1, \dots, N$ unit of demand
- For each j : demand $d[j]$
- Fixed cost : $c_f[j]$
- Variable cost : $c_v[i][j]$

Applications

- Value-chain design

Warehouse i	Demand j	$cv[i][j]$
1	1	7
1	2	8
1	3	13
1	4	7
2	1	2
2	2	15
2	3	21
2	4	7
3	1	9
3	2	9
3	3	7
3	4	5

Warehouse i	$cf[i]$
1	10
2	15
3	8

Demand j	$d[j]$
1	8
2	5
3	11
3	17

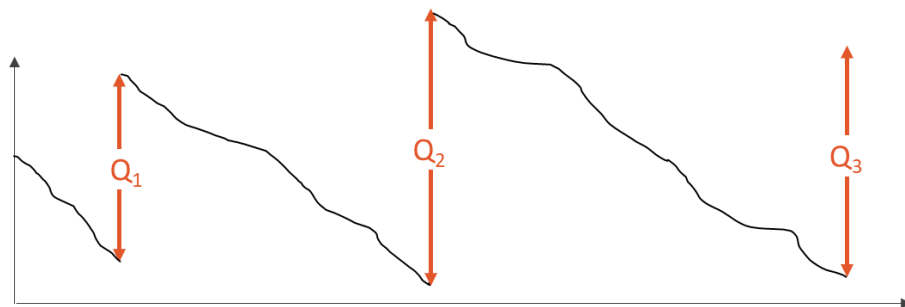
Questions

- What would be the decision variables ? What would be their nature ?
- What would be the objective function ?

Inventory management / Lot-sizing problem

Description

- You have to decide how much, and at which time, replenishing your inventory
- Your goal is to **satisfy the demand** (which can be deterministic or uncertain) at least cost



Variants

Supply	Procurement	Production		
		W/O changeover	With changeover	
Demand	Steady-state demand	Dynamic demand	Uncertain demand	
			Shortage	Backlog
Leadtime	None	Deterministic	Uncertain	
Costs	Order cost	Holding cost	Supply cost	
Location	One single warehouse	Parallel warehouses	Sequence of warehouses	
Policy	Periodic	Threshold	Periodic + threshold	

Inventory management : The Economic Order Quantity (EOQ) problem

Problem statement

You are the manager of a warehouse. You know for sure the demand for the upcoming year, which is constant (global volume D).

You want to minimize your fixed order costs, but without exploding your storage costs: What is x the optimal quantity to order at each order ?

Costs data

- ▶ Fixed order cost C_c (\$ /order)
- ▶ Storage cost C_s (\$ /average volume of storage on the year)
- ▶ Purchase cost C_p (\$ /unit of purchased volume)

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Costs data

- ▶ Fixed order cost C_c (\$ /order)
- ▶ Storage cost C_s (\$ /average volume of storage on the year)
- ▶ Purchase cost C_p (\$ /unit of purchased volume)

Solution

The cost $f(x) = C_c \frac{D}{x} + \frac{C_s}{2}x$ and $f'(x) = -\frac{C_c D}{x^2} + \frac{C_s}{2}$

$$\text{So : } f'(x) = 0 \Rightarrow 2C_c D = C_s x^2 \Rightarrow x^* = \sqrt{\frac{2C_c D}{C_s}}$$

The second derivative at x^* is strictly positive so x is a local minima.

Scheduling is the allocation of shared resources over time to competing activities

Description

Machine scheduling problem :

- **Activities** → **jobs** = a set of operations
- **Resources** → **machines** that can process at most one operations at a time

Objective :

- Min makespan
- Min cost
- Max flowtime
-

Inputs

- A set of **jobs** & a set of **machines**
- Each job = a set of operations to be processed on dedicated machines(s) & their associated processing time
- **Various constraints** (precedence, changeover, ...)

Scheduling

Outputs

An allocation of jobs x resources over time
= Assignment of each operation on a resource
+ Sequencing
+ Starting time

4 majors fields of applications of scheduling problems

1

Production

Flexible manufacturing
Assembly problems
With or without transportation

2

Computer science

CPU Scheduling
Mono or multi processor systems

3

Project management

Multi-resource scheduling
Precedence constraints
PERT

4

Workforce management

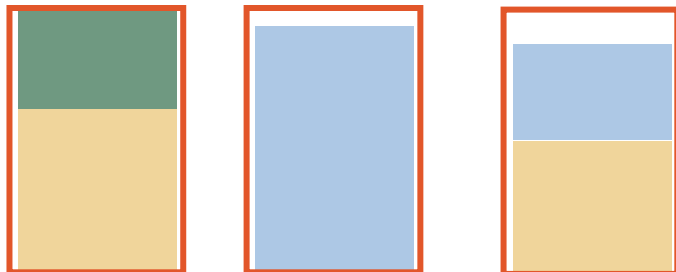
Timetabling scheduling problems
(education, health, transport, ...)

What's the difference between planning & scheduling ?

Planning

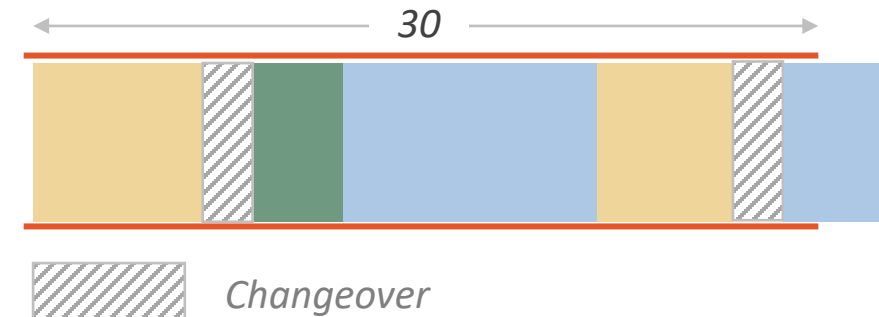
- ▶ **Tactical (mid-term)**
- ▶ **Discrete time**
- ▶ For each time step, look if the capacity is sufficient to complete a series of task
- ▶ “Think globally” = the task will be done during the time step but we don't know exactly when
- ▶ In the case where the order impacts the capacity to produce (typically: changeover) → risk of being over-optimist (~ constraint relaxation)
- ▶ Small time step implies better precision but higher computation time

3 time-steps
of 10



Scheduling

- ▶ **Operational (short-term)**
- ▶ **Continuous time** (No need to discretize)
- ▶ Each task is allocated to the resource within a precise time slot
- ▶ Make it possible to consider changeover
- ▶ 2 key **decision variables** :
 - Loading = assignment to resources
 - Sequencing = order in which they are carried out (notion of successor and/or predecessor)



Key characteristics

Operations characteristics

- Preemption or not
- Processing time

Machine type

- Identical
- Uniform (different yield)
- Homogeneous

Constraints

- Earliest date or deadline
- Changeover or setup
- Same machine
-

Operations per job

- Single
- Ordered
- Precedence (represented through an acyclic graph)
- Non ordered = totally free

Work process = Possible machine per operations

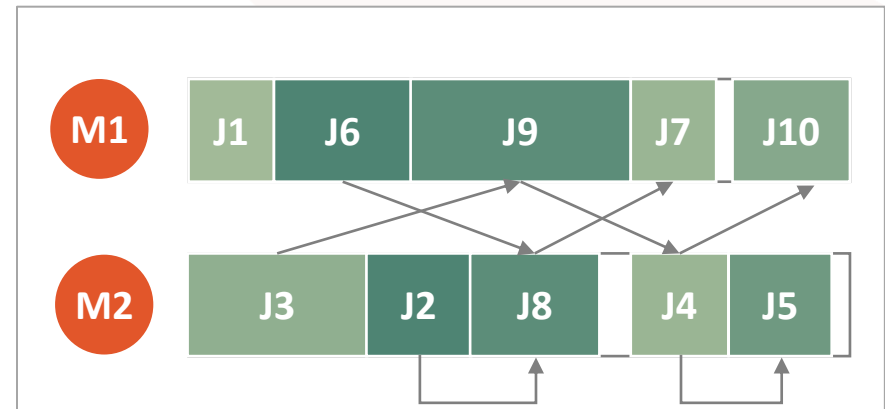
- Only one dedicated machine
- Several but with different processing time
- Several with same processing time

Objective

- Let C_i be the completion time of job J_i : objective = $f(C)$
- Cost function
 - Makespan
 - Weighted flowtime = $\sum_i w_i C_i$
 - ...

A simple scheduling example

Jobs	<ul style="list-style-type: none">10 jobs to allocate either on M1, or on M2Each job j can be done on the two machines but with different duration d_{1j} or d_{2j}
Machine	<div><div>M1</div><div>M2</div></div>
Constraints	<ul style="list-style-type: none">Non preemptivePrecedence constraints



Scheduling : 3 possible formulations as a MIP

- $j=1,\dots,J$ jobs of duration $d[j]$
- $m=1,\dots,M$ machines
- $t=1,\dots,T$ time step

Variables

Key constraints

Time-indexed

- $X[t][j][m]$ in $\{0,1\}$ #equal to 1 if job j starts at time t at machine i .

- $\sum[j][t-d[j][m]+1 \leq t' \leq t] X[t'][j][m] \leq 1$ # for all j, m

Rank-indexed

- $X[j][m][k]$ in $\{0,1\}$ #equal to 1 if job j is scheduled at the k -th position on machine i
- $Y[m][k]$ #start time of the job at the k -th position of machine i

- $Y[m][k] + \sum[j] d[j][m] X[j][m][k] \leq Y[m][k+1]$
for all m, k

Precedence

- $X[j][j'] [m]$ in $\{0,1\}$ #equal to 1 if j precedes j' on machine m
- $Y[j][m]$ #start time of job j on machine m

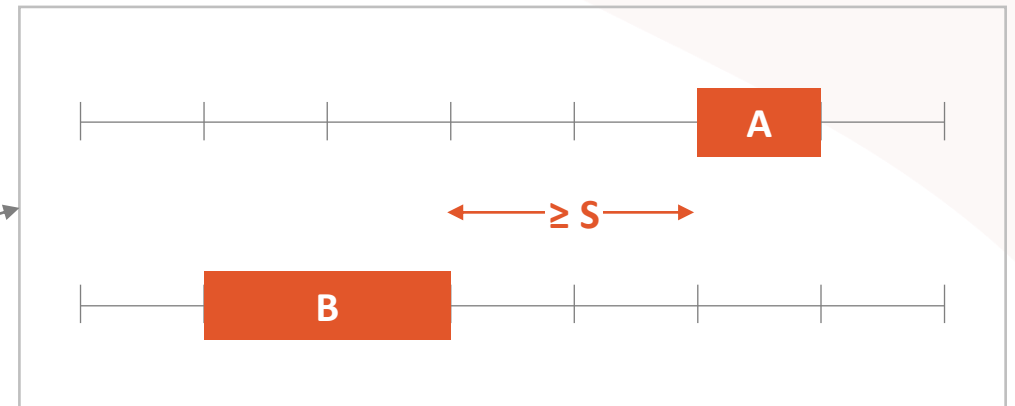
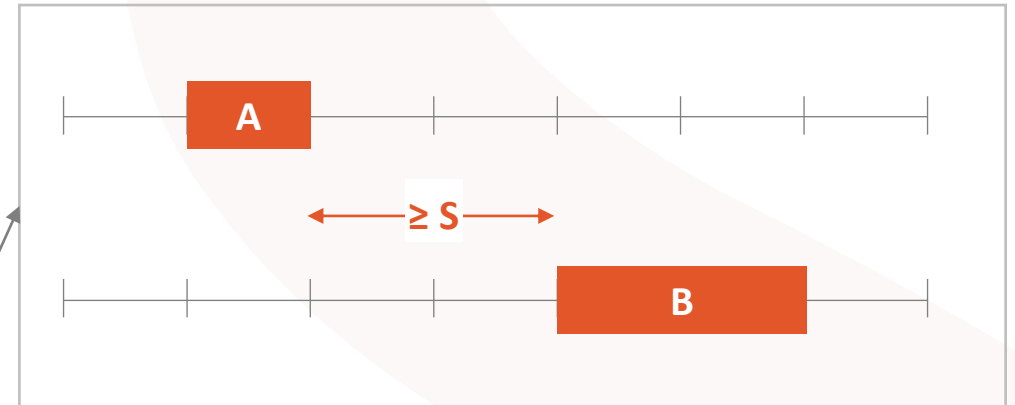
- $Y[j][m] + d[j][m] \leq Y[j'][m] + M X[j][j'] [m]$ #for all j, j', m

Disjunctive constraints

- **Problem statement** : 2 events A and B, of duration d_A and d_B , to schedule with a minimum space S :
- **Decision variables** :
 - $A[t] = 1$ if the event A starts at t
 - $B[t] = 1$ if the event B starts at t
- **Starting dates** express as :
 - $\sum_t t A[t]$
 - $\sum_t t B[t]$

Minimal space S constraint :

- Either **A is before B** then : $\sum_t t B[t] - (\sum_t t A[t] + d_A) \geq S$
- Or **A is after B** then : $\sum_t t A[t] - (\sum_t t B[t] + d_B) \geq S$



Disjunctive constraints : 3 possible formulations

	Variables	Key constraints
The most natural (BigM)	<ul style="list-style-type: none"> X in $\{0,1\}$ equals 0 if A is before B 	<ul style="list-style-type: none"> $\sum_t t B[t] - \sum_t t A[t] \geq d_A + S - M X$ $\sum_t t A[t] - \sum_t t B[t] \geq d_B + S - M(1-X)$
2 to 2 exclusion		<ul style="list-style-type: none"> $A[t] + B[t'] \leq 1$, for all (t, t') that violate the space constraint
Quadratic		<ul style="list-style-type: none"> Either $\sum_t t B[t] - \sum_t t A[t] - d_A - S \geq 0$ and $\sum_t t A[t] - \sum_t t B[t] - d_B - S \leq 0$ Or $\sum_t t B[t] - \sum_t t A[t] - d_A - S \leq 0$ and $\sum_t t A[t] - \sum_t t B[t] - d_B - S \geq 0$ <p>It suffices to impose that the product be negative :</p> $(\sum_t t B[t] - \sum_t t A[t] - d_A - S) (\sum_t t A[t] - \sum_t t B[t] - d_B - S) \leq 0$

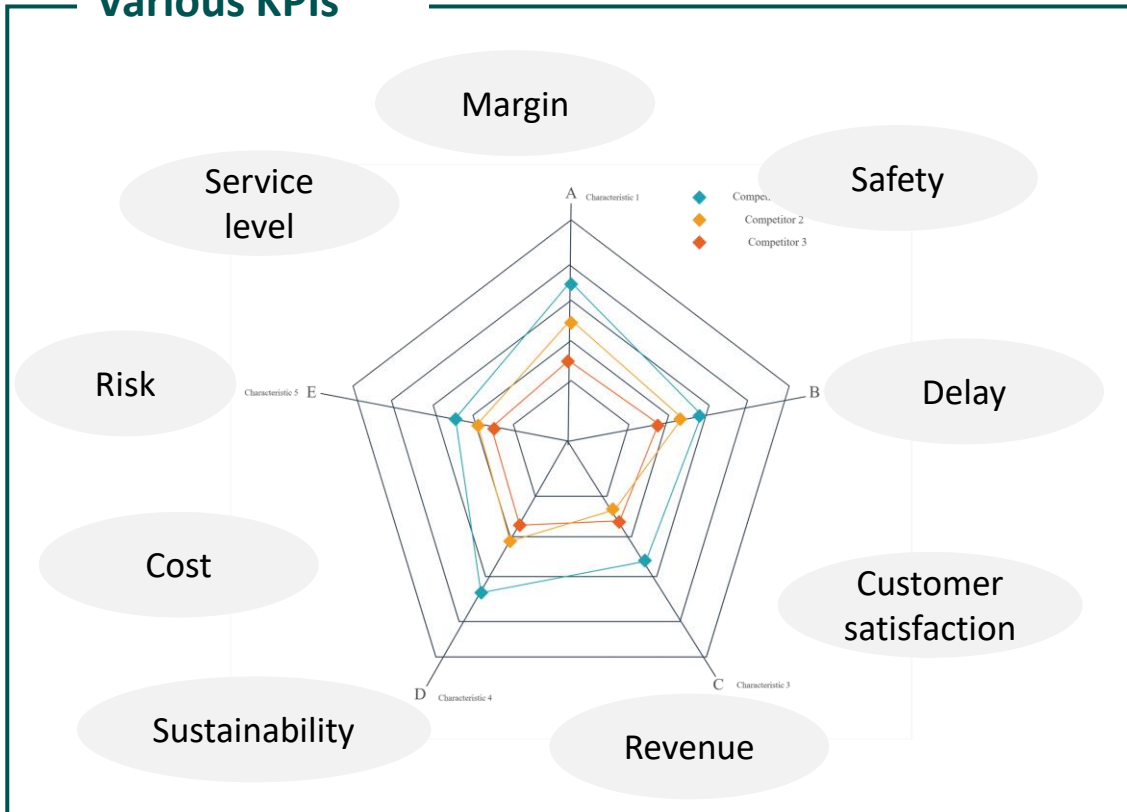
Multi-criteria optimization

Which criteria to guide the decision ?

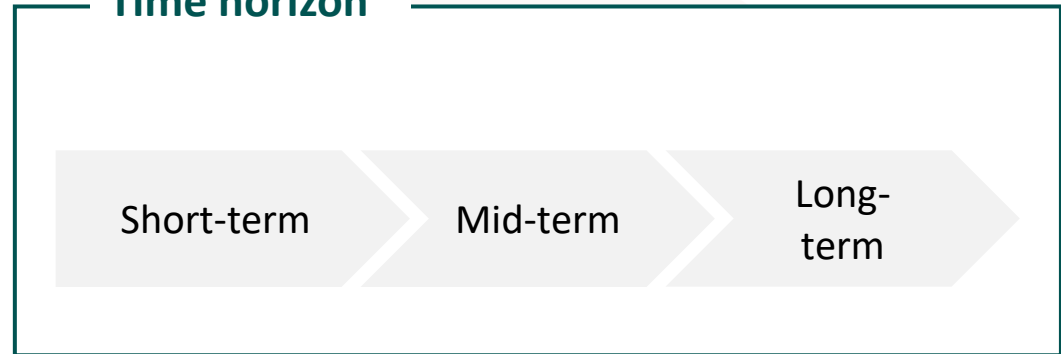
Quantitative

Qualitative

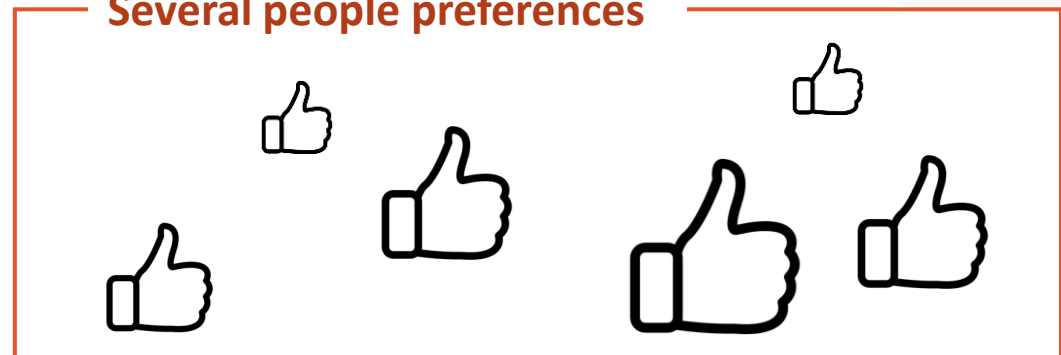
Various KPIs



Time horizon

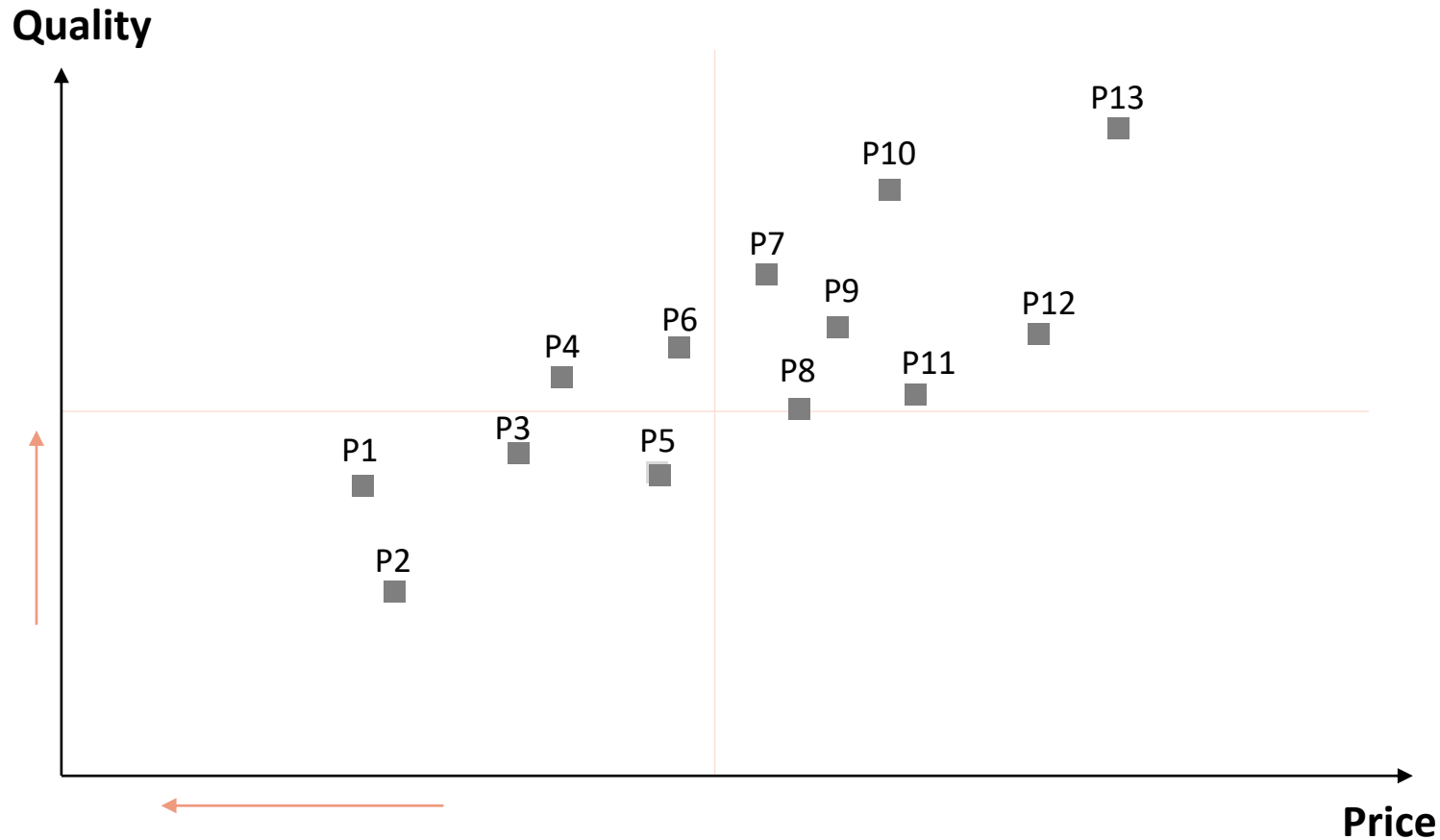


Several people preferences



Example with 2 criteria

You have to buy a product. On the market, you find 13 offers (P1, ... P13) that differs in price and quality as represented on the following graph :

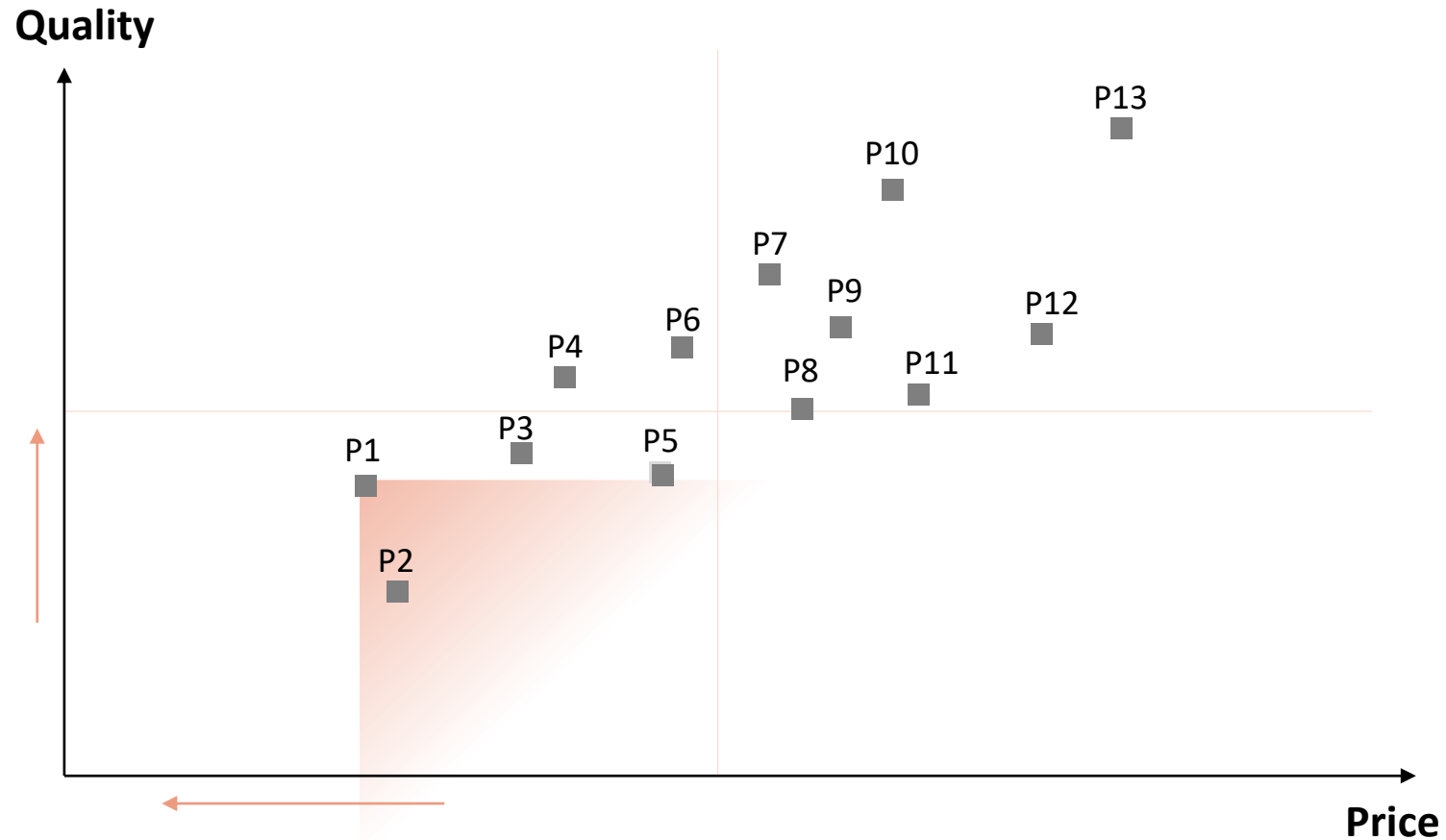


2 questions :

- Which product would you choose ?
- In which quadrant would be your ideal solution ?

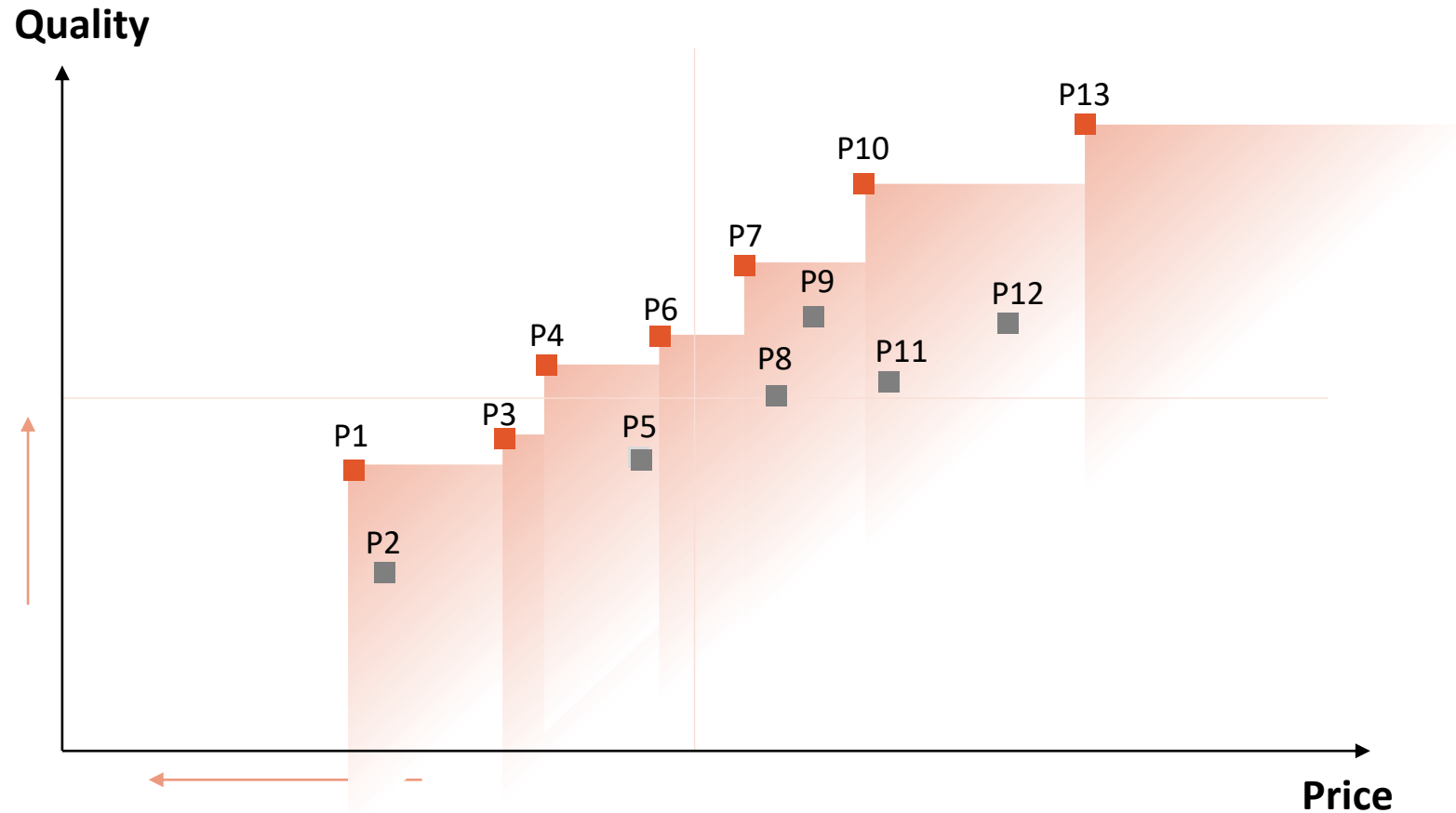
First, we remove the solutions that are dominated by another one

P1 dominates P2 since $\text{quality}_1 > \text{quality}_2$ and $\text{price}_1 < \text{price}_2$

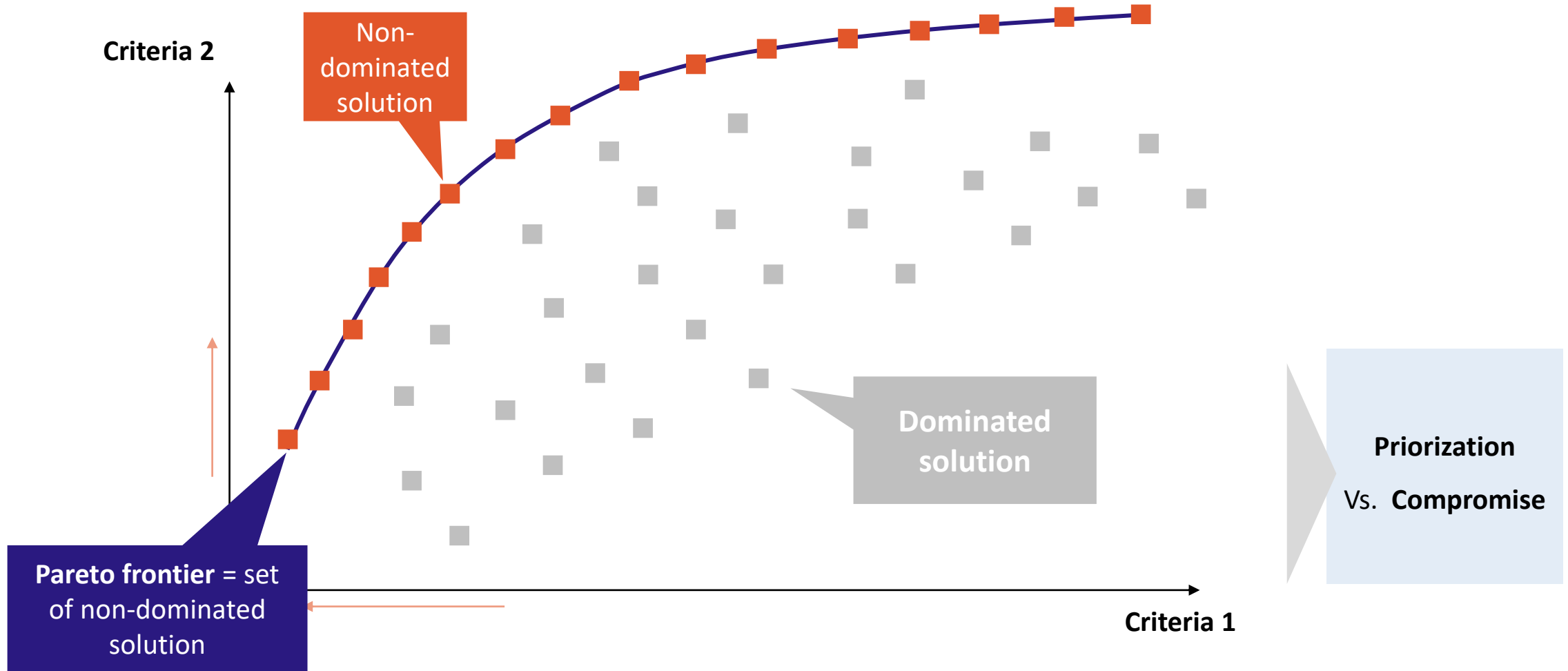


First, we remove the solutions that are dominated by another one

P_i dominates P_j if and only if **quality_i > quality_j** and **price_i < price_j**

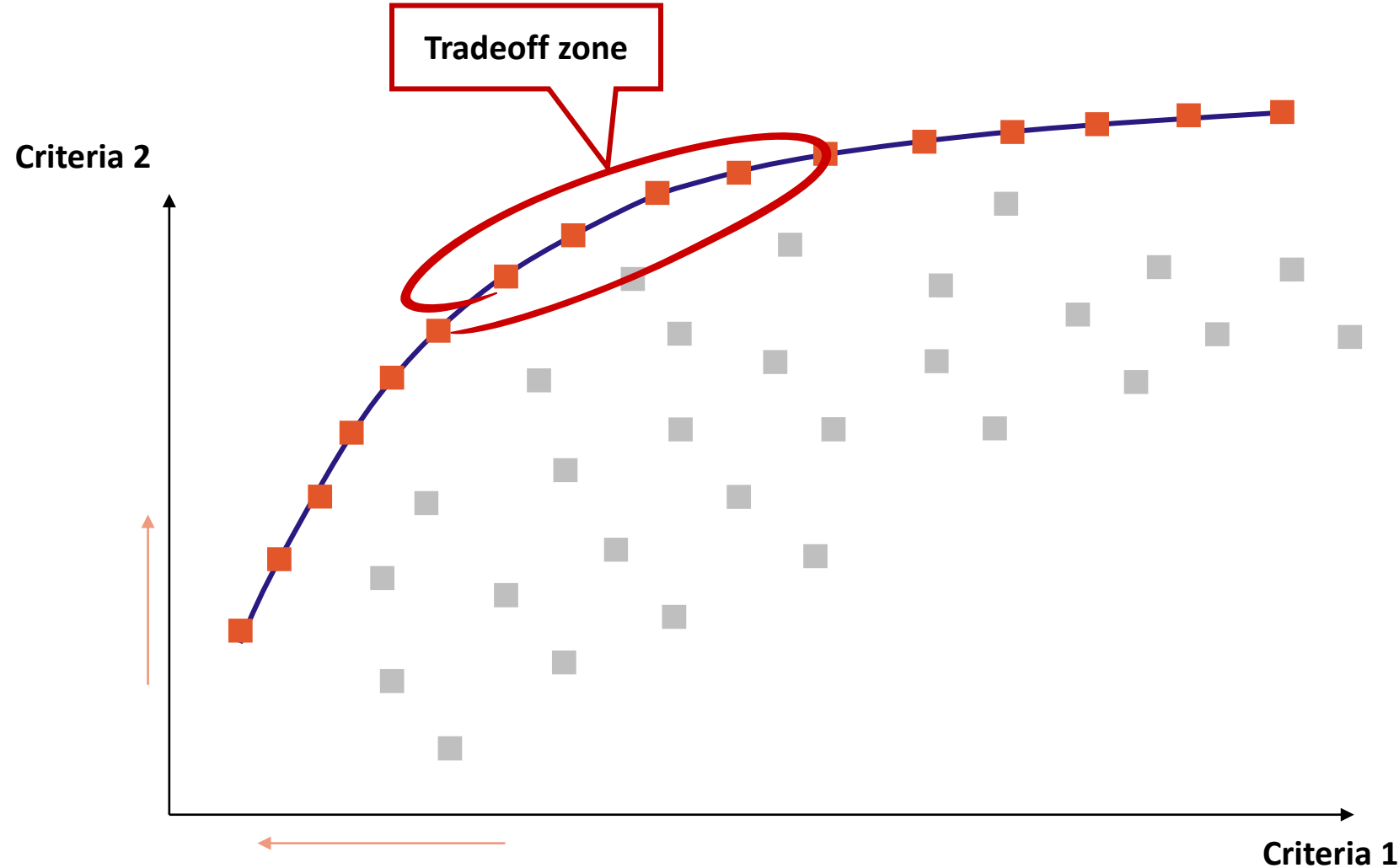


The set of non-dominated solutions form the **Pareto frontier**

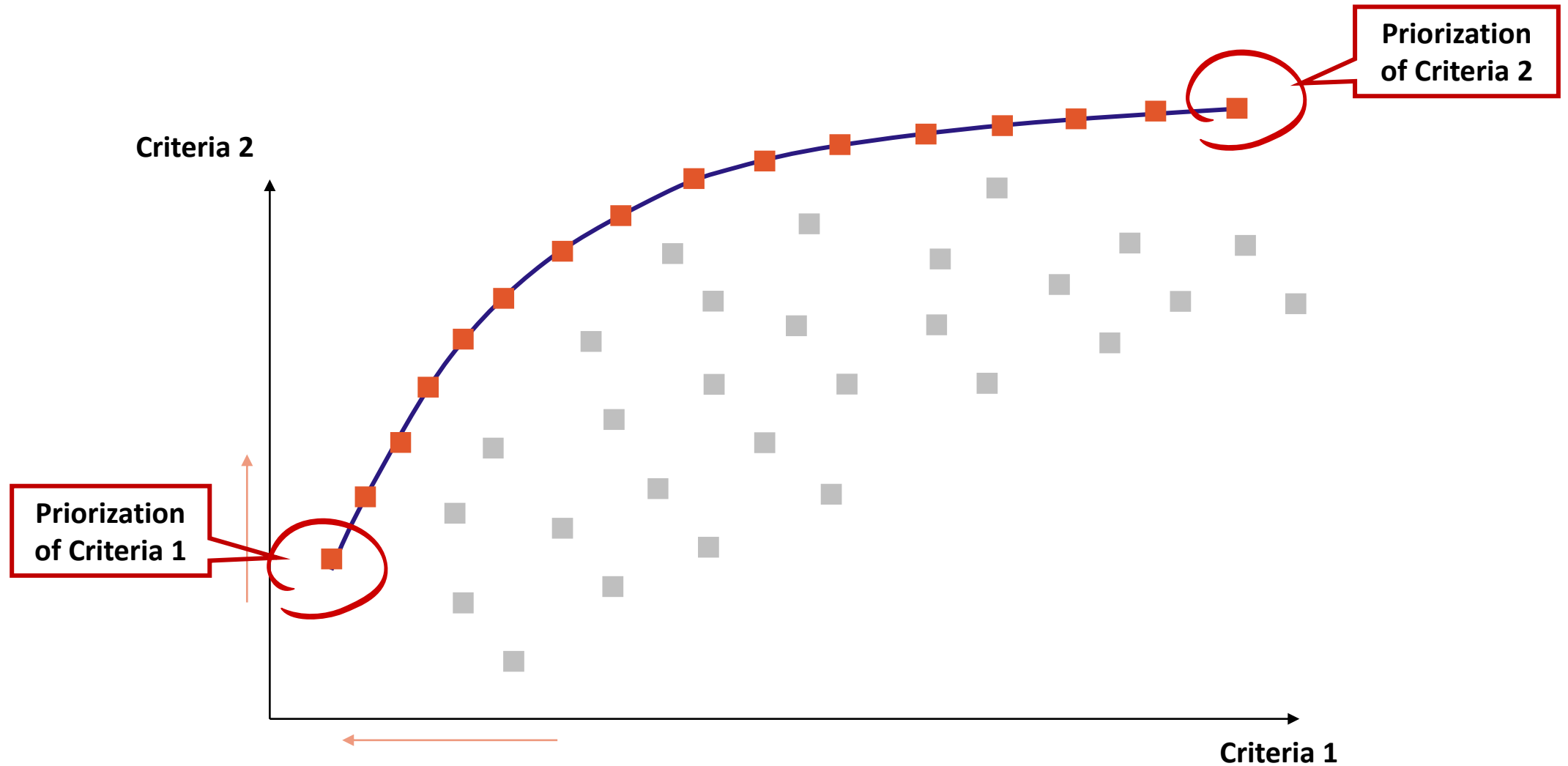


Generally, this set is hard to identify

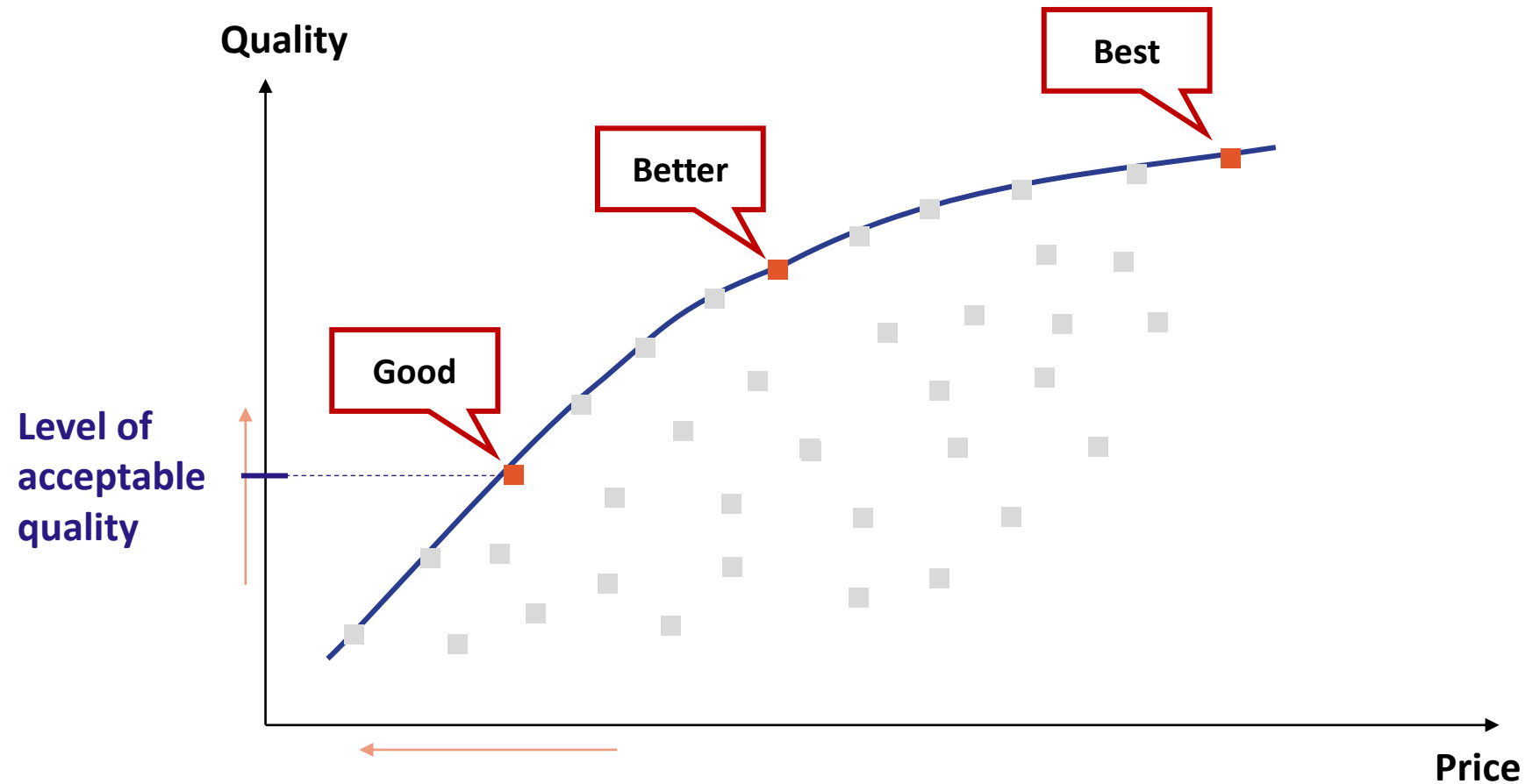
Then select your best solution among the Pareto frontier



Then select your best solution among the Pareto frontier



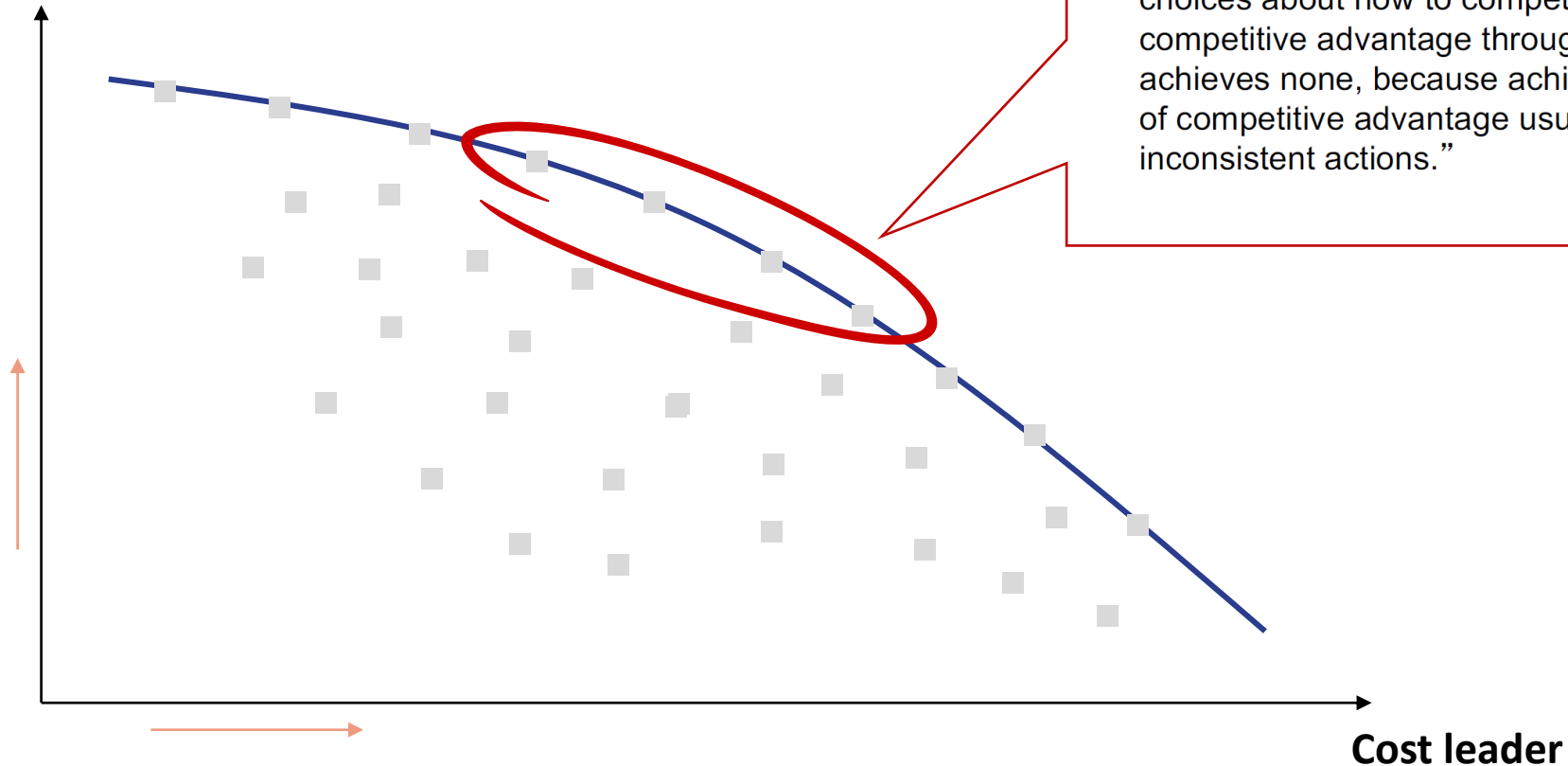
The « Good-Better-Best » pricing strategy from a multi-criteria perspective



Sometimes prioritizing is better than compromising

Strategy example

Product leader



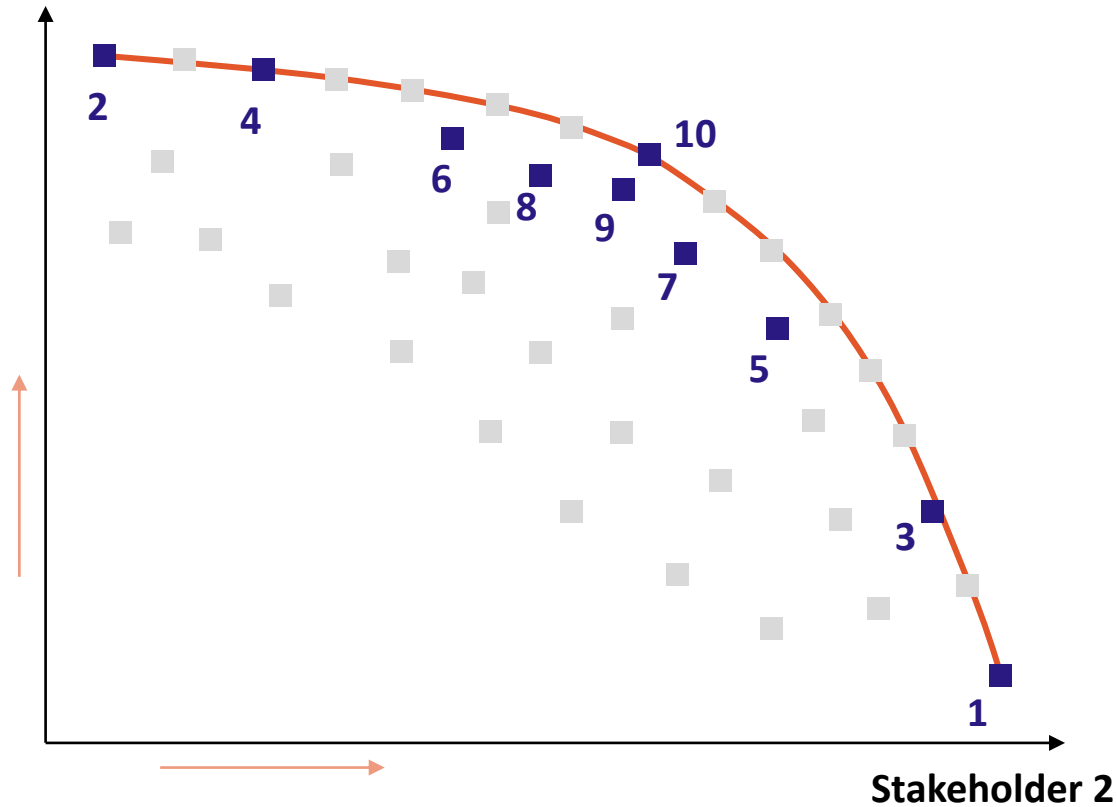
“Stuck in the Middle”

“Becoming stuck in the middle is often a manifestation of a firm’s unwillingness to make choices about how to compete. It tries for competitive advantage through every means and achieves none, because achieving different types of competitive advantage usually requires inconsistent actions.”

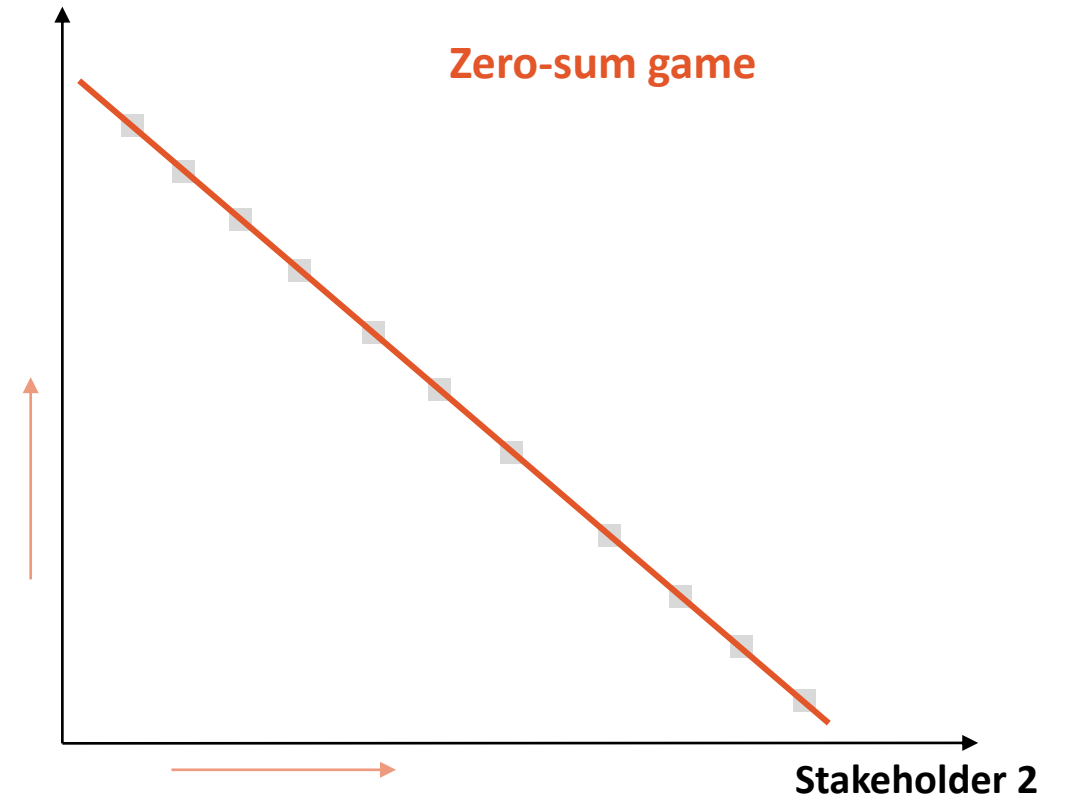
Michael Porter

Negotiation aims to explore this field and to identify a non-dominated tradeoff

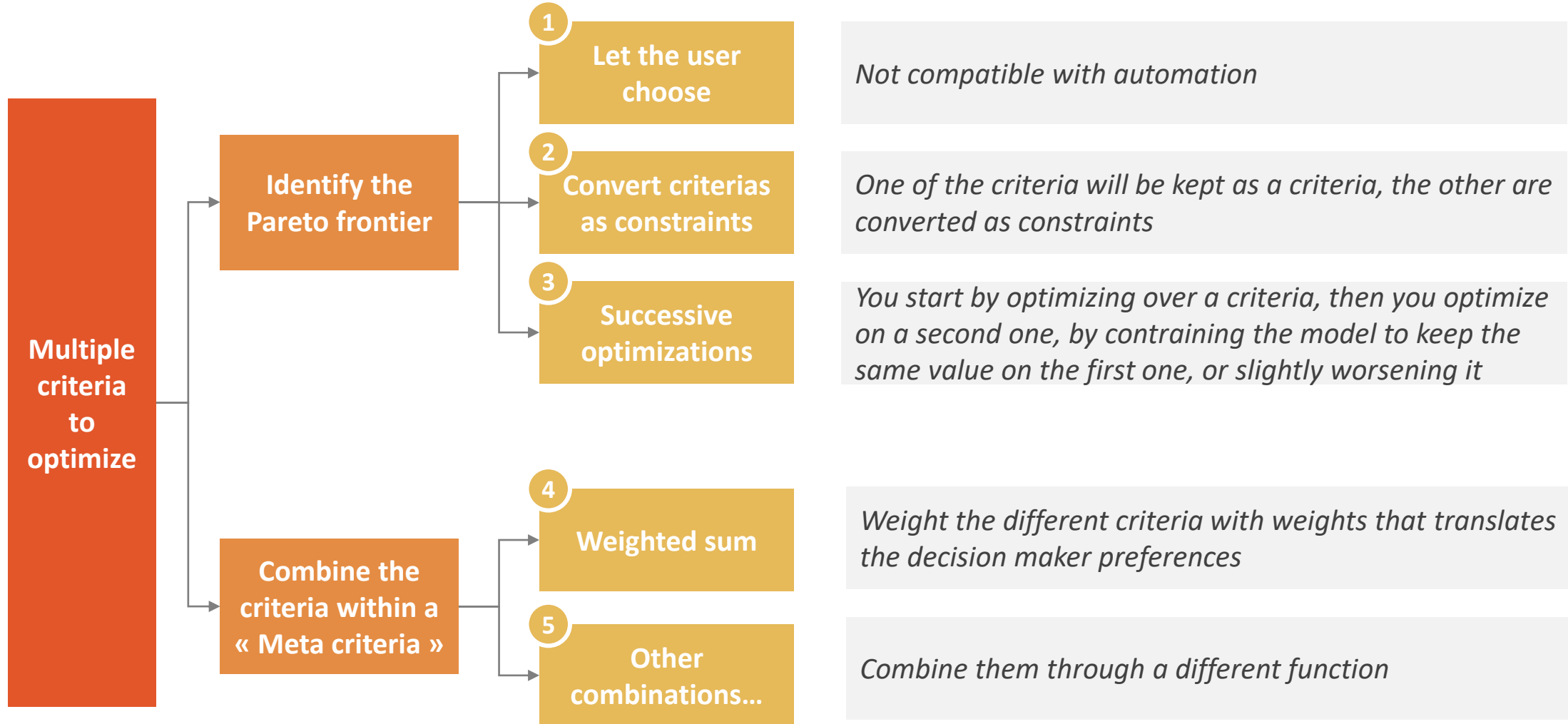
Stakeholder 1



Stakeholder 1



How to deal with multiple criteria ?



How to consider multiple objective in an optimization problem ?

2

Convert criterias as constraints



3

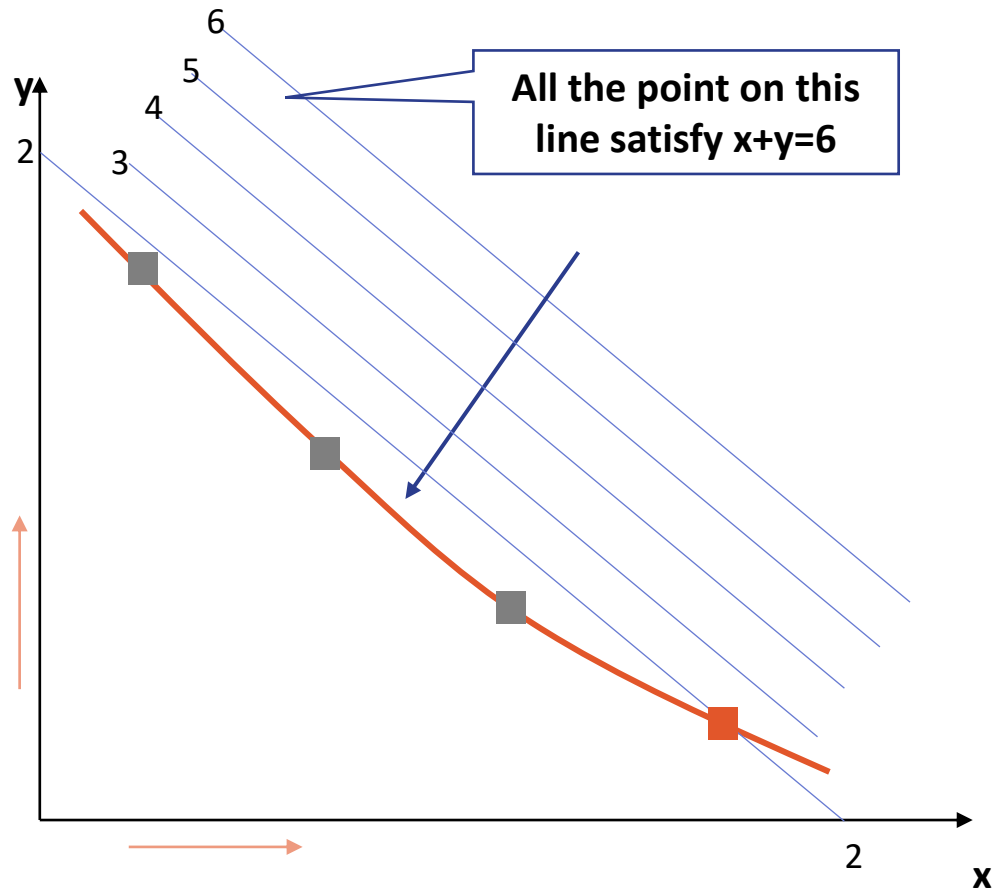
Successive optimizations



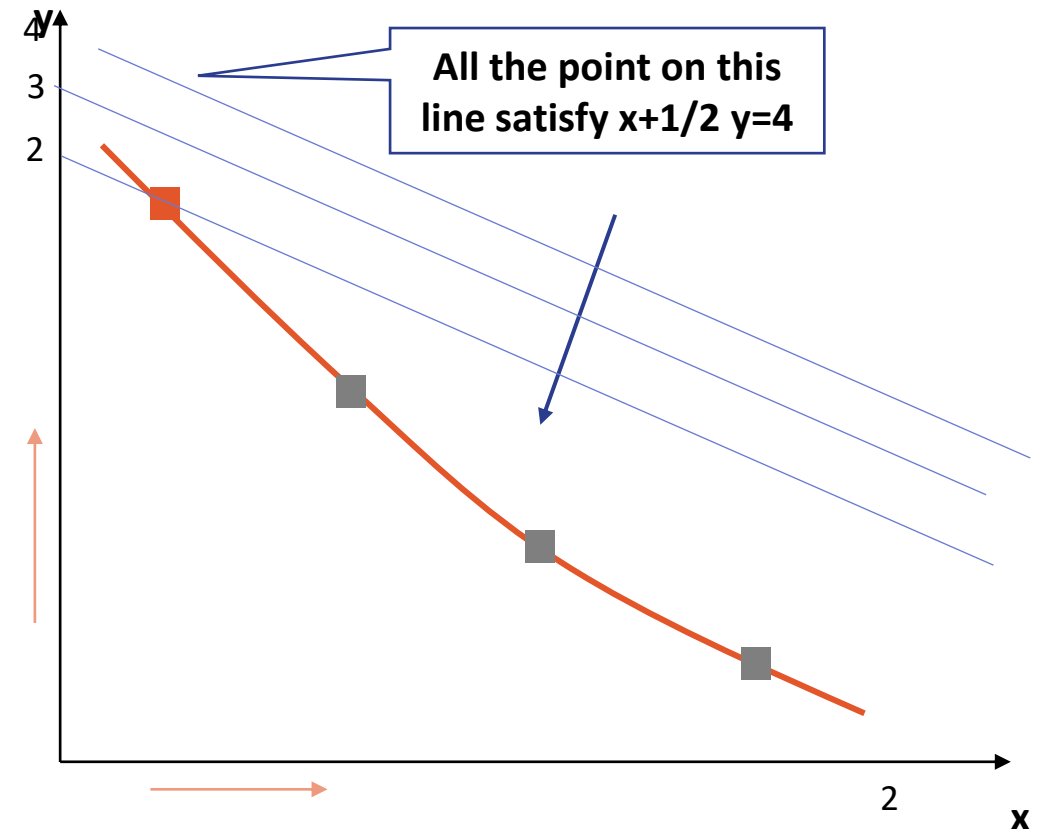
Using a weighted sum can be risky

Due to the convex shape of the curve, midpoints can not be reached

Ex : Criteria = $w_1 x + w_2 y$ with $w_1 = w_2 = 1$



Ex : Criteria = $w_1 x + w_2 y$ with $w_1 = 1$ et $w_2 = 1/2$



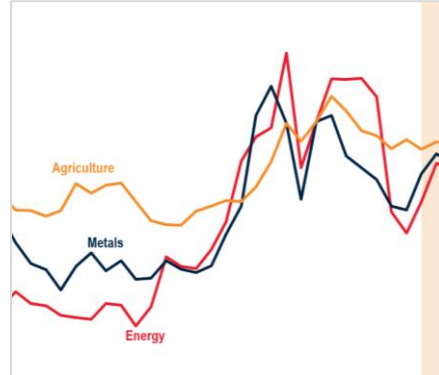
Optimization under uncertainty

Uncertainty is everywhere ...

*"To be uncertain is to be uncomfortable,
but to be certain is to be ridiculous."*
Chinese proverb*



Weather



Prices



Failure

*Customers' behaviors,
competitors reactions,
R&D success, ...*

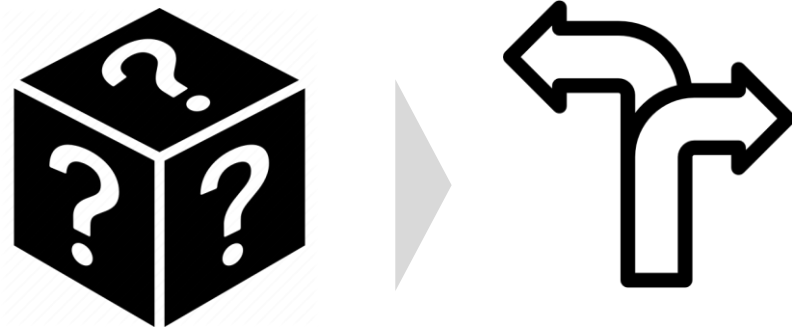
And so many others

... making rational decision-making
(and therefore optimization) much harder

* From A. Ben-Tal and L. El-Ghaoui. *Robust Optimization*. Princeton University Press, 2009.

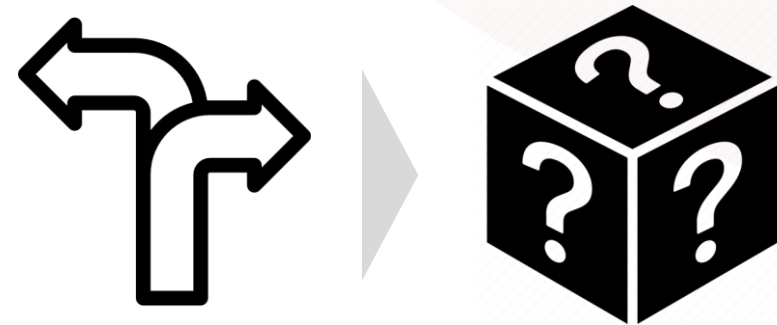
Decision under uncertainty : do I really have to make my decision before knowing what will happen ?

Cas 1 : hazard-decision



Deciding not to decide right now may have a cost

Cas 2 : decision-hazard



Sometime we have to decide right now

In the case « decision – hazard », 2 possible ways of making decisions

I take a bet on the future

I take a bet on one scenario (the most probable, or the expected) and **I make my decision based this scenario**

I don't even consider what might happen in other scenarios.

If my prediction fails, I'll lose a lot

« I believe I know »

Back to deterministic decision-making

The effort focuses on identifying the right scenario, through intelligence, forecasts, ...

I consider all the possibilities in my decision

I optimize in order to **min-maximize the expected outcomes or another risk measures (standard deviation, ...)**

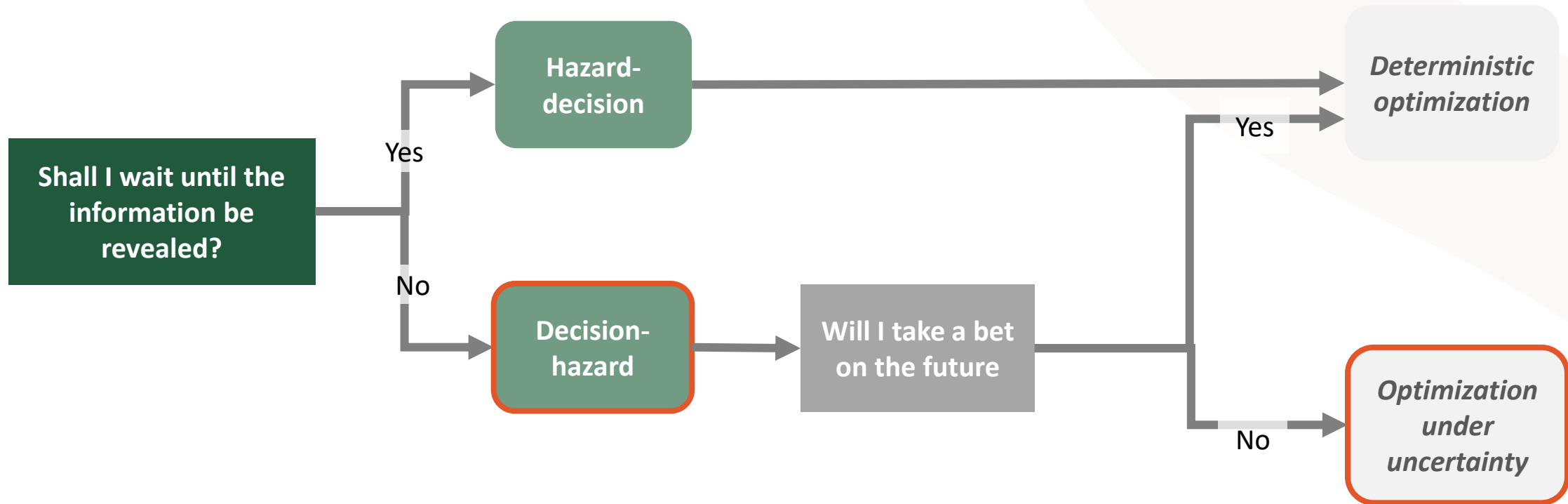
*I consider all the possibility in my decision
I aim at remaining close to the optimum regardless of the scenario that finally occurs*

« I know that I don't know »

Welcome to stochastic & robust optimization

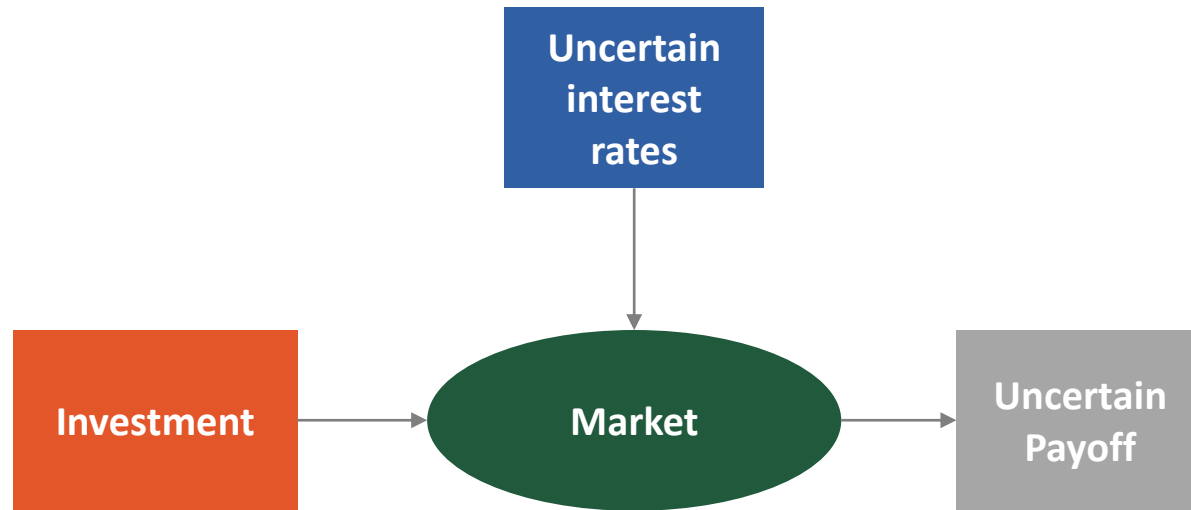
The effort focuses on structuring the available information (without extrapolating it) and using all this information for common decision-making

In the case « decision – hazard », 2 possible configurations



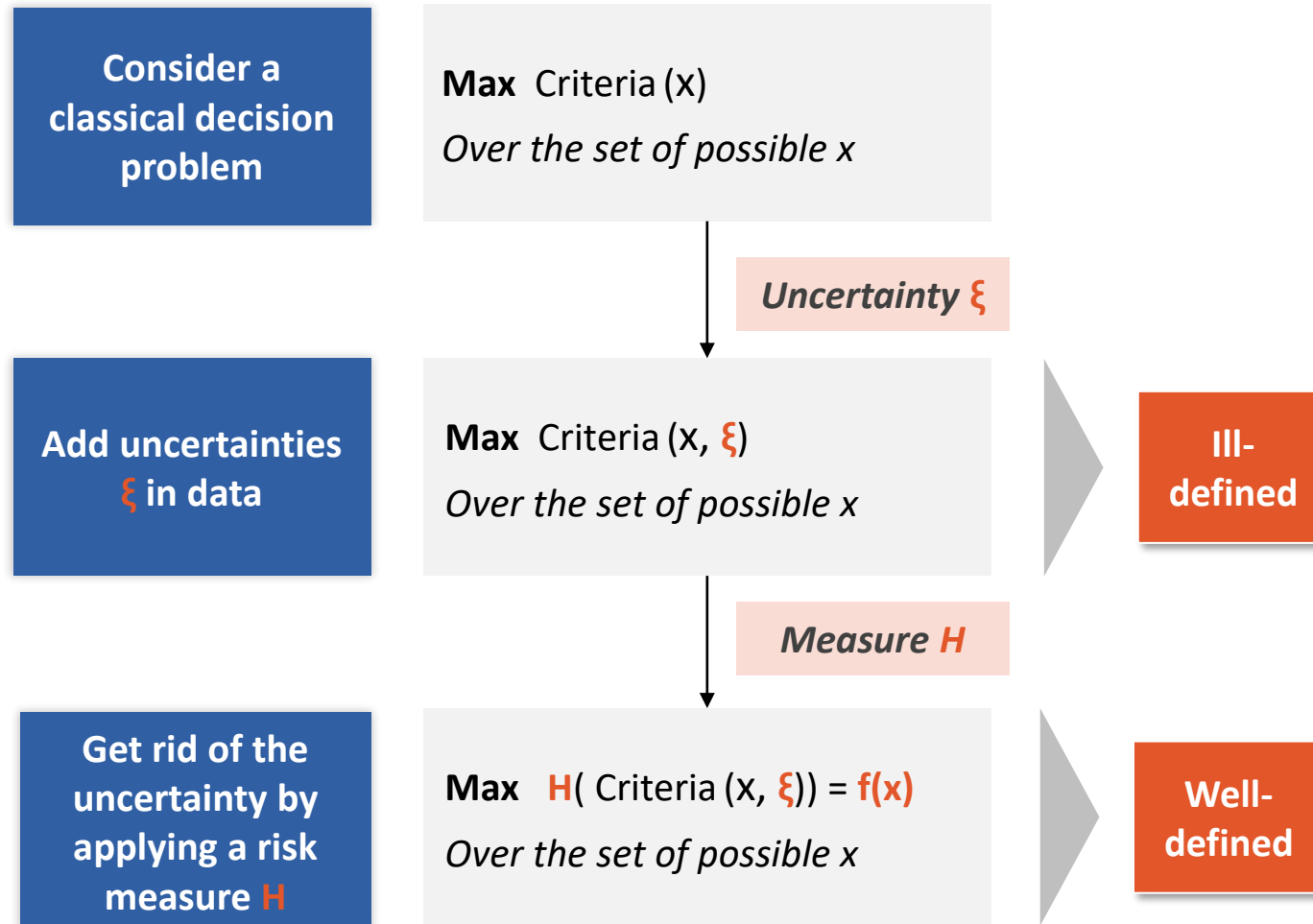
Typical example : the portfolio problem

You're an investor and you have to choose between investing in stocks, bonds or the money market

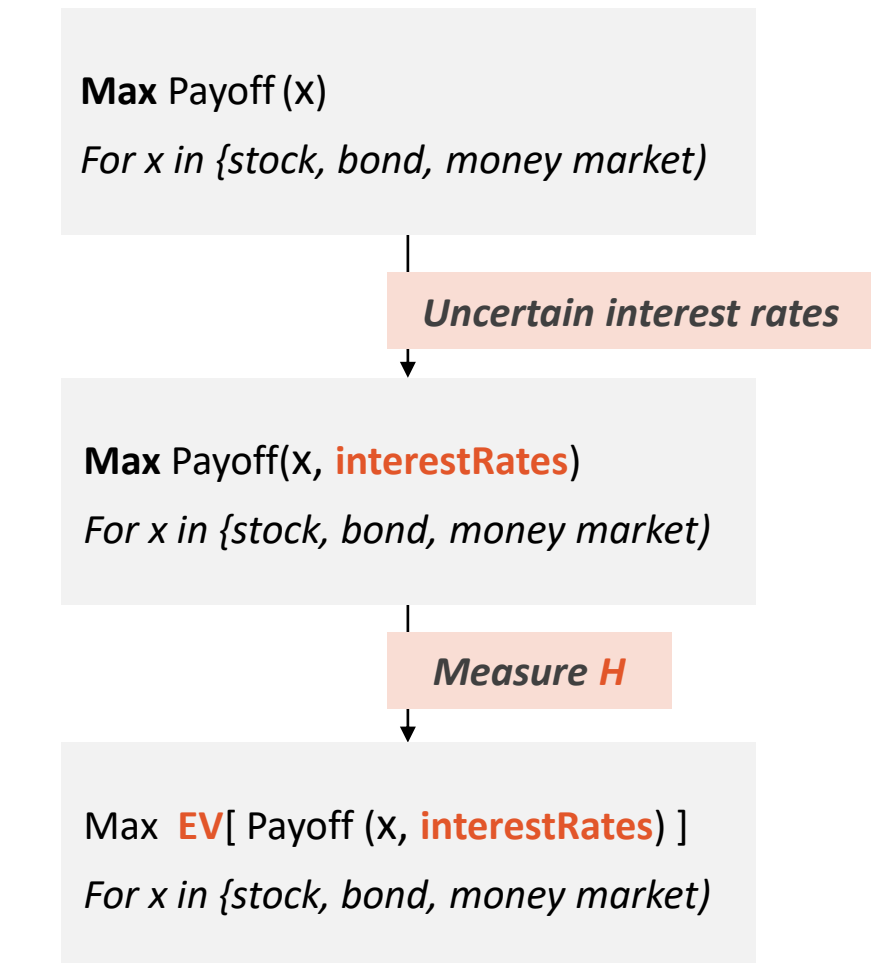


How considering uncertainties in an optimization problem ?

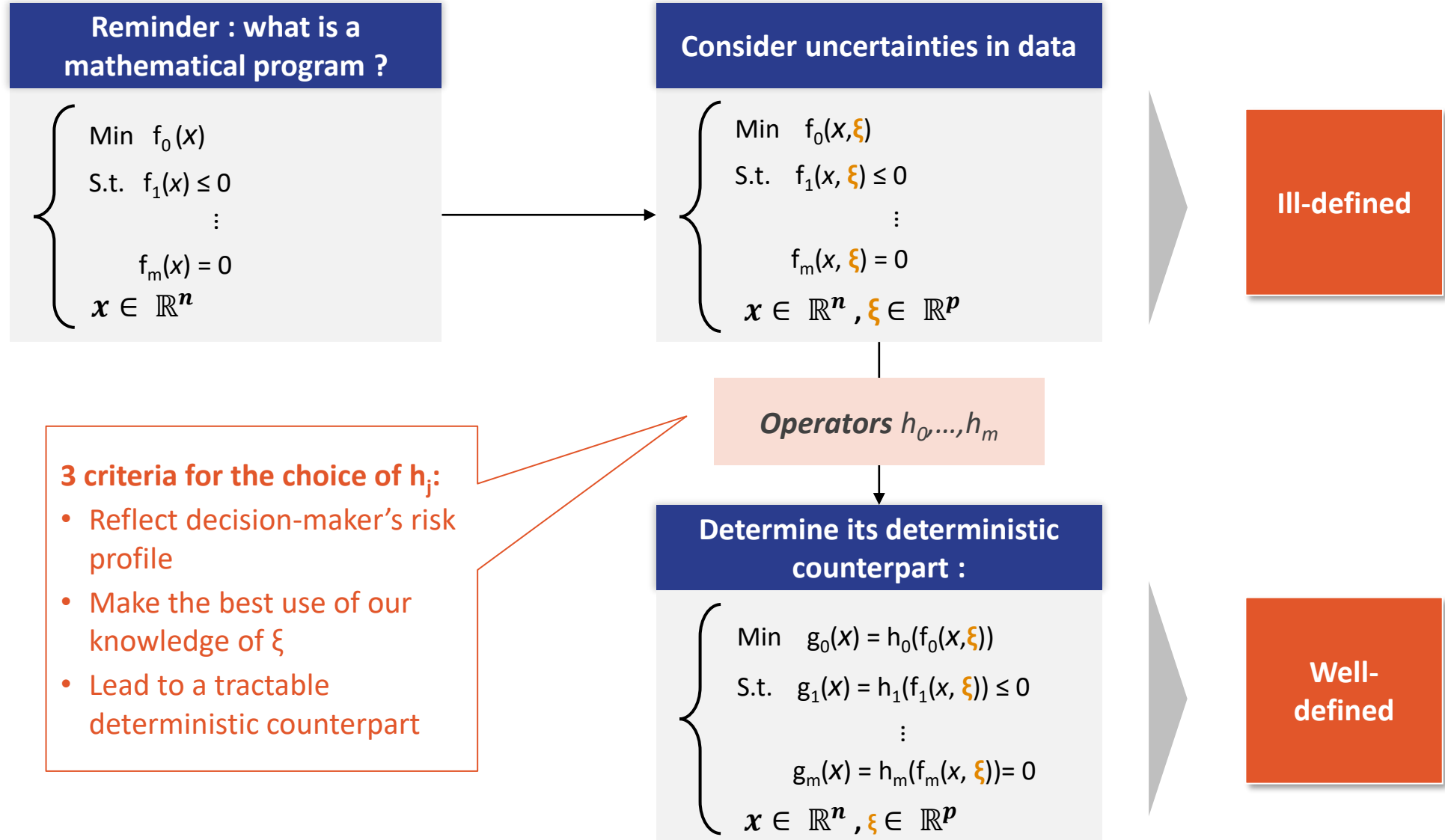
Generic framework



Investment example



More generally, how to consider uncertainty in an optimization problem ?



Ex : if the uncertainty is represented by a discrete set of scenarios

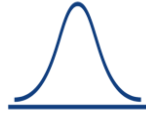
You're an investor and you have to choose between investing in stocks, bonds or the money market :

		Scenarios			Possible criterias		
		Interest rates rise	Static rates	Interest rates fall	Expected payoff*	Worst payoff**	Variance*
Probability		20%	50%	30%			
Possible decisions	Stocks	-4	4	12	4,8	-4	31,4
	Bonds	-2	3	8	3,5	-2	12,3
	Money market	3	2	1	1,9	1	0,5

* Requires probability

** Do not require probability

This leads to two commonly used paradigms to consider uncertainty in a decision problem



Stochastic optimization



Robust optimization

Available
information

Probability distribution of ξ

Support = all possible values for ξ

Risk measure

$H = \text{Expected value} + \text{Quantile}$

$H = \text{worst-case}$

Philosophy

Average approach

Requires a good knowledge of the uncertainties

Worst-case approach

Very conservative

Typical
application field



Finance



Engineering

Chance-constraint or probability constraints : satisfying a constraint with a given probability

Deterministic
constraint

$$f(x, \xi) \leq a$$

Chance-constraint
(or probability
constraint)

$$P_{\xi} [f(x, \xi) \leq a] \geq 1-\epsilon$$

Or equivalently : $P_{\xi} [f(x) > a] \leq \epsilon$

Example

$$P [\text{power shortout}] \leq 1\%$$

How to formulate a constraint in an uncertain optimization problem where the uncertainty is represented by a set of scenarios

Problem statement

Consider the constraint : $f(x, \xi) \leq a$

With ξ in $\{\xi_s\}_{s=1, \dots, n} \rightarrow n$ possible scenarios for ξ with probability p_s , $s = 1, \dots, n$

Robust constraint

Satisfy the constraint in the worst-case \equiv Satisfy the constraint on all cases :

$$f(x, \xi_s) \leq a, \quad \text{for all } s=1, \dots, n$$

Chance-constraint (or probability constraint)

$$P_{\xi} [f(x) > a] \leq \varepsilon$$

Define a binary variable per scenario y_s such that the non-satisfaction of the constraint on this scenario implies $y_s=1$ (BigM constraint) :

$$f(x, \xi_s) \leq a + M y_s$$

Then limit the number of $y_s=1$ in order to satisfy the required probability :

$$\sum_s p_s y_s \leq \varepsilon$$

3 choices to make

How to model uncertainty ?

- ▶ Continuous distribution
- ▶ Discrete distribution (scenarios)
- ▶ Fuzzy logic

Preferences of the decision maker

- ▶ Risk-neutral
- ▶ Risk-averse
- ▶ Risk-lovers

How to deal with uncertain constraints

- ▶ Penalisation
- ▶ Chance constraints
- ▶ Worst-case
- ▶ Recourse action

The efficient portfolio

The efficient portfolio

Problem statement

- You want to invest your budget (a total amount of 1) into different assets and you're looking for the optimal fraction of each asset.
- The rate of return of asset i is a random variable with expected value m_i
- Assets are not independent, as quantified by the covariance matrix C
- Your objective function combines the expected rate of return and a risk indicator.

Questions

- Formulate the problem as a 2-criteria optimization problem, combining the expected return and the variance as risk indicator
- How do you compute the variance of the portfolio return ?
- How could you determine the efficient frontier ? Hint : *apply KKT*

Refresher

$$\text{Var}(aX + bY) = a^2\text{Var}(X) + b^2\text{Var}(Y) + 2ab\text{Cov}(X, Y)$$

The efficient portfolio - Solution

Problem statement

Let C the covariance matrix and m the mean returns of stocks. We are looking for a solution that satisfies two criteria :

- ▶ Minimize the risk, computed as $x^T C x$
- ▶ Maximize the return, computed as $m^T x$

Problem formulation

In order to explore the efficient frontier, we convert one of the criteria as a constraint, and therefore solve the following problem for different values of m_{target} :

$$(P) \begin{cases} \min_x & x^T C x \\ \text{s.t.} & e^T x = 1, \\ & m^T x \geq m_{target} \\ & x \in \mathbb{R}_+^n \end{cases}$$

The efficient portfolio – Step 1

The linear problem

In order to define the range for m , we start by looking for the best possible value of m (independantly of the risk criteria) :

$$(P) \begin{cases} \max_x & m^T x \\ \text{s.t.} & e^T x = 1, \\ & x \in \mathbb{R}_+^n \end{cases}$$

KKT conditions

Stationarity conditions :

x is optimal if and only if there exists $\mu \in \mathbb{R}$ and $\lambda \in \mathbb{R}_+^n$ such that :
 $\nabla_x L(x, \lambda, \mu) = 0$, with $L(x, \lambda, \mu) = -m^T x + \mu(e^T x) - \lambda^T x$.

$$\nabla_{x_i} L(x, \lambda, \mu) = -m_i + \mu - \lambda_i = 0 \Leftrightarrow -m_i + \mu = \lambda_i \geq 0 \text{ so } \mu \geq m_i, \forall i$$

Complementarity slackness :

$\lambda_i x_i = 0$: either $x_i = 0$, or $\lambda_i = 0$.

As $e^T x = 1$, there is at least one value of i for which $x_i > 0$.

Let's i^* be such that $x_{i^*} > 0$, then $\lambda_{i^*} = 0$ so $\mu = m_{i^*}$ and therefore $m_{i^*} \geq m_i, \forall i$, so $i^* = \arg \max_i m_i$. In the sequel, let's assume that $i^* = 1$.

The efficient portfolio – Step 2

The
quadratic
problem

Iterate on $k = 1, \dots, N$:
 $m_{target} = \frac{k}{N} m_1$:

$$(P) \begin{cases} \max_x & x^T C x \\ \text{s.t.} & e^T x = 1, \\ & m^T x = m_{target} \\ & x \in \mathbb{R}_+^n \end{cases}$$

KKT
conditions
(w/o
inequality
constraint)

Solve the linear system :

$$\begin{bmatrix} C & e & m \\ e^T & 0 & 0 \\ m^T & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ \mu_1 \\ \mu_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ m_{target} \end{bmatrix}$$

Then check whether $x \geq 0$. If $x_i < 0$, add the constraint $x_i = 0$ and add the corresponding $\lambda \geq 0$ variable in the system.

KKT
conditions
(with 1
inequality
constraint)

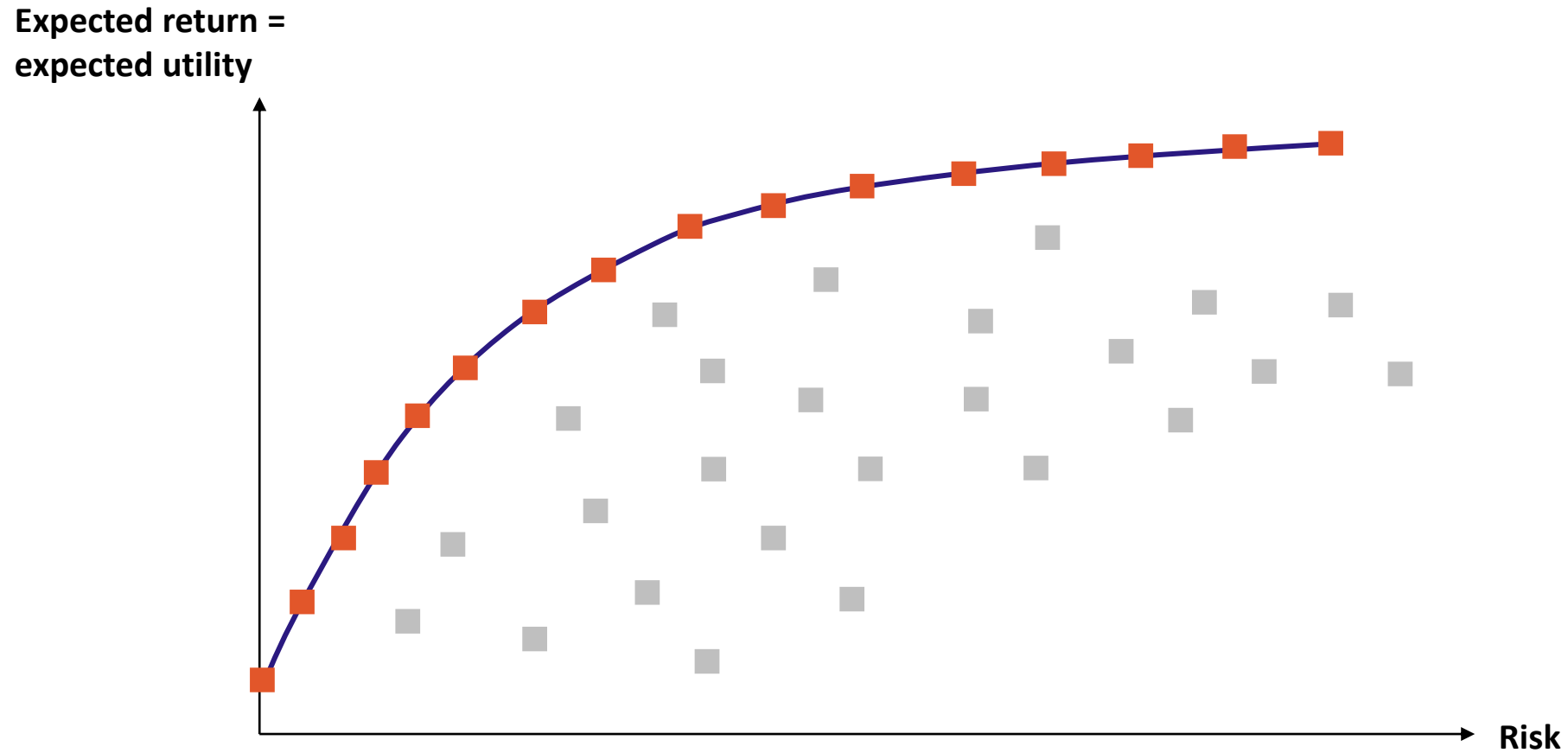
Solve the linear system :

$$\begin{bmatrix} C & e & m & e_{(j)} \\ e^T & 0 & 0 & 0 \\ m^T & 0 & 0 & 0 \\ e_{(j)}^T & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ \mu_1 \\ \mu_2 \\ \lambda_j \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ m_{target} \\ 0 \end{bmatrix}$$

with $e_{(j)}$ is the null vector except the j -th component that equals to 1.

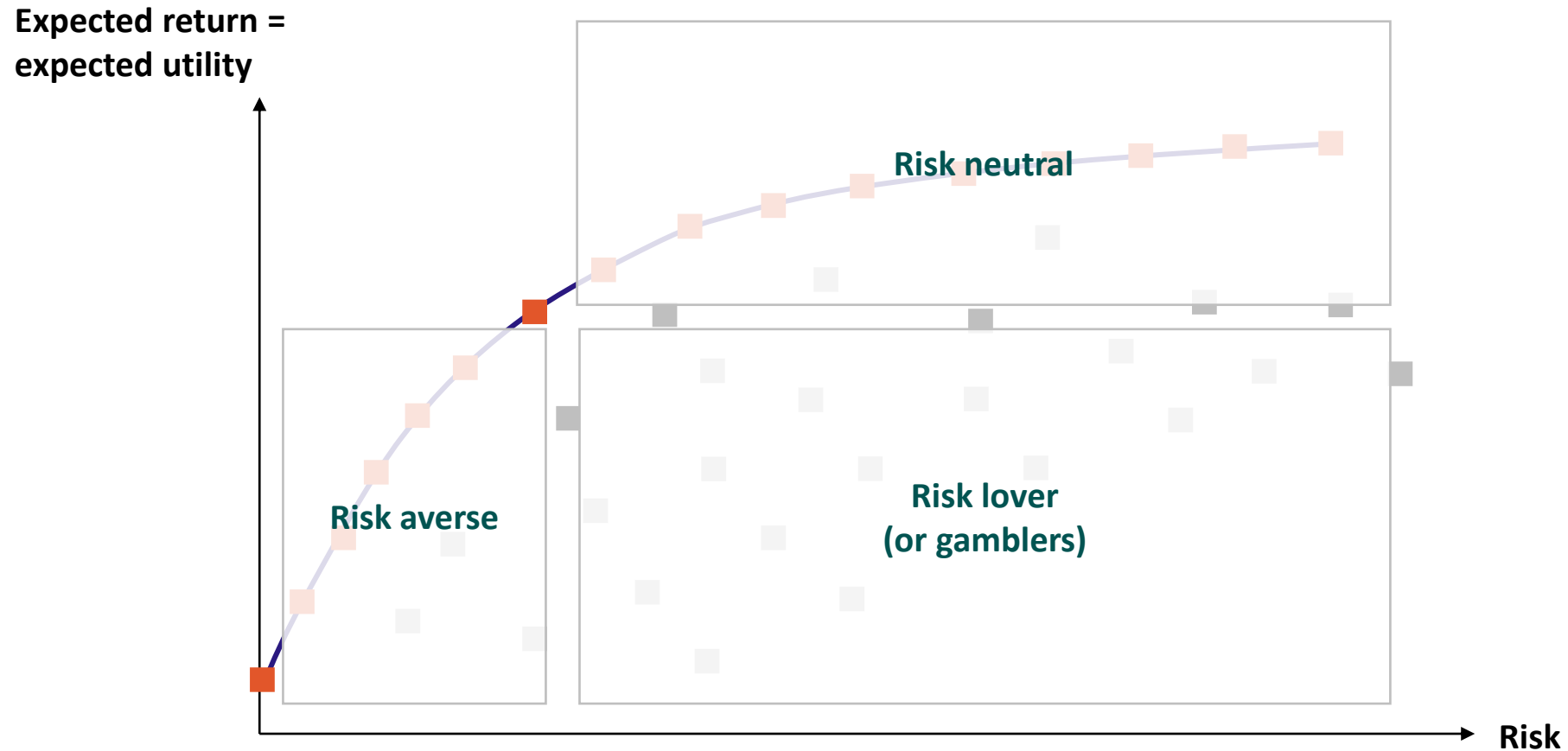
Add non-negativity constraints conjointly if required

Connecting the dots between Markowitz portfolio & expected utility theory



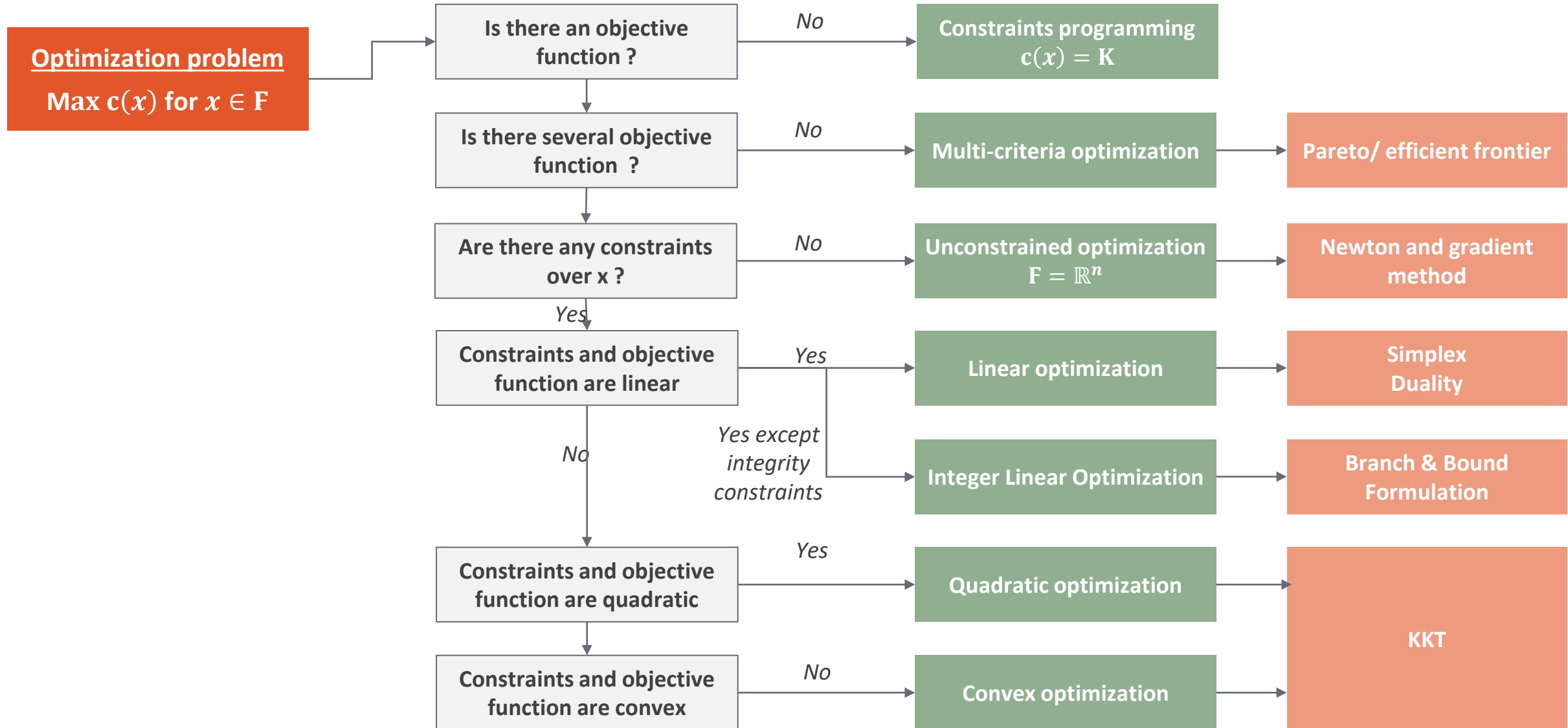
Markowitz portfolio theory

Connecting the dots between Markowitz portfolio & expected utility theory

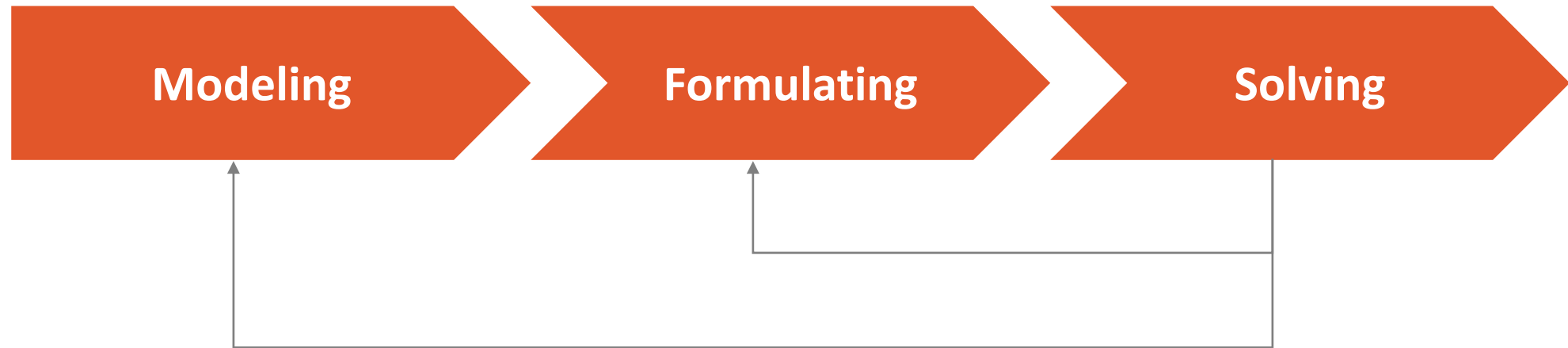


Markowitz portfolio theory

WRAP-UP on optimization



3 tasks



Conclusion

Static paradigm

- I have a random vector that depend one my decision : $\xi(x)$
- I use risk measures (such as expected value, quantile, CVaR, worst-case...) to get rid of the uncertainty
- I have 3 ways of representing uncertainties :
 - Continuous distribution
 - Uncertainty sets
 - Discrete distribution (scenarios)

Dynamic paradigm

- Some of my decisions are made after the uncertainty is known (recourse variables)
- In order to consider them in an optimization problem, uncertainties has to be represented through scenarios

Optimization under uncertainty brings additional difficulties compared to deterministic optimization

1

Modeling

How to model uncertainty ?

- Uncertainty set : $\varpi \in \Omega$
- Random variables (with probability)
 - Continuous
 - Discrete but countable infinite
 - Discrete and finite (scenarios)
- Fuzzy logic,

How to model decision dynamics

Which dependency to upcoming information ?

- Static
- Dynamic :
 - With recourse
 - Multi-stage

2

Solving

Uncertain problems are significantly **more difficult to solve** than their deterministic version :

- **Larger scale** (more variables, more constraints, more inputs data, ...)
- Converting the stochastic problem into their deterministic counterpart generally introduces more **complex mathematical structure** (not linear, ...)

The different choices to make

How to model uncertainty ?

- ▶ Continuous distribution
- ▶ Discrete distribution (scenarios)
- ▶ Fuzzy logic

How to intertwine decision with upcoming information ?

- ▶ Static
- ▶ Dynamic
 - ▶ With recourse
 - ▶ Multi-stage

Preferences of the decision maker

- ▶ Risk-neutral
- ▶ Risk-averse
- ▶ Risk-lovers

How to deal with uncertain constraints

- ▶ Penalisation
- ▶ Chance constraints
- ▶ Worst-case
- ▶ Recourse action

In the case « decision – hazard », 2 possible configurations

