

PATTERN

RECOGNITION

Daily and Sports
Activity Detection



TABLE OF CONTENTS

| Problem Statement | 3 |
|------------------------------------|----|
| 1. Dataset Configuration | 4 |
| 2. Clustering using K-Means | 7 |
| 3. Clustering using Normalized-Cut | 10 |
| 4. Evaluation Measures | 13 |
| 5. Clustering using DBSCAN | 16 |

PROBLEM STATEMENT

Clustering is a fundamental technique in unsupervised machine learning that plays a key role in organizing data into meaningful groups based on similarities. The objective of this assignment is to help students understand how K-Means and Normalized Cut algorithms can be used for the detection of daily and sports activities captured using motion sensors.

- 1. Download Dataset and Understand the Format
 - We will use the "Daily and Sports Activity" dataset for this assignment.
- 2. Clustering Using K-Means and Normalized Cut (Your implementation)
 - We will use K-Means to cluster the daily and sports activity data and cluster them.
 - We will change the K of the K-means algorithm between {8, 13, 19, 28, 38} clusters. You will produce different clusters.
- 3. Normalized Cut (Your implementation)
 - Apply Normalized Cut algorithm to the two solutions to cluster the data into 19 clusters.
 - Compare the results of K-Means and Normalized Cut clustering regarding the number of detected activities and their characteristics.

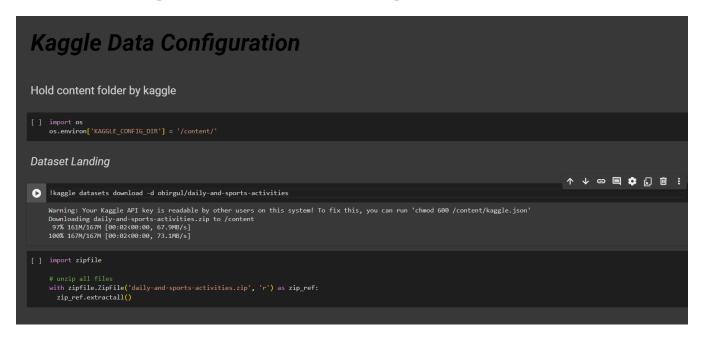
4. Evaluation

- We will evaluate models based on their ability to detect daily and sports activities accurately. You will be required to use the following metrics to evaluate the quality of their models:
 - Precision
 - Recall
 - F1 score
 - Conditional Entropy
- 5. New Clustering Algorithm (Your implementation)
 - Choose any clustering technique of your own choice, implement it and repeat the above experiments.

1. DATASET CONFIGURATION

We have downloaded the "daily-and-sports-activities" dataset from Kaggle.

Downloading the dataset and understanding it's format:



- We've used the Kaggle CLI to download the dataset specifying it's slug (obirgul/daily-and-sports-activities).
- Then we made a folder for activities and extracted the zip file of the dataset in it.
- We have 19 labels and for each label we have 480 data points, so by total we have 9120 data points and each data point is 45 labels vector.

Generate the Data Matrix and the Label vector:

```
Data Loader
import imageio as img
     import pandas as pd
     def basic_load_for_dataset(absolute_directory_path):
       naive_data = []
       naive_truth = []
       for activity_folder in sorted(os.listdir(absolute_directory_path)):
           activity_path = os.path.join(absolute_directory_path, activity_folder)
           activity_data = []
           activity_truth = []
           for subject_folder in sorted(os.listdir(activity_path)):
               subject_path = os.path.join(activity_path, subject_folder)
               segment_data = []
               segment_truth = []
               for segment_file in sorted(os.listdir(subject_path)):
                   segment_path = os.path.join(subject_path, segment_file)
                   df = pd.read_csv(segment_path, header=None)
                   segment_data.append(df.values.tolist())
                   segment_truth.append(get_truth_value_for_segment(activity_folder, subject_folder, segment_file))
               activity_data.append(segment_data)
               activity_truth.append(segment_truth)
           naive_data.append(activity_data)
           naive_truth.append(activity_truth)
       return np.array(naive_data), np.array(naive_truth)
```

- We've created a function that takes the directory and iterates on each activity folder and for each subject.
- .For each subject read the 125x45 vector, and append it in the data matrix.
- for each point now we have two options:
 - take the mean for each column and now our labels vector is 1d of size 45.
 - Flatten the vector and perform PCA on it to reduce it to be 1d of size 45.

• Reformulate the dataset using mean

Reformulate the dataset using dimensionality reduction algorithm (PCA).

2. Clustering Using K-Means

Code:

- Training:
 - k-means clustering algorithm initializes random k centroids, in this implementation each centroid is a random point from the dataset. Then for each point in the training set, calculate the distance between it and each of the k centroids. Assign the point to the centroid of the smallest distance between it. After assigning each point to the nearest centroid, each centroid is updated to a new value that equals the mean of the points assigned to it. These steps are repeated until the norm of difference between old values and new values of each centroid is less than a given threshold.

- Testing:

- For each point in the testing dataset, calculate the distance between it and each of the k centroids calculated in the training stage, and assign it to the centroid with the smallest distance between them.

```
def k_means_testing(testing_dataset, centroids):
    testing_samples_size = testing_dataset.shape[0]
    predictions = np.zeros((testing_samples_size))
    for i in range(testing_samples_size):
        predictions[i] = predict_cluster_for_point(testing_dataset[i], centroids)
        predictions = np.array(predictions, dtype=int)
        return predictions;
```

Results of k-means:

- By splitting the data matrix into training and test sets by ratio 0.8 for training and 0.2 for testing.

By using mean reformulation.

| K | Tra | aining se | et evaluatio | n | Testing set evaluation | | | | |
|----|-----------|-----------|--------------|---------|------------------------|---------|----------|---------|--|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy | |
| 8 | 0.22957 | 0.4846 | 0.3539 | 3.07712 | 0.2655 | 0.45717 | 0.3403 | 3.1048 | |
| 13 | 0.2509 | 0.3405 | 0.29804 | 2.944 | 0.25109 | 0.3407 | 0.2978 | 2.9196 | |
| 19 | 0.27069 | 0.2571 | 0.26634 | 2.8509 | 0.26206 | 0.2489 | 0.2512 | 2.7965 | |
| 28 | 0.2915 | 0.191 | 0.22959 | 2.758 | 0.29769 | 0.19504 | 0.2213 | 2.6282 | |
| 38 | 0.3018 | 0.147 | 0.1953 | 2.7029 | 0.31907 | 0.15544 | 0.20614 | 2.5366 | |

By using PCA reformulation

| K | Tr | aining se | et evaluatio | n | Testing set evaluation | | | | |
|----|-----------|-----------|--------------|---------|------------------------|---------|----------|---------|--|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy | |
| 8 | 0.18188 | 0.3839 | 0.28262 | 3.47597 | 0.18366 | 0.38773 | 0.29413 | 3.42913 | |
| 13 | 0.19682 | 0.2671 | 0.23558 | 3.37264 | 0.20285 | 0.27529 | 0.24179 | 3.30504 | |
| 19 | 0.20367 | 0.1934 | 0.20102 | 3.3442 | 0.21217 | 0.20156 | 0.21049 | 3.23586 | |
| 28 | 0.22491 | 0.1473 | 0.17028 | 3.2857 | 0.22532 | 0.14762 | 0.17377 | 3.16323 | |
| 38 | 0.23862 | 0.1162 | 0.15275 | 3.2419 | 0.25712 | 0.12526 | 0.16613 | 3.05277 | |

• Comments:

- The results are relatively worse than Spectral clustering which indicates that the data is not spherical so K-means is not the better approach to cluster it.
- Precision score is better when near to 1 but average is 0.270146 and 0.217688 for mean reformulation and PCA reformulation respectively
- F1 score is better when near to 1 but average is 0.270146 and 0.217688 for mean reformulation and PCA reformulation respectively
- Entropy is better when near zero and worse is log₂(K) and average is 2.78738
 and 3.349452 for mean reformulation and PCA reformulation respectively

3. Clustering Using Normalized -Cut

Code:

```
def k_way_normalized_cut(data, k, gamma):
  parameter:
    - The data matrix containing all the data points
    - The gamma value that will be used for generation of similarity matrix
    - The number of clusters that will be generated
  return:
   - The Labels of each data point in the data matrix
  # Compute similarity matrix using RBF kernel
  similarity_matrix = compute_similarity_matrix(data, gamma)
  # Compute the degree matrix
  degree matrix = np.diag(np.sum(similarity matrix, axis=1))
  # Compute the Laplacian matrix
  laplacian_matrix = degree_matrix - similarity_matrix
  # Compute the normalized Laplacian matrix (B matrix)
  for i in range(len(laplacian matrix)):
    laplacian_matrix[i][i] /= degree_matrix[i][i]
  normalized_laplacian_matrix = laplacian_matrix
  # Compute the first k normalized eigenvectors
  _, eigenvectors = np.linalg.eig(normalized_laplacian_matrix)
  eigenvectors = eigenvectors[:, :k]
  eigenvectors = np.real(eigenvectors)
  # Compute the normalized eigenvectors
  normalized_eigenvectors = normalize_eigenvectors(eigenvectors)
  # Perform Kmeans on the normalized eigenvectors and get the labels of each point
  labels = KMeans(n_clusters=k, random_state=0).fit(normalized_eigenvectors).labels_
  return labels
```

- This function performs the algorithm of Normalized-Cut (Spectral Clustering).
- Compute the similarity matrix, which calculates the pairwise distance for all points.
- We've chosen the distance function as the RBF-Kernel function, with specified gamma = 0.00001.
- Calculate the diagonal matrix from the similarity matrix.
- Calculate the Laplacian matrix from the difference of degree matrix and similarity matrix.
- Calculate the normalized laplacian matrix from the dot product of inverse of degree matrix and laplacian matrix.
- Calculate the eigenvectors of the normalized laplacian matrix using eig function, then choose the first 19 eigenvectors then calculate the normalized eigenvectors.
- Perform K-means with 19 clusters on the normalized eigenvectors and return the labels for each datapoint.

Evaluation on two cases:

```
➤ Evaluation on mean dataset
Fit the train of mean dataset in the model

# load the mean dataset
train_mean_dataset, train_mean_truth, test_mean_dataset, test_mean_truth = get_mean_dataset(naive_data, naive_truth, 0.8)

# Reformulate the test data
test_mean_dataset, test_mean_truth = dataset_after_mean_reformulation(test_mean_dataset, test_mean_truth)

# perfrom normalized cut on test mean dataset
test_predictions = k_way_normalized_cut(test_mean_dataset, k=19, gamma=0.00001) + 1

Evaluate the clusters using different measures

Print("Evaluation on mean dataset: ")
evaluate(test_predictions, test_mean_truth)
```

```
Fit the train of PCA dataset

Fit the train of PCA dataset in the model

# load the PCA dataset
pca, train_pca_dataset, train_pca_truth, test_pca_dataset, test_pca_truth = get_reduced_dataset(naive_data, naive_truth, 0.8)

# Reformulate the PCA dataset
collapsed_arr = test_pca_dataset.reshape((19 * 8 * 12, 125 * 45))
collapsed_truth = test_pca_truth.reshape((19 * 8 * 12))

# Reduce the dimensinos of test pca
test_pca_dataset = pca.transform(collapsed_arr)

# perfrom normalized cut on test PCA dataset
test_pca_predictions = k_way_normalized_cut(test_pca_dataset, k=19, gamma=0.00001) + 1

Evaluate the clusters using different measures
```

• Compare with K-Means:

• Comparison on Testing set on mean reformulated data:

| K | K-Means | | | | | Spectral | Clustering | |
|----|-----------|--------|----------|---------|-----------|----------|------------|---------|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy |
| 19 | 0.26206 | 0.2489 | 0.2512 | 2.7965 | 0.42817 | 0.4067 | 0.42622 | 2.02945 |

• Comparison on Testing set on dimensionality reduced data:

| K | K-Means | | | | Spectral Clustering | | | |
|----|-----------|--------|----------|---------|---------------------|--------|----------|---------|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy |
| 19 | 0.26206 | 0.2489 | 0.2512 | 2.7965 | 0.43695 | 0.4151 | 0.44091 | 2.06317 |

Comments:

- Spectral Clustering gives higher precision in both cases, as mentioned above the reason for this is that the data is not spherical.
- It's observed that the dimensionality reduced data gives higher precision than the mean reformulated data, and that because the mean summarizes the data without concerning the variance, while in PCA it captures the most important features of the data to increase the variance.
- If we perform the LDA algorithm instead of PCA, we'll get higher measures (precision) and that is because LDA exploits class information and enhances class separability.

4. EVALUATION MEASURES

First, Build the contingency matrix.

```
def count(i, j, predictions, truth):
    count = 0
    for idx in range(len(predictions)):
        if predictions[idx] == i and truth[idx] == j:
            count += 1
    return count

def map(predictions, truth):
    truth_classes_num = np.unique(np.array(truth)).shape[0] + 1
    predicted_classes_num = np.unique(np.array(predictions)).shape[0] + 1

    matrix = np.zeros((predicted_classes_num, truth_classes_num))

for i in range(predicted_classes_num):
    for j in range(truth_classes_num):
        matrix[i][j] = count(i, j, predictions, truth)

return matrix
```

Given the contingency matrix, calculate the Precision.

```
def total_precision(matrix):
    precision_classes = np.zeros(len(matrix))
    total = 0
    total_occurences = np.sum(matrix)

for i in range(len(precision_classes)):
    max_occurence = np.max(matrix[i])
    class_occurence = np.sum(matrix[i])
    if np.sum(matrix[i]):
        precision_classes[i] = max_occurence / np.sum(matrix[i])
    if total_occurences != 0:
        total += max_occurence / total_occurences

return total, precision_classes
```

- Given the contingency matrix, calculate the Recall.

```
def total_recall(matrix):
    recall_classes = np.zeros(len(matrix))
    total = 0

    for i in range(len(recall_classes)):
        max_ind = np.argmax(matrix[i])
        val = np.sum(matrix[:, max_ind])
        if val != 0:
            recall_classes[i] = matrix[i][max_ind] / val
            total += recall_classes[i] / len(matrix)

    return total, recall_classes
```

- Given the contingency matrix, calculate the F1-score.

```
def f_measure(precision, recall):
    total = 0
    for i in range(len(precision)):
        if precision[i] + recall[i] > 0:
            total += 2 * (precision[i] * recall[i]) / (precision[i] + recall[i])
    return total / (len(precision) - 1)
```

- Given the contingency matrix, calculate the Conditional Entropy.

```
def entropy(matrix):
    entropy_classes = np.zeros(len(matrix))
    total = 0
    total_occurences = np.sum(matrix)

for i in range(len(entropy_classes)):
    cluster_sum = np.sum(matrix[i])
    for j in range(len(matrix[i])):
        if cluster_sum > 0 and matrix[i][j] / cluster_sum > 0:
            entropy_classes[i] -= matrix[i][j] / cluster_sum * np.log2(matrix[i][j] / cluster_sum)
    if total_occurences != 0:
        total += entropy_classes[i] * (cluster_sum / total_occurences)

return total, entropy_classes
```

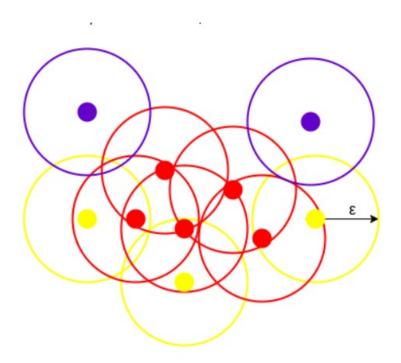
- Given the predictions and the ground truth, calculate all the measures.

```
def evaluate(predictions, truth):
    contingency_matrix = map(predictions, truth)
    total_pre, precision_classes = total_precision(contingency_matrix)
    total_rec, recall_classes = total_recall(contingency_matrix)
    f_score = f_measure(precision_classes, recall_classes)
    entropy_value, entropy_classes = entropy(contingency_matrix)
    print("\tPrecision : ", total_pre)
    print("\tRecall : ", total_rec)
    print("\tF-score : ", f_score)
    print("\tEntropy : ", entropy_value)
```

5. CLUSTERING USING DB-SCAN

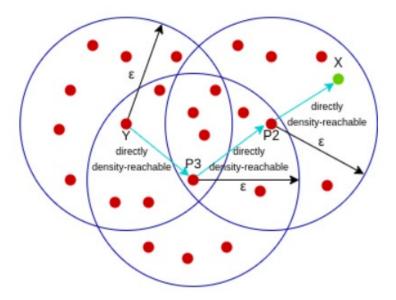
Intuition:

- Similar to the human naive clustering to each image of points, It groups 'densely grouped' data points into a single cluster so density of Circle is introduced to know how many nodes in the circle of a single point of radius ε.
- Moveover, different types of points are introduced: **Core**, **Border** and **Noise** points. Set of core points is a category of points that have at least k points in its ε-neighborhood. Furthermore, set of border points has less than k points in its ε-neighborhood but exists on a circle of a core point.



Algorithm:

- We get all core points in given data set according to the above intuition.
- Create a separate cluster:
 - To create Cluster, we start each core point with cluster i and for each density connected point, we will assign the same cluster i to this point.
 - After that, Recursively call each core point in the density connected points of previous point and apply same logic until no core point exists in the density connected points of the current point core point.
 - This totally means: assigning all reachable core points to same cluster.



Abstract Code:

```
Algorithm
 def DBSCAN_algorithm(D, ε, min_points):
   global global_counter
   n = D.shape[0]
   d = D.shape[1]
   cluster_id = [-1] * n
   # get core points:
   core_indices = get_core_indices(D, n, ε, min_points)
   core_indices_set = set(core_indices)
   # build connected components:
   cluster_counter = -1
   for i in range(len(core_indices)):
     if cluster_id[core_indices[i]] != -1: continue
     cluster_counter = cluster_counter + 1
     cluster_id[core_indices[i]] = cluster_counter
     connect_to_adj_cores(D, n, &, core_indices[i], cluster_counter, core_indices_set, cluster_id)
   return cluster_id
```

Advantages:

- is able to identify noise or outliers in the dataset
- It can identify clusters of arbitrary shape, making it suitable for datasets with complex cluster structures with flexibility of detecting the number of clusters.

Disadvantages:

- Very sensitive to two parameters ε and k.

- Compare with K-Means:
- Comparison on Testing set on mean reformulated data:

| K | K-Means | | | | DBscan | | | |
|---|-----------|--------|----------|---------|-----------|---------|----------|---------|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy |
| 8 | 0.2655 | 0.4571 | 0.3403 | 3.1048 | 0.7338 | 0.25505 | 0.39253 | 0.8098 |

• Comparison on Testing set on dimensionality reduced data:

| K | K-Means | | | | DBscan | | | |
|---|-----------|--------|----------|---------|---------------|--------|----------|---------|
| | Precision | Recall | F1-Score | Entropy | Precision | Recall | F1-Score | Entropy |
| 8 | 0.18366 | 0.3877 | 0.29413 | 3.42913 | 0.9999 | 0.1999 | 0.34386 | 0.0001 |

• Comments:

- After Fitting DBSCAN over hyper-parameters that get best accuracy and evaluation values, We simply can observe that DBSCAN evaluation values are better than K-Means ones.
- Observations almost make sense because DBSCAN can detect spherical data because of the perspective that each algorithm assign each cluster with more similarity.