

Genetic Algorithms

Chapter 20, Section 8

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Introduction to Genetic Algorithms (GA)

- **Inspired by natural evolution:**

- living things evolved into more successful organisms
- offspring exhibit some traits of each parent
- hereditary traits are determined by genes
- genetic instructions are contained in chromosomes
- chromosomes are strands of DNA
- DNA is composed of base pairs (ACGT), when in meaningful combinations, encode hereditary traits

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Introduction to Genetic Algorithms

- **Mechanisms of evolutionary change:**

- crossover: the random exchange of parent's chromosomes during reproduction resulting in:
 - offspring have some traits of each parent

*** Crossover requires genetic diversity among the parents to ensure sufficiently varied offspring.**

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Introduction to Genetic Algorithms

- **Mechanisms of evolutionary change:**

- mutation: the rare occurrence of errors during the process of copying chromosomes resulting in:
 - changes that are nonsensical/deadly producing organisms that can't survive
 - changes are beneficial producing "stronger" organisms
 - changes aren't harmful/deadly but aren't beneficial producing organisms that aren't improved

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Introduction to Genetic Algorithms

- **Mechanisms of evolutionary change:**
 - natural selection: in a competitive environment the fittest survive resulting in better organisms
 - individuals with better survival traits generally survive for a longer period of time
 - this provides a better chance for reproducing and passing the successful traits on to offspring
 - over many generations the species improves since better traits will out number weaker ones

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Introduction to Genetic Algorithms

- **Keep a population of individuals that are complete or partial solutions**
- **Explore solution space by having these individuals interact and compete**
 - interaction produces new individuals
 - competition eliminates weak individuals
- **After multiple generations a strong individual (i.e. solution) should be found**

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Representation of Individuals

- **Some problems have solutions that can be represented as a vector of values:**
 - e.g. satisfiability problem (SAT):
 - determine if a statement in propositional logic is satisfiable**
 $(P_1 \wedge P_2) \vee (P_1 \wedge \neg P_3) \vee (P_1 \wedge \neg P_4) \vee (\neg P_3 \wedge \neg P_4)$
 - each element corresponds with a proposition having a truth value of either true (i.e. 1) or false (i.e. 0)
 - vector: $P_1 \ P_2 \ P_3 \ P_4$
 - values: 1 0 1 1
- **Some problems have solutions that can be represented as a permutation of values:**
 - e.g. traveling sales person problem (TSP)

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Algorithm for Simulated Evolution

- Individual evolutionaryAlgorithm (Problem problem)**
- **Problem:** object that contains
 - **initialize:** returns an initial population of individuals
 - a population size (e.g. 100)
 - **evaluate:** sorts the population of individuals by fitness
 - **atFitnessThreshold:** test if desired solution quality reached
 - **select:** chooses individuals that survive
 - **alter:** generates new individuals
 - method that implements crossover
 - a fraction of population to be generated by crossover (e.g. 0.6)
 - method that implements mutation
 - a mutation rate (e.g. 0.001)
 - **Individual:** the best solution found

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Algorithm for Simulated Evolution

```
Individual evolutionaryAlgorithm(Problem problem) {  
    Population currGen = problem.initialize();  
    problem.evaluate(currGen);  
    while (!problem.atFitnessThreshold(currGen)) {  
        Population nextGen = problem.select(currGen);  
        problem.alter(nextGen);  
        currGen = nextGen;  
        problem.evaluate(currGen);  
    }  
    return problem.mostFitIndividual(currGen);  
}
```

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Initialization: Seeding the Population

*** Initialization sets the beginning population of individuals from which future generations are produced.**

• Concerns:

- size of the initial population
experimentally determined for problem
- diversity of the initial population (genetic diversity)
a common issue resulting from the lack of diversity
is premature convergence on non-optimal solution

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Initialization: Seeding the Population

• How is a diverse initial population generated?

- uniformly random: generate individuals randomly from a solution space with uniform distribution
- grid initialization: choose individuals at regular "intervals" from the solution space
- non-clustering: require individuals to be a predefined "distance" away from those already in the population
- local optimization: use another technique (e.g. HC) to find initial population of local optima, doesn't ensure diversity but guarantees solution to be no worse

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Evaluation: Ranking by Fitness

*** Evaluation ranks the individuals by some fitness measure that corresponds with the quality of the individual solutions.**

• For example, given individual i :

- classification: $(correct(i))^2$
- TSP: $distance(i)$
- SAT: $\#ofTermsSatisfied(i)$
- walking animation: *subjective rating*

• Often fitness functions have local minima.

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Selection: Finding the Fittest

- * *Choose which individuals survive and possibly reproduce in the next generation.*
- **Selection depends on the evaluation function**
 - if too dependent then like greedy search a non-optimal solution may be found
 - if not dependent enough then may not converge to a solution at all
- **Nature doesn't eliminate all "unfit" genes. They usually become recessive for a long period of time, and then may mutate to something useful.**

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Selection Techniques

- **Deterministic Selection:**
 - relies heavily on evaluation
 - converges fastest
- **Two approaches:**
 - next generation is parents and their children
 - parents are the best of the current generation
 - parents are used to produce children and survive
 - next generation is only the children
 - parents are the best of the current generation
 - parents are used to produce children only
 - parents don't survive (counters early convergence)

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Selection Techniques

- **Proportional Fitness Selection:**
 - each individual is selected proportionally to their evaluation score
 - even the worst individual has a chance to survive
 - this helps prevent stagnation in the population
- **Two approaches:**
 - rank selection: individual selected with a probability proportional to its rank in population sorted by fitness
 - proportional selection: individual selected with a probability $\text{Fitness}(\text{individual}) / \text{sum Fitness for all individuals}$

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Selection Techniques

Proportional selection example:

- **Given the following population and fitness:**

- **Sum the Fitness**

$$5 + 20 + 11 + 8 + 6 = 50$$

- **Determine probabilities**

$$\text{Fitness}(i) / 50$$

Individual	Fitness	Prob.
A	5	10%
B	20	40%
C	11	22%
D	8	16%
E	6	12%

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Selection Techniques

- **Tournament Selection:**

- randomly select two individuals and the one with the highest fitness wins to go on and reproduce
- cares only about ranking, not the spread of scores
- puts an upper and lower bound on the chances that any individual to reproduce for the next generation equal to: $(2n - 2m + 1) / n^2$
 - n is the size of the population
 - m is the rank of the "winning" individual
- can be generalized to select best of n individuals

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Selection Techniques

Tournament selection example:

- **Given the following population and fitness:**

- **Select B and D**

- **B wins**

- **Probability:**

$$(2n - 2m + 1) / n^2$$

Individual	Fitness	Prob.
A	5	1/25 = 4%
B	20	9/25 = 36%
C	11	7/25 = 28%
D	8	5/25 = 20%
E	6	3/25 = 12%

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Selection Techniques

- **Crowding:**

a potential problem associated with the selection

- occurs when the individuals that are most fit quickly reproduce so that a large percentage of the entire population looks very similar
- reduces diversity in the population
- may hinder the long-run progress of the algorithm

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Alteration: Producing new Individuals

*** Alteration is used to produce new individuals.**

- **Mutation:**

- randomly change an individual
- e.g. TSP: two swap, two interchange
- e.g. SAT: bit flip

- **Parameters:**

- mutation rate
- size of the mutation

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Alteration: Producing new Individuals

- **Crossover for vector representations:**
 - pick one or more pairs of individuals as parents and randomly swap their segments
 - also known as "cut and splice"
- **Parameters:**
 - crossover rate
 - number of crossover points
 - positions of the crossover points

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Alteration: Producing new Individuals

- **1-point crossover:**
 - pick a dividing point in the parents' vectors and swap the segments
- **For Example**
 - given parents: 1101101101 and 0001001000
 - crossover point: after the 4th digit
 - children produced are:
1101 + 001000 and 0001 + 101101

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Alteration: Producing new Individuals

- **N-point crossover:**
 - generalization of 1-point crossover
 - pick n dividing points in the parents' vectors and splice together alternating segments
- **Uniform crossover:**
 - the value of each element of the vector is randomly chosen from the values in the corresponding elements of the two parents
- **Techniques exist for permutation representations.**

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Genetic Algorithms (GA) as Search

- **The problem of local maxima:**
 - individuals stuck at a pretty good but not optimal
 - any small mutation gives worse fitness
 - crossover can help them get out of a local maximum
 - mutation is a random process, so it is possible that we may have a sudden large mutation to get these individuals out of this situation

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Genetic Algorithms (GA) as Search

- GA is a kind of hill-climbing (HC) search
- Very similar to a randomized beam search
- One significant difference between GAs and HC is that, it is generally a good idea in GAs to fill the local maxima up with individuals
- Overall, GAs have less problems with local maxima than back-propagation neural networks

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Summary

- Easy to apply to a wide range of problems:
 - optimization like TSP
 - inductive concept learning
 - scheduling
 - layout
- The results can be very good on some problems, and rather poor on others.
- GA is very slow if only mutation is used. Crossover makes the algorithm significantly faster.

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